

4- Chapter 7

(1)

7.3 a)

$$u = e^{x-2\sin y}$$

$$u_x = e^{x-2\sin y}, \quad u_{xy} = e^{x-2\sin y} (-2) \cos y$$

$$u_y = e^{x-2\sin y} (-2) \cos y \quad u_{yx} = e^{x-2\sin y} (-2) \cos y$$

$$u = 4x \sin x^3 y$$

$$u_x = 4 \sin x^3 y + 4x \cos x^3 y \cdot 3x^2 y$$

$$= 4 \sin x^3 y + 12x^3 y \cos x^3 y$$

$$u_y = 4x \cos x^3 y \cdot x^3 = 4x^4 \cos x^3 y$$

$$u_{yx} = 16x^3 \cos x^3 y + 4x^4 (-\sin x^3 y) \cdot 3x^2 y$$

$$= 16x^3 \cos x^3 y - 12x^6 y \sin x^3 y$$

$$u_{xy} = 4 \cos x^3 y \cdot x^3 + 12x^3 \cos x^3 y + 12x^3 y (-\sin x^3 y) \cdot x^3$$

$$= 16x^3 \cos x^3 y - 12x^6 y \sin x^3 y$$

$$b) \quad u(x, y) = \begin{cases} \frac{xy^3}{x^2 + y^2} & x, y \neq 0 \\ 0 & x = y = 0 \end{cases}$$

$$\begin{aligned} x, y \neq 0 \quad u_x(x, y) &= \frac{y^3(x^2 + y^2) - xy^3 \cdot 2x}{(x^2 + y^2)^2} = \frac{x^2 y^3 + y^5 - 2x^2 y^3}{(x^2 + y^2)^2} \\ &= \frac{-x^2 y^3 + y^5}{(x^2 + y^2)^2} \end{aligned}$$

$$u_x(0, 0) = \lim_{t \rightarrow 0} \frac{1}{t} \left(\frac{t \cdot 0}{t^2 + 0} - 0 \right) = 0$$

$$\begin{aligned} \text{So. } u_{xy}(0, 0) &= \lim_{t \rightarrow 0} \frac{1}{t} (u_x(0, t) - u_x(0, 0)) \\ &= \lim_{t \rightarrow 0} \frac{1}{t} \left(\frac{-t^5}{t^4} - 0 \right) = -1 \end{aligned}$$

$$\begin{aligned}
 (x, y) \neq (0, 0) \quad u_y(x, y) &= \frac{3xy^2(x^2+y^2) - xy^3 \cdot 2y}{(x^2+y^2)^2} \\
 &= \frac{3x^3y^2 + 3xy^4 - 2xy^4}{(x^2+y^2)^2} \\
 &= \frac{3x^3y^2 + xy^4}{(x^2+y^2)^2}
 \end{aligned}$$

$$\begin{aligned}
 (x, y) = (0, 0) \quad u_y(0, 0) &= \lim_{t \rightarrow 0} \frac{1}{t} (u(0, t) - u(0, 0)) \\
 &= \lim_{t \rightarrow 0} \frac{1}{t} (0 - 0) = 0
 \end{aligned}$$

$$\begin{aligned}
 u_{yx}(0, 0) &= \lim_{t \rightarrow 0} \frac{1}{t} (u_y(t, 0) - u_y(0, 0)) \\
 &= \lim_{t \rightarrow 0} \frac{1}{t} (0 - 0) = 0
 \end{aligned}$$

The point: In this case $u_{xy}(0, 0) \neq u_{yx}(0, 0)$!

