

Numerical Treatment of Differential Equations: Homework 4

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Problem 1

Compute the domain of linear stability for the RK2 scheme:

$$y_{n+1} = y_n + \frac{h}{2} [f(t_n, y_n) + f(t_{n+1}, y_n + hf(t_n, y_n))] .$$

Solution

First we write out the tableau for this method:

$$\begin{array}{c|c} \mathbf{c} & A \\ \hline & \mathbf{b}^T \end{array} = \begin{array}{c|cc} & 0 & 0 \\ 1 & 1 & 0 \\ \hline & \frac{1}{2} & \frac{1}{2} \end{array} .$$

Now

$$\begin{aligned} p(z) &= 1 + z\mathbf{b}^T(\mathbf{I} - z\mathbf{A})^{-1}\mathbf{1} \\ &= 1 + z\mathbf{b}^T \begin{pmatrix} 1 & 0 \\ -z & 1 \end{pmatrix}^{-1} \mathbf{1} \\ &= 1 + z \begin{pmatrix} \frac{1}{2} & \frac{1}{2} \end{pmatrix} \begin{pmatrix} 1 & 0 \\ z & 1 \end{pmatrix} \begin{pmatrix} 1 \\ 1 \end{pmatrix} \\ &= 1 + z + \frac{1}{2}z^2 . \end{aligned}$$

Now we wish to find

$$|p(z)| = \left| 1 + z + \frac{1}{2}z^2 \right| < 1.$$

Using Mathematica, we were able to plot this region as shown in Figure 1.

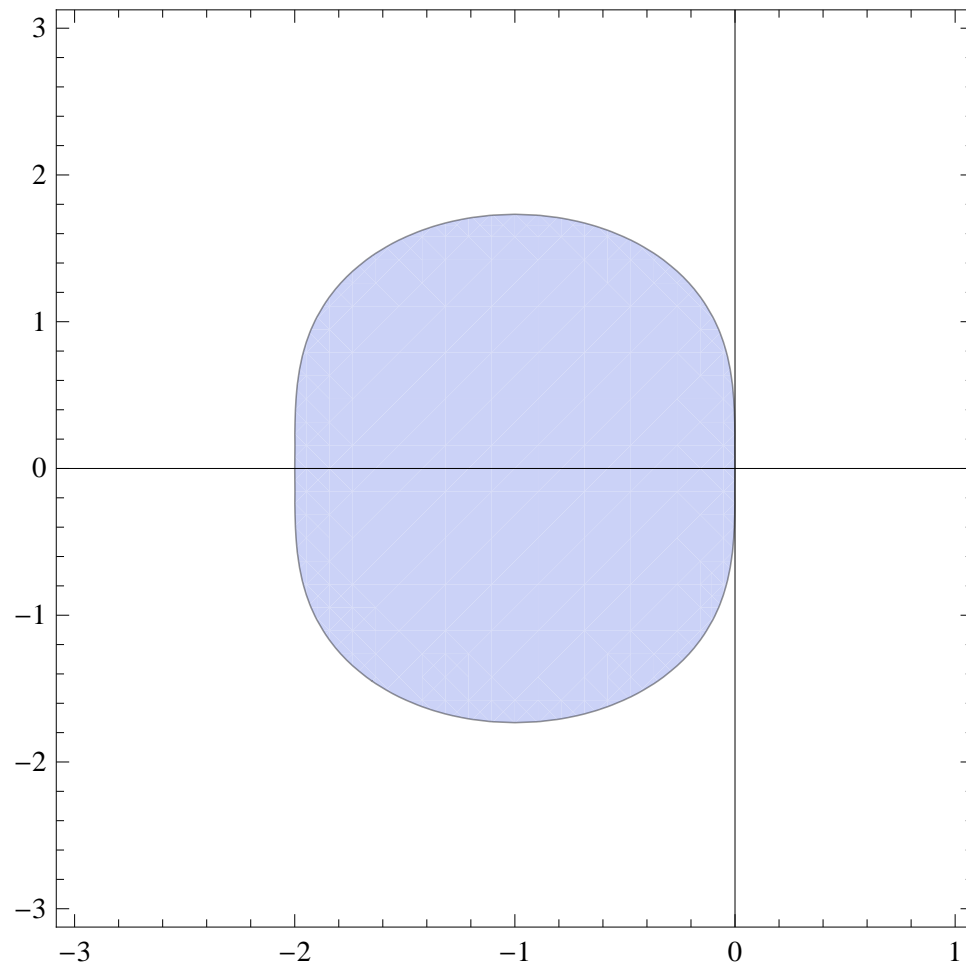


Figure 1: Domain of linear stability is the interior of the plotted region

Problem 2

Part a

(i) For $0 \leq t \leq 1$ and $h = 0.1$, the Euler method produced a log error of $8.8499e + 00$ while the backward Euler method only produced a log error of $-4.0362e + 00$.

(ii) For $0 \leq t \leq 10$ and $h = 0.01$, the Euler method produced a log error of $-6.2941e + 00$ while the backward Euler method only produced a log error of $-6.3025e + 00$.

The stiffness ratio for this system is 100. By a simple linear stability analysis of the Euler method, we discover that a time step $0 < h < 0.2$ is necessary for stability. Indeed we see this prediction manifested in the results. With a timestep of 0.1, the Euler method diverges radically from the exact solution. When we reduce the time step to the acceptable range, we see dramatic improvement in the error.

The backward Euler method on the other hand carries no timestep restrictions for stability and we readily see this in our results. We are able to get somewhat reasonable results for even the larger timestep.

Part b

(i) For $h = 0.05$, the Euler method produced a log error of $5.1083e - 01$ while the backward Euler only produced a log error of $-3.6031e - 01$.

(ii) For $h = 0.2$, the Euler method produced a log error of $1.6608e + 01$ while the backward Euler only produced a log error of $5.1083e - 01$.

We will be able to study the stability properties of this problem more easily if we linearize it:

$$\begin{aligned}\mathbf{y}' &= \begin{pmatrix} -y_1^2 \\ -y_1 y_2 \end{pmatrix} = \mathbf{f}(\mathbf{y}) \\ &\approx \mathbf{f}(\mathbf{y}_0) + \nabla \mathbf{f}(\mathbf{y}_0)(\mathbf{y} - \mathbf{y}_0) \\ &= \begin{pmatrix} -100 \\ -100 \end{pmatrix} + \begin{pmatrix} -20 & 0 \\ -10 & -10 \end{pmatrix} \begin{pmatrix} y_1 - 10 \\ y_2 - 10 \end{pmatrix}.\end{aligned}$$

Now we can see that the linearized system has eigenvalues 10 and 20. By a linear stability analysis, the Euler method needs a timestep $0 < h < 0.1$. The numerical experiment bears this out. The solution quickly becomes unstable for $h = 0.2$, but we get a reasonable error level when we reduce the timestep to $h = 0.05$. Similarly as before, the backward Euler method has no stability bounds on the timestep and we are able to get reasonable solutions with both timestep sizes.