Run/Drivers	TravelTime (s)	LaneOffset (cm)	Total Fitness Function	Best driver	DesiredVelocity	DesiredAcceleration	DesiredDeceleration	CurveBehavior	ObserveSpeedLimits	DistanceKeeping	LaneKeeping	SpeedKeeping	LaneChangingDynamic	UrgeToOvertake	RespondToTailgatingVehicles	ForesightDistance	SteeringDistance	ObserveKeepRightRule	Consider Env Conditions	UseOfIndicator	ReactionTime	ObeyTrafficSigns	ObeyTrafficLights	ObeyTrafficRules	Swarm	RouteAdherence
1	13,08	8,760762215	-1	1	0.40		0.65		0.90				0.35					0.50				1	1	1	0	1
2	13,08	8,760356158	-1	2	0.40	0.33	0.65	0.35	0.90	0.65	0.30	0.30	0.35	0.20	0.50	0.30	0.30	0.50	0.50	0.20	0.50	1	1	1	0	1
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Run/Drivers	TravelTime (s)	LaneOffset (cm)	Total Fitness Function	Best driver	DesiredVelocity	Desired Acceleration	DesiredDeceleration	CurveBehavior	ObserveSpeedLimits	DistanceKeeping	LaneKeeping	SpeedKeeping	LaneChangingDynamic	UrgeToOvertake	RespondToTailgatingVehicles	ForesightDistance	SteeringDistance	ObserveKeepRightRule	Consider Env Conditions	UseOfIndicator	ReactionTime	ObeyTrafficSigns	ObeyTrafficLights	ObeyTrafficRules	Swarm	RouteAdherence
1	13,08	8,760762215	-1	1	0.40		0.65		0.90									0.50			-	1	1	1	0	1
2	13,08	8,760356158	-1	2	0.40	0.33	0.65	0.35	0.90	0.65	0.30	0.30	0.35	0.20	0.50	0.30	0.30	0.50	0.50	0.20	0.50	1	1	1	0	1
3	13,08	8,746193349	-1	3	0.40	0.07	0.65	0.35	0.90	0.65	0.30	0.30	0.35	0.20	0.50	0.30	0.30	0.50	0.50	0.20	0.50	1	1	1	0	1
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Run/Drivers	TravelTime (s)	LaneOffset (cm)	Total Fitness Function	Best driver	DesiredVelocity	DesiredAcceleration	DesiredDeceleration	CurveBehavior	ObserveSpeedLimits	DistanceKeeping	LaneKeeping	SpeedKeeping	LaneChangingDynamic	UrgeToOvertake	RespondToTailgatingVehicles	ForesightDistance	SteeringDistance	ObserveKeepRightRule	Consider Env Conditions	UseOfIndicator	ReactionTime	ObeyTrafficSigns	ObeyTrafficLights	ObeyTrafficRules	Swarm	RouteAdherence
1	13,08	8,760762215	-1	1	0.40	0.35	0.65	0.35	0.90	0.65	0.30	0.30	0.35	0.20	0.50	0.30	0.30	0.50	0.50	0.20	0.50	1	1	1	0	1
2	13,08	8,760356158	-1	2	0.40	0.33	0.65	0.35	0.90	0.65	0.30	0.30	0.35	0.20	0.50	0.30	0.30	0.50	0.50	0.20	0.50	1	1	1	0	1
3	13,08	8,746193349	-1	3	0.40	0.07	0.65	0.35	0.90	0.65	0.30	0.30	0.35	0.20	0.50	0.30	0.30	0.50	0.50	0.20	0.50	1	1	1	0	1
4	13,08	8,746193349	-1	3	0.33	0.07	0.65	0.35	0.90	0.65	0.30	0.30	0.35	0.20	0.50	0.30	0.30	0.50	0.50	0.20	0.50	1	1	1	0	1

Run/Drivers	TravelTime (s)	LaneOffset (cm)	Total Fitness Function	Best driver	DesiredVelocity	DesiredAcceleration	DesiredDeceleration	CurveBehavior	ObserveSpeedLimits	DistanceKeeping	LaneKeeping	SpeedKeeping	LaneChangingDynamic	UrgeToOvertake	<b>RespondToTailgatingVehicles</b>	ForesightDistance	SteeringDistance	ObserveKeepRightRule	Consider Env Conditions	UseOfIndicator	ReactionTime	ObeyTrafficSigns	ObeyTrafficLights	ObeyTrafficRules	Swarm	RouteAdherence
1	13,08	8,760762215	-1	1	0.40	0.35	0.65	0.35	0.90	0.65	0.30	0.30	0.35	0.20	0.50	0.30	0.30	0.50	0.50	0.20	0.50	1	1	1	0	1
2	13,08	8,760356158	-1	2	0.40	0.33	0.65	0.35	0.90	0.65	0.30	0.30	0.35	0.20	0.50	0.30	0.30	0.50	0.50	0.20	0.50	1	1	1	0	1
3	13,08	8,746193349	-1	3	0.40	0.07	0.65	0.35	0.90	0.65	0.30	0.30	0.35	0.20	0.50	0.30	0.30	0.50	0.50	0.20	0.50	1	1	1	0	1
4	13,08	8,746193349	-1	3	0.33	0.07	0.65	0.35	0.90	0.65	0.30	0.30	0.35	0.20	0.50	0.30	0.30	0.50	0.50	0.20	0.50	1	1	1	0	1
5	13,08	8,746191859	-1	5	0.40	0.07	0.56	0.35	0.90	0.65	0.30	0.30	0.35	0.20	0.50	0.30	0.30	0.50	0.50	0.20	0.50	1	1	1	0	1
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Run/Drivers	TravelTime (s)	LaneOffset (cm)	Total Fitness Function	Best driver	DesiredVelocity	DesiredAcceleration	DesiredDeceleration	CurveBehavior	ObserveSpeedLimits	DistanceKeeping	LaneKeeping	SpeedKeeping	LaneChangingDynamic	UrgeToOvertake	RespondToTailgatingVehicles	ForesightDistance	SteeringDistance	ObserveKeepRightRule	ConsiderEnvConditions	UseOfIndicator	ReactionTime	ObeyTrafficSigns	ObeyTrafficLights	ObeyTrafficRules	Swarm	RouteAdherence
1	13,08	8,760762215	0,489534377	1	0.40	0.35	0.65	0.35	0.90	0.65	0.30	0.30	0.35	0.20	0.50	0.30	0.30	0.50	0.50	0.20	0.50	1	1	1	0	1
2	13,08	8,760356158	0,503481067	2	0.40	0.33	0.65	0.35	0.90	0.65	0.30	0.30	0.35	0.20	0.50	0.30	0.30	0.50	0.50	0.20	0.50	1	1	1	0	1
3	13,08	8,746193349	1,168453137	3	0.40	0.07	0.65	0.35	0.90	0.65	0.30	0.30	0.35	0.20	0.50	0.30	0.30	0.50	0.50	0.20	0.50	1	1	1	0	1
4	13,08	8,746193349	1,168453137	3	0.33	0.07	0.65	0.35	0.90	0.65	0.30	0.30	0.35	0.20	0.50	0.30	0.30	0.50	0.50	0.20	0.50	1	1	1	0	1
5	13,08	8,746191859	1,168502298	5	0.40	0.07	0.56	0.35	0.90	0.65	0.30	0.30	0.35	0.20	0.50	0.30	0.30	0.50	0.50	0.20	0.50	1	1	1	0	1
6	12,56	8,761464804	1,127115574	5	0.40	0.39	0.56	0.35	0.90	0.65	0.30	0.30	0.35	0.20	0.50	0.30	0.30	0.50	0.50	0.20	0.50	1	1	1	0	1

