

# THE ART OF COMPUTER PROGRAMMING

VOLUME 4    PRE-FASCICLE 0B

## A DRAFT OF SECTION 7.1.1: BOOLEAN BASICS

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See also <http://www-cs-faculty.stanford.edu/~knuth/sgb.html> for information about *The Stanford GraphBase*, including downloadable software for dealing with the graphs used in many of the examples in Chapter 7.

See also <http://www-cs-faculty.stanford.edu/~knuth/mmixware.html> for downloadable software to simulate the MMIX computer.

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## PREFACE

*Bitte ein Bit!*

— Slogan of Bitburger Brauerei (1951)

THIS BOOKLET contains draft material that I'm circulating to experts in the field, in hopes that they can help remove its most egregious errors before too many other people see it. I am also, however, posting it on the Internet for courageous and/or random readers who don't mind the risk of reading a few pages that have not yet reached a very mature state. *Beware:* This material has not yet been proofread as thoroughly as the manuscripts of Volumes 1, 2, and 3 were at the time of their first printings. And those carefully-checked volumes, alas, were subsequently found to contain thousands of mistakes.

Given this caveat, I hope that my errors this time will not be so numerous and/or obtrusive that you will be discouraged from reading the material carefully. I did try to make the text both interesting and authoritative, as far as it goes. But the field is so vast, I cannot hope to have surrounded it enough to corral it completely. Therefore I beg you to let me know about any deficiencies you discover.

To put the material in context, this pre-fascicle contains Section 7.1.1 of a long, long chapter on combinatorial algorithms. Chapter 7 will eventually fill at least three volumes (namely Volumes 4A, 4B, and 4C), assuming that I'm able to remain healthy. It will begin with a short review of graph theory, with emphasis on some highlights of significant graphs in the Stanford GraphBase, from which I will be drawing many examples. Then comes Section 7.1: Boolean Functions and Bit Manipulation, beginning with the stuff you're about to read here. Section 7.1.2 will deal with efficient Boolean function evaluation; Section 7.1.3 will deal with tricks and techniques of bitwise calculation; and Section 7.1.4 will discuss the representation of Boolean functions.

The next section, 7.2, is about generating all possibilities, and it begins with Section 7.2.1: Generating Basic Combinatorial Patterns. Fascicles for this section have already appeared on the Web and/or in print. Section 7.2.2 will deal with backtracking in general. And so it will go on, if all goes well; an outline of the entire Chapter 7 as currently envisaged appears on the **taocp** webpage that is cited on page ii.

The topic of Boolean functions and bit manipulation can of course be interpreted so broadly that it encompasses the entire subject of computer programming. My original title for Section 7.1 — “Bit Fiddling” — was much more

modest; I decided, however, that that was a bit too low-brow. The real goal of this fascicle is to focus on concepts that appear at the lowest levels, on which we can erect significant superstructures. And even these apparently lowly notions turn out to be surprisingly rich, with explicit ties to Sections 1.2.3, 1.2.6, 2.2.1, 2.2.3, 2.3.3, 3.3.2, 4.6, 4.6.1, 4.6.4, 5, 5.3.4, and 6.5 of the first three volumes. I strongly believe in building up a firm foundation, so I have discussed Boolean topics much more thoroughly than I will be able to do with material that is newer or less basic. After typing the material I was astonished to discover that I had come up with 129 exercises, even though—believe it or not—I had to eliminate quite a lot of the interesting material that appears in my files.

My notes on combinatorial algorithms have been accumulating for more than forty years, so I fear that in several respects my knowledge is woefully behind the times. Please look, for example, at the exercises that I’ve classed as research problems (rated with difficulty level 46 or higher), namely exercises 66, 89, 90, 116, and 120; I’ve also implicitly mentioned or posed additional unsolved questions in the answers to exercises 25, 27, and 93. Are those problems still open? Please let me know if you know of a solution to any of these intriguing questions. And of course if no solution is known today but you do make progress on any of them in the future, I hope you’ll let me know.

I urgently need your help also with respect to some exercises that I made up as I was preparing this material. I certainly don’t like to get credit for things that have already been published by others, and most of these results are essentially “low-hanging fruits” that were just waiting to be plucked. Therefore please tell me if you know who I should have credited, with respect to the ideas found in exercises 15, 25, 34(b,c,d), 41 (Solution 2), 47, 51, 81, 96, 104, 107(g,h), 118, 119, 123(c), 124, and 125. Furthermore I’ve credited exercises 60, 65, and 67 to unpublished work of Craige Schensted, and exercise 57 to unpublished work of Dan Pehoushek. Have any of those results appeared in print, to your knowledge?

I’ve decided to introduce the terms “proper Horn clause” and “proper Horn function” in this draft; I hope they don’t conflict with anybody else’s usage.

I shall happily pay a finder’s fee of \$2.56 for each error in this draft when it is first reported to me, whether that error be typographical, technical, or historical. The same reward holds for items that I forgot to put in the index. And valuable suggestions for improvements to the text are worth 32¢ each. (Furthermore, if you find a better solution to an exercise, I’ll actually reward you with immortal glory instead of mere money, by publishing your name in the eventual book:—)

Cross references to yet-unwritten material sometimes appear as ‘00’; this impossible value is a placeholder for the actual numbers to be supplied later.

Happy reading!

*Stanford, California*  
*05 September 2005*

D. E. K.

*Yet now and then your men of wit  
Will condescend to take a bit.*

— JONATHAN SWIFT, *Cadenus and Vanessa* (1713)

*If the base 2 is used the resulting units may be called binary digits,  
or more briefly bits, a word suggested by J. W. Tukey.*

— CLAUDE E. SHANNON, in *Bell System Technical Journal* (1948)

*bit (bit), n ... [A] boring tool ...*

— *Random House Dictionary of the English Language* (1987)

## 7.1. BIT MANIPULATION

COMBINATORIAL ALGORITHMS often require special attention to efficiency, and the proper representation of data is an important way to gain the necessary speed. It is therefore wise to beef up our knowledge of elementary representation techniques before we set out to study combinatorial algorithms in detail.

Most of today's computers are based on the binary number system, instead of working directly with the decimal numbers that human beings prefer, because machines are especially good at dealing with the two-state on-off quantities that we usually denote by the digits 0 and 1. But in Chapters 1 to 6 we haven't made much use of the fact that binary computers can do several things quickly that decimal computers cannot. A binary machine can usually perform "logical" or "bitwise" operations just as easily as it can add or subtract; yet we have seldom capitalized on that capability. We've seen that binary and decimal computers are not significantly different, for many purposes, but in a sense we've been asking a binary computer to operate with one hand tied behind its back.

The amazing ability of 0s and 1s to encode information as well as to encode the logical relations between items, and even to encode algorithms for processing information, makes the study of binary digits especially rich. Indeed, we not only use bitwise operations to enhance combinatorial algorithms, we also find that the properties of binary logic lead naturally to new combinatorial problems that are of great interest in their own right.

Computer scientists have gradually become better and better at taming the wild 0s and 1s of the universe and making them do useful tricks. But as bit players on the world's stage, we'd better have a thorough understanding of the low-level properties of binary quantities before we launch into a study of higher-level concepts and techniques. Therefore we shall start by investigating basic ways to combine individual bits and sequences of bits.

### 7.1.1. Boolean Basics

There are 16 possible functions  $f(x, y)$  that transform two given bits  $x$  and  $y$  into a third bit  $z = f(x, y)$ , since there are two choices for each of  $f(0, 0)$ ,  $f(0, 1)$ ,  $f(1, 0)$ , and  $f(1, 1)$ . Table 1 indicates the names and notations that have traditionally been associated with these functions in studies of formal logic, assuming that 1 corresponds to "true" and 0 to "false." The sequence of four values  $f(0, 0)f(0, 1)f(1, 0)f(1, 1)$  is customarily called the *truth table* of the function  $f$ .

*Let us conceive, then, of an Algebra  
in which the symbols  $x, y, z$ , &c. admit indifferently of  
the values 0 and 1, and of these values alone.*

— GEORGE BOOLE, *An Investigation of the Laws of Thought* (1854)

*‘Contrariwise,’ continued Tweedledee, ‘if it was so, it might be;  
and if it were so, it would be;  
but as it isn’t, it ain’t. That’s logic.’*

— LEWIS CARROLL, *Through the Looking Glass* (1871)

Such functions are often called “Boolean operations” in honor of George Boole, who first discovered that algebraic operations on 0s and 1s could be used to construct a calculus for logical reasoning [*The Mathematical Analysis of Logic* (Cambridge: 1847); *An Investigation of the Laws of Thought* (London: 1854)]. But Boole never actually dealt with the “logical or” operation  $\vee$ ; he confined himself strictly to ordinary arithmetic operations on 0s and 1s. Thus he would write  $x + y$  to stand for disjunction, but he took pains never to use this notation unless  $x$  and  $y$  were mutually exclusive (not both 1). If necessary, he wrote  $x + (1-x)y$  to ensure that the result of a disjunction would never be equal to 2.

When rendering the  $+$  operation in English, Boole sometimes called it “and,” sometimes “or.” This practice may seem strange to modern mathematicians until we realize that his usage was in fact normal English; we say, for example, that “boys and girls are children,” but “children are boys or girls.”

Boole’s calculus was extended to include the unconventional rule  $x + x = x$  by W. Stanley Jevons [*Pure Logic* (London: Edward Stanford, 1864), §69], who pointed out that  $(x + y)z$  was equal to  $xz + yz$  using his new  $+$  operation. But Jevons did not know the other distributive law  $xy + z = (x + z)(y + z)$ . Presumably he missed this because of the notation he was using, since the second distributive law has no familiar counterpart in arithmetic; the more symmetrical notations  $x \wedge y$ ,  $x \vee y$  in Table 1 make it easier for us to remember both distributive laws

$$(x \vee y) \wedge z = (x \wedge z) \vee (y \wedge z); \quad (1)$$

$$(x \wedge y) \vee z = (x \vee z) \wedge (y \vee z). \quad (2)$$

The second law (2) was introduced by C. S. Peirce, who had discovered independently how to extend Boole’s calculus [*Proc. Amer. Acad. Arts and Sciences* **7** (1867), 250–261]. Incidentally, when Peirce discussed these early developments several years later [*Amer. J. Math.* **3** (1880), 32], he referred to “the Boolean algebra, with Jevons’s addition”; his now-unfamiliar spelling of “Boolean” was in use for many years, appearing in the Funk and Wagnalls unabridged dictionary as late as 1963.

The notion of truth-value combination is actually much older than Boolean algebra. Indeed, propositional logic had been developed by Greek philosophers already in the fourth century B.C. There was considerable debate in those days about how to assign an appropriate true-or-false value to the proposition “if  $x$  then  $y$ ” when  $x$  and  $y$  are propositions; Philo of Megara, about 300 B.C., defined

**Table 1**  
THE SIXTEEN LOGICAL OPERATIONS ON TWO VARIABLES

Truth table	Notation(s)	Operator symbol $\circ$	Name(s)
0000	0	$\perp$	Contradiction; falsehood; constant 0
0001	$xy, x \wedge y, x \& y$	$\wedge$	Conjunction; and
0010	$x \wedge \bar{y}, x \not\supset y, [x > y], x \dot{-} y$	$\supset$	Nonimplication; difference; but not
0011	$x$	$\mathsf{L}$	Left projection
0100	$\bar{x} \wedge y, x \not\subset y, [x < y], y \dot{-} x$	$\bar{\supset}$	Converse nonimplication; not ... but
0101	$y$	$\mathsf{R}$	Right projection
0110	$x \oplus y, x \neq y, x \hat{\wedge} y$	$\oplus$	Exclusive disjunction; nonequivalence; “xor”
0111	$x \vee y, x \mid y$	$\vee$	(Inclusive) disjunction; or; and/or
1000	$\bar{x} \wedge \bar{y}, \overline{x \vee y}, x \nabla y, x \downarrow y$	$\nabla$	Nondisjunction; joint denial; neither ... nor
1001	$x \equiv y, x \leftrightarrow y, x \Leftrightarrow y$	$\equiv$	Equivalence; if and only if
1010	$\bar{y}, \neg y, !y, \sim y$	$\bar{\mathsf{R}}$	Right complementation
1011	$x \vee \bar{y}, x \subset y, x \Leftarrow y, [x \geq y], x^y$	$\subset$	Converse implication; if
1100	$\bar{x}, \neg x, !x, \sim x$	$\bar{\mathsf{L}}$	Left complementation
1101	$\bar{x} \vee y, x \supset y, x \Rightarrow y, [x \leq y], y^x$	$\supset$	Implication; only if; if ... then
1110	$\bar{x} \vee \bar{y}, \overline{x \wedge y}, x \bar{\wedge} y, x \mid y$	$\bar{\wedge}$	Nonconjunction; not both ... and; “nand”
1111	1	$\top$	Affirmation; validity; tautology; constant 1

it by the truth table shown in Table 1, which states in particular that the implication is true when both  $x$  and  $y$  are false. Much of this early work has been lost, but there are passages in the works of Galen (2nd century A.D.) that refer to both inclusive and exclusive disjunction of propositions. [See I. M. Bocheński, *Formale Logik* (1956), English translation by Ivo Thomas (1961), for an excellent survey of the development of logic from ancient times up to the 20th century.]

A function of two variables is often written  $x \circ y$  instead of  $f(x, y)$ , using some appropriate operator symbol  $\circ$ . Table 1 shows the sixteen operator symbols that we shall adopt for Boolean functions of two variables; for example,  $\perp$  symbolizes the function whose truth table is 0000,  $\wedge$  is the symbol for 0001,  $\supset$  is the symbol for 0010, and so on. We have  $x \perp y = 0$ ,  $x \wedge y = xy$ ,  $x \supset y = x \dot{-} y$ ,  $x \mathsf{L} y = x$ , ...,  $x \bar{\wedge} y = \bar{x} \vee \bar{y}$ ,  $x \top y = 1$ .

Of course the operations in Table 1 aren't all of equal importance. For example, the first and last cases are trivial, since they have a constant value independent of  $x$  and  $y$ . Four of them are functions of  $x$  alone or  $y$  alone. We write  $\bar{x}$  for  $1 - x$ , the *complement* of  $x$ .

The four operations whose truth table contains just a single 1 are easily expressed in terms of the AND operator  $\wedge$ , namely  $x \wedge y$ ,  $x \wedge \bar{y}$ ,  $\bar{x} \wedge y$ ,  $\bar{x} \wedge \bar{y}$ . Those with three 1s are easily written in terms of the OR operator  $\vee$ , namely  $x \vee y$ ,  $x \vee \bar{y}$ ,  $\bar{x} \vee y$ ,  $\bar{x} \vee \bar{y}$ . The basic functions  $x \wedge y$  and  $x \vee y$  have proved to be more useful in practice than their complemented or half-complemented cousins, although the NOR and NAND operations  $x \nabla y = \bar{x} \wedge \bar{y}$  and  $x \bar{\wedge} y = \bar{x} \vee \bar{y}$  are also of interest because they are easily implemented in transistor circuits.

In 1913, H. M. Sheffer showed that all 16 of the functions can be expressed in terms of just one, starting with either  $\nabla$  or  $\bar{\wedge}$  as the given operation (see exercise 4). Actually C. S. Peirce had made the same discovery about 1880, but his work on the subject remained unpublished until after his death [*Collected Papers of Charles Sanders Peirce* 4 (1933), §§12–20, 264]. Table 1 indicates that NAND and NOR have occasionally been written  $x | y$  and  $x \downarrow y$ ; sometimes they have been called “Sheffer’s stroke” and the “Peirce arrow.” Nowadays it is best *not* to use Sheffer’s vertical line for NAND, because  $x | y$  denotes bitwise  $x \vee y$  in programming languages like C.

So far we have discussed all but two of the functions in Table 1. The remaining two are  $x \equiv y$  and  $x \oplus y$ , “equivalence” and “exclusive-or,” which are related by the identities

$$x \equiv y = \bar{x} \oplus y = x \oplus \bar{y} = 1 \oplus x \oplus y; \quad (3)$$

$$x \oplus y = \bar{x} \equiv y = x \equiv \bar{y} = 0 \equiv x \equiv y. \quad (4)$$

Both operations are associative (see exercise 6). In propositional logic, the notion of equivalence is more important than the notion of exclusive-or, which means inequivalence; but when we consider bitwise operations on full computer words, we shall see in Section 7.1.3 that the situation is reversed: Exclusive-or turns out to be the most useful of the two. The chief reason why  $x \oplus y$  has significant applications, even in the one-bit case, is the fact that

$$x \oplus y = (x + y) \bmod 2. \quad (5)$$

Therefore  $x \oplus y$  and  $x \wedge y$  denote addition and multiplication in the field of two elements (see Section 4.6), and  $x \oplus y$  naturally inherits many “clean” mathematical properties.

**Basic identities.** Now let’s take a look at interactions between the fundamental operators  $\wedge$ ,  $\vee$ ,  $\oplus$ , and  $\bar{\phantom{x}}$ , since the other operations are easily expressed in terms of these four. Each of  $\wedge$ ,  $\vee$ ,  $\oplus$  is associative and commutative. Besides the distributive laws (1) and (2), we also have

$$(x \oplus y) \wedge z = (x \wedge z) \oplus (y \wedge z), \quad (6)$$

as well as the *absorption laws*

$$(x \wedge y) \vee x = (x \vee y) \wedge x = x. \quad (7)$$

One of the simplest, yet most useful, identities is

$$x \oplus x = 0, \quad (8)$$

since it implies among other things that

$$(x \oplus y) \oplus x = y, \quad (x \oplus y) \oplus y = x, \quad (9)$$

when we use the obvious fact that  $x \oplus 0 = x$ . In other words, given  $x \oplus y$  and either  $x$  or  $y$ , it is easy to determine the other. And let us not overlook the simple *complementation law*

$$\bar{x} = x \oplus 1. \quad (10)$$



Another important pair of identities is known as *De Morgan's laws* in honor of Augustus De Morgan, who stated that “The contrary of an aggregate is the compound of the contraries of the aggregants; the contrary of a compound is the aggregate of the contraries of the components. Thus  $(A, B)$  and  $AB$  have  $ab$  and  $(a, b)$  for contraries.” [*Trans. Cambridge Philos. Soc.* **10** (1858), 208.] In more modern notation, these are the rules we have implicitly derived via truth tables in connection with the operations NAND and NOR in Table 1, namely

$$\overline{x \wedge y} = \bar{x} \vee \bar{y}; \quad (11)$$

$$\overline{x \vee y} = \bar{x} \wedge \bar{y}. \quad (12)$$

Incidentally, W. S. Jevons knew (12) but not (11); he consistently wrote  $\bar{A}B + \bar{B}A + \bar{A}\bar{B}$  instead of  $\bar{A} + \bar{B}$  for the complement of  $AB$ . Yet De Morgan was not the first Englishman who enunciated the laws above. Both (11) and (12) can be found in the early 14th century writings of two scholastic philosophers, William of Ockham [*Summa Logicae* **2** (1323)] and Walter Burley [*De Puritate Artis Logicae* (c. 1330)].

De Morgan's laws and a few other identities can be used to express  $\wedge$ ,  $\vee$ , and  $\oplus$  in terms of each other:

$$x \wedge y = \overline{\bar{x} \vee \bar{y}} = x \oplus y \oplus (x \vee y); \quad (13)$$

$$x \vee y = \overline{\bar{x} \wedge \bar{y}} = x \oplus y \oplus (x \wedge y); \quad (14)$$

$$x \oplus y = (x \vee y) \wedge \overline{x \wedge y} = (x \wedge \bar{y}) \vee (\bar{x} \wedge y). \quad (15)$$

According to exercise 7.1.2–00, all computations of  $x_1 \oplus x_2 \oplus \cdots \oplus x_n$  that use only the operations  $\wedge$ ,  $\vee$ , and  $\bar{\phantom{x}}$  must be at least  $4(n-1)$  steps long; thus, the other three operations are not an especially good substitute for  $\oplus$ .

**Functions of  $n$  variables.** A Boolean function  $f(x, y, z)$  of three Boolean variables  $x, y, z$  can be defined by its 8-bit truth table  $f(0, 0, 0) f(0, 0, 1) \dots f(1, 1, 1)$ ; and in general, every  $n$ -ary Boolean function  $f(x_1, \dots, x_n)$  corresponds to a  $2^n$ -bit truth table that lists the successive values of  $f(0, \dots, 0, 0)$ ,  $f(0, \dots, 0, 1)$ ,  $f(0, \dots, 1, 0)$ ,  $\dots$ ,  $f(1, \dots, 1, 1)$ .

We needn't devise special names and notations for all these functions, since they can all be expressed in terms of the binary functions that we've already learned. For example, as observed by I. I. Zhegalkin [*Matematicheskiĭ Sbornik* **35** (1928), 311–369], we can always write

$$f(x_1, \dots, x_n) = g(x_1, \dots, x_{n-1}) \oplus h(x_1, \dots, x_{n-1}) \wedge x_n \quad (16)$$

when  $n > 0$ , for appropriate functions  $g$  and  $h$ , by letting

$$\begin{aligned} g(x_1, \dots, x_{n-1}) &= f(x_1, \dots, x_{n-1}, 0); \\ h(x_1, \dots, x_{n-1}) &= f(x_1, \dots, x_{n-1}, 0) \oplus f(x_1, \dots, x_{n-1}, 1). \end{aligned} \quad (17)$$

(The operation  $\wedge$  conventionally takes precedence over  $\oplus$ , so we need not use parentheses to enclose the subformula ' $h(x_1, \dots, x_{n-1}) \wedge x_n$ ' on the right-hand side of (16).) Repeating this process recursively on  $g$  and  $h$  until we're down

to 0-ary functions leaves us with an expression that involves only the operators  $\oplus$ ,  $\wedge$ , and a sequence of  $2^n$  constants; those constants can usually be simplified away, because we have

$$x \wedge 0 = 0 \quad \text{and} \quad x \wedge 1 = x \oplus 0 = x. \quad (18)$$

After applying the associative and distributive laws, we end up needing the constant 0 only if  $f(x_1, \dots, x_n)$  is identically zero, and the constant 1 only if  $f(0, \dots, 0) = 1$ .

We might have, for instance,

$$\begin{aligned} f(x, y, z) &= ((1 \oplus 0 \wedge x) \oplus (0 \oplus 1 \wedge x) \wedge y) \oplus ((0 \oplus 1 \wedge x) \oplus (1 \oplus 1 \wedge x) \wedge y) \wedge z \\ &= (1 \oplus x \wedge y) \oplus (x \oplus y \oplus x \wedge y) \wedge z \\ &= 1 \oplus x \wedge y \oplus x \wedge z \oplus y \wedge z \oplus x \wedge y \wedge z. \end{aligned}$$

Furthermore, by rule (5), we see that we're simply left with the polynomial

$$f(x, y, z) = (1 + xy + xz + yz + xyz) \bmod 2, \quad (19)$$

because  $x \wedge y = xy$ . Notice that this polynomial is linear (of degree  $\leq 1$ ) in each of its variables. And in general, a similar calculation will show that *any* Boolean function  $f(x_1, \dots, x_n)$  has a unique representation such as this, called its *multilinear representation*, which is a sum (modulo 2) of zero or more of the  $2^n$  possible terms  $1, x_1, x_2, x_1x_2, x_3, x_1x_3, x_2x_3, x_1x_2x_3, \dots, x_1x_2 \dots x_n$ .

George Boole decomposed Boolean functions in a different way, which is often simpler for the kinds of functions that arise in practice. Instead of (16), he essentially wrote

$$f(x_1, \dots, x_n) = (g(x_1, \dots, x_{n-1}) \wedge \bar{x}_n) \vee (h(x_1, \dots, x_{n-1}) \wedge x_n) \quad (20)$$

and called it the “law of development,” where we now have simply

$$\begin{aligned} g(x_1, \dots, x_{n-1}) &= f(x_1, \dots, x_{n-1}, 0), \\ h(x_1, \dots, x_{n-1}) &= f(x_1, \dots, x_{n-1}, 1), \end{aligned} \quad (21)$$

instead of (17). Repeatedly iterating Boole's procedure, using the distributive law (1), and eliminating constants, leaves us with a formula that is a disjunction of zero or more *minterms*, where each minterm is a conjunction such as  $x_1 \wedge \bar{x}_2 \wedge \bar{x}_3 \wedge x_4 \wedge x_5$  in which every variable or its complement is present. Notice that a minterm is a Boolean function that is true at exactly one point.

For example, let's consider the more-or-less random function  $f(w, x, y, z)$  whose truth table is

$$1100 \ 1001 \ 0000 \ 1111. \quad (22)$$

When this function is expanded by repeatedly applying Boole's law (20), we get a disjunction of eight minterms, one for each of the 1s in the truth table:

$$\begin{aligned} f(w, x, y, z) &= (\bar{w} \wedge \bar{x} \wedge \bar{y} \wedge \bar{z}) \vee (\bar{w} \wedge \bar{x} \wedge \bar{y} \wedge z) \vee (\bar{w} \wedge x \wedge \bar{y} \wedge \bar{z}) \vee (\bar{w} \wedge x \wedge y \wedge z) \\ &\vee (w \wedge x \wedge \bar{y} \wedge \bar{z}) \vee (w \wedge x \wedge \bar{y} \wedge z) \vee (w \wedge x \wedge y \wedge \bar{z}) \vee (w \wedge x \wedge y \wedge z). \end{aligned} \quad (23)$$

In general, a disjunction of minterms is called a *full disjunctive normal form*. Every Boolean function can be expressed in this way, and the result is unique—except, of course, for the order of the minterms. *Nitpick:* A special case arises when  $f(x_1, \dots, x_n)$  is identically zero. We consider ‘0’ to be an empty disjunction, with no terms, and we also consider ‘1’ to be an empty conjunction, for the same reasons as we defined  $\sum_{k=1}^0 a_k = 0$  and  $\prod_{k=1}^0 a_k = 1$  in Section 1.2.3.

C. S. Peirce observed, in *Amer. J. Math.* **3** (1880), 37–39, that every Boolean function also has a *full conjunctive normal form*, which is a conjunction of “minclauses” like  $\bar{x}_1 \vee x_2 \vee \bar{x}_3 \vee \bar{x}_4 \vee x_5$ . A minclause is 0 at only one point; so each clause in such a conjunction accounts for a place where the truth table has a 0. For example, the full conjunctive normal form of our function in (22) and (23) is

$$\begin{aligned} f(w, x, y, z) = & (w \vee x \vee \bar{y} \vee z) \wedge (w \vee x \vee \bar{y} \vee \bar{z}) \wedge (w \vee \bar{x} \vee y \vee \bar{z}) \wedge (w \vee \bar{x} \vee \bar{y} \vee z) \\ & \wedge (\bar{w} \vee x \vee y \vee z) \wedge (\bar{w} \vee x \vee y \vee \bar{z}) \wedge (\bar{w} \vee x \vee \bar{y} \vee z) \wedge (\bar{w} \vee x \vee \bar{y} \vee \bar{z}). \end{aligned} \quad (24)$$

Not surprisingly, however, we often want to work with disjunctions and conjunctions that *don’t* necessarily involve full minterms or minclauses. Therefore, following nomenclature introduced by Paul Bernays in his *Habilitationsschrift* (1918), we speak in general of a *disjunctive normal form* or “DNF” as *any* disjunction of conjunctions,

$$\bigvee_{j=1}^m \bigwedge_{k=1}^{s_j} u_{jk} = (u_{11} \wedge \dots \wedge u_{1s_1}) \vee \dots \vee (u_{m1} \wedge \dots \wedge u_{ms_m}), \quad (25)$$

where each  $u_{jk}$  is a *literal*, namely a variable  $x_i$  or its complement. Similarly, any conjunction of disjunctions of literals,

$$\bigwedge_{j=1}^m \bigvee_{k=1}^{s_j} u_{jk} = (u_{11} \vee \dots \vee u_{1s_1}) \wedge \dots \wedge (u_{m1} \vee \dots \vee u_{ms_m}), \quad (26)$$

is called a *conjunctive normal form*, or “CNF” for short.

A great many electrical circuits embedded inside today’s computer chips are composed of “programmable logic arrays” (PLAs), which are ORs of ANDs of possibly complemented input signals. In other words, a PLA basically computes one or more disjunctive normal forms. Such circuits are fast, versatile, and relatively inexpensive; and indeed, DNFs have played a prominent role in electrical engineering ever since the 1950s, when switching circuits were implemented with comparatively old-fashioned devices like relays or vacuum tubes. Therefore people have long been interested in finding the simplest DNFs for classes of Boolean functions, and we can expect that an understanding of disjunctive normal forms will continue to be important as technology continues to evolve.

The terms of a DNF are often called *implicants*, because the truth of any term in a disjunction implies the truth of the whole formula. In a formula like

$$f(x, y, z) = (x \wedge \bar{y} \wedge z) \vee (y \wedge z) \vee (\bar{x} \wedge y \wedge \bar{z}),$$

for example, we know that  $f$  is true when  $x \wedge \bar{y} \wedge z$  is true, namely when  $(x, y, z) = (1, 0, 1)$ . But notice that in this example the shorter term  $x \wedge z$  also turns out to

be an implicant of  $f$ , even though not written explicitly, because the additional term  $y \wedge z$  makes the function true whenever  $x = z = 1$ , regardless of the value of  $y$ . Similarly,  $\bar{x} \wedge y$  is an implicant of this particular function. So we might as well work with the simpler formula

$$f(x, y, z) = (x \wedge z) \vee (y \wedge z) \vee (\bar{x} \wedge y). \quad (27)$$

At this point no more deletions are possible within the implicants, because neither  $x$  nor  $y$  nor  $z$  nor  $\bar{x}$  is a strong enough condition to imply the truth of  $f$ .

An implicant that can't be factored further by removing any of its literals without making it too weak is called a *prime implicant*, following the terminology of W. V. Quine in *AMM* **59** (1952), 521–531.

These basic concepts can perhaps be understood most easily if we simplify the notation and adopt a more geometric viewpoint. We can write simply ' $f(x)$ ' instead of  $f(x_1, \dots, x_n)$ , and regard  $x$  as a vector, or as a binary string  $x_1 \dots x_n$  of length  $n$ . For example, the strings  $wxyz$  where the function of (22) is true are

$$\{0000, 0001, 0100, 0111, 1100, 1101, 1110, 1111\}, \quad (28)$$

and we can think of them as eight points in the 4-dimensional hypercube  $2 \times 2 \times 2 \times 2$ . The eight points in (28) correspond to the minterm implicants that are explicitly present in the full disjunctive normal form (23); but none of those implicants is actually prime. For example, the first two points of (28) make the subcube  $000*$ , and the last four points constitute the subcube  $11**$ , if we use asterisks to denote "wild cards" as we did when discussing database queries in Section 6.5; therefore  $\bar{w} \wedge \bar{x} \wedge \bar{y}$  is an implicant of  $f$ , and so is  $w \wedge x$ . Similarly, we can see that the subcube  $0*00$  accounts for two of the eight points in (28), making  $\bar{w} \wedge \bar{y} \wedge \bar{z}$  an implicant.

In general, each prime implicant corresponds in this way to a *maximal* subcube that stays within the set of points that make  $f$  true. (The subcube is maximal in the sense that it isn't contained in any larger subcube with the same property; we can't replace any of its explicit bits by an asterisk. A maximal subcube has a maximal number of asterisks, hence a minimal number of constrained coordinates, hence a minimal number of variables in the corresponding implicant.) The maximal subcubes of the eight points in (28) are

$$000*, 0*00, *100, *111, 11**; \quad (29)$$

so the prime implicants of the function  $f(w, x, y, z)$  in (23) are

$$(\bar{w} \wedge \bar{x} \wedge \bar{y}) \vee (\bar{w} \wedge \bar{y} \wedge \bar{z}) \vee (x \wedge \bar{y} \wedge \bar{z}) \vee (x \wedge y \wedge z) \vee (w \wedge x). \quad (30)$$

The *disjunctive prime form* of a Boolean function is the disjunction of all its prime implicants. Exercise 30 contains an algorithm to find all the prime implicants of a given function, based on a list of the points where the function is true.

We can define a *prime clause* in an exactly similar way: It is a disjunctive clause that is implied by  $f$ , having no subclause with the same property. And the *conjunctive prime form* of  $f$  is the conjunction of all its prime clauses. (An example appears in exercise 19.)

In many simple cases, the disjunctive prime form is the shortest possible disjunctive normal form that a function can have. But we can often do better, because we might be able to cover all the necessary points with only a few of the maximal subcubes. For example, the prime implicant  $(y \wedge z)$  is unnecessary in (27). And in expression (30) we don't need both  $(\bar{w} \wedge \bar{y} \wedge \bar{z})$  and  $(x \wedge \bar{y} \wedge \bar{z})$ ; either one is sufficient, in the presence of the other terms.

Unfortunately, we will see in Section 7.9 that the task of finding a best disjunctive normal form is NP-complete, thus quite difficult in general. But many useful shortcuts have been developed for sufficiently small problems, and they are well explained in the book *Introduction to the Theory of Switching Circuits* by E. J. McCluskey (New York: McGraw-Hill, 1965). For later developments, see Petr Fišer and Jan Hlavička, *Computing and Informatics* **22** (2003), 19–51.

There's an important special case for which the shortest DNF is, however, easily characterized. A Boolean function is said to be *monotone* or *positive* if its value does not change from 1 to 0 when any of its variables changes from 0 to 1. In other words,  $f$  is monotone if and only if  $f(x) \leq f(y)$  whenever  $x \subseteq y$ , where the bit string  $x = x_1 \dots x_n$  is regarded as contained in or equal to the bit string  $y = y_1 \dots y_n$  if and only if  $x_j \leq y_j$  for all  $j$ . An equivalent condition (see exercise 21) is that the function  $f$  either is constant or can be expressed entirely in terms of  $\wedge$  and  $\vee$ , without complementation.

**Theorem Q.** *The shortest disjunctive normal form of a monotone Boolean function is its disjunctive prime form.*

*Proof.* [W. V. Quine, *Boletín de la Sociedad Matemática Mexicana* **10** (1953), 64–70.] Let  $f(x_1, \dots, x_n)$  be monotone, and let  $u_1 \wedge \dots \wedge u_s$  be one of its prime implicants. We cannot have, say,  $u_1 = \bar{x}_i$ , because in that case the shorter term  $u_2 \wedge \dots \wedge u_s$  would also be an implicant, by monotonicity. Therefore no prime implicant has a complemented literal.

Now if we set  $u_1 \leftarrow \dots \leftarrow u_s \leftarrow 1$  and all other variables to 0, the value of  $f$  will be 1, but all of  $f$ 's other prime implicants will vanish. Thus  $u_1 \wedge \dots \wedge u_s$  must be in every shortest DNF, because every implicant of a shortest DNF is clearly prime. ■

**Corollary Q.** *A disjunctive normal form is the disjunctive prime form of a monotone Boolean function if and only if it has no complemented literals and none of its implicants is contained in another.* ■

**Satisfiability.** A Boolean function is said to be *satisfiable* if it is not identically zero—that is, if it has at least one implicant. The most famous unsolved problem in all of computer science is to find an efficient way to decide whether a given Boolean function is satisfiable or unsatisfiable. More precisely, we ask: Is there an algorithm that inputs a Boolean formula of length  $N$  and tests it for satisfiability, always giving the correct answer after performing at most  $N^{O(1)}$  steps?

When you hear about this problem for the first time, you might be tempted to ask a question of your own in return: “What? Are you serious that computer scientists still haven't figured out how to do such a simple thing?”

Well, if you think satisfiability testing is trivial, please tell us your method. We agree that the problem isn't always difficult; if, for example, the given formula involves only 30 Boolean variables, a brute-force trial of  $2^{30}$  cases — that's about a billion — will indeed settle the matter. But an enormous number of practical problems that still await solution can be formulated as Boolean functions with, say, 100 variables, because mathematical logic is a very powerful way to express concepts. And the solutions to those problems correspond to the vectors  $x = x_1 \dots x_{100}$  for which  $f(x) = 1$ . So a truly efficient solution to the satisfiability problem would be a wonderful achievement.

There is at least one sense in which satisfiability testing is a no-brainer: If the function  $f(x_1, \dots, x_n)$  has been chosen at random, so that all  $2^n$  truth tables are equally likely, then  $f$  is almost surely satisfiable, and we can find an  $x$  with  $f(x) = 1$  after making fewer than 2 trials (on the average). It's like flipping a coin until it comes up heads; we rarely need to wait long. But the catch, of course, is that practical problems do not have random truth tables.

Okay, let's grant that satisfiability testing does seem to be tough, in general. In fact, satisfiability turns out to be difficult even when we try to simplify it by requiring that the Boolean function be presented as a "formula in 3CNF" — namely as a conjunctive normal form that has only *three* literals in each clause:

$$f(x_1, \dots, x_n) = (t_1 \vee u_1 \vee v_1) \wedge (t_2 \vee u_2 \vee v_2) \wedge \dots \wedge (t_m \vee u_m \vee v_m). \quad (31)$$

Here each  $t_j$ ,  $u_j$ , and  $v_j$  is  $x_k$  or  $\bar{x}_k$  for some  $k$ . The problem of deciding satisfiability for formulas in 3CNF is called "3SAT," and exercise 39 explains why it is not really easier than satisfiability in general.

We will be seeing many examples of hard-to-crack 3SAT problems, especially in Section 7.9, where satisfiability testing will be discussed in great detail. The situation is a little peculiar, however, because a formula needs to be fairly long before we need to think twice about its satisfiability. For example, the shortest unsatisfiable formula in 3CNF is  $(x \vee x \vee x) \wedge (\bar{x} \vee \bar{x} \vee \bar{x})$ ; but it is obviously no challenge to the intellect. We don't get into rough waters unless the three literals  $t_j$ ,  $u_j$ ,  $v_j$  of a clause correspond to three different variables. And in that case, each clause rules out exactly  $1/8$  of the possibilities, because seven different settings of  $(t_j, u_j, v_j)$  will make it true. Consequently every such 3CNF with at most seven clauses is automatically satisfiable, and a random setting of its variables will succeed with probability  $\geq 1 - 7/8 = 1/8$ .

The shortest interesting formula in 3CNF therefore has at least eight clauses. And in fact, an interesting 8-clause formula does exist, based on the associative block design by R. L. Rivest that we considered in 6.5-(13):

$$\begin{aligned} & (x_2 \vee x_3 \vee \bar{x}_4) \wedge (x_1 \vee x_3 \vee x_4) \wedge (\bar{x}_1 \vee x_2 \vee x_4) \wedge (\bar{x}_1 \vee \bar{x}_2 \vee x_3) \\ & \wedge (\bar{x}_2 \vee \bar{x}_3 \vee x_4) \wedge (\bar{x}_1 \vee \bar{x}_3 \vee \bar{x}_4) \wedge (x_1 \vee \bar{x}_2 \vee \bar{x}_4) \wedge (x_1 \vee x_2 \vee \bar{x}_3). \end{aligned} \quad (32)$$

Any seven of these eight clauses are satisfiable, in exactly two ways, and they force the values of three variables; for example, the first seven imply that we have  $x_1 x_2 x_3 = 001$ . But the complete set of eight cannot be satisfied simultaneously.

**Simple special cases.** Two important classes of Boolean formulas have been identified for which the satisfiability problem does turn out to be pretty easy. These special cases arise when the conjunctive normal form being tested consists entirely of “Horn clauses” or entirely of “Krom clauses.” A *Horn clause* is an OR of literals in which all or nearly all of the literals are complemented—at most one of its literals is a pure, unbarred variable. A *Krom clause* is an OR of exactly two literals. Thus, for example,

$$\bar{x} \vee \bar{y}, \quad w \vee \bar{y} \vee \bar{z}, \quad \bar{u} \vee \bar{v} \vee \bar{w} \vee \bar{x} \vee \bar{y} \vee z, \quad \text{and} \quad x$$

are examples of Horn clauses; and

$$x \vee x, \quad \bar{x} \vee \bar{x}, \quad \bar{x} \vee \bar{y}, \quad x \vee \bar{y}, \quad \bar{x} \vee y, \quad \text{and} \quad x \vee y$$

are examples of Krom clauses, only the last of which is not also a Horn clause. (The first example qualifies because  $x \vee x = x$ .) Notice that a Horn clause is allowed to contain any number of literals, but when we restrict ourselves to Krom clauses we are essentially considering the 2SAT problem. In both cases we will see that satisfiability can be decided in linear time—that is, by carrying out only  $O(N)$  simple steps, when given a formula of length  $N$ .

Let’s consider Horn clauses first. Why are they so easy to handle? The main reason is that a clause like  $\bar{u} \vee \bar{v} \vee \bar{w} \vee \bar{x} \vee \bar{y} \vee z$  can be recast in the form  $\neg(u \wedge v \wedge w \wedge x \wedge y) \vee z$ , which is the same as

$$u \wedge v \wedge w \wedge x \wedge y \Rightarrow z.$$

In other words, if  $u$ ,  $v$ ,  $w$ ,  $x$ , and  $y$  are all true, then  $z$  must also be true. For this reason, parameterized Horn clauses were chosen to be the basic underlying mechanism of the programming language called Prolog. Furthermore there is an easy way to characterize exactly which Boolean functions can be represented entirely with Horn clauses:

**Theorem H.** *The Boolean function  $f(x_1, \dots, x_n)$  is expressible as a conjunction of Horn clauses if and only if*

$$f(x_1, \dots, x_n) = f(y_1, \dots, y_n) = 1 \quad \text{implies} \quad f(x_1 \wedge y_1, \dots, x_n \wedge y_n) = 1 \quad (33)$$

for all Boolean values  $x_j$  and  $y_j$ .

*Proof.* [Alfred Horn, *J. Symbolic Logic* **16** (1951), 14–21, Lemma 7.] If we have  $x_0 \vee \bar{x}_1 \vee \dots \vee \bar{x}_k = 1$  and  $y_0 \vee \bar{y}_1 \vee \dots \vee \bar{y}_k = 1$ , then

$$\begin{aligned} (x_0 \wedge y_0) \vee \overline{x_1 \wedge y_1} \vee \dots \vee \overline{x_k \wedge y_k} \\ = (x_0 \vee \bar{x}_1 \vee \bar{y}_1 \vee \dots \vee \bar{x}_k \vee \bar{y}_k) \wedge (y_0 \vee \bar{x}_1 \vee \bar{y}_1 \vee \dots \vee \bar{x}_k \vee \bar{y}_k) \\ \geq (x_0 \vee \bar{x}_1 \vee \dots \vee \bar{x}_k) \wedge (y_0 \vee \bar{y}_1 \vee \dots \vee \bar{y}_k) = 1; \end{aligned}$$

and a similar (but simpler) calculation applies when the unbarred literals  $x_0$  and  $y_0$  are not present. Therefore every conjunction of Horn clauses satisfies (33).