$$7.5 \quad u(x, t) = f(x+at) + g(x-at)$$

$$\begin{aligned}
 f &= f(y) \\
 g &= g(y)
 \end{aligned}$$

$$\frac{\partial u}{\partial x}(x, t) = \frac{\partial f}{\partial y}(x+at) + \frac{\partial g}{\partial y}(x-at)$$

$$\frac{\partial^2 u}{\partial x^2}(x, t) = \frac{\partial^2 f}{\partial y^2}(x+at) + \frac{\partial^2 g}{\partial y^2}(x-at)$$

$$\frac{\partial u}{\partial t}(x, t) = \frac{\partial f}{\partial y}(x+at) \cdot a + \frac{\partial g}{\partial y}(x-at) \cdot (-a)$$

$$\frac{\partial^2 u}{\partial t^2}(x, t) = \frac{\partial^2 f}{\partial y^2}(x+at) \cdot a^2 + \frac{\partial^2 g}{\partial y^2}(x-at) \cdot a^2$$

compare

*

7.7

a)

$$\begin{aligned}
 f(\lambda x, \lambda y) &= (\lambda x)^2 + 3(\lambda x)(\lambda y) = \lambda^2 [x^2 + 3xy] \\
 &= \lambda^2 f(x, y) \\
 &\quad \underline{\text{yes, } k=2}
 \end{aligned}$$

$$\begin{aligned}
 f(\lambda x, \lambda y) &= \ln((\lambda x)^2 + (\lambda y)^2) = \ln(\lambda^2(x^2 + y^2)) \\
 &= \ln \lambda^2 + \ln(x^2 + y^2) \neq \lambda^k \ln(x^2 + y^2) \quad \neq k \\
 &\quad \underline{\text{no}}
 \end{aligned}$$

$$\begin{aligned}
 f(\lambda x, \lambda y) &= ((\lambda x)^2 - (\lambda x)(\lambda y)) / (2\lambda x + \lambda y) \\
 &= \lambda \frac{x^2 - xy}{2x + y} = \lambda f(x, y) \\
 &\quad \underline{\text{yes, } k=1}
 \end{aligned}$$

$$\begin{aligned}
 f(\lambda x, \lambda y) &= (\lambda x)^2 e^{\frac{\lambda x}{2\lambda y}} = \lambda^2 x^2 e^{\frac{x}{2y}} = \lambda^2 f(x, y) \\
 &\quad \underline{\text{yes, } k=2}
 \end{aligned}$$

$$b) \quad f(\lambda x, \lambda y, \lambda z) = \lambda^k f(x, y, z) / \frac{\partial}{\partial x}$$

$$\lambda \frac{\partial f}{\partial x}(\lambda x, \lambda y, \lambda z) = \lambda^k \frac{\partial f}{\partial x}(x, y, z) / \lambda$$

$$\frac{\partial f}{\partial x}(\lambda x, \lambda y, \lambda z) = \lambda^{k-1} \frac{\partial f}{\partial x}(x, y, z)$$

$$c) \quad f(\lambda x_1, \lambda x_2, \dots, \lambda x_n) = \lambda^k f(x_1, x_2, \dots, x_n) / \frac{\partial}{\partial \lambda} \quad k \geq 1$$

$$\sum_{i=1}^n \frac{\partial f}{\partial x_i}(\lambda x_1, \dots, \lambda x_n) \cdot x_i = k \lambda^{k-1} f(x_1, x_2, \dots, x_n)$$

$$\text{Set } \lambda=1 \quad \sum_{i=1}^n \frac{\partial f}{\partial x_i}(x_1, \dots, x_n) \cdot x_i = k f(x_1, \dots, x_n)$$

$$d) f(x, y) = \sqrt{x^4 + y^4} \sin^{-1} \frac{y}{2x}$$

$$f(\lambda x, \lambda y) = \sqrt{(\lambda x)^4 + (\lambda y)^4} \sin^{-1} \frac{\lambda y}{2 \lambda x}$$

$$= \lambda^2 f(x, y) \quad K=2$$

$$\frac{\partial f}{\partial x} = \frac{1}{2\sqrt{x^4+y^4}} 4x^3 \sin^{-1} \frac{y}{2x} + \sqrt{x^4+y^4} \frac{1}{\sqrt{1-\left(\frac{y}{2x}\right)^2}} \left(-\frac{y}{2x^2}\right)$$