Run/Drivers	TravelTime (s)	LaneOffset (cm)	Total Fitness Function	Best driver	DesiredVelocity	DesiredAcceleration	DesiredDeceleration	CurveBehavior	ObserveSpeedLimits	DistanceKeeping	LaneKeeping	SpeedKeeping	LaneChangingDynamic	UrgeToOvertake	RespondToTailgatingVehicles	ForesightDistance	SteeringDistance	ObserveKeepRightRule	Consider Env Conditions	UseOfIndicator	ReactionTime	ObeyTrafficSigns	ObeyTrafficLights	ObeyTrafficRules	Swarm	RouteAdherence
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1	13,08	8,760762215	0,468665537	1	0.40	0.35	0.65	0.35	0.90	0.65	0.30	0.30	0.35	0.20	0.50	0.30	0.30	0.50	0.50	0.20	0.50	1	1	1	0	1
2	13,08	8,760356158	0,480678905	2	0.40	0.33	0.65	0.35	0.90	0.65	0.30	0.30	0.35	0.20	0.50	0.30	0.30	0.50	0.50	0.20	0.50	1	1	1	0	1
3	13,08	8,746193349	1,14807008	3	0.40	0.07	0.65	0.35	0.90	0.65	0.30	0.30	0.35	0.20	0.50	0.30	0.30	0.50	0.50	0.20	0.50	1	1	1	0	1
4	13,08	8,746193349	1,14807008	3	0.33	0.07	0.65	0.35	0.90	0.65	0.30	0.30	0.35	0.20	0.50	0.30	0.30	0.50	0.50	0.20	0.50	1	1	1	0	1
5	13,08	8,746191859	1,148126353	5	0.40	0.07	0.56	0.35	0.90	0.65	0.30	0.30	0.35	0.20	0.50	0.30	0.30	0.50	0.50	0.20	0.50	1	1	1	0	1
6	12,56	8,761464804	1,100924577	5	0.40	0.39	0.56	0.35	0.90	0.65	0.30	0.30	0.35	0.20	0.50	0.30	0.30	0.50	0.50	0.20	0.50	1	1	1	0	1
7	13,08	8,746191114	1,148154486	7	0.35	0.07	0.56	0.35	0.90	0.65	0.30	0.30	0.35	0.20	0.50	0.30	0.30	0.50	0.50	0.20	0.50	1	1	1	0	1
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Run/Drivers	TraveITime (s)	LaneOffset (cm)	Total Fitness Function	Best driver	DesiredVelocity	DesiredAcceleration	DesiredDeceleration	CurveBehavior	<b>ObserveSpeedLimits</b>	DistanceKeeping	LaneKeeping	SpeedKeeping	LaneChangingDynamic	UrgeToOvertake	RespondToTailgatingVehicles	ForesightDistance	SteeringDistance	ObserveKeepRightRule	Consider Env Conditions	UseOfIndicator	ReactionTime	ObeyTrafficSigns	ObeyTrafficLights	ObeyTrafficRules	Swarm	RouteAdherence
1	13,08	8,760762215	0,45369195	1	0.40	0.35	0.65	0.35	0.90	0.65	0.30	0.30	0.35	0.20	0.50	0.30	0.30	0.50	0.50	0.20	0.50	1	1	1	0	1
2	13,08	8,760356158	0,464160781	2	0.40	0.33	0.65	0.35	0.90	0.65	0.30	0.30	0.35	0.20	0.50	0.30	0.30	0.50	0.50	0.20	0.50	1	1	1	0	1
3	13,08	8,746193349	1,133217733	3	0.40	0.07	0.65	0.35	0.90	0.65	0.30	0.30	0.35	0.20	0.50	0.30	0.30	0.50	0.50	0.20	0.50	1	1	1	0	1
4	13,08	8,746193349	1,133217733	3	0.33	0.07	0.65	0.35	0.90	0.65	0.30	0.30	0.35	0.20	0.50	0.30	0.30	0.50	0.50	0.20	0.50	1	1	1	0	1
5	13,08	8,746191859	1,13327973	5	0.40	0.07	0.56	0.35	0.90	0.65	0.30	0.30	0.35	0.20	0.50	0.30	0.30	0.50	0.50	0.20	0.50	1	1	1	0	1
6	12,56	8,761464804	1,080499607	5	0.40	0.39	0.56	0.35	0.90	0.65	0.30	0.30	0.35	0.20	0.50	0.30	0.30	0.50	0.50	0.20	0.50	1	1	1	0	1
7	13,08	8,746191114	1,133310725	7	0.35	0.07	0.56	0.35	0.90	0.65	0.30	0.30	0.35	0.20	0.50	0.30	0.30	0.50	0.50	0.20	0.50	1	1	1	0	1
8	13,08	8,746191859	1,13327973	7	0.32	0.07	0.56	0.35	0.90	0.65	0.30	0.30	0.35	0.20	0.50	0.30	0.30	0.50	0.50	0.20	0.50	1	1	1	0	1
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Run/Drivers	TravelTime (s)	LaneOffset (cm)	Total Fitness Function	Best driver	DesiredVelocity	DesiredAcceleration	DesiredDeceleration	CurveBehavior	ObserveSpeedLimits	DistanceKeeping	LaneKeeping	SpeedKeeping	LaneChangingDynamic	UrgeToOvertake	RespondToTailgatingVehicles	ForesightDistance	SteeringDistance	ObserveKeepRightRule	Consider Env Conditions	UseOfIndicator	ReactionTime	ObeyTrafficSigns	ObeyTrafficLights	ObeyTrafficRules	Swarm	RouteAdherence
1	13,08	8,760762215	0,466321822	1	0.40	0.35	0.65	0.35	0.90	0.65	0.30	0.30	0.35	0.20	0.50	0.30	0.30	0.50	0.50	0.20	0.50	1	1	1	0	1
2	13,08	8,760356158	0,477488613	2	0.40	0.33	0.65	0.35	0.90	0.65	0.30	0.30	0.35	0.20	0.50	0.30	0.30	0.50	0.50	0.20	0.50	1	1	1	0	1
3	13,08	8,746193349	1,17094844	3	0.40	0.07	0.65	0.35	0.90	0.65	0.30	0.30	0.35	0.20	0.50	0.30	0.30	0.50	0.50	0.20	0.50	1	1	1	0	1
4	13,08	8,746193349	1,17094844	3	0.33	0.07	0.65	0.35	0.90	0.65	0.30	0.30	0.35	0.20	0.50	0.30	0.30	0.50	0.50	0.20	0.50	1	1	1	0	1
5	13,08	8,746191859	1,171007751	5	0.40	0.07	0.56	0.35	0.90	0.65	0.30	0.30	0.35	0.20	0.50	0.30	0.30	0.50	0.50	0.20	0.50	1	1	1	0	1
6	12,56	8,761464804	1,084707109	5	0.40	0.39	0.56	0.35	0.90	0.65	0.30	0.30	0.35	0.20	0.50	0.30	0.30	0.50	0.50	0.20	0.50	1	1	1	0	1
7	13,08	8,746191114	1,171037403	7	0.35	0.07	0.56	0.35	0.90	0.65	0.30	0.30	0.35	0.20	0.50	0.30	0.30	0.50	0.50	0.20	0.50	1	1	1	0	1
8	13,08	8,746191859	1,171007751	7	0.32	0.07	0.56	0.35	0.90	0.65	0.30	0.30	0.35	0.20	0.50	0.30	0.30	0.50	0.50	0.20	0.50	1	1	1	0	1
9	13,08	8,756010234	0,649127614	7	0.35	0.19	0.56	0.35	0.90	0.65	0.30	0.30	0.35	0.20	0.50	0.30	0.30	0.50	0.50	0.20	0.50	1	1	1	0	1
