#### Lecture 4 – Testability Measures

- Purpose, origins
- Analysis, measures and computation
- Summary

#### Purpose

- Need approximate measure of:
  - Difficulty of setting internal circuit lines to 0 or 1 by setting primary circuit inputs
  - Difficulty of observing internal circuit lines by observing primary outputs

#### • Uses:

- Analysis of difficulty of testing internal circuit parts redesign or add special test hardware
- Guidance for algorithms computing test patterns avoid using hard-to-control lines
- Estimation of fault coverage
- Estimation of test vector length

### Origins

- Control theory
- Rutman 1972 -- First definition of controllability
- Goldstein 1979 -- SCOAP
  - First definition of observability
  - First elegant formulation
  - First efficient algorithm to compute controllability and observability
- Parker & McCluskey 1975
- Brglez 1984 -- COP
- Seth, Pan & Agrawal 1985

### **Testability Analysis**

- Involves Circuit Topological analysis, but no test vectors and no search algorithm
  - Static analysis
- Linear computational complexity
  - Otherwise, is pointless might as well use automatic test-pattern generation and calculate:
    - Exact fault coverage
    - Exact test vectors

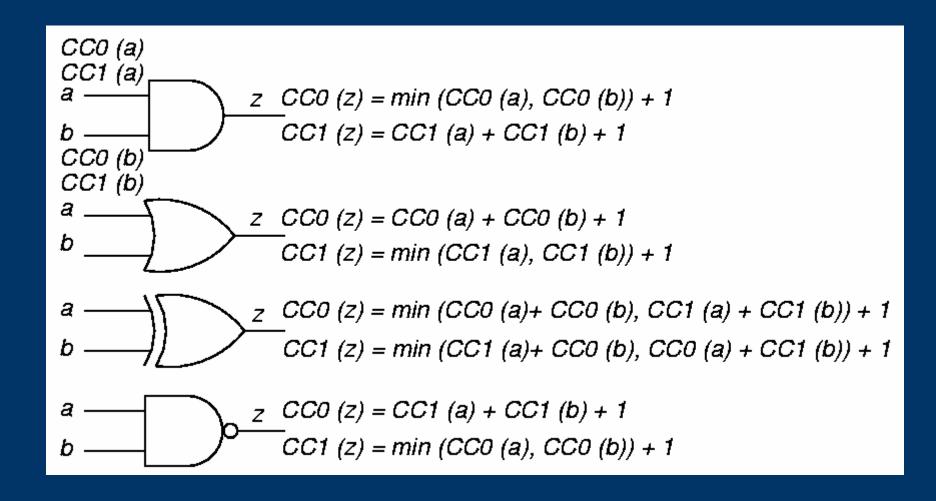
#### Types of Measures

- SCOAP Sandia Controllability and Observability Analysis Program
- Combinational measures:
  - CC0 Difficulty of setting circuit line to logic 0
  - CC1 Difficulty of setting circuit line to logic 1
  - CO Difficulty of observing a circuit line
- Sequential measures analogous:
  - **SC**0
  - **SC1**
  - **SO**

### Range of SCOAP Measures

- Controllabilities 1 (easiest) to infinity (hardest)
- Observabilities 0 (easiest) to infinity (hardest)
- Combinational measures:
  - Roughly proportional to # circuit lines that must be set to control or observe given line
- Sequential measures:
  - Roughly proportional to # times a flip-flop must be clocked to control or observe given line

