



CHAPTER 3 - MEMORY MANAGEMENT

- Basic memory management
- Swapping
- Virtual memory
- Design issues for paging systems
- Implementation issues
- Segmentation



Memory Management

➤ Ideally programmers want memory that is

- large
- fast
- non volatile

➤ Memory hierarchy

- small amount of fast, expensive memory – cache
- some medium-speed, medium price main memory
- gigabytes of slow, cheap disk storage

➤ Memory manager handles the memory hierarchy



Basic Memory Management

Logical vs. Physical Address Space

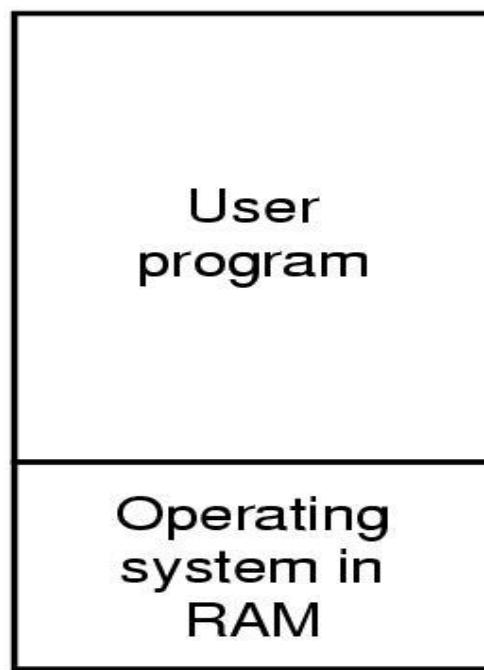
- The concept of a logical address space that is bound to a separate **physical address space** is central to proper memory management
 - **Logical address** – generated by the CPU; also referred to as **virtual address**
 - **Physical address** – address seen by the memory unit

Basic Memory Management

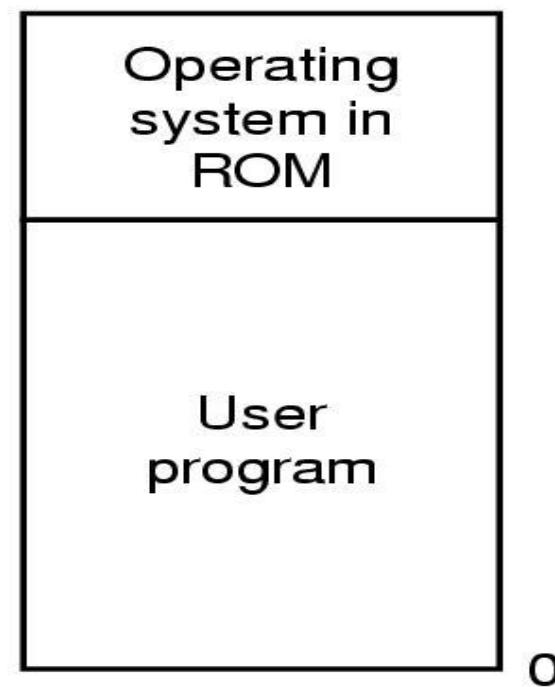
Monoprogramming without Swapping or Paging

Three simple ways of organizing memory

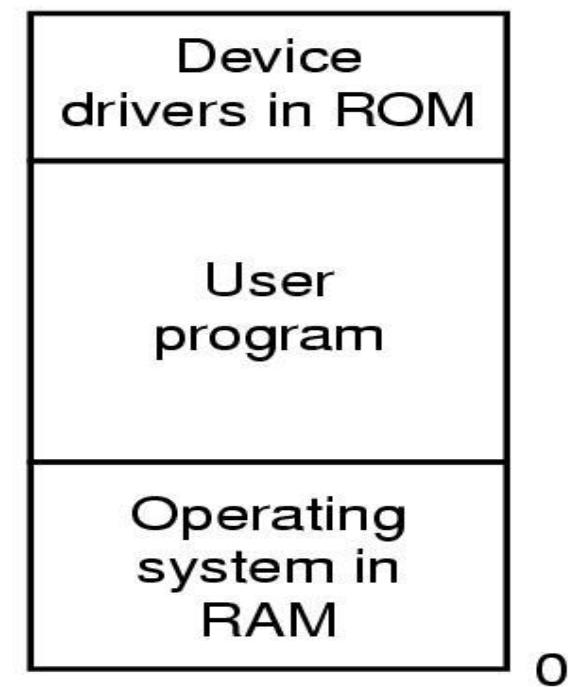
- an operating system with one user process



(a)



(b)



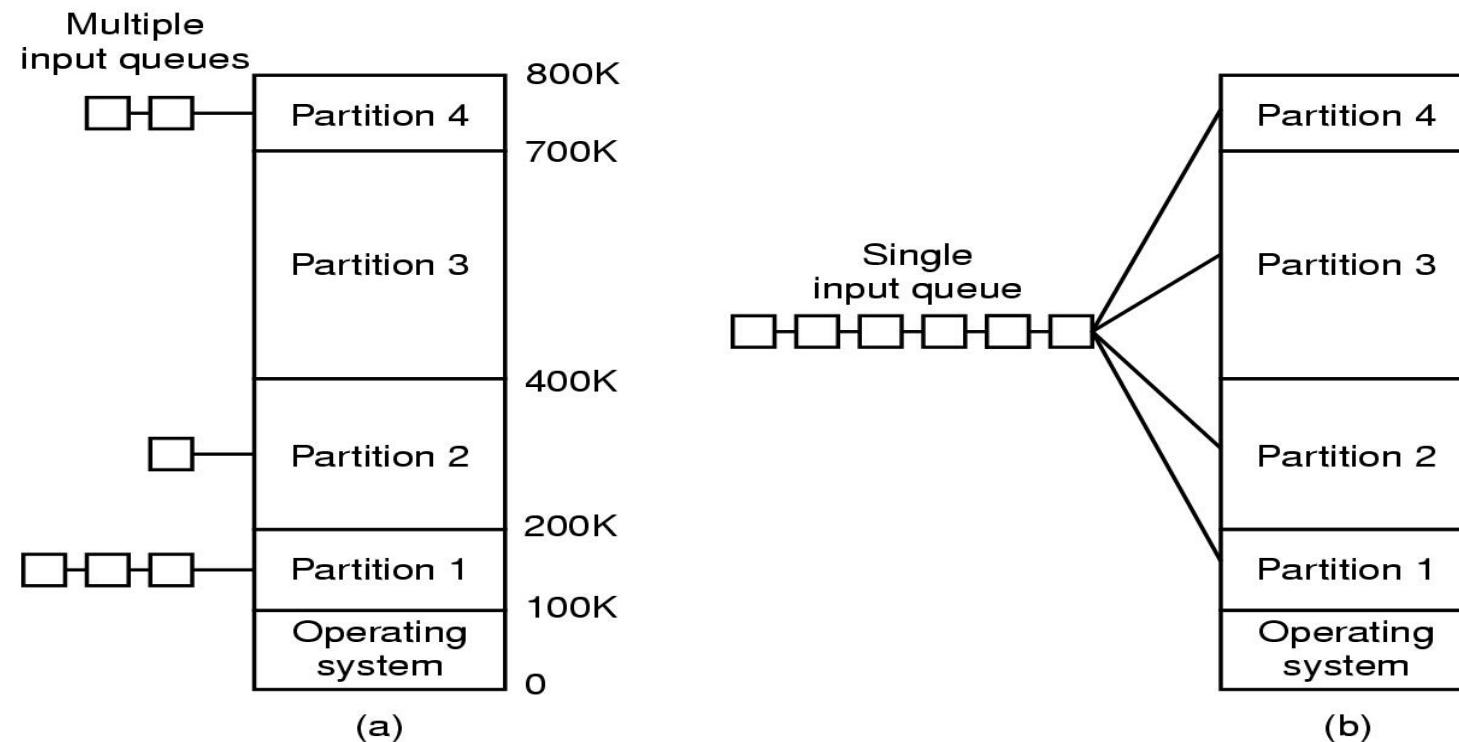
(c)

Basic Memory Management

Multiprogramming with Fixed Partitions

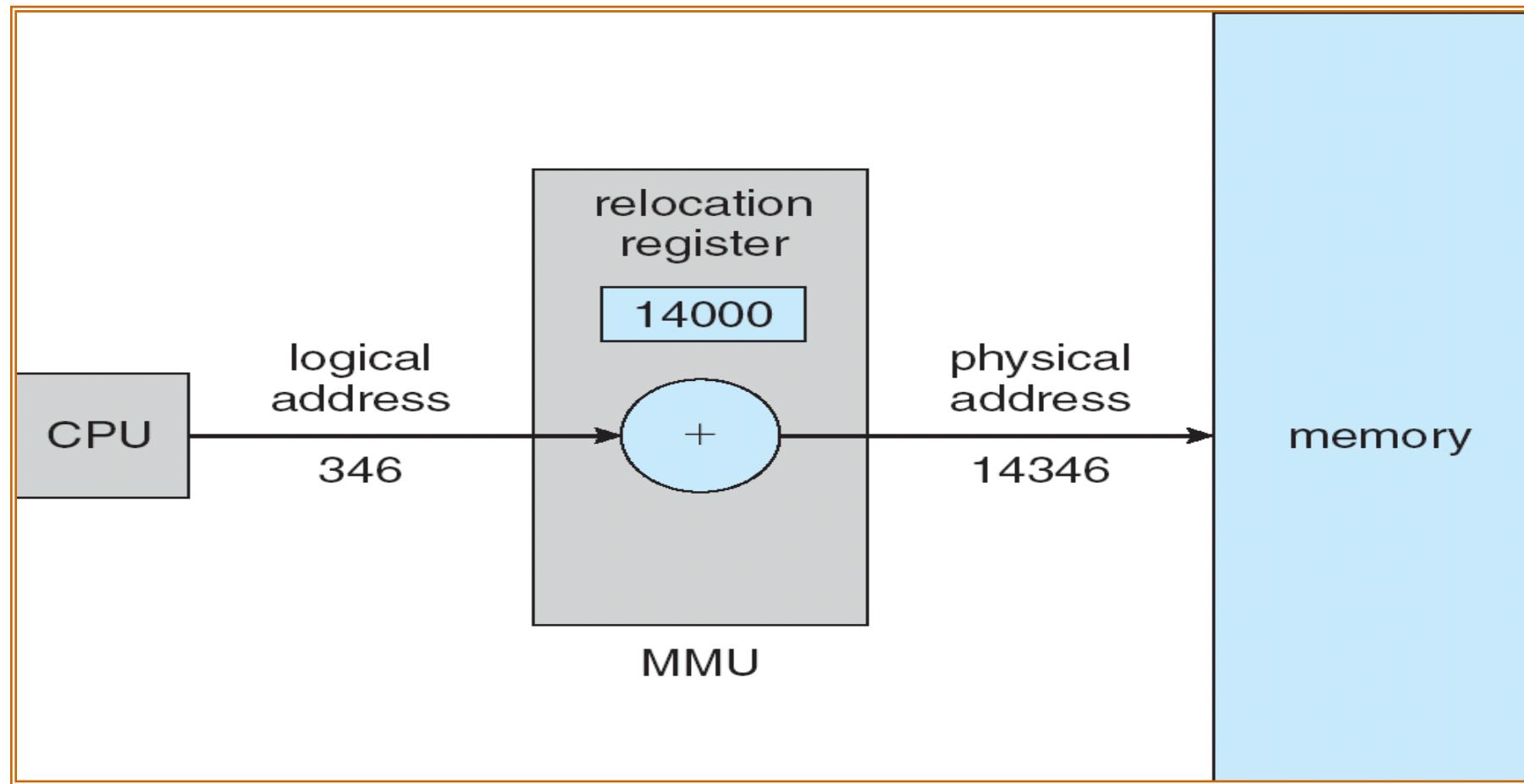
➤ Fixed memory partitions

- (a) separate input queues for each partition
- (b) single input queue



Basic Memory Management

Dynamic relocation using a relocation register





Basic Memory Management

Relocation and Protection

- Cannot be sure where program will be loaded in memory
 - address locations of variables, code routines cannot be absolute
 - must keep a program out of other processes' partitions
- Use base and limit values
 - address locations added to base value to map to physical addr
 - address locations larger than limit value is an error