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Run/Drivers	TravelTime (s)	LaneOffset (cm)	Total Fitness Function	Best driver	DesiredVelocity	DesiredAcceleration	DesiredDeceleration	CurveBehavior	ObserveSpeedLimits	DistanceKeeping	LaneKeeping	SpeedKeeping	LaneChangingDynamic	UrgeToOvertake	RespondToTailgatingVehicles	ForesightDistance	SteeringDistance	ObserveKeepRightRule	ConsiderEnvConditions	UseOfIndicator	ReactionTime	ObeyTrafficSigns	ObeyTrafficLights	ObeyTrafficRules	Swarm	RouteAdherence
1	13,08	8,760762215	0,701038564	1	0.40	0.35	0.65	0.35	0.90	0.65	0.30	0.30	0.35	0.20	0.50	0.30	0.30	0.50	0.50	0.20	0.50	1	1	1	0	1
2	13,08	8,760356158	0,70794413	2	0.40	0.33	0.65	0.35	0.90	0.65	0.30	0.30	0.35	0.20	0.50	0.30	0.30	0.50	0.50	0.20	0.50	1	1	1	0	1
3	13,08	8,746193349	1,010048662	3	0.40	0.07	0.65	0.35	0.90	0.65	0.30	0.30	0.35	0.20	0.50	0.30	0.30	0.50	0.50	0.20	0.50	1	1	1	0	1
4	13,08	8,746193349	1,010048662	3	0.33	0.07	0.65	0.35	0.90	0.65	0.30	0.30	0.35	0.20	0.50	0.30	0.30	0.50	0.50	0.20	0.50	1	1	1	0	1
5	13,08	8,746191859	1,010083552	5	0.40	0.07	0.56	0.35	0.90	0.65	0.30	0.30	0.35	0.20	0.50	0.30	0.30	0.50	0.50	0.20	0.50	1	1	1	0	1
6	12,56	8,761464804	1,185984278	5	0.40	0.39	0.56	0.35	0.90	0.65	0.30	0.30	0.35	0.20	0.50	0.30	0.30	0.50	0.50	0.20	0.50	1	1	1	0	1
7	13,08	8,746191114	1,010100997	7	0.35	0.07	0.56	0.35	0.90	0.65	0.30	0.30	0.35	0.20	0.50	0.30	0.30	0.50	0.50	0.20	0.50	1	1	1	0	1
8	13,08	8,746191859	1,010083552	7	0.32	0.07	0.56	0.35	0.90	0.65	0.30	0.30	0.35	0.20	0.50	0.30	0.30	0.50	0.50	0.20	0.50	1	1	1	0	1
9	13,08	8,756010234	0,789668465	7	0.35	0.19	0.56	0.35	0.90	0.65	0.30	0.30	0.35	0.20	0.50	0.30	0.30	0.50	0.50	0.20	0.50	1	1	1	0	1
10	13,56	8,699711412	1,012494564	10	0.15	0.07	0.56	0.35	0.90	0.65	0.30	0.30	0.35	0.20	0.50	0.30	0.30	0.50	0.50	0.20	0.50	1	1	1	0	1
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Run/Drivers	TraveITime (s)	LaneOffset (cm)	Total Fitness Function	Best driver	DesiredVelocity	DesiredAcceleration	DesiredDeceleration	CurveBehavior	ObserveSpeedLimits	DistanceKeeping	LaneKeeping	SpeedKeeping	LaneChangingDynamic	UrgeToOvertake	RespondToTailgatingVehicles	ForesightDistance	SteeringDistance	ObserveKeepRightRule	Consider Env Conditions	UseOfIndicator	ReactionTime	ObeyTrafficSigns	ObeyTrafficLights	ObeyTrafficRules	Swarm	RouteAdherence
1	13,08	8,760762215	0,688961604	1	0.40	0.35	0.65	0.35	0.90	0.65	0.30	0.30	0.35	0.20	0.50	0.30	0.30	0.50	0.50	0.20	0.50	1	1	1	0	1
2	13,08	8,760356158	0,694310037	2	0.40	0.33	0.65	0.35	0.90	0.65	0.30	0.30	0.35	0.20	0.50	0.30	0.30	0.50	0.50	0.20	0.50	1	1	1	0	1
3	13,08	8,746193349	0,926433717	3	0.40	0.07	0.65	0.35	0.90	0.65	0.30	0.30	0.35	0.20	0.50	0.30	0.30	0.50	0.50	0.20	0.50	1	1	1	0	1
4	13,08	8,746193349	0,926433717	3	0.33	0.07	0.65	0.35	0.90	0.65	0.30	0.30	0.35	0.20	0.50	0.30	0.30	0.50	0.50	0.20	0.50	1	1	1	0	1
5	13,08	8,746191859	0,926461425	5	0.40	0.07	0.56	0.35	0.90	0.65	0.30	0.30	0.35	0.20	0.50	0.30	0.30	0.50	0.50	0.20	0.50	1	1	1	0	1
6	12,56	8,761464804	1,178961086	5	0.40	0.39	0.56	0.35	0.90	0.65	0.30	0.30	0.35	0.20	0.50	0.30	0.30	0.50	0.50	0.20	0.50	1	1	1	0	1
7	13,08	8,746191114	0,926475279	7	0.35	0.07	0.56	0.35	0.90	0.65	0.30	0.30	0.35	0.20	0.50	0.30	0.30	0.50	0.50	0.20	0.50	1	1	1	0	1
8	13,08	8,746191859	0,926461425	7	0.32	0.07	0.56	0.35	0.90	0.65	0.30	0.30	0.35	0.20	0.50	0.30	0.30	0.50	0.50	0.20	0.50	1	1	1	0	1
9	13,08	8,756010234	0,756821904	7	0.35	0.19	0.56	0.35	0.90	0.65	0.30	0.30	0.35	0.20	0.50	0.30	0.30	0.50	0.50	0.20	0.50	1	1	1	0	1
10	13,56	8,699711412	0,990476201	10	0.15	0.07	0.56	0.35	0.90	0.65	0.30	0.30	0.35	0.20	0.50	0.30	0.30	0.50	0.50	0.20	0.50	1	1	1	0	1
11	13,08	8,699733764	1,471926789	11	0.15	0.07	0.21	0.35	0.90	0.65	0.30	0.30	0.35	0.20	0.50	0.30	0.30	0.50	0.50	0.20	0.50	1	1	1	0	1

Run/Drivers	TravelTime (s)	LaneOffset (cm)	Total Fitness Function	Best driver	DesiredVelocity	DesiredAcceleration	DesiredDeceleration	CurveBehavior	ObserveSpeedLimits	DistanceKeeping	LaneKeeping	SpeedKeeping	LaneChangingDynamic	UrgeToOvertake	RespondToTailgatingVehicles	ForesightDistance	SteeringDistance	ObserveKeepRightRule	Consider Env Conditions	UseOfIndicator	ReactionTime	ObeyTrafficSigns	ObeyTrafficLights	ObeyTrafficRules	Swarm	RouteAdherence
1	13,08	8,760762215	0,683103404	1	0.40	0.35	0.65	0.35	0.90	0.65	0.30	0.30	0.35	0.20	0.50	0.30	0.30	0.50	0.50	0.20	0.50	1	1	1	0	1
2	13,08	8,760356158	0,688578528	2	0.40	0.33	0.65	0.35	0.90	0.65	0.30	0.30	0.35	0.20	0.50	0.30	0.30	0.50	0.50	0.20	0.50	1	1	1	0	1
3	13,08	8,746193349	0,929604107	3	0.40	0.07	0.65	0.35	0.90	0.65	0.30	0.30	0.35	0.20	0.50	0.30	0.30	0.50	0.50	0.20	0.50	1	1	1	0	1
4	13,08	8,746193349	0,929604107	3	0.33	0.07	0.65	0.35	0.90	0.65	0.30	0.30	0.35	0.20	0.50	0.30	0.30	0.50	0.50	0.20	0.50	1	1	1	0	1
5	13,08	8,746191859	0,929633048	5	0.40	0.07	0.56	0.35	0.90	0.65	0.30	0.30	0.35	0.20	0.50	0.30	0.30	0.50	0.50	0.20	0.50	1	1	1	0	1
6	12,56	8,761464804	1,174653982	5	0.40	0.39	0.56	0.35	0.90	0.65	0.30	0.30	0.35	0.20	0.50	0.30	0.30	0.50	0.50	0.20	0.50	1	1	1	0	1