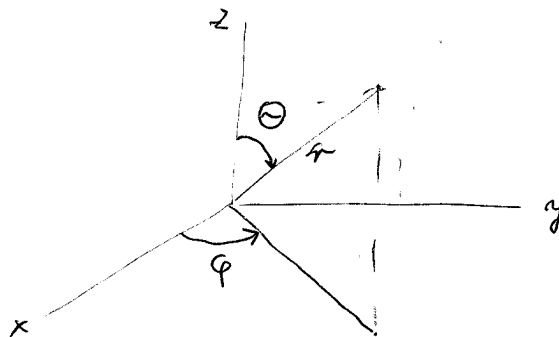
$$\frac{\partial f}{\partial y} = \frac{1}{2\sqrt{x^4+y^4}} 4y^3 \sin^{-1} \frac{y}{2x} + \sqrt{x^4+y^4} \frac{1}{\sqrt{1-\left(\frac{y}{2x}\right)^2}} \frac{1}{2x}$$

$$\begin{aligned} \frac{\partial f}{\partial x} x + \frac{\partial f}{\partial y} y &= \frac{1}{2\sqrt{x^4+y^4}} 4(x^4+y^4) \sin^{-1} \frac{y}{2x} \\ &\quad + \sqrt{x^4+y^4} \frac{2x}{\sqrt{4x^2-y^2}} \left(\frac{y}{2x} - \frac{y}{2x} \right) \\ &= 2 \sqrt{x^4+y^4} \sin^{-1} \frac{y}{2x} = 2 f(x, y) \end{aligned}$$

✱

7.11

$$\begin{cases} x = r \sin \theta \cos \varphi \\ y = r \sin \theta \sin \varphi \\ z = r \cos \theta \end{cases}$$



$$f = f(x(r, \theta, \varphi), y(r, \theta, \varphi), z(r, \theta, \varphi))$$

$$\begin{aligned} \frac{\partial f}{\partial r} &= \frac{\partial f}{\partial x} \frac{\partial x}{\partial r} + \frac{\partial f}{\partial y} \frac{\partial y}{\partial r} + \frac{\partial f}{\partial z} \frac{\partial z}{\partial r} \\ &= \nabla f \cdot \frac{\partial \underline{x}}{\partial r} \end{aligned}$$

Similarly

$$\frac{\partial f}{\partial \theta} = \nabla f \cdot \frac{\partial \underline{x}}{\partial \theta}, \quad \frac{\partial f}{\partial \varphi} = \nabla f \cdot \frac{\partial \underline{x}}{\partial \varphi}$$

where

$$\frac{\partial \underline{x}}{\partial r} = (\sin \theta \cos \varphi, \sin \theta \sin \varphi, \cos \theta)$$

$$\frac{\partial \underline{x}}{\partial \theta} = (r \cos \theta \cos \varphi, r \cos \theta \sin \varphi, -r \sin \theta)$$

$$\frac{\partial \underline{x}}{\partial \varphi} = (-r \sin \theta \sin \varphi, r \sin \theta \cos \varphi, 0)$$

Note that the three vectors are orthogonal!

Representing ∇f in the form

$$\nabla f = A \frac{\partial x}{\partial r} + B \frac{\partial x}{\partial \theta} + C \frac{\partial x}{\partial \varphi} \quad (*)$$

we get A, B, C by multiplying $(*)$ (in the scalar sense) by vectors $\frac{\partial x}{\partial r}, \frac{\partial x}{\partial \theta}, \frac{\partial x}{\partial \varphi}$ resp.