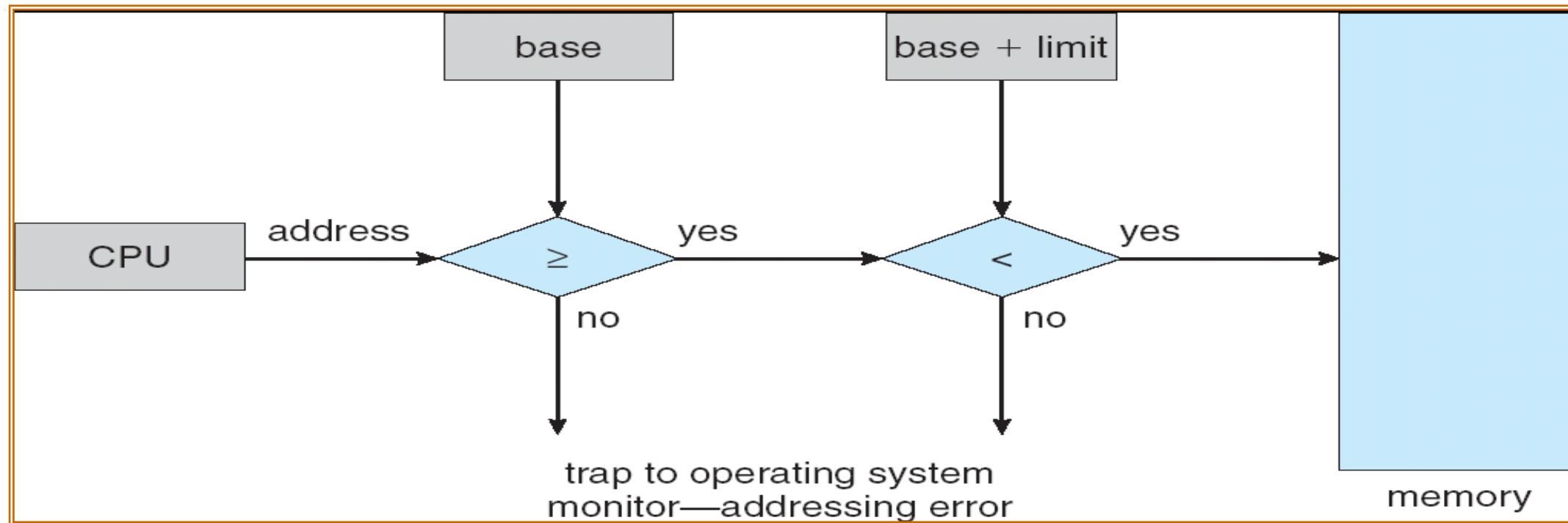
Basic Memory Management

Relocation and Protection

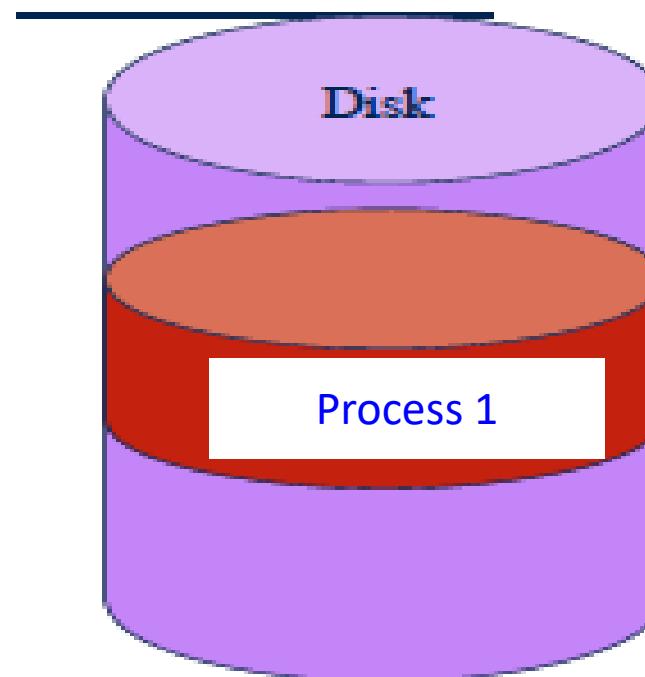
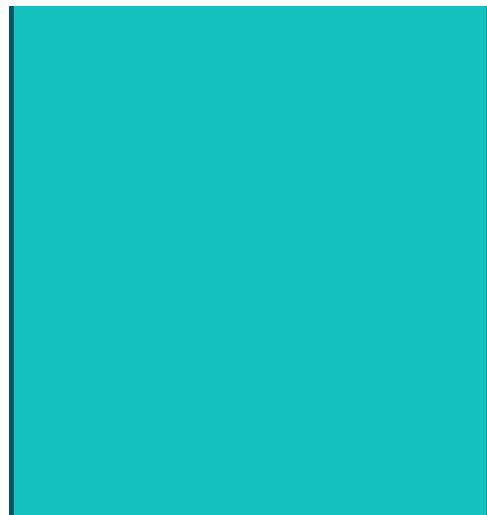
- Relocation registers used to protect user processes from each other, and from changing operating-system code and data
 - Base register contains value of smallest physical address
 - Limit register contains range of logical addresses – each logical address must be less than the limit register
 - MMU maps logical address *dynamically*

Basic Memory Management

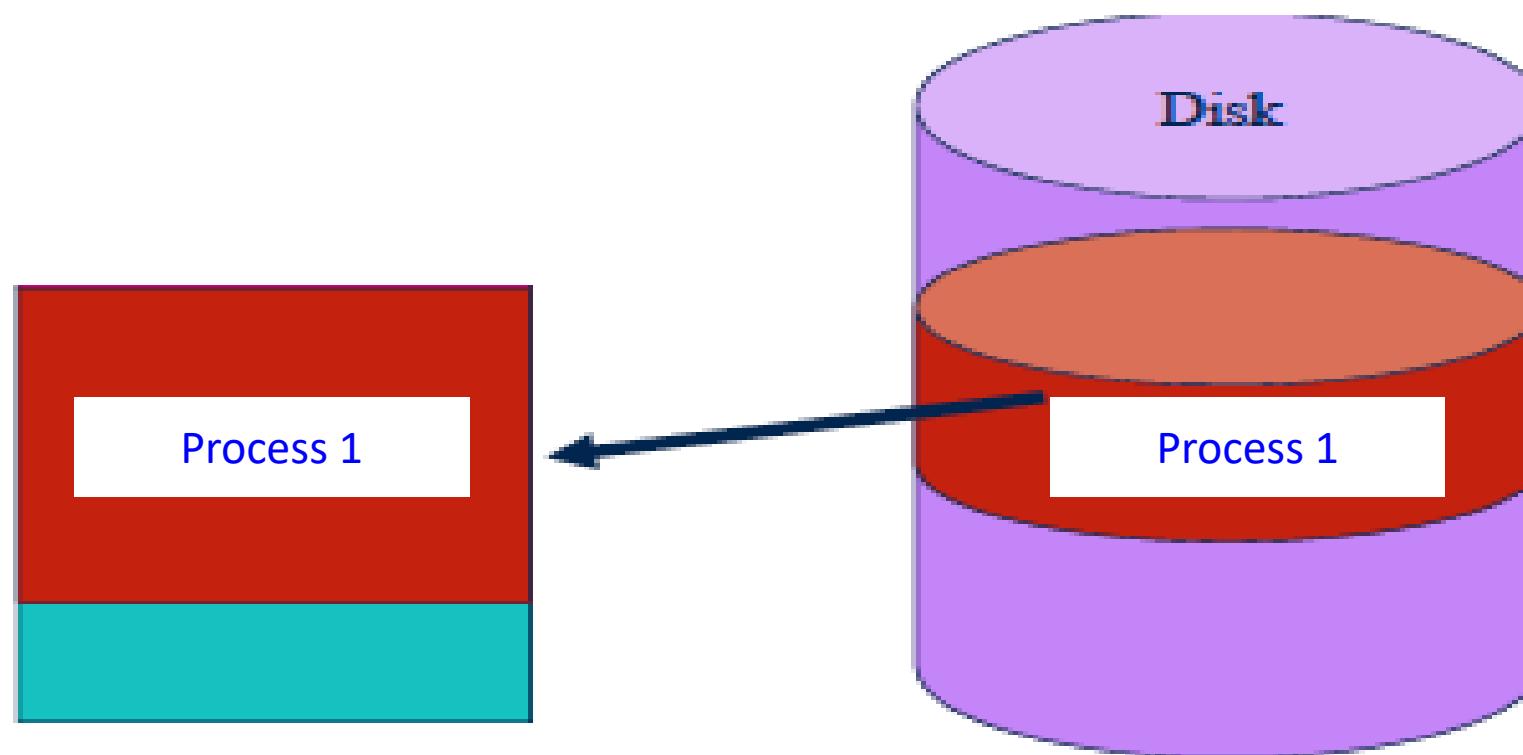
HW address protection with base and limit registers