7	13,08	8,746191114	0,929647519	7	0.35	0.07	0.56	0.35	0.90	0.65	0.30	0.30	0.35	0.20	0.50	0.30	0.30	0.50	0.50	0.20	0.50	1	1	1	0	1
8	13,08	8,746191859	0,929633048	7	0.32	0.07	0.56	0.35	0.90	0.65	0.30	0.30	0.35	0.20	0.50	0.30	0.30	0.50	0.50	0.20	0.50	1	1	1	0	1
9	13,08	8,756010234	0,752963862	7	0.35	0.19	0.56	0.35	0.90	0.65	0.30	0.30	0.35	0.20	0.50	0.30	0.30	0.50	0.50	0.20	0.50	1	1	1	0	1
10	13,56	8,699711412	0,992461237	10	0.15	0.07	0.56	0.35	0.90	0.65	0.30	0.30	0.35	0.20	0.50	0.30	0.30	0.50	0.50	0.20	0.50	1	1	1	0	1
11	13,08	8,699733764	1,476921421	11	0.15	0.07	0.21	0.35	0.90	0.65	0.30	0.30	0.35	0.20	0.50	0.30	0.30	0.50	0.50	0.20	0.50	1	1	1	0	1
12	13,08	8,746186644	0,929734344	11	0.22	0.07	0.21	0.35	0.90	0.65	0.30	0.30	0.35	0.20	0.50	0.30	0.30	0.50	0.50	0.20	0.50	1	1	1	0	1

Run/Drivers	TravelTime (s)	LaneOffset (cm)	Total Fitness Function	Best driver	DesiredVelocity	DesiredAcceleration	DesiredDeceleration	CurveBehavior	ObserveSpeedLimits	DistanceKeeping	LaneKeeping	SpeedKeeping	LaneChangingDynamic	UrgeToOvertake	RespondToTailgatingVehicles	ForesightDistance	SteeringDistance	ObserveKeepRightRule	Consider Env Conditions	UseOfIndicator	ReactionTime	ObeyTrafficSigns	ObeyTrafficLights	ObeyTrafficRules	Swarm	RouteAdherence
1	13,08	8,760762215	0,674940192	1	0.40	0.35	0.65	0.35	0.90	0.65	0.30	0.30	0.35	0.20	0.50	0.30	0.30	0.50	0.50	0.20	0.50	1	1	1	0	1
2	13,08	8,760356158	0,679603848	2	0.40	0.33	0.65	0.35	0.90	0.65	0.30	0.30	0.35	0.20	0.50	0.30	0.30	0.50	0.50	0.20	0.50	1	1	1	0	1
3	13,08	8,746193349	0,885541966	3	0.40	0.07	0.65	0.35	0.90	0.65	0.30	0.30	0.35	0.20	0.50	0.30	0.30	0.50	0.50	0.20	0.50	1	1	1	0	1
4	13,08	8,746193349	0,885541966	3	0.33	0.07	0.65	0.35	0.90	0.65	0.30	0.30	0.35	0.20	0.50	0.30	0.30	0.50	0.50	0.20	0.50	1	1	1	0	1
5	13,08	8,746191859	0,88556715	5	0.40	0.07	0.56	0.35	0.90	0.65	0.30	0.30	0.35	0.20	0.50	0.30	0.30	0.50	0.50	0.20	0.50	1	1	1	0	1
6	12,56	8,761464804	1,162971387	5	0.40	0.39	0.56	0.35	0.90	0.65	0.30	0.30	0.35	0.20	0.50	0.30	0.30	0.50	0.50	0.20	0.50	1	1	1	0	1
7	13,08	8,746191114	0,885579742	7	0.35	0.07	0.56	0.35	0.90	0.65	0.30	0.30	0.35	0.20	0.50	0.30	0.30	0.50	0.50	0.20	0.50	1	1	1	0	1
8	13,08	8,746191859	0,88556715	7	0.32	0.07	0.56	0.35	0.90	0.65	0.30	0.30	0.35	0.20	0.50	0.30	0.30	0.50	0.50	0.20	0.50	1	1	1	0	1
9	13,08	8,756010234	0,734284344	7	0.35	0.19	0.56	0.35	0.90	0.65	0.30	0.30	0.35	0.20	0.50	0.30	0.30	0.50	0.50	0.20	0.50	1	1	1	0	1
10	13,56	8,699711412	0,96838378	10	0.15	0.07	0.56	0.35	0.90	0.65	0.30	0.30	0.35	0.20	0.50	0.30	0.30	0.50	0.50	0.20	0.50	1	1	1	0	1
11	13,08	8,699733764	1,460990824	11	0.15	0.07	0.21	0.35	0.90	0.65	0.30	0.30	0.35	0.20	0.50	0.30	0.30	0.50	0.50	0.20	0.50	1	1	1	0	1
12	13,08	8,746186644	0,885655297	11	0.22	0.07	0.21	0.35	0.90	0.65	0.30	0.30	0.35	0.20	0.50	0.30	0.30	0.50	0.50	0.20	0.50	1	1	1	0	1
13	13,12	8,699740469	1,380348458	11	0.15	0.07	0.13	0.35	0.90	0.65	0.30	0.30	0.35	0.20	0.50	0.30	0.30	0.50	0.50	0.20	0.50	1	1	1	0	1

Run/Drivers	TravelTime (s)	LaneOffset (cm)	Total Fitness Function	Best driver	DesiredVelocity	DesiredAcceleration	DesiredDeceleration	CurveBehavior	ObserveSpeedLimits	DistanceKeeping	LaneKeeping	SpeedKeeping	LaneChangingDynamic	UrgeToOvertake	RespondToTailgatingVehicles	ForesightDistance	SteeringDistance	ObserveKeepRightRule	ConsiderEnvConditions	UseOfIndicator	ReactionTime	ObeyTrafficSigns	ObeyTrafficLights	ObeyTrafficRules	Swarm	RouteAdherence
1	13,08	8,760762215	0,719909294	1	0.40	0.35	0.65	0.35	0.90	0.65	0.30	0.30	0.35	0.20	0.50	0.30	0.30	0.50	0.50	0.20	0.50	1	1	1	0	1
2	13,08	8,760356158	0,724037291	2	0.40	0.33	0.65	0.35	0.90	0.65	0.30	0.30	0.35	0.20	0.50	0.30	0.30	0.50	0.50	0.20	0.50	1	1	1	0	1
3	13,08	8,746193349	0,908009491	3	0.40	0.07	0.65	0.35	0.90	0.65	0.30	0.30	0.35	0.20	0.50	0.30	0.30	0.50	0.50	0.20	0.50	1	1	1	0	1
4	13,08	8,746193349	0,908009491	3	0.33	0.07	0.65	0.35	0.90	0.65	0.30	0.30	0.35	0.20	0.50	0.30	0.30	0.50	0.50	0.20	0.50	1	1	1	0	1
5	13,08	8,746191859	0,908032338	5	0.40	0.07	0.56	0.35	0.90	0.65	0.30	0.30	0.35	0.20	0.50	0.30	0.30	0.50	0.50	0.20	0.50	1	1	1	0	1
6	12,56	8,761464804	1,14555665	5	0.40	0.39	0.56	0.35	0.90	0.65	0.30	0.30	0.35	0.20	0.50	0.30	0.30	0.50	0.50	0.20	0.50	1	1	1	0	1
7	13,08	8,746191114	0,908043761	7	0.35	0.07	0.56	0.35	0.90	0.65	0.30	0.30	0.35	0.20	0.50	0.30	0.30	0.50	0.50	0.20	0.50	1	1	1	0	1
8	13,08	8,746191859	0,908032338	7	0.32	0.07	0.56	0.35	0.90	0.65	0.30	0.30	0.35	0.20	0.50	0.30	0.30	0.50	0.50	0.20	0.50	1	1	1	0	1
9	13,08	8,756010234	0,772485035	7	0.35	0.19	0.56	0.35	0.90	0.65	0.30	0.30	0.35	0.20	0.50	0.30	0.30	0.50	0.50	0.20	0.50	1	1	1	0	1
10	13,56	8,699711412	0,962272847	10	0.15	0.07	0.56	0.35	0.90	0.65	0.30	0.30	0.35	0.20	0.50	0.30	0.30	0.50	0.50	0.20	0.50	1	1	1	0	1
11	13,08	8,699733764	1,498001895	11	0.15	0.07	0.21	0.35	0.90	0.65	0.30	0.30	0.35	0.20	0.50	0.30	0.30	0.50	0.50	0.20	0.50	1	1	1	0	1