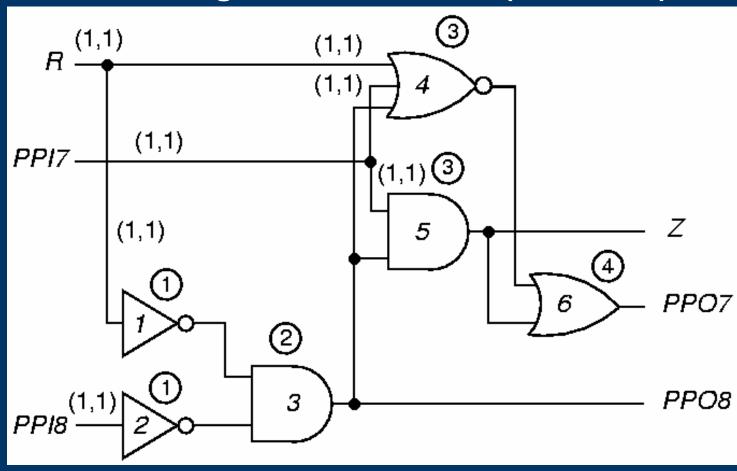
### Controllability Examples



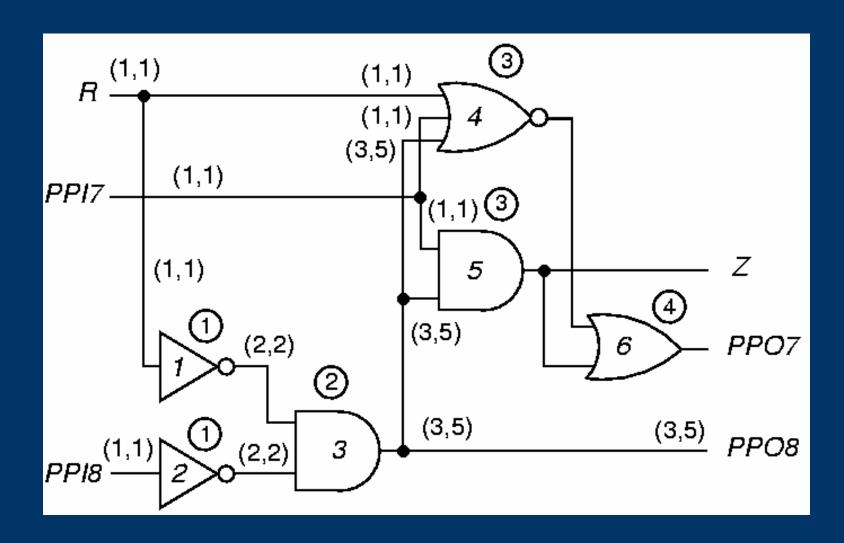
#### More Controllability Examples

### Controllability Through Level 0

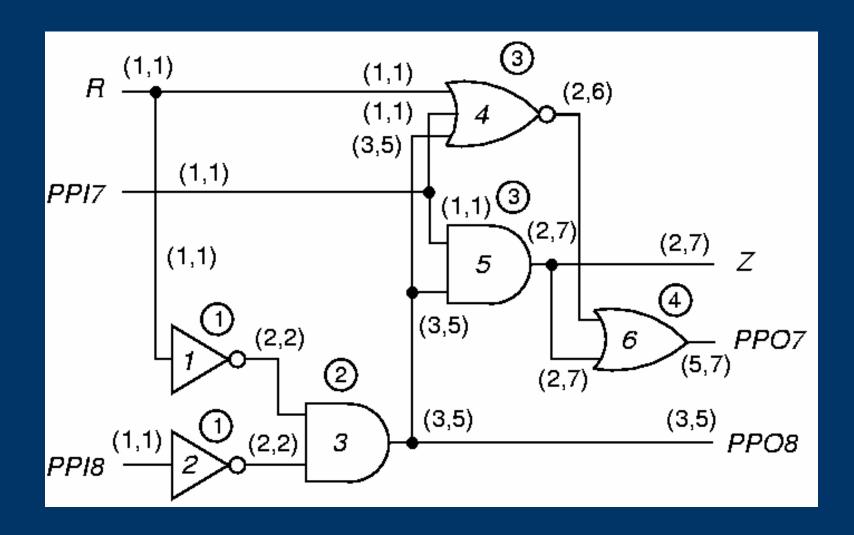
Circled numbers give level number. (CC0, CC1)



### Controllability Through Level 2



#### Final Combinational Controllability



#### Observability Examples

To observe a gate input:

Observe output and make other input values non-controlling

$$CO(a) = CO(z) + CC1(b) + 1$$

$$CO(b) = CO(z) + CC1(a) + 1$$

$$CO(b) = CO(z) + CC1(a) + 1$$

$$CO(a) = CO(z) + CC0(b) + 1$$

$$CO(b) = CO(z) + CC0(a) + 1$$

$$CO(a) = CO(z) + CC0(a) + 1$$

$$CO(a) = CO(z) + min(CC0(b), CC1(b)) + 1$$

$$CO(b) = CO(z) + min(CC0(a), CC1(a)) + 1$$

$$CO(b) = CO(z) + CC1(b) + 1$$

$$CO(b) = CO(z) + CC1(a) + 1$$

### More Observability Examples

To observe a fanout stem:

Observe it through branch with best observability

$$CO(a) = CO(z) + CCO(b) + 1$$

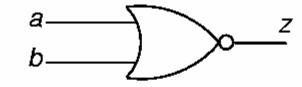
$$CO(b) = CO(z) + CCO(a) + 1$$

$$CO(a) = CO(z) + min(CCO(b), CC1(b)) + 1 a -$$

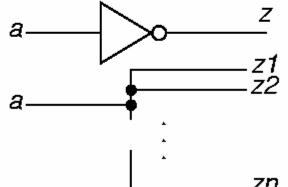
$$CO(b) = CO(z) + min(CCO(a), CC1(a)) + 1 b_{---}$$