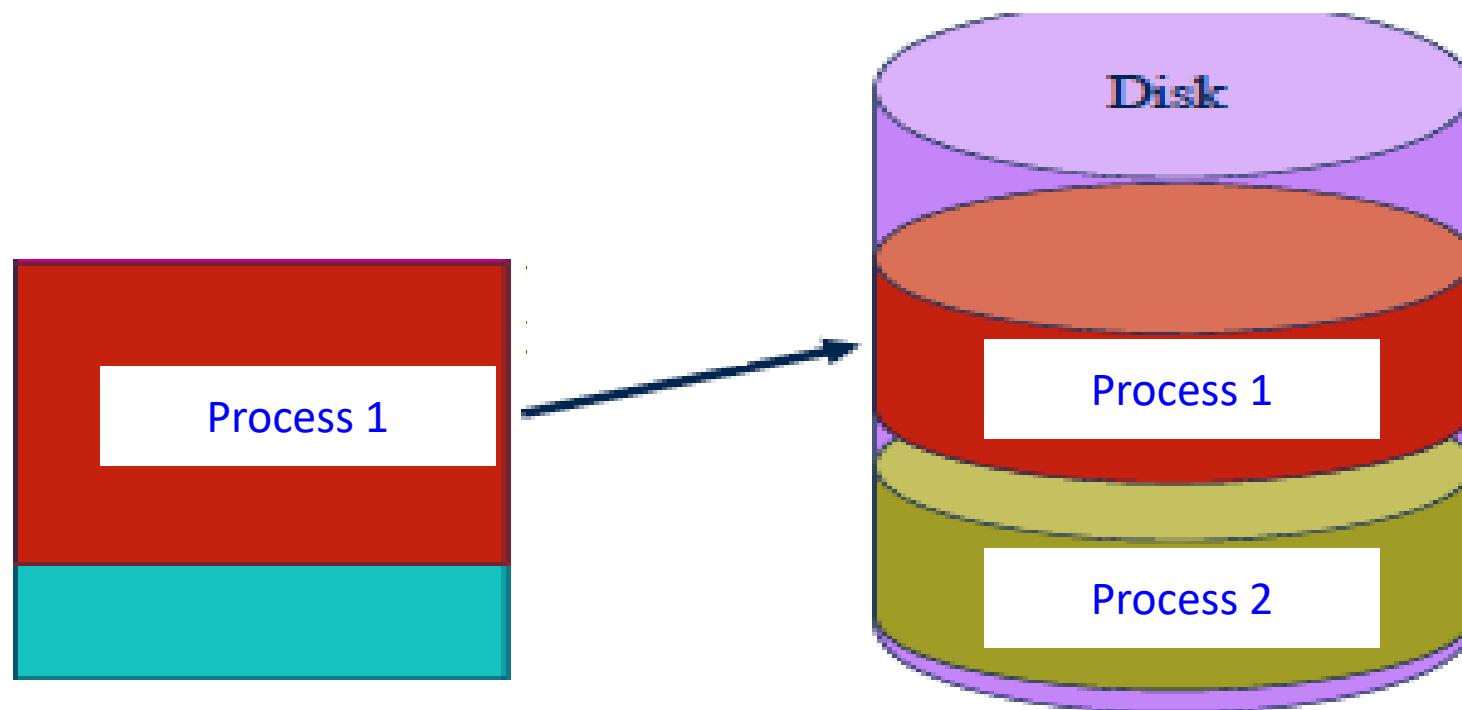
Swapping



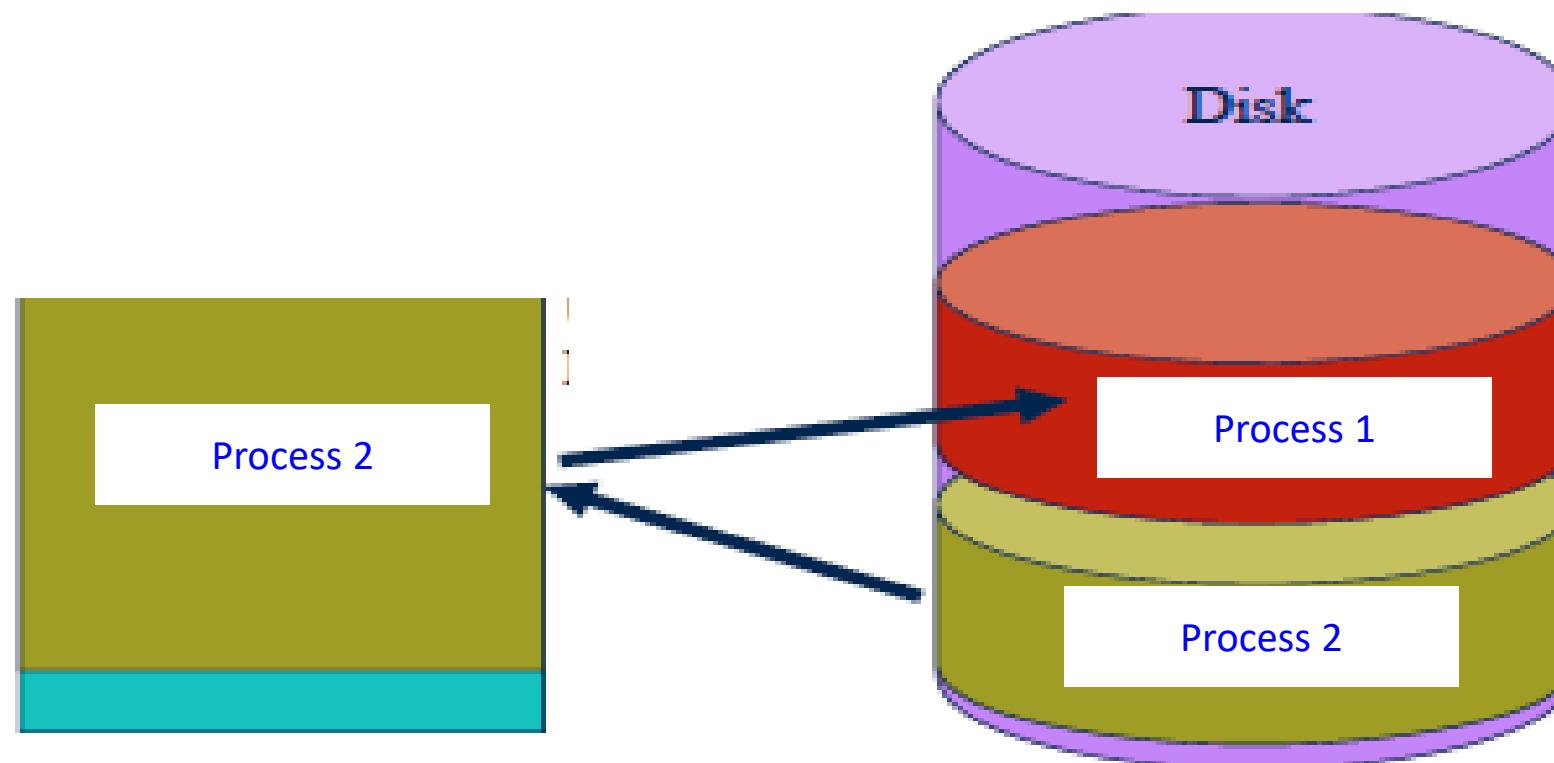
Swapping process 1's data into memory



Swapping

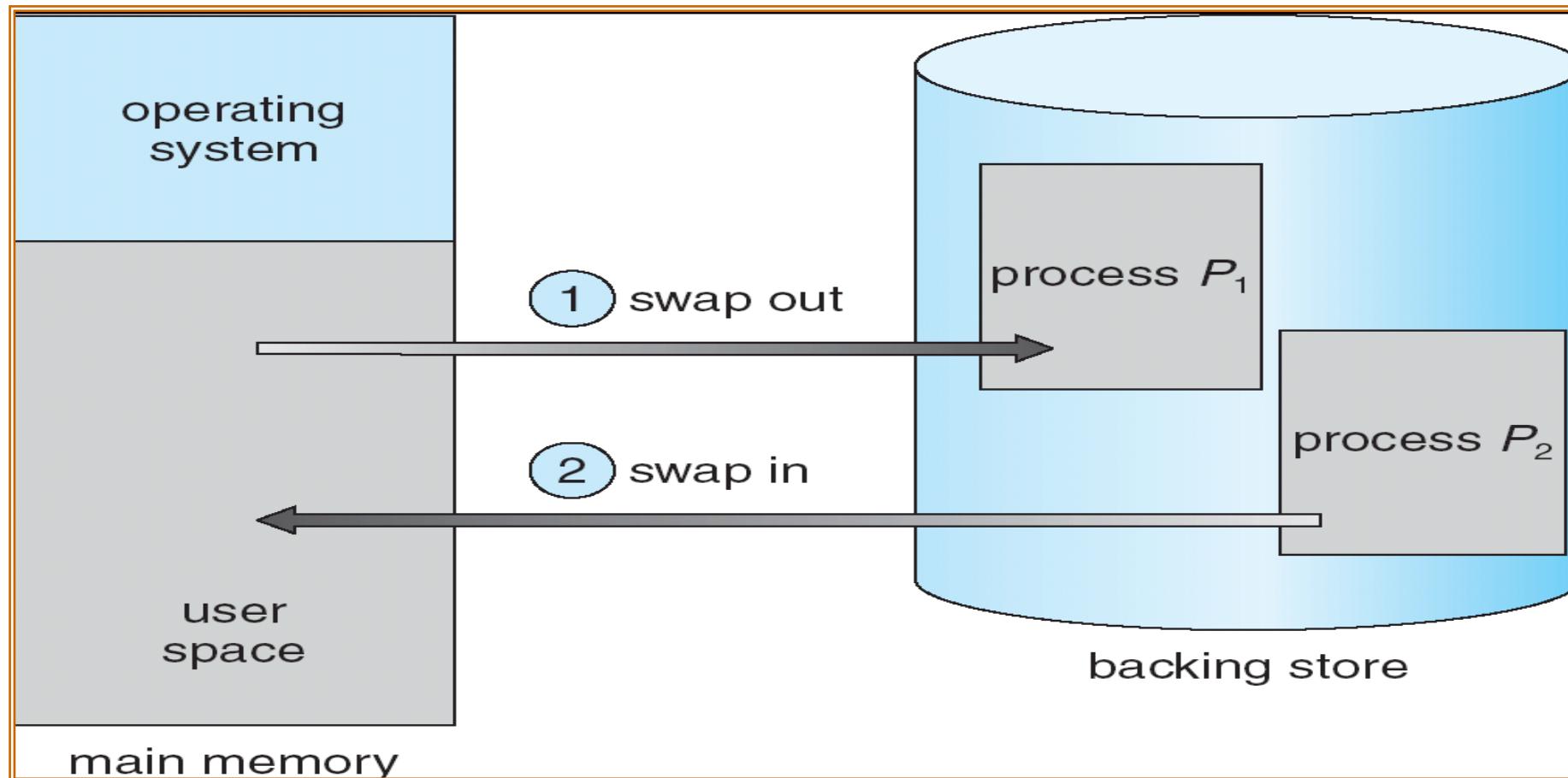


Swapping



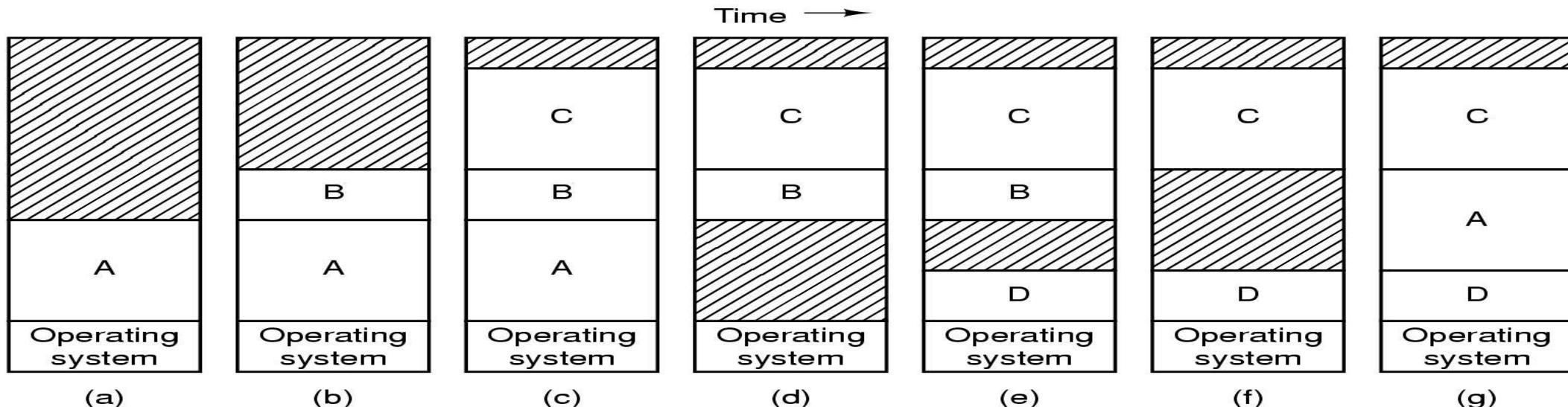
Swapping (1)

Schematic View of Swapping



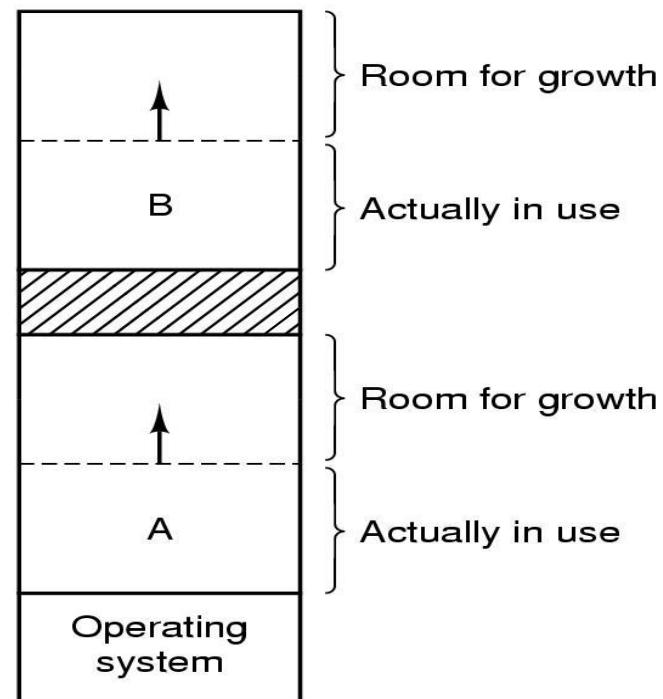
Swapping (2)

- Memory allocation changes as
 - processes come into memory
 - leave memory
- Shaded regions are unused memory
- **External Fragmentation** – total memory space exists to satisfy a request, but it is not contiguous
- **Internal Fragmentation** – allocated memory may be slightly larger than requested memory; this size difference is memory internal to a partition, but not being used

