

# Messomat 7K

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mit Rust und Angular

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```
38
39     // build our application with a single route
40     let app = Router::new()
41
42     .route("/all", get(get_all)
43     .with_state(sensordb))
44
45     .route("/status", get(get_status)
46     .with_state(command_sender.clone()))
47
48     .route("/set-fan", post(post_set_fan)
49     .with_state(command_sender.clone()))
50
51     .route("/set-send-mode", post(post_set_send_mode)
52     .with_state(command_sender.clone()))|
53
54     .route("/set-on", post(post_set_on)
55     .with_state(command_sender.clone()))
56
57     .route("/set-off", post(post_set_off))
58     .with_state(command_sender.clone())
59
60     .layer(cors);
61
```

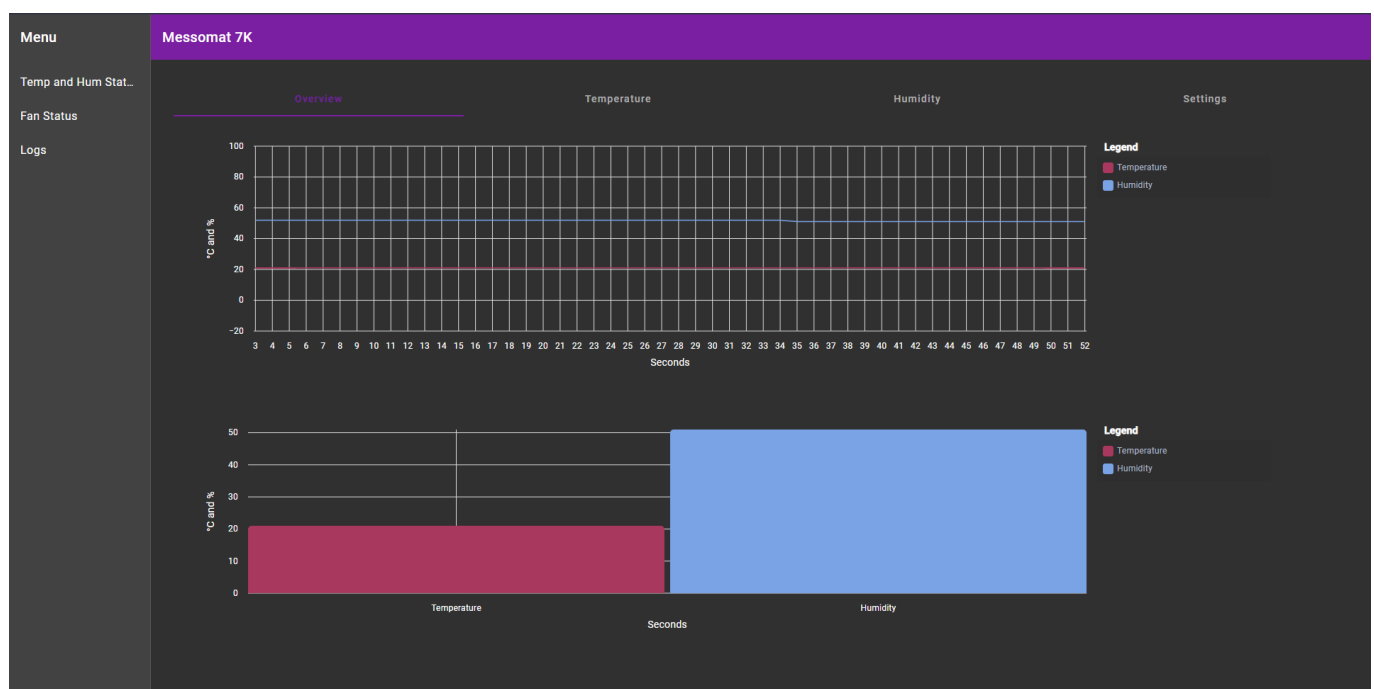
## Backend

- Rust Nightly
  - Tokio Async Runtime
  - Tokio Serial (Serialport Library)
  - parallel Request Handling
  - Protocol fully mapped in Rust
-

```
1 use anyhow::anyhow;
2 use tokio_serial::{SerialPortBuilderExt, SerialStream};
3
4 use std::time::Duration;
5
6 use tokio_serial::{DataBits, FlowControl, Parity, StopBits};
7
8 ✓ pub fn create_serialport(port_name: &str) -> Result<SerialStream, anyhow::Error> {
9     tokio_serial::new(port_name, 9600)
10         .data_bits(DataBits::Eight)
11         .stop_bits(StopBits::One)
12         .parity(Parity::None)
13         .flow_control(FlowControl::None)
14         .timeout(Duration::from_secs(1))
15         .baud_rate(9600)
16         .open_native_async()
17         .map_err(|e| anyhow!(e))
18 }
```

## Frontend

- Angular (JS Framework)
- ruft API auf
- nutzt Angular Material (UI-Library wie MudBlazor)
- nutzt NgxCharts für Diagramme (Line & Bar Charts)





Menu

Temp and Hum Stat...

Fan Status

Logs

Messomat 7K

Remote station: On

Fan Status: On

Menu

Temp and Hum Stat...

Fan Status

Logs

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Overview

Temperature

Turn off

Time Interval

slow

fast



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**THX**

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