Conversely, condition (33) implies that every prime clause of  $f$  is a Horn clause (see exercise 44). ■

Let's say that a *Horn function* is a Boolean function that satisfies condition (33), and let's also call it *proper* if it satisfies the further condition  $f(1, \dots, 1) = 1$ . It's easy to see that a conjunction of Horn clauses is proper if and only if each clause has *exactly* one unbarred literal, because only an entirely negative clause like  $\bar{x} \vee \bar{y}$  will fail if all variables are true. Proper Horn functions are slightly simpler to work with than Horn functions in general, because they are obviously always satisfiable. Thus, by Theorem H, they have a unique least vector  $x$  such that  $f(x) = 1$ , namely the bitwise AND of all vectors that satisfy all clauses. The *core* of a proper Horn function is the set of all variables  $x_j$  that are true in this minimum vector  $x$ . Notice that the variables in the core must be true whenever  $f$  is true, so we can essentially factor them out.

Proper Horn functions arise in many ways, for example in the analysis of games (see exercises 50 and 51). Another nice example comes from compiler technology. Consider the following typical (but simplified) grammar for algebraic expressions in a programming language:

$$\begin{aligned}
 \langle \text{expression} \rangle &\rightarrow \langle \text{term} \rangle \mid \langle \text{expression} \rangle + \langle \text{term} \rangle \mid \langle \text{expression} \rangle - \langle \text{term} \rangle \\
 \langle \text{term} \rangle &\rightarrow \langle \text{factor} \rangle \mid -\langle \text{factor} \rangle \mid \langle \text{term} \rangle * \langle \text{factor} \rangle \mid \langle \text{term} \rangle / \langle \text{factor} \rangle \\
 \langle \text{factor} \rangle &\rightarrow \langle \text{variable} \rangle \mid \langle \text{constant} \rangle \mid (\langle \text{expression} \rangle) \\
 \langle \text{variable} \rangle &\rightarrow \langle \text{letter} \rangle \mid \langle \text{variable} \rangle \langle \text{letter} \rangle \mid \langle \text{variable} \rangle \langle \text{digit} \rangle \\
 \langle \text{letter} \rangle &\rightarrow a \mid b \mid c \\
 \langle \text{constant} \rangle &\rightarrow \langle \text{digit} \rangle \mid \langle \text{constant} \rangle \langle \text{digit} \rangle \\
 \langle \text{digit} \rangle &\rightarrow 0 \mid 1
 \end{aligned} \tag{34}$$

For example, the string  $a/(-b0-10)+cc*cc$  meets the syntax for  $\langle \text{expression} \rangle$  and uses each of the grammatical rules at least once.

Suppose we want to know what pairs of characters can appear next to each other in such expressions. Proper Horn clauses provide the answer, because we can set the problem up as follows: Let the quantities  $Xx$ ,  $xX$ , and  $xy$  denote Boolean “propositions,” where  $X$  is one of the symbols  $\{E, T, F, V, L, C, D\}$  standing respectively for  $\langle \text{expression} \rangle$ ,  $\langle \text{term} \rangle$ ,  $\dots$ ,  $\langle \text{digit} \rangle$ , and where  $x$  and  $y$  are symbols in the set  $\{+, -, *, /, (, ), a, b, c, 0, 1\}$ . The proposition  $Xx$  means, “ $X$  can end with  $x$ ”; similarly,  $xX$  means, “ $X$  can start with  $x$ ”; and  $xy$  means, “The character  $x$  can be followed immediately by  $y$  in an expression.” (There are  $7 \times 11 + 11 \times 7 + 11 \times 11 = 275$  propositions altogether.) Then we can write

$$\begin{array}{llllll}
 xT \Rightarrow xE & \Rightarrow -T & xC \Rightarrow xF & Vx \wedge yL \Rightarrow xy & \Rightarrow Lc & \\
 Tx \Rightarrow Ex & xF \Rightarrow -x & Cx \Rightarrow Fx & Vx \wedge yD \Rightarrow xy & xD \Rightarrow xC & \\
 Ex \Rightarrow x+ & Tx \Rightarrow x* & \Rightarrow (F & Dx \Rightarrow Vx & Dx \Rightarrow Cx & \\
 xT \Rightarrow +x & xF \Rightarrow *x & xE \Rightarrow (x & \Rightarrow aL & Cx \wedge yD \Rightarrow xy & \\
 Ex \Rightarrow x- & Tx \Rightarrow x/ & Ex \Rightarrow x) & \Rightarrow La & \Rightarrow OD & \\
 xT \Rightarrow -x & xF \Rightarrow /x & \Rightarrow F) & \Rightarrow bL & \Rightarrow DO & \\
 xF \Rightarrow xT & xV \Rightarrow xF & xL \Rightarrow xV & \Rightarrow Lb & \Rightarrow 1D & \\
 Fx \Rightarrow Tx & Vx \Rightarrow Fx & Lx \Rightarrow Vx & \Rightarrow cL & \Rightarrow D1 & 
 \end{array} \tag{35}$$

where  $x$  and  $y$  run through the eleven terminal symbols  $\{+, \dots, 1\}$ . This schematic specification gives us a total of  $24 \times 11 + 3 \times 11 \times 11 + 13 \times 1 = 640$  proper



Horn clauses, which we could write out formally as

$$(\overline{+T} \vee +E) \wedge (\overline{-T} \vee -E) \wedge \cdots \wedge (\overline{V+} \vee \overline{OL} \vee +0) \wedge \cdots \wedge (D1)$$

if we prefer the cryptic notation of Boolean algebra to the  $\Rightarrow$  convention of (35).

Why did we do this? Because *the core of all these clauses is the set of all propositions that are true in this particular grammar*. For example, one can verify that  $-E$  is true, hence the symbols  $(-)$  can occur next to each other within an expression; but the symbol pairs  $++$  and  $*-$  cannot (see exercise 46).

Furthermore, we can find the core of any given set of proper Horn clauses without great difficulty. We just start out with the propositions that appear alone, on the right-hand side of  $\Rightarrow$  when the left-hand side is empty; thirteen clauses of that kind appear in (35). And once we assert the truth of those propositions, we might find one or more clauses whose left-hand sides are now known to be true. Hence their right-hand sides also belong to the core, and we can keep going in the same way. The whole procedure is pretty much like letting water run downhill until it has found its proper level. In fact, when we choose appropriate data structures, this downhill process goes quite fast, requiring only  $O(N+n)$  steps, when  $N$  denotes the total length of the clauses and  $n$  is the number of propositional variables. (We assume here that all clauses have been expanded out, not abbreviated in terms of parameters like  $x$  and  $y$  above. More sophisticated techniques of theorem proving are available to deal with parameterized clauses, but they are beyond the scope of our present discussion.)

**Algorithm C** (*Core computation for proper Horn clauses*). Given a set  $P$  of propositional variables and a set  $C$  of clauses, each having the form

$$u_1 \wedge \cdots \wedge u_k \Rightarrow v \quad \text{where } k \geq 0 \text{ and } \{u_1, \dots, u_k, v\} \subseteq P, \quad (36)$$

this algorithm finds the set  $Q \subseteq P$  of all propositional variables that are necessarily true whenever all of the clauses are true.

We use the following data structures for clauses  $c$ , propositions  $p$ , and hypotheses  $h$ , where a “hypothesis” is the appearance of a proposition on the left-hand side of a clause:

- CONCLUSION( $c$ ) is the proposition on the right of clause  $c$ ;
- COUNT( $c$ ) is the number of hypotheses of  $c$  not yet asserted;
- TRUTH( $p$ ) is 1 if  $p$  is known to be true, otherwise 0;
- LAST( $p$ ) is the last hypothesis in which  $p$  appears;
- CLAUSE( $h$ ) is the clause for which  $h$  appears on the left;
- PREV( $h$ ) is the previous hypothesis containing the proposition of  $h$ .

We also maintain a stack  $S_0, S_1, \dots, S_{s-1}$  of all propositions that are known to be true but not yet asserted.

**C1.** [Initialize.] Set LAST( $p$ )  $\leftarrow \Lambda$  and TRUTH( $p$ )  $\leftarrow 0$  for each proposition  $p$ . Also set  $s \leftarrow 0$ , so that the stack is empty. Then for each clause  $c$ , having the form (36), set CONCLUSION( $c$ )  $\leftarrow v$  and COUNT( $c$ )  $\leftarrow k$ . If  $k = 0$  and

$\text{TRUTH}(v) = 0$ , set  $\text{TRUTH}(v) \leftarrow 1$ ,  $S_s \leftarrow v$ , and  $s \leftarrow s + 1$ . Otherwise, for  $1 \leq j \leq k$ , create a hypothesis record  $h$  and set  $\text{CLAUSE}(h) \leftarrow c$ ,  $\text{PREV}(h) \leftarrow \text{LAST}(u_j)$ ,  $\text{LAST}(u_j) \leftarrow h$ .

- C2.** [Prepare to assert  $p$ .] Terminate the algorithm if  $s = 0$ ; the desired core now consists of all propositions whose  $\text{TRUTH}$  has been set to 1. Otherwise set  $s \leftarrow s - 1$ ,  $p \leftarrow S_s$ , and  $h \leftarrow \text{LAST}(p)$ .
- C3.** [Done with hypotheses?] If  $h = \Lambda$ , return to C2.
- C4.** [Validate  $h$ .] Set  $c \leftarrow \text{CLAUSE}(h)$  and  $\text{COUNT}(c) \leftarrow \text{COUNT}(c) - 1$ . If the new value of  $\text{COUNT}(c)$  is still nonzero, go to step C6.
- C5.** [Deduce  $\text{CONCLUSION}(c)$ .] Set  $p \leftarrow \text{CONCLUSION}(c)$ . If  $\text{TRUTH}(p) = 0$ , set  $\text{TRUTH}(p) \leftarrow 1$ ,  $S_s \leftarrow p$ ,  $s \leftarrow s + 1$ .
- C6.** [Loop on  $h$ .] Set  $h \leftarrow \text{PREV}(h)$  and return to C3. ■

Notice how smoothly the data structures work together, avoiding any need to search for a place to make progress in the calculation. Algorithm C is similar in many respects to Algorithm 2.2.3T (topological sorting), which was the first example of multilinked data structures that we discussed long ago in Chapter 2; in fact, we can regard Algorithm 2.2.3T as the special case of Algorithm C in which every proposition appears on the right-hand side of exactly one clause. (See exercise 47.)

Exercise 48 shows that a slight modification of Algorithm C solves the satisfiability problem for Horn clauses in general. Further discussion can be found in a paper by W. F. Dowling and J. H. Gallier, *J. Logic Programming* **1** (1984), 267–284.

We turn now to Krom functions and the 2SAT problem. Again there's a linear-time algorithm; but again, we can probably appreciate it best if we look first at a simplified-but-practical application. Let's suppose that seven comedians have each agreed to do one-night standup gigs at two of five hotels during a three-day festival, but each of them is available for only two of those days because of other commitments:

- Tomlin should do Aladdin and Caesars on days 1 and 2;
  - Unwin should do Bellagio and Excalibur on days 1 and 2;
  - Vegas should do Desert and Excalibur on days 2 and 3;
  - Williams should do Aladdin and Desert on days 1 and 3;
  - Xie should do Caesars and Excalibur on days 1 and 3;
  - Yankovic should do Bellagio and Desert on days 2 and 3;
  - Zany should do Bellagio and Caesars on days 1 and 2.
- (37)

Is it possible to schedule them all without conflict?

To solve this problem, we can introduce seven Boolean variables  $\{t, u, v, w, x, y, z\}$ , where  $t$  (for example) means that Tomlin does Aladdin on day 1 and Caesars on day 2 while  $\bar{t}$  means that the days and hotels occur in the opposite order. Then we can set up constraints to ensure that no two comedians are

booked in the same hotel on the same day:

$$\begin{array}{llll}
 \neg(t \wedge w) & [A1] & \neg(y \wedge \bar{z}) & [B2] & \neg(t \wedge z) & [C2] & \neg(w \wedge y) & [D3] \\
 \neg(u \wedge z) & [B1] & \neg(\bar{t} \wedge x) & [C1] & \neg(v \wedge \bar{y}) & [D2] & \neg(\bar{u} \wedge \bar{x}) & [E1] \\
 \neg(\bar{u} \wedge y) & [B2] & \neg(\bar{t} \wedge \bar{z}) & [C1] & \neg(\bar{v} \wedge w) & [D3] & \neg(u \wedge \bar{v}) & [E2] \\
 \neg(\bar{u} \wedge \bar{z}) & [B2] & \neg(x \wedge \bar{z}) & [C1] & \neg(\bar{v} \wedge y) & [D3] & \neg(v \wedge x) & [E3]
 \end{array} \quad (38)$$

Each of these constraints is, of course, a Krom clause; we must satisfy

$$\begin{aligned}
 & (\bar{t} \vee \bar{w}) \wedge (\bar{u} \vee \bar{z}) \wedge (u \vee \bar{y}) \wedge (u \vee z) \wedge (\bar{y} \vee z) \wedge (t \vee \bar{x}) \wedge (t \vee z) \wedge (\bar{x} \vee z) \\
 & \wedge (\bar{t} \vee \bar{z}) \wedge (\bar{v} \vee y) \wedge (v \vee \bar{w}) \wedge (v \vee \bar{y}) \wedge (\bar{w} \vee \bar{y}) \wedge (u \vee x) \wedge (\bar{u} \vee v) \wedge (\bar{v} \vee \bar{x}). \quad (39)
 \end{aligned}$$

Furthermore, Krom clauses (like Horn clauses) can be written as implications:

$$\begin{aligned}
 & t \Rightarrow \bar{w}, \quad u \Rightarrow \bar{z}, \quad \bar{u} \Rightarrow \bar{y}, \quad \bar{u} \Rightarrow z, \quad y \Rightarrow z, \quad \bar{t} \Rightarrow \bar{x}, \quad \bar{t} \Rightarrow z, \quad x \Rightarrow z, \\
 & t \Rightarrow \bar{z}, \quad v \Rightarrow y, \quad \bar{v} \Rightarrow \bar{w}, \quad \bar{v} \Rightarrow \bar{y}, \quad w \Rightarrow \bar{y}, \quad \bar{u} \Rightarrow x, \quad u \Rightarrow v, \quad v \Rightarrow \bar{x}. \quad (40)
 \end{aligned}$$

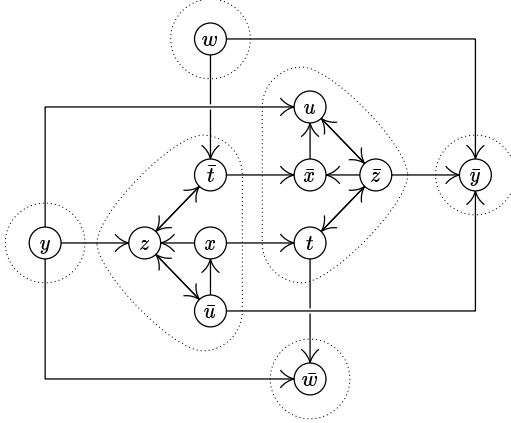
And every such implication also has an alternative, “contrapositive” form:

$$\begin{aligned}
 & w \Rightarrow \bar{t}, \quad z \Rightarrow \bar{u}, \quad y \Rightarrow u, \quad \bar{z} \Rightarrow u, \quad \bar{z} \Rightarrow \bar{y}, \quad x \Rightarrow t, \quad \bar{z} \Rightarrow t, \quad \bar{z} \Rightarrow \bar{x}, \\
 & z \Rightarrow \bar{t}, \quad \bar{y} \Rightarrow \bar{v}, \quad w \Rightarrow v, \quad y \Rightarrow v, \quad y \Rightarrow \bar{w}, \quad \bar{x} \Rightarrow u, \quad \bar{v} \Rightarrow \bar{u}, \quad x \Rightarrow \bar{v}. \quad (41)
 \end{aligned}$$

But oops — alas — there is a vicious cycle,

$$\begin{array}{ccccccccccc}
 u & \Rightarrow & \bar{z} & \Rightarrow & \bar{y} & \Rightarrow & \bar{v} & \Rightarrow & \bar{u} & \Rightarrow & z & \Rightarrow & \bar{t} & \Rightarrow & \bar{x} & \Rightarrow & u \\
 [B1] & & [B2] & & [D2] & & [E2] & & [B2] & & [C2] & & [C1] & & [E1]
 \end{array} \quad (42)$$

This cycle tells that  $u$  and  $\bar{u}$  must both have the same value; so there is no way to accommodate all of the conditions in (37). The festival organizers will have to renegotiate their agreement with at least one of the six comedians  $\{t, u, v, x, y, z\}$ , if a viable schedule is to be achieved. (See exercise 52.)



**Fig. 4.** The digraph corresponding to all implications of (40) and (41) that do not involve either  $v$  or  $\bar{v}$ . Assigning appropriate values to the literals in each strong component will solve a binary scheduling problem that is an instance of 2SAT.

The organizers might, for instance, try to leave  $v$  out of the picture temporarily. Then five of the sixteen constraints in (38) would go away and only 22 of the implications from (40) and (41) would remain, leaving the directed graph illustrated in Fig. 4. This digraph does contain cycles, like  $z \Rightarrow \bar{u} \Rightarrow x \Rightarrow z$  and  $t \Rightarrow \bar{z} \Rightarrow t$ ; but no cycle contains both a variable and its complement. Indeed,

we can see from Fig. 4 that the values  $tuwxyz = 110000$  do satisfy every clause of (39) that doesn't involve  $v$  or  $\bar{v}$ . These values give us a schedule that satisfies six of the seven original stipulations in (37), starting with (Tomlin, Unwin, Zany, Williams, Xie) at the (Aladdin, Bellagio, Caesars, Desert, Excalibur) on day 1.

In general, given any 2SAT problem with  $m$  Krom clauses that involve  $n$  Boolean variables, we can form a directed graph in the same way. There are  $2n$  vertices  $\{x_1, \bar{x}_1, \dots, x_n, \bar{x}_n\}$ , one for each possible literal; and there are  $2m$  arcs of the form  $\bar{u} \rightarrow v$  and  $\bar{v} \rightarrow u$ , two for each clause  $u \vee v$ . Two literals  $u$  and  $v$  belong to the same *strong component* of this digraph if and only if there are oriented paths from  $u$  to  $v$  and from  $v$  to  $u$ . For example, the six strong components of the digraph in Fig. 4 are indicated by dotted contours. All literals in a strong component must have the same Boolean value, in any solution to the corresponding 2SAT problem.

**Theorem K.** *A conjunctive normal form with two literals per clause is satisfiable if and only if no strong component of the associated digraph contains both a variable and its complement.*

*Proof.* [Melven Krom, *Zeitschrift für mathematische Logik und Grundlagen der Mathematik* **13** (1967), 15–20, Corollary 2.2.] If there are paths from  $x$  to  $\bar{x}$  and from  $\bar{x}$  to  $x$ , the formula is certainly unsatisfiable.

Conversely, assume that no such paths exist. Any digraph has at least one strong component  $S$  that is a “source,” having no incoming arcs from vertices in any other strong component. Moreover, our digraph always has an attractive antisymmetry, illustrated in Fig. 4: We have  $u \rightarrow v$  if and only if  $\bar{v} \rightarrow \bar{u}$ . Therefore the complements of the literals in  $S$  form another strong component  $\bar{S} \neq S$  that is a “sink,” having no *outgoing* arcs to other strong components. Hence we can assign the value 0 to all literals in  $S$  and 1 to all literals in  $\bar{S}$ , then remove them from the digraph and proceed in the same way until all literals have received a value. The resulting values satisfy  $u \leq v$  whenever  $u \rightarrow v$  in the digraph; hence they satisfy  $\bar{u} \vee v$  whenever  $\bar{u} \vee v$  is a clause of the formula. ■

Theorem K leads immediately to an efficient solution of the 2SAT problem, because of an algorithm by R. E. Tarjan that finds strong components in linear time. [See *SICOMP* **1** (1972), 146–160; D. E. Knuth, *The Stanford GraphBase*, 512–519.] We shall study Tarjan's algorithm in detail in Section 7.4.1. Exercise 53 shows that the condition of Theorem K is readily checked whenever the algorithm detects a new strong component. Furthermore, the algorithm detects “sinks” first; thus, as a simple byproduct of Tarjan's procedure, we can assign values that establish satisfiability by choosing the value 1 for each literal in a strong component that occurs before its complement.

**Medians.** We've been focusing on Boolean binary operations like  $x \vee y$  or  $x \oplus y$ . But there's also a significant *ternary* operation  $\langle xyz \rangle$ , called the *median* of  $x$ ,  $y$ , and  $z$ :

$$\langle xyz \rangle = (x \wedge y) \vee (y \wedge z) \vee (x \wedge z) = (x \vee y) \wedge (y \vee z) \wedge (x \vee z). \quad (43)$$

In fact,  $\langle xyz \rangle$  is probably the most important ternary operation in the entire universe, because it has amazing properties that are continually being discovered and rediscovered.

In the first place, we can see easily that this formula for  $\langle xyz \rangle$  describes the *majority* value of any three Boolean quantities  $x$ ,  $y$ , and  $z$ :  $\langle 000 \rangle = \langle 001 \rangle = 0$  and  $\langle 011 \rangle = \langle 111 \rangle = 1$ . We call  $\langle xyz \rangle$  the “median” instead of the “majority” because, if  $x$ ,  $y$ , and  $z$  are arbitrary *real* numbers, and if the operations  $\wedge$  and  $\vee$  denote min and max, then

$$\langle xyz \rangle = y \quad \text{when } x \leq y \leq z. \quad (44)$$

Secondly, the basic binary operations  $\wedge$  and  $\vee$  are special cases of medians:

$$x \wedge y = \langle x0y \rangle; \quad x \vee y = \langle x1y \rangle. \quad (45)$$

Thus *any* monotone Boolean function can be expressed entirely in terms of the ternary median operator and the constants 0 and 1. In fact, if we lived in a median-only world, we could let  $\wedge$  stand for falsehood and  $\vee$  for truth; then  $x \wedge y = \langle x \wedge y \rangle$  and  $x \vee y = \langle x \vee y \rangle$  would be perfectly natural expressions, and we could even use Polish notation like  $\langle \wedge xy \rangle$  and  $\langle \vee xy \rangle$  if that was our preference! The same idea applies to extended real numbers under the min-max interpretation of  $\wedge$  and  $\vee$ , if we take medians with respect to the constants  $\wedge = -\infty$  and  $\vee = +\infty$ .

A Boolean function  $f(x_1, x_2, \dots, x_n)$  is called *self-dual* when it satisfies

$$\overline{f(x_1, x_2, \dots, x_n)} = f(\bar{x}_1, \bar{x}_2, \dots, \bar{x}_n). \quad (46)$$

We’ve noted that a Boolean function is monotone if and only if it can be expressed in terms of  $\wedge$  and  $\vee$ ; by De Morgan’s laws (11) and (12), a monotone formula is self-dual if and only if the symbols  $\wedge$  and  $\vee$  can be interchanged without changing the formula’s value. Thus the median operation defined in (43) is both monotone and self-dual. In fact, it is the simplest nontrivial function of that kind, since none of the binary operations in Table 1 are both monotone and self-dual except the projections  $\perp$  and  $\top$ .

Furthermore, *any* expression that has been formed entirely with the median operator, without using constants, is both monotone and self-dual. For example, the function  $\langle w \langle xyz \rangle \langle w \langle uvw \rangle x \rangle \rangle$  is self-dual because

$$\begin{aligned} \overline{\langle w \langle xyz \rangle \langle w \langle uvw \rangle x \rangle} &= \langle \bar{w} \overline{\langle xyz \rangle} \overline{\langle w \langle uvw \rangle x \rangle} \rangle \\ &= \langle \bar{w} \langle \bar{x} \bar{y} \bar{z} \rangle \langle \bar{w} \overline{\langle uvw \rangle} \bar{x} \rangle \rangle = \langle \bar{w} \langle \bar{x} \bar{y} \bar{z} \rangle \langle \bar{w} \langle \bar{u} \bar{v} \bar{w} \rangle \bar{x} \rangle \rangle. \end{aligned}$$

Emil Post, while working on his Ph.D. thesis (1920), proved that the converse statement is also true:

**Theorem P.** *Every monotone, self-dual Boolean function  $f(x_1, \dots, x_n)$  can be expressed entirely in terms of the median operation  $\langle xyz \rangle$ .*

*Proof.* [Annals of Mathematics Studies 5 (1941), 74–75.] Observe first that

$$\begin{aligned} & \langle x_1 y \langle x_2 y \dots y \langle x_{s-1} y x_s \rangle \dots \rangle \rangle \\ &= ((x_1 \vee x_2 \vee \dots \vee x_{s-1} \vee x_s) \wedge y) \vee (x_1 \wedge x_2 \wedge \dots \wedge x_{s-1} \wedge x_s); \end{aligned} \quad (47)$$

this formula for repeated medianing is easily proved by induction on  $s$ .

Now suppose  $f(x_1, \dots, x_n)$  is monotone, self-dual, and has the disjunctive prime form

$$f(x_1, \dots, x_n) = t_1 \vee \dots \vee t_m, \quad t_j = x_{j_1} \wedge \dots \wedge x_{j_{s_j}},$$

where no prime implicant  $t_j$  is contained in another (Corollary Q). Any two prime implicants must have at least one variable in common. For if we had, say,  $t_1 = x \wedge y$  and  $t_2 = u \wedge v \wedge w$ , the value of  $f$  would be 1 when  $x = y = 1$  and  $u = v = w = 0$ , as well as when  $x = y = 0$  and  $u = v = w = 1$ , contradicting self-duality. Therefore if any  $t_j$  consists of a single variable  $x$ , it must be the only prime implicant—in which case  $f$  is the trivial function  $f(x_1, \dots, x_n) = x = \langle x x x \rangle$ .

Define the functions  $g_0, g_1, \dots, g_m$  by composing medians as follows:

$$\begin{aligned} g_0(x_1, \dots, x_n) &= \langle x_1 x_1 x_1 \rangle; \\ g_j(x_1, \dots, x_n) &= h(x_{j_1}, \dots, x_{j_{s_j}}; g_{j-1}(x_1, \dots, x_n)), \text{ for } 1 \leq j \leq m; \end{aligned} \quad (48)$$

here  $h(x_1, \dots, x_s; y)$  denotes the function on the top line of (47). By induction on  $j$ , we can prove from (47) and (48) that  $g_j(x_1, \dots, x_n) = 1$  whenever we have  $t_1 \vee \dots \vee t_j = 1$ , because  $(x_{j_1} \vee \dots \vee x_{j_{s_j}}) \wedge t_k = t_k$  when  $k < j$ .

Finally,  $f(x_1, \dots, x_n)$  must equal  $g_m(x_1, \dots, x_n)$ , because both functions are monotone and self-dual, and we have shown that  $f(x_1, \dots, x_n) \leq g(x_1, \dots, x_n)$  for all combinations of 0s and 1s. This inequality suffices to prove equality, because a self-dual function equals 1 in exactly half of the  $2^n$  possible cases. ■

One consequence of Theorem P is that we can express the median of five elements via medians of three, because the median of any odd number of Boolean variables is obviously a monotone and self-dual Boolean function. Let's write  $\langle x_1 \dots x_{2k-1} \rangle$  for such a median. Then the disjunctive prime form of  $\langle v w x y z \rangle$  is

$$\begin{aligned} & (v \wedge w \wedge x) \vee (v \wedge w \wedge y) \vee (v \wedge w \wedge z) \vee (v \wedge x \wedge y) \vee (v \wedge x \wedge z) \\ & \vee (v \wedge y \wedge z) \vee (w \wedge x \wedge y) \vee (w \wedge x \wedge z) \vee (w \wedge y \wedge z) \vee (x \wedge y \wedge z); \end{aligned}$$

so the construction in the proof of Theorem P expresses  $\langle v w x y z \rangle$  as a huge formula  $g_{10}(v, w, x, y, z)$  involving 1,022 median-of-3 operations. Of course this expression isn't the shortest possible one; we actually have

$$\langle v w x y z \rangle = \langle v \langle x y z \rangle \langle w x \langle y z \rangle \rangle \rangle. \quad (49)$$

[See H. S. Müller and R. O. Winder, *IRE Transactions* **EC-11** (1962), 89–90.]

**\*Median algebras and median graphs.** We noted earlier that the ternary operation  $\langle x y z \rangle$  is useful when  $x, y$ , and  $z$  belong to any ordered set like the real numbers, when  $\wedge$  and  $\vee$  are regarded as the operators min and max. In fact, the operation  $\langle x y z \rangle$  also plays a useful role in far more general circumstances. A

*median algebra* is any set  $M$  on which a ternary operation  $\langle xyz \rangle$  is defined that takes elements of  $M$  into elements of  $M$  and obeys the following three axioms:

$$\langle xxy \rangle = x \quad (\text{majority law}); \quad (50)$$

$$\langle xyz \rangle = \langle xzy \rangle = \langle yxz \rangle = \langle yzx \rangle = \langle zxy \rangle = \langle zyx \rangle \quad (\text{commutative law}); \quad (51)$$

$$\langle xw \langle ywz \rangle \rangle = \langle \langle xwy \rangle wz \rangle \quad (\text{associative law}). \quad (52)$$

In the Boolean case, for example, the associative law (52) holds for  $w = 0$  and  $w = 1$  because  $\wedge$  and  $\vee$  are associative. Exercise 74 proves that these three axioms imply also a *distributive law* for medians, which has both a short form

$$\langle \langle xyz \rangle uv \rangle = \langle x \langle yuv \rangle \langle zuv \rangle \rangle \quad (53)$$

and a more symmetrical long form

$$\langle \langle xyz \rangle uv \rangle = \langle \langle xuv \rangle \langle yuv \rangle \langle zuv \rangle \rangle. \quad (54)$$

No simple proof of this fact is known, but we can at least verify the special case of (53) and (54) when  $y = u$  and  $z = v$ : We have

$$\langle \langle xyz \rangle yz \rangle = \langle xyz \rangle \quad (55)$$

because both sides equal  $\langle xy \langle zyz \rangle \rangle$ . In fact, the associative law (52) is just the special case  $y = u$  of (53). And with (55) and (52) we can also verify the case  $x = u$ :  $\langle \langle uyz \rangle uv \rangle = \langle vu \langle yuz \rangle \rangle = \langle \langle vuy \rangle uz \rangle = \langle \langle yuv \rangle uz \rangle = \langle \langle \langle yuv \rangle uv \rangle uz \rangle = \langle \langle yuv \rangle u \langle vuz \rangle \rangle = \langle u \langle yuv \rangle \langle zuv \rangle \rangle$ .

An *ideal* in a median algebra  $M$  is a set  $C \subseteq M$  for which we have

$$\langle xyz \rangle \in C \quad \text{whenever } x \in C, y \in C, \text{ and } z \in M. \quad (56)$$

If  $u$  and  $v$  are any elements of  $M$ , the *interval*  $[u \dots v]$  is defined as follows:

$$[u \dots v] = \{ \langle xuv \rangle \mid x \in M \}. \quad (57)$$

We say that “ $x$  is between  $u$  and  $v$ ” if and only if  $x \in [u \dots v]$ . According to these definitions,  $u$  and  $v$  themselves always belong to the interval  $[u \dots v]$ .

**Lemma M.** *Every interval  $[u \dots v]$  is an ideal, and  $x \in [u \dots v] \iff x = \langle u xv \rangle$ .*

*Proof.* Let  $\langle xuv \rangle$  and  $\langle yuv \rangle$  be arbitrary elements of  $[u \dots v]$ . Then

$$\langle \langle xuv \rangle \langle yuv \rangle z \rangle = \langle \langle xyz \rangle uv \rangle \in [u \dots v]$$

for all  $z \in M$ , by (51) and (53), so  $[u \dots v]$  is an ideal. Furthermore every element  $\langle xuv \rangle \in [u \dots v]$  satisfies  $\langle xuv \rangle = \langle u \langle xuv \rangle v \rangle$  by (51) and (55). ■

Our intervals  $[u \dots v]$  have nice properties, because of the median laws:

$$v \in [u \dots u] \implies u = v; \quad (58)$$

$$x \in [u \dots v] \text{ and } y \in [u \dots x] \implies y \in [u \dots v]; \quad (59)$$

$$x \in [u \dots v] \text{ and } y \in [u \dots z] \text{ and } y \in [v \dots z] \implies y \in [x \dots z]. \quad (60)$$

Equivalently,  $[u \dots u] = \{u\}$ ; if  $x \in [u \dots v]$  then  $[u \dots x] \subseteq [u \dots v]$ ; and  $x \in [u \dots v]$  also implies that  $[u \dots z] \cap [v \dots z] \subseteq [x \dots z]$  for all  $z$ . (See exercise 70.)

Now let's define a graph on the vertex set  $M$ , with the following edges:

$$u \text{ --- } v \iff u \neq v \text{ and } \langle xuv \rangle \in \{u, v\} \text{ for all } x \in M. \quad (6_1)$$

In other words,  $u$  and  $v$  are adjacent if and only if the interval  $[u..v]$  consists of just the two points  $u$  and  $v$ .

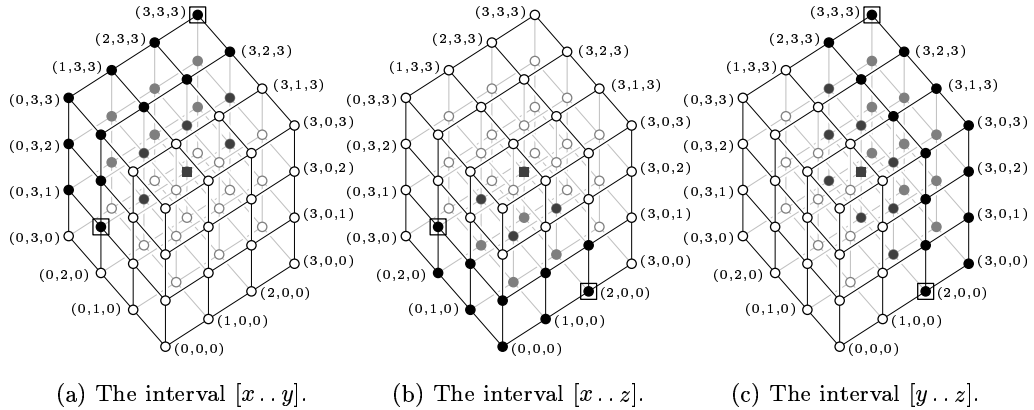
**Theorem G.** *If  $M$  is any finite median algebra, the graph defined by (6<sub>1</sub>) is connected. Moreover, vertex  $x$  belongs to the interval  $[u..v]$  if and only if  $x$  lies on a shortest path from  $u$  to  $v$ .*

*Proof.* If  $M$  isn't connected, choose  $u$  and  $v$  so that there is no path from  $u$  to  $v$  and the interval  $[u..v]$  has as few elements as possible. Let  $x \in [u..v]$  be distinct from  $u$  and  $v$ . Then  $\langle xuv \rangle = x \neq v$ , so  $v \notin [u..x]$ ; similarly  $u \notin [x..v]$ . But  $[u..x]$  and  $[x..v]$  are contained in  $[u..v]$ , by (59). So they are smaller intervals, and there must be a path from  $u$  to  $x$  and from  $x$  to  $v$ . Contradiction.

The other half of the theorem is proved in exercise 71. ■

Our definition of intervals implies that  $\langle xyz \rangle \in [x..y] \cap [x..z] \cap [y..z]$ , because  $\langle xyz \rangle = \langle \langle xyz \rangle xy \rangle = \langle \langle xyz \rangle xz \rangle = \langle \langle xyz \rangle yz \rangle$  by (55). Conversely, if  $w \in [x..y] \cap [x..z] \cap [y..z]$ , exercise 72 proves that  $w = \langle xyz \rangle$ . In other words, *the intersection  $[x..y] \cap [x..z] \cap [y..z]$  always contains exactly one point*, whenever  $x$ ,  $y$ , and  $z$  are points of  $M$ .

Figure 5 illustrates this principle in a  $4 \times 4 \times 4$  cube, where each point  $x$  has coordinates  $(x_1, x_2, x_3)$  with  $0 \leq x_1, x_2, x_3 < 4$ . The vertices of this cube form a median algebra because  $\langle xyz \rangle = (\langle x_1 y_1 z_1 \rangle, \langle x_2 y_2 z_2 \rangle, \langle x_3 y_3 z_3 \rangle)$ ; furthermore, the edges of the graph in Fig. 5 are those defined in (6<sub>1</sub>), running between vertices whose coordinates agree except that one coordinate changes by  $\pm 1$ . Three typical intervals  $[x..y]$ ,  $[x..z]$ , and  $[y..z]$  are shown; the only point common to all three intervals is the vertex  $\langle xyz \rangle = (2, 2, 1)$ .



**Fig. 5.** Intervals between the vertices  $x = (0, 2, 1)$ ,  $y = (3, 3, 3)$ , and  $z = (2, 0, 0)$  in a  $4 \times 4 \times 4$  cube.



So far we've started with a median algebra and used it to define a graph with certain properties. But we can also start with a graph that has those properties and use it to define a median algebra. If  $u$  and  $v$  are vertices of *any* graph, let us define the interval  $[u \dots v]$  to be the set of all points on shortest paths between  $u$  and  $v$ . A finite graph is said to be a *median graph* if exactly one vertex lies in the intersection  $[x \dots y] \cap [x \dots z] \cap [y \dots z]$  of the three intervals that tie any three given vertices  $x$ ,  $y$ , and  $z$  together; and we denote that vertex by  $\langle xyz \rangle$ . Exercise 73 proves that the resulting ternary operation satisfies the median axioms.

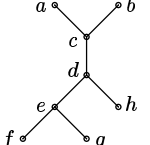
Many important graphs turn out to be median graphs according to this definition. For example, any free tree is easily seen to be a median graph; and a graph like the  $n_1 \times n_2 \times \dots \times n_m$  hyperrectangle provides another simple example. Cartesian products of arbitrary median graphs also satisfy the required condition.

**\*Median labels.** If  $u$  and  $v$  are any elements of a median algebra, the mapping  $f(x)$  that takes  $x \mapsto \langle xuv \rangle$  is a *homomorphism*; that is, it satisfies

$$f(\langle xyz \rangle) = \langle f(x)f(y)f(z) \rangle, \quad (62)$$

because of the long distributive law (54). This function “projects” any given point  $x$  into the interval  $[u \dots v]$ , by (57). And it is particularly interesting in the case when  $u \text{ --- } v$  is an edge of the corresponding graph, because  $f(x)$  is then essentially a Boolean mapping.

For example, consider the typical free tree shown below, with eight vertices and seven edges. We can project each vertex  $x$  onto each of the edge intervals  $[u \dots v]$  by deciding whether  $x$  is closer to  $u$  or to  $v$ :



	$ac$	$bc$	$cd$	$de$	$ef$	$eg$	$dh$	
$a \mapsto$	$a$	$c$	$c$	$d$	$e$	$e$	$d$	0000000
$b \mapsto$	$c$	$b$	$c$	$d$	$e$	$e$	$d$	1100000
$c \mapsto$	$c$	$c$	$c$	$d$	$e$	$e$	$d$	1000000
$d \mapsto$	$c$	$c$	$d$	$d$	$e$	$e$	$d$	1010000
$e \mapsto$	$c$	$c$	$d$	$e$	$e$	$e$	$d$	1011000
$f \mapsto$	$c$	$c$	$d$	$e$	$f$	$e$	$d$	1011100
$g \mapsto$	$c$	$c$	$d$	$e$	$e$	$g$	$d$	1011010
$h \mapsto$	$c$	$c$	$d$	$d$	$e$	$e$	$h$	1010001

$(63)$

On the right we've reduced the projections to 0s and 1s, arbitrarily deciding that  $a \mapsto 0000000$ . The resulting bit strings are called *labels* of the vertices, and we write, for example,  $l(b) = 1100000$ . Since each projection is a homomorphism, we can calculate the median of any three points by simply taking Boolean medians in each component of their labels. For example, to compute  $\langle bgh \rangle$  we find the bitwise median of  $l(b) = 1100000$ ,  $l(g) = 1011010$ , and  $l(h) = 1010001$ , namely  $1010000 = l(d)$ .

When we project onto all the edges of a median graph, we might find that two columns of the binary labels are identical. This situation cannot occur with a free tree, but let's consider what would happen if the edge  $g \text{ --- } h$  were added to the tree in (63): The resulting graph would still be a median graph, but the

columns for  $eg$  and  $dh$  would become identical (except with  $e \leftrightarrow d$  and  $g \leftrightarrow h$ ). Furthermore, the new column for  $gh$  would turn out to be equivalent to the column for  $de$ . Redundant components should be omitted from the labels in such cases; therefore the vertices of the augmented graph would have six-bit labels, like  $l(g) = 101101$  and  $l(h) = 101001$ , instead of seven-bit labels.

The elements of any median algebra can always be represented by labels in this way. Therefore *any identity that holds in the Boolean case will be true in all median algebras*. This “zero-one principle” makes it possible to test whether any two given expressions built from the ternary operation  $\langle xyz \rangle$  can be shown to be equal as a consequence of axioms (50), (51), and (52)—although we do have to check  $2^{n-1} - 1$  cases when we test  $n$ -variable expressions by this method.