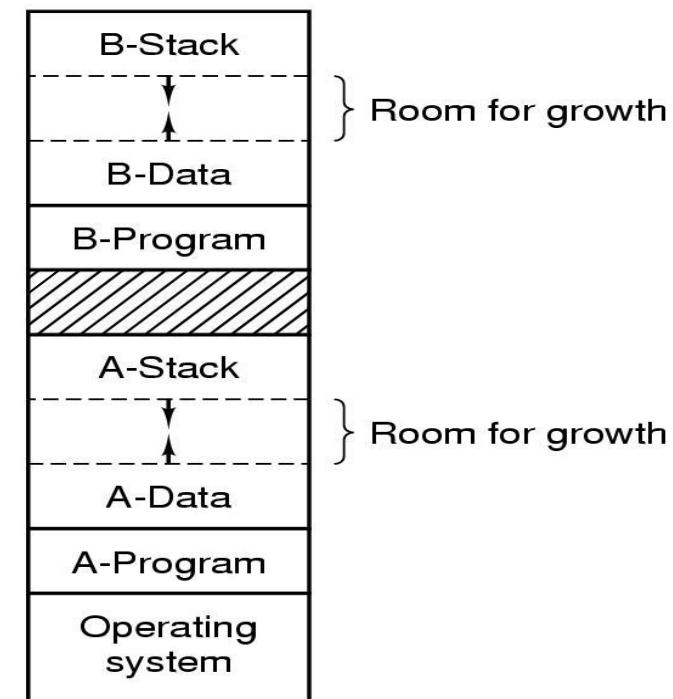


Swapping (3)

- (a) Allocating space for growing data segment
- (b) Allocating space for growing stack & data segment



(a)



(b)



Swapping (4)

Multiple-partition allocation

➤ Multiple-partition allocation

- Hole – block of available memory; holes of various size are scattered throughout memory
- When a process arrives, it is allocated memory from a hole large enough to accommodate it
- Operating system maintains information about:
 - a) allocated partitions
 - b) free partitions (hole)
- There are two ways to keep track of memory usages
 - ✓ Memory Management with Bit Maps
 - ✓ Memory Management with Linked Lists

Swapping (4)

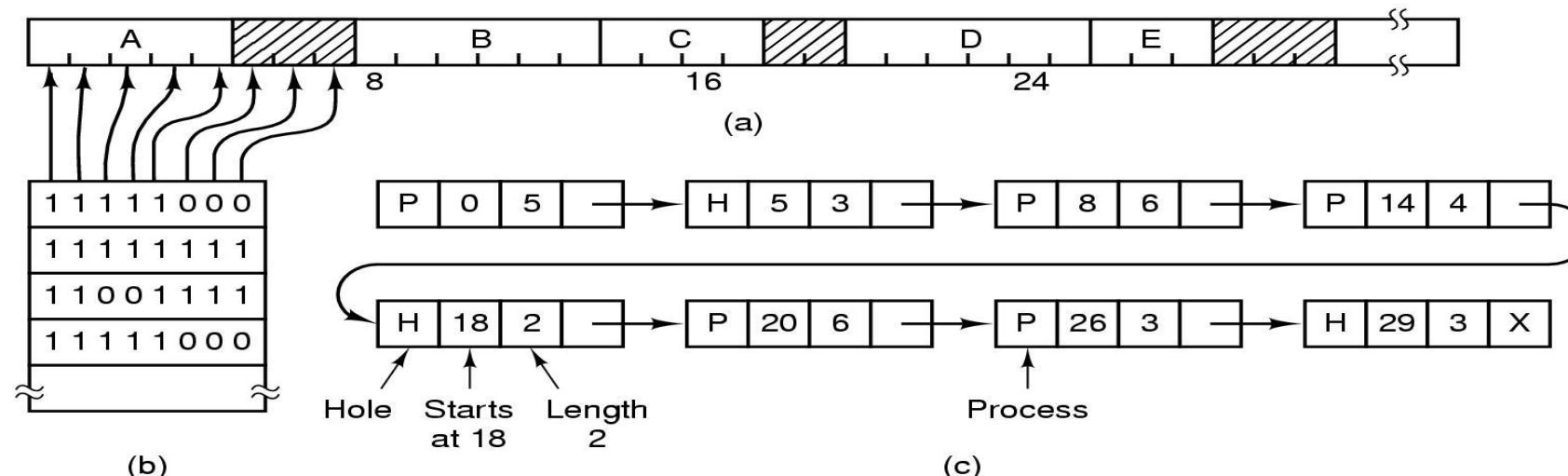
Multiple-partition allocation

Memory Management with Bit Maps

- (a) Part of memory with 5 processes, 3 holes

 - tick marks show allocation units
 - shaded regions are free

- (b) Corresponding bit map
- (c) Same information as a list





Swapping (5) Dynamic Storage-Allocation Problem

- First-fit: Allocate the first hole that is big enough
- Next fit: Start searching the list from the place where it left off last time
- Best-fit: Allocate the smallest hole that is big enough; must search entire list, unless ordered by size
 - Produces the smallest leftover hole
- Worst-fit: Allocate the largest hole; must also search entire list
 - Produces the largest leftover hole
- First-fit and best-fit better than worst-fit in terms of speed and storage utilization

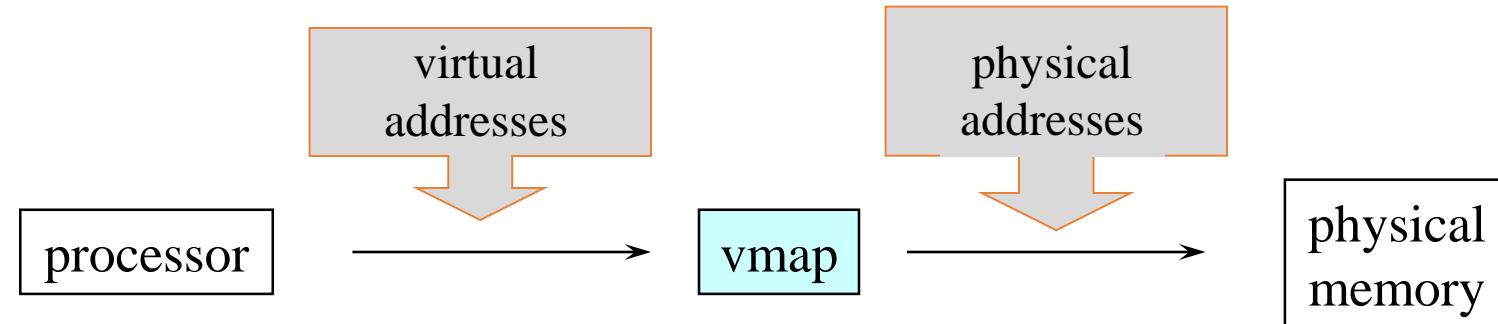


Virtual Memory Paging

Virtual Memory Addresses

➤ Many ways to do this translation...

- Start with old, simple ways, progress to current techniques





Virtual Memory

➤ **Virtual memory** – separation of user logical memory from physical memory.

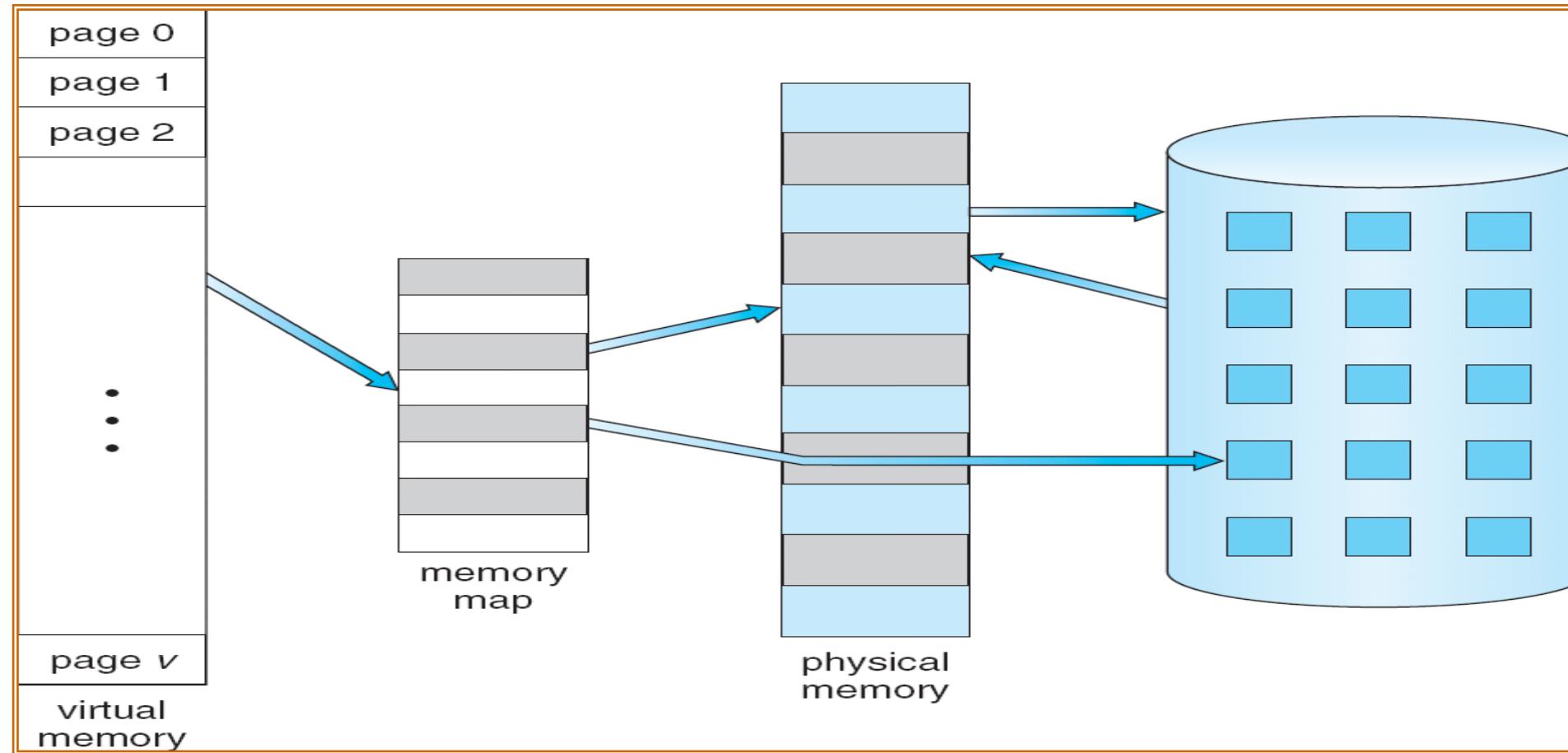
- Only part of the program needs to be in memory for execution
- Logical address space can therefore be much larger than physical address space
- Allows address spaces to be shared by several processes
- Allows for more efficient process creation

➤ Virtual memory can be implemented via:

- Demand **paging**
- Demand **segmentation**

Virtual Memory

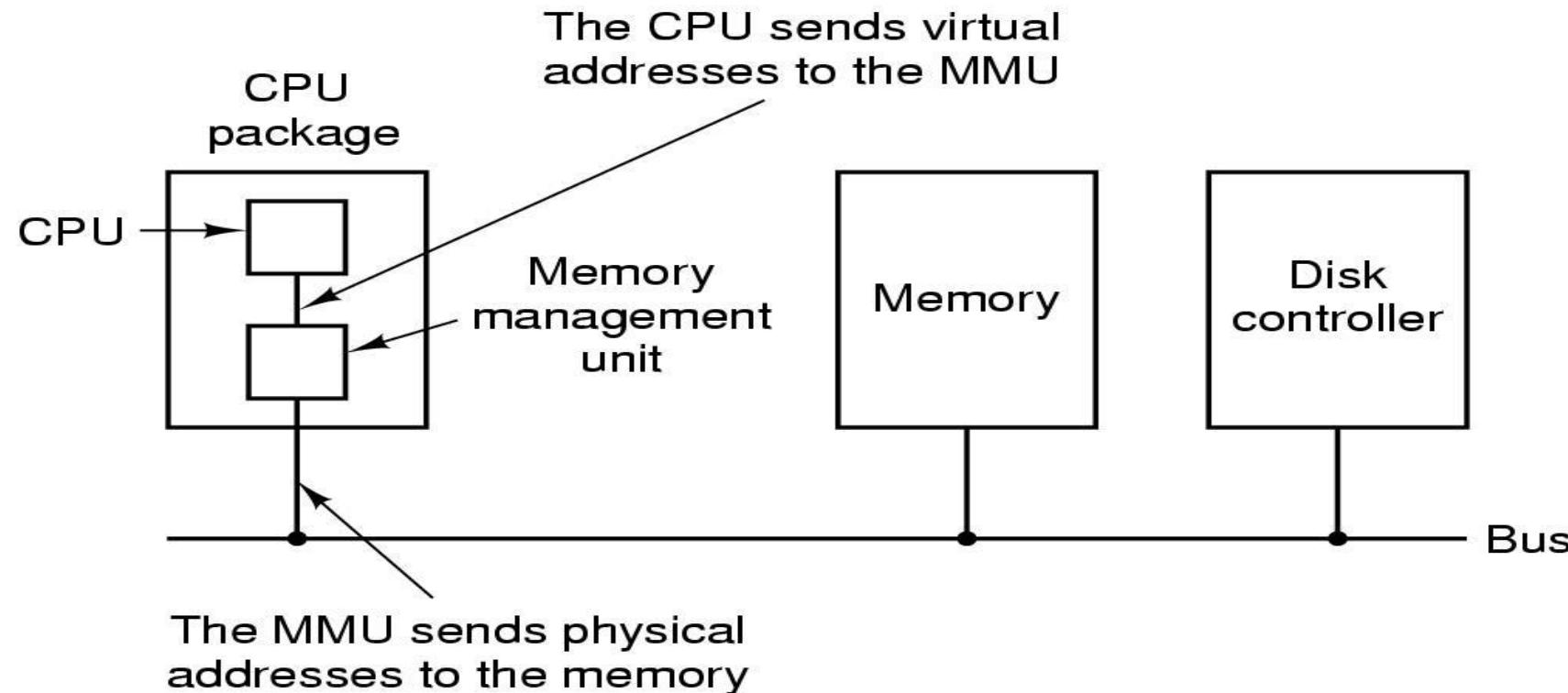
Paging



Virtual Memory

Paging

The position and function of the MMU





Virtual Memory

Paging

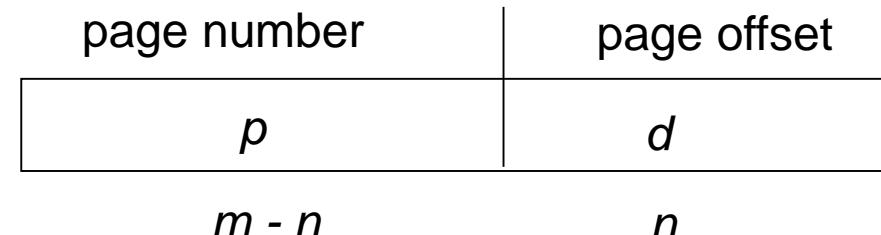
- Virtual address space of a process can be noncontiguous; process is allocated physical memory whenever the latter is available
- Divide physical memory into fixed-sized blocks called **Page frames** (size is power of 2, between 512 bytes and 8,192 bytes)
- Divide logical memory into blocks of same size called **pages**
- Keep track of all free frames
- To run a program of size n pages, need to find n free frames and load program
- Set up a **page table** to translate logical to physical addresses
- Internal fragmentation

Virtual Memory

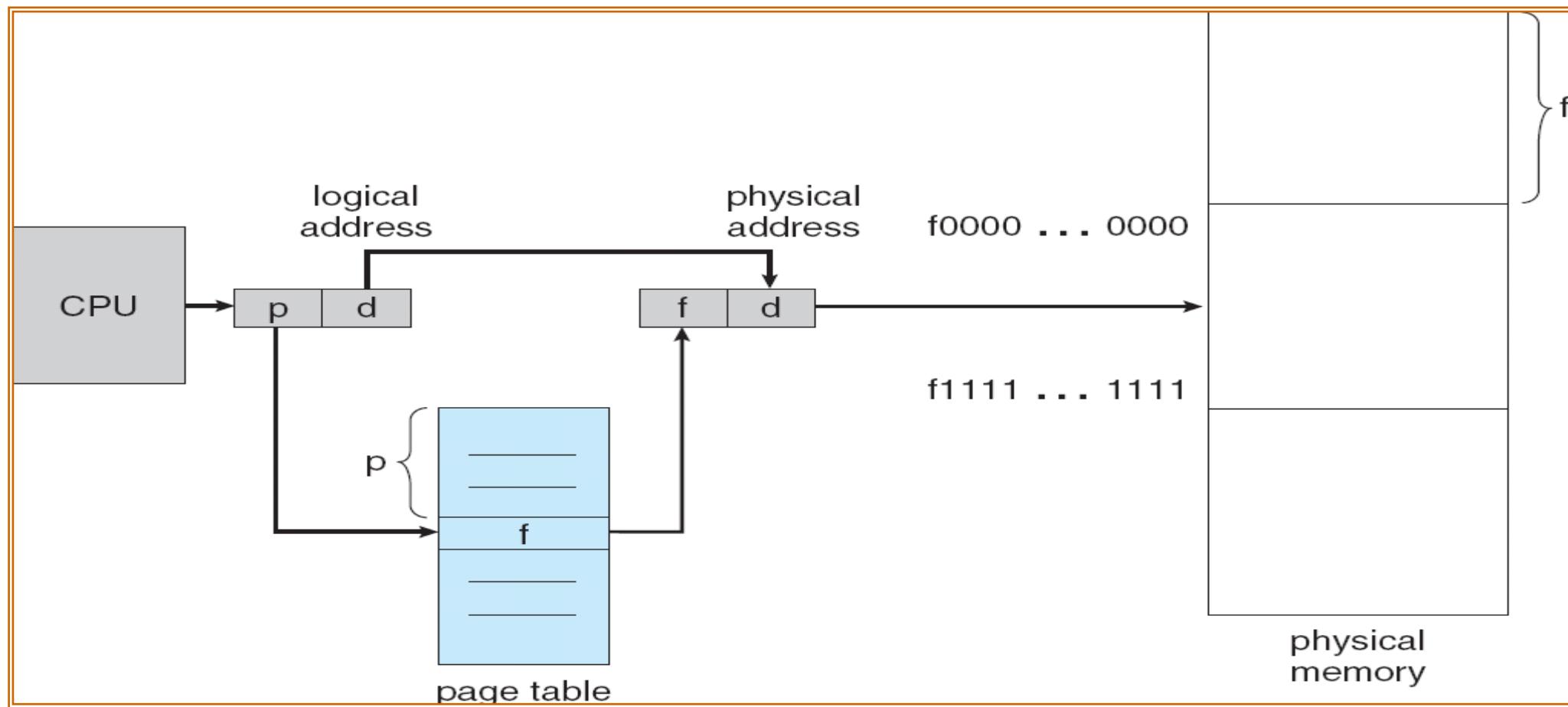
Address Translation Scheme

➤ Address generated by CPU is divided into:

- **Page number (p)** – used as an index into a *page table* which contains base address of each page in physical memory



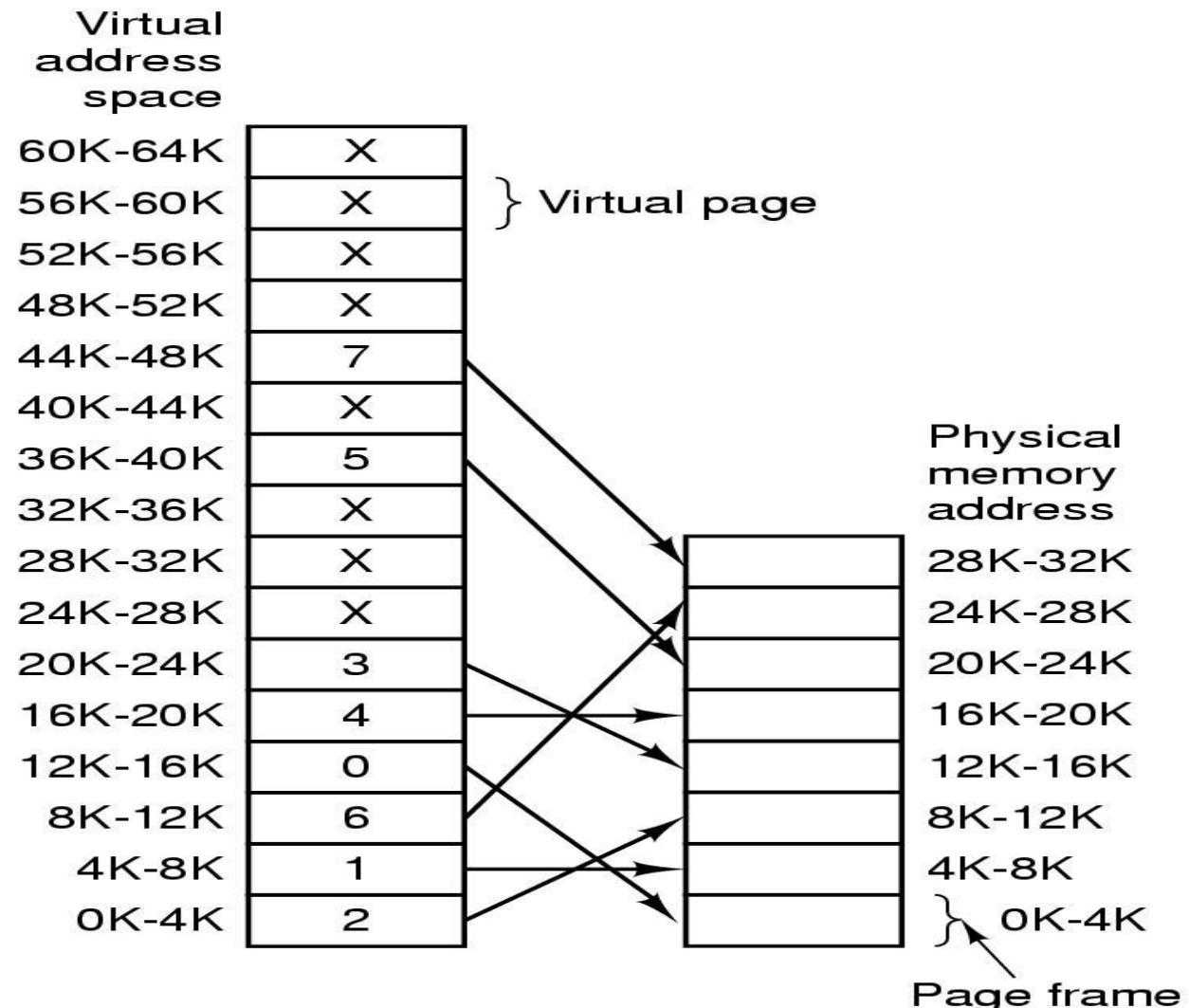
- **Page offset (d)** – combined with base address to define the physical memory address that is sent to the memory unit
- For given logical address space 2^m and page size 2^n