$$\frac{\partial f}{\partial r} = A \frac{\partial x}{\partial r} \cdot \frac{\partial x}{\partial r} = A \cdot 1 \Rightarrow A = \frac{\partial f}{\partial r}$$

$$\frac{\partial f}{\partial \theta} = B \frac{\partial x}{\partial \theta} \cdot \frac{\partial x}{\partial \theta} = B r^2 \Rightarrow B = \frac{1}{r^2} \frac{\partial f}{\partial \theta}$$

$$\frac{\partial f}{\partial \varphi} = C \frac{\partial x}{\partial \varphi} \cdot \frac{\partial x}{\partial \varphi} = C r^2 \sin^2 \theta \Rightarrow C = \frac{1}{r^2 \sin^2 \theta} \frac{\partial f}{\partial \varphi}$$

or switching to the unit vectors, we can write

$$\nabla f = \frac{\partial f}{\partial r} \underline{u}_r + \frac{1}{r} \frac{\partial f}{\partial \theta} \underline{u}_\theta + \frac{1}{r \sin \theta} \frac{\partial f}{\partial \varphi} \underline{u}_\varphi$$

where $\underline{u}_r = \frac{\partial x}{\partial r} = (\sin \theta \cos \varphi, \sin \theta \sin \varphi, \cos \theta)$

$$\underline{u}_\theta = (\cos \theta \cos \varphi, \cos \theta \sin \varphi, -\sin \theta)$$

$$\underline{u}_\varphi = (-\sin \varphi, \cos \varphi, 0)$$

Laplacien : (compare page 159)

$$\Delta f = \nabla^2 f = \nabla \cdot (\nabla f)$$

$$= \left(\frac{\partial}{\partial r} u_r + \frac{1}{r} \frac{\partial}{\partial \theta} u_\theta + \frac{1}{r \sin \theta} \frac{\partial}{\partial \varphi} u_\varphi \right) \cdot \left(\frac{\partial f}{\partial r} u_r + \frac{1}{r} \frac{\partial f}{\partial \theta} u_\theta + \frac{1}{r \sin \theta} \frac{\partial f}{\partial \varphi} u_\varphi \right)$$

$$\begin{aligned} \frac{\partial}{\partial r} (\nabla f) &= \frac{\partial^2 f}{\partial r^2} u_r + \cancel{\frac{\partial f}{\partial r} \frac{\partial u_r}{\partial r}} \\ &\quad - \frac{1}{r^2} \frac{\partial f}{\partial \theta} u_\theta + \frac{1}{r} \frac{\partial^2 f}{\partial r \partial \theta} u_\theta + \cancel{\frac{1}{r} \frac{\partial f}{\partial \theta} \frac{\partial u_\theta}{\partial r}} \\ &\quad - \frac{1}{r^2 \sin^2 \theta} \frac{\partial f}{\partial \varphi} u_\varphi + \frac{1}{r \sin \theta} \frac{\partial^2 f}{\partial r \partial \varphi} u_\varphi + \frac{1}{r \sin \theta} \frac{\partial f}{\partial \varphi} \cancel{\frac{\partial u_\varphi}{\partial r}} \end{aligned}$$

$$\frac{\partial}{\partial r} (\nabla f) \cdot u_r = \frac{\partial^2 f}{\partial r^2}$$

$$\begin{aligned} \frac{\partial}{\partial \theta} (\nabla f) &= \frac{\partial^2 f}{\partial \theta \partial r} u_r + \cancel{\frac{\partial f}{\partial r} \frac{\partial u_r}{\partial \theta}} u_\theta \\ &\quad + \frac{1}{r} \frac{\partial^2 f}{\partial \theta^2} u_\theta + \frac{1}{r} \frac{\partial f}{\partial \theta} \cancel{\frac{\partial u_\theta}{\partial \theta}} - u_r \\ &\quad - \frac{1}{r \sin^2 \theta} \cos \theta \frac{\partial f}{\partial \varphi} u_\varphi + \frac{1}{r \sin \theta} \frac{\partial^2 f}{\partial \theta \partial \varphi} u_\varphi + \frac{1}{r \sin \theta} \frac{\partial f}{\partial \varphi} \cancel{\frac{\partial u_\varphi}{\partial \theta}} \end{aligned}$$