For example, the associative law  $\langle xw \langle ywz \rangle \rangle = \langle \langle xwy \rangle wz \rangle$  suggests that there should be a symmetrical interpretation of both sides that does not involve nested brackets. And indeed, there is such a formula:

$$\langle xw \langle ywz \rangle \rangle = \langle \langle xwy \rangle wz \rangle = \langle xwywz \rangle, \quad (64)$$

where  $\langle xwywz \rangle$  denotes the median of the five-element multiset  $\{x, w, y, w, z\} = \{w, w, x, y, z\}$ . We can prove this formula by using the zero-one principle, noting also that median is the same thing as majority in the Boolean case. In a similar way we can prove (49), and we can show that the function used by Post in (47) can be simplified to

$$\langle x_1 y \langle x_2 y \dots y \langle x_{s-1} y x_s \rangle \dots \rangle \rangle = \langle x_1 y x_2 y \dots y x_{s-1} y x_s \rangle; \quad (65)$$

it's a median of  $2s - 1$  quantities, where nearly half of them are equal to  $y$ .

A set  $C$  of vertices in a graph is called *convex* if  $[u \dots v] \subseteq C$  whenever  $u \in C$  and  $v \in C$ . In other words, whenever the endpoints of a shortest path belong to  $C$ , all vertices of that path must also be present in  $C$ . (A convex set is therefore identical to what we called an “ideal,” a few pages ago; now our language has become geometric instead of algebraic.) The *convex hull* of  $\{v_1, \dots, v_m\}$  is defined to be the smallest convex set that contains each of the vertices  $v_1, \dots, v_m$ . Our theoretical results above have shown that every interval  $[u \dots v]$  is convex; hence  $[u \dots v]$  is the convex hull of the two-point set  $\{u, v\}$ . But in fact much more is true:

**Theorem C.** *The convex hull of  $\{v_1, v_2, \dots, v_m\}$  in a median graph is the set of all points*

$$C = \{ \langle v_1 x v_2 x \dots x v_m \rangle \mid x \in M \}. \quad (66)$$

Furthermore,  $x$  is in  $C$  if and only if  $x = \langle v_1 x v_2 x \dots x v_m \rangle$ .

*Proof.* Clearly  $v_j \in C$  for  $1 \leq j \leq m$ . Every point of  $C$  must belong to the convex hull, because the point  $x' = \langle v_2 x \dots x v_m \rangle$  is in the hull (by induction on  $m$ ), and because  $x \in [v_1 \dots x']$ . The zero-one principle proves that

$$\langle x \langle v_1 y v_2 y \dots y v_m \rangle \langle v_1 z v_2 z \dots z v_m \rangle \rangle = \langle v_1 \langle xyz \rangle v_2 \langle xyz \rangle \dots \langle xyz \rangle v_m \rangle; \quad (67)$$

hence  $C$  is convex. Setting  $x = y$  in this formula proves that  $\langle v_1 x v_2 x \dots x v_m \rangle$  is the closest point of  $C$  to  $x$ , and that  $\langle v_1 x v_2 x \dots x v_m \rangle \in [x \dots z]$  for all  $z \in C$ . ■

**Corollary C.** *Let the label of  $v_j$  be  $v_{j1} \dots v_{jt}$  for  $1 \leq j \leq m$ . Then the convex hull of  $\{v_1, \dots, v_m\}$  is the set of all  $x \in M$  whose label  $x_1 \dots x_t$  satisfies  $x_j = c_j$  whenever  $v_{1j} = v_{2j} = \dots = v_{mj} = c_j$ . ■*

For example, the convex hull of  $\{c, g, h\}$  in (63) consists of all elements whose label matches the pattern  $10**0**$ , namely  $\{c, d, e, g, h\}$ .

When a median graph contains a 4-cycle  $u - x - v - y - u$ , the edges  $u - x$  and  $v - y$  are equivalent, in the sense that projection onto  $[u \dots x]$  and projection onto  $[v \dots y]$  both yield the same label coordinates. The reason is that, for any  $z$  with  $\langle zux \rangle = u$ , we have

$$\begin{aligned} y &= \langle uvy \rangle = \langle \langle zux \rangle vy \rangle \\ &= \langle \langle zvy \rangle \langle uvy \rangle \langle xvy \rangle \rangle \\ &= \langle \langle zvy \rangle yv \rangle, \end{aligned}$$

hence  $\langle zvy \rangle = y$ ; similarly  $\langle zux \rangle = x$  implies  $\langle zvy \rangle = v$ . The edges  $x - v$  and  $y - u$  are equivalent for the same reasons. Exercise 75 shows, among other things, that two edges yield equivalent projections if and only if they can be proved equivalent by a chain of equivalences obtained from 4-cycles in this way. Therefore the number of bits in each vertex label is the number of equivalence classes of edges induced by the 4-cycles; and it follows that the reduced labels for vertices are uniquely determined, once we specify a vertex whose label is  $00 \dots 0$ .

A nice way to find the vertex labels of any median graph was discovered by J. Hagauer, W. Imrich, and S. Klavžar [*Theoretical Computer Science* **215** (1999), 123–136]:

**Algorithm H** (*Median labels*). Given a median graph  $G$  and a source vertex  $a$ , this algorithm determines the equivalence classes defined by the 4-cycles of  $G$ , and computes the labels  $l(v) = v_1 \dots v_t$  of each vertex, where  $t$  is the number of classes and  $l(a) = 0 \dots 0$ .

- H1.** [Initialize.] Preprocess  $G$  by visiting all vertices in order of their distance from  $a$ . For each edge  $u - v$ , we say that  $u$  is an *early neighbor* of  $v$  if  $a$  is closer to  $u$  than to  $v$ , otherwise  $u$  is a *late neighbor*; in other words, the early neighbors of  $v$  will already have been visited when  $v$  is encountered, but the late neighbors will still be awaiting their turn. Rearrange all adjacency lists so that early neighbors are listed first. Place each edge initially in its own equivalence class; a “union-find algorithm” like Algorithm 2.3.3E will be used to merge classes when the algorithm learns that they’re equivalent.
- H2.** [Call the subroutine.] Set  $j \leftarrow 0$  and invoke Subroutine I with parameter  $a$ . (Subroutine I appears below. The global variable  $j$  will be used to create a master list of edges  $r_j - s_j$  for  $1 \leq j < n$ , where  $n$  is the total number of vertices; there will be one entry with  $s_j = v$ , for each vertex  $v \neq a$ .)
- H3.** [Assign the labels.] Number the equivalence classes from 1 to  $t$ . Then set  $l(a)$  to the  $t$ -bit string  $0 \dots 0$ . For  $j = 1, 2, \dots, n - 1$  (in this order), set  $l(s_j)$  to  $l(r_j)$  with bit  $k$  changed from 0 to 1, where  $k$  is the equivalence class of edge  $r_j - s_j$ . ■

**Subroutine I** (*Process descendants of  $r$* ). This recursive subroutine, with parameter  $r$  and global variable  $j$ , does the main work of Algorithm H on the graph of all vertices currently reachable from vertex  $r$ . In the course of processing, all such vertices will be recorded on the master list, except  $r$  itself, and all edges between them will be removed from the current graph. Each vertex has four fields called its **LINK**, **MARK**, **RANK**, and **MATE**.

- I1.** [Loop over  $s$ .] Choose a vertex  $s$  with  $r \text{ --- } s$ . If there is no such vertex, return from the subroutine.
- I2.** [Record the edge.] Set  $j \leftarrow j + 1$ ,  $r_j \leftarrow r$ , and  $s_j \leftarrow s$ .
- I3.** [Begin breadth-first search.] (Now we want to find and delete all edges of the current graph that are equivalent to  $r \text{ --- } s$ .) Set **MARK**( $s$ )  $\leftarrow s$ , **RANK**( $s$ )  $\leftarrow 1$ , **LINK**( $s$ )  $\leftarrow \Lambda$ , and  $v \leftarrow q \leftarrow s$ .
- I4.** [Find the mate of  $v$ .] Find the early neighbor  $u$  of  $v$  for which **MARK**( $u$ )  $\neq s$ . (There will be exactly one such vertex  $u$ . Recall that early neighbors have been placed first, in step H1.) Set **MATE**( $v$ )  $\leftarrow u$ .
- I5.** [Delete  $u \text{ --- } v$ .] Make the edges  $u \text{ --- } v$  and  $r \text{ --- } s$  equivalent by merging their equivalence classes. Remove  $u$  and  $v$  from each other's adjacency lists.
- I6.** [Classify the neighbors of  $v$ .] For each early neighbor  $u$  of  $v$ , do step I7; for each late neighbor  $u$  of  $v$ , do step I8. Then go to step I9.
- I7.** [Note a possible equivalence.] If **MARK**( $u$ ) =  $s$  and **RANK**( $u$ ) = 1, make the edge  $u \text{ --- } v$  equivalent to the edge **MATE**( $u$ )  $\text{---}$  **MATE**( $v$ ). Return to I6.
- I8.** [Rank  $u$ .] If **MARK**( $u$ ) =  $s$  and **RANK**( $u$ ) = 1, return to I6. Otherwise set **MARK**( $u$ )  $\leftarrow s$  and **RANK**( $u$ )  $\leftarrow 2$ . Set  $w$  to the first neighbor of  $u$  (it will be early). If  $w = v$ , reset  $w$  to  $u$ 's second early neighbor; but return to I6 if  $u$  has only one early neighbor. If **MARK**( $w$ )  $\neq s$  or **RANK**( $w$ )  $\neq 2$ , set **RANK**( $u$ )  $\leftarrow 1$ , **LINK**( $u$ )  $\leftarrow \Lambda$ , **LINK**( $q$ )  $\leftarrow u$ , and  $q \leftarrow u$ . Return to I6.
- I9.** [Continue breadth-first search.] Set  $v \leftarrow \text{LINK}(v)$ . Return to I4 if  $v \neq \Lambda$ .
- I10.** [Process subgraph  $s$ .] Call Subroutine I recursively with parameter  $s$ . Then return to I1. ■

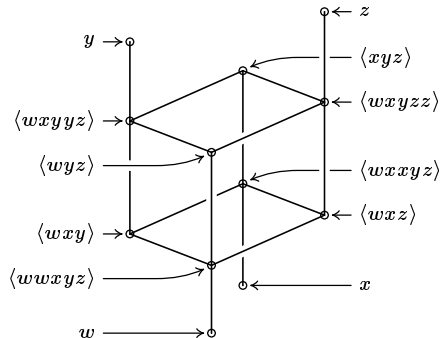
This algorithm and subroutine have been described in terms of relatively high-level data structures; further details are left to the reader. For example, adjacency lists should be doubly linked, so that edges can readily be deleted in step I5. Any convenient method for merging equivalence classes can be used in that step.

Exercise 75 explains the theory that makes this algorithm work, and exercise 76 proves that each vertex is encountered at most  $\lg n$  times in step I4. Furthermore, exercise 77 shows that a median graph has at most  $O(n \log n)$  edges. Therefore the total running time of Algorithm H is  $O(n(\log n)^2)$ , except perhaps for the bit-setting in step H3.

The reader may wish to play through Algorithm H by hand on the median graph in Table 2, whose vertices represent the twelve monotone self-dual Boolean functions of four variables  $\{w, x, y, z\}$ . All such functions that actually involve all four variables can be expressed as a median of five things, like (64). With

**Table 2**

LABELS FOR THE FREE MEDIAN ALGEBRA ON FOUR GENERATORS

	$j$	$r_j$	$s_j$	$l(s_j)$
			$w$	0000000
	1	$w$	$\langle wxyz \rangle$	0000001
	2	$\langle wxyz \rangle$	$\langle wyz \rangle$	0010001
	3	$\langle wyz \rangle$	$\langle wxyz \rangle$	0010101
	4	$\langle wxyz \rangle$	$\langle xyz \rangle$	0010111
	5	$\langle wxyz \rangle$	$z$	1010101
	6	$\langle wyz \rangle$	$\langle wxyz \rangle$	0010011
	7	$\langle wxyz \rangle$	$y$	0110011
	8	$\langle wxyz \rangle$	$\langle wxz \rangle$	0000101
	9	$\langle wxz \rangle$	$\langle wxyz \rangle$	0000111
	10	$\langle wxyz \rangle$	$x$	0001111
	11	$\langle wxyz \rangle$	$\langle wxy \rangle$	0000011

starting vertex  $a = w$ , the algorithm computes the master list of edges  $r_j \text{ --- } s_j$  and the binary labels shown in the table. (The actual order of processing depends on the order in which vertices appear in adjacency lists. But the final labels will be the same under any ordering, except for permutations of the columns.)

Notice that the number of 1-bits in each label  $l(v)$  is the distance of  $v$  from the starting vertex  $a$ . In fact, the uniqueness of labels tells us that *the distance between any two vertices is the number of bit positions in which their labels differ*, because we could have started at any particular vertex.

The special median graph in Table 2 could actually have been handled in a completely different way, without using Algorithm H at all, because the labels in this case are essentially the same as the *truth tables* of the corresponding functions. Here's why: We can say that the simple functions  $w$ ,  $x$ ,  $y$ ,  $z$  have the respective truth tables  $t(w) = 0000000011111111$ ,  $t(x) = 0000111100001111$ ,  $t(y) = 0011001100110011$ ,  $t(z) = 0101010101010101$ . Then the truth table of  $\langle wxyz \rangle$  is the bitwise majority function  $\langle t(w)t(x)t(y)t(z) \rangle$ , namely the string 0000000101111111; and a similar computation gives the truth tables of all the other vertices.

The last half of any self-dual function's truth table is the same as the first half, but complemented and reversed, so we can eliminate it. Furthermore the leftmost bit in each of our truth tables is always zero. We are left with the seven-bit labels shown in Table 2; and the uniqueness property guarantees that Algorithm H will produce the same result, except for possible permutation of columns, when it is presented with this particular graph.

This reasoning tells us that the edges of the graph in Table 2 correspond to pairs of functions whose truth tables are almost the same. We move between neighboring vertices by switching only two complementary bits of their truth tables. In fact, the degree of each vertex turns out to be exactly the number of prime implicants in the disjunctive prime form of the monotone self-dual function represented by that vertex (see exercises 68 and 82).

**\*Median sets.** A *median set* is a collection  $X$  of binary vectors with the property that  $\langle xyz \rangle \in X$  whenever  $x \in X$ ,  $y \in X$ , and  $z \in X$ , where the medians are computed componentwise as we've done with median labels. Thomas Schaefer noticed in 1978 that median sets provide us with an attractive counterpoint to the characterization of Horn functions in Theorem H:

**Theorem S.** *The Boolean function  $f(x_1, \dots, x_n)$  is expressible as a conjunction of Krom clauses if and only if*

$$\begin{aligned} f(x_1, \dots, x_n) = f(y_1, \dots, y_n) = f(z_1, \dots, z_n) = 1 \\ \text{implies } f(\langle x_1 y_1 z_1 \rangle, \dots, \langle x_n y_n z_n \rangle) = 1 \end{aligned} \quad (68)$$

for all Boolean values  $x_j$ ,  $y_j$ , and  $z_j$ .

*Proof.* [STOC 10 (1978), 216–226, Lemma 3.1B.] If we have  $x_1 \vee x_2 = y_1 \vee y_2 = z_1 \vee z_2 = 1$ , say, with  $x_1 \leq y_1 \leq z_1$ , then  $\langle x_1 y_1 z_1 \rangle \vee \langle x_2 y_2 z_2 \rangle = y_1 \vee \langle x_2 y_2 z_2 \rangle = 1$ , since  $y_1 = 0$  implies that  $x_2 = y_2 = 1$ . Thus (68) is necessary.

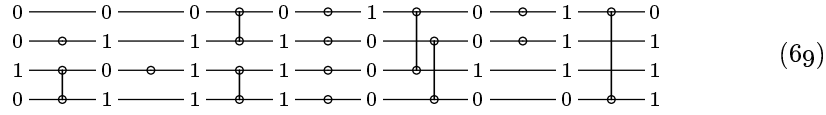
Conversely, if (68) holds, let  $u_1 \vee \dots \vee u_k$  be a prime clause of  $f$ , where each  $u_j$  is a literal. Then, for  $1 \leq j \leq k$ , the clause  $u_1 \vee \dots \vee u_{j-1} \vee u_{j+1} \vee \dots \vee u_k$  is not a clause of  $f$ ; so there's a vector  $x^{(j)}$  with  $f(x^{(j)}) = 1$  but with  $u_i^{(j)} = 0$  for all  $i \neq j$ . If  $k \geq 3$ , the median  $\langle x^{(1)} x^{(2)} x^{(3)} \rangle$  has  $u_i = 0$  for  $1 \leq i \leq k$ ; but that's impossible, because  $u_1 \vee \dots \vee u_k$  was supposedly a clause. Hence  $k \leq 2$ . ■

Thus median sets are the same as “2SAT instances,” the sets of points that satisfy some formula  $f$  in 2CNF.

A median set is said to be *reduced* if its vectors  $x = x_1 \dots x_t$  contain no redundant components. In other words, for each coordinate position  $k$ , a reduced median set has at least two vectors  $x^{(k)}$  and  $y^{(k)}$  with the property that  $x_k^{(k)} = 0$  and  $y_k^{(k)} = 1$  but  $x_i^{(k)} = y_i^{(k)}$  for all  $i \neq k$ . We've seen that the labels of a median graph satisfy this condition; in fact, if coordinate  $k$  corresponds to the edge  $u - v$  in the graph, we can let  $x^{(k)}$  and  $y^{(k)}$  be the labels of  $u$  and  $v$ . Conversely, any reduced median set  $X$  defines a median graph, with one vertex for each element of  $X$  and with adjacency defined by all-but-one equality of coordinates. The median labels of these vertices must be identical to the original vectors in  $X$ , because we know that median labels are essentially unique.

Median labels and reduced median sets can also be characterized in yet another instructive way, which harks back to the networks of *comparator modules* that we studied in Section 5.3.4. We noted in that section that such networks are useful for “oblivious sorting” of numbers, and we noted in Theorem 5.3.4Z that a network of comparators will sort all  $n!$  possible input permutations if and only if it correctly sorts all  $2^n$  combinations of 0s and 1s. When a comparator module is attached to two horizontal lines, with inputs  $x$  and  $y$  entering from the left, it outputs the same two values on the right, but with  $\min(x, y) = x \wedge y$  on the upper line and  $\max(x, y) = x \vee y$  on the lower line. Let's now extend the concept slightly by also allowing *inverter modules*, which change 0 to 1 and vice versa. Here, for example, is a comparator-inverter network (or CI-net, for

short), which transforms the binary value 0010 into 0111:



(A single dot denotes an inverter.) Indeed, this network transforms

$$\begin{array}{llll}
 0000 \mapsto 0110; & 0100 \mapsto 0111; & 1000 \mapsto 0111; & 1100 \mapsto 0110; \\
 0001 \mapsto 0111; & 0101 \mapsto 1111; & 1001 \mapsto 0101; & 1101 \mapsto 0111; \\
 0010 \mapsto 0111; & 0110 \mapsto 1111; & 1010 \mapsto 0101; & 1110 \mapsto 0111; \\
 0011 \mapsto 0110; & 0111 \mapsto 0111; & 1011 \mapsto 0111; & 1111 \mapsto 0110.
 \end{array} \quad (69)$$

Suppose a CI-net transforms the bit string  $x = x_1 \dots x_t$  into the bit string  $x'_1 \dots x'_t = f(x)$ . This function  $f$ , which maps the  $t$ -cube into itself, is in fact a *graph homomorphism*. In other words, we have  $f(x) \sim f(y)$  whenever  $x \sim y$  in the  $t$ -cube: Changing one bit of  $x$  always causes exactly one bit of  $f(x)$  to change, because every module in the network has this behavior. Moreover, CI-nets have a remarkable connection with median labels:

**Theorem F.** *Every set  $X$  of  $t$ -bit median labels can be represented by a comparator-inverter network that computes a Boolean function  $f(x)$  with the property that  $f(x) \in X$  for all bit vectors  $x_1 \dots x_t$ , and  $f(x) = x$  for all  $x \in X$ .*

*Proof.* [Tomás Feder, *Memoirs Amer. Math. Soc.* **555** (1995), 1–223, Lemma 3.37.] Consider columns  $i$  and  $j$  of the median labels, where  $1 \leq i < j \leq t$ . Any such pair of columns contains at least three of the four possibilities  $\{00, 01, 10, 11\}$ , if we look through the entire set of labels, because median labels have no redundant columns. Let us write  $\bar{j} \rightarrow i$ ,  $j \rightarrow i$ ,  $i \rightarrow j$ , or  $i \rightarrow \bar{j}$  if the value 00, 01, 10, or 11 (respectively) is missing from those two columns; we can also note the equivalent relations  $\bar{i} \rightarrow j$ ,  $\bar{i} \rightarrow \bar{j}$ ,  $\bar{j} \rightarrow \bar{i}$ , or  $j \rightarrow \bar{i}$ , respectively, which involve  $\bar{i}$  instead of  $i$ . For example, the labels in Table 2 give us the relations

$$\begin{array}{ll}
 1 \rightarrow \bar{2}, 3, \bar{4}, 5, \bar{6}, 7 & 2, \bar{3}, 4, \bar{5}, 6, \bar{7} \rightarrow \bar{1}; \\
 2 \rightarrow 3, \bar{4}, \bar{5}, 6, 7 & \bar{3}, 4, 5, \bar{6}, \bar{7} \rightarrow \bar{2}; \\
 3 \rightarrow \bar{4}, 7 & 4, \bar{7} \rightarrow \bar{3}; \\
 4 \rightarrow 5, 6, 7 & \bar{5}, \bar{6}, \bar{7} \rightarrow \bar{4}; \\
 5 \rightarrow 7 & \bar{7} \rightarrow \bar{5}; \\
 6 \rightarrow 7 & \bar{7} \rightarrow \bar{6}.
 \end{array} \quad (71)$$

(There is no relation between 3 and 5 because all four possibilities occur in those columns. But we have  $3 \rightarrow \bar{4}$  because 11 doesn't appear in columns 3 and 4. The vertices whose label has a 1 in column 3 are those closer to  $\langle wyz \rangle$  than to  $\langle wxyz \rangle$  in Table 2; they form a convex set in which column 4 of the labels is always 0, because they are also closer to  $\langle wxyz \rangle$  than to  $x$ .)

These relations between the literals  $\{1, \bar{1}, 2, \bar{2}, \dots, t, \bar{t}\}$  contain no cycles, so they can always be topologically sorted into an anti-symmetrical sequence

$u_1 u_2 \dots u_{2t}$  in which  $u_j$  is the complement of  $u_{2t+1-j}$ . For example,

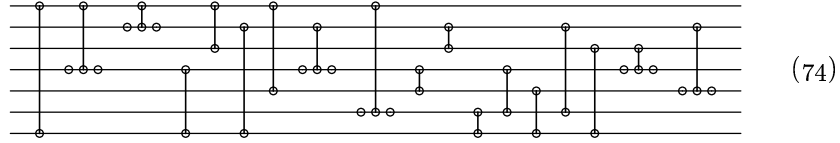
$$1 \bar{7} 4 2 \bar{3} \bar{5} \bar{6} 6 5 3 \bar{2} \bar{4} 7 \bar{1} \quad (72)$$

is one such way to sort the relations in (71) topologically.

Now we proceed to construct the network, by starting with  $t$  empty lines and successively examining elements  $u_k$  and  $u_{k+d}$  in the topological sequence, for  $d = 2t - 2, 2t - 3, \dots, 1$  (in this order), and for  $k = 1, 2, \dots, t - \lceil d/2 \rceil$ . If  $u_k \leq u_{k+d}$  is a relation between columns  $i$  and  $j$ , where  $i < j$ , we append new modules to lines  $i$  and  $j$  of the network as follows:

$$\begin{array}{llll} \text{If } i \rightarrow j & \text{If } i \rightarrow \bar{j} & \text{If } \bar{i} \rightarrow j & \text{If } \bar{i} \rightarrow \bar{j} \\ \begin{array}{c} \text{---} \circ \text{---} \\ | \\ \text{---} \circ \text{---} \end{array} & \begin{array}{c} \text{---} \circ \text{---} \\ | \\ \text{---} \circ \text{---} \end{array} & \begin{array}{c} \text{---} \circ \text{---} \\ | \\ \text{---} \circ \text{---} \end{array} & \begin{array}{c} \text{---} \circ \text{---} \\ | \\ \text{---} \circ \text{---} \end{array} \end{array} \quad (73)$$

For example, from (71) and (72) we first enforce  $1 \rightarrow 7$ , then  $1 \rightarrow \bar{4}$ , then  $1 \rightarrow \bar{2}$ , then  $\bar{7} \rightarrow \bar{4}$  (that is,  $4 \rightarrow 7$ ), etc., obtaining the following network:



(Go figure. No modules are contributed when, say,  $u_k$  is  $\bar{7}$  and  $u_{k+d}$  is 3, because the relation  $\bar{3} \rightarrow 7$  does not appear in (71).)

Exercise 87 proves that each new cluster of modules (73) preserves all of the previous inequalities and enforces a new one. Therefore, if  $x$  is any input vector,  $f(x)$  satisfies all of the inequalities; so  $f(x) \in X$  by Theorem S. Conversely, if  $x \in X$ , every cluster of modules in the network leaves  $x$  unchanged. ■

**Corollary F.** Suppose the median labels in Theorem F are closed under the operations of bitwise AND and OR, so that  $x \& y \in X$  and  $x \mid y \in X$  whenever  $x \in X$  and  $y \in X$ . Then there is a permutation of coordinates under which the labels are representable by a network of comparator modules only.

*Proof.* The bitwise AND of all labels is  $0 \dots 0$ , and the bitwise OR is  $1 \dots 1$ . So the only possible relations between columns are  $i \rightarrow j$  and  $j \rightarrow i$ . By topologically sorting and renaming the columns, we can ensure that only  $i \rightarrow j$  occurs when  $i < j$ ; and in this case the construction in the proof never uses an inverter. ■

In general, if  $G$  is any graph, a homomorphism  $f$  that maps the vertices of  $G$  onto a subset  $X$  of those vertices is called a *retraction* if it satisfies  $f(x) = x$  for all  $x \in X$ ; and we call  $X$  a *retract* of  $G$  when such an  $f$  exists. The importance of this concept in the theory of graphs was first pointed out by Pavol Hell [see *Lecture Notes in Math.* **406** (1974), 291–301]. One consequence, for example, is that the distance between vertices in  $X$  — the number of edges on a shortest path — remains the same even if we restrict consideration to paths that lie entirely in  $X$ . (See exercise 91.)

Theorem F demonstrates that every  $t$ -dimensional set of median labels is a retract of the  $t$ -dimensional hypercube. Conversely, exercise 92 shows that hypercube retracts are always median graphs.



**Threshold functions.** A particularly appealing and important class of Boolean functions  $f(x_1, x_2, \dots, x_n)$  arises when  $f$  can be defined by the formula

$$f(x_1, x_2, \dots, x_n) = [w_1x_1 + w_2x_2 + \dots + w_nx_n \geq t], \quad (75)$$

where the constants  $w_1, w_2, \dots, w_n$  are integer “weights” and  $t$  is an integer “threshold” value. For example, threshold functions are important even when all the weights are unity: We have

$$x_1 \wedge x_2 \wedge \dots \wedge x_n = [x_1 + x_2 + \dots + x_n \geq n]; \quad (76)$$

$$x_1 \vee x_2 \vee \dots \vee x_n = [x_1 + x_2 + \dots + x_n \geq 1]; \quad (77)$$

$$\text{and } \langle x_1x_2 \dots x_{2t-1} \rangle = [x_1 + x_2 + \dots + x_{2t-1} \geq t], \quad (78)$$

where  $\langle x_1x_2 \dots x_{2t-1} \rangle$  stands for the median (or majority) value of a multiset that consists of any odd number of Boolean values  $\{x_1, x_2, \dots, x_{2t-1}\}$ . In particular, the basic mappings  $x \wedge y$ ,  $x \vee y$ , and  $\langle xyz \rangle$  are all threshold functions, and so is

$$\bar{x} = [-x \geq 0]. \quad (79)$$

With more general weights we get many other functions of interest, such as

$$[2^{n-1}x_1 + 2^{n-2}x_2 + \dots + x_n \geq (t_1t_2 \dots t_n)_2], \quad (80)$$

which is true if and only if the binary string  $x_1x_2 \dots x_n$  is lexicographically greater than or equal to a given binary string  $t_1t_2 \dots t_n$ . Given a set of  $n$  objects having sizes  $w_1, w_2, \dots, w_n$ , a subset of those objects will fit into a knapsack of size  $t + 1$  if and only if  $f(x_1, x_2, \dots, x_n) = 0$ , where  $x_j = 1$  represents the presence of object  $j$  in the subset. Simple models of neurons, originally proposed by W. McCulloch and W. Pitts in *Bull. Math. Biophysics* **5** (1943), 115–133, have led to thousands of research papers about “neural networks” built from threshold functions.

We can get rid of any negative weight  $w_j$  by setting  $x_j \leftarrow \bar{x}_j$ ,  $w_j \leftarrow -w_j$ , and  $t \leftarrow t + |w_j|$ . Thus a general threshold function can be reduced to a positive threshold function in which all weights are nonnegative. Furthermore, any positive threshold function (75) can be expressed as a special case of the median/majority-of-odd function, because we have

$$\langle 0^a 1^b x_1^{w_1} x_2^{w_2} \dots x_n^{w_n} \rangle = [b + w_1x_1 + w_2x_2 + \dots + w_nx_n \geq b + t], \quad (81)$$

where  $x^m$  stands for  $m$  copies of  $x$ , and where  $a$  and  $b$  are defined by the rules

$$a = \max(0, 2t - 1 - w), \quad b = \max(0, w + 1 - 2t), \quad w = w_1 + w_2 + \dots + w_n. \quad (82)$$

For example, when all weights are 1, we have

$$\langle 0^{n-1} x_1 \dots x_n \rangle = x_1 \wedge \dots \wedge x_n \quad \text{and} \quad \langle 1^{n-1} x_1 \dots x_n \rangle = x_1 \vee \dots \vee x_n; \quad (83)$$

we’ve already seen these formulas in (45) when  $n = 2$ . In general, either  $a$  or  $b$  is zero, and the left-hand side of (81) specifies a median of  $2T - 1$  elements, where

$$T = b + t = \max(t, w_1 + w_2 + \dots + w_n - t). \quad (84)$$

There would be no point in letting both  $a$  and  $b$  be greater than zero, because the majority function clearly satisfies the cancellation law

$$\langle 01x_1x_2 \dots x_{2t-1} \rangle = \langle x_1x_2 \dots x_{2t-1} \rangle. \quad (85)$$

One important consequence of (81) is that every positive threshold function comes from the pure majority function

$$g(x_0, x_1, x_2, \dots, x_n) = \langle x_0^{a+b} x_1^{w_1} x_2^{w_2} \dots x_n^{w_n} \rangle \quad (86)$$

by setting  $x_0 = 0$  or  $1$ . In other words, we know all threshold functions of  $n$  variables if and only if we know all of the distinct median-of-odd functions of  $n+1$  or fewer variables (containing no constants). Every pure majority function is monotone and self-dual; thus we've seen the pure majority functions of four variables  $\{w, x, y, z\}$  in column  $s_j$  of Table 2 on page 25, namely  $\langle w \rangle$ ,  $\langle wwx yz \rangle$ ,  $\langle wyz \rangle$ ,  $\langle wxyz \rangle$ ,  $\langle xyz \rangle$ ,  $\langle z \rangle$ ,  $\langle wxyyz \rangle$ ,  $\langle y \rangle$ ,  $\langle wxz \rangle$ ,  $\langle wxyz \rangle$ ,  $\langle x \rangle$ ,  $\langle wxy \rangle$ . By setting  $w = 0$  or  $1$ , we obtain all positive threshold functions  $f(x, y, z)$  of three variables:

$$\begin{aligned} &\langle 0 \rangle, \langle 1 \rangle, \langle 00xyz \rangle, \langle 11xyz \rangle, \langle 0yz \rangle, \langle 1yz \rangle, \langle 0xyz \rangle, \langle 1xyz \rangle, \langle xyz \rangle, \langle z \rangle, \\ &\langle 0xyyz \rangle, \langle 1xyyz \rangle, \langle y \rangle, \langle 0xz \rangle, \langle 1xz \rangle, \langle 0xyz \rangle, \langle 1xyz \rangle, \langle x \rangle, \langle 0xy \rangle, \langle 1xy \rangle. \end{aligned} \quad (87)$$

All 150 positive threshold functions of four variables can be obtained in a similar fashion from the self-dual majority functions in the answer to exercise 82.

There are infinitely many sequences of weights  $(w_1, w_2, \dots, w_n)$ , but only finitely many threshold functions for any given value of  $n$ . So it is clear that many different weight sequences are equivalent. For example, consider the pure majority function

$$\langle x_1^2 x_2^3 x_3^5 x_4^7 x_5^{11} x_6^{13} \rangle,$$

in which prime numbers have been used as weights. A brute-force examination of  $2^6$  cases shows that

$$\langle x_1^2 x_2^3 x_3^5 x_4^7 x_5^{11} x_6^{13} \rangle = \langle x_1 x_2^2 x_3^2 x_4^3 x_5^4 x_6^5 \rangle; \quad (88)$$

thus we can express the same function with substantially smaller weights. Similarly, the threshold function

$$[(x_1 x_2 \dots x_{20})_2 \geq (01100100100001111110)_2] = \langle 1^{225028} x_1^{524299} x_2^{262144} \dots x_{20} \rangle,$$

a special case of (80), turns out to be simply

$$\langle 1^{323} x_1^{764} x_2^{323} x_3^{323} x_4^{118} x_5^{118} x_6^{87} x_7^{31} x_8^{31} x_9^{25} x_{10}^6 x_{11}^6 x_{12}^6 x_{13}^6 x_{14} x_{15} x_{16} x_{17} x_{18} x_{19} \rangle. \quad (89)$$

Exercise 101 explains how to find a minimum set of weights without resorting to a huge brute-force search, using linear programming.

A nice indexing scheme by which a unique identifier can be assigned to any threshold function was discovered by C. K. Chow [FOCS 2 (1961), 34–38]. Given any Boolean function  $f(x_1, \dots, x_n)$ , let  $N(f)$  be the number of vectors  $x = (x_1, \dots, x_n)$  for which  $f(x) = 1$ , and let  $\Sigma(f)$  be the sum of all those vectors. For example, if  $f(x_1, x_2) = x_1 \vee x_2$ , we have  $N(f) = 3$  and  $\Sigma(f) = (0, 1) + (1, 0) + (1, 1) = (2, 2)$ .

**Theorem T.** Let  $f(x_1, \dots, x_n)$  and  $g(x_1, \dots, x_n)$  be Boolean functions with  $N(f) = N(g)$  and  $\Sigma(f) = \Sigma(g)$ , where  $f$  is a threshold function. Then  $f = g$ .

*Proof.* Suppose there are exactly  $k$  vectors  $x^{(1)}, \dots, x^{(k)}$  such that  $f(x^{(j)}) = 1$  and  $g(x^{(j)}) = 0$ . Since  $N(f) = N(g)$ , there must be exactly  $k$  vectors  $y^{(1)}, \dots, y^{(k)}$  such that  $f(y^{(j)}) = 0$  and  $g(y^{(j)}) = 1$ . And since  $\Sigma(f) = \Sigma(g)$ , we must also have  $x^{(1)} + \dots + x^{(k)} = y^{(1)} + \dots + y^{(k)}$ .

Now suppose  $f$  is the threshold function (75); then we have  $w \cdot x^{(j)} \geq t$  and  $w \cdot y^{(j)} < t$  for  $1 \leq j \leq k$ . But if  $f \neq g$  we have  $k > 0$ , and  $w \cdot (x^{(1)} + \dots + x^{(k)}) \geq kt > w \cdot (y^{(1)} + \dots + y^{(k)})$ , a contradiction. ■

Threshold functions have many curious properties, some of which are explored in the exercises below. Their classical theory is well summarized in Saburo Muroga's book *Threshold Logic and its Applications* (Wiley, 1971).

**Symmetric Boolean functions.** A function  $f(x_1, \dots, x_n)$  is called *symmetric* if  $f(x_1, \dots, x_n)$  is equal to  $f(x_{p(1)}, \dots, x_{p(n)})$  for all permutations  $p(1) \dots p(n)$  of  $\{1, \dots, n\}$ . When all the  $x_j$  are 0 or 1, this condition means that  $f$  depends only on the number of 1s that are present in the arguments, namely the "sideways sum"  $\nu x = \nu(x_1, \dots, x_n) = x_1 + \dots + x_n$ . The notation  $S_{k_1, k_2, \dots, k_r}(x_1, \dots, x_n)$  is commonly used to stand for the Boolean function that is true if and only if  $\nu x$  is either  $k_1$  or  $k_2$  or  $\dots$  or  $k_r$ . For example,  $S_{1,3,5}(v, w, x, y, z) = v \oplus w \oplus x \oplus y \oplus z$ ;  $S_{3,4,5}(v, w, x, y, z) = \langle vwx yz \rangle$ ;  $S_{4,5}(v, w, x, y, z) = \langle 00vwx yz \rangle$ .

Many applications of symmetry involve the basic functions  $S_k(x_1, \dots, x_n)$  that are true only when  $\nu x = k$ . For example,  $S_3(x_1, x_2, x_3, x_4, x_5, x_6)$  is true if and only if exactly half of the arguments  $\{x_1, \dots, x_6\}$  are true and the other half are false. In such cases we obviously have

$$S_k(x_1, \dots, x_n) = S_{\geq k}(x_1, \dots, x_n) \wedge \overline{S_{\geq k+1}(x_1, \dots, x_n)}, \quad (90)$$

where  $S_{\geq k}(x_1, \dots, x_n)$  is an abbreviation for  $S_{k, k+1, \dots, n}(x_1, \dots, x_n)$ . The functions  $S_{\geq k}(x_1, \dots, x_n)$  are, of course, the threshold functions  $[x_1 + \dots + x_n \geq k]$  that we have already studied.

More complicated cases can be treated as threshold functions of threshold functions. For example, we have

$$\begin{aligned} S_{2,3,6,8,9}(x_1, \dots, x_{12}) &= [\nu x \geq 2 + 4[\nu x \geq 4] + 2[\nu x \geq 7] + 5[\nu x \geq 10]] \\ &= \langle 00x_1 \dots x_{12} \langle 0^5 \bar{x}_1 \dots \bar{x}_{12} \rangle^4 \langle 1\bar{x}_1 \dots \bar{x}_{12} \rangle^2 \langle 1^7 \bar{x}_1 \dots \bar{x}_{12} \rangle^5 \rangle, \end{aligned} \quad (91)$$

because the number of 1s in the outermost majority-of-25 turns out to be respectively (11, 12, 13, 14, 11, 12, 13, 12, 13, 14, 10, 11, 12) when  $x_1 + \dots + x_{12} = (0, 1, \dots, 12)$ . A similar two-level scheme works in general [R. C. Minnick, *IRE Trans. EC-10* (1961), 6–16]; and with three or more levels of logic we can reduce the number of thresholding operations even further. (See exercise 111.)

Many ingenious tricks have been discovered for evaluating symmetric Boolean functions. For example, S. Muroga attributes the following remarkable sequence of formulas to F. Sasaki:

$$\begin{aligned} x_0 \oplus x_1 \oplus \dots \oplus x_{2m} &= \langle \bar{x}_0 s_1 s_2 \dots s_{2m} \rangle, \\ \text{where } s_j &= \langle x_0 x_j x_{j+1} \dots x_{j+m-1} \bar{x}_{j+m} \bar{x}_{j+m+1} \dots \bar{x}_{j+2m-1} \rangle, \end{aligned} \quad (92)$$

if  $m > 0$  and if we consider  $x_{2m+k}$  to be the same as  $x_k$  for  $k \geq 1$ . In particular, when  $m = 1$  and  $m = 2$  we have the identities

$$x_0 \oplus x_1 \oplus x_2 = \langle \bar{x}_0 \langle x_0 x_1 \bar{x}_2 \rangle \langle x_0 x_2 \bar{x}_1 \rangle \rangle; \quad (93)$$

$$x_0 \oplus \cdots \oplus x_4 = \langle \bar{x}_0 \langle x_0 x_1 x_2 \bar{x}_3 \bar{x}_4 \rangle \langle x_0 x_2 x_3 \bar{x}_4 \bar{x}_1 \rangle \langle x_0 x_3 x_4 \bar{x}_1 \bar{x}_2 \rangle \langle x_0 x_4 x_1 \bar{x}_2 \bar{x}_3 \rangle \rangle. \quad (94)$$

The right-hand sides are fully symmetric, but not obviously so! (See exercise 113.)

**Canalizing functions.** A Boolean function  $f(x_1, \dots, x_n)$  is said to be *canalizing* or “forcing” if we might be able to deduce its value by examining at most one of its variables. More precisely,  $f$  is canalizing if  $n = 0$  or if there’s a subscript  $j$  for which  $f(x)$  either has a constant value when we set  $x_j = 0$  or a constant value when we set  $x_j = 1$ . For example,  $f(x, y, z) = (x \oplus z) \vee \bar{y}$  is canalizing because it always equals 1 when  $y = 0$ . (When  $y = 1$  we don’t know the value of  $f$  without examining also  $x$  and  $z$ ; but half a loaf is better than none.) Such functions, introduced by Stuart Kauffman [*Lectures on Mathematics in the Life Sciences* **3** (1972), 63–116; *J. Theoretical Biology* **44** (1974), 167–190], have proved to be important in many applications, especially in chemistry and biology. Some of their properties are examined in exercises 122–126.

**Quantitative considerations.** We’ve been studying many different kinds of Boolean functions, so it’s natural to ask: How many  $n$ -variable functions of each type actually exist? Tables 3, 4, and 5 provide the answers, at least for small values of  $n$ .

All functions are counted in Table 3. There are  $2^{2^n}$  possibilities for each  $n$ , since there are  $2^{2^n}$  possible truth tables. Some of these functions are self-dual, some are monotone; some are both monotone and self-dual, as in Theorem P. Some are Horn functions as in Theorem H; some are Krom functions as in Theorem S; and so on.

But in Table 4, two functions are considered identical if they differ only because the names of variables have changed. Thus only 12 different cases arise when  $n = 2$ , because (for example)  $x \vee \bar{y}$  and  $\bar{x} \vee y$  are essentially the same.