12	13,08	8,746186644	0,908112306	11	0.22	0.07	0.21	0.35	0.90	0.65	0.30	0.30	0.35	0.20	0.50	0.30	0.30	0.50	0.50	0.20	0.50	1	1	1	0	1
13	13,12	8,699740469	1,427653395	11	0.15	0.07	0.13	0.35	0.90	0.65	0.30	0.30	0.35	0.20	0.50	0.30	0.30	0.50	0.50	0.20	0.50	1	1	1	0	1
14	13,56	8,699729294	0,962181984	11	0.15	0.07	0.28	0.35	0.90	0.65	0.30	0.30	0.35	0.20	0.50	0.30	0.30	0.50	0.50	0.20	0.50	1	1	1	0	1

Run/Drivers	TravelTime (s)	LaneOffset (cm)	Total Fitness Function	Best driver	DesiredVelocity	DesiredAcceleration	DesiredDeceleration	CurveBehavior	ObserveSpeedLimits	DistanceKeeping	LaneKeeping	SpeedKeeping	LaneChangingDynamic	UrgeToOvertake	RespondToTailgatingVehicles	ForesightDistance	SteeringDistance	ObserveKeepRightRule	Consider Env Conditions	UseOfIndicator	ReactionTime	ObeyTrafficSigns	ObeyTrafficLights	ObeyTrafficRules	Swarm	RouteAdherence
1	13,08	8,760762215	0,704087615	1	0.40	0.35	0.65	0.35	0.90	0.65	0.30	0.30	0.35	0.20	0.50	0.30	0.30	0.50	0.50	0.20	0.50	1	1	1	0	1
2	13,08	8,760356158	0,707801645	2	0.40	0.33	0.65	0.35	0.90	0.65	0.30	0.30	0.35	0.20	0.50	0.30	0.30	0.50	0.50	0.20	0.50	1	1	1	0	1
3	13,08	8,746193349	0,874911347	3	0.40	0.07	0.65	0.35	0.90	0.65	0.30	0.30	0.35	0.20	0.50	0.30	0.30	0.50	0.50	0.20	0.50	1	1	1	0	1
4	13,08	8,746193349	0,874911347	3	0.33	0.07	0.65	0.35	0.90	0.65	0.30	0.30	0.35	0.20	0.50	0.30	0.30	0.50	0.50	0.20	0.50	1	1	1	0	1
5	13,08	8,746191859	0,874932371	5	0.40	0.07	0.56	0.35	0.90	0.65	0.30	0.30	0.35	0.20	0.50	0.30	0.30	0.50	0.50	0.20	0.50	1	1	1	0	1
6	12,56	8,761464804	1,133842133	5	0.40	0.39	0.56	0.35	0.90	0.65	0.30	0.30	0.35	0.20	0.50	0.30	0.30	0.50	0.50	0.20	0.50	1	1	1	0	1
7	13,08	8,746191114	0,874942883	7	0.35	0.07	0.56	0.35	0.90	0.65	0.30	0.30	0.35	0.20	0.50	0.30	0.30	0.50	0.50	0.20	0.50	1	1	1	0	1
8	13,08	8,746191859	0,874932371	7	0.32	0.07	0.56	0.35	0.90	0.65	0.30	0.30	0.35	0.20	0.50	0.30	0.30	0.50	0.50	0.20	0.50	1	1	1	0	1
9	13,08	8,756010234	0,751466691	7	0.35	0.19	0.56	0.35	0.90	0.65	0.30	0.30	0.35	0.20	0.50	0.30	0.30	0.50	0.50	0.20	0.50	1	1	1	0	1
10	13,56	8,699711412	0,934122233	10	0.15	0.07	0.56	0.35	0.90	0.65	0.30	0.30	0.35	0.20	0.50	0.30	0.30	0.50	0.50	0.20	0.50	1	1	1	0	1
11	13,08	8,699733764	1,471891755	11	0.15	0.07	0.21	0.35	0.90	0.65	0.30	0.30	0.35	0.20	0.50	0.30	0.30	0.50	0.50	0.20	0.50	1	1	1	0	1
12	13,08	8,746186644	0,87500596	11	0.22	0.07	0.21	0.35	0.90	0.65	0.30	0.30	0.35	0.20	0.50	0.30	0.30	0.50	0.50	0.20	0.50	1	1	1	0	1
13	13,12	8,699740469	1,399094421	11	0.15	0.07	0.13	0.35	0.90	0.65	0.30	0.30	0.35	0.20	0.50	0.30	0.30	0.50	0.50	0.20	0.50	1	1	1	0	1
14	13,56	8,699729294	0,934010827	11	0.15	0.07	0.28	0.35	0.90	0.65	0.30	0.30	0.35	0.20	0.50	0.30	0.30	0.50	0.50	0.20	0.50	1	1	1	0	1
15	13,08	8,697737008	1,483680871	15	0.15	0.06	0.21	0.35	0.90	0.65	0.30	0.30	0.35	0.20	0.50	0.30	0.30	0.50	0.50	0.20	0.50	1	1	1	0	1
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Run/Drivers	TravelTime (s)	LaneOffset (cm)	Total Fitness Function	Best driver	DesiredVelocity	DesiredAcceleration	DesiredDeceleration	CurveBehavior	ObserveSpeedLimits	DistanceKeeping	LaneKeeping	SpeedKeeping	LaneChangingDynamic	UrgeToOvertake	RespondToTailgatingVehicles	ForesightDistance	SteeringDistance	ObserveKeepRightRule	Consider Env Conditions	UseOfIndicator	ReactionTime	ObeyTrafficSigns	ObeyTrafficLights	ObeyTrafficRules	Swarm	RouteAdherence
1	13,08	8,760762215	0,689439082	1	0.40	0.35	0.65	0.35	0.90	0.65	0.30	0.30	0.35	0.20	0.50	0.30	0.30	0.50	0.50	0.20	0.50	1	1	1	0	1
2	13,08	8,760356158	0,692829704	2	0.40	0.33	0.65	0.35	0.90	0.65	0.30	0.30	0.35	0.20	0.50	0.30	0.30	0.50	0.50	0.20	0.50	1	1	1	0	1
3	13,08	8,746193349	0,847155019	3	0.40	0.07	0.65	0.35	0.90	0.65	0.30	0.30	0.35	0.20	0.50	0.30	0.30	0.50	0.50	0.20	0.50	1	1	1	0	1
4	13,08	8,746193349	0,847155019	3	0.33	0.07	0.65	0.35	0.90	0.65	0.30	0.30	0.35	0.20	0.50	0.30	0.30	0.50	0.50	0.20	0.50	1	1	1	0	1
5	13,08	8,746191859	0,84717468	5	0.40	0.07	0.56	0.35	0.90	0.65	0.30	0.30	0.35	0.20	0.50	0.30	0.30	0.50	0.50	0.20	0.50	1	1	1	0	1
6	12,56	8,761464804	1,122695424	5	0.40	0.39	0.56	0.35	0.90	0.65	0.30	0.30	0.35	0.20	0.50	0.30	0.30	0.50	0.50	0.20	0.50	1	1	1	0	1
7	13,08	8,746191114	0,84718451	7	0.35	0.07	0.56	0.35	0.90	0.65	0.30	0.30	0.35	0.20	0.50	0.30	0.30	0.50	0.50	0.20	0.50	1	1	1	0	1
8	13,08	8,746191859	0,84717468	7	0.32	0.07	0.56	0.35	0.90	0.65	0.30	0.30	0.35	0.20	0.50	0.30	0.30	0.50	0.50	0.20	0.50	1	1	1	0	1
9	13,08	8,756010234	0,732806893	7	0.35	0.19	0.56	0.35	0.90	0.65	0.30	0.30	0.35	0.20	0.50	0.30	0.30	0.50	0.50	0.20	0.50	1	1	1	0	1
10	13,56	8,699711412	0,909042424	10	0.15	0.07	0.56	0.35	0.90	0.65	0.30	0.30	0.35	0.20	0.50	0.30	0.30	0.50	0.50	0.20	0.50	1	1	1	0	1
11	13,08	8,699733764	1,448328113	11	0.15	0.07	0.21	0.35	0.90	0.65	0.30	0.30	0.35	0.20	0.50	0.30	0.30	0.50	0.50	0.20	0.50	1	1	1	0	1