Virtual Memory

Paging: Example

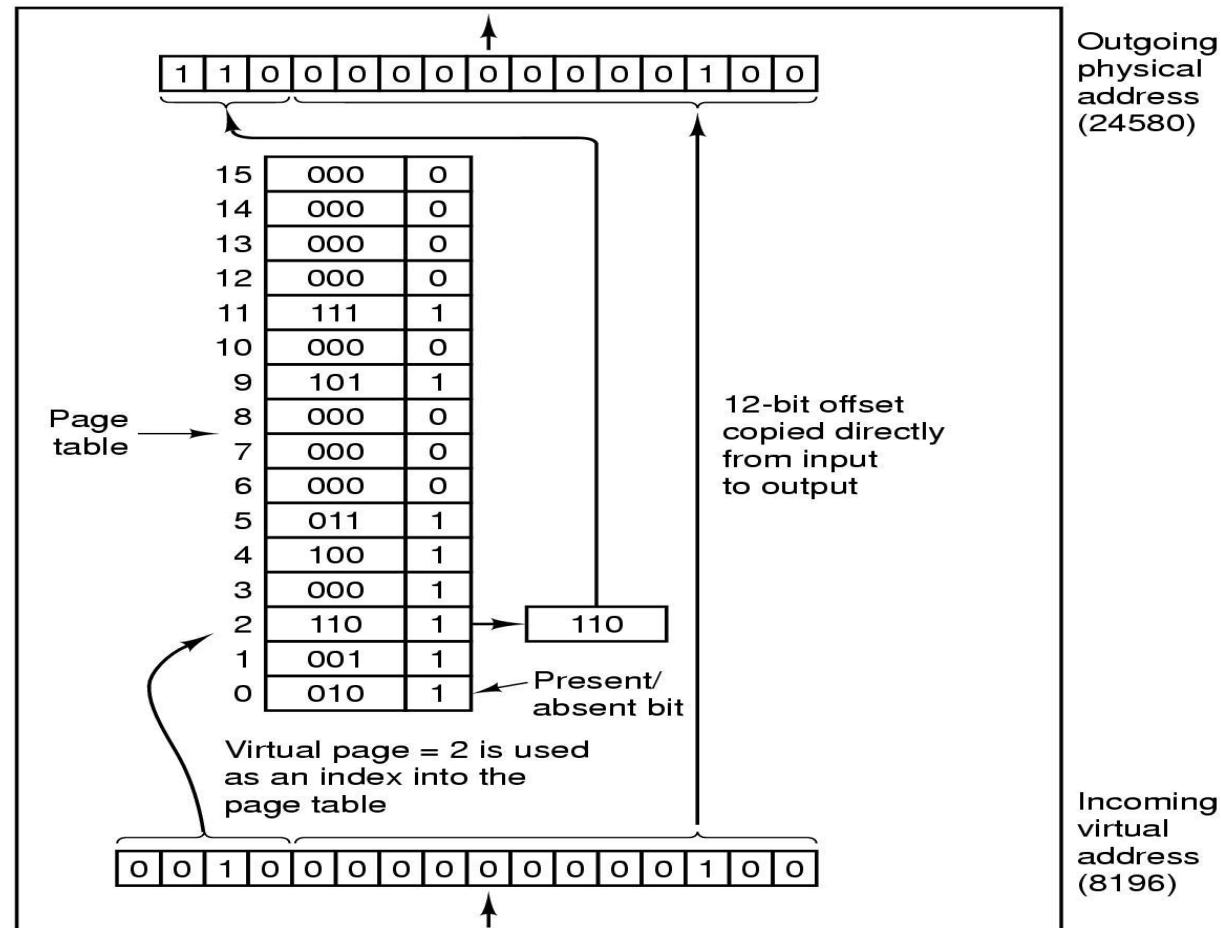
The relation between virtual addresses and physical memory addresses given by page table



Virtual Memory

Page Tables: Example

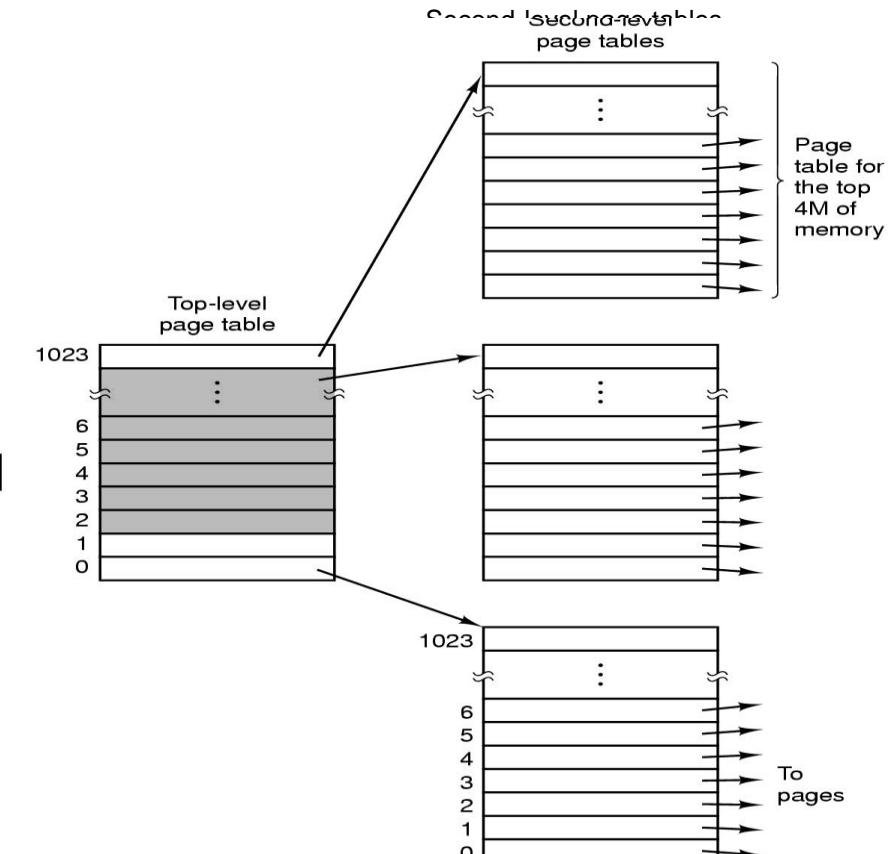
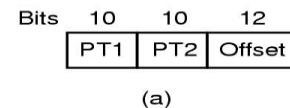
Internal operation of MMU with 16 4 KB pages



Virtual Memory

Two-level page tables

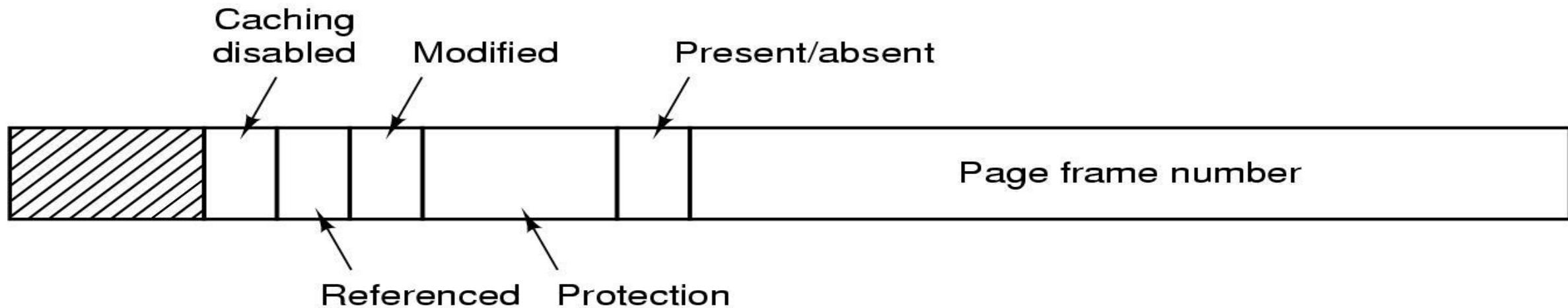
- 32 bit address with 2 page table fields
- Two-level page tables



Virtual Memory

Typical page table entry

Typical page table entry





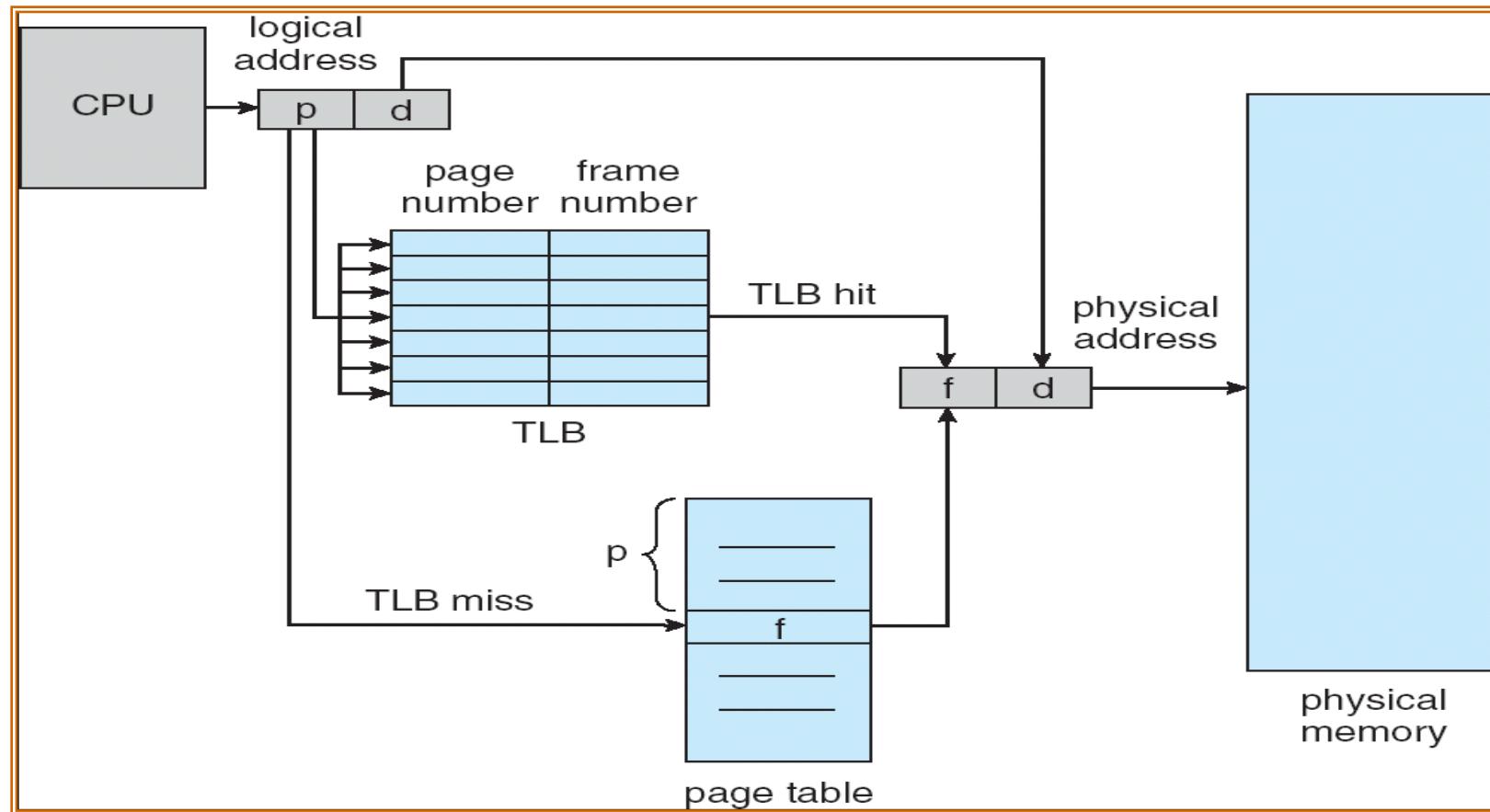
Virtual Memory

Implementation of Page Table

- Page table is kept in main memory
- **Page-table base register (PTBR)** points to the page table
- **Page-table length register (PRLR)** indicates size of the page table
- In this scheme every data/instruction access requires two memory accesses. One for the page table and one for the data/instruction.
- The two memory access problem can be solved by the use of a special fast-lookup hardware cache called **associative memory** or **translation look-aside buffers (TLBs)**

Virtual Memory

Paging Hardware With TLB





Virtual Memory

TLBs – Translation Lookaside Buffers

A TLB to speed up paging

Valid	Virtual page	Modified	Protection	Page frame
1	140	1	RW	31
1	20	0	R X	38
1	130	1	RW	29
1	129	1	RW	62
1	19	0	R X	50
1	21	0	R X	45
1	860	1	RW	14
1	861	1	RW	75