$$\frac{\partial u_r}{\partial \theta} = (\cos \theta \cos \varphi, \cos \theta \sin \varphi, -\sin \theta) = u_\theta$$

$$\frac{\partial u_\varphi}{\partial \theta} = 0 \quad \frac{\partial u_\theta}{\partial \theta} = -u_r$$

$$\frac{\partial}{\partial \theta} (\nabla f) \cdot u_\theta = \frac{\partial f}{\partial r} + \frac{1}{r} \frac{\partial^2 f}{\partial \theta^2}$$

$$\begin{aligned} \frac{\partial}{\partial \varphi} (\nabla f) &= \frac{\partial^2 f}{\partial \varphi \partial r} u_r + \frac{\partial f}{\partial r} \left(\frac{\partial u_r}{\partial \varphi} \right) \\ &\quad + \frac{1}{r} \frac{\partial^2 f}{\partial \varphi \partial \theta} u_\theta + \frac{1}{r} \frac{\partial f}{\partial \theta} \frac{\partial u_\theta}{\partial \varphi} \\ &\quad + \frac{1}{r \sin \theta} \frac{\partial^2 f}{\partial \varphi^2} u_\varphi + \frac{1}{r \sin \theta} \frac{\partial f}{\partial \varphi} \frac{\partial u_\varphi}{\partial \varphi} \end{aligned}$$

$$\frac{\partial \underline{u}_r}{\partial \varphi} = (-\sin \theta \sin \varphi, \sin \theta \cos \varphi, 0) = \sin \theta \underline{u}_\varphi$$

$$\frac{\partial \underline{u}_\theta}{\partial \varphi} = (-\cos \theta \sin \varphi, \cos \theta \cos \varphi, 0) = \cos \theta \underline{u}_\varphi$$

$$\frac{\partial \underline{u}_\varphi}{\partial \varphi} = (-\cos \varphi, -\sin \varphi, 0) = -\sin \theta \underline{u}_r - \cos \theta \underline{u}_\theta$$

$$\frac{\partial}{\partial \varphi} (\nabla f) \cdot \underline{u}_\varphi = \frac{\partial f}{\partial r} \sin \theta + \frac{1}{r} \frac{\partial f}{\partial \theta} \cos \theta + \frac{1}{r \sin \theta} \frac{\partial^2 f}{\partial \varphi^2}$$

Summing up :

$$\begin{aligned} \Delta f &= \frac{\partial^2 f}{\partial r^2} + \frac{1}{r} \frac{\partial f}{\partial r} + \frac{1}{r^2} \frac{\partial^2 f}{\partial \theta^2} + \frac{1}{r \sin \theta} \left(\frac{\partial f}{\partial r} \sin \theta + \frac{1}{r} \frac{\partial f}{\partial \theta} \cos \theta \right. \\ &\quad \left. + \frac{1}{r \sin \theta} \frac{\partial^2 f}{\partial \varphi^2} \right) \\ &= \frac{\partial^2 f}{\partial r^2} + \frac{2}{r} \frac{\partial f}{\partial r} + \frac{1}{r^2} \frac{\partial^2 f}{\partial \theta^2} + \frac{1}{r^2} \cot \theta \frac{\partial f}{\partial \theta} + \frac{1}{r^2 \sin^2 \theta} \frac{\partial^2 f}{\partial \varphi^2} \end{aligned}$$

Checking with the formula in the book.

