

# Session 6: Exercises

M2 MOSIG: Distributed Systems

Thomas Ropars

2025

## 1 About $f$

**Question 1.1:** *An algorithm  $A$  that solves problem  $P$  is proven correct for some  $f$ . What claims below are correct:*

1. *In an execution, at most  $f$  processes may crash.*
2. *In each execution  $f$  processes crash.*
3. *If more than  $f$  processes crash in an execution, algorithm  $A$  may not solve problem  $P$ .*
4. *If less than  $f$  processes crash in an execution, algorithm  $A$  may not solve problem  $P$ .*

## 2 Univalent configuration

**Question 2.2:** *Give an example of a univalent configuration for the FloodSet consensus algorithm (Algorithm 4).*

**Question 2.3:** *In OTR consensus algorithm (Algorithm 6), can a configuration be univalent before GSR?*

**Question 2.4:** *In OTR consensus algorithm (Algorithm 6), can an initial configuration, where not all the initial values are identical, be univalent? If yes, give an example. If no, explain why?*

## 3 More about OTR

All the following questions are about OTR (Algorithm 6)

**Question 3.5:** *Let condition  $f < n/3$  hold, but assume an execution where more than  $f$  processes crash. Which property of consensus is violated in such an execution? Give an example.*

**Question 3.6:** *Conversely, assume an execution with no more than  $f$  processes crash, but  $f \geq n/3$ . Which property of consensus is violated in such a execution? Give an example.*