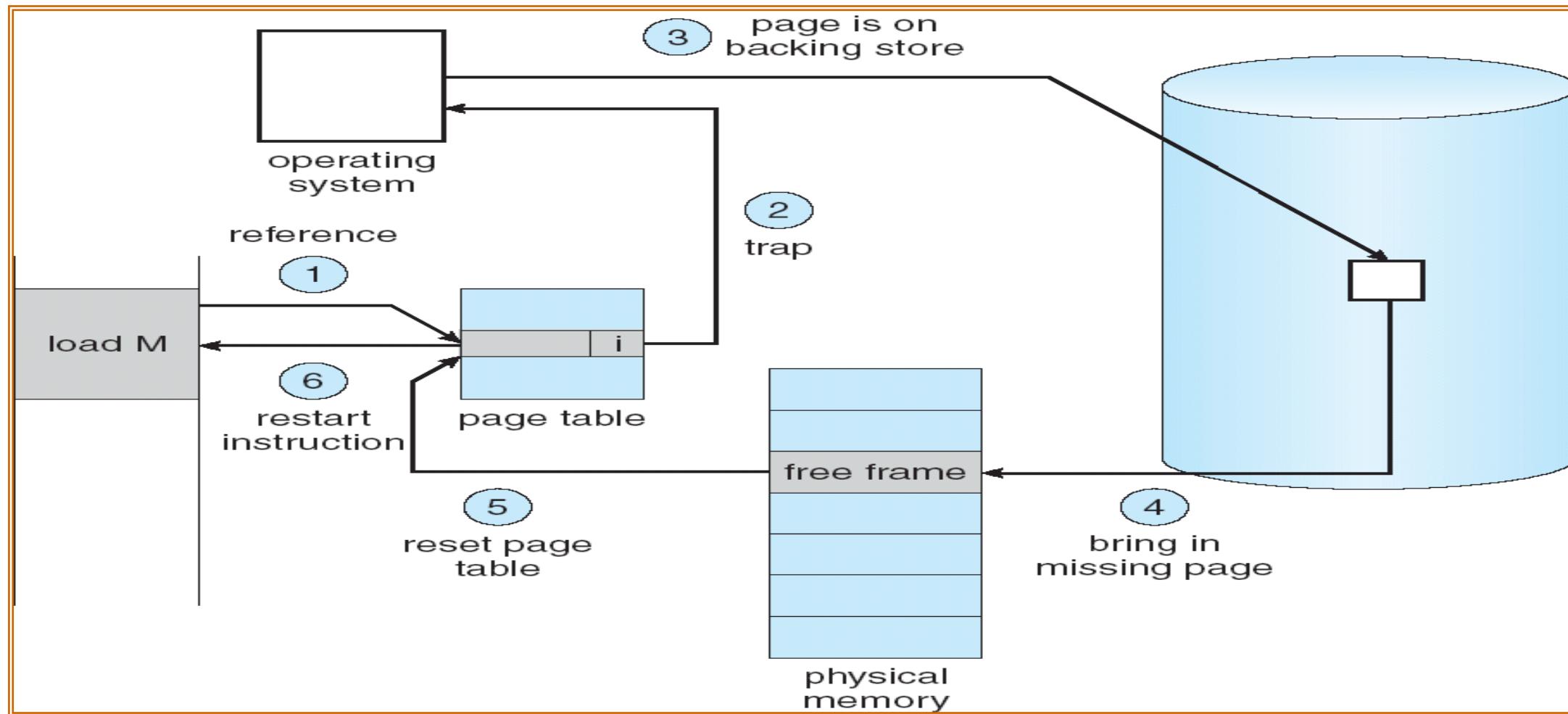
Virtual Memory

Page Fault

1. If there is a reference to a page, Just not in memory: **page fault**,
2. Trap to operating system:
3. Get empty page frame, Determine page on backing store
4. Swap page from disk into page frame in memory
5. Modifies page tables, Set validation bit = **v**
6. Restart the instruction that caused the page fault

Virtual Memory

Steps in Handling a Page Fault





Virtual Memory

Page Replacement Algorithms

- What happens if there is no free frame?
- Page replacement – find some page in memory, but not really in use, swap it out
 - algorithm
 - performance – want an algorithm which will result in minimum number of page faults
- Same page may be brought into memory several times



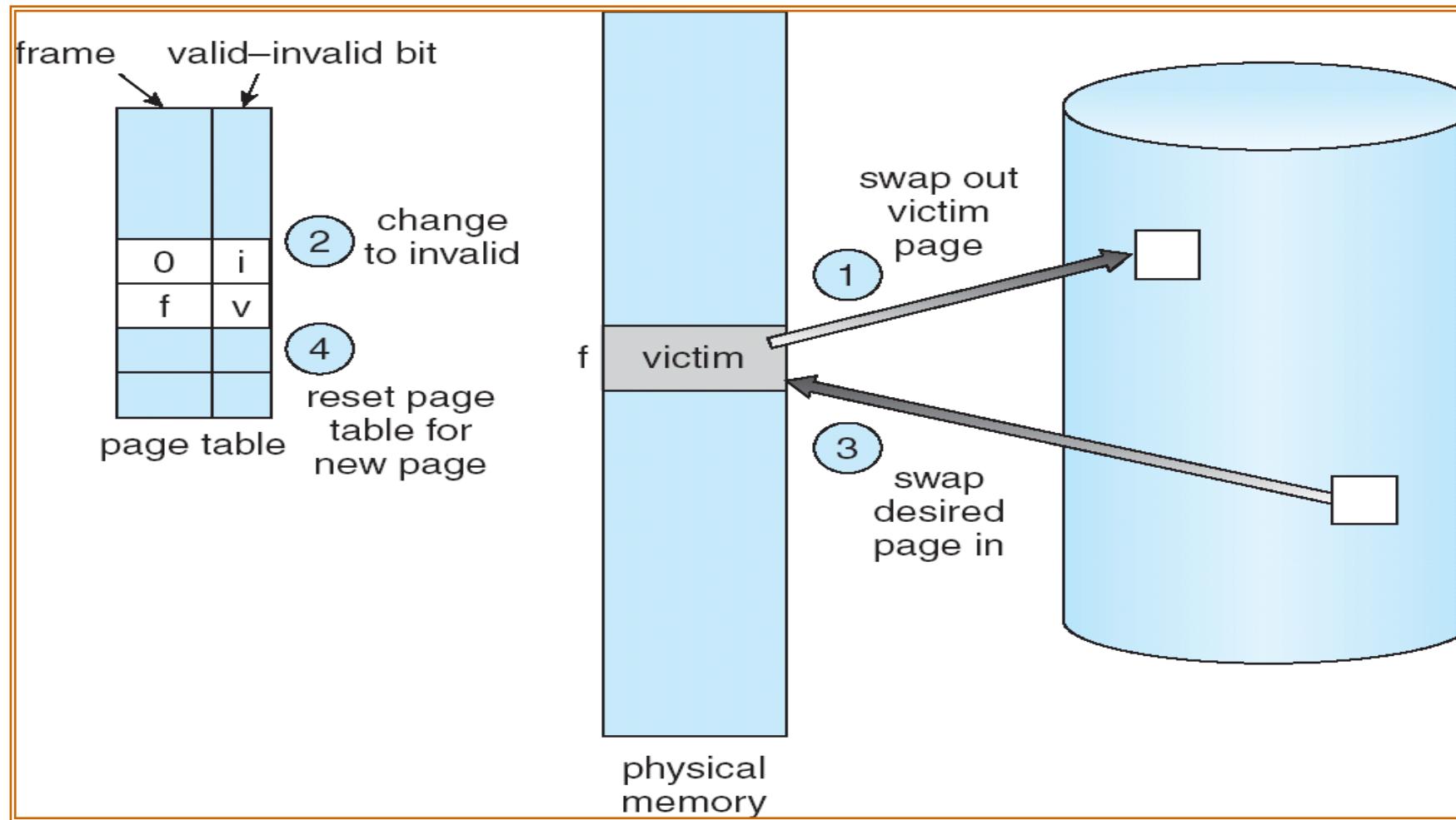
Virtual Memory

Basic Page Replacement

1. Find the location of the desired page on disk
2. Find a free frame:
 - If there is a free frame, use it
 - If there is no free frame, use a page replacement algorithm to select a **victim** frame
3. Bring the desired page into the (newly) free frame; update the page and frame tables
4. Restart the process

Virtual Memory

Page Replacement





Virtual Memory

Page Replacement Algorithms

Algorithm	Comment
Optimal	Not implementable, but useful as a benchmark
NRU (Not Recently Used)	Very crude
FIFO (First-In, First-Out)	Might throw out important pages
Second chance	Big improvement over FIFO
Clock	Realistic
LRU (Least Recently Used)	Excellent, but difficult to implement exactly
NFU (Not Frequently Used)	Fairly crude approximation to LRU
Aging	Efficient algorithm that approximates LRU well
Working set	Somewhat expensive to implement
WSClock	Good efficient algorithm

- (a) Original configuration
- (b) Local page replacement
- (c) Global page replacement

Age
A0
10
A1
7
A2
5
A3
4
A4
6
A5
3
B0
9
B1
4
B2
6
B3
2
B4
5
B5
6
B6
12
C1
3
C2
5
C3
6

(a)

A0
A1
A2
A3
A4
A5
A6
B0
B1
B2
B3
B4
B5
B6
C1
C2
C3

(b)

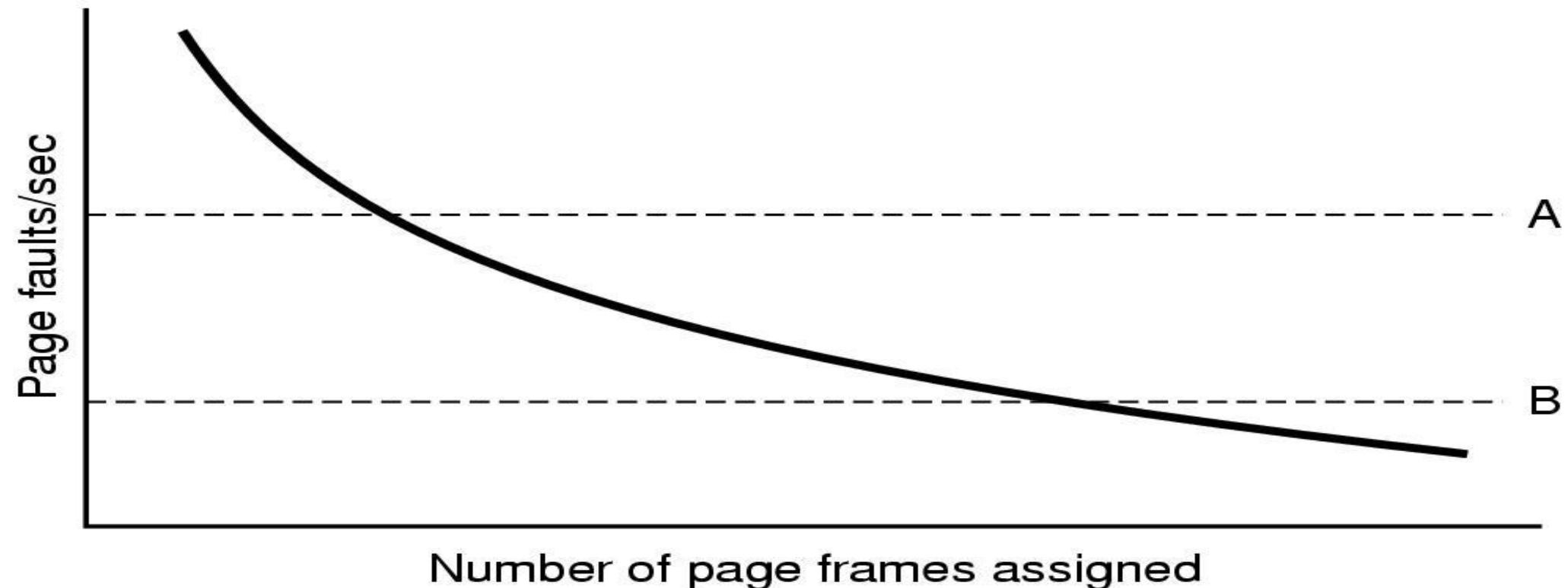
A0
A1
A2
A3
A4
A5
B0
B1
B2
A6
B4
B5
B6
C1
C2
C3

(c)

Virtual Memory

Design issues: Page Frame Allocation

Page fault rate as a function of the number of page frames assigned





Virtual Memory

Design issues: Page Size (1)

Small page size

➤ Advantages

- less internal fragmentation
- better fit for various data structures, code sections
- less unused program in memory

➤ Disadvantages

- programs need many pages, larger page tables

Virtual Memory

Design issues: Page Size (2)