$$\begin{aligned} &\frac{1}{r^2 \sin \theta} \left[\frac{\partial}{\partial r} (r^2 \sin \theta \frac{\partial u}{\partial r}) + \frac{\partial}{\partial \theta} (\sin \theta \frac{\partial u}{\partial \theta}) + \frac{\partial}{\partial \varphi} (\frac{1}{\sin \theta} \frac{\partial u}{\partial \varphi}) \right] \\ &= \frac{1}{r^2 \sin \theta} \left[\cancel{2r \sin \theta} \frac{\partial u}{\partial r} + \cancel{r^2 \sin \theta} \frac{\partial^2 u}{\partial r^2} + \cancel{\cos \theta} \frac{\partial u}{\partial \theta} + \cancel{\sin \theta} \frac{\partial^2 u}{\partial \theta^2} + \frac{1}{\sin \theta} \frac{\partial^2 u}{\partial \varphi^2} \right] \\ &= \frac{\partial^2 u}{\partial r^2} + \frac{2}{r} \frac{\partial u}{\partial r} + \frac{\cot \theta}{r^2} \frac{\partial u}{\partial \theta} + \frac{1}{r^2} \frac{\partial^2 u}{\partial \theta^2} + \frac{1}{r^2 \sin^2 \theta} \frac{\partial^2 u}{\partial \varphi^2} \end{aligned}$$

Ok.

$$f(x, y, z) = 0$$

$$\cdot y = y(x, z) \Rightarrow f(x, y(x, z), z) \Big/ \frac{\partial}{\partial x} \\ f_x + f_y \frac{\partial y}{\partial x} = 0$$

$$\therefore \frac{\partial y}{\partial x} = - \frac{f_x}{f_y}$$

$$\cdot \text{ similarly } \frac{\partial x}{\partial y} = - \frac{f_y}{f_x}, \text{ so } \frac{\partial x}{\partial y} \frac{\partial y}{\partial x} = 1$$

$$\cdot \frac{\partial x}{\partial y} \frac{\partial y}{\partial z} \frac{\partial z}{\partial x} = \left(-\frac{f_y}{f_x}\right) \left(-\frac{f_z}{f_y}\right) \left(-\frac{f_x}{f_z}\right) = -1$$

✖

7.16

$$a) f(x, y) = \sin(x+y) \quad f(0, 0) = 0$$

$$\frac{\partial f}{\partial x}(x, y) = \cos(x+y) \quad \frac{\partial f}{\partial x}(0, 0) = 1$$

$$\frac{\partial f}{\partial y}(x, y) = \cos(x+y) \quad \frac{\partial f}{\partial y}(0, 0) = 1$$

$$\frac{\partial^2 f}{\partial x^2}(x, y) = -\sin(x+y) \quad \frac{\partial^2 f}{\partial x^2}(0, 0) = 0$$

$$\frac{\partial^2 f}{\partial y^2}(x, y) = -\sin(x+y) \quad \frac{\partial^2 f}{\partial y^2}(0, 0) = 0$$

$$\frac{\partial^2 f}{\partial x \partial y}(x, y) = -\sin(x+y) \quad \frac{\partial^2 f}{\partial x \partial y}(0, 0) = 0$$

All third order derivatives = $-\cos(x+y)$, at $(0, 0)$, = -1

$$\text{so: } \sin(x+y) = x+y + \frac{1}{6} [x^3 + 3x^2y + 3xy^2 + y^3] + \dots$$

$$= (x+y) + \frac{1}{6} (x+y)^3 + \dots$$

the same result can be obtained by expanding $\sin t$ (around 0) and then substituting $t = x+y$ ✖

7.16 b)

$$\sin(x+y+z^2) \quad (x_0, y_0, z_0) = (0, 0, 1)$$

$$a = x - x_0, b = y - y_0, z = z - z_0$$

$$\begin{cases} x = x_0 + at \\ y = y_0 + bt \\ z = z_0 + ct \end{cases}$$

$$\varphi(t) = \sin(x_0 + at + y_0 + bt + (z_0 + ct)^2)$$

$$\varphi'(t) = \cos(\quad) [a + b + 2(z_0 + ct)c]$$

$$\varphi''(t) = -\sin(\quad) [a + b + 2(z_0 + ct)c]^2 + \cos(\quad) \cdot 2c^2$$