Table 5 goes a step further: It allows us to complement individual variables, and even to complement the entire function, without essentially changing it. From this perspective the 256 Boolean functions of  $(x, y, z)$  fall into only 14 different equivalence classes:

Representative	Class size	Representative	Class size	
1	2	$S_1(x, y, z)$	16	
$x$	6	$S_{0,3}(x, y, z)$	8	
$x \wedge y$	24	$x \wedge (y \vee z)$	48	
$x \oplus y$	6	$x \wedge (y \oplus z)$	24	(95)
$x \wedge y \wedge z$	16	$x \oplus (y \wedge z)$	24	
$x \oplus y \oplus z$	2	$(x \wedge y) \vee (\bar{x} \wedge z)$	24	
$\langle xyz \rangle$	8	$(x \wedge y \wedge z) \vee (\bar{x} \wedge \bar{y})$	48	

We shall study ways to count and to list inequivalent combinatorial objects in Section 7.2.3.

**Table 3**BOOLEAN FUNCTIONS OF  $n$  VARIABLES

	$n=0$	$n=1$	$n=2$	$n=3$	$n=4$	$n=5$	$n=6$
arbitrary	2	4	16	256	65,536	4,294,967,296	18,446,744,073,709,551,616
self-dual	0	2	4	16	256	65,536	4,294,967,296
monotone	2	3	6	20	168	7,581	7,828,354
both	0	1	2	4	12	81	2,646
Horn	2	4	14	122	4,960	2,771,104	151,947,502,948
Krom	2	4	16	166	4,170	224,716	24,445,368
threshold	2	4	14	104	1,882	94,572	15,028,134
symmetric	2	4	8	16	32	64	128
canalizing	2	4	14	120	3,514	1,292,276	103,071,426,294

**Table 4**

BOOLEAN FUNCTIONS DISTINCT UNDER PERMUTATION OF VARIABLES

	$n=0$	$n=1$	$n=2$	$n=3$	$n=4$	$n=5$	$n=6$
arbitrary	2	4	12	80	3,984	37,333,248	25,626,412,338,274,304
self-dual	0	2	2	8	32	1,088	6,385,408
monotone	2	3	5	10	30	210	16,353
both	0	1	1	2	3	7	30
Horn	2	4	10	38	368	29,328	216,591,692
Krom	2	4	12	48	308	3,028	49,490
threshold	2	4	10	34	178	1,720	590,440
canalizing	2	4	10	38	294	15,774	149,325,022

**Table 5**

BOOLEAN FUNCTIONS DISTINCT UNDER COMPLEMENTATION/PERMUTATION

	$n=0$	$n=1$	$n=2$	$n=3$	$n=4$	$n=5$	$n=6$
arbitrary	1	2	4	14	222	616,126	200,253,952,527,184
self-dual	0	1	1	3	7	83	109,950
threshold	1	2	3	6	15	63	567
both	0	1	1	2	3	7	21
canalizing	1	1	3	6	22	402	1,228,158

**EXERCISES**

1. [15] (Lewis Carroll.) Make sense of Tweedledee's comment, quoted near the beginning of this section. [Hint: See Table 1.]

2. [17] Logicians on the remote planet Pincus use the symbol 1 to represent "false" and 0 to represent "true." Thus, for example, they have a binary operation called "or" whose properties

$$1 \text{ or } 1 = 1, \quad 1 \text{ or } 0 = 0, \quad 0 \text{ or } 1 = 0, \quad 0 \text{ or } 0 = 0$$

we associate with  $\wedge$ . What operations would we associate with the 16 logical operators that Pincusians respectively call "falsehood," "and," ..., "nand," "validity" (see Table 1)?

- 3. [13] Suppose logical values were respectively  $-1$  for falsehood and  $+1$  for truth, instead of  $0$  and  $1$ . What operations  $\circ$  in Table 1 would then correspond to (a)  $\max(x, y)$ ? (b)  $\min(x, y)$ ? (c)  $-x$ ? (d)  $x \cdot y$ ?
4. [24] (H. M. Sheffer.) The purpose of this exercise is to show that all of the operations in Table 1 can be expressed in terms of NAND. (a) For each of the 16 operators  $\circ$  in that table, find a formula equivalent to  $x \circ y$  that uses only  $\bar{\wedge}$  as an operator. Your formula should be as short as possible. For example, the answer for operation  $\sqcup$  is simply “ $x$ ”, but the answer for  $\bar{\sqcup}$  is “ $x \bar{\wedge} x$ ”. Do not use the constants  $0$  or  $1$  in your formulas. (b) Similarly, find 16 short formulas when constants *are* allowed. For example,  $x \bar{\sqcup} y$  can now be expressed also as “ $x \bar{\wedge} 1$ ”.
5. [24] Consider exercise 4 with  $\bar{\sqcup}$  as the basic operation instead of  $\bar{\wedge}$ .
6. [21] (E. Schröder.) (a) Which of the 16 operations in Table 1 are associative—in other words, which of them satisfy  $x \circ (y \circ z) = (x \circ y) \circ z$ ? (b) Which of them satisfy the identity  $(x \circ y) \circ (y \circ z) = x \circ z$ ?
7. [20] Which operations in Table 1 have the property that  $x \circ y = z$  if and only if  $y \circ z = x$ ?
8. [24] Which of the  $16^2$  pairs of operations  $(\circ, \square)$  satisfy the left-distributive law  $x \circ (y \square z) = (x \circ y) \square (x \circ z)$ ?
9. [15] True or false? (a)  $(x \oplus y) \vee z = (x \vee z) \oplus (y \vee z)$ ; (b)  $(w \oplus x \oplus y) \vee z = (w \vee z) \oplus (x \vee z) \oplus (y \vee z)$ .
10. [17] What is the multilinear representation of the “random” function (22)?
11. [M25] Is there an intuitive way to understand exactly when the multilinear representation of  $f(x_1, \dots, x_n)$  contains, say, the term  $x_2 x_3 x_6 x_8$ ? (See (19).)
- 12. [M21] The *integer multilinear representation* of a Boolean function extends representations like (19) to a polynomial  $f(x_1, \dots, x_n)$  with integer coefficients, in such a way that  $f(x_1, \dots, x_n)$  has the correct value ( $0$  or  $1$ ) for all  $2^n$  possible  $0$ – $1$  vectors  $(x_1, \dots, x_n)$ , *without* taking a remainder mod  $2$  as in (23). For example, the integer multilinear representation corresponding to (19) is  $1 - xy - xz - yz + 3xyz$ .
- What is the integer multilinear representation of the “random” function (22)?
  - How large can the coefficients of such a representation be, when  $f$  is a function of  $n$  variables?
  - Show that, in every integer multilinear representation,  $0 \leq f(x_1, \dots, x_n) \leq 1$  whenever  $x_1, \dots, x_n$  are real numbers with  $0 \leq x_1, \dots, x_n \leq 1$ .
  - If  $f$  is monotone and  $0 \leq x_j \leq y_j \leq 1$  for  $1 \leq j \leq n$ , prove that  $f(x) \leq f(y)$ .
- 13. [20] Consider a system that consists of  $n$  units, each of which may be “working” or “failing.” If  $x_j$  represents the condition “unit  $j$  is working,” then a Boolean function like  $x_1 \wedge (\bar{x}_2 \vee \bar{x}_3)$  represents the statement “unit 1 is working, but either unit 2 or unit 3 is failing”; and  $S_3(x_1, \dots, x_n)$  means “exactly three units are working.”
- Suppose each unit  $j$  is in working order with probability  $p_j$ , independent of the other units. Show that a Boolean function  $f(x_1, \dots, x_n)$  is true with probability  $F(p_1, \dots, p_n)$ , where  $F$  is a polynomial in the variables  $p_1, \dots, p_n$ .
14. [20] The probability function  $F(p_1, \dots, p_n)$  in exercise 13 is often called the *availability* of the system. Find the self-dual function  $f(x_1, x_2, x_3)$  of maximum availability when the probabilities  $(p_1, p_2, p_3)$  are (a)  $(.9, .8, .7)$ ; (b)  $(.8, .6, .4)$ ; (c)  $(.8, .6, .1)$ .

- 15. [M20] If  $f(x_1, \dots, x_n)$  is any Boolean function, show that there is a polynomial  $F(x)$  with the property that  $F(x)$  is an integer when  $x$  is an integer, and  $f(x_1, \dots, x_n) = F((x_n \dots x_1)_2) \bmod 2$ . *Hint:* Consider  $\binom{x}{k} \bmod 2$ .
16. [13] Can we replace each  $\vee$  by  $\oplus$  in a full disjunctive normal form?
17. [10] By De Morgan's laws, a general disjunctive normal form such as (25) is not only an OR of ANDs, it is a NAND of NANDs:

$$\overline{\overline{(u_{11} \wedge \dots \wedge u_{1s_1})} \wedge \dots \wedge \overline{(u_{m1} \wedge \dots \wedge u_{ms_m})}}.$$

Both levels of logic can therefore be considered to be identical.

A student named J. H. Quick rewrote this expression in the form

$$(u_{11} \bar{\wedge} \dots \bar{\wedge} u_{1s_1}) \bar{\wedge} \dots \bar{\wedge} (u_{m1} \bar{\wedge} \dots \bar{\wedge} u_{ms_m}).$$

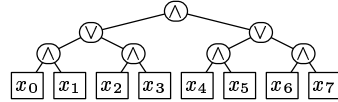
Was that a good idea?

- 18. [20] Let  $u_1 \wedge \dots \wedge u_s$  be an implicant in a disjunctive normal form for a Boolean function  $f$ , and let  $v_1 \vee \dots \vee v_t$  be a clause in a conjunctive normal form for the same function. Prove that  $u_i = v_j$  for some  $i$  and  $j$ .
19. [20] What is the conjunctive prime form of the “random” function in (22)?
20. [M21] True or false: Every prime implicant of  $f \wedge g$  can be written  $f' \wedge g'$ , where  $f'$  is a prime implicant of  $f$  and  $g'$  is a prime implicant of  $g$ .
21. [M20] Prove that a nonconstant Boolean function is monotone if and only if it can be expressed entirely in terms of the operations  $\wedge$  and  $\vee$ .
22. [20] Suppose  $f(x_1, \dots, x_n) = g(x_1, \dots, x_{n-1}) \oplus h(x_1, \dots, x_{n-1}) \wedge x_n$  as in (16). What conditions on the functions  $g$  and  $h$  are necessary and sufficient for  $f$  to be monotone?
23. [15] What is the conjunctive prime form of  $(v \wedge w \wedge x) \vee (v \wedge x \wedge z) \vee (x \wedge y \wedge z)$ ?
24. [M20] Consider the complete binary tree with  $2^k$  leaves, illustrated here for  $k = 3$ . Operate alternately with  $\wedge$  or  $\vee$  on each level, using  $\wedge$  at the root, obtaining for example  $((x_0 \wedge x_1) \vee (x_2 \wedge x_3)) \wedge ((x_4 \wedge x_5) \vee (x_6 \wedge x_7))$ . How many prime implicants does the resulting function contain?
25. [M21] How many prime implicants does  $(x_1 \vee x_2) \wedge (x_2 \vee x_3) \wedge \dots \wedge (x_{n-1} \vee x_n)$  have?
26. [M22] Let  $\mathcal{F}$  and  $\mathcal{G}$  be the families of index sets for the prime clauses and the prime implicants of a monotone CNF and a monotone DNF:

$$f(x) = \bigwedge_{I \in \mathcal{F}} \bigvee_{i \in I} x_i; \quad g(x) = \bigvee_{J \in \mathcal{G}} \bigwedge_{j \in J} x_j.$$

Exhibit an  $x$  such that  $f(x) \neq g(x)$  if any of the following conditions hold:

- There is an  $I \in \mathcal{F}$  and a  $J \in \mathcal{G}$  with  $I \cap J = \emptyset$ .
  - $\bigcup_{I \in \mathcal{F}} I \neq \bigcup_{J \in \mathcal{G}} J$ .
  - There's an  $I \in \mathcal{F}$  with  $|I| > |\mathcal{G}|$ , or a  $J \in \mathcal{G}$  with  $|J| > |\mathcal{F}|$ .
  - $\sum_{I \in \mathcal{F}} 2^{n-|I|} + \sum_{J \in \mathcal{G}} 2^{n-|J|} < 2^n$ , where  $n = |\bigcup_{I \in \mathcal{F}} I|$ .
27. [M30] Continuing the previous exercise, consider the following algorithm  $X(\mathcal{F}, \mathcal{G})$ , which either returns a vector  $x$  with  $f(x) \neq g(x)$ , or returns  $\Lambda$  if  $f = g$ :



**X1.** [Check necessary conditions.] Return an appropriate value  $x$  if condition (a), (b), (c), or (d) in exercise 26 applies.

**X2.** [Done?] If  $|\mathcal{F}||\mathcal{G}| \leq 1$ , return  $\Lambda$ .

**X3.** [Recurse.] Compute the reduced families

$$\begin{aligned}\mathcal{F}_1 &= \{I \mid I \in \mathcal{F}, x_k \notin I\}, & \mathcal{F}_0 &= \mathcal{F}_1 \cup \{I \mid I \cup \{x_k\} \in \mathcal{F}\}; \\ \mathcal{G}_0 &= \{J \mid J \in \mathcal{G}, x_k \notin J\}, & \mathcal{G}_1 &= \mathcal{G}_0 \cup \{J \mid J \cup \{x_k\} \in \mathcal{G}\}.\end{aligned}$$

Delete any member of  $\mathcal{F}_0$  or  $\mathcal{G}_1$  that contains another member of the same family. The index  $k$  should be chosen so that the ratio  $\rho = \min(|\mathcal{F}_1|/|\mathcal{F}|, |\mathcal{G}_0|/|\mathcal{G}|)$  is as small as possible. If  $X(\mathcal{F}_0, \mathcal{G}_0)$  returns a vector  $x$ , return the same vector extended with  $x_k = 0$ . Otherwise if  $X(\mathcal{F}_1, \mathcal{G}_1)$  returns a vector  $x$ , return the same vector extended with  $x_k = 1$ . Otherwise return  $\Lambda$ . ■

If  $N = |\mathcal{F}| + |\mathcal{G}|$ , prove that step X1 is executed at most  $N^{O(\log N)^2}$  times. *Hint:* Show that  $\rho \leq 1 - 1/\lg N$  in step X3.

**28.** [21] (W. V. Quine, 1952.) If  $f(x_1, \dots, x_n)$  is a Boolean function with prime implicants  $p_1, \dots, p_q$ , let  $g(y_1, \dots, y_q) = \bigvee_{f(x)=1} \bigwedge \{y_j \mid p_j(x) = 1\}$ . For example, the “random” function (22) is true at the eight points (28), and it has five prime implicants given by (29) and (30); so  $g(y_1, \dots, y_5)$  is

$$\begin{aligned}(y_1 \vee y_2) \wedge (y_1) \wedge (y_2 \vee y_3) \wedge (y_4) \wedge (y_3 \vee y_5) \wedge (y_5) \wedge (y_5) \wedge (y_4 \vee y_5) \\ = (y_1 \wedge y_2 \wedge y_4 \wedge y_5) \vee (y_1 \wedge y_3 \wedge y_4 \wedge y_5)\end{aligned}$$

in this case. Prove that every shortest DNF expression for  $f$  corresponds to a prime implicant of the monotone function  $g$ .

**29.** [22] (The next several exercises are devoted to algorithms that deal with the implicants of Boolean functions by representing points of the  $n$ -cube as  $n$ -bit numbers  $(b_{n-1} \dots b_1 b_0)_2$ , rather than as bit strings  $x_1 \dots x_n$ .) Given a bit position  $j$ , and given  $n$ -bit values  $v_0 < v_1 < \dots < v_{m-1}$ , explain how to find all pairs  $(k, k')$  such that  $0 \leq k < k' < m$  and  $v_{k'} = v_k + 2^j$ , in increasing order of  $k$ . The running time of your procedure should be  $O(m)$ , if bitwise operations on  $n$ -bit words take constant time.

- **30.** [27] The text points out that an implicant of a Boolean function can be regarded as a subcube such as  $01*0*$ , contained in the set  $V$  of all points for which the function is true. Every subcube can be represented as a pair of binary numbers  $a = (a_{n-1} \dots a_0)_2$  and  $b = (b_{n-1} \dots b_0)_2$ , where  $a$  records the positions of the asterisks and  $b$  records the bits in non-\* positions. For example, the numbers  $a = (00101)_2$  and  $b = (01000)_2$  represent the subcube  $c = 01*0*$ . We always have  $a \& b = 0$ .

The “ $j$ -buddy” of a subcube is defined whenever  $a_j = 0$ , by changing  $b$  to  $b \oplus 2^j$ . For example,  $01*0*$  has three buddies, namely its 4-buddy  $11*0*$ , its 3-buddy  $00*0*$ , and its 1-buddy  $01*1*$ . Every subcube  $c \subseteq V$  can be assigned a tag value  $(t_{n-1} \dots t_0)_2$ , where  $t_j = 1$  if and only if the  $j$ -buddy of  $c$  is defined and contained in  $V$ . With this definition,  $c$  represents a maximal subcube (hence a prime implicant) if and only if its tag is zero.

Use these concepts to design an algorithm that finds all maximal subcubes  $(a, b)$  of a given set  $V$ , where  $V$  is represented by the  $n$ -bit numbers  $v_0 < v_1 < \dots < v_{m-1}$ .

- **31.** [28] The algorithm in exercise 30 requires a complete list of all points where a Boolean function is true, and that list may be quite long. Therefore we may prefer to



work directly with subcubes, never going down to the level of explicit  $n$ -tuples unless necessary. The key to such higher-level methods is the notion of *consensus* between subcubes  $c$  and  $c'$ , denoted by  $c \sqcup c'$  and defined to be the largest subcube  $c''$  such that

$$c'' \subseteq c \cup c', \quad c'' \not\subseteq c, \quad \text{and} \quad c'' \not\subseteq c'.$$

Such a  $c''$  does not always exist. For example, if  $c = 000*$  and  $c' = *111$ , every subcube contained in  $c \cup c'$  is contained either in  $c$  or in  $c'$ .

- a) Prove that the consensus, when it exists, can be computed componentwise using the following formulas in each coordinate position:

$$x \sqcup x = x \sqcup * = * \sqcup x = x \quad \text{and} \quad x \sqcup \bar{x} = * \sqcup * = *, \quad \text{for } x = 0 \text{ and } x = 1.$$

Furthermore,  $c \sqcup c'$  exists if and only if the rule  $x \sqcup \bar{x} = *$  has been used in exactly one component.

- b) A subcube with  $k$  asterisks is called a  $k$ -cube. Show that, if  $c$  is a  $k$ -cube and  $c'$  is a  $k'$ -cube, and if the consensus  $c'' = c \sqcup c'$  exists, then  $c''$  is a  $k''$ -cube where  $1 \leq k'' \leq \min(k, k') + 1$ .
- c) If  $C$  and  $C'$  are families of subcubes, let

$$C \sqcup C' = \{c \sqcup c' \mid c \in C, c' \in C', \text{ and } c \sqcup c' \text{ exists}\}.$$

Explain why the following algorithm works.

**Algorithm E** (*Find maximal subcubes*). Given a family  $C$  of subcubes of the  $n$ -cube, this algorithm outputs the maximal subcubes of  $V = \bigcup_{c \in C} c$ , without actually computing the set  $V$  itself.

- E1.** [Initialize.] Set  $j \leftarrow 0$ . Delete any subcube  $c$  of  $C$  that is contained in another.
- E2.** [Done?] (At this point, every  $j$ -cube  $\subseteq V$  is contained in some element of  $C$ , and  $C$  contains no  $k$ -cubes with  $k < j$ .) If  $C$  is empty, the algorithm terminates.
- E3.** [Take consensuses.] Set  $C' \leftarrow C \sqcup C$ , and remove all subcubes from  $C'$  that are  $k$ -cubes for  $k \leq j$ . While performing this computation, also output any  $j$ -cube  $c \in C$  for which  $c \sqcup C$  does not produce a  $(j+1)$ -cube of  $C'$ .
- E4.** [Advance.] Set  $C \leftarrow C \cup C'$ , but delete all  $j$ -cubes from this union. Then delete any subcube  $c \in C$  that is contained in another. Set  $j \leftarrow j+1$  and go to E2. ■

(See exercise 7.1.3–00 for an efficient way to perform these computations.)

- **32.** [M27] Let  $c_1, \dots, c_m$  be subcubes of the  $n$ -cube.
- a) Prove that  $c_1 \cup \dots \cup c_m$  contains at most one maximal subcube  $c$  that has a point in common with each of  $c_1, \dots, c_m$ . (If  $c$  exists, we call it the *generalized consensus* of  $c_1, \dots, c_m$ , because  $c = c_1 \sqcup c_2$  in the notation of exercise 31 when  $m = 2$ .)
- b) Find a set of  $m$  subcubes for which each of the  $2^m - 1$  nonempty subsets of  $\{c_1, \dots, c_m\}$  has a generalized consensus.
- c) Prove that a DNF with  $m$  implicants has at most  $2^m - 1$  prime implicants.
- d) Find a DNF that has  $m$  implicants and  $2^m - 1$  prime implicants.
- 33.** [M21] Let  $f(x_1, \dots, x_n)$  be one of the  $\binom{2^n}{m}$  Boolean functions that is true at exactly  $m$  points. If  $f$  is chosen at random, what is the probability that  $x_1 \wedge \dots \wedge x_k$  is (a) an implicant of  $f$ ? (b) a prime implicant of  $f$ ? [Give the answer to part (b) as a sum; but evaluate it in closed form when  $k = n$ .]

- **34.** [HM37] Continuing exercise 33, let  $c(m, n)$  be the average total number of implicants, and let  $p(m, n)$  be the average total number of prime implicants.
- If  $0 \leq m \leq 2^n/n$ , show that  $m \leq c(m, n) \leq \frac{3}{2}m + O(m/n)$  and  $p(m, n) \geq me^{-1} + O(m/n)$ ; hence  $p(m, n) = \Theta(c(m, n))$  in this range.
  - Now let  $2^n/n \leq m \leq (1 - \epsilon)2^n$ , where  $\epsilon$  is a fixed positive constant. Define the numbers  $t$  and  $\alpha_{mn}$  by the relations

$$n^{-4/3} \leq \left(\frac{m}{2^n}\right)^{2^t} = \alpha_{mn} < n^{-2/3}, \quad \text{integer } t.$$

Express the asymptotic values of  $c(m, n)$  and  $p(m, n)$  in terms of  $n$ ,  $t$ , and  $\alpha_{mn}$ . [Hint: Show that almost all of the implicants have exactly  $n - t$  or  $n - t - 1$  literals.]

- Estimate  $c(m, n)/p(m, n)$  when  $m = 2^{n-1}$  and  $n = \lfloor (\ln t - \ln \ln t)2^{2^t} \rfloor$ , integer  $t$ .
  - Prove that  $c(m, n)/p(m, n) = O(\log \log \log n / \log \log n)$  when  $m \leq (1 - \epsilon)n$ .
- **35.** [M25] A DNF is called *orthogonal* if its implicants correspond to disjoint subcubes. Orthogonal disjunctive normal forms are particularly useful when the reliability polynomial of exercise 13 is being calculated or estimated.

The full DNF of every function is obviously orthogonal, because its subcubes are single points. But we can often find an orthogonal DNF that has significantly fewer implicants, especially when the function is monotone. For example, the function  $(x_1 \wedge x_2) \vee (x_2 \wedge x_3) \vee (x_3 \wedge x_4)$  is true at eight points, and it has the orthogonal DNF

$$(x_1 \wedge x_2) \vee (\bar{x}_1 \wedge x_2 \wedge x_3) \vee (\bar{x}_2 \wedge x_3 \wedge x_4).$$

In other words, the overlapping subcubes 11\*\*, \*11\*, \*\*11 can be replaced by the disjoint subcubes 11\*\*, 011\*, \*011. Using the binary notation for subcubes in exercise 30, these subcubes have asterisk codes 0011, 0001, 1000 and bit codes 1100, 0110, 0011.

Every monotone function can be defined by a list of bit codes  $B_1, \dots, B_p$ , when the asterisk codes are respectively  $\bar{B}_1, \dots, \bar{B}_p$ . Given such a list, let the “shadow”  $S_k$  of  $B_k$  be the bitwise OR of  $B_j \& \bar{B}_k$ , for all  $1 \leq j < k$  such that  $\nu(B_j \& \bar{B}_k) = 1$ :

$$S_k = \beta_{1k} | \dots | \beta_{(k-1)k}, \quad \beta_{jk} = ((B_j \& \bar{B}_k) \& -(B_j \& \bar{B}_k)) \dot{-} ((B_j \& \bar{B}_k) \& ((B_j \& \bar{B}_k) - 1)).$$

For example, when the bit codes are  $(B_1, B_2, B_3) = (1100, 0110, 0011)$ , we get the shadow codes  $(S_1, S_2, S_3) = (0000, 1000, 0100)$ .

- Show that the asterisk codes  $A'_j = \bar{B}_j - S_j$  and bit codes  $B_j$  define subcubes that cover the same points as the subcubes with asterisk codes  $A_j = \bar{B}_j$ .
- A list of bit codes  $B_1, \dots, B_p$  is called a *shelling* if  $B_j \& S_k$  is nonzero for all  $1 \leq j < k \leq p$ . For example, (1100, 0110, 0011) is a shelling; but if we arrange those bit codes in the order (1100, 0011, 0110) the shelling condition fails when  $j = 1$  and  $k = 2$ , although we do have  $S_3 = 1001$ . Prove that the subcubes in part (a) are disjoint if and only if the list of bit codes is a shelling.
- According to Theorem Q, every prime implicant must appear among the  $B$ ’s when we represent a monotone Boolean function in this way. But sometimes we need to add additional implicants if we want the subcubes to be disjoint. For example, there is no shelling for the bit codes 1100 and 0011. Show that we can, however, obtain a shelling for this function  $(x_1 \wedge x_2) \vee (x_3 \wedge x_4)$  by adding one more bit code. What is the resulting orthogonal DNF?
- Permute the bit codes {11000, 01100, 00110, 00011, 11010} to obtain a shelling.
- Add two bit codes to the set {110000, 011000, 001100, 000110, 000011} in order to make a shellable list.

**36.** [M21] Continuing exercise 35, let  $f$  be any monotone function. Show that the set

$$B = \{x \mid f(x) = 1 \text{ and } (x = 0 \dots 0 \text{ or } f(x') = 0)\}, \quad x' = x \& (x-1),$$

is always shellable when listed in decreasing lexicographic order. (The vector  $x'$  is obtained from  $x$  by zeroing out the rightmost 1.) For example, this method produces an orthogonal DNF for  $(x_1 \wedge x_2) \vee (x_3 \wedge x_4)$  from the list (1100, 1011, 0111, 0011).

► **37.** [M31] Find a shellable DNF for  $(x_1 \wedge x_2) \vee (x_3 \wedge x_4) \vee \dots \vee (x_{2n-1} \wedge x_{2n})$  that has  $2^n - 1$  implicants, and prove that no orthogonal DNF for this function has fewer.

**38.** [05] Is it hard to test the satisfiability of functions in *disjunctive* normal form?

► **39.** [25] Let  $f(x_1, \dots, x_n)$  be a Boolean formula represented as an extended binary tree with  $N$  internal nodes and  $N + 1$  leaves. Each leaf is labeled with a variable  $x_k$ , and each internal node is labeled with one of the sixteen binary operators in Table 1; applying the operators from bottom to top yields  $f(x_1, \dots, x_n)$  as the value of the root.

Explain how to construct a formula  $F(x_1, \dots, x_n, y_1, \dots, y_N)$  in 3CNF, having exactly  $4N + 1$  clauses, with the property that  $f$  is satisfiable if and only if  $F$  is satisfiable.

**40.** [23] Given an undirected graph  $G$ , construct the following clauses on the Boolean variables  $\{p_{uv} \mid u \neq v\} \cup \{q_{uvw} \mid u \neq v, u \neq w, v \neq w, u \dashv v\}$ , where  $u, v$ , and  $w$  denote vertices of  $G$ :

$$A = \bigwedge \{(p_{uv} \vee p_{vu}) \mid u \neq v\};$$

$$B = \bigwedge \{(\bar{p}_{uv} \vee \bar{p}_{vw} \vee p_{uw}) \mid u \neq v, u \neq w, v \neq w\};$$

$$C = \bigwedge \{(\bar{q}_{uvw} \vee p_{uv}) \wedge (\bar{q}_{uvw} \vee p_{vw}) \wedge (q_{uvw} \vee \bar{p}_{uv} \vee \bar{p}_{vw}) \mid u \neq v, u \neq w, v \neq w, u \dashv v\};$$

$$D = \bigwedge \{(\bigvee_{w \notin \{u,v\}} (q_{uvw} \vee q_{vuw})) \mid u \neq v, u \dashv v\}.$$

Prove that the formula  $A \wedge B \wedge C \wedge D$  is satisfiable if and only if  $G$  has a Hamiltonian path. *Hint:* Think of  $p_{uv}$  as the statement ' $u < v$ '.

**41.** [20] (*The pigeonhole principle.*) The island of San Serriffe contains  $m$  pigeons and  $n$  holes. Find a conjunctive normal form that is satisfiable if and only if each pigeon can be the sole occupant of at least one hole.

**42.** [20] Find a short, unsatisfiable CNF that is not totally trivial, although it consists entirely of Horn clauses that are also Krom clauses.

**43.** [20] Is there an efficient way to decide satisfiability of a conjunctive normal form that consists entirely of Horn clauses and/or Krom clauses (possibly mixed)?

**44.** [M23] Complete the proof of Theorem H by studying the implications of (33).

**45.** [M20] (a) Show that exactly half of the Horn functions of  $n$  variables are proper. (b) Also show that there are more Horn functions of  $n$  variables than monotone functions of  $n$  variables (unless  $n = 0$ ).

**46.** [20] Which of the  $11 \times 11$  character pairs  $xy$  can occur next to each other in the context-free grammar (34)?

**47.** [20] Given a sequence of relations  $j \prec k$  with  $1 \leq j, k \leq n$  as in Algorithm 2.2.3T (topological sorting), consider the clauses

$$x_{j_1} \wedge \dots \wedge x_{j_t} \Rightarrow x_k \quad \text{for } 1 \leq k \leq n,$$

where  $\{j_1, \dots, j_t\}$  is the set of elements such that  $j_i \prec k$ . Compare the behavior of Algorithm C on these clauses to the behavior of Algorithm 2.2.3T.

- 48. [21] What's a good way to test a set of Horn clauses for satisfiability?

49. [HM40] There are  $(n+2)2^{n-1}$  possible Horn clauses on  $n$  variables. Select  $c \cdot 2^n$  of them at random, with repetition permitted, and let  $P_n(c)$  be the probability that all of the selected clauses are simultaneously satisfiable. Prove that

$$\lim_{n \rightarrow \infty} P_n(c) = 1 - (1 - e^{-c})(1 - e^{-2c})(1 - e^{-4c})(1 - e^{-8c}) \dots$$

- 50. [22] A great many two-player games can be defined by specifying a directed graph in which each vertex represents a game position. There are two players, Alice and Bob, who construct an oriented path by starting at a particular vertex and taking turns to extend the path, one arc at a time. Before the game starts, each vertex has either been marked A (meaning that Alice wins), or marked B (meaning that Bob wins), or marked C (meaning that the cat wins), or left unmarked.

When the path reaches a vertex  $v$  marked A or B, that player wins. The game stops without a winner if  $v$  has been visited before, with the same player to move. If  $v$  is marked C, the currently active player has the option of accepting a draw; otherwise he or she must choose an outgoing arc to extend the path, and the other player becomes active. (If  $v$  is an unmarked vertex with outdegree zero, the active player loses.)

Associating four propositional variables  $A^+(v)$ ,  $A^-(v)$ ,  $B^+(v)$ , and  $B^-(v)$  with every vertex  $v$  of the graph, explain how to construct a set of proper Horn clauses such that  $A^+(v)$  is in the core if and only if Alice can force a win when the path starts at  $v$  and she moves first;  $A^-(v)$  is in the core if and only if Bob can force her to lose in that game;  $B^+(v)$  and  $B^-(v)$  are similar to  $A^+(v)$  and  $A^-(v)$ , but with roles reversed.

51. [25] (*Boolean games*.) Any Boolean function  $f(x_1, \dots, x_n)$  leads to a game called "two steps forward or one step back," in the following way: There are two players, 0 and 1, who repeatedly assign values to the variables  $x_j$ ; player  $y$  tries to make  $f(x_1, \dots, x_n)$  equal to  $y$ . Initially all variables are unassigned, and the position marker  $m$  is zero. Players take turns, and the currently active player either sets  $m \leftarrow m + 2$  (if  $m + 2 \leq n$ ) or  $m \leftarrow m - 1$  (if  $m - 1 \geq 1$ ), then sets

$$\begin{cases} x_m \leftarrow 0 \text{ or } 1, & \text{if } x_m \text{ was not previously assigned;} \\ x_m \leftarrow \bar{x}_m, & \text{if } x_m \text{ was previously assigned.} \end{cases}$$

The game is over as soon as a value has been assigned to all variables; then  $f(x_1, \dots, x_n)$  is the winner. A draw is declared if the same state (including the value of  $m$ ) is reached twice. Notice that at most four moves are possible at any time.

Study examples of this game when  $2 \leq n \leq 9$ , in the following four cases:

- $f(x_1, \dots, x_n) = [x_1 \dots x_n < x_n \dots x_1]$  (in lexicographic order);
- $f(x_1, \dots, x_n) = x_1 \oplus \dots \oplus x_n$ ;
- $f(x_1, \dots, x_n) = [x_1 \dots x_n \text{ contains no two consecutive 1s}]$ ;
- $f(x_1, \dots, x_n) = [(x_1 \dots x_n)_2 \text{ is prime}]$ .

52. [23] Show that the impossible comedy festival of (37) can be scheduled if a change is made to the requirements of only (a) Tomlin; (b) Unwin; (c) Vegas; (d) Xie; (e) Yankovic; (f) Zany.

53. [20] Let  $S = \{u_1, u_2, \dots, u_k\}$  be the set of literals in some strong component of a digraph that corresponds to a 2CNF formula as in Fig. 4. Show that  $S$  contains both a variable and its complement if and only if  $u_j = \bar{u}_1$  for some  $j$  with  $2 \leq j \leq k$ .

- 54. [20] The satisfiability problem for a Boolean function  $f(x_1, x_2, \dots, x_n)$  can be stated formally as the question of whether or not the quantified formula

$$\exists x_1 \exists x_2 \dots \exists x_n f(x_1, x_2, \dots, x_n)$$

is true; here ‘ $\exists x_j \alpha$ ’ means, “there exists a Boolean value  $x_j$  such that  $\alpha$  holds.”

A much more general evaluation problem arises when we replace one or more of the existential quantifiers  $\exists x_j$  by the universal quantifier  $\forall x_j$ , where ‘ $\forall x_j \alpha$ ’ means, “for all Boolean values  $x_j$ ,  $\alpha$  holds.”

Which of the eight quantified formulas  $\exists x \exists y \exists z f(x, y, z)$ ,  $\exists x \exists y \forall z f(x, y, z)$ ,  $\dots$ ,  $\forall x \forall y \forall z f(x, y, z)$  are true when  $f(x, y, z) = (x \vee y) \wedge (\bar{x} \vee z) \wedge (y \vee \bar{z})$ ?

- 55. [30] (B. Aspvall, M. F. Plass, and R. E. Tarjan.) Continuing exercise 54, design an algorithm that decides in linear time whether or not a given fully quantified formula  $f(x_1, \dots, x_n)$  is true, when  $f$  is any formula in 2CNF (any conjunction of Krom clauses).
- 56. [35] Continuing exercise 55, design an efficient algorithm that decides whether or not a given fully quantified conjunction of *Horn* clauses is true.
- 57. [M20] (D. Pehoushek, 1999.) If the truth table for  $f(x_1, x_2, \dots, x_n)$  has exactly  $k$  1s, show that exactly  $k$  of the fully quantified formulas  $Qx_1 Qx_2 \dots Qx_n f(x_1, x_2, \dots, x_n)$  are true, when each  $Q$  is either  $\exists$  or  $\forall$ .
58. [12] Which of the following expressions yield the median  $\langle xyz \rangle$ , as defined in (43)?  
 (a)  $(x \wedge y) \oplus (y \wedge z) \oplus (x \wedge z)$ . (b)  $(x \vee y) \oplus (y \vee z) \oplus (x \vee z)$ . (c)  $(x \oplus y) \wedge (y \oplus z) \wedge (x \oplus z)$ .  
 (d)  $(x \equiv y) \oplus (y \equiv z) \oplus (x \equiv z)$ . (e)  $(x \bar{\wedge} y) \wedge (y \bar{\wedge} z) \wedge (x \bar{\wedge} z)$ . (f)  $(x \bar{\wedge} y) \vee (y \bar{\wedge} z) \vee (x \bar{\wedge} z)$ .
59. [13] True or false: If  $\circ$  is any one of the Boolean binary operations in Table 1, we have the distributive law  $w \circ \langle xyz \rangle = \langle (w \circ x)(w \circ y)(w \circ z) \rangle$ .
60. [25] (C. Schensted.) If  $f(x_1, \dots, x_n)$  is a monotone Boolean function and  $n \geq 3$ , prove the median expansion formula

$$f(x_1, \dots, x_n) = \langle f(x_1, x_1, x_3, x_4, \dots, x_n) f(x_1, x_2, x_2, x_4, \dots, x_n) f(x_3, x_2, x_3, x_4, \dots, x_n) \rangle.$$

61. [20] Equation (49) shows how to compute the median of five elements via medians of three. Conversely, can we compute  $\langle xyz \rangle$  with a subroutine for medians of five?
62. [23] (S. B. Akers, Jr.) (a) Prove that a Boolean function  $f(x_1, \dots, x_n)$  is monotone and self-dual if and only if it satisfies the following condition:

For all  $x = x_1 \dots x_n$  and  $y = y_1 \dots y_n$  there exists  $k$  such that  $f(x) = x_k$  and  $f(y) = y_k$ .

(b) Suppose  $f$  is undefined for certain values, but the stated condition holds whenever both  $f(x)$  and  $f(y)$  are defined. Show that there is a monotone self-dual Boolean function  $g$  for which  $g(x) = f(x)$  whenever  $f(x)$  is defined.

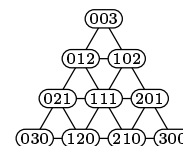
- 63. [M21] Any subset  $X$  of  $\{1, 2, \dots, n\}$  corresponds to a binary vector  $x = x_1 x_2 \dots x_n$  via the rule  $x_j = [j \in X]$ . And any family  $\mathcal{F}$  of such subsets corresponds to a Boolean function  $f(x) = f(x_1, x_2, \dots, x_n)$  of  $n$  variables, via the rule  $f(x) = [X \in \mathcal{F}]$ . Therefore every statement about families of subsets corresponds to a statement about Boolean functions, and vice versa.

A family  $\mathcal{F}$  is called *intersecting* if  $X \cap Y \neq \emptyset$  whenever  $X, Y \in \mathcal{F}$ . An intersecting family that loses this property whenever we try to add another subset is said to be *maximal*. Prove that  $\mathcal{F}$  is a maximal intersecting family if and only if the corresponding Boolean function  $f$  is monotone and self-dual.

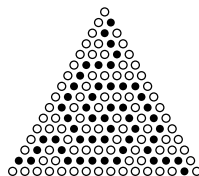
- **64.** [M25] A *coterie* of  $\{1, \dots, n\}$  is a family  $\mathcal{C}$  of subsets called *quorums*, which have the following properties whenever  $Q \in \mathcal{C}$  and  $Q' \in \mathcal{C}$ : (i)  $Q \cap Q' \neq \emptyset$ ; (ii)  $Q \subseteq Q'$  implies  $Q = Q'$ . Coterie  $\mathcal{C}$  *dominates* coterie  $\mathcal{C}'$  if  $\mathcal{C} \neq \mathcal{C}'$  and if, for every  $Q' \in \mathcal{C}'$ , there is a  $Q \in \mathcal{C}$  with  $Q \subseteq Q'$ . For example, the coterie  $\{\{1, 2\}, \{2, 3\}\}$  is dominated by  $\{\{1, 2\}, \{1, 3\}, \{2, 3\}\}$  and also by  $\{\{2\}\}$ . [Coterie were introduced in classic papers by L. Lamport, *CACM* **21** (1978), 558–565; H. Garcia-Molina and D. Barbara, *JACM* **32** (1985), 841–860. They have numerous applications to distributed system protocols, including mutual exclusion, data replication, and name servers. In these applications  $\mathcal{C}$  is preferred to any coterie that it dominates.]

Prove that  $\mathcal{C}$  is a nondominated coterie if and only its quorums are the index sets of variables in the prime implicants of a monotone self-dual Boolean function  $f(x_1, \dots, x_n)$ . (Thus Table 2 illustrates the nondominated coterie on  $\{1, 2, 3, 4\}$ .)

- **65.** [M30] (C. Schensted.) A triangular grid of order  $n$ , illustrated here for  $n = 3$ , contains  $(n+2)(n+1)/2$  points with “barycentric coordinates”  $xyz$ , where  $x, y, z \geq 0$  and  $x+y+z = n$ . Two points are adjacent if they differ by  $\pm 1$  in exactly two coordinate positions. A point is said to lie on the  $x$  side if its  $x$  coordinate is zero, on the  $y$  side if its  $y$  coordinate is zero, or on the  $z$  side if its  $z$  coordinate is zero; thus each side contains  $n+1$  points. If  $n > 0$ , a point lies on two different sides if and only if it occupies one of the three corner positions.



A “Y” is a connected set of points with at least one point on each side. Suppose each vertex of a triangular grid is covered with a white stone or a black stone. For example, the 52 black stones in



contain a (somewhat distorted) Y; but if any of them is changed from black to white, there is a white Y instead. A moment’s thought makes it intuitively clear that, in any placement, the black stones contain a Y if and only if the white stones do not.

We can represent the color of each stone by a Boolean variable, with 0 for white and 1 for black. Let  $Y(t) = 1$  if and only if there’s a black Y, where  $t$  is a triangular grid comprising all the Boolean variables. This function  $Y$  is clearly monotone; and the intuitive claim made in the preceding paragraph is equivalent to saying that  $Y$  is also self-dual. The purpose of this exercise is to prove the claim rigorously, using median algebra.