12	13,08	8,746186644	0,847243498	11	0.22	0.07	0.21	0.35	0.90	0.65	0.30	0.30	0.35	0.20	0.50	0.30	0.30	0.50	0.50	0.20	0.50	1	1	1	0	1
13	13,12	8,699740469	1,373166331	11	0.15	0.07	0.13	0.35	0.90	0.65	0.30	0.30	0.35	0.20	0.50	0.30	0.30	0.50	0.50	0.20	0.50	1	1	1	0	1
14	13,56	8,699729294	0,90891481	11	0.15	0.07	0.28	0.35	0.90	0.65	0.30	0.30	0.35	0.20	0.50	0.30	0.30	0.50	0.50	0.20	0.50	1	1	1	0	1
15	13,08	8,697737008	1,461917327	15	0.15	0.06	0.21	0.35	0.90	0.65	0.30	0.30	0.35	0.20	0.50	0.30	0.30	0.50	0.50	0.20	0.50	1	1	1	0	1
16	13,08	8,697715402	1,462057137	16	0.15	0.06	0.57	0.35	0.90	0.65	0.30	0.30	0.35	0.20	0.50	0.30	0.30	0.50	0.50	0.20	0.50	1	1	1	0	1
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Run/Drivers	TravelTime (s)	LaneOffset (cm)	Total Fitness Function	Best driver	DesiredVelocity	DesiredAcceleration	DesiredDeceleration	CurveBehavior	ObserveSpeedLimits	DistanceKeeping	LaneKeeping	SpeedKeeping	LaneChangingDynamic	UrgeToOvertake	RespondToTailgatingVehicles	ForesightDistance	SteeringDistance	ObserveKeepRightRule	Consider Env Conditions	UseOfIndicator	ReactionTime	ObeyTrafficSigns	ObeyTrafficLights	ObeyTrafficRules	Swarm	RouteAdherence
1	13,08	8,760762215	0,953354059	1	0.40	0.35	0.65	0.35	0.90	0.65	0.30	0.30	0.35	0.20	0.50	0.30	0.30	0.50	0.50	0.20	0.50	1	1	1	0	1
2	13,08	8,760356158	0,954105272	2	0.40	0.33	0.65	0.35	0.90	0.65	0.30	0.30	0.35	0.20	0.50	0.30	0.30	0.50	0.50	0.20	0.50	1	1	1	0	1
3	13,08	8,746193349	0,980661104	3	0.40	0.07	0.65	0.35	0.90	0.65	0.30	0.30	0.35	0.20	0.50	0.30	0.30	0.50	0.50	0.20	0.50	1	1	1	0	1
4	13,08	8,746193349	0,980661104	3	0.33	0.07	0.65	0.35	0.90	0.65	0.30	0.30	0.35	0.20	0.50	0.30	0.30	0.50	0.50	0.20	0.50	1	1	1	0	1
5	13,08	8,746191859	0,980663932	5	0.40	0.07	0.56	0.35	0.90	0.65	0.30	0.30	0.35	0.20	0.50	0.30	0.30	0.50	0.50	0.20	0.50	1	1	1	0	1
6	12,56	8,761464804	1,087428822	5	0.40	0.39	0.56	0.35	0.90	0.65	0.30	0.30	0.35	0.20	0.50	0.30	0.30	0.50	0.50	0.20	0.50	1	1	1	0	1
7	13,08	8,746191114	0,980665347	7	0.35	0.07	0.56	0.35	0.90	0.65	0.30	0.30	0.35	0.20	0.50	0.30	0.30	0.50	0.50	0.20	0.50	1	1	1	0	1
8	13,08	8,746191859	0,980663932	7	0.32	0.07	0.56	0.35	0.90	0.65	0.30	0.30	0.35	0.20	0.50	0.30	0.30	0.50	0.50	0.20	0.50	1	1	1	0	1
9	13,08	8,756010234	0,962182149	7	0.35	0.19	0.56	0.35	0.90	0.65	0.30	0.30	0.35	0.20	0.50	0.30	0.30	0.50	0.50	0.20	0.50	1	1	1	0	1
10	13,56	8,699711412	0,933268522	10	0.15	0.07	0.56	0.35	0.90	0.65	0.30	0.30	0.35	0.20	0.50	0.30	0.30	0.50	0.50	0.20	0.50	1	1	1	0	1
11	13,08	8,699733764	1,071366181	11	0.15	0.07	0.21	0.35	0.90	0.65	0.30	0.30	0.35	0.20	0.50	0.30	0.30	0.50	0.50	0.20	0.50	1	1	1	0	1
12	13,08	8,746186644	0,980673831	11	0.22	0.07	0.21	0.35	0.90	0.65	0.30	0.30	0.35	0.20	0.50	0.30	0.30	0.50	0.50	0.20	0.50	1	1	1	0	1
13	13,12	8,699740469	1,060101979	11	0.15	0.07	0.13	0.35	0.90	0.65	0.30	0.30	0.35	0.20	0.50	0.30	0.30	0.50	0.50	0.20	0.50	1	1	1	0	1
14	13,56	8,699729294	0,93323294	11	0.15	0.07	0.28	0.35	0.90	0.65	0.30	0.30	0.35	0.20	0.50	0.30	0.30	0.50	0.50	0.20	0.50	1	1	1	0	1
15	13,08	8,697737008	1,07534116	15	0.15	0.06	0.21	0.35	0.90	0.65	0.30	0.30	0.35	0.20	0.50	0.30	0.30	0.50	0.50	0.20	0.50	1	1	1	0	1
16	13,08	8,697715402	1,075384191	16	0.15	0.06	0.57	0.35	0.90	0.65	0.30	0.30	0.35	0.20	0.50	0.30	0.30	0.50	0.50	0.20	0.50	1	1	1	0	1
17	18,88	7,889828086	1,000002044	16	0.09	0.06	0.57	0.35	0.90	0.65	0.30	0.30	0.35	0.20	0.50	0.30	0.30	0.50	0.50	0.20	0.50	1	1	1	0	1

Run/Drivers	TravelTime (s)	LaneOffset (cm)	Total Fitness Function	Best driver	DesiredVelocity	DesiredAcceleration	DesiredDeceleration	CurveBehavior	ObserveSpeedLimits	DistanceKeeping	LaneKeeping	SpeedKeeping	LaneChangingDynamic	UrgeToOvertake	RespondToTailgatingVehicles	ForesightDistance	SteeringDistance	ObserveKeepRightRule	ConsiderEnvConditions	UseOfIndicator	ReactionTime	ObeyTrafficSigns	ObeyTrafficLights	ObeyTrafficRules	Swarm	RouteAdherence
1	13,08	8,760762215	0,950690734	1	0.40	0.35	0.65	0.35	0.90	0.65	0.30	0.30	0.35	0.20	0.50	0.30	0.30	0.50	0.50	0.20	0.50	1	1	1	0	1
2	13,08	8,760356158	0,951463143	2	0.40	0.33	0.65	0.35	0.90	0.65	0.30	0.30	0.35	0.20	0.50	0.30	0.30	0.50	0.50	0.20	0.50	1	1	1	0	1
3	13,08	8,746193349	0,978776474	3	0.40	0.07	0.65	0.35	0.90	0.65	0.30	0.30	0.35	0.20	0.50	0.30	0.30	0.50	0.50	0.20	0.50	1	1	1	0	1
4	13,08	8,746193349	0,978776474	3	0.33	0.07	0.65	0.35	0.90	0.65	0.30	0.30	0.35	0.20	0.50	0.30	0.30	0.50	0.50	0.20	0.50	1	1	1	0	1
5	13,08	8,746191859	0,978779384	5	0.40	0.07	0.56	0.35	0.90	0.65	0.30	0.30	0.35	0.20	0.50	0.30	0.30	0.50	0.50	0.20	0.50	1	1	1	0	1
6	12,56	8,761464804	1,088527211	5	0.40	0.39	0.56	0.35	0.90	0.65	0.30	0.30	0.35	0.20	0.50	0.30	0.30	0.50	0.50	0.20	0.50	1	1	1	0	1
7	13,08	8,746191114	0,978780838	7	0.35	0.07	0.56	0.35	0.90	0.65	0.30	0.30	0.35	0.20	0.50	0.30	0.30	0.50	0.50	0.20	0.50	1	1	1	0	1
8	13,08	8,746191859	0,978779384	7	0.32	0.07	0.56	0.35	0.90	0.65	0.30	0.30	0.35	0.20	0.50	0.30	0.30	0.50	0.50	0.20	0.50	1	1	1	0	1
