

Session 6: Exercises

M2 MOSIG: Distributed Systems

Thomas Ropars

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1 About f

Question 1.1: An algorithm A that solves problem P is proven correct for some f . What claims below are correct:

1. In an execution, at most f processes may crash.
2. In each execution f processes crash.
3. If more than f processes crash in an execution, algorithm A may not solve problem P .
4. If less than f processes crash in an execution, algorithm A may not solve problem P .

2 Univalent configuration

Question 2.2: Give an example of a univalent configuration for the FloodSet consensus algorithm (Algorithm 4).

Question 2.3: In OTR consensus algorithm (Algorithm 6), can a configuration be univalent before GSR?

Question 2.4: In OTR consensus algorithm (Algorithm 6), can an initial configuration, where not all the initial values are identical, be univalent? If yes, give an example. If no, explain why?

3 More about OTR

All the following questions are about OTR (Algorithm 6)

Question 3.5: Let condition $f < n/3$ hold, but assume an execution where more than f processes crash. Which property of consensus is violated in such an execution? Give an example.

Question 3.6: Conversely, assume an execution with no more than f processes crash, but $f \geq n/3$. Which property of consensus is violated in such a execution? Give an example.