Given  $a, b, c \geq 0$ , let  $t_{abc}$  be the triangular subgrid containing all points whose coordinates  $xyz$  satisfy  $x \geq a, y \geq b, z \geq c$ . For example,  $t_{001}$  denotes all points except those on the  $z$  side (the bottom row). Notice that, if  $a+b+c = n$ ,  $t_{abc}$  is the single point with coordinates  $abc$ ; and in general,  $t_{abc}$  is a triangular grid of order  $n-a-b-c$ .

- Prove that, if  $n > 0$ ,  $Y(t) = \langle Y(t_{100})Y(t_{010})Y(t_{001}) \rangle$ .
- If  $n > 0$ , let  $t^*$  be the triangular grid of order  $n-1$  defined by the rule

$$t_{xyz}^* = \langle t_{(x+1)yz} t_{x(y+1)z} t_{xy(z+1)} \rangle, \quad \text{for } x+y+z = n-1.$$

Prove that  $Y(t) = Y(t^*)$ . [In other words,  $t^*$  condenses each small triangle of stones by taking the median of their colors. Repeating this process defines a

*pyramid* of stones, with the top stone black if and only if there is a black Y at the bottom. It's fun to apply this condensation principle to the twisted Y above.]

**66.** [46] The just-barely-Y configuration shown in the previous exercise has 52 black stones. What is a largest number of black stones possible in such a configuration?

- **67.** [M26] (C. Schensted.) Exercise 65 expresses the  $Y$  function in terms of medians. Conversely, let  $f(x_1, \dots, x_n)$  be any monotone self-dual Boolean function with  $m+1$  prime implicants  $p_0, p_1, \dots, p_m$ . Prove that  $f(x_1, \dots, x_n) = Y(T)$ , where  $T$  is any triangular grid of order  $m-1$  in which  $T_{abc}$  is a variable common to  $p_a$  and  $p_{a+b+1}$ , for  $a+b+c = m-1$ . For example, when  $f(w, x, y, z) = \langle xwywz \rangle$  we have  $m=3$  and

$$f(w, x, y, z) = (w \wedge x) \vee (w \wedge y) \vee (w \wedge z) \vee (x \wedge y \wedge z) = Y\left(\begin{smallmatrix} w & & \\ & w & \\ x & y & z \end{smallmatrix}\right).$$

- **68.** [M20] (A. Meyerowitz, 1989.) Given any monotone self-dual Boolean function  $f(x) = f(x_1, \dots, x_n)$ , choose any prime implicant  $x_{j_1} \wedge \dots \wedge x_{j_s}$  and let

$$g(x) = (f(x) \wedge [x \neq t]) \vee [x = \bar{t}],$$

where  $t = t_1 \dots t_n$  is the bit vector that has 1s in positions  $\{j_1, \dots, j_s\}$ . Prove that  $g(x)$  is also monotone and self-dual. (Notice that  $g(x)$  is equal to  $f(x)$  except at the two points  $t$  and  $\bar{t}$ .)

- **69.** [M21] Given the axioms (50), (51), and (52) of a median algebra, prove that the long distributive law (54) is a consequence of the shorter law (53).

**70.** [M22] Derive (58), (59), and (60) from the median laws (50)–(53).

**71.** [M32] (S. P. Avann.) Given a median algebra  $M$ , whose intervals are defined by (57) and whose corresponding median graph is defined by (61), let  $d(u, v)$  denote the distance from  $u$  to  $v$ . Also let ' $[uxv]$ ' stand for the statement " $x$  lies on a shortest path from  $u$  to  $v$ ."

- Prove that  $[uxv]$  holds if and only if  $d(u, v) = d(u, x) + d(x, v)$ .
- Suppose  $x \in [u \dots v]$  and  $u \in [x \dots y]$ , where  $y - v$  is an edge of the graph. Show that  $x - u$  is also an edge.
- If  $x \in [u \dots v]$ , prove  $[uxv]$ , by induction on  $d(u, v)$ .
- Conversely, prove that  $[uxv]$  implies  $x \in [u \dots v]$ .

**72.** [M21] In a median algebra, show that  $w = \langle xyz \rangle$  whenever we have  $w \in [x \dots y]$ ,  $w \in [x \dots z]$ , and  $w \in [y \dots z]$  according to definition (57).

- **73.** [M36] (M. Sholander, 1954.) Suppose  $M$  is a set of points with a betweenness relation " $x$  lies between  $u$  and  $v$ ," symbolized by  $[uxv]$ , which satisfies the following three axioms:

- If  $[uvu]$  then  $u = v$ .
- If  $[uxv]$  and  $[xyu]$  then  $[vyu]$ .
- Given  $x, y$ , and  $z$ , exactly one point  $w = \langle xyz \rangle$  satisfies  $[xwy]$ ,  $[xwz]$ , and  $[y wz]$ .

The object of this exercise is to prove that  $M$  is a median algebra.

- Prove the majority law  $\langle xxy \rangle = x$ , Eq. (50).
- Prove the commutative law  $\langle xyz \rangle = \langle xzy \rangle = \dots = \langle zyx \rangle$ , Eq. (51).
- Prove that  $[uxv]$  if and only if  $x = \langle uxv \rangle$ .
- If  $[uxy]$  and  $[uyv]$ , prove that  $[xyv]$ .
- If  $[uxv]$  and  $[uyz]$  and  $[vyz]$ , prove that  $[xyz]$ . *Hint:* Construct the points  $w = \langle yuv \rangle$ ,  $p = \langle wvx \rangle$ ,  $q = \langle wxz \rangle$ ,  $r = \langle p x z \rangle$ ,  $s = \langle q x z \rangle$ , and  $t = \langle r s z \rangle$ .
- Finally, deduce the short distributive law, Eq. (53):  $\langle \langle xyz \rangle uv \rangle = \langle x \langle yuv \rangle \langle zuv \rangle \rangle$ .

**74.** [M33] Derive the betweenness axioms (i), (ii), and (iii) of exercise 73, starting from the three median axioms (50), (51), and (52), letting  $[uxv]$  be an abbreviation for “ $x = \langle uxv \rangle$ .” Do not use the distributive law (53). *Hint:* See exercise 72.

**75.** [M28] Let  $G$  be a median graph containing the edge  $r - s$ . For each edge  $u - v$ , call  $u$  an *early neighbor* of  $v$  if and only if  $r$  is closer to  $u$  than to  $v$ . Partition the vertices into “left” and “right” parts, where left vertices are closer to  $r$  than to  $s$  and right vertices are closer to  $s$  than to  $r$ . Each right vertex  $v$  has a *rank*, which is the shortest distance from  $v$  to a left vertex. Similarly, each left vertex  $u$  has rank  $1 - d$ , where  $d$  is the shortest distance from  $u$  to a right vertex. Thus  $u$  has rank zero if it is adjacent to a right vertex, otherwise its rank is negative. Vertex  $r$  clearly has rank 0, and  $s$  has rank 1.

- Show that every vertex of rank 1 is adjacent to exactly one vertex of rank 0.
- Show that the set of all right vertices is convex.
- Show that the set of all vertices with rank 1 is convex.
- Prove that steps I3–I9 of Subroutine I correctly mark all vertices of ranks 1 and 2.
- Prove that Algorithm H is correct.

► **76.** [M26] If the vertex  $v$  is examined  $k$  times in step I4 during the execution of Algorithm H, prove that the graph has at least  $2^k$  vertices. *Hint:* There are  $k$  ways to start a shortest path from  $v$  to  $a$ ; thus at least  $k$  1s appear in  $l(v)$ .

► **77.** [M27] (R. L. Graham.) A *subgraph of a hypercube* is a graph whose vertices  $v$  can be labeled with bit strings  $l(v)$  in such a way that  $u - v$  if and only if  $l(u)$  and  $l(v)$  differ in exactly one bit position. (Each label has the same length.)

- One way to define an  $n$ -vertex subgraph of a hypercube is to let  $l(v)$  be the binary representation of  $v$ , for  $0 \leq v < n$ . Show that this subgraph has exactly  $f(n) = \sum_{k=0}^{n-1} \nu(k)$  edges, where  $\nu(k)$  is the sideways addition function.
- Prove that  $f(n) \leq n \lceil \lg n \rceil / 2$ .
- Prove that no  $n$ -vertex subgraph of a hypercube has more than  $f(n)$  edges.

**78.** [27] A *partial cube* is an “isometric” subgraph of a hypercube, namely a subgraph in which the distances between vertices are the same as they are in the full graph. The vertices of a partial cube can therefore be labeled in such a way that the distance from  $u$  to  $v$  is the “Hamming distance” between  $l(u)$  and  $l(v)$ , namely  $\nu(l(u) \oplus l(v))$ . Algorithm H shows that every median graph is a partial cube.

- Find a subgraph of the 4-cube that isn’t a partial cube.
- Give an example of a partial cube that isn’t a median graph.

**79.** [16] Is every median graph bipartite?

**80.** [25] (*Incremental changes in service.*) Given a sequence of vertices  $(v_0, v_1, \dots, v_t)$  in a graph  $G$ , consider the problem of finding another sequence  $(u_0, u_1, \dots, u_t)$  for which  $u_0 = v_0$  and the sum

$$(d(u_0, u_1) + d(u_1, u_2) + \dots + d(u_{t-1}, u_t)) + (d(u_1, v_1) + d(u_2, v_2) + \dots + d(u_t, v_t))$$

is minimized, where  $d(u, v)$  denotes the distance from  $u$  to  $v$ . (Each  $v_k$  can be regarded as a request for a resource needed at that vertex; a server moves to  $u_k$  as those requests are handled in sequence.) Prove that if  $G$  is a median graph, we get an optimum solution by choosing  $u_k = \langle u_{k-1} v_k v_{k+1} \rangle$  for  $0 < k < t$ , and  $u_t = v_t$ .

► **81.** [28] Generalizing exercise 80, find an efficient way to minimize

$$(d(u_0, u_1) + d(u_1, u_2) + \dots + d(u_{n-1}, u_n)) + \rho(d(u_1, v_1) + d(u_2, v_2) + \dots + d(u_n, v_n))$$

in a median graph, given any positive ratio  $\rho$ .



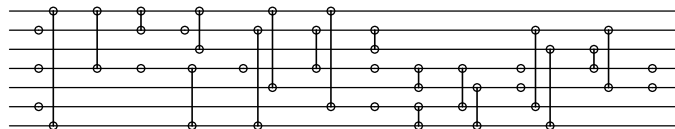
**82.** [30] Write a program to find all monotone self-dual Boolean functions of five variables. What are the edges of the corresponding median graph? (Table 2 illustrates the four-variable case.)

► **83.** [M22] Theorem S tells us that every formula in 2CNF corresponds to a median set; therefore every antisymmetric digraph such as Fig. 4 also corresponds to a median set. Precisely which of those digraphs correspond to *reduced* median sets?

**84.** [15] If  $v, w, x, y$ , and  $z$  belong to a median set  $X$ , does their five-element median  $\langle vwxyz \rangle$ , computed componentwise, always belong to  $X$ ?

**85.** [24] What CI-net does the proof of Theorem F construct for the free tree (63)?

**86.** [M21] We can use parallel computation to condense the network (74) into



by letting each module act at the earliest possible time. Prove that, although the network constructed in the proof of Theorem F may contain  $\Omega(t^2)$  modules, it always requires at most  $O(t \log t)$  levels of delay.

**87.** [24] When the construction (73) appends a new cluster of modules to enforce the condition  $u \rightarrow v$ , for some literals  $u$  and  $v$ , prove that it preserves all previously enforced conditions  $u' \rightarrow v'$ .

► **88.** [21] Construct a CI-net with input bits  $x_1 \dots x_t$  and output bits  $y_1 \dots y_t$ , where  $y_1 = \dots = y_{t-1} = 0$  and  $y_t = x_1 \oplus \dots \oplus x_t$ . Try for only  $O(\log t)$  levels of delay.

**89.** [46] Can a retraction mapping for the labels of every median graph of dimension  $t$  be computed by a CI-net that has only  $O(\log t)$  levels of delay? [This question is motivated by the existence of asymptotically optimum networks for the analogous problem of sorting; see M. Ajtai, J. Komlós, and E. Szemerédi, *Combinatorica* **3** (1983), 1–19.]

**90.** [46] Can a CI-net sort  $n$  Boolean inputs with fewer modules than a “pure” sorting network that has no inverters?

**91.** [M20] Prove that every retract  $X$  of a graph  $G$  is an isometric subgraph of  $G$ . (In other words, distances in  $X$  are the same as in  $G$ ; see exercise 78.)

**92.** [M21] Prove that every retract  $X$  of a hypercube is a set of median labels, if we suppress coordinates that are constant for all  $x \in X$ .

**93.** [M25] True or false: The set of all outputs produced by a comparator-inverter network, when the inputs range over all possible bit strings, is always a median set.

**94.** [HM25] Instead of insisting that the constants  $w_1, w_2, \dots, w_n$ , and  $T$  in (75) must be integers, we could allow them to be arbitrary real numbers. Would that increase the number of threshold functions?

**95.** [10] What median/majority functions arise in (81) when  $n = 2$ ,  $w_1 = w_2 = 1$ , and  $t = -1, 0, 1, 2, 3$ , or  $4$ ?

**96.** [M21] Prove that any self-dual threshold function can be expressed in the form

$$f(x_1, x_2, \dots, x_n) = [v_1 y_1 + \dots + v_n y_n > 0],$$

where each  $y_j$  is either  $x_j$  or  $\bar{x}_j$ . For example,  $2x_1 + 3x_2 + 5x_3 + 7x_4 + 11x_5 + 13x_6 \geq 21$  if and only if  $2x_1 + 3x_2 + 5x_3 - 7\bar{x}_4 + 11x_5 - 13\bar{x}_6 > 0$ .

- 97. [20] (J. E. Mezei, 1961.) Prove that

$$\langle x_1 \dots x_{2s-1} \rangle y_1 \dots y_{2t-2} = \langle x_1 \dots x_{2s-1} y_1^s \dots y_{2t-2}^s \rangle.$$

98. [20] True or false: If  $f(x_1, \dots, x_n)$  is a threshold function, so are the functions  $f(x_1, \dots, x_n) \wedge x_{n+1}$  and  $f(x_1, \dots, x_n) \vee x_{n+1}$ .

99. [M23] The *Fibonacci threshold function*  $F_n(x_1, \dots, x_n)$  is defined by the formula  $\langle x_1^{F_1} x_2^{F_2} \dots x_{n-1}^{F_{n-1}} x_n^{F_n-2} \rangle$  when  $n \geq 3$ ; for example,  $F_7(x_1, \dots, x_7) = \langle x_1 x_2 x_3^2 x_4^3 x_5^5 x_6^8 x_7^5 \rangle$ .

- What are the prime implicants of  $F_n(x_1, \dots, x_n)$ ?
- Find an orthogonal DNF for  $F_n(x_1, \dots, x_n)$  (see exercise 35).
- Express  $F_n(x_1, \dots, x_n)$  in terms of the  $Y$  function (see exercises 65 and 67).

100. [M21] The *self-dualization* of a Boolean function is defined by the formulas

$$\begin{aligned} \hat{f}(x_0, x_1, \dots, x_n) &= (x_0 \wedge f(x_1, \dots, x_n)) \vee (\bar{x}_0 \wedge \overline{f(\bar{x}_1, \dots, \bar{x}_n)}) \\ &= (\bar{x}_0 \vee f(x_1, \dots, x_n)) \wedge (x_0 \vee \overline{f(\bar{x}_1, \dots, \bar{x}_n)}). \end{aligned}$$

- If  $f(x_1, \dots, x_n)$  is any Boolean function, prove that  $\hat{f}$  is self-dual.
- Prove that  $\hat{f}$  is a threshold function if and only if  $f$  is a threshold function.

101. [HM25] Explain how to use linear programming to test whether or not a monotone, self-dual Boolean function is a threshold function, given a list of its prime implicants. Also, if it is a threshold function, explain how to minimize the size of its representation as a majority function  $\langle x_1^{w_1} \dots x_n^{w_n} \rangle$ .

102. [25] Apply the method of exercise 101 to find the shortest representations of the following threshold functions as majority functions: (a)  $\langle x_1^2 x_2^3 x_3^5 x_4^7 x_5^{11} x_6^{13} x_7^{17} x_8^{19} \rangle$ ; (b)  $\langle (x_1 x_2 x_3 x_4)_2 \geq t \rangle$ , for  $0 \leq t \leq 16$  (17 cases); (c)  $\langle x_1^{29} x_2^{25} x_3^{19} x_4^{15} x_5^{12} x_6^8 x_7^8 x_8^3 x_9^3 x_{10} \rangle$ .

103. [M25] Show that the Fibonacci threshold function in exercise 99 has no shorter representation as a majority function than the one used to define it.

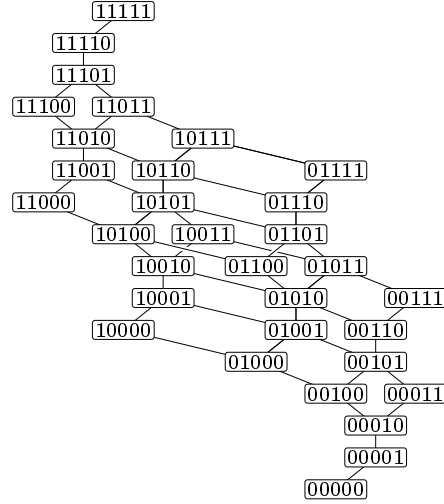
- 104. [M25] The median-of-three operation  $\langle x\bar{y}\bar{z} \rangle$  is true if and only if  $x \geq y + z$ .
- Generalizing, show that we can test the condition  $(x_1 x_2 \dots x_n)_2 \geq (y_1 y_2 \dots y_n)_2 + z$  by performing a median of  $2^{n+1} - 1$  Boolean variables.
  - Prove that no median of fewer than  $2^{n+1} - 1$  will suffice for this problem.

105. [17] Calculate  $N(f)$  and  $\Sigma(f)$  for the 16 functions in Table 1. (See Theorem T.)

106. [M21] Let  $g(x_0, x_1, \dots, x_n)$  be a self-dual function; thus  $N(g) = 2^n$  in the notation of Theorem T. Express  $N(f)$  and  $\Sigma(f)$  in terms of  $\Sigma(g)$ , when  $f(x_1, \dots, x_n)$  is (a)  $g(0, x_1, \dots, x_n)$ ; (b)  $g(1, x_1, \dots, x_n)$ .

107. [M25] The binary string  $\alpha = a_1 \dots a_n$  is said to *majorize* the binary string  $\beta = b_1 \dots b_n$ , written  $\alpha \succeq \beta$  or  $\beta \preceq \alpha$ , if  $a_1 + \dots + a_k \geq b_1 + \dots + b_k$  for all  $k \geq 0$ .

- Let  $\bar{\alpha} = \bar{a}_1 \dots \bar{a}_n$ . Show that  $\alpha \succeq \beta$  if and only if  $\bar{\beta} \succeq \bar{\alpha}$ .
- Show that any two binary strings of length  $n$  have a greatest lower bound  $\alpha \wedge \beta$ , which has the property that  $\alpha \succeq \gamma$  and  $\beta \succeq \gamma$  if and only if  $\alpha \wedge \beta \succeq \gamma$ . Explain how to compute  $\alpha \wedge \beta$ , given  $\alpha$  and  $\beta$ .
- Similarly, explain how to compute a least upper bound  $\alpha \vee \beta$ , with the property that  $\gamma \succeq \alpha$  and  $\gamma \succeq \beta$  if and only if  $\gamma \succeq \alpha \vee \beta$ .
- True or false:  $\alpha \wedge (\beta \vee \gamma) = (\alpha \wedge \beta) \vee (\alpha \wedge \gamma)$ ;  $\alpha \vee (\beta \wedge \gamma) = (\alpha \vee \beta) \wedge (\alpha \vee \gamma)$ .
- Say that  $\alpha$  *covers*  $\beta$  if  $\alpha \succeq \beta$  and  $\alpha \neq \beta$ , and if  $\alpha \succeq \gamma \succeq \beta$  implies that we have either  $\gamma = \alpha$  or  $\gamma = \beta$ . For example, Fig. 6 illustrates the covering relations between binary strings of length 5. Find a simple way to describe the strings that are covered by a given binary string.



**Fig. 6.** The binary majorization lattice for strings of length 5. (See exercise 107.)

- f) Show that every path  $\alpha = \alpha_0, \alpha_1, \dots, \alpha_r = 0 \dots 0$  from a given string  $\alpha$  to  $0 \dots 0$ , where  $\alpha_{j-1}$  covers  $\alpha_j$  for  $1 \leq j \leq r$ , has the same length  $r = r(\alpha)$ .
- g) Let  $m(\alpha)$  be the number of binary strings  $\beta$  with  $\beta \succeq \alpha$ . Prove that  $m(1\alpha) = m(\alpha)$  and  $m(0\alpha) = m(\alpha) + m(\alpha')$ , where  $\alpha'$  is  $\alpha$  with its leftmost 1 (if any) changed to 0.
- h) How many strings  $\alpha$  of length  $n$  satisfy  $\bar{\alpha} \succeq \alpha$ ?
- 108.** [M21] A Boolean function is called *regular* if  $x \preceq y$  implies that  $f(x) \leq f(y)$  for all vectors  $x$  and  $y$ , where  $\preceq$  is the majorization relation in exercise 107. Prove or disprove the following statements:
- Every regular function is monotone.
  - If  $f$  is a threshold function (75) for which  $w_1 \geq w_2 \geq \dots \geq w_n$ ,  $f$  is regular.
  - If  $f$  is as in (b) and  $\Sigma(f) = (s_1, \dots, s_n)$ , then  $s_1 \geq s_2 \geq \dots \geq s_n$ .
  - If  $f$  is a threshold function (75) with  $s_1 \geq s_2 \geq \dots \geq s_n$ , then  $w_1 \geq w_2 \geq \dots \geq w_n$ .
- 109.** [M30] An *optimum coterie* for a system with working probabilities  $(p_1, \dots, p_n)$  is a coterie that corresponds to a monotone self-dual function with maximum availability, among all monotone self-dual functions with  $n$  variables. (See exercises 14 and 64.)
- Prove that if  $1 \geq p_1 \geq \dots \geq p_n \geq \frac{1}{2}$ , at least one self-dual function with maximum availability is a regular function.
  - Furthermore, it suffices to test the optimality of  $f$  at points  $y$  of the binary majorization lattice for which  $f(y) = 1$  but  $f(x) = 0$  for all  $x$  covered by  $y$ .
  - What coterie is optimum when some probabilities are  $< \frac{1}{2}$ ?
- **110.** [M37] (J. Håstad.) If  $f(x_1, x_2, \dots, x_m)$  is a Boolean function, let  $M(f)$  be its representation as a multilinear polynomial with integer coefficients (see exercise 12). Arrange the terms in this polynomial by using Chase's sequence  $\alpha_0 = 00 \dots 0$ ,  $\alpha_1 = 10 \dots 0$ ,  $\dots$ ,  $\alpha_{2^m-1} = 11 \dots 1$  to order the exponents; Chase's sequence, obtained by concatenating the sequences  $A_{n_0}, A_{(n-1)_1}, \dots, A_{0n}$  of 7.2.1.3–(35), has the nice property that  $\alpha_j$  is identical to  $\alpha_{j+1}$  except for a slight change, either  $0 \rightarrow 1$  or  $01 \rightarrow 10$  or  $001 \rightarrow 100$  or  $10 \rightarrow 01$  or  $100 \rightarrow 001$ . For example, Chase's sequence is

0000, 1000, 0010, 0001, 0100, 1100, 1010, 1001, 0011, 0101, 0110, 1110, 1101, 1011, 0111, 1111

when  $m = 4$ , corresponding to the respective terms  $1, x_1, x_3, x_4, x_2, x_1x_2, \dots, x_2x_3x_4, x_1x_2x_3x_4$ ; so the multilinear representation of, say,  $((x_1 \oplus \bar{x}_2) \wedge x_3) \vee (x_1 \wedge \bar{x}_3 \wedge x_4)$  is

$$x_3 - x_1x_3 + x_1x_4 - x_2x_3 + 2x_1x_2x_3 - x_1x_3x_4$$

when the terms have been arranged in this order. Now let

$$F(f) = [\text{the most significant coefficient of } M(f) \text{ is positive}].$$

For example, the most significant (final) nonzero term of  $((x_1 \oplus \bar{x}_2) \wedge x_3) \vee (x_1 \wedge \bar{x}_3 \wedge x_4)$  is  $-x_1x_3x_4$  in Chase's ordering, so  $F(f) = 0$  in this case.

- a) Determine  $F(f)$  for each of the 16 functions in Table 1.
- b) Show that  $F(f)$  is a threshold function of the  $n = 2^m$  entries  $\{f_{0\dots 00}, f_{0\dots 01}, \dots, f_{1\dots 11}\}$  of the truth table for  $f$ . Write this function out explicitly when  $m = 2$ .
- c) Prove that, when  $m$  is large, all the weights in any threshold representation of  $F$  must be huge: Their absolute values must all exceed

$$\frac{3^{\binom{m}{3}} 7^{\binom{m}{4}} 15^{\binom{m}{5}} \dots (2^m - 1)^{\binom{m}{m}}}{n} = 2^{mn/2 - n - 2(3/2)^m / \ln 2 + O((5/4)^m)}.$$

*Hint:* Consider discrete Fourier transforms of the truth table entries.

**111.** [24] Show that the following three threshold operations suffice to evaluate the function  $S_{2,3,6,8,9}(x_1, \dots, x_{12})$  in  $(g_1)$ :

$$\begin{aligned} g_1(x_1, \dots, x_{12}) &= [\nu x \geq 6] = \langle 1x_1 \dots x_{12} \rangle; \\ g_2(x_1, \dots, x_{12}) &= [\nu x - 6g_1 \geq 2] = \langle 1^3 x_1 \dots x_{12} g_1^6 \rangle; \\ g_3(x_1, \dots, x_{12}) &= [-2\nu x + 13g_1 + 7g_2 \geq 1] = \langle 0^5 \bar{x}_1^2 \dots \bar{x}_{12} g_1^{13} g_2^7 \rangle. \end{aligned}$$

Also find a four-threshold scheme that evaluates  $S_{1,3,5,8}(x_1, \dots, x_{12})$ .

**112.** [20] (D. A. Huffman.) What is the function  $S_{3,6}(xxxxyyz)$ ?

**113.** [M22] Explain why  $(g_2)$  correctly computes the parity function  $x_0 \oplus x_1 \oplus \dots \oplus x_{2m}$ .

► **114.** [HM28] (B. Dunham and R. Fridshal, 1957.) By considering symmetric functions, one can prove that Boolean functions of  $n$  variables can have many prime implicants.

- a) Suppose  $0 \leq j \leq k \leq n$ . For which symmetric functions  $f(x_1, \dots, x_n)$  is the term  $x_1 \wedge \dots \wedge x_j \wedge \bar{x}_{j+1} \wedge \dots \wedge \bar{x}_k$  a prime implicant?
- b) How many prime implicants does the function  $S_{3,4,5,6}(x_1, \dots, x_9)$  have?
- c) Let  $\hat{b}(n)$  be the maximum number of prime implicants, over all symmetric Boolean functions of  $n$  variables. Find a recurrence formula for  $\hat{b}(n)$ , and compute  $\hat{b}(9)$ .
- d) Prove that  $\hat{b}(n) = \Theta(3^n/n)$ .
- e) Show that, furthermore, there are symmetric functions  $f(x_1, \dots, x_n)$  for which both  $f$  and  $\bar{f}$  have  $\Theta(2^{3n/2}/n)$  prime implicants.

**115.** [M26] A disjunctive normal form is called *irredundant* if none of its implicants implies another. Let  $b^*(n)$  be the maximum number of implicants in an irredundant DNF, over all Boolean functions of  $n$  variables. Find a simple formula for  $b^*(n)$ , and determine its asymptotic value.

**116.** [M48] Continuing the previous exercises, let  $b(n)$  be the maximum number of prime implicants in a Boolean function of  $n$  variables. Clearly  $\hat{b}(n) \leq b(n) < b^*(n)$ ; what is the asymptotic value of  $b(n)$ ?

- 117.** [23] What is the shortest DNF for the symmetric functions (a)  $x_1 \oplus x_2 \oplus \cdots \oplus x_n$ ? (b)  $S_{0,1,3,4,6,7}(x_1, \dots, x_7)$ ? (c) Prove that every Boolean function of  $n$  variables can be expressed as a DNF with at most  $2^{n-1}$  prime implicants.
- **118.** [M23] The function  $\langle 1(x_1 \oplus x_2)y_1y_2y_3 \rangle$  is partially symmetric, since it is symmetric in  $\{x_1, x_2\}$  and in  $\{y_1, y_2, y_3\}$ , but not in all five variables  $\{x_1, x_2, y_1, y_2, y_3\}$ .
- Exactly how many Boolean functions  $f(x_1, \dots, x_m, y_1, \dots, y_n)$  are symmetric in  $\{x_1, \dots, x_m\}$  and  $\{y_1, \dots, y_n\}$ ?
  - How many of those functions are monotone?
  - How many of those functions are self-dual?
  - How many of those functions are monotone and self-dual?
- 119.** [M25] Continuing exercises 108 and 118, find all Boolean functions  $f(x_1, x_2, x_3, y_1, y_2, y_3, y_4, y_5, y_6)$  that are simultaneously symmetric in  $\{x_1, x_2, x_3\}$ , symmetric in  $\{y_1, y_2, \dots, y_6\}$ , self-dual, and regular. Which of them are threshold functions?
- 120.** [46] How many self-dual Boolean functions of ten variables are (a) regular? (b) threshold functions?
- 121.** [20] Find a Boolean function of four variables that is equivalent to 767 other functions, under the ground rules of Table 5.
- 122.** [18] Which of the function classes in (95) are canalizing?
- 123.** [23] (a) Show that a Boolean function is canalizing if and only if its sets of prime implicants and prime clauses have a certain simple property. (b) Show that a Boolean function is canalizing if and only if its Chow parameters  $N(f)$  and  $\Sigma(f)$  have a certain simple property (see Theorem T). (c) Define the Boolean vectors
- $$\vee(f) = \bigvee \{x \mid f(x) = 1\} \quad \text{and} \quad \wedge(f) = \bigwedge \{x \mid f(x) = 1\};$$
- by analogy with the integer vector  $\Sigma(f)$ . Show that it's possible to decide whether or not  $f$  is canalizing, given only the four vectors  $\vee(f)$ ,  $\vee(\bar{f})$ ,  $\wedge(f)$ , and  $\wedge(\bar{f})$ .
- 124.** [M25] Which canalizing functions are (a) self-dual? (b) proper Horn functions?
- **125.** [20] Find a noncanalizing  $f(x_1, \dots, x_n)$  that is true at exactly two points.
- 126.** [M25] How many different canalizing functions of  $n$  variables exist?
- 127.** [M21] According to Table 3, there are 168 monotone Boolean functions of four variables. But some of them, like  $x \wedge y$ , depend on only three variables or fewer.
- How many 4-variable monotone Boolean functions actually involve each variable?
  - How many of those functions are distinct under permutation, as in Table 4?
- 128.** [HM42] Table 3 makes it clear that there are many more Horn functions than Krom functions. What is the asymptotic number, as  $n \rightarrow \infty$ ?
- **129.** [20] (Mark A. Smith, 1990.) Suppose we flip  $n$  independent coins to get  $n$  random bits, where the  $k$ th coin produces bit 1 with probability  $p_k$ . Find a way to choose  $(p_1, \dots, p_n)$  so that  $f(x_1, \dots, x_n) = 1$  with probability  $(t_0 t_1 \dots t_{2^n-1})_2 / (2^{2^n} - 1)$ , where  $t_0 t_1 \dots t_{2^n-1}$  is the truth table of the Boolean function  $f$ . (Thus,  $n$  suitable random coins can generate a probability with  $2^n$ -bit precision.)

## SECTION 7.1.1

1. He was describing the equation  $x \wedge y = z$ , with “it” standing respectively for  $x$ ,  $z$ ,  $y$ ,  $z$ ,  $y$  (or perhaps  $x$ ),  $z$ .

2. The Earth operation corresponding to the Pincusian  $x \circ y$  is  $\overline{x \circ y}$ ; its truth table is therefore the reverse of the complement of the truth table for  $\circ$ . Hence the respective answers are  $\top, \vee, \subset, \sqsubset, \supset, \sqsupset, \equiv, \wedge, \bar{\wedge}, \oplus, \bar{\oplus}, \bar{\supset}, \bar{\sqsupset}, \bar{\sqsubset}, \bar{\sqsupset}, \bar{\vee}, \perp$ . (Any identity involving the 16 operations of Table 1 implies a corresponding dual identity obtained by substituting the Pincusian equivalents. For example, each of De Morgan’s laws (11) and (12) is the dual of the other, as are the identities (3), (4) relating  $\equiv$  and  $\oplus$ . In this sense  $\equiv$  can be considered to be just as useful as its dual,  $\oplus$ .)

3. (a)  $\vee$ ; (b)  $\wedge$ ; (c)  $\bar{\sqsubset}$ ; (d)  $\equiv$ . [Many formulas actually work out better if we use  $-1$  for truth and  $+1$  for falsehood, even though this convention seems a bit immoral; then  $x \cdot y$  corresponds to  $\oplus$ . See the next exercise.]

4. [Trans. Amer. Math. Soc. 14 (1913), 481–488.] (a) Start with the truth tables for  $\sqsubset$  and  $\sqsupset$ ; then compute truth table  $\alpha \bar{\wedge} \beta$  bitwise from each known pair of truth tables  $\alpha$  and  $\beta$ , generating the results in order of the length of each formula and writing down a shortest formula that leads to each new 4-bit table:

$\sqsubset$ : $(x \bar{\wedge} (x \bar{\wedge} x)) \bar{\wedge} (x \bar{\wedge} (x \bar{\wedge} x))$	$\bar{\vee}$ : $(x \bar{\wedge} (x \bar{\wedge} x)) \bar{\wedge} ((y \bar{\wedge} y) \bar{\wedge} (x \bar{\wedge} x))$
$\wedge$ : $(x \bar{\wedge} y) \bar{\wedge} (x \bar{\wedge} y)$	$\equiv$ : $(x \bar{\wedge} y) \bar{\wedge} ((y \bar{\wedge} y) \bar{\wedge} (x \bar{\wedge} x))$
$\bar{\supset}$ : $(x \bar{\wedge} (x \bar{\wedge} y)) \bar{\wedge} (x \bar{\wedge} (x \bar{\wedge} y))$	$\bar{\sqsupset}$ : $y \bar{\wedge} y$
$\sqsubset$ : $x$	$\subset$ : $y \bar{\wedge} (x \bar{\wedge} x)$
$\bar{\sqsubset}$ : $(y \bar{\wedge} (x \bar{\wedge} x)) \bar{\wedge} (y \bar{\wedge} (x \bar{\wedge} x))$	$\bar{\sqsubset}$ : $x \bar{\wedge} x$
$\sqsupset$ : $y$	$\supset$ : $x \bar{\wedge} (x \bar{\wedge} y)$
$\oplus$ : $(y \bar{\wedge} (x \bar{\wedge} x)) \bar{\wedge} (x \bar{\wedge} (x \bar{\wedge} y))$	$\bar{\wedge}$ : $x \bar{\wedge} y$
$\vee$ : $(y \bar{\wedge} y) \bar{\wedge} (x \bar{\wedge} x)$	$\top$ : $x \bar{\wedge} (x \bar{\wedge} x)$

(b) In this case we start with four tables  $\sqsubset, \top, \sqsubset, \sqsupset$ , and we prefer formulas with fewer occurrences of variables whenever there’s a choice between formulas of a given length:

$\sqsubset$ : 0	$\bar{\vee}$ : $1 \bar{\wedge} ((y \bar{\wedge} 1) \bar{\wedge} (x \bar{\wedge} 1))$
$\wedge$ : $(x \bar{\wedge} y) \bar{\wedge} 1$	$\equiv$ : $(x \bar{\wedge} y) \bar{\wedge} ((y \bar{\wedge} 1) \bar{\wedge} (x \bar{\wedge} 1))$
$\bar{\supset}$ : $((y \bar{\wedge} 1) \bar{\wedge} x) \bar{\wedge} 1$	$\bar{\sqsupset}$ : $y \bar{\wedge} 1$
$\sqsubset$ : $x$	$\subset$ : $y \bar{\wedge} (x \bar{\wedge} 1)$
$\bar{\sqsubset}$ : $(y \bar{\wedge} (x \bar{\wedge} 1)) \bar{\wedge} 1$	$\bar{\sqsubset}$ : $x \bar{\wedge} 1$
$\sqsupset$ : $y$	$\supset$ : $(y \bar{\wedge} 1) \bar{\wedge} x$
$\oplus$ : $(y \bar{\wedge} (x \bar{\wedge} 1)) \bar{\wedge} ((y \bar{\wedge} 1) \bar{\wedge} x)$	$\bar{\wedge}$ : $x \bar{\wedge} y$
$\vee$ : $(y \bar{\wedge} 1) \bar{\wedge} (x \bar{\wedge} 1)$	$\top$ : 1

5. (a)  $\sqsubset$ :  $x \bar{\sqsubset} x$ ;  $\wedge$ :  $(x \bar{\sqsubset} y) \bar{\sqsubset} y$ ;  $\bar{\supset}$ :  $y \bar{\sqsubset} x$ ;  $\sqsubset$ :  $x$ ;  $\bar{\sqsubset}$ :  $x \bar{\sqsubset} y$ ;  $\sqsupset$ :  $y$ ; the other 10 cannot be expressed. (b) With constants, however, all 16 are possible:

$\sqsubset$ : 0	$\bar{\vee}$ : $y \bar{\sqsubset} (x \bar{\sqsubset} 1)$
$\wedge$ : $(y \bar{\sqsubset} 1) \bar{\sqsubset} x$	$\equiv$ : $(y \bar{\sqsubset} x) \bar{\sqsubset} ((x \bar{\sqsubset} y) \bar{\sqsubset} 1)$
$\bar{\supset}$ : $y \bar{\sqsubset} x$	$\bar{\sqsupset}$ : $y \bar{\sqsubset} 1$
$\sqsubset$ : $x$	$\subset$ : $(x \bar{\sqsubset} y) \bar{\sqsubset} 1$
$\bar{\sqsubset}$ : $x \bar{\sqsubset} y$	$\bar{\sqsubset}$ : $x \bar{\sqsubset} 1$
$\sqsupset$ : $y$	$\supset$ : $(y \bar{\sqsubset} x) \bar{\sqsubset} 1$
$\oplus$ : $((y \bar{\sqsubset} x) \bar{\sqsubset} ((x \bar{\sqsubset} y) \bar{\sqsubset} 1)) \bar{\sqsubset} 1$	$\bar{\wedge}$ : $((y \bar{\sqsubset} 1) \bar{\sqsubset} x) \bar{\sqsubset} 1$
$\vee$ : $(y \bar{\sqsubset} (x \bar{\sqsubset} 1)) \bar{\sqsubset} 1$	$\top$ : 1

[B. A. Bernstein, *University of California Publications in Mathematics* 1 (1914), 87–96.]

6. (a)  $\perp, \wedge, \sqcup, \sqcap, \oplus, \vee, \equiv, \top$ . (b)  $\perp, \sqcup, \sqcap, \oplus, \equiv, \top$ . [Notice that all of these operators are associative. In fact, the stated identity implies the associative law in general: First we have (i)  $(x \circ y) \circ ((z \circ y) \circ w) = ((x \circ z) \circ (z \circ y)) \circ ((z \circ y) \circ w) = (x \circ z) \circ w$ , and similarly (ii)  $(x \circ (y \circ z)) \circ (y \circ w) = x \circ (z \circ w)$ . Furthermore (iii)  $(x \circ y) \circ (z \circ w) = (x \circ y) \circ ((z \circ y) \circ (y \circ w)) = (x \circ z) \circ (y \circ w)$  by (i). Thus  $(x \circ z) \circ w = (x \circ z) \circ ((z \circ z) \circ w) = (x \circ (z \circ z)) \circ (z \circ w) = x \circ (z \circ w)$  by (i), (iii), (ii). The free system generated by  $\{x_1, \dots, x_n\}$  has exactly  $n + 2^n n^2$  distinct elements, namely  $\{x_j \mid 1 \leq j \leq n\}$  and  $\{x_i \circ x_{j_1} \circ \dots \circ x_{j_r} \circ x_k \mid r \geq 0 \text{ and } 1 \leq i, k \leq n \text{ and } 1 \leq j_1 < \dots < j_r \leq n\}$ .]

7. Equivalently, we want the identity  $y \circ (x \circ y) = x$ , which holds only for  $\oplus$  and  $\equiv$ . [Jevons noticed this property of  $\oplus$  in *Pure Logic* §151, but he did not pursue the matter. We will investigate general systems of this nature, called “grotes,” in Section 7.2.3.]

8.  $(\{\perp, \wedge, \sqcup\}, S_0)$ ,  $(\{\top, \vee, \sqcap\}, S_1)$ ,  $(\{\sqcup, \sqcap\}, S_0 \cap S_1)$ ,  $(\{\oplus, \equiv, \bar{\sqcap}\}, S_2)$ ,  $(\{\bar{\sqcup}, \bar{\sqcap}\}, S_0 \cap S_2)$ ,  $(\{\bar{\sqcup}, \bar{\sqcap}\}, S_1 \cap S_2)$ , and  $(\{\bar{\sqcup}, \bar{\sqcap}\}, S_0 \cap S_1 \cap S_2)$ , where  $S_0 = \{\square \mid 0 \square 0 = 0\}$ ,  $S_1 = \{\square \mid 1 \square 1 = 1\}$ , and  $S_2 = \{\square \mid \bar{\square} \bar{\square} = \bar{\square}\}$ . Thus 92 of the 256 pairs are left-distributive. [This problem and those of exercise 6 were first treated by E. Schröder in §55 of his posthumously published *Vorlesungen über die Algebra der Logik* 2, 2 (1905). He expressed the answer by saying in essence that the respective truth tables  $(pqrs, wxyz)$  of  $(\circ, \square)$  must satisfy the relation  $((pq \vee rs) \wedge \bar{z}) \vee ((\bar{p}\bar{q} \vee \bar{r}\bar{s}) \wedge w) \vee ((p\bar{q} \vee r\bar{s}) \wedge ((w \equiv z) \vee (x \equiv y))) = 0$ .]