$$CO(a) = CO(z) + 1$$

$$CO(a) = min(CO(z1), CO(z2), ..., CO(zn))$$

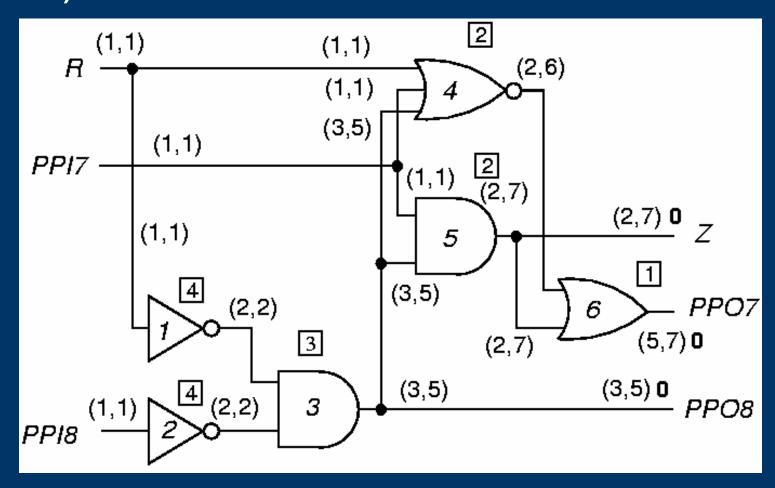




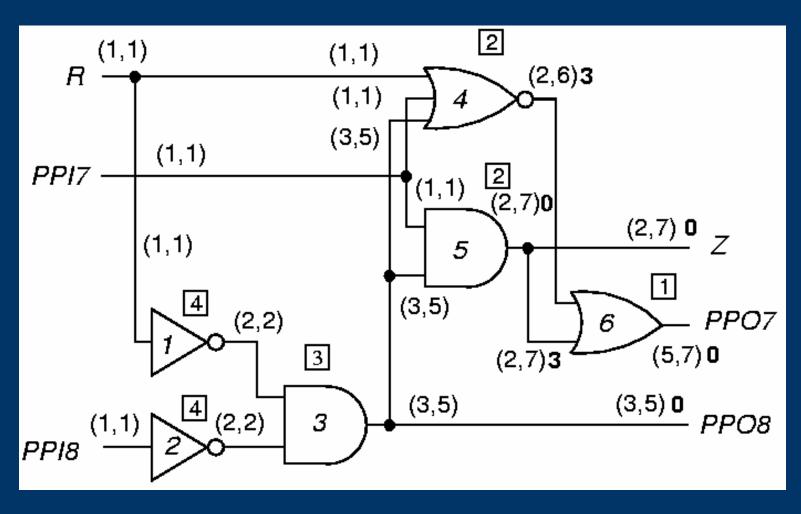


## Combinational Observability for Level 1

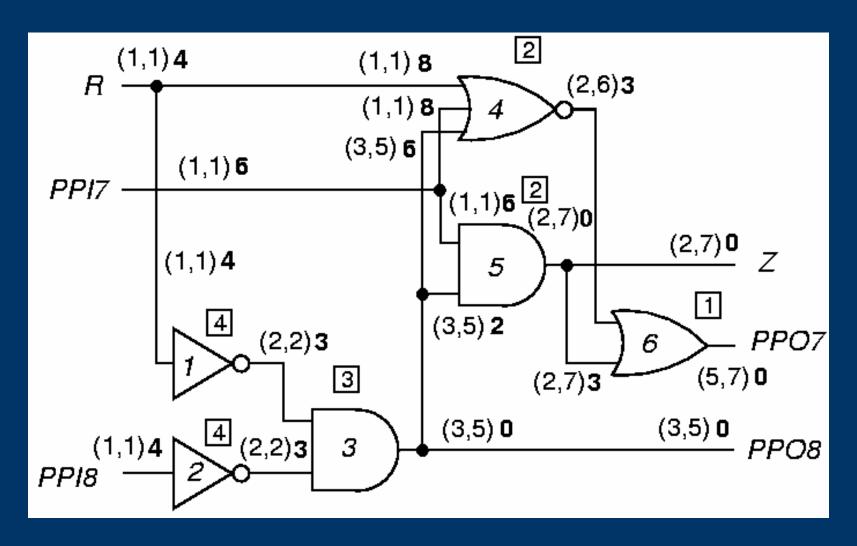
Number in square box is level from *primary outputs* (POs). (CC0, CC1) CO



# Combinational Observabilities for Level 2



# Final Combinational Observabilities



### Testability Computation

- 1. For all PIs, CC0 = CC1 = 1 and SC0 = SC1 = 0
- 2. For all other nodes,  $CC0 = CC1 = SC0 = SC1 = \infty$
- 3. Go from PIs to POS, using *CC* and *SC* equations to get controllabilities -- Iterate on loops until *SC* stabilizes -- convergence guaranteed
- 4. For all POs, set CO = SO = 0
- 5. Work from POs to PIs, Use CO, SO, and controllabilities to get observabilities
- 6. Fanout stem (CO, SO) = min branch (CO, SO)
- 7. If a CC or SC (CO or SO) is<sup>∞</sup>, that node is uncontrollable (unobservable)

#### Summary

- Testability approximately measures:
  - Difficulty of setting circuit lines to 0 or 1
  - Difficulty of observing internal circuit lines

#### Uses:

- Analysis of difficulty of testing internal circuit parts
- Redesign circuit hardware or add special test hardware where measures show bad controllability or observability
- Guidance for algorithms computing test patterns avoid using hard-to-control lines
- Estimation of fault coverage
- Estimation of test vector length