pds_bersbceo.m

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Abstract

The function $pds_bersbceo()$ represent the formulation of Bit Error Rate (BER) in the symmetric binary CEO problem.

1 Introduction

The function pds_bersbceo() in the m-file pds_bersbceo.m is defined as:

E = pds_bersbceo(Ps,M);

This function represent the formulation of BER in the symmetric binary CEO problem.

$$BER = \begin{cases} \sum_{k=\lfloor \frac{M}{2} \rfloor + 1}^{M} {M \choose k} (1 - P_s)^{M-k} P_s^k & \text{if } M \text{ odd} \\ \sum_{k=\lfloor \frac{M}{2} \rfloor + 1}^{M} {M \choose k} (1 - P_s)^{M-k} P_s^k & \text{if } M \text{ even} \\ + 0.5 {M \choose \frac{M}{2}} (1 - P_s)^{\frac{M}{2}} P_s^{\frac{M}{2}} \end{cases}$$
 (1)

This form is showed in [1], a similar form is presented in [2, 3].

1.1 Working with the probability $BER = P(\hat{U_0} \neq U_0)$

In [2, 3] is considered a maximum a posteriori (MAP) fusion rule $f(\Omega_M)$, where the output value \hat{u}_0 of \hat{U}_0 is obtained as

$$\hat{u}_0 = \arg_{u_0} \max P(U_0 | \Omega_M)
\equiv \arg_{u_0} \max P(\Omega_M | U_0)$$
(2)

Thus, considering that m_0 is the number of zeros in Ω_M , the decision is simplify to

$$\hat{u}_0 = 1
m_0 \geq \lfloor \frac{M}{2} \rfloor
\hat{u}_0 = 0$$
(3)

In this expression is considered that if M is even and $m_0 = M/2$, the decision is arbitrarily assume that $\hat{u}_0 = 1$, so that $P(\hat{U}_0 \neq U_0)$ is BER = 0.5 $[P(\hat{u}_0 = 0.5)]$

 $0|u_0 = 1) + P(\hat{u}_0 = 1|u_0 = 0)],$

$$BER = 0.5 \sum_{k=0}^{\lfloor \frac{M}{2} \rfloor - 1} {M \choose k} (1 - P_s)^k P_s^{M-k} + 0.5 \sum_{k=\lfloor \frac{M}{2} \rfloor}^{M} {M \choose k} (1 - P_s)^{M-k} P_s^{k}$$
(4)

where, $\lfloor . \rfloor$ is the floor function and the value BER only is valid for values of $P_s \leq 1/2^{-1}$. The Equation (4) can be sort as (1).

References

- [1] Haghighat, J.; Behroozi, Hamid; Plant, D.V., "Iterative joint decoding for sensor networks with binary CEO model," Signal Processing Advances in Wireless Communications, 2008. SPAWC 2008. IEEE 9th Workshop on , vol., no., pp.41,45, 6-9 July 2008. doi: 10.1109/SPAWC.2008.4641566
- [2] Abrardo, A.; Ferrari, G.; Martalò, M.; Perna, F. Feedback Power Control Strategies in Wireless Sensor Networks with Joint Channel Decoding. Sensors 2009, 9, 8776-8809. doi:10.3390/s91108776
- [3] Ferrari, G.; Martalo, M.; Abrardo, A.; Raheli, R., "Orthogonal multiple access and information fusion: How many observations are needed?," Information Theory and Applications Workshop (ITA), 2012, vol., no., pp.311,320, 5-10 Feb. 2012. doi: 10.1109/ITA.2012.6181783

 $^{^{1}\}mathrm{Here}$ is important note that in [2, 3] your value ρ is equal to $1-P_{s}$ here, and your result is for $\rho>0.5$