9. (a) False;  $(x \oplus y) \vee z = (x \vee z) \oplus (y \vee z) \oplus z$ . (b) True, because the identity obviously holds when  $z = 0$  and when  $z = 1$ .

10. The first stage of decomposition (16) yields the functions with truth tables  $g = 11001001$  and  $h = 11001001 \oplus 00001111 = 11000110$ ; and the process continues in a similar way, yielding  $1 + y + xz + w + wy + wx + wxz$  (modulo 2).

11. The stated term is present if and only if  $f(x_1, \dots, x_n)$  is true an odd number of times when  $x_1 = x_4 = x_5 = x_7 = x_9 = x_{10} = \dots = 0$ . (There are  $2^k$  such cases when we set all but  $k$  variables to zero.) In other words the multilinear representation can be expressed in a suggestive notation like

$$f(x, y, z) = (f_{000} + f_{00*}z + f_{0*0}y + f_{0**}yz + f_{*00}x + f_{*0*}xz + f_{**0}xy + f_{***}xyz) \bmod 2$$

illustrated here for  $n = 3$ , where  $f_{**0} = f(1, 1, 0) \oplus f(1, 0, 0) \oplus f(0, 1, 0) \oplus f(0, 0, 0)$ , etc.

12. (a) Substitute  $1 - w$  for  $\bar{w}$ , etc., in (20), getting  $1 - y - xz + 2xyz - w + wy + wx + wxz - 2wxyz$ . [Some authors have called this the “Zhegalkin polynomial”; but I. I. Zhegalkin himself always worked modulo 2.]

(b) The corresponding coefficients for an arbitrary  $n$ -ary function can be as large as  $2^{n-1}$  in absolute value (and this, by induction, is the maximum). For example, the integer multilinear representation of  $x_1 \oplus \dots \oplus x_n$  over the integers turns out to be  $e_1 - 2e_2 + 4e_3 - \dots + (-2)^{n-1}e_n$ , where  $e_k$  is the  $k$ th elementary symmetric function of  $\{x_1, \dots, x_n\}$ . The formula in the previous answer becomes

$$f(x, y, z) = f_{000} + f_{00*}z + f_{0*0}y + f_{0**}yz + f_{*00}x + f_{*0*}xz + f_{**0}xy + f_{***}xyz$$

over the integers, where we now have  $f_{**0} = f(1, 1, 0) - f(1, 0, 0) - f(0, 1, 0) + f(0, 0, 0)$ , etc. This expansion is a disguised form of the Hadamard transform, Eq. 4.6.4–(38).

(c) The polynomial is the sum of its minterms like  $x_1(1 - x_2)(1 - x_3)x_4$ . Each minterm is nonnegative for  $0 \leq x_1, \dots, x_n \leq 1$ , and the sum of all minterms is 1.

(d) Use induction on  $n$ , since  $f = x_n g + h - x_n g h$ .

13. In fact,  $F$  is precisely the integer multilinear representation (see exercise 12).

14. Let  $r_j = p_j/(1 - p_j)$ . We want  $f(0, 0, 0) = 0$  and  $f(1, 1, 1) = 1 \Leftrightarrow r_1 r_2 r_3 > 1$ ,  $f(0, 0, 1) = 0$  and  $f(1, 1, 0) = 1 \Leftrightarrow r_1 r_2 > r_3$ ,  $f(0, 1, 0) = 0$  and  $f(1, 0, 1) = 1 \Leftrightarrow r_1 r_3 > r_2$ ,  $f(0, 1, 1) = 0$  and  $f(1, 0, 0) = 1 \Leftrightarrow r_1 > r_2 r_3$ . So we get (a)  $\langle x_1 x_2 x_3 \rangle$ ; (b)  $x_1$ ; (c)  $\bar{x}_3$ .

15. Exercise 1.2.6–10 tells us that  $\binom{x}{k} \bmod 2 = [x \& k = k]$ . Hence, for example,  $\binom{x}{11} \equiv x_4 \wedge x_2 \wedge x_1$  (modulo 2) when  $x = (x_n \dots x_1)_2$ ; and we can obtain every term in a multilinear representation like (19) in this way. Moreover, we needn't work mod 2, because the interpolating polynomial  $\binom{x}{11} \binom{15-x}{4}$  represents  $x_4 \wedge x_2 \wedge x_1$  exactly.

16. Yes, or even by +, because different minterms can't be simultaneously true. (But we can't do that in ordinary disjunctive normal forms like (25). See exercise 35.)

17. The binary operation  $\bar{\wedge}$  is not associative, so an expression like  $x \bar{\wedge} y \bar{\wedge} z$  must be interpreted as a *ternary* operation. Quick's notation is fine if one understands NAND to be an  $n$ -ary operation, being careful to note that the NAND of a *single* variable  $x$  is  $\bar{x}$ .

18. If not, we could set  $u_1 \leftarrow \dots \leftarrow u_s \leftarrow 1$  and  $v_1 \leftarrow \dots \leftarrow v_t \leftarrow 0$ , making  $f$  both true and false. (And if we consider applying the distributive law (2) repeatedly to a DNF until it becomes a CNF, we find that the converse is also true: The disjunction  $v_1 \vee \dots \vee v_t$  is implied by  $f$  if and only if it has a literal in common with every implicant of  $f$ , if and only if it has a literal in common with every prime implicant of  $f$ , if and only if it has a literal in common with every implicant of some DNF for  $f$ .)

19. The maximal subcubes contained in 0010, 0011, 0101, 0110, 1000, 1001, 1010, and 1011 are 0\*10, 0101, \*01\*, and 10\*\*; so the answer is  $(w \vee \bar{y} \vee z) \wedge (w \vee \bar{x} \vee y \vee \bar{z}) \wedge (x \vee \bar{y}) \wedge (\bar{w} \vee x)$ . (This CNF is also shortest.)

20. True. The corresponding maximal subcube is contained in some maximal subcubes  $f'$  and  $g'$ , and their intersection can't be larger. (This observation is due to Samson and Mills, whose paper is cited in answer 31 below.)

21. By Boole's law (20), we see that an  $n$ -ary function  $f$  is monotone if and only if its  $(n - 1)$ -ary projections  $g$  and  $h$  are monotone and satisfy  $g \leq h$ . Therefore

$$f = (g \wedge \bar{x}_n) \vee (h \wedge x_n) = (g \wedge \bar{x}_n) \vee (g \wedge x_n) \vee (h \wedge x_n) = g \vee (h \wedge x_n),$$

so we can do without complementation. The constants 0 and 1 disappear unless the function is identically constant. Conversely, any expression built up from  $\wedge$  and  $\vee$  is obviously monotone.

*Note on terminology:* Strictly speaking, we should say “monotone nondecreasing” instead of simply “monotone,” if we want to preserve the language of classical mathematics, because a decreasing function of a real variable is also said to be monotonic. (See, for example, the “run test” in Section 3.3.2G.) But “nondecreasing” is quite a mouthful; so researchers who work extensively on Boolean functions have almost unanimously opted to assume that “monotone” automatically implies nondecreasing, in a Boolean context. Similarly, the mathematical term “positive function” normally refers to a function whose value exceeds zero; but authors who write about “positive Boolean functions” are referring to the functions that we are calling monotone. Since a monotone function is order-preserving, some authors have adopted the term *isotone*; but that word has already been coopted by physicists, chemists, and musicologists.

A Boolean function like  $\bar{x} \vee y$ , which becomes monotone if some subset of its variables is complemented, is called *unate*. Theorem Q obviously applies to unate functions.

22. Both  $g$  and  $g \oplus h$  must be monotone, and  $g(x) \wedge h(x) = 0$ .

23.  $x \wedge (v \vee y) \wedge (v \vee z) \wedge (w \vee z)$ . (Corollary Q applies also to *conjunctive* prime forms of monotone functions. Therefore, to solve any problem of this kind, we need only



apply the distributive law (2) until no  $\wedge$  occurs within a  $\vee$ , then remove any clause that contains all the variables of another.)

**24.** By induction on  $k$ , the similar tree with  $\vee$  at the root gives a function with  $2^{2^{\lceil k/2 \rceil} - 1}$  prime implicants of length  $2^{\lfloor k/2 \rfloor}$ , while the tree with  $\wedge$  gives  $4^{2^{\lfloor k/2 \rfloor} - 1}$  of length  $2^{\lceil k/2 \rceil}$ . When  $k = 6$ , for example, the  $4^7 = 2^{14}$  prime implicants in the  $\wedge$  case have the form

$$\begin{aligned} & x_{(0t_00t_{00}0t_{000})_2} \wedge x_{(0t_00t_{00}1t_{001})_2} \wedge x_{(0t_01t_{01}0t_{010})_2} \wedge x_{(0t_01t_{01}1t_{011})_2} \\ & \wedge x_{(1t_10t_{10}0t_{100})_2} \wedge x_{(1t_10t_{10}1t_{101})_2} \wedge x_{(1t_11t_{11}0t_{110})_2} \wedge x_{(1t_11t_{11}1t_{111})_2}, \end{aligned}$$

with the  $t$ 's either 0 or 1. [For further information about such Boolean functions, see D. E. Knuth and R. W. Moore, *Artificial Intelligence* **6** (1975), 293–326; V. Gurvich and L. Khachiyan, *Discrete Mathematics* **169** (1957), 245–248.]

**25.** Let  $a_n$  be the answer. Then  $a_2 = a_3 = 2$ ,  $a_4 = 3$ , and  $a_n = a_{n-2} + a_{n-3}$  for  $n > 4$ , because the prime implicants when  $n > 4$  are either  $p_{n-2} \wedge x_{n-1}$  or  $p_{n-3} \wedge x_{n-2} \wedge x_n$  for some prime implicant  $p_k$  in the  $k$ -variable case. (Is there a simple formula for the shortest *shellable* list of implicants, in the sense of exercise 35?)

**26.** (a) Let  $x_j = [j \in J]$ . Then  $f(x) = 0$  and  $g(x) = 1$ . (This fact was exercise 18.)

(b) Suppose, for example, that  $k \in J \in \mathcal{G}$  and  $k \notin \bigcup_{I \in \mathcal{F}} I$ , and assume that test (a) has been passed. Let  $x_j = [j \in J \text{ and } j \neq k]$ . Then  $f(x) = 1$ ; and  $g(x) = 0$ , because every  $J' \in \mathcal{G}$  with  $J' \neq J$  contains an element  $\notin J$ .

(c) Again assume that condition (a) has been ruled out. If, say,  $|I| > |\mathcal{G}|$ , let  $x_j = [j \text{ is the smallest element of } I \cup J, \text{ for some } J \in \mathcal{G}]$ . Then  $f(x) = 0$ ,  $g(x) = 1$ .

(d) Now we assume that  $\bigcup_{I \in \mathcal{F}} I = \bigcup_{J \in \mathcal{G}} J$ . Each  $I \in \mathcal{F}$  stands for  $2^{n-|I|}$  vectors where  $f(x) = 0$ ; similarly, each  $J \in \mathcal{G}$  stands for  $2^{n-|J|}$  vectors where  $g(x) = 1$ . If the sum  $s$  is less than  $2^n$ , we can compute  $s = s_0 + s_1$ , where  $s_0$  counts the contributions to  $s$  when  $x_n = 0$ . If  $s_0 < 2^{n-1}$ , set  $x_n \leftarrow 0$ ; otherwise  $s_1 < 2^{n-1}$ , so we set  $x_n \leftarrow 1$ . Then we set  $n \leftarrow n - 1$ ; eventually all  $x_j$  are known, and  $f(x) = 1$ ,  $g(x) = 0$ .

**27.** Let  $m = \min(\{I \mid I \in \mathcal{F}\} \cup \{J \mid J \in \mathcal{G}\})$  be the length of the shortest prime clause or implicant. Then  $N \cdot 2^{n-m} \geq \sum_{I \in \mathcal{F}} 2^{n-|I|} + \sum_{J \in \mathcal{G}} 2^{n-|J|} \geq 2^n$ ; so we have  $m \leq \lg N$ . If, say,  $|I| = m$ , some variable  $x_k$  appears in at least  $1/m$  of the members  $J \in \mathcal{G}$ , because each  $J$  intersects  $I$ . This observation proves the hint.

Now let  $A(0) = A(1) = 1$  and  $A(v) = 1 + A(v-1) + A(\lfloor \rho v \rfloor)$  for  $v > 1$ . Then  $A(|\mathcal{F}| |\mathcal{G}|)$  is an upper bound on the number of recursive calls (the number of times X1 is performed). Letting  $B(v) = A(v) + 1$ , we have  $B(v) = B(v-1) + B(\lfloor \rho v \rfloor)$  for  $v > 1$ , hence  $B(v) \leq B(v-k) + kB(\lfloor \rho v \rfloor)$  for  $v > k$ . Taking  $k = v - \lfloor \rho v \rfloor$  shows that  $B(v) \leq ((1-\rho)v + 2)B(\lfloor \rho v \rfloor)$ ; hence  $B(v) = O((1-\rho)v + 2)^t$  when  $\rho^t v \leq 1$ , namely when  $t \geq \ln v / \ln(1/\rho) = \Theta((\log v)(\log N))$ . Consequently  $A(|\mathcal{F}| |\mathcal{G}|) \leq A(N^2/4) = N^{O(\log N)^2}$ .

In practice the algorithm will run much faster than the pessimistic bounds just derived. Since the prime clauses of a function are the prime implicants of its dual, this problem is essentially the same as verifying that one given DNF is the dual of another. Moreover, if we start with  $f(x) = 0$  and repeatedly find minimal  $x$ 's where  $f(x) = g(\bar{x}) = 0$ , we can “grow”  $f$  until we’ve obtained the dual of  $g$ .

The ideas presented here are due to M. L. Fredman and L. Khachiyan, *J. Algorithms* **21** (1996), 618–628, who also presented refinements that reduce the running time to  $N^{O(\log N / \log \log N)}$ . No polynomial-time algorithm is known; yet the problem is unlikely to be NP-complete, because we can solve it in less-than-exponential time.

**28.** This result is obvious once understood, but the notations and terminology can make it confusing; so let’s consider a concrete example: If, say,  $y_1 = y_4 = y_6 = 1$  and

the other  $y_k$  are zero, the function  $g$  is true if and only if the prime implicants  $p_1$ ,  $p_4$ , and  $p_6$  cover all the places where  $f$  is true. Thus we see that there is a one-to-one correspondence between every implicant of  $g$  and every DNF for  $f$  that contains only prime implicants  $p_j$ . In this correspondence, the prime implicants of  $g$  correspond to the “irredundant” DNFs in which no  $p_j$  can be left out.

Numerous refinements of this principle have been discussed by R. B. Cutler and S. Muroga, *IEEE Transactions* **C-36** (1987), 277–292.

- 29. B1.** [Initialize.] Set  $k \leftarrow k' \leftarrow 0$ . (Similar methods are discussed in exercise 5–19.)  
**B2.** [Find a zero.] Increase  $k$  zero or more times, until either  $k = m$  (terminate) or  $v_k \& 2^j = 0$ .  
**B3.** [Make  $k' > k$ .] If  $k' \leq k$ , set  $k' \leftarrow k + 1$ .  
**B4.** [Advance  $k'$ .] Increase  $k'$  zero or more times, until either  $k' = m$  (terminate) or  $v_{k'} \geq v_k + 2^j$ .  
**B5.** [Skip past a big mismatch.] If  $v_k \oplus v_{k'} \geq 2^{j+1}$ , set  $k \leftarrow k'$  and return to B2.  
**B6.** [Record a match.] If  $v_{k'} = v_k + 2^j$ , output  $(k, k')$ .  
**B7.** [Advance  $k$ .] Set  $k \leftarrow k + 1$  and return to B2. ■

(Steps B3 and B5 are optional, but recommended.)

**30.** The following algorithm keeps variable-length, sorted lists in a stack  $S$  whose size will never exceed  $2m + n$ . When the topmost entry of the stack is  $S_t = s$ , the topmost list is the ordered set  $S_s < S_{s+1} < \dots < S_{t-1}$ . Tag bits are maintained in another stack  $T$ , having the same size as  $S$  (after the initialization step).

- P1.** [Initialize.] Set  $T_k \leftarrow 0$  for  $0 \leq k < m$ . Then for  $0 \leq j < m$ , apply the  $j$ -buddy scan algorithm of exercise 29, and set  $T_k \leftarrow T_k + 2^j$ ,  $T_{k'} \leftarrow T_{k'} + 2^j$  for all pairs  $(k, k')$  found. Then set  $s \leftarrow t \leftarrow 0$  and repeat the following operations until  $s = m$ : If  $T_s = 0$ , output the subcube  $(0, v_s)$  and set  $s \leftarrow s + 1$ ; otherwise set  $S_t \leftarrow v_s$ ,  $T_t \leftarrow T_s$ ,  $t \leftarrow t + 1$ ,  $s \leftarrow s + 1$ . Finally set  $A \leftarrow 0$  and  $S_t \leftarrow 0$ .  
**P2.** [Advance  $A$ .] (At this point stack  $S$  contains  $\nu(A) + 1$  lists of subcubes. Namely, if  $A = 2^{e_1} + \dots + 2^{e_r}$  with  $e_1 > \dots > e_r \geq 0$ , the stack contains the  $b$ -values of all subcubes  $(a, b) \subseteq V$  whose  $a$ -values are respectively  $0, 2^{e_1}, 2^{e_1} + 2^{e_2}, \dots, A$ , except that subcubes whose tags are zero do not appear. All of these lists are nonempty, except possibly the last. We will now increase  $A$  to the next relevant value.) Set  $j \leftarrow 0$ . If  $S_t = t$  (that is, if the topmost list is empty), increase  $j$  zero or more times until  $j \geq n$  or  $A \& 2^j \neq 0$ . Then while  $j < n$  and  $A \& 2^j \neq 0$ , set  $t \leftarrow S_t - 1$ ,  $A \leftarrow A - 2^j$ , and  $j \leftarrow j + 1$ . Terminate the algorithm if  $j \geq n$ ; otherwise set  $A \leftarrow A + 2^j$ .  
**P3.** [Generate list  $A$ .] Set  $r \leftarrow t$ ,  $s \leftarrow s_t$ , and apply the  $j$ -buddy scan algorithm of exercise 29 to the  $r - s$  numbers  $S_s < \dots < S_{r-1}$ . For all pairs  $(k, k')$  found, set  $x \leftarrow (T_k \& T_{k'}) - 2^j$ ; and if  $x = 0$ , output the subcube  $(A, S_k)$ , otherwise set  $t \leftarrow t + 1$ ,  $S_t \leftarrow S_k$ ,  $T_t \leftarrow x$ . Finally set  $t \leftarrow t + 1$ ,  $S_t \leftarrow r + 1$ , and go back to step P2. ■

This algorithm is based in part on ideas of Eugenio Morreale [*IEEE Trans.* **EC-16** (1967), 611–620; *Proc. ACM Nat. Conf.* **23** (1968), 355–365]. The running time is essentially proportional to  $mn$  (for step P1) plus the total number of subcubes contained in  $V$ . If  $m \leq 2^n(1 - \epsilon)$ , and if  $V$  is chosen at random with size  $m$ , exercise 34 shows that the average total number of subcubes is at most  $O(\log \log n / \log \log \log n)$  times the average number of maximal subcubes; hence the average running time in most cases

will be nearly proportional to the average amount of output produced. On the other hand, exercises 32 and 114 show that the amount of output might be huge.

**31.** (a) Let  $c = c_{n-1} \dots c_0$ ,  $c' = c'_{n-1} \dots c'_0$ ,  $c'' = c''_{n-1} \dots c''_0$ . There must be some  $j$  with  $c_j \neq *$  and  $c_j \neq c''_j$ ; otherwise  $c'' \subseteq c$ . Similarly there must be some  $k$  with  $c'_k \neq *$  and  $c'_k \neq c''_k$ . If  $j \neq k$ , there would be a point  $x_{n-1} \dots x_0 \in c''$  that is in neither  $c$  nor  $c'$ , because we could let  $x_j = \bar{c}_j$  and  $x_k = \bar{c}'_k$ . Hence  $j = k$ , and the value of  $j$  is uniquely determined. Furthermore it's easy to see that  $c'_j = \bar{c}_j$ . And if  $i \neq j$ , we have either  $c_i = *$  or  $c_i = c''_i$ , and either  $c'_i = *$  or  $c'_i = c''_i$ .

(b) This statement is an obvious consequence of (a).

(c) First we prove that the parenthesized remark in step E2 is true whenever that step is encountered. It's clearly true when  $j = 0$ . Otherwise, let  $c \subseteq V$  be a  $j$ -cube, and suppose  $c = c_0 \sqcup c_1$  where  $c_0$  and  $c_1$  are  $(j-1)$ -cubes. On the preceding execution of step E2 we had  $c_0 \subseteq c'_0 \in C$  and  $c_1 \subseteq c'_1 \in C$  for some  $c'_0$  and  $c'_1$ ; hence either  $c \subseteq c'_0 \sqcup c'_1$  or  $c \subseteq c'_0$  or  $c \subseteq c'_1$ . In each case,  $c$  is now contained in some element of  $C$ .

Secondly, we prove that the outputs in step E3 are precisely the maximal  $j$ -cubes contained in  $V$ : Let  $c \subseteq V$  be any  $k$ -cube. If  $c$  is maximal, then  $c$  will be in  $C$  when we reach step E3 with  $j = k$ , and it will be output. If  $c$  isn't maximal, it has a buddy  $c' \subseteq V$ , which is a  $k$ -cube contained in some subcube  $c'' \in C$  when we reach E3. Since  $c \not\subseteq c''$ , the consensus  $c \sqcup c''$  will be a  $(j+1)$ -cube of  $C'$ , and  $c$  will not be output.

*References:* The notion of consensus was first defined by Archie Blake in his Ph.D. dissertation at the University of Chicago (1937); see *J. Symbolic Logic* **3** (1938), 93, 112–113. It was independently rediscovered by Edward W. Samson and Burton E. Mills [Air Force Cambridge Research Center Tech. Report 54-21 (Cambridge, Mass.: April 1954), 54 pp.] and by W. V. Quine [AMM **62** (1955), 627–631]. The operation is also sometimes called the *resolvent*, since J. A. Robinson used it in a more general form (but with respect to clauses rather than implicants) as the basis of his “resolution principle” for theorem proving [JACM **12** (1965), 23–41]. Algorithm E is due to Ann C. Ewing, J. Paul Roth, and Eric G. Wagner, *AIEE Transactions*, Part 1, **80** (1961), 450–458.

**32.** (a) Change the definition of  $\sqcup$  in exercise 31 to the following associative and commutative operation on the four symbols  $A = \{0, 1, *, \bullet\}$ , for all  $a \in A$  and  $x \in \{0, 1\}$ :

$$* \sqcup a = a \sqcup * = a, \quad \bullet \sqcup a = a \sqcup \bullet = x \sqcup \bar{x} = \bullet, \quad \text{and} \quad x \sqcup x = x.$$

Also let  $h(0) = 0$ ,  $h(1) = 1$ ,  $h(*) = *$ , and  $h(\bullet) = *$ . Then  $c = h(c_1 \sqcup \dots \sqcup c_m)$ , computed componentwise, is the generalized consensus if and only if this subcube is contained in  $c_1 \cup \dots \cup c_m$ . [See P. Tison, *IEEE Transactions EC-16* (1967), 446–456.]

(b) For example, let  $c_j = *^{j-1}1*^{m-j}1^{j-1}0*^{m-j}$ . [The final component is superfluous. All solutions have been characterized by R. H. Sloan, B. Szörényi, and G. Turán, in *Electronic Colloquium on Computational Complexity* (2005), Report 23.]

(c) By (a), every prime implicant corresponds uniquely to the subset of implicants that it “meets.” [A. K. Chandra and G. Markowsky, *Discrete Math.* **24** (1978), 7–11.]

(d) For example,  $(y_1 \wedge \bar{x}_1) \vee (y_2 \wedge x_1 \wedge \bar{x}_2) \vee \dots \vee (y_m \wedge x_1 \wedge \dots \wedge x_{m-1} \wedge \bar{x}_m)$  as in (b). [J.-M. Laborde, *Discrete Math.* **32** (1980), 209–212.]

**33.** (a)  $\binom{2^n - 2^{n-k}}{m - 2^{n-k}} / \binom{2^n}{m}$ . (b) We must exclude the cases when  $x_1 \wedge \dots \wedge x_{j-1} \wedge \bar{x}_j \wedge x_{j+1} \wedge \dots \wedge x_k$  is also an implicant. By the inclusion-exclusion principle, the answer is

$$\sum_l \binom{k}{l} (-1)^l \binom{2^n - (l+1)2^{n-k}}{m - (l+1)2^{n-k}} / \binom{2^n}{m};$$

it simplifies to  $\binom{2^n - n - 1}{m-1} / \binom{2^n}{m}$  when  $k = n$ .

**34.** (a) We have  $c(m, n) = \sum c_j(m, n)$ , where  $c_j(m, n) = 2^{n-j} \binom{n}{j} \binom{2^n - 2^j}{m - 2^j} / \binom{2^n}{m}$  is the average number of implicants with  $n - j$  literals (the average number of subcubes of dimension  $j$  in the terminology of exercise 30). Clearly  $c_0(m, n) = m$ , and

$$c_1(m, n) = \frac{nm(m-1)}{2(2^n-1)} < \frac{mn}{2} \left( \frac{m}{2^n} \right) \leq \frac{1}{2}m;$$

similarly  $c_j(m, n) < m/(2^j! n^{2^j-1-j})$ . Also  $p(m, n) = \sum_j p_j(m, n)$ , where we have

$$\begin{aligned} p_0(m, n) &= \binom{2^n - n - 1}{m - 1} / \binom{2^n}{m} = m \frac{(2^n - n - 1)^{m-1}}{(2^n - 1)^{m-1}} \geq m \frac{(2^n - n - m)^{m-1}}{(2^n - m)^{m-1}} \\ &> m \left( \frac{1 - n}{2^n - m} \right)^m > m \left( 1 - \frac{n}{2^n - 2^n/n} \right)^{2^n/n} = m \exp \left( \frac{2^n}{n} \ln \left( 1 - \frac{n^2}{2^n(n-1)} \right) \right). \end{aligned}$$

(b) Notice that  $t = \lfloor \lg \lg n - \lg \lg(2^n/m) + \lg(4/3) \rfloor \leq \lg \lg n + O(1)$  is quite small. We will repeatedly use the fact that  $\binom{2^n - j \cdot 2^t}{m - j \cdot 2^t} / \binom{2^n}{m} < \alpha_{mn}^j$ , and indeed that

$$\binom{2^n - j \cdot 2^t}{m - j \cdot 2^t} / \binom{2^n}{m} = \alpha_{mn}^j (1 + O(j^2 2^{2t}/m))$$

is an extremely good approximation when  $j$  isn't too large. To establish the hint, note that  $\sum_{j < t} c_j(m, n)/c_t(m, n) = O(tc_{j-1}(m, n)/c_j(m, n)) = O(t^2/(n\sqrt{\alpha_{mn}})) = O((\log \log n)^2/n^{1/3})$ ; and  $c_{t+j}(m, n)/c_t(m, n) = O((n/(2t))^j \alpha_{mn}^{2^j-1})$ . Consequently we have  $c(m, n)/c_t(m, n) \approx 1 + \frac{1}{2} \left( \frac{n-t}{t+1} \right) \alpha_{mn}$ , where the second term dominates when  $\alpha_{mn}$  is in the upper part of its range. Furthermore

$$\sum_l \binom{n-t}{l} (-1)^l \alpha_{mn}^l \left( 1 + O \left( \frac{l^2 2^{2t}}{m} \right) \right) = (1 - \alpha_{mn})^{n-t} + O(n^2 \alpha_{mn}^2 (1 + \alpha_{mn})^n 2^{2t}/m)$$

has an exponentially small error term, because  $(1 + \alpha_{mn})^n = O(e^{n^{1/3}}) \ll m$ . Therefore  $p(m, n)/c_t(m, n)$  is asymptotically  $e^{-n\alpha_{mn}} + \frac{1}{2} \left( \frac{n-t}{t+1} \right) \alpha_{mn} e^{-n\alpha_{mn}^2}$ .

(c) Here  $\alpha_{mn} = 2^{-2^t} \approx n^{-1} \ln(t/\ln t)$ ; so  $c(m, n)/c_t(m, n) = 1 + O(t^{-1} \log t)$ ,  $p(m, n)/c_t(m, n) = t^{-1} \ln t + \frac{1}{2} t^{-1} \ln t + O(t^{-1} \log \log t)$ . We conclude that, in this case,

$$\frac{c(m, n)}{p(m, n)} = \frac{2}{3} \frac{\lg \lg n}{\lg \lg \lg n} \left( 1 + O \left( \frac{\log \log \log \log n}{\log \log \log n} \right) \right).$$

(d) If  $n\alpha_{mn} \leq \ln t - \ln \ln t$ , we have  $p(m, n)/c(m, n) \geq p_t(m, n)/c(m, n) \geq t^{-1} \ln t + O(t^{-1} \log t)^2$ . On the other hand if  $n\alpha_{mn} \geq \ln t - \ln \ln t$ , we have  $p(m, n)/c(m, n) \geq p_{t+1}(m, n)/c(m, n) \geq \frac{1}{2} t^{-1} \ln t + O(t^{-1} \log \log t)$ .

[The mean and variance of  $c(m, n)$  and the mean of  $p(m, n)$  were first studied by F. Mileto and G. Putzolu, *IEEE Trans.* **EC-13** (1964), 87–92; *JACM* **12** (1965), 364–375. Detailed asymptotic information about implicants, prime implicants, and irredundant DNFs of random Boolean functions, when each value  $f(x_1, \dots, x_n)$  is independently equal to 1 with probability  $p(n)$ , has been derived by Karl Weber, *Elektronische Informationsverarbeitung und Kybernetik* **19** (1983), 365–374, 449–458, 529–534.]

**35.** (a) By rearranging coordinates we can assume that the  $p$ th subcube is  $0^k 1^u *^v$ , so that  $B_p = 0^k 1^p 0^v$  and  $S_p = 1^k 0^{u+v}$ . Then all points of  $*^k 1^u *^v$  are still covered, by induction on  $p$ , because all points of  $*^{j-1} 1 *^{k-j} 1^u *^v$  have been covered for  $1 \leq j \leq k$ .

(b) The  $j$ th and  $k$ th subcubes differ in every coordinate position where  $B_j$  &  $S_k$  is nonzero. On the other hand if  $B_j$  &  $S_k$  is zero, the point  $\bar{S}_k$  of subcube  $k$  lies in a previous subcube, by (a), because we have  $\bar{S}_k \supseteq B_j$ .

(c) From the list 1100, 1011, 0011 (with the bits of each  $S_k$  underlined) we obtain the orthogonal DNF  $(x_1 \wedge x_2) \vee (x_1 \wedge \bar{x}_2 \wedge x_3 \wedge x_4) \vee (\bar{x}_1 \wedge x_3 \wedge x_4)$ .

(d) (01100, 00110, 00011, 11010, 11000) is one of the eight solutions.

(e) (001100, 011000, 000110, 110010, 110000, 010011, 000011) is a symmetrical solution. And there are many more possibilities; for example, 42 permutations of the bit codes {110000, 011000, 001100, 000110, 000011, 110010, 011010} are shellings.

[The concept of a shelling for monotone Boolean functions was introduced by Michael O. Ball and J. Scott Provan, *Operations Research* **36** (1988), 703–715, who discussed many significant applications.]

**36.** If  $j < k$  we have  $B_j = \alpha 1 \beta$  and  $B_k = \alpha 0 \gamma$  for some strings  $\alpha, \beta, \gamma$ . Form the sequence  $x_0 = \alpha 1 \gamma$ ,  $x_1 = x'_0, \dots, x_l = x'_{l-1}$ , where  $x_l = \alpha 0 0^{|\gamma|}$ . We have  $f(x_0) = 1$  since  $x_0 \supseteq B_k$ , but  $f(x_l) = 0$  since  $x_l \subseteq B'_j$ . So the string  $x_i$ , where  $f(x_i) = 1$  and  $f(x_{i+1}) = \dots = f(x_l) = 0$ , is in  $B$ . It precedes  $B_k$  and proves that  $B_j$  &  $S_k \supseteq 0^{|\alpha|} 1 0^{|\beta|}$ .

[This construction and parts of exercise 35 are due to E. Boros, Y. Crama, O. Ekin, P. L. Hammer, T. Ibaraki, and A. Kogan, *SIAM J. Discrete Math.* **13** (2000), 212–226.]

**37.** The shelling order (000011, 001101, 001100, 110101, 110100, 110001, 110000) generalizes to all  $n$ . There also are interesting solutions not based on shelling, like the cyclically symmetrical (110000, 110000, 001100, 001110, 000011, 100011, 111111).

For the lower bound, assign the weight  $w_x = -\prod_{j=1}^n (x_{2j-1} + x_{2j} - 3x_{2j-1}x_{2j})$  to each point  $x$ , and notice that the sum of  $w_x$  over all  $x$  in any subcube is 0 or  $\pm 1$ . (It suffices to verify this curious fact for each of the nine possible subcubes when  $n = 1$ .) Now choose a set of disjoint subcubes that cover the set  $F = \{x \mid f(x) = 1\}$ ; we have

$$\sum_{C \text{ chosen}} 1 \geq \sum_{C \text{ chosen}} \sum_{x \in C} w_x = \sum_{x \in F} \sum_{C \text{ chosen}} [x \in C] = \sum_{x \in F} w_x.$$

There are  $\binom{n}{k} 2^{n-k}$  vectors  $x$  with exactly  $k$  pairs  $x_{2j-1}x_{2j} = 1$  and nonzero weight. Their weight is  $(-1)^{k-1}$ , and they lie in  $F$  except when  $k = 0$ . Hence  $\sum_{x \in F} w_x = \sum_{k>0} \binom{n}{k} 2^k (-1)^{k-1} = 2^n - (2-1)^n$ . [See M. O. Ball and G. L. Nemhauser, *Mathematics of Operations Research* **4** (1979), 132–143.]

**38.** Certainly not; a DNF is satisfiable if and only if it has at least one implicant. The hard problem for a DNF is to decide whether or not it is a *tautology* (always true).

**39.** Associate variables  $y_1, \dots, y_N$  with each internal node in preorder, so that every tree node corresponds to exactly one variable of  $F$ . For each internal node  $y$ , with children  $(l, r)$  and labeled with the binary operator  $\circ$ , construct four 3CNF clauses  $c_{00} \wedge c_{01} \wedge c_{10} \wedge c_{11}$ , where

$$c_{pq} = (y^{\bar{p}\bar{q}N} \vee l^{pN} \vee r^{qN})$$

and  $N$  denotes complementation (so that  $x^{0N} = x$  and  $x^{1N} = \bar{x}$ ). These clauses state in effect that  $y = l \circ r$ ; for example, if  $\circ$  is  $\wedge$ , the four clauses are  $(\bar{y} \vee l \vee r) \wedge (\bar{y} \vee l \vee \bar{r}) \wedge (\bar{y} \vee \bar{l} \vee r) \wedge (y \vee \bar{l} \vee \bar{r})$ . Finally, add one more clause,  $(y_1 \vee y_1 \vee y_1)$ , to force  $F = 1$ .

**40.** Following the hint,  $A$  says ' $u < v$  or  $v < u$ ' and  $B$  says ' $u < v$  and  $v < w \Rightarrow u < w$ '. So  $A \wedge B$  says that there's a linear ordering of the vertices,  $u_1 < u_2 < \dots < u_n$ . (There are  $n!$  ways to satisfy  $A \wedge B$ .) Now  $C$  says that  $q_{uvv}$  is equivalent to  $u < w < v$ ; so  $D$  says that  $u$  and  $v$  are not consecutive in the ordering, when  $u \dashv v$ . Thus  $A \wedge B \wedge C \wedge D$

is satisfiable if and only if there is a linear ordering in which all nonadjacent vertices are nonconsecutive (that is, in which all consecutive vertices are adjacent).

41. Solution 0: ‘ $[m \leq n]$ ’ is such a formula, but it is not in the spirit of this exercise.

Solution 1: Let  $x_{jk}$  mean that pigeon  $j$  occupies hole  $k$ . Then the clauses are  $(x_{j1} \vee \dots \vee x_{jn})$  for  $1 \leq j \leq m$  and  $(\bar{x}_{ik} \vee \bar{x}_{jk})$  for  $1 \leq i < j \leq m$  and  $1 \leq k \leq n$ . [See S. A. Cook and R. A. Reckhow, *J. Symbolic Logic* **44** (1979), 36–50; A. Haken, *Theoretical Comp. Sci.* **39** (1985), 297–308.]

Solution 2: Assume that  $n = 2^t$  and let pigeon  $j$  occupy hole  $(x_{j1} \dots x_{jt})_2$ . The clauses  $((x_{i1} \oplus x_{j1}) \vee \dots \vee (x_{it} \oplus x_{jt}))$  for  $1 \leq i < j \leq m$  can be put into the CNF form  $(y_{ij1} \vee \dots \vee y_{ijt})$  as in exercise 39, by introducing auxiliary clauses  $(\bar{y}_{ijk} \vee x_{ik} \vee x_{jk}) \wedge (y_{ijk} \vee x_{ik} \vee \bar{x}_{jk}) \wedge (\bar{y}_{ijk} \vee \bar{x}_{ik} \vee \bar{x}_{jk})$ . If  $n$  is not a power of 2,  $O(m \log n)$  additional clauses of size  $O(\log n)$  will rule out inappropriate values. The total size of this CNF is  $\Theta(m^2 \log n)$ , compared to  $\Theta(m^2 n)$  in Solution 1.

42.  $(\bar{x} \vee y) \wedge (\bar{y} \vee z) \wedge (\bar{z} \vee x) \wedge (\bar{y} \vee \bar{z}) \wedge (z \vee z)$ .

43. Probably not, because every 3SAT problem can be converted to this form. For example, the clause  $(x_1 \vee x_2 \vee \bar{x}_3)$  can be replaced by  $(x_1 \vee \bar{y} \vee \bar{x}_3) \wedge (\bar{y} \vee \bar{x}_2) \wedge (y \vee x_2)$ , where  $y$  is a new variable (essentially equivalent to  $\bar{x}_2$ ).

44. Suppose  $f(x) = f(y) = 1$  implies  $f(x \& y) = 1$  and also that, say,  $c = x_1 \vee x_2 \vee \bar{x}_3 \vee \bar{x}_4$  is a prime clause of  $f$ . Then  $c' = \bar{x}_1 \vee x_2 \vee \bar{x}_3 \vee \bar{x}_4$  is *not* a clause; otherwise  $c \wedge c' = x_2 \vee \bar{x}_3 \vee \bar{x}_4$  would also be a clause, contradicting primality. So there’s a vector  $y$  with  $f(y) = 1$  and  $y_1 = 1, y_2 = 0, y_3 = y_4 = 1$ . Similarly, there’s a  $z$  with  $f(z) = 1$  and  $z_1 = 0, z_2 = 1, z_3 = z_4 = 1$ . But then  $f(y \& z) = 1$ , and  $c$  isn’t a clause. The same argument works for a clause  $c$  that has a different number of literals, as long as at least two of the literals aren’t complemented.

45. (a) A Horn function  $f(x_1, \dots, x_n)$  is improper if and only if it is unequal to the proper Horn function  $g(x_1, \dots, x_n) = f(x_1, \dots, x_n) \vee (x_1 \wedge \dots \wedge x_n)$ . So  $f \leftrightarrow g$  is a one-to-one correspondence between improper and proper Horn functions. (b) If  $f$  is monotone, its complement  $\bar{f}$  is either identically 1 or an improper Horn function.

46. Algorithm C puts 88 pairs  $xy$  in the core: When  $x = a, b, c, 0$ , or  $1$ , the following character  $y$  can be anything but  $()$ . When  $x = (, *, /, +, -$ , we can have  $y = (, a, b, c, 0, 1$ ; also  $y = -$  when  $x = (, +$ , or  $-$ . Finally, the legitimate pairs beginning with  $x = )$  are  $)+, )-, )*, )/, ))$ .

47. The order in which Algorithm C brings vertices into the core is a topological sort, since all predecessors of  $k$  are asserted before the algorithm sets  $\text{TRUTH}(x_k) \leftarrow 1$ . But Algorithm 2.2.3T uses a queue instead of a stack, so the ordering it actually produces is usually different from that of Algorithm C.

48. Let  $\perp$  be a new variable, and change every improper Horn clause to a proper one by ORing in this new variable. (For example, ‘ $\bar{w} \vee \bar{y}$ ’ becomes ‘ $\bar{w} \vee \bar{y} \vee \perp$ ’, namely ‘ $w \wedge y \Rightarrow \perp$ ’; proper Horn clauses stay unchanged.) Then apply Algorithm C. The original clauses are unsatisfiable if and only if  $\perp$  is in the core of the new clauses. The algorithm can therefore be terminated as soon as it is about to set  $\text{TRUTH}(\perp) \leftarrow 1$ .

(J. H. Quick thought of another solution: We could apply Algorithm C to the function  $g$  constructed in the answer to exercise 57(a), because  $f$  is unsatisfiable if and only if *every* variable  $x_j$  is in the core of  $g$ . However, improper clauses of  $f$  such as  $\bar{w} \vee \bar{y}$  become many different proper clauses  $(\bar{w} \vee \bar{y} \vee z) \wedge (\bar{w} \vee \bar{y} \vee x) \wedge (\bar{w} \vee \bar{y} \vee v) \wedge (\bar{w} \vee \bar{y} \vee u) \wedge \dots$  of  $g$ , one for each variable not in the original clause. So Quick’s suggestion, which might sound elegant at first blush, could increase the number of clauses by a factor of  $\Omega(n)$ .