9	13,08	8,756010234	0,95976882	7	0.35	0.19	0.56	0.35	0.90	0.65	0.30	0.30	0.35	0.20	0.50	0.30	0.30	0.50	0.50	0.20	0.50	1	1	1	0	1
10	13,56	8,699711412	0,930168313	10	0.15	0.07	0.56	0.35	0.90	0.65	0.30	0.30	0.35	0.20	0.50	0.30	0.30	0.50	0.50	0.20	0.50	1	1	1	0	1
11	13,08	8,699733764	1,072103795	11	0.15	0.07	0.21	0.35	0.90	0.65	0.30	0.30	0.35	0.20	0.50	0.30	0.30	0.50	0.50	0.20	0.50	1	1	1	0	1
12	13,08	8,746186644	0,978789567	11	0.22	0.07	0.21	0.35	0.90	0.65	0.30	0.30	0.35	0.20	0.50	0.30	0.30	0.50	0.50	0.20	0.50	1	1	1	0	1
13	13,12	8,699740469	1,060511672	11	0.15	0.07	0.13	0.35	0.90	0.65	0.30	0.30	0.35	0.20	0.50	0.30	0.30	0.50	0.50	0.20	0.50	1	1	1	0	1
14	13,56	8,699729294	0,930131716	11	0.15	0.07	0.28	0.35	0.90	0.65	0.30	0.30	0.35	0.20	0.50	0.30	0.30	0.50	0.50	0.20	0.50	1	1	1	0	1
15	13,08	8,697737008	1,076192008	15	0.15	0.06	0.21	0.35	0.90	0.65	0.30	0.30	0.35	0.20	0.50	0.30	0.30	0.50	0.50	0.20	0.50	1	1	1	0	1
16	13,08	8,697715402	1,076236262	16	0.15	0.06	0.57	0.35	0.90	0.65	0.30	0.30	0.35	0.20	0.50	0.30	0.30	0.50	0.50	0.20	0.50	1	1	1	0	1
17	18,88	7,889828086	1,000001272	16	0.09	0.06	0.57	0.35	0.90	0.65	0.30	0.30	0.35	0.20	0.50	0.30	0.30	0.50	0.50	0.20	0.50	1	1	1	0	1
18	13,08	8,724738657	1,021321084	16	0.15	0.53	0.57	0.35	0.90	0.65	0.30	0.30	0.35	0.20	0.50	0.30	0.30	0.50	0.50	0.20	0.50	1	1	1	0	1

Run/Drivers	TravelTime (s)	LaneOffset (cm)	Total Fitness Function	Best driver	DesiredVelocity	DesiredAcceleration	DesiredDeceleration	CurveBehavior	ObserveSpeedLimits	DistanceKeeping	LaneKeeping	SpeedKeeping	LaneChangingDynamic	UrgeToOvertake	RespondToTailgatingVehicles	ForesightDistance	SteeringDistance	ObserveKeepRightRule	Consider Env Conditions	UseOfIndicator	ReactionTime	ObeyTrafficSigns	ObeyTrafficLights	ObeyTrafficRules	Swarm	RouteAdherence
1	13,08	8,760762215	0,9465773	1	0.40	0.35	0.65	0.35	0.90	0.65	0.30	0.30	0.35	0.20	0.50	0.30	0.30	0.50	0.50	0.20	0.50	1	1	1	0	1
2	13,08	8,760356158	0,947369465	2	0.40	0.33	0.65	0.35	0.90	0.65	0.30	0.30	0.35	0.20	0.50	0.30	0.30	0.50	0.50	0.20	0.50	1	1	1	0	1
3	13,08	8,746193349	0,975394692	3	0.40	0.07	0.65	0.35	0.90	0.65	0.30	0.30	0.35	0.20	0.50	0.30	0.30	0.50	0.50	0.20	0.50	1	1	1	0	1
4	13,08	8,746193349	0,975394692	3	0.33	0.07	0.65	0.35	0.90	0.65	0.30	0.30	0.35	0.20	0.50	0.30	0.30	0.50	0.50	0.20	0.50	1	1	1	0	1
5	13,08	8,746191859	0,975397679	5	0.40	0.07	0.56	0.35	0.90	0.65	0.30	0.30	0.35	0.20	0.50	0.30	0.30	0.50	0.50	0.20	0.50	1	1	1	0	1
6	12,56	8,761464804	1,088057273	5	0.40	0.39	0.56	0.35	0.90	0.65	0.30	0.30	0.35	0.20	0.50	0.30	0.30	0.50	0.50	0.20	0.50	1	1	1	0	1
7	13,08	8,746191114	0,975399172	7	0.35	0.07	0.56	0.35	0.90	0.65	0.30	0.30	0.35	0.20	0.50	0.30	0.30	0.50	0.50	0.20	0.50	1	1	1	0	1
8	13,08	8,746191859	0,975397679	7	0.32	0.07	0.56	0.35	0.90	0.65	0.30	0.30	0.35	0.20	0.50	0.30	0.30	0.50	0.50	0.20	0.50	1	1	1	0	1
9	13,08	8,756010234	0,955888987	7	0.35	0.19	0.56	0.35	0.90	0.65	0.30	0.30	0.35	0.20	0.50	0.30	0.30	0.50	0.50	0.20	0.50	1	1	1	0	1
10	13,56	8,699711412	0,92560332	10	0.15	0.07	0.56	0.35	0.90	0.65	0.30	0.30	0.35	0.20	0.50	0.30	0.30	0.50	0.50	0.20	0.50	1	1	1	0	1
11	13,08	8,699733764	1,07125785	11	0.15	0.07	0.21	0.35	0.90	0.65	0.30	0.30	0.35	0.20	0.50	0.30	0.30	0.50	0.50	0.20	0.50	1	1	1	0	1
12	13,08	8,746186644	0,975408132	11	0.22	0.07	0.21	0.35	0.90	0.65	0.30	0.30	0.35	0.20	0.50	0.30	0.30	0.50	0.50	0.20	0.50	1	1	1	0	1
13	13,12	8,699740469	1,059346927	11	0.15	0.07	0.13	0.35	0.90	0.65	0.30	0.30	0.35	0.20	0.50	0.30	0.30	0.50	0.50	0.20	0.50	1	1	1	0	1
14	13,56	8,699729294	0,925565723	11	0.15	0.07	0.28	0.35	0.90	0.65	0.30	0.30	0.35	0.20	0.50	0.30	0.30	0.50	0.50	0.20	0.50	1	1	1	0	1
15	13,08	8,697737008	1,075457677	15	0.15	0.06	0.21	0.35	0.90	0.65	0.30	0.30	0.35	0.20	0.50	0.30	0.30	0.50	0.50	0.20	0.50	1	1	1	0	1
16	13,08	8,697715402	1,075503139	16	0.15	0.06	0.57	0.35	0.90	0.65	0.30	0.30	0.35	0.20	0.50	0.30	0.30	0.50	0.50	0.20	0.50	1	1	1	0	1
17	18,88	7,889828086	1,000000721	16	0.09	0.06	0.57	0.35	0.90	0.65	0.30	0.30	0.35	0.20	0.50	0.30	0.30	0.50	0.50	0.20	0.50	1	1	1	0	1
18	13,08	8,724738657	1,019085191	16	0.15	0.53	0.57	0.35	0.90	0.65	0.30	0.30	0.35	0.20	0.50	0.30	0.30	0.50	0.50	0.20	0.50	1	1	1	0	1
19	13,08	8,710406721	1,04887481	16	0.15	0.16	0.57	0.35	0.90	0.65	0.30	0.30	0.35	0.20	0.50	0.30	0.30	0.50	0.50	0.20	0.50	1	1	1	0	1

Run/Drivers	TravelTime (s)	LaneOffset (cm)	Total Fitness Function	Best driver	DesiredVelocity	DesiredAcceleration	DesiredDeceleration	CurveBehavior	ObserveSpeedLimits	DistanceKeeping	LaneKeeping	SpeedKeeping	LaneChangingDynamic	UrgeToOvertake	RespondToTailgatingVehicles	ForesightDistance	SteeringDistance	ObserveKeepRightRule	Consider Env Conditions	UseOfIndicator	ReactionTime	ObeyTrafficSigns	ObeyTrafficLights	ObeyTrafficRules	Swarm	RouteAdherence