$$\varphi(0) = \sin(x_0 + y_0 + z_0^2) = \sin 1$$

$$\varphi'(0) = \cos 1 [a + b + 2c]$$

$$\varphi''(0) = -\sin 1 [a + b + 2c]^2 + \cos 1 \cdot 2c^2$$

$$\varphi(1) = \varphi(0) + \varphi'(0) + \frac{\varphi''(0)}{2} + \dots$$

$$\sin(x+y+z^2) = \sin 1 + \cos 1 [x+y+2(z-1)]$$

$$- \frac{1}{2} \sin 1 [x+y+2(z-1)]^2 + \frac{\cos 1}{2} 2(z-1)^2 + \dots$$

✱

7.20

$$(y-1)e^y = \sqrt{x} - 1 \quad / ()' \quad (1)$$

$$y'e^y + (y-1)e^y y' = \frac{1}{2\sqrt{x}}$$

$$y'e^y(x+y-1) = \frac{1}{2\sqrt{x}} \quad (2)$$

$$y' = \frac{1}{2\sqrt{x} y e^y}$$

Differentiating (2)

$$y'e^y y + y'e^y y' y + y'e^y y' = -\frac{1}{4} x^{-\frac{3}{2}}$$

$$y'' = \frac{-1}{e^y y} \left(\frac{1}{4} x^{-\frac{3}{2}} + (y')^2 e^y (y+1) \right) \quad (3)$$

Select, say, $x=1$

From (1) $y=1$

From (2) $y' = \frac{1}{2 \cdot 1 e} = \frac{1}{2e}$

From (3) $y'' = \frac{-1}{e} \left(\frac{1}{4} + \frac{1}{4e} \cdot 2 \right)$
 $= -\frac{1}{e} \left(\frac{1}{4} + \frac{1}{2e} \right)$

$$= -\frac{1}{e} \left(\frac{e+2}{4e} \right) = -\frac{e+2}{4+e^2}$$

So: $y = 1 + \frac{1}{2e} (x-1) - \frac{e+2}{2(4+e^2)} (x-1)^2 + O((x-1)^3)$

#

7.2.3

$$\begin{cases} Au_x + Bu_y + Cv_x + Dv_y = 0 \\ Eu_x + Fu_y + Gv_x + Hv_y = 0 \end{cases}$$

$$A = A(u, v), \dots, H = H(u, v)$$

$$\begin{cases} u(x(u, v), y(u, v)) = u & (1) \\ v(x(u, v), y(u, v)) = v & (2) \end{cases}$$

Differentiating (1) wrt u and v we get

$$\begin{cases} u_x x_u + u_y y_u = 1 \\ u_x x_v + u_y y_v = 0 \end{cases}$$

$$\begin{pmatrix} x_u & y_u \\ x_v & y_v \end{pmatrix} \begin{pmatrix} u_x \\ u_y \end{pmatrix} = \begin{pmatrix} 1 \\ 0 \end{pmatrix}$$

$$u_x = \frac{y_v}{x_u y_v - y_u x_v} = y_v \cdot J, \text{ where } J^{-1} = (x_u y_v - y_u x_v)$$

$$u_y = -x_v J$$

Similarly, differentiating (2) wrt u and v we get

$$\begin{cases} v_x x_u + v_y y_u = 0 \\ v_x x_v + v_y y_v = 1 \end{cases} \quad \text{or} \quad \begin{pmatrix} x_u & y_u \\ x_v & y_v \end{pmatrix} \begin{pmatrix} v_x \\ v_y \end{pmatrix} = \begin{pmatrix} 0 \\ 1 \end{pmatrix}$$

$$\text{So: } v_x = -y_u J, \quad v_y = x_u J$$

Now

$$u_x v_y - u_y v_x = J^2 (y_v x_u - x_v y_u) = J, \text{ i.e.}$$

$$J = u_x v_y - u_y v_x$$

Substituting formulas for u_x, \dots, v_y into the original equations and multiplying by J we get the result required. #