Let  $f = f_0 \wedge f_1$  be the conjunction of the original clauses, where  $f_0$  is the conjunction of the improper ones and  $f_1$  is the conjunction of the proper ones. Adding the new variable  $\perp$ , as above, changes  $f$  to  $(f_0 \vee \perp) \wedge f_1$ , which is proper and has the same number of clauses as  $f$ .)

49. See Gabriel Istrate, *Random Structures & Algorithms* **20** (2002), 483–506.

50. If vertex  $v$  is marked A, introduce the clauses  $\Rightarrow A^+(v)$  and  $\Rightarrow B^-(v)$ ; if it is marked B, introduce  $\Rightarrow A^-(v)$  and  $\Rightarrow B^+(v)$ . Otherwise let  $v$  have  $k$  outgoing arcs  $v \rightarrow u_1, \dots, v \rightarrow u_k$ . Introduce the clauses  $A^-(u_j) \Rightarrow B^+(v)$  and  $B^-(u_j) \Rightarrow A^+(v)$  for  $1 \leq j \leq k$ . Also, if  $v$  is not marked C, introduce the clauses  $A^+(u_1) \wedge \dots \wedge A^+(u_k) \Rightarrow B^-(v)$  and  $B^+(u_1) \wedge \dots \wedge B^+(u_k) \Rightarrow A^-(v)$ . All forcing strategies are consequences of these clauses. Exercise 2.2.3–28 and its answer provide further information.

Notice that, in principle, Algorithm C can therefore be used to decide whether or not the game of chess is a forced victory for the white pieces—except for the annoying detail that the corresponding digraph is larger than the physical universe.

51. With best play, the results (see exercise 50) are:

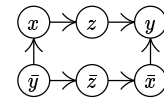
$n$	(a)	(b)	(c)	(d)
2	0 wins	second player wins	1 wins	second player wins
3	0 wins	first player wins	first player wins	first player wins
4	first player wins	first player wins	first player wins	first player wins
5	second player wins	draw	draw	1 loses if first
6	second player wins	second player wins	1 loses if first	1 loses if first
7	1 loses if first	second player wins	1 loses if first	1 loses if first
8	draw	draw	draw	1 loses if first
9	draw	draw	draw	1 loses if first

(Here “1 loses if first” means that the game is a draw if player 0 plays first, otherwise 0 can win.) *Comments:* In (a), player 1 has a slight disadvantage, because  $f = 0$  when  $x_1 \dots x_n$  is a palindrome. This small difference affects the results when  $n = 7$ . Although player 1 would seem to be better off playing 0s in the left half of the board, it turns out that his/her first move when  $n = 4$  must be to  $*1**$ ; the alternative,  $*0**$ , loses. Game (b) is essentially a race to see who can eliminate the last \*. In game (c), a random choice of  $x_1 \dots x_n$  makes  $f = 1$  with probability  $F_{n+2}/2^n = \Theta(\phi/2)^n$ ; in game (d), this probability approaches zero more slowly, as  $\Theta(1/\log n)$ . Still, player 1 does better in (c) than in (d) when  $n = 2, 5, 8$ , and 9; no worse in the other cases.

52. (a) She should switch either day 1 or day 2 to day 3. (b) Change day 2 to day 3. (c) This case is illustrated in Fig. 4; change either Desert or Excalibur to Aladdin. (d) Change either Caesars or Excalibur to Aladdin. (e) Change either Bellagio or Desert to Aladdin. (f) Change day 2 to day 3. Of course Williams, who doesn’t appear in the cycle (42), bears no responsibility whatever for the conflicts.

53. If  $x$  and  $\bar{x}$  are both in  $S$ , then  $u \in S \iff \bar{u} \in S$ , because the existence of paths from  $x$  to  $\bar{x}$  and  $x$  to  $u$  and  $u$  to  $x$  implies the existence of paths from  $\bar{u}$  to  $\bar{x}$  and  $\bar{x}$  to  $\bar{u}$ , hence from  $u$  to  $\bar{u}$  and  $\bar{u}$  to  $u$ .

54. Here  $f(x, y, z)$  corresponds to the digraph shown below (analogous to Fig. 4), and it can also be simplified to  $y \wedge (\bar{x} \vee z)$ . Each vertex is a strong component. So the formula is true with respect to the quantifiers  $\exists\exists\exists, \exists\exists\forall, \forall\exists\exists$ ; false in the other cases  $\exists\forall(\text{any}), \forall(\text{any})(\text{any})$ . In general the eight possibilities can be arranged at the corners of a cube, with each change from  $\exists$  to  $\forall$  making the formula more likely to be false.



**55.** Forming the digraph as in Theorem K, we can prove that the quantified formula holds if and only if (i) no strong component contains both  $x$  and  $\bar{x}$ ; (ii) there is no path from one universal variable  $x$  to another universal variable  $y$  or to its complement  $\bar{y}$ ; (iii) no strong component containing a universal variable  $x$  also contains an existential variable  $v$  or its complement  $\bar{v}$ , when ‘ $\exists v$ ’ appears to the left of ‘ $\forall x$ ’. These three conditions are clearly necessary, and they are readily tested as the strong components are being found.

To show that they are sufficient, notice first that no strong component  $S$  equals its complement  $\bar{S}$  (see exercise 53). Therefore if  $S$  has only existential literals, we can set them all equal as in Theorem K. Otherwise  $S$  has exactly one universal literal,  $u_j = x_j$  or  $\bar{x}_j$ ; all other literals in  $S$  are existential and declared to the right of  $x_j$ , so we can equate them to  $u_j$ . And all paths into  $S$  in such a case come from purely existential strong components, whose value can be set to 0 because the complements of such strong components cannot also lead into  $S$ ; for if  $v$  and  $\bar{v}$  imply  $u_j$ , then  $\bar{u}_j$  implies  $\bar{v}$  and  $v$ .

[*Information Proc. Letters* **8** (1979), 121–123. By contrast, M. Krom had proved in *J. Symbolic Logic* **35** (1970), 210–216, that an analogous problem in first-order predicate calculus (where parameterized predicates take the place of simple Boolean variables, and quantification is over the parameters) is actually unsolvable in general.]

**56.** We can assume that each clause is proper, by introducing ‘ $\perp$ ’ as in exercise 48 and placing ‘ $\forall \perp$ ’ at the left. Call the universal variables  $x_0, x_1, \dots, x_m$  (where  $x_0$  is  $\perp$ ) and call the existential variables  $y_1, \dots, y_n$ . Remove  $x_j$  from any clause whose unbarred literal is  $y_k$  when  $x_j$  appears to the right of  $y_k$ . Then, for  $0 \leq j \leq m$ , let  $C_j$  be the core of the Horn clauses when the additional clauses  $(x_0) \wedge \dots \wedge (x_{j-1}) \wedge (x_{j+1}) \wedge \dots \wedge (x_m)$  are appended. (In other words,  $C_j$  tells us what can be deduced when all the  $x$ ’s except  $x_j$  are assumed to be true.) We claim that the given formula is true if and only if  $x_j \notin C_j$ , for  $0 \leq j \leq m$ .

To prove this claim, note first that the formula is certainly false if  $x_j \in C_j$  for some  $j$ . Otherwise we can choose each  $y_k$  to make the formula true, as follows: If  $y_k \notin C_0$ , set  $y_k \leftarrow 0$ ; otherwise set  $y_k \leftarrow \bigwedge \{x_j \mid y_k \notin C_j\}$ . Notice that  $y_k$  depends on  $x_j$  only when  $\forall x_j$  appears to the left of  $\exists y_k$  in the list of quantifiers. Each clause  $c$  with unbarred literal  $x_j$  is now true: For if  $x_j = 0$ , some  $\bar{y}_k$  appears in  $c$  for which  $y_k \notin C_j$ , because  $x_j \notin C_j$ ; hence  $y_k = 0$ . And each clause  $c$  with unbarred literal  $y_k$  is also true: If  $y_k = 0$ , we either have  $y_k \notin C_0$ , in which case some  $\bar{y}_l$  in  $c$  is  $\notin C_0$ , hence  $y_l = 0$ ; or  $y_k \in C_0 \setminus C_j$  for some  $j$ , in which case some  $x_l$  appears in  $C_0$  and  $x_l = 0$ , or some  $\bar{y}_l$  appears in  $c$  where  $y_l \notin C_j$ , making  $y_l = 0$ .

[See M. Karpinski, H. Kleine-Büning, and P. H. Schmitt, *Lecture Notes in Comp. Sci.* **329** (1988), 129–137; H. Kleine Büning, K. Subramani, and X. Zhao, *Lecture Notes in Comp. Sci.* **2919** (2004), 93–104.]

**57.** By induction on  $n$ : Suppose  $f(0, x_2, \dots, x_n)$  leads to the quantified results  $y_1, \dots, y_{2n-1}$ , while  $f(1, x_2, \dots, x_n)$  leads similarly to  $z_1, \dots, z_{2n-1}$ . Then  $\exists x_1 f(x_1, x_2, \dots, x_n)$  leads to  $y_1 \vee z_1, \dots, y_{2n-1} \vee z_{2n-1}$ , and  $\forall x_1 f(x_1, x_2, \dots, x_n)$  leads to  $y_1 \wedge z_1, \dots, y_{2n-1} \wedge z_{2n-1}$ . Now use the fact that  $(y \vee z) + (y \wedge z) = y + z$ .

**58.** Both (a) and (b). But (c) is always 0; (d) is always 1; (e) is  $\overline{xy\bar{z}}$ ; (f) is  $\bar{x} \vee \bar{y} \vee \bar{z}$ .

**59.** True — indeed obviously so, when  $w = 0$ , and when  $w = 1$ .

**60.** Since  $\{x_1, x_2, x_3\} \subseteq \{0, 1\}$ , we can assume by symmetry that  $x_1$  equals  $x_2$ . Then either  $f(x_1, x_1, x_3, x_4, \dots, x_n) = f(x_1, x_1, x_1, x_4, \dots, x_n)$  or  $f(x_1, x_1, x_3, x_4, \dots, x_n) = f(x_3, x_1, x_3, x_4, \dots, x_n)$ , assuming only that  $f$  is monotone in its first three variables.



**61.**  $\langle xyz \rangle = \langle xy yz \rangle$ . *Note:* Emil Post proved, in fact, that a single subroutine for *any* nontrivial monotone self-dual function will suffice to compute them all. (By induction on  $n$ , at least one appropriate way to call such an  $n$ -ary subroutine will yield  $\langle xyz \rangle$ .)

**62.** [FOCS 3 (1962), 149–157.] (a) If  $f$  is monotone and self-dual, Theorem P says that  $f(x) = x_k$  or  $f(x) = \langle f_1(x)f_2(x)f_3(x) \rangle$ . The condition therefore holds either immediately or by induction. Conversely, if the condition holds it implies that  $f$  is monotone (when  $x$  and  $y$  differ in just one bit) and self-dual (when they differ in all bits).

(b) We merely need to show that it is possible to define  $f$  at one new point without introducing a conflict. Let  $x$  be the lexicographically smallest point where  $f(x)$  is undefined. If  $f(\bar{x})$  is defined, set  $f(x) = \bar{f}(\bar{x})$ . Otherwise if  $f(x') = 1$  for some  $x' \subseteq x$ , set  $f(x) = 1$ ; otherwise set  $f(x) = 0$ . Then the condition still holds.

**63.** If  $\mathcal{F}$  is maximal intersecting, we have (i)  $X \in \mathcal{F} \implies \bar{X} \notin \mathcal{F}$ , where  $\bar{X}$  is the complementary set  $\{1, 2, \dots, n\} \setminus X$ ; (ii)  $X \in \mathcal{F}$  and  $X \subseteq Y \implies Y \in \mathcal{F}$ , because  $\mathcal{F} \cup \{Y\}$  is intersecting; and (iii)  $X \notin \mathcal{F} \implies \bar{X} \in \mathcal{F}$ , because  $\mathcal{F} \cup \{X\}$  must contain an element  $Y \subseteq \bar{X}$ . Conversely, one can prove without difficulty that any family  $\mathcal{F}$  satisfying (i) and (ii) is intersecting, and maximal if it also satisfies (iii).

*Punch line:* All three statements can readily be translated into the language of Boolean functions: (i)  $f(x) = 1 \implies f(\bar{x}) = 0$ ; (ii)  $x \subseteq y \implies f(x) \leq f(y)$ ; (iii)  $f(x) = 0 \implies f(\bar{x}) = 1$ .

**64.** [T. Ibaraki and T. Kameda, *IEEE Transactions on Parallel and Distributed Systems* 4 (1993), 779–794.] Every family with the property that  $Q \subseteq Q'$  implies  $Q = Q'$  clearly corresponds to the prime implicants of a monotone Boolean function  $f$ . The further condition that  $Q \cap Q' \neq \emptyset$  corresponds to the further relation  $f(\bar{x}) \leq \bar{f}(x)$ , because  $f(\bar{x}) = f(x) = 1$  holds if and only if  $x$  and  $\bar{x}$  both make prime implicants true.

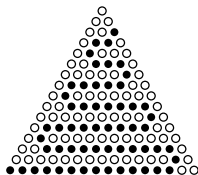
If coterie  $\mathcal{C}$  and  $\mathcal{C}'$  correspond in this way to functions  $f$  and  $f'$ , then  $\mathcal{C}$  dominates  $\mathcal{C}'$  if and only if  $f \neq f'$  and  $f'(x) \leq f(x)$  for all  $x$ . Then  $f'$  is not self-dual, because there is an  $x$  with  $f'(\bar{x}) = 0$ ,  $f(\bar{x}) = 1$ ; and we have  $f(x) = 0$ , hence  $f'(x) = 0$ .

Conversely, if  $f'$  is not self-dual, there's a  $y$  with  $f'(y) = f'(\bar{y}) = 0$ . If  $y = 0 \dots 0$ , coterie  $\mathcal{C}'$  is empty, and dominated by every other coterie. Otherwise define  $f(x) = f'(x) \vee [x \supseteq y]$ . Then  $f$  is monotone, and  $f(\bar{x}) \leq \bar{f}(x)$  for all  $x$ ; so it corresponds to a coterie that dominates  $\mathcal{C}'$ .

**65.** (a) By induction, if  $Y(t_{100}) = Y(t_{010}) = 1$  we have a Y of 1s, because the Ys in  $t_{100}$  and  $t_{010}$  either intersect or are adjacent. Similarly, if  $Y(t_{100}) = Y(t_{010}) = 0$  we do not have a Y of 1s, because there is a Y of 0s.

(b) This formula follows from (a) and the fact that  $(t_{abc})_{def} = t_{(a+d)(b+e)(c+f)} = (t_{def})_{abc}$ . [Schensted stated the results of this exercise, and those of exercises 60 and 67, in a 28-page letter sent to Martin Gardner on 21 January 1979.]

**66.** When  $n = 15$ , the author's best attempt so far has 58 black stones:



**67.** The proof of Theorem P shows that we need only prove  $Y(T) \leq f(x)$ . A Y in  $T$  means that we've got at least one variable in each  $p_j$ . Therefore  $f(\bar{x}_1, \dots, \bar{x}_n) = 0$ , and  $f(x_1, \dots, x_n) = 1$ .

**68.** Self-duality of  $g$  is obvious for arbitrary  $t$  when  $f$  is self-dual:  $\overline{g(\bar{x})} = (\overline{f(\bar{x})} \vee [\bar{x} \neq t]) \wedge [\bar{x} = \bar{t}] = (f(x) \vee [x = \bar{t}]) \wedge [x \neq t] = (f(x) \wedge [x \neq t]) \vee ([x = \bar{t}] \wedge [x \neq t]) = g(x)$ .

Let  $x = x_1 \dots x_{j-1} 0 x_{j+1} \dots x_n$  and  $y = x_1 \dots x_{j-1} 1 x_{j+1} \dots x_n$ ; for monotonicity we must prove that  $g(x) \leq g(y)$ . If  $x = t$  or  $y = t$ , we have  $g(x) = 0$ ; if  $x = \bar{t}$  or  $y = \bar{t}$ , we have  $g(y) = 1$ ; otherwise  $g(x) = f(x) \leq f(y) = g(y)$ . [European J. Combinatorics **16** (1995), 491–501; discovered independently by J. C. Bioch and H. Ibaraki, IEEE Transactions on Parallel and Distributed Systems **6** (1995), 905–914.]

**69.**  $\langle \langle xyz \rangle uv \rangle = \langle \langle \langle xyz \rangle uv \rangle uv \rangle = \langle \langle \langle yuv \rangle x \langle zuv \rangle \rangle uv \rangle = \langle \langle yuv \rangle \langle xuv \rangle \langle \langle zuv \rangle uv \rangle \rangle = \langle \langle xuv \rangle \langle yuv \rangle \langle zuv \rangle \rangle$ .

**70.** For (58),  $v = \langle uvu \rangle = u$ . For (59),  $\langle u y v \rangle = \langle v u \langle x u y \rangle \rangle = \langle \langle v u x \rangle u y \rangle = \langle x u y \rangle = y$ . And for (60),  $\langle x y z \rangle = \langle \langle x u v \rangle y z \rangle = \langle x \langle u y z \rangle \langle v y z \rangle \rangle = \langle x y y \rangle = y$ .

**71.** (a) If  $d(u, v) = d(u, x) + d(x, v)$ , we obviously obtain a shortest path of the form  $u \dots x \dots v$ . Conversely, if  $[u x v]$ , let  $u \dots x \dots v$  be a shortest path, with  $l$  steps to  $x$  followed by  $m$  steps to  $v$ . Then  $d(u, v) = l + m \geq d(u, x) + d(x, v) \geq d(u, v)$ .

(b) For all  $z$ ,  $\langle z x y \rangle = \langle z \langle v u x \rangle \langle y u x \rangle \rangle = \langle \langle z v y \rangle u x \rangle \in \{ \langle y u x \rangle, \langle v u x \rangle \} = \{ u, x \}$ .

(c) We can assume that  $d(x, u) \geq d(x, v) > 0$ . Let  $u \dots y \dots v$  be a shortest path, and let  $w = \langle x u y \rangle$ . Then  $\langle v x w \rangle = \langle v \langle v u x \rangle \langle w u x \rangle \rangle = \langle \langle v v w \rangle u x \rangle = \langle v u x \rangle = x$ , so  $x \in [w \dots v]$ . We have  $[u w y]$ , because  $d(u, y) < d(u, v)$  and  $w \in [u \dots y]$ . If  $w \neq u$  we have  $d(w, x) < d(u, v)$ ; hence  $[w x v]$ , hence  $[u x v]$ . If  $w = u$  we have  $x \dots u$  by (b). But  $d(x, u) \geq d(x, v)$ ; therefore  $x \dots v$ , and  $[u x v]$ .

(d) Let  $y = \langle u x v \rangle$ . Since  $y \in [u \dots x]$ , we have  $d(u, x) = d(u, y) + d(y, x)$  by (a) and (c). Similarly,  $d(u, v) = d(u, y) + d(y, v)$  and  $d(x, v) = d(x, y) + d(y, v)$ . But these three equations, together with  $d(u, v) = d(u, x) + d(x, v)$ , yield  $d(x, y) = 0$ . [Proc. Amer. Math. Soc. **12** (1961), 407–414.]

**72.**  $w = \langle y x w \rangle = \langle y x \langle z x w \rangle \rangle = \langle y x \langle z x \langle y z w \rangle \rangle \rangle = \langle \langle y x z \rangle x \langle y z w \rangle \rangle = \langle x \langle x y z \rangle \langle w y z \rangle \rangle = \langle x y z \rangle$  by (55), the associative law (52), and the case  $x = y$  of (53).

**73.** (a) If  $w = \langle x y x \rangle$  we have  $[x w x]$  by (iii), hence  $w = x$  by (i).

(b) Axiom (iii) and part (a) tell us that  $[x y x]$  is always true. So we can set  $x = y$  in (ii) to conclude that  $[u x v] \iff [v x u]$ . The definition of  $\langle x y z \rangle$  in (iii) is therefore perfectly symmetrical between  $x, y$ , and  $z$ .

(c) By the definition of  $\langle u x v \rangle$  in (iii), we have  $x = \langle u x v \rangle$  if and only if  $[u x x]$ ,  $[u x v]$ , and  $[x x v]$ . But we know that  $[u x x]$  and  $[x x v]$  are always true.

(d) In this step and subsequent steps, we will construct one or more auxiliary points of  $M$  and then use Algorithm C to derive every consequence of the betweenness relations that are known. (The axioms have the convenient form of Horn clauses.) For example, here we define  $z = \langle x y v \rangle$ , so that we know  $[u x y]$ ,  $[u y v]$ ,  $[x z y]$ ,  $[x z v]$ , and  $[y z v]$ . From these hypotheses we deduce, successively,  $[u x v]$ ,  $[u z y]$ ,  $[u z v]$ . So  $z = \langle u y v \rangle = y$ .

(e) The hinted construction implies, among many other things,  $[u t z]$ ,  $[v t z]$ ,  $[u w v]$ ,  $[u w z]$ ,  $[v w z]$ ; hence  $t = w$ . (A computer program is helpful here.) Adding the hypotheses  $[r w s]$ ,  $[r w z]$ ,  $[s w z]$  now yields  $[x y z]$  as desired; it also turns out that  $r = p$  and  $s = q$ .

(f) Let  $r = \langle y u v \rangle$ ,  $s = \langle z u v \rangle$ ,  $t = \langle x y z \rangle$ ,  $p = \langle x r s \rangle$ ,  $q = \langle t u v \rangle$ ; then  $[p q p]$  flows out. [Proc. Amer. Math. Soc. **5** (1954), 801–807.]

**74.** Axiom (i) obviously holds, and axiom (ii) follows from commutativity and (55). The answer to exercise 86 derives (iii) from the identity  $\langle x y z \rangle = \langle x \langle x y z \rangle \langle w y z \rangle \rangle$ ; so we need only verify that formula:  $\langle x \langle x y z \rangle \langle w y z \rangle \rangle = \langle \langle y x z \rangle x \langle w y z \rangle \rangle = \langle \langle \langle y x z \rangle x z \rangle x \langle w y z \rangle \rangle = \langle \langle y x z \rangle x \langle z x \langle w y z \rangle \rangle \rangle = \langle x \langle x y z \rangle \langle z x y z \rangle w \rangle = \langle \langle x \langle x y z \rangle z \rangle \langle x y z \rangle w \rangle = \langle \langle x y z \rangle \langle x y z \rangle w \rangle$ .

*Notes:* The original treatment of median algebra by Birkhoff and Kiss in *Bull. Amer. Math. Soc.* **53** (1947), 749–752, assumed (50), (51), and the short distributive law (53). The fact that associativity (52) actually implies distributivity was not realized until many years later; M. Kolibiar and T. Marcisová, *Matematicky Časopis* **24** (1974), 179–185, proved it via Sholander’s axioms as in this exercise. A mechanical derivation of (53) from (50)–(52) was found in 2005 by R. Veroff and W. McCune, using an extension of the Otter theorem prover [to appear].

**75.** (a) Suppose  $r$  has 0 and  $s$  has 1, in coordinate  $r \text{ --- } s$  of the labels. Then the left vertices are those with 0 in that coordinate. If  $u \text{ --- } v \text{ --- } u'$ , where  $u$  and  $u'$  are on the left but  $v$  is on the right,  $\langle uu'v \rangle$  lies on the left. But  $[u \dots v] \cap [u' \dots v] = \{v\}$ , unless  $u = u'$ .

(b) This statement is obvious, by Corollary C.

(c) Suppose  $u \text{ --- } v$  and  $u' \text{ --- } v'$ , where  $u$  and  $u'$  are on the left,  $v$  and  $v'$  are on the right. Let  $v = v_0 \text{ --- } \dots \text{ --- } v_k = v'$  be a shortest path, and let  $u_0 = u$ ,  $u_k = u'$ . All vertices  $v_j$  lie on the right, by (b). The left vertex  $u_1 = \langle u_0 v_1 u_k \rangle$  must be a common neighbor of  $u_0$  and  $v_1$ , since the distance  $d(u_0, v_1) = 2$ . (We cannot have  $u_1 = u_0$ , because that would imply the existence of a shortest path from  $v$  to  $v'$  going through the left vertex  $u$ .) Therefore  $v_1$  has rank 1; and so do  $v_2, \dots, v_{k-1}$ , by the same argument. [L. Nebeský, *Commentationes Mathematicae Universitatis Carolinae* **12** (1971), 317–325; M. Mulder, *Discrete Math.* **24** (1978), 197–204.]

(d) These steps visit all vertices  $v$  of rank 1 in order of their distance  $d(v, s)$  from  $s$ . If such a  $v$  has a late neighbor  $u$  not yet seen, the rank of  $u$  must be 1 or 2. If the rank is 1,  $u$  will have at least two early neighbors, namely  $v$  and the future  $\text{MATE}(u)$ . Step I8 bases its decision on an arbitrary early neighbor  $w$  of  $u$  such that  $w \neq v$ . Since  $d(w, v) = 2$ , the vertex  $x = \langle svw \rangle$  has rank 1 by (c). If  $w$  has rank 0, then  $x = v$ ; so  $u$  has rank 1. Otherwise  $d(x, s) < d(v, s)$ , and the rank of  $w$  was correctly determined when  $x$  was visited. If  $w$  has rank 1,  $u$  lies on a shortest path from  $v$  to  $w$ ; if  $w$  has rank 2,  $w$  lies on a shortest path from  $u$  to  $s$ . In both cases  $u$  and  $w$  have the same rank, by (c).

(e) The algorithm removes all edges equivalent to  $r \text{ --- } s$ , by (a) and (c). Their removal clearly disconnects the graph; the two pieces that remain are convex by (b), so they are connected and in fact they are median graphs. Step I7 records all of the relevant relations between the two pieces, because all 4-cycles that disappear are examined there. By induction on the number of vertices, each piece is properly labeled.

**76.** Every time  $v$  appears in step I4, it loses one of its neighbors  $u_j$ . Each of these edges  $v \text{ --- } u_j$  corresponds to a different coordinate of the labels, so we can assume that  $l(v)$  has the form  $\alpha 1^k$  for some binary string  $\alpha$ . The labels for  $u_1, u_2, \dots, u_k$  are then  $\alpha 01^{k-1}, \alpha 101^{k-2}, \dots, \alpha 1^{k-1}0$ . By taking componentwise medians, we can now prove that all  $2^k$  labels of the form  $\alpha\beta$  occur for vertices in the graph, since  $\langle (\alpha\beta)(\alpha\beta')(0 \dots 0) \rangle$  is the bit string  $\alpha(\beta \& \beta')$ .

**77.** (a) If  $l(v) = k$ , exactly  $\nu(k)$  smaller vertices are neighbors of  $v$ .

(b) At most  $\lfloor n/2 \rfloor$  1s appear in bit position  $j$ , for  $0 \leq j < \lceil \lg n \rceil$ .

(c) Suppose  $k$  vertices have labels beginning with 0. At most  $\min(k, n-k)$  edges correspond to that bit position, and at most  $f(k) + f(n-k)$  other edges are present. But

$$f(n) = \max_{0 \leq k \leq n} (\min(k, n-k) + f(k) + f(n-k)),$$

because the function  $g(m, n) = f(m+n) - m - f(m) - f(n)$  satisfies the recurrence

$$g(2m+a, 2n+b) = ab + g(m+a, n) + g(m, n+b) \quad \text{for } 0 \leq a, b \leq 1.$$

It follows by induction that  $g(m, m) = g(m, m+1) = 0$ , and that  $g(m, n) \geq 0$  when  $m \leq n$ . [Annals of the New York Academy of Sciences **175** (1970), 170–186; D. E. Knuth, *Proc. IFIP Congress 1971* (1972), 24.]

**78.** (a) (Solution by W. Imrich.) The graph with vertex labels 0000, 0001, 0010, 0011, 0100, 0110, 0111, 1100, 1101, 1110, 1111 cannot be labeled in any essentially different way; but the distance from 0001 to 1101 is 4, not 2.

(b) The cycle  $C_{2m}$  is a partial cube, because its vertices can be labeled  $l(k) = 1^k 0^{m-k}$ ,  $l(m+k) = 0^k 1^{m-k}$  for  $0 \leq k < m$ . But the bitwise median of  $l(0)$ ,  $l(m-1)$ , and  $l(m+1)$  is  $01^{m-2}0$ ; and indeed those vertices don't have a median, when  $m > 2$ .

**79.** Yes. A median graph is a subgraph of a hypercube, which is bipartite.

**80.** The general case reduces to the simple case where  $G$  has only two vertices  $\{0, 1\}$ , because we can operate componentwise on the median labels, and because  $d(u, v)$  is the Hamming distance between  $l(u)$  and  $l(v)$ .

In the simple case, the stated rule sets  $u_k \leftarrow v_k$  except when  $u_{k-1} = v_{k-1} = v_{k+1} \neq v_k$ , and it is readily proved optimum. (Other optimum possibilities do exist, however; for example, if  $v_0 v_1 v_2 v_3 = 0110$ , we could set  $u_0 u_1 u_2 u_3 = 0000$ .)

[This problem was motivated by the study of self-organizing data structures. F. R. K. Chung, R. L. Graham, and M. E. Saks, in *Discrete Algorithms and Complexity* (Academic Press, 1987), 351–387, have proved that median graphs are the *only* graphs for which  $u_k$  can always be chosen optimally as a function of  $(v_0, v_1, \dots, v_{k+1})$ , regardless of the subsequent values  $(v_{k+2}, \dots, v_t)$ . They have also characterized all cases for which a given finite amount of lookahead will suffice, in *Combinatorica* **9** (1989), 111–131.]

**81.** Again it suffices to consider the simple two-vertex case. An optimum solution in that case can never have  $u_{k-1} \neq u_k$  except when  $u_{k-1} = v_{k-1} \neq v_k = u_k$ . Therefore we must only decide which runs of consecutive 0s or 1s in  $v_0 v_1 \dots v_t$  should induce matching runs in  $u_0 u_1 \dots u_t$ .

Suppose  $v_{k-1} v_k \dots v_{k+r} = 01^r 0$  and  $u_{k-1} = 0$ . The cost of  $u_{k-1} u_k \dots u_{k+r} = 00 \dots 0$  is  $r\rho$ , compared to a cost of 2 if  $u_{k-1} u_k \dots u_{k+r} = 01^r 0$ ; so we must choose the former if  $\rho < 2/r$  and the latter if  $\rho > 2/r$ . This policy can be expressed in terms of medians, if we set  $u_k = \langle u_{k-1} \dots u_{k-1} v_k \dots v_{k+r} \rangle$  when  $2/(r+1) \leq \rho < 2/r$  for  $r \geq 0$ , where there are  $r$  occurrences of  $u_{k-1}$ . (This median-of- $(2r+1)$  gives correct results in a general median graph, since it will produce valid median labels; see exercise 84.)

But we must change this rule when we get near the end, because it eventually asks for the values of  $v_j$  with  $j > t$ . The endgame is tricky; for if  $v_{k-1} v_k \dots v_t = 01^r$  and  $u_{k-1} = 0$ , with  $r = t+1-k$ , the choice  $u_{k-1} u_k \dots u_t = 00 \dots 0$  is now preferable only if  $\rho < 1/r$ . For example, if  $2/4 < \rho < 2/3$  and  $v_0 v_1 = 01$  and  $t = 1$ , we want to choose  $u_0 u_1 = 00$ ; but if  $v_0 v_1 v_2 = 011$  and  $t = 2$  we want  $u_0 u_1 u_2 = 011$ . One solution is to set  $v_{t+j} \leftarrow v_t$  for  $1 \leq j \leq \lceil r/2 \rceil$  and  $v_{t+j} \leftarrow v_0$  for  $\lceil r/2 \rceil < j \leq r$ .

**82.** There are 81 such functions, each of which can be represented as the median of an odd number of elements. Seven types of vertices occur:

Type	Typical vertex	Cases	Adjacent to	Degree
1	$\langle z \rangle$	5	$\langle v w x y z z z \rangle$	1
2	$\langle v w x y z z z \rangle$	5	$\langle z \rangle, \langle w x y z z \rangle$	5
3	$\langle w x y z z \rangle$	20	$\langle v w x y z z z \rangle, \langle v w x x y y z z z \rangle$	4
4	$\langle v w x x y y z z z \rangle$	30	$\langle x y z \rangle, \langle w x y z z \rangle, \langle v w x y y z z \rangle$	5
5	$\langle v w x y y z z \rangle$	10	$\langle v w x x y y z z z \rangle, \langle v w x y z \rangle$	7
6	$\langle v w x y z \rangle$	1	$\langle v w x y y z z \rangle$	10
7	$\langle x y z \rangle$	10	$\langle v w x x y y z z z \rangle$	3

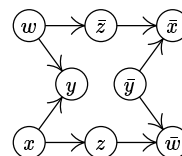
[Von Neumann and Morgenstern enumerated these seven types in their book *Theory of Games and Economic Behavior* (1944), §52.5, in connection with the study of an equivalent problem about systems of winning coalitions that they called *simple games*. The graph for six-variable functions, which has 2646 vertices of 30 types, appears in the paper by Meyerowitz cited in exercise 68. Only 21 of those types can be represented as a simple median-of-odd; a vertex like  $\langle\langle abd\rangle\langle ace\rangle\langle bcf\rangle\rangle$ , for example, has no such representation. Let the corresponding graph for  $n$  variables have  $M_n$  vertices; P. Erdős and N. Hindman, in *Discrete Math.* **48** (1984), 61–65, showed that  $\lg M_n$  is asymptotic to  $\binom{n-1}{\lfloor n/2 \rfloor}$ . D. Kleitman, in *J. Combin. Theory* **1** (1966), 153–155, showed that the vertices for distinct projection functions like  $x$  and  $y$  are always furthest apart in this graph.]

**83.** Every strong component must consist of a single vertex; otherwise two coordinates would always be equal, or always complementary. Thus the digraph must be acyclic.

Furthermore, there must be no path from a vertex to its complement; otherwise a coordinate would be constant.

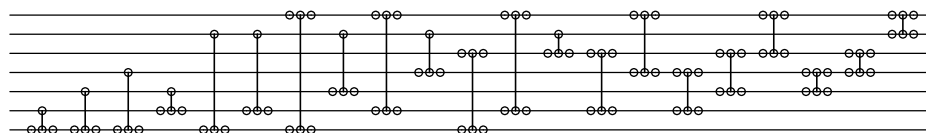
When these two conditions are satisfied, we can prove that no vertex  $x$  is redundant, by assigning the value 0 to all vertices that precede  $x$  or  $\bar{x}$ , assigning 1 to all vertices that follow, and giving appropriate values to all other vertices.

(Consequently we obtain a completely different way to represent a median graph. For example, the digraph shown corresponds to the median graph whose labels are  $\{0000, 0001, 0010, 0011, 0111, 1010\}$ .)



**84.** Yes. By Theorem P, *any* monotone self-dual function maps elements of  $X$  into  $X$ .

**85.** Here the topological ordering  $7\ 6\ 5\ 4\ 3\ 2\ 1\ \bar{1}\ \bar{2}\ \bar{3}\ \bar{4}\ \bar{5}\ \bar{6}\ \bar{7}$  can replace  $(72)$ ; we get




(Consecutive inverters on the same line can, of course, be canceled out.)

**86.** A given value of  $d$  contributes at most  $6\lceil t/d \rceil$  units of delay (for  $2\lceil t/d \rceil$  clusters).

**87.** Suppose first that the new condition is  $i \rightarrow j$  while the old was  $i' \rightarrow j'$ , where  $i < j$  and  $i' < j'$  and there are no complemented literals. The new module changes  $x_1 \dots x_t$  to  $y_1 \dots y_t$ , where  $y_i = x_i \wedge x_j$ ,  $y_j = x_i \vee x_j$ , and  $y_k = x_k$  otherwise. We certainly have  $y_{i'} \leq y_{j'}$  when  $\{i', j'\} \cap \{i, j\} = \emptyset$ . And there is no problem if  $i = i'$ , since  $y_{i'} = y_i \leq x_i = x_{i'} \leq x_{j'} = y_{j'}$ . But the case  $i = j'$  is trickier: Here the relations  $i' \rightarrow i$  and  $i \rightarrow j$  imply also  $i' \rightarrow j$ ; and this relation has been enforced by *previous* modules, because modules have been appended in order of decreasing distance  $d$  in the topological ordering  $u_1 \dots u_{2t}$ . Therefore  $y_{i'} = x_{i'} \leq x_j \leq y_i = y_{j'}$ . A similar proof works when  $j = i'$  or  $j = j'$ .

Finally, with complemented literals, the construction cleverly reduces the general case to the uncomplemented case by inverting and un-inverting the bits.

**88.** When  $t = 2$ ,  does the job. The general case follows recursively from this building block by reducing  $t$  to  $\lfloor t/2 \rfloor$ .

[The study of CI-nets, and other networks of greater generality, was initiated by E. W. Mayr and A. Subramanian, *J. Computer and System Sci.* **44** (1992), 302–323.]

**89.** The answer does not yet seem to be known even in the special case when the median graph is a free tree (with  $t + 1$  vertices), or in the monotone case when it is a distributive lattice as in Corollary F. In the latter case, inverters may be unnecessary.

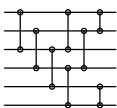
**91.** Let  $d_X(u, v)$  be the number of edges on a shortest path between  $u$  and  $v$ , when the path lies entirely within  $X$ . Clearly  $d_X(u, v) \geq d_G(u, v)$ . And if  $u = u_0 - u_1 - \dots - u_k = v$  is a shortest path in  $G$ , the path  $u = f(u_0) - f(u_1) - \dots - f(u_k) = v$  lies in  $X$  when  $f$  is a retraction from  $G$  to  $X$ ; hence  $d_X(u, v) \leq d_G(u, v)$ .

**92.** If  $f$  is a retraction of the  $t$ -cube onto  $X$ , two different coordinate positions cannot always be equal or always complementary for all  $x \in X$ , unless they are constant. For if, say, all elements of  $X$  have the forms  $00*\dots*$  or  $11*\dots*$ , there would be no path between vertices of those two types, contradicting the fact that  $X$  is an isometric subgraph (hence connected).

Given  $x, y, z \in X$ , let  $w = \langle xyz \rangle$  be their median in the  $t$ -cube. Then  $f(w) \in [x \dots y] \cap [x \dots z] \cap [y \dots z]$ , because (for example)  $f(w)$  lies on a shortest path from  $x$  to  $y$  in  $X$ . So  $f(w) = w$ , and we have proved that  $w \in X$ . [This result and its considerably more subtle converse are due to H. J. Bandelt, *J. Graph Theory* **8** (1984), 501–510.]

**93.** False (although the author was hoping otherwise); the network at the right takes  $0001 \mapsto 0000$ ,  $0010 \mapsto 0011$ ,  $1101 \mapsto 0110$ , but nothing  $\mapsto 0010$ .

(The set of all possible outputs appears to have no easy characterization, even when no inverters are used. For example, the pure-comparator network at the left, constructed by Tomás Feder, takes  $000000 \mapsto 000000$ ,  $010101 \mapsto 010101$ , and  $101010 \mapsto 011001$ , but nothing  $\mapsto 010001$ . See also exercises 5.3.4–50, 5.3.4–52.)



**94.** No. If  $f$  is a threshold function based on real parameters  $w = (w_1, \dots, w_n)$  and  $T$ , let  $\max\{w \cdot x \mid f(x) = 0\} = T - \epsilon$ . Then  $\epsilon > 0$ , and  $f$  is defined by the  $2^n$  inequalities  $w \cdot x - T \geq 0$  when  $f(x) = 1$ ,  $T - w \cdot x - \epsilon \geq 0$  when  $f(x) = 0$ . If  $A$  is any  $M \times N$  matrix of integers for which the system of linear inequalities  $Av \geq (0, \dots, 0)^T$  has a real-valued solution  $v = (v_1, \dots, v_N)^T$  with  $v_N > 0$ , there also is such a solution in integers. (Proof by induction on  $N$ .) So we can assume that  $w_1, \dots, w_n, T$ , and  $\epsilon$  are integers.

[A closer analysis using Hadamard's inequality (see Eq. 4.6.1–(25)) proves in fact that integer weights of magnitude at most  $(n + 1)^{(n+1)/2}/2^n$  will suffice; see S. Muroga, I. Toda, and S. Takasu, *J. Franklin Inst.* **271** (1961), 376–418, Theorem 16. Furthermore, exercise 110 shows that weights nearly that large are sometimes needed.]

**95.**  $\langle 11111x_1x_2 \rangle, \langle 111x_1x_2 \rangle, \langle 1x_1x_2 \rangle, \langle 0x_1x_2 \rangle, \langle 000x_1x_2 \rangle, \langle 00000x_1x_2 \rangle$ .

**96.** We may assume that  $f(x_1, \dots, x_n) = \langle y_1^{w_1} \dots y_n^{w_n} \rangle$ , with positive integer weights  $w_j$  and with  $w_1 + \dots + w_n$  odd. Let  $\delta$  be the minimum positive value of the  $2^n$  sums  $\pm w_1 \pm \dots \pm w_n$ , with  $n$  independently varying signs. Renumber all subscripts so that  $w_1 + \dots + w_k - w_{k+1} - \dots - w_n = \delta$ . Then  $w_1y_1 + \dots + w_ny_n > \frac{1}{2}(w_1 + \dots + w_n) \iff w_1(y_1 - \frac{1}{2}) + \dots + w_n(y_n - \frac{1}{2}) > 0 \iff w_1(y_1 - \frac{1}{2}) + \dots + w_n(y_n - \frac{1}{2}) > -\delta/2 \iff w_1y_1 + \dots + w_ny_n > \frac{1}{2}(w_1 + \dots + w_n - (w_1 + \dots + w_k - w_{k+1} - \dots - w_n)) = w_{k+1} + \dots + w_n \iff w_1y_1 + \dots + w_ky_k - w_{k+1}\bar{y}_{k+1} - \dots - w_n\bar{y}_n > 0$ .

**97.** We have  $[x_1 + \dots + x_{2s-1} + s(y_1 + \dots + y_{2t-2}) \geq st] = [\lfloor (x_1 + \dots + x_{2s-1})/s \rfloor + y_1 + \dots + y_{2t-2} \geq t]$ ; and  $\lfloor (x_1 + \dots + x_{2s-1})/s \rfloor = [x_1 + \dots + x_{2s-1} \geq s]$ .