1	13,08	8,760762215	0,94635071	1	0.40	0.35	0.65	0.35	0.90	0.65	0.30	0.30	0.35	0.20	0.50	0.30	0.30	0.50	0.50	0.20	0.50	1	1	1	0	1
2	13,08	8,760356158	0,947163595	2	0.40	0.33	0.65	0.35	0.90	0.65	0.30	0.30	0.35	0.20	0.50	0.30	0.30	0.50	0.50	0.20	0.50	1	1	1	0	1
3	13,08	8,746193349	0,975923396	3	0.40	0.07	0.65	0.35	0.90	0.65	0.30	0.30	0.35	0.20	0.50	0.30	0.30	0.50	0.50	0.20	0.50	1	1	1	0	1
4	13,08	8,746193349	0,975923396	3	0.33	0.07	0.65	0.35	0.90	0.65	0.30	0.30	0.35	0.20	0.50	0.30	0.30	0.50	0.50	0.20	0.50	1	1	1	0	1
5	13,08	8,746191859	0,975926461	5	0.40	0.07	0.56	0.35	0.90	0.65	0.30	0.30	0.35	0.20	0.50	0.30	0.30	0.50	0.50	0.20	0.50	1	1	1	0	1
6	12,56	8,761464804	1,091361142	5	0.40	0.39	0.56	0.35	0.90	0.65	0.30	0.30	0.35	0.20	0.50	0.30	0.30	0.50	0.50	0.20	0.50	1	1	1	0	1
7	13,08	8,746191114	0,975927994	7	0.35	0.07	0.56	0.35	0.90	0.65	0.30	0.30	0.35	0.20	0.50	0.30	0.30	0.50	0.50	0.20	0.50	1	1	1	0	1
8	13,08	8,746191859	0,975926461	7	0.32	0.07	0.56	0.35	0.90	0.65	0.30	0.30	0.35	0.20	0.50	0.30	0.30	0.50	0.50	0.20	0.50	1	1	1	0	1
9	13,08	8,756010234	0,955906205	7	0.35	0.19	0.56	0.35	0.90	0.65	0.30	0.30	0.35	0.20	0.50	0.30	0.30	0.50	0.50	0.20	0.50	1	1	1	0	1
10	13,56	8,699711412	0,924975438	10	0.15	0.07	0.56	0.35	0.90	0.65	0.30	0.30	0.35	0.20	0.50	0.30	0.30	0.50	0.50	0.20	0.50	1	1	1	0	1
11	13,08	8,699733764	1,074239435	11	0.15	0.07	0.21	0.35	0.90	0.65	0.30	0.30	0.35	0.20	0.50	0.30	0.30	0.50	0.50	0.20	0.50	1	1	1	0	1
12	13,08	8,746186644	0,975937189	11	0.22	0.07	0.21	0.35	0.90	0.65	0.30	0.30	0.35	0.20	0.50	0.30	0.30	0.50	0.50	0.20	0.50	1	1	1	0	1
13	13,12	8,699740469	1,062018129	11	0.15	0.07	0.13	0.35	0.90	0.65	0.30	0.30	0.35	0.20	0.50	0.30	0.30	0.50	0.50	0.20	0.50	1	1	1	0	1
14	13,56	8,699729294	0,924936921	11	0.15	0.07	0.28	0.35	0.90	0.65	0.30	0.30	0.35	0.20	0.50	0.30	0.30	0.50	0.50	0.20	0.50	1	1	1	0	1
15	13,08	8,697737008	1,078541787	15	0.15	0.06	0.21	0.35	0.90	0.65	0.30	0.30	0.35	0.20	0.50	0.30	0.30	0.50	0.50	0.20	0.50	1	1	1	0	1
16	13,08	8,697715402	1,078588355	16	0.15	0.06	0.57	0.35	0.90	0.65	0.30	0.30	0.35	0.20	0.50	0.30	0.30	0.50	0.50	0.20	0.50	1	1	1	0	1
17	18,88	7,889828086	1,000000434	16	0.09	0.06	0.57	0.35	0.90	0.65	0.30	0.30	0.35	0.20	0.50	0.30	0.30	0.50	0.50	0.20	0.50	1	1	1	0	1
18	13,08	8,724738657	1,020752027	16	0.15	0.53	0.57	0.35	0.90	0.65	0.30	0.30	0.35	0.20	0.50	0.30	0.30	0.50	0.50	0.20	0.50	1	1	1	0	1
19	13,08	8,710406721	1,051300776	16	0.15	0.16	0.57	0.35	0.90	0.65	0.30	0.30	0.35	0.20	0.50	0.30	0.30	0.50	0.50	0.20	0.50	1	1	1	0	1
20	13,08	8,744521439	0,979366976	16	0.32	0.06	0.57	0.35	0.90	0.65	0.30	0.30	0.35	0.20	0.50	0.30	0.30	0.50	0.50	0.20	0.50	1	1	1	0	1

Run/Drivers	TravelTime (s)	LaneOffset (cm)	Total Fitness Function	Best driver	DesiredVelocity	DesiredAcceleration	Desired Deceleration	CurveBehavior	ObserveSpeedLimits	DistanceKeeping	LaneKeeping	SpeedKeeping	LaneChangingDynamic	UrgeToOvertake	RespondToTailgatingVehicles	ForesightDistance	SteeringDistance	ObserveKeepRightRule	ConsiderEnvConditions	UseOfIndicator			ObeyTrafficLights	Swarm	RouteAdherence
1	13,08	8,760762215	0,701038564	1	0.40	0.35	0.65	0.35	0.90	0.65	0.30	0.30	0.35						0.50				1 1	. 0	1
2		8,760356158		2	0.40	0.33	0.65	0.35	0.90	0.65	0.30	0.30	0.35						0.50				1 1	. 0	
3		8,746193349	1,010048662	3	0.40	0.07	0.65	0.35	0.90	0.65	0.30	0.30	0.35						0.50				1 1	. 0	
4	13,08	8,746193349	1,010048662	3	0.33	0.07	0.65	0.35	0.90	0.65	0.30	0.30	0.35						0.50				1 1	. 0	1
5	13,08	8,746191859	1,010083552	5	0.40	0.07	0.56	0.35	0.90	0.65	0.30	0.30	0.35	0.20	0.50	0.30	0.30	0.50	0.50	0.20	0.50	1	1 1	. 0	
6	12,56	8,761464804	1,185984278	5	0.40	0.39	0.56	0.35	0.90	0.65	0.30	0.30	0.35	0.20	0.50	0.30	0.30	0.50	0.50	0.20	0.50	1	1 1	. 0	1
7	13,08	8,746191114	1,010100997	7	0.35	0.07	0.56	0.35	0.90	0.65	0.30	0.30	0.35	0.20	0.50	0.30	0.30	0.50	0.50	0.20	0.50	1	1 1	. 0	1
8	13,08	8,746191859	1,010083552	7	0.32	0.07	0.56	0.35	0.90	0.65	0.30	0.30	0.35	0.20	0.50	0.30	0.30	0.50	0.50	0.20	0.50	1	1 1	. 0	1
9	13,08	8,756010234	0,789668465	7	0.35	0.19	0.56	0.35	0.90	0.65	0.30	0.30	0.35						0.50			1	1 1	. 0	1
10	13,56	8,699711412	1,012494564	10	0.15	0.07	0.56	0.35	0.90	0.65	0.30	0.30	0.35	0.20	0.50	0.30	0.30	0.50	0.50	0.20	0.50	1	1 1	. 0	1

 minTT
 maxTT
 minLO
 maxLO

 10
 20
 0
 10

D1	0,308	0,692	0,876076221	0,123923779	1,184076221	0,815923779
D2	0,308	0,692	0,876035616	0,123964384	1,184035616	0,815964384
D3	0,308	0,692	0,874619335	0,125380665	1,182619335	0,817380665
D4	0,308	0,692	0,874619335	0,125380665	1,182619335	0,817380665
D5	0,308	0,692	0,874619186	0,125380814	1,182619186	0,817380814
D6	0,256	0,744	0,87614648	0,12385352	1,13214648	0,86785352
D7	0,308	0,692	0,874619111	0,125380889	1,182619111	0,817380889
D8	0,308	0,692	0,874619186	0,125380814	1,182619186	0,817380814
D9	0,308	0,692	0,875601023	0,124398977	1,183601023	0,816398977
D10	0,356	0,644	0,869971141	0,130028859	1,225971141	0,774028859