★ (/xwiki/bin/view/Main/) ▼ / MASTERs (/xwiki/wiki/masters/view/Main/) ▼

/ MASTERs 2025 Lab Manual Developement (/xwiki/wiki/masters/view/masters-2025-lab-manuals/) ▼ / 25085 MTR4 - Developing Motor Control Applications using Model Based Design (/xwiki/wiki/masters/view/masters-2025-lab-manuals/25085/) ▼

# 25085 MTR4 - Developing Motor Control Applications using Model Based Design

Last modified by Mark Reynolds (/xwiki/bin/view/XWiki/MarkReynolds) on 2025/07/22 11:49

#### Introduction



The purpose of this class and lab manual is to explore model-based design with embedded drive applications.

The labs incorporate various software and hardware tools to introduce you to the basics of model-based design and the development process. The lab begins with simple frequency modulation simulation and embedded code generation processes. In the later sections, it delves into more complex motor control models to demonstrate control loop tuning, showcasing real engineering use cases.

Upon completion, you will be able to:

- Build a model-based project from the very beginning
- Use the Scilab<sup>®</sup> tool to design a model
- Use X2C® communicator to analyse signals within the model
- Optimize control loops with model-based design techniques

## <u>Lab 1 - Model-Based Design - "HelloWorld" (/xwiki/wiki/masters/view/masters-2025-lab-manuals/25085/lab1/)</u>

Lab 2 - Torque Mode (/xwiki/wiki/masters/view/masters-2025-lab-manuals/25085/lab2/)

Lab 3 - Speed Control Mode (/xwiki/wiki/masters/view/masters-2025-lab-manuals/25085/lab3/)

#### **Prerequisites**

The lab material assumes you have prior experience with:

- MPLAB® X Integrated Development Environment (IDE)
- MPLAB development ecosystem-based programming/debugging fundamentals
- MPLAB Code Configurator (MCC) Melody
- C language programming
- · Motor control fundamentals
- Real-time control loop fundamentals

#### Hardware Requirements

Here is the list of hardware needed to complete the labs:

• MCLV-48V-300W Part number: <u>EV18H47A (https://www.microchip.com/en-us/development-tool/EV18H47A)</u>

1 of 3 29-Jul-25, 9:39



dsPIC33AK128MC106 MC DIM Part number: <u>EV68M17A (https://www.microchipdirect.com/dev-tools/EV68M17A)</u>



• Brushless DC Motor ACT 57BLF02



### Software Requirements

Here is the list of software needed to complete the labs:

- ✓ MPLAB® X IDE (version 6.25) (https://www.microchip.com/en-us/tools-resources/develop/mplab-x-ide)
- ✓ MPLAB® XC16 Compiler (version 2.10) (https://www.microchip.com/en-us/tools-resources/develop/mplab-xc-compilers/xc16)
- √ Scilab® (https://www.scilab.org/)
- ✓ X2C<sup>®</sup> (https://x2c.lcm.at/)

Scilab: v2024.1.0 is preferred (64-bit) (version 6 or newer supported)

X2C: v6.5 Free (latest nightly build)

2 of 3 29-Jul-25, 9:39

#### Next

<u>Lab 1 - Model-Based Design – "HelloWorld" (/xwiki/wiki/masters/view/masters-2025-lab-manuals/25085/lab1/)</u>



Tags:

Created by Mark Reynolds (/xwiki/bin/view/XWiki/MarkReynolds) on 2024/12/23 06:56

Information contained on this site regarding device applications and the like is provided only for your convenience and may be superseded by updates. It is your responsibility to ensure that your application meets with your specifications. MICROCHIP MAKES NO REPRESENTATIONS OR WARRANTIES OF ANY KIND WHETHER EXPRESS OR IMPLIED, WRITTEN OR ORAL, STATUTORY OR OTHERWISE, RELATED TO THE INFORMATION, INCLUDING BUT NOT LIMITED TO ITS CONDITION, QUALITY, PERFORMANCE, MERCHANTABILITY OR FITNESS FOR PURPOSE. Microchip disclaims all liability arising from this information and its use. Use of Microchip devices in life support and/or safety applications is entirely at the buyer's risk, and the buyer agrees to defend, indemnify and hold harmless Microchip from any and all damages, claims, suits, or expenses resulting from such use. No licenses are conveyed, implicitly or otherwise, under any Microchip intellectual property rights.

No comments for this page



3 of 3 29-Jul-25, 9:39