(For example,  $\langle \langle xyz \rangle uv \rangle = \langle xyz u^2 v^2 \rangle$ , a quantity that we also know is equal to  $\langle x \langle yuv \rangle \langle zuv \rangle \rangle$  and  $\langle \langle xuv \rangle \langle yuv \rangle \langle zuv \rangle \rangle$  by Eqs. (53) and (54). Reference: C. C. Elgot, *FOCS* **2** (1961), 238.)

**98.** True, because of the preceding exercise and (45).

**99.** (a) When  $n = 7$  they are  $x_7 \wedge x_6$ ,  $x_6 \wedge x_5$ ,  $x_7 \wedge x_5 \wedge x_4$ ,  $x_6 \wedge x_4 \wedge x_3$ ,  $x_7 \wedge x_5 \wedge x_3 \wedge x_2$ ,  $x_6 \wedge x_4 \wedge x_2 \wedge x_1$ ,  $x_7 \wedge x_5 \wedge x_3 \wedge x_1$ ; and in general there are  $n$  prime implicants, forming a similar pattern. (We have either  $x_n = x_{n-1}$  or  $x_n = \bar{x}_{n-1}$ . In the first case,  $x_n \wedge x_{n-1}$  is obviously a prime implicant. In the second case,  $F_n(x_1, \dots, x_{n-1}, \bar{x}_n) = F_{n-1}(x_1, \dots, x_{n-1})$ ; so we use the prime implicants of the latter, and insert  $x_n$  when  $x_{n-1}$  does not appear.)

(b) The shelling pattern (0000011, 0000110, 0001101, 0011010, 0110101, 1101010, 1010101) for  $n = 7$  works for all  $n$ .

(c) Two of several possibilities for  $n = 7$  illustrate the general case:

$$F_7(x_1, \dots, x_7) = Y \begin{pmatrix} x_6 \\ x_7 \ x_5 \\ x_6 \ x_6 \ x_4 \\ x_7 \ x_5 \ x_7 \ x_3 \\ x_6 \ x_6 \ x_4 \ x_6 \ x_2 \\ x_7 \ x_5 \ x_7 \ x_3 \ x_7 \ x_1 \end{pmatrix} = Y \begin{pmatrix} x_6 \\ x_7 \ x_5 \\ x_6 \ x_6 \ x_4 \\ x_7 \ x_5 \ x_5 \ x_3 \\ x_6 \ x_6 \ x_4 \ x_4 \ x_2 \\ x_7 \ x_5 \ x_5 \ x_3 \ x_3 \ x_1 \end{pmatrix}.$$

[The Fibonacci threshold functions were introduced by S. Muroga, who also discovered the optimality result in exercise 103; see *IEEE Transactions EC-14* (1965), 136–148.]

**100.** (a) By (1) and (2),  $\hat{f}(\bar{x}_0, \bar{x}_1, \dots, \bar{x}_n)$  is the complement of  $\hat{f}(x_0, x_1, \dots, x_n)$ .

(b) If  $f$  is given by (75),  $\hat{f}$  is  $[(w + 1 - 2t)x_0 + w_1x_1 + \dots + w_nx_n \geq w + 1 - t]$ , where  $w = w_1 + \dots + w_n$ . Conversely, if  $\hat{f}$  is a threshold function, so is  $f(x_1, \dots, x_n) = \hat{f}(1, x_1, \dots, x_n)$ . [E. Goto and H. Takahashi, *Proc. IFIP Congress* (1962), 747–752.]

**101.** [See R. C. Minnick, *IRE Transactions EC-10* (1961), 6–16.] We want to minimize  $w_1 + \dots + w_n$  subject to the constraints  $w_j \geq 0$  for  $1 \leq j \leq n$  and  $(2e_1 - 1)w_1 + \dots + (2e_n - 1)w_n \geq 1$  for each prime implicant  $x_1^{e_1} \wedge \dots \wedge x_n^{e_n}$ . For example, if  $n = 6$ , the prime implicant  $x_2 \wedge x_5 \wedge x_6$  would lead to the constraint  $-w_1 + w_2 - w_3 - w_4 + w_5 + w_6$ . If the minimum is  $+\infty$ , the given function is not a threshold function. (The answer to exercise 94 gives one of the simplest examples of such a case.) Otherwise, if the solution  $(w_1, \dots, w_n)$  involves only integers, it minimizes the desired size. When noninteger solutions arise, additional constraints must be added until the best solution is found, as in part (c) of the following exercise.

**102.** First we need an algorithm to generate the prime implicants  $x_1^{e_1} \wedge \dots \wedge x_n^{e_n}$  of a given majority function  $\langle x_1^{w_1} \dots x_n^{w_n} \rangle$ , when  $w_1 + \dots + w_n$  is odd:

**K1.** [Initialize.] Set  $t \leftarrow 0$ . Then for  $j = n, n - 1, \dots, 1$  (in this order), set  $a_j \leftarrow t$ ,  $t \leftarrow t + w_j$ ,  $e_j \leftarrow 0$ . Finally set  $t \leftarrow (t + 1)/2$ ,  $s_1 \leftarrow 1$ , and  $l \leftarrow 1$ .

**K2.** [Enter level  $l$ .] Set  $l \leftarrow l + 1$ ,  $e_l \leftarrow 1$ ,  $s_{l+1} \leftarrow s_l + w_l$ .

**K3.** [Below threshold?] If  $s_{l+1} < t$ , return to K2.

**K4.** [Visit a prime implicant.] Visit the exponents  $(e_1, \dots, e_n)$ .

**K5.** [Downsize.] Set  $e_l \leftarrow 0$ . Then if  $s_l + a_{l+1} \geq t$ , set  $s_{l+1} \leftarrow s_l$  and go to K2.

**K6.** [Backtrack.] Set  $l \leftarrow l - 1$ . Terminate if  $l = 0$ ; otherwise go to K5 if  $e_l = 1$ ; otherwise repeat this step. ■

(a)  $\langle x_1x_2^2x_3^5x_4^6x_5^8x_7^{10}x_9^{12} \rangle$  (95 prime implicants).

(b) The optimum weights for  $\langle x_0^{16-2t}x_1^8x_2^4x_3^2x_4 \rangle$  are  $w_0w_1w_2w_3w_4 = 10000, 31111, 21110, 32211, 11100, 23211, 12110, 13111, 01000$ , for  $0 \leq t \leq 8$ ; the other cases are dual.

(c) Here the optimum weights  $(w_1, \dots, w_{10})$  are  $(29, 25, 19, 15, 12, 8, 8, 3, 3, 0)/2$ ; so we learn that  $x_{10}$  is irrelevant, and we must deal with fractional weights. Constraining  $w_8 \geq 2$  gives integer weights  $(15, 13, 10, 8, 6, 4, 4, 2, 1, 0)$ , which must be optimum

because their sum exceeds the previous sum by 2. (Only two of the 175,428 self-dual threshold functions on nine variables have nonintegral weights minimizing  $w_1 + \dots + w_n$ ; the other one is  $\langle x_1^{17} x_2^{15} x_3^{11} x_4^9 x_5^7 x_6^5 x_7^4 x_8^2 x_9 \rangle$ . The largest  $w_1$  in a minimum representation occurs in  $\langle x_1^{42} x_2^{22} x_3^{18} x_4^{15} x_5^{13} x_6^{10} x_7^8 x_8^4 x_9^3 \rangle$ ; the largest  $w_1 + \dots + w_9$  occurs uniquely in  $\langle x_1^{34} x_2^{32} x_3^{28} x_4^{27} x_5^{24} x_6^{20} x_7^{18} x_8^{15} x_9^{11} \rangle$ , which is also an example of the largest  $w_9$ . See S. Muroga, T. Tsuboi, and C. R. Baugh, *IEEE Transactions C-19* (1970), 818–825.)

**103.** When  $n = 7$ , the inequalities generated in exercise 101 are  $w_7 + w_6 - w_5 - w_4 - w_3 - w_2 - w_1 \geq 1$ ,  $-w_7 + w_6 + w_5 - w_4 - w_3 - w_2 - w_1 \geq 1$ ,  $w_7 - w_6 + w_5 + w_4 - w_3 - w_2 - w_1 \geq 1$ ,  $-w_7 + w_6 - w_5 + w_4 + w_3 - w_2 - w_1 \geq 1$ ,  $w_7 - w_6 + w_5 - w_4 + w_3 + w_2 - w_1 \geq 1$ ,  $-w_7 + w_6 - w_5 + w_4 - w_3 + w_2 + w_1 \geq 1$ ,  $w_7 - w_6 + w_5 - w_4 + w_3 - w_2 + w_1 \geq 1$ . Multiply them respectively by 1, 1, 2, 3, 5, 8, 5 to get  $w_1 + \dots + w_7 \geq 1 + 1 + 2 + 3 + 5 + 8 + 5$ . The same idea works for all  $n \geq 3$ .

**104.** (a)  $\langle x_1^{2^{n-1}} x_2^{2^{n-2}} \dots x_n \bar{y}_1^{2^{n-1}} \bar{y}_2^{2^{n-2}} \dots \bar{y}_n \bar{z} \rangle$ . (By exercise 97, we could also perform  $n$  medians-of-three:  $\langle \dots \langle x_n \bar{y}_n \bar{z} \rangle \dots x_2 \bar{y}_2 \rangle x_1 \bar{y}_1 \rangle$ .)

(b) If  $\langle x_1^{u_1} x_2^{u_2} \dots x_n^{u_n} \bar{y}_1^{v_1} \bar{y}_2^{v_2} \dots \bar{y}_n^{v_n} \bar{z}^w \rangle$  solves the problem,  $2^{n+1} - 1$  basic inequalities need to hold; for example, when  $n = 2$  they are  $u_1 + u_2 - v_1 + v_2 - w \geq 1$ ,  $u_1 + u_2 - v_1 - v_2 + w \geq 1$ ,  $u_1 - u_2 + v_1 - v_2 - w \geq 1$ ,  $u_1 - u_2 - v_1 + v_2 + w \geq 1$ ,  $-u_1 + u_2 + v_1 + v_2 - w \geq 1$ ,  $-u_1 + u_2 + v_1 - v_2 + w \geq 1$ ,  $-u_1 - u_2 + v_1 + v_2 + w \geq 1$ . Add them all up to get  $u_1 + u_2 + \dots + u_n + v_1 + v_2 + \dots + v_n + w \geq 2^{n+1} - 1$ .

105.	$f$	$N(f)$	$\Sigma(f)$	$f$	$N(f)$	$\Sigma(f)$	$f$	$N(f)$	$\Sigma(f)$	$f$	$N(f)$	$\Sigma(f)$
	$\perp$	0	(0, 0)	$\overline{\cap}$	1	(0, 1)	$\bar{\vee}$	1	(0, 0)	$\sqsubset$	2	(0, 1)
	$\wedge$	1	(1, 1)	$\cap$	2	(1, 2)	$\equiv$	2	(1, 1)	$\supset$	3	(1, 2)
	$\supset$	1	(1, 0)	$\oplus$	2	(1, 1)	$\bar{\cap}$	2	(1, 0)	$\bar{\wedge}$	3	(1, 1)
	$\sqsubset$	2	(2, 1)	$\vee$	3	(2, 2)	$\subset$	3	(2, 1)	$\top$	4	(2, 2)

Notice that  $\oplus$  and  $\equiv$  have the same parameters  $N(f)$  and  $\Sigma(f)$ ; they are the only Boolean binary operations that aren't threshold functions.

**106.** If  $\Sigma(g) = (s_0, s_1, \dots, s_n)$ , the value of  $g$  is 1 in  $s_0$  cases when  $x_0 = 1$  and in  $2^n - s_0$  cases when  $x_0 = 0$ . We also have  $\Sigma(f_0) + \Sigma(f_1) = (s_1, \dots, s_n)$ , and

$$\begin{aligned} \Sigma(f_0) &= \sum_{x_1=0}^1 \dots \sum_{x_n=0}^1 (\bar{x}_1, \dots, \bar{x}_n) g(0, \bar{x}_1, \dots, \bar{x}_n) \\ &= \sum_{x_1=0}^1 \dots \sum_{x_n=0}^1 ((1, \dots, 1) - (x_1, \dots, x_n)) (1 - g(1, x_1, \dots, x_n)) \\ &= (2^{n-1} - s_0, \dots, 2^{n-1} - s_0) + \Sigma(f_1). \end{aligned}$$

So the answers, for  $n > 0$ , are (a)  $N(f_0) = 2^n - s_0$ ,  $\Sigma(f_0) = \frac{1}{2}(s_1 - s_0 + 2^{n-1}, \dots, s_n - s_0 + 2^{n-1})$ ; (b)  $N(f_1) = s_0$ ,  $\Sigma(f_0) = \frac{1}{2}(s_1 + s_0 - 2^{n-1}, \dots, s_n + s_0 - 2^{n-1})$ . [Equivalent results were presented by E. Goto in lectures at MIT in 1963.]

**107.** (a)  $a_1 + \dots + a_k \geq b_1 + \dots + b_k$  if and only if  $k - a_1 - \dots - a_k \leq k - b_1 - \dots - b_k$ .

(b) Let  $\alpha^+ = (a_1, a_1 + a_2, \dots, a_1 + \dots + a_n)$ . Then the vector  $(c_1, \dots, c_n)$  obtained by componentwise minimization of  $\alpha^+$  and  $\beta^+$  is  $(\alpha \wedge \beta)^+$ . (Clearly  $c_j = c_{j-1} + 0$  or 1.)

(c) Proceed as in (b) but with componentwise *maximization*; or take  $\bar{\alpha} \wedge \bar{\beta}$ .

(d) True, because max and min satisfy these distributive laws. (In fact, we obtain a distributive *mixed-radix majorization lattice* in a similar way from the set of all  $n$ -tuples  $a_1 \dots a_n$  such that  $0 \leq a_j < m_j$  for  $1 \leq j \leq n$ .)



(e)  $\alpha 1$  covers  $\alpha 0$  and  $\alpha 10\beta$  covers  $\alpha 01\beta$ . [This characterization is due to R. O. Winder, *IEEE Trans.* **EC-14** (1965), 315–325, but he didn't prove the lattice property. The lattice is often called  $M(n)$ ; see B. Lindström, *Nordisk Mat. Tidskrift* **17** (1969), 61–70; R. P. Stanley, *SIAM J. Algebraic and Discrete Methods* **1** (1980), 177–179.]

(f) Because of (e) we have  $r(a) = na_1 + (n-1)a_2 + \cdots + a_n$ .

(g) The point is that  $0\beta \succeq 0\alpha$  if and only if  $\beta \succeq \alpha$  and that  $1\beta \succeq 0\alpha$  if and only if  $1\beta \succeq 10 \dots 0 \vee \alpha = 1\alpha'$ .

(h) That is, how many  $a_1 \dots a_n$  have the property that  $a_1 \dots a_k$  contains no more 1s than 0s? The answer is  $\binom{n}{\lfloor n/2 \rfloor}$ ; see, for example, exercise 2.2.1–4 or 7.2.1.6–42(a).

**108.** (a) If  $x \subseteq y$  then  $x \preceq y$ , hence  $f(x) \leq f(y)$ ; QED.

(b) No; a threshold function need not be monotone (see (79)). But we *can* show that  $f$  is regular if we also require  $w_n \geq 0$ : For if  $f(x) = 1$  and  $y$  covers  $x$  we then have  $w \cdot y \geq w \cdot x$ .

(c) Whenever  $f(x) = 1$  and  $x_j < x_{j+1}$ , we have  $f(y) = 1$  when  $y$  covers  $x$  with  $x_j \leftrightarrow x_{j+1}$ ; hence  $s_j \geq s_{j+1}$ . (This argument holds even when  $w_n < 0$ .)

(d) No; consider, for example,  $\langle x_1 x_2^2 x_3^2 \rangle$ , which equals  $\langle x_1 x_2 x_3 \rangle$ . Counterexamples can arise even when the weights minimize  $w_1 + \cdots + w_n$ , because the solution to the linear program in exercise 101 is not always unique. One such case, found by Muroga, Tsuboi, and Baugh, is  $\langle x_1^{17} x_2^9 x_3^8 x_4^6 x_5^7 x_6^5 x_7^3 x_8^2 x_9^2 \rangle$ , a function that is actually symmetric in  $x_4$  and  $x_5$ . But if  $s_j > s_{j+1}$  we must have  $w_j > w_{j+1}$ , because of (c).

**109.** (a) Find an optimum self-dual function  $f$  pointwise as in exercise 14; in case of ties, set  $f(x_1, \dots, x_n) = x_n$ . Then if  $f(x_1, \dots, x_{n-1}, 0) = 1$  but  $f(x_1, \dots, x_{n-1}, 1) = 0$ , we have  $ar_n < b$  and  $a > br_n$  for some  $a$  and  $b$ , contradicting the fact that  $r_n \geq 1$ . And if  $f(x_1, \dots, x_{j-2}, 0, 1, x_{j+1}, \dots, x_n) = 1$  but  $f(x_1, \dots, x_{j-2}, 1, 0, x_{j+1}, \dots, x_n) = 0$ , we have  $ar_j b > cr_{j-1} d$  and  $ar_{j-1} b < cr_j d$  for some  $(a, b, c, d)$ , contradicting  $r_{j-1} \geq r_j$ .

(b) Let  $p(x)$  be the vector  $(x_1 p_1 + \bar{x}_1 \bar{p}_1, \dots, x_n p_n + \bar{x}_n \bar{p}_n)$ , where  $\bar{p} = 1 - p$ . Then the availability function is  $F(p(x))$ .

If  $x \preceq x'$  we have  $F(p(x)) \leq F(p(x'))$ , by part (a). Now if  $x$  is any vector with  $f(x) = 1$ , we want to prove the optimality condition  $F(p(\bar{x})) \leq F(p(x))$ . There is a minimal  $y \preceq x$  such that  $f(y) = 1$ . And if we have verified that  $F(p(\bar{y})) \leq F(p(y))$ , then indeed  $F(p(\bar{x})) \leq F(p(\bar{y})) \leq F(p(y)) \leq F(p(x))$ . [H. Makino and T. Kameda, *SIAM Journal on Discrete Mathematics* **14** (2001), 381–407.]

For example, there are only seven self-dual regular Boolean functions when  $n = 5$ , generated by the following minimal elements in Fig. 6: 10000; 01111, 10001; 01110, 10010; 01101, 10011, 10100; 01100; 01011, 11000; 00111. So the optimum coterie can be found by examining only a few function values.

(c) Suppose  $p_n < \frac{1}{2}$ . If  $n = 1$ , the only possibility is  $f(x_1) = x_1$ . Otherwise  $F(p(x_1 \dots x_{n-1} 1)) < F(p(x_1 \dots x_{n-1} 0))$ , so we can prove that  $n$  is not in any optimum quorum: Let  $y = y_1 \dots y_{n-1}$  be minimal with  $f(y 1) = 1$ . We can assume that  $y \neq 0 \dots 0$ ; otherwise  $f(x) = x_n$ , and  $f(x) = x_1$  would be no worse. By minimality we have  $f(y 0) = 0$ ; hence, by self-duality,  $f(\bar{y} 1) = 1$ . But the optimum solution satisfies  $F(p(\bar{x})) \leq F(p(x))$  for all  $x$  with  $f(x) = 1$  (see exercise 68). So we have a contradiction:  $F(p(\bar{y} 1)) < F(p(\bar{y} 0)) \leq F(p(y 1)) < F(p(y 0)) \leq F(p(\bar{y} 1))$ .

Thus  $f(y 0) = 0$  for all  $y$ ; we can use the optimum coterie for  $\{1, \dots, n-1\}$ . [Y. Amir and A. Wool, *Information Processing Letters* **65** (1998), 223–228.]

**110.** (a) The leading terms are respectively 0,  $+xy$ ,  $-xy$ ,  $+x$ ,  $-xy$ ,  $+y$ ,  $-2xy$ ,  $-xy$ ,  $+xy$ ,  $+2xy$ ,  $-y$ ,  $+xy$ ,  $-x$ ,  $+xy$ ,  $-xy$ , 1; so  $F(f) = 1$  when  $f$  is  $\wedge, \sqcup, \sqcap, \nabla, \equiv, \subset, \supset, \top$ .

(b) The coefficient corresponding to exponents 01101, say, is  $f_{0**0*}$  in the notation of answer 12; it is a linear combination of truth table entries, always lying in the range  $-2^{k-1} \leq f_{0**0*} \leq 2^{k-1}$  when there are  $k$  asterisks. Thus the leading coefficient is positive if and only if the mixed-radix number

$$\begin{bmatrix} f_{****}, & f_{0****} & \dots, & f_{*0...0}, & f_{00...0} \\ 2^m+1, & 2^{m-1}+1, & \dots, & 2^1+1, & 2^0+1 \end{bmatrix}$$

is positive, where the  $f$ 's are arranged in reverse order of Chase's sequence and the radix  $2^k + 1$  corresponds to an  $f$  with  $k$  asterisks. For example, when  $m = 2$  we have  $F(f) = 1$  if and only if the sum  $18f_{**} + 6f_{0*} + 2f_{*0} + f_{00} = 18(f_{11} - f_{01} - f_{10} + f_{00}) + 6(f_{01} - f_{00}) + 2(f_{10} - f_{00}) + f_{00} = 18f_{11} - 12f_{01} - 16f_{10} + 11f_{00}$  is positive; so the threshold function can be written  $\langle f_{11}^{18} \bar{f}_{01}^{12} \bar{f}_{10}^{16} f_{00}^{11} \rangle$ .

(In this particular case the much simpler expression  $\langle f_{11}f_{11}\bar{f}_{01}\bar{f}_{10}f_{00} \rangle$  is actually valid. But part (c) will show that when  $m$  is large we can't do a great deal better.)

(c) Suppose  $F(f) = [\sum_{\alpha} v_{\alpha}(f_{\alpha} - \frac{1}{2}) > 0]$ , where the sum is over all  $2^m$  binary strings  $\alpha$  of length  $m$  and where each  $v_{\alpha}$  is an integer weight. Define

$$w_{\alpha} = \sum_{\beta} (-1)^{\nu(\alpha \dot{-} \beta)} v_{\beta} - 2^{m-1} [\alpha = 00 \dots 0] \quad \text{and} \quad F_{\alpha} = \sum_{\beta} (-1)^{\nu(\alpha \dot{-} \beta)} f_{\beta};$$

thus, for example,  $w_{01} = -v_{00} + v_{01} - v_{10} + v_{11}$  and  $F_{11} = f_{00} - f_{01} - f_{10} + f_{11}$ . One can show that  $F_{1^k 0^l} = 2^l f_{*^k 0^l}$ , if  $k > 0$  and if  $F_{\alpha} = 0$  whenever  $\nu(\alpha) > k$ ; therefore the signs of the transformed truth coefficients  $F_{\alpha}$  determine the sign of the leading coefficient in the multilinear representation. Furthermore, we now have  $F(f) = [\sum_{\alpha} w_{\alpha} F_{\alpha} > 0]$ .

The general idea of the proof is to choose test functions  $f$  from which we can derive properties of the transformed weights  $w_{\alpha}$ . For example, if  $f(x_1, \dots, x_m) = x_1 \oplus \dots \oplus x_k$ , we find  $F_{\alpha} = 0$  for all  $\alpha$  except that  $F_{1^k 0^{m-k}} = (-1)^{k-1} 2^{m-1}$ . The multilinear representation of  $x_1 \oplus \dots \oplus x_k$  has leading term  $(-2)^{k-1} x_1 \dots x_k$ ; hence we can conclude that  $w_{1^k 0^{m-k}} > 0$ , and in a similar way that  $w_{\alpha} > 0$  for all  $\alpha$ . In general if  $m$  changes to  $m+1$  but  $f$  does not depend on  $x_{m+1}$ , we have  $F_{\alpha 0} = 2F_{\alpha}$  and  $F_{\alpha 1} = 0$ .

The test function  $x_2 \oplus \dots \oplus x_m \oplus x_1 \bar{x}_2 \dots \bar{x}_m$  proves that

$$w_{1^m} > (2^{m-1} - 1)w_{01^{m-1}} + \sum_{k=1}^{m-1} w_{1^k 01^{m-1-k}} + \text{smaller terms},$$

where the smaller terms involve only  $w_{\alpha}$  with  $\nu(\alpha) \leq m-2$ . In particular,  $w_{11} > w_{01} + w_{10} + w_{00}$ . The test function  $x_1 \oplus \dots \oplus x_{m-1} \oplus \bar{x}_1 \dots \bar{x}_{m-2}(x_{m-1} \oplus \bar{x}_m)$  proves

$$w_{1^{m-2} 01} > (2^{m-2} - 1)w_{1^{m-2} 10} + \sum_{k=0}^{m-3} (w_{1^k 01^{m-3-k} 10} + w_{1^k 01^{m-3-k} 01}) + \text{smaller terms},$$

where the smaller terms this time have  $\nu(\alpha) \leq m-3$ . In particular,  $w_{101} > w_{110} + w_{010} + w_{001}$ . By permuting subscripts, we obtain similar inequalities leading to

$$w_{\alpha_{\alpha_j}} > (2^{\nu(\alpha_j)-1} - 1)w_{\alpha_{\alpha_j-1}} \quad \text{for } 0 < j < 2^m,$$

because the  $w$ 's begin to grow rapidly. But we have  $v_{\alpha} = \sum_{\beta} (-1)^{\nu(\beta \dot{-} \alpha)} w_{\beta} / n$ ; hence  $|v_{\alpha}| = w_{11\dots 1} / n + O(w_{11\dots 1} / n^2)$ . [SIAM J. Discrete Math. **7** (1994), 484–492. Important generalizations of this result have been obtained by N. Alon and V. H. Vū, J. Combinatorial Theory **A79** (1997), 133–160.]

**111.** The stated  $g_3$  is  $S_{2,3,6,8,9}$  because the stated  $g_2$  is  $S_{2,3,4,5,8,9,10,11,12}$ .

For the more difficult function  $S_{1,3,5,8}$ , let  $g_1 = [\nu x \geq 6]$ ;  $g_2 = [\nu x \geq 3]$ ;  $g_3 = [\nu x - 5g_1 - 2g_2 \geq 2] = S_{2,4,5,9,10,11,12}$ ;  $g_4 = [2\nu x - 15g_1 - 9g_3 \geq 1] = S_{1,3,5,8}$ . [See M. A. Fischler and M. Tannenbaum, *IEEE Transactions* **C-17** (1968), 273–279.]

**112.**  $[4x + 2y + z \in \{3, 6\}] = (\bar{x} \wedge y \wedge z) \vee (x \wedge y \wedge \bar{z})$ . In the same way, *any* Boolean function of  $n$  variables is a special case of a symmetric function of  $2^n - 1$  variables. [See W. H. Kautz, *IRE Transactions* **EC-10** (1961), 378.]

**113.** Both sides are self-dual, so we may assume that  $x_0 = 0$ . Then

$$s_j = [x_j + \cdots + x_{j+m-1} > x_{j+m} + \cdots + x_{j+2m-1}].$$

If  $x_1 + \cdots + x_{2m}$  is odd, we have  $s_j = \bar{s}_{j+m}$ ; hence  $s_1 + \cdots + s_{2m} = m$  and the result is 1. But if  $x_1 + \cdots + x_{2m}$  is even, the difference  $x_j + \cdots + x_{j+m-1} - x_{j+m} - \cdots - x_{j+2m-1}$  will be zero for at least one  $j \leq m$ ; that makes  $s_j = s_{j+m} = 0$ , so we will have  $s_1 + \cdots + s_{2m} < m$ .

**114.** (a) It's an implicant if and only if  $f(x) = 1$  whenever  $j \leq \nu x \leq n - k + j$ . It's a prime implicant if and only if we also have  $f(x) = 0$  when  $\nu x = j - 1$  or  $\nu x = n - k + j + 1$ .

(b) Consider the string  $v = v_0 v_1 \dots v_n$  such that  $f(x) = [v_{\nu x}]$ . By part (a), there are  $\binom{a+b+c}{a, b, c}$  prime implicants when  $v = 0^a 1^{b+1} 0^c$ . In the stated case,  $a = b = c = 3$ , so there are 1680 prime implicants.

(c) For a general symmetric function, we add together the prime implicants for each run of 1s in  $v$ . Clearly there are more for  $v = 0^{a+1} 1^{b+1} 0^{c-1}$  than for  $v = 0^a 1^{b+1} 0^c$  when  $a < c - 1$ ; so  $v$  contains no two consecutive 0s when the maximum is reached.

Let  $\hat{b}(m, n)$  be the maximum number of prime implicants possible when  $v_m = 1$  and  $v_j = 0$  for  $m < j \leq n$ . Then when  $m \leq \frac{1}{2}n$  we have

$$\begin{aligned} \hat{b}(m, n) &= \max_{0 \leq k \leq m} \left( \binom{n}{k, m-k, n-m} + \hat{b}(k-2, n) \right) \\ &= \binom{n}{\lceil m/2 \rceil, \lfloor m/2 \rfloor, n-m} + \hat{b}(\lceil m/2 \rceil - 2, n), \end{aligned}$$

with  $\hat{b}(-2, n) = \hat{b}(-1, n) = 0$ . And the overall maximum is

$$\hat{b}(n) = \binom{n}{n_0, n_1, n_2} + \hat{b}(n_1 - 1, n) + \hat{b}(n_2 - 1, n), \quad n_j = \left\lfloor \frac{n+j}{3} \right\rfloor.$$

In particular we have  $\hat{b}(9) = 1698$ , with the maximum occurring for  $v = 1101111011$ .

(d) By Stirling's approximation,  $\hat{b}(n) = 3^{n+3/2}/(2\pi n) + O(3^n/n^2)$ .

(e) In this case the appropriate recurrence for  $m < \lceil n/2 \rceil$  is

$$\begin{aligned} \tilde{b}(m, n) &= \max_{0 \leq k \leq m} \left( \binom{n}{k, m-k, n-m} + \binom{n}{k-1, 0, n-k+1} + \tilde{b}(k-2, n) \right) \\ &= \binom{n}{\lceil m/2 \rceil, \lfloor m/2 \rfloor, n-m} + \binom{n}{\lceil m/2 \rceil - 1} + \tilde{b}(\lceil m/2 \rceil - 2, n) \end{aligned}$$

and  $\tilde{b}(n) = \tilde{b}(\lceil n/2 \rceil - 1, n)$  maximizes  $\min(\text{prime implicants}(f), \text{prime implicants}(\bar{f}))$ . We have  $(\tilde{b}(1), \tilde{b}(2), \dots) = (1, 1, 4, 5, 21, 31, 113, 177, 766, 1271, 4687, 7999, 34412, \dots)$ ; for example,  $\tilde{b}(9) = 766$  corresponds to  $S_{0,2,3,4,8}(x_1, \dots, x_9)$ . Asymptotically,  $\tilde{b}(n) = 2^{(3n+3+(n \bmod 2))/2}/(2\pi n) + O(2^{3n/2}/n^2)$ .

*References:* *Summaries, Summer Inst. for Symbolic Logic* (Dept. of Math., Cornell Univ., 1957), 211–212; B. Dunham and R. Fridshal, *J. Symbolic Logic* **24** (1959), 17–19; A. P. Vikulin, *Problemy Kibernetiki* **29** (1974), 151–166, which reports on work done in 1960; Y. Igarashi, *Transactions of the IECE of Japan* **E62** (1979), 389–394.

**115.** The maximum number of subcubes of the  $n$ -cube, with none contained in another, is obtained when we choose all subcubes of dimension  $\lfloor n/3 \rfloor$ . (It is also obtained by choosing all subcubes of dimension  $\lfloor (n+1)/3 \rfloor$ ; for example, when  $n = 2$  we can choose either  $\{0*, 1*, *0, *1\}$  or  $\{00, 01, 10, 11\}$ .) Hence  $b^*(n) = \binom{n}{\lfloor n/3 \rfloor} 2^{n-\lfloor n/3 \rfloor} = 3^{n+1}/\sqrt{4\pi n} + O(3^n/n^{3/2})$ . [See the paper of Vikulin in the previous answer, pages 164–166; A. K. Chandra and G. Markowsky, *Discrete Math.* **24** (1978), 7–11; N. Metropolis and G. C. Rota, *SIAM J. Applied Math.* **35** (1978), 689–694.]

**116.** Several authors have conjectured that  $b(n) = \hat{b}(n)$ ; M. M. Gadzhiev has proved that equality holds for  $n \leq 6$  [*Diskretnyi Analiz* **18** (1971), 3–24].

**117.** (a) Every prime implicant is a minterm, since no adjacent points of the  $n$ -cube have the same parity. So the full disjunctive form is the only decent DNF in this case.

(b) Now all prime implicants consist of two adjacent points. We must include the 14 subcubes  $0^j * 0^{6-j}$  and  $1^j * 1^{6-j}$  for  $0 \leq j \leq 6$ , in order to cover the points with  $\nu x = 1$  and  $\nu x = 6$ . The other  $\binom{7}{3} + \binom{7}{4} = 70$  points can be covered by 35 well-chosen prime implicants (see, for example, exercise 6.5–1, or the “Christmas tree pattern” in Section 7.2.1.6). Thus the shortest DNF has length 49. [An ingeniously plausible but fallacious argument that 70 prime implicants are necessary was presented by S. B. Yablonsky in *Problemy Kibernetiki* **7** (1962), 229–230.]

(c) For each of  $2^{n-1}$  choices of  $(x_1, \dots, x_{n-1})$  we need at most one implicant to account for the behavior of the function with respect to  $x_n$ .

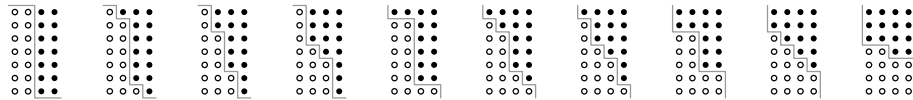
[Asymptotically, almost all Boolean functions of  $n$  variables have a shortest DNF with  $\Theta(2^n/(\log n \log \log n))$  prime implicants. See R. G. Nigmatullin, *Diskretnyi Analiz* **10** (1967), 69–89; V. V. Glagolev, *Problemy Kibernetiki* **19** (1967), 75–94; A. D. Korshunov, *Metody Diskretnogo Analiza* **37** (1981), 9–41; N. Pippenger, *Random Structures & Algorithms* **22** (2003), 161–186.]

**118.** (a) Let  $x = x_1 \dots x_m$  and  $y = y_1 \dots y_n$ . Since  $f$  is a function of  $(\nu x, \nu y)$ , there are altogether  $2^{(m+1)(n+1)}$  possibilities.

(b) In this case  $\nu x \leq \nu x'$  and  $\nu y \leq \nu y'$  implies  $f(x, y) \leq f(x', y')$ . Every such function corresponds to a zigzag path from  $a_0 = (-\frac{1}{2}, n + \frac{1}{2})$  to  $a_{m+n+2} = (m + \frac{1}{2}, -\frac{1}{2})$ , with  $a_j = a_{j-1} + (1, 0)$  or  $a_j = a_{j-1} - (0, 1)$  for  $1 \leq j \leq m+n+2$ ; we have  $f(x, y) = 1$  if and only if the point  $(\nu x, \nu y)$  lies above the path. So the number of possibilities is the number of such paths, namely  $\binom{m+n+2}{m+1}$ .

(c) Complementing  $x$  and  $y$  changes  $\nu x$  to  $m - \nu x$  and  $\nu y$  to  $n - \nu y$ . So there are no such functions when  $m$  and  $n$  are both even; otherwise there are  $2^{(m+1)(n+1)/2}$ .

(d) The path in (b) must now satisfy  $a_j + a_{m+n+2-j} = (m, n)$  for  $0 \leq j \leq m+n+2$ . Hence there are  $\binom{\lceil m/2 \rceil + \lceil n/2 \rceil}{\lceil m/2 \rceil} [m \text{ odd or } n \text{ odd}]$  such functions. For example, the ten cases when  $m = 3$  and  $n = 6$  are



**119.** A function of this kind is regular with the  $x$ 's to the left of the  $y$ 's if and only if the zigzag path does not contain two points  $(x, y)$  and  $(x+2, y)$  with  $0 < y < n$ ; it is regular with the  $y$ 's left of the  $x$ 's if and only if the zigzag path does not contain both  $(x, y+2)$  and  $(x, y)$  with  $0 < x < m$ . It is a threshold function if and only if there is a straight line through the point  $(m/2, n/2)$  with the property that  $(s, t)$  is above the line if and only if  $(s, t)$  is above the path, for  $0 \leq s \leq m$  and  $0 \leq t \leq n$ . So cases 5 and 8, illustrated in the previous answer, fail to be regular; cases 1, 2, 3, 7, 9, and 10

are threshold functions. The regular non-threshold functions that remain can also be expressed as follows:  $((x_1 \vee x_2 \vee x_3) \wedge \langle x_1 x_2 x_3 y_1 y_2 y_3 y_4 y_5 y_6 \rangle) \vee (x_1 \wedge x_2 \wedge x_3)$  (case 4);  $\langle 00 x_1 x_2 x_3 y_1 y_2 y_3 y_4 y_5 y_6 \rangle \vee (\langle x_1 x_2 x_3 \rangle \wedge \langle 11 x_1 x_2 x_3 y_1 y_2 y_3 y_4 y_5 y_6 \rangle)$  (case 6).

**120.** Self-dual regular functions are relatively easy to enumerate, but the numbers grow rapidly; when  $n = 9$  there are 319,124 of them, found by Muroga, Tsuboi, and Baugh in 1967. (The corresponding numbers for  $n \leq 6$  appear in Table 5, because all such functions are threshold functions when  $n < 9$ . There are 135 when  $n = 7$ , and 2470 when  $n = 8$ .) The threshold condition can be tested quickly for any such function by improving on the method of exercise 101, because constraints are needed only for the *minimal* vectors  $x$  (with respect to majorization) such that  $f(x) = 1$ .

**121.** The 222 equivalence classes listed in Table 5 include 24 classes of size  $2^{n+1}n! = 768$ ; so there are  $24 \times 768 = 18432$  answers to this problem. One of them is the function  $(x \wedge (y \vee z)) \vee (\bar{x} \wedge \bar{y} \wedge (w \oplus z))$ .

**122.**  $1; x; x \wedge y; x \wedge y \wedge z; x \wedge (y \vee z); x \wedge (y \oplus z)$ .

**123.** (a) The function is canalizing if and only if it has a prime implicant with at most one literal, or a prime clause with at most one literal.

(b) The function is canalizing if and only if at least one of the components of  $\Sigma(f)$  is equal to 0,  $2^{n-1}$ ,  $N(f)$ , or  $N(f) - 2^{n-1}$ . [See I. Shmulevich, H. Lähdesmäki, and K. Egiazarian, *IEEE Signal Processing Letters* **11** (2004), 289–292, Proposition 6.]

(c) If, say,  $\vee(f) = y_1 \dots y_n$  with  $y_j = 0$ , then  $f(x) = 0$  whenever  $x_j = 1$ . Therefore  $f$  is canalizing if and only if we don't have  $\vee(f) = \vee(\bar{f}) = 1 \dots 1$  and  $\wedge(f) = \wedge(\bar{f}) = 0 \dots 0$ . With this test one can prove that many functions are noncanalizing when their value is known at only a few points.

**124.** (a) Since a self-dual function  $f(x_1, \dots, x_n)$  is true at exactly  $2^{n-1}$  points, it is canalizing with respect to the variable  $x_j$  if and only if  $f(x_1, \dots, x_n) = x_j$ .

(b) A proper Horn function is clearly canalizing if (i) it contains any clause with a single literal, or (ii) some literal occurs in every clause. Otherwise it is not canalizing. For we have  $f(0, \dots, 0) = f(1, \dots, 1) = 1$ , because (i) is false; and if  $x_j$  is any variable, there is a clause  $C_0$  not containing  $\bar{x}_j$  and a clause  $C_1$  not containing  $x_j$ , because (ii) is false. By choosing appropriate values of the other variables, we can make  $C_0 \wedge C_1$  false when  $x_j = 0$  and also when  $x_j = 1$ .

**125.** For example,  $(x_1 \wedge \dots \wedge x_n) \vee (\bar{x}_1 \wedge \dots \wedge \bar{x}_n)$ .

**126.**  $\sum_{k=1}^n (-1)^{k+1} \binom{n}{k} 2^{2^{n-k}+k+1} - 2(n-1) - 4(n \bmod 2) = n2^{2^{n-1}+2} + O(n^2 2^{2^{n-2}})$ . [See W. Just, I. Shmulevich, and J. Konvalina, *Physica* **D197** (2004), 211–221.]

**127.** (a) If there are  $a_n$  functions of  $n$  or fewer variables, but  $b_n$  functions of exactly  $n$  variables, we have  $a_n = \sum_k \binom{n}{k} b_k$ . Therefore  $b_n = \sum_k (-1)^{n-k} \binom{n}{k} a_k$ . (This rule applies to all rows of Table 3, *except* for the case of symmetric functions.) In particular, the answer sought here is  $168 - 4 \cdot 20 + 6 \cdot 6 - 4 \cdot 3 + 2 = 114$ .

(b) If there are  $a'_n$  essentially distinct functions of  $n$  or fewer variables, and  $b'_n$  of exactly  $n$  variables, we have  $a'_n = \sum_{k=0}^n b'_k$ . Hence  $b'_n = a'_n - a'_{n-1}$ , and the answer in this case is  $30 - 10 = 20$ .

**128.** Let there be  $h(n)$  Horn functions and  $k(n)$  Krom functions. Clearly  $\lg h(n) \geq \binom{n}{\lfloor n/2 \rfloor}$  and  $\lg k(n) \geq \binom{n}{2}$ . V. B. Alekseyev [*Diskretnaia Matematika* **1** (1989), 129–136] has proved that  $\lg h(n) = \binom{n}{\lfloor n/2 \rfloor} (1 + O(n^{-1/4} \log n))$ . B. Bollobás, G. Brightwell, and I. Leader [*Israel J. Math.* **133** (2003), 45–60] have proved that  $\lg k(n) \sim \frac{1}{2}n^2$ .

**129.** Let  $p_k = 1/(2^{2^{n-k}} + 1)$ , so that  $\bar{p}_k = 2^{2^{n-k}}/(2^{2^{n-k}} + 1)$ . [Ph.D. thesis (MIT, 1994).]

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