- Overhead due to page table and internal fragmentation

$$\text{overhead} = \frac{s \cdot e}{p} + \frac{p}{2}$$

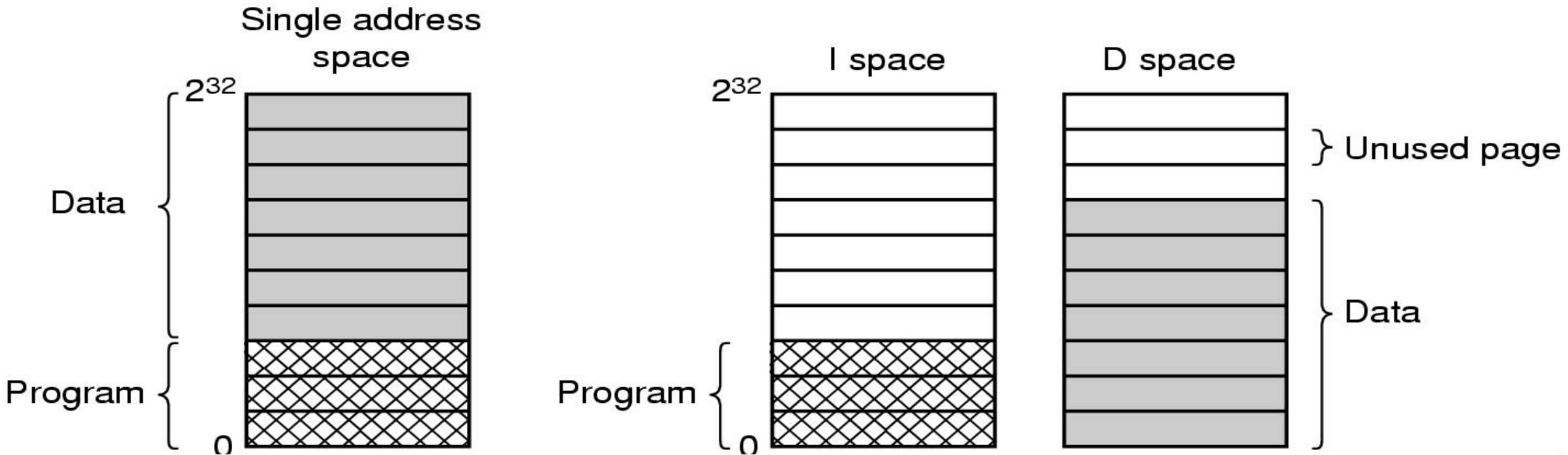
The diagram illustrates the formula for overhead. It shows a bracket on the right side of the equation $\text{overhead} = \frac{s \cdot e}{p} + \frac{p}{2}$ pointing to two separate components: 'page table space' and 'internal fragmentation'. Arrows point from the terms $\frac{s \cdot e}{p}$ and $\frac{p}{2}$ to these respective labels.

- Where

- s = average process size in bytes
- p = page size in bytes
- e = page entry in bytes

Optimized when
 $p = \sqrt{2se}$

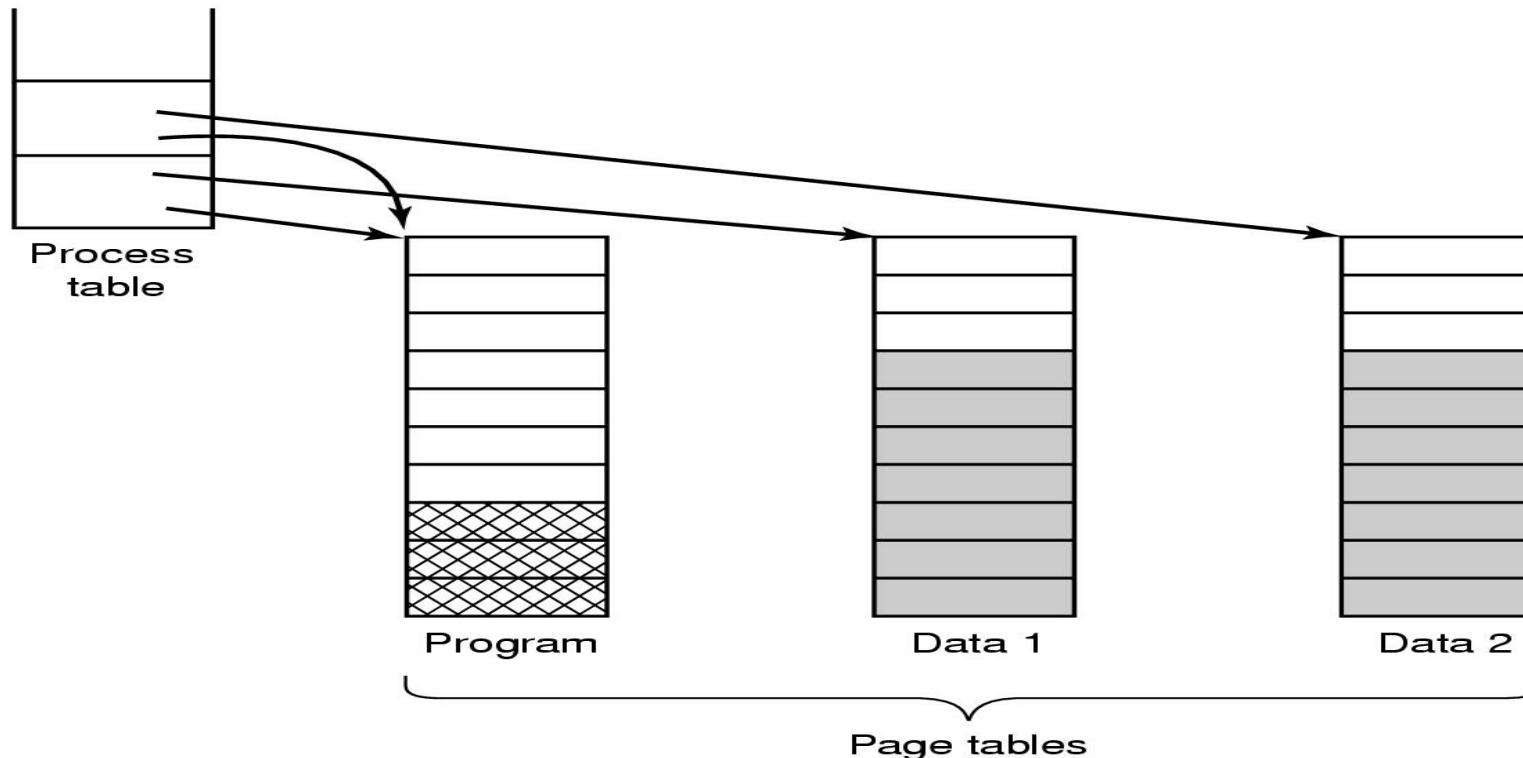
- One address space
- Separate I and D spaces



Virtual Memory

Design issues: Shared Pages

Two processes sharing same program sharing its page table





Virtual Memory

Design issues: Cleaning Policy

- Need for a background process, paging daemon
 - periodically inspects state of memory
- When too few frames are free
 - selects pages to evict using a replacement algorithm
- It can use same circular list (clock)
 - as regular page replacement algorithm but with diff ptr



Virtual Memory

Implementation Issues

Operating System Involvement with Paging

Four times when OS involved with paging

1. Process creation
 - determine program size
 - create page table
2. Process execution
 - MMU reset for new process
 - TLB flushed
3. Page fault time
 - determine virtual address causing fault
 - swap target page out, needed page in
4. Process termination time
 - release page table, pages



Virtual Memory

Implementation Issues

Page Fault Handling (1)

1. Hardware traps to kernel
2. General registers saved
3. OS determines which virtual page needed
4. OS checks validity of address, seeks page frame
5. If selected frame is dirty, write it to disk



Virtual Memory

Implementation Issues

Page Fault Handling (2)

6. OS brings schedules new page in from disk
7. Page tables updated
8. Faulting instruction backed up to when it began
9. Faulting process scheduled
10. Registers restored, Program continues



Virtual Memory

Implementation Issues

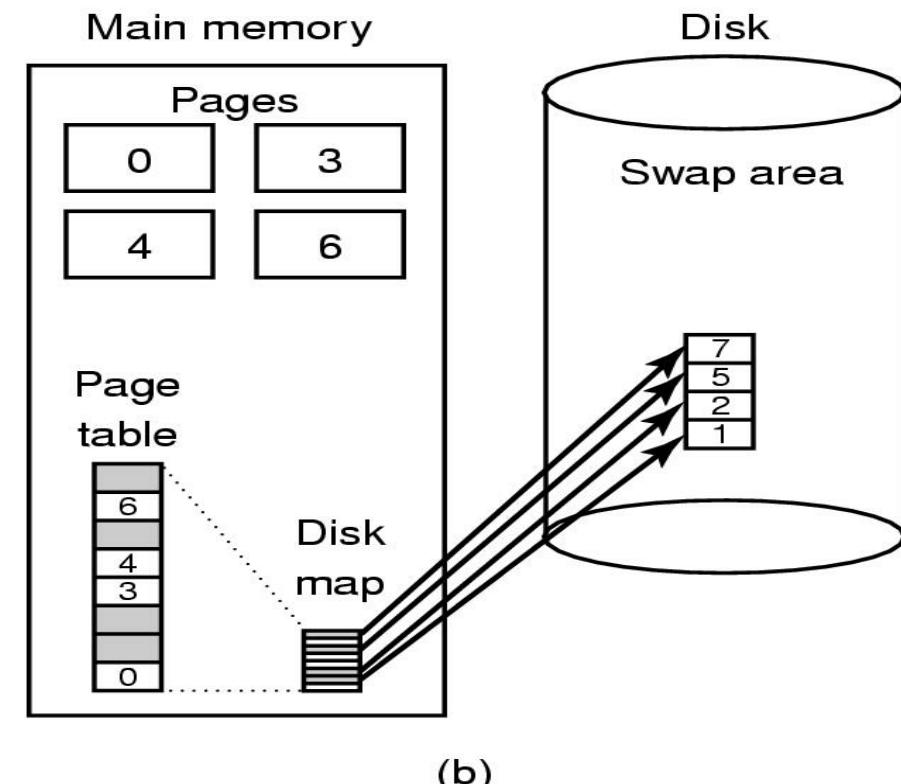
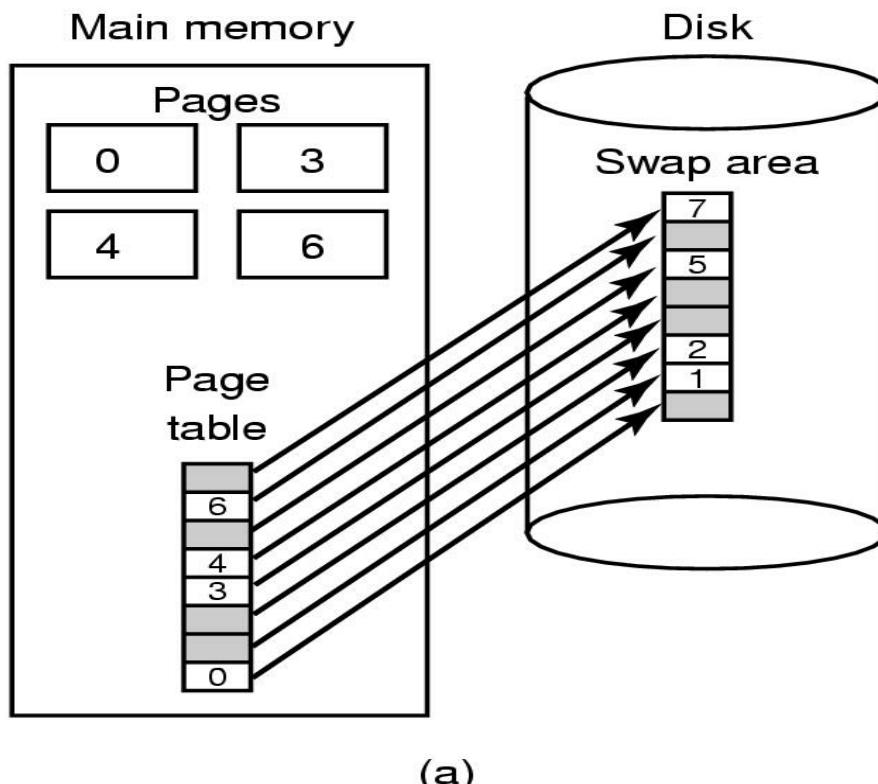
Locking Pages in Memory

- Virtual memory and I/O occasionally interact
- Proc issues call for read from device into buffer
 - while waiting for I/O, another processes starts up
 - has a page fault
 - buffer for the first proc may be chosen to be paged out
- Need to specify some pages locked
 - exempted from being target pages

Virtual Memory

Implementation Issues: Backing Store

- (a) Paging to static swap area
- (b) Backing up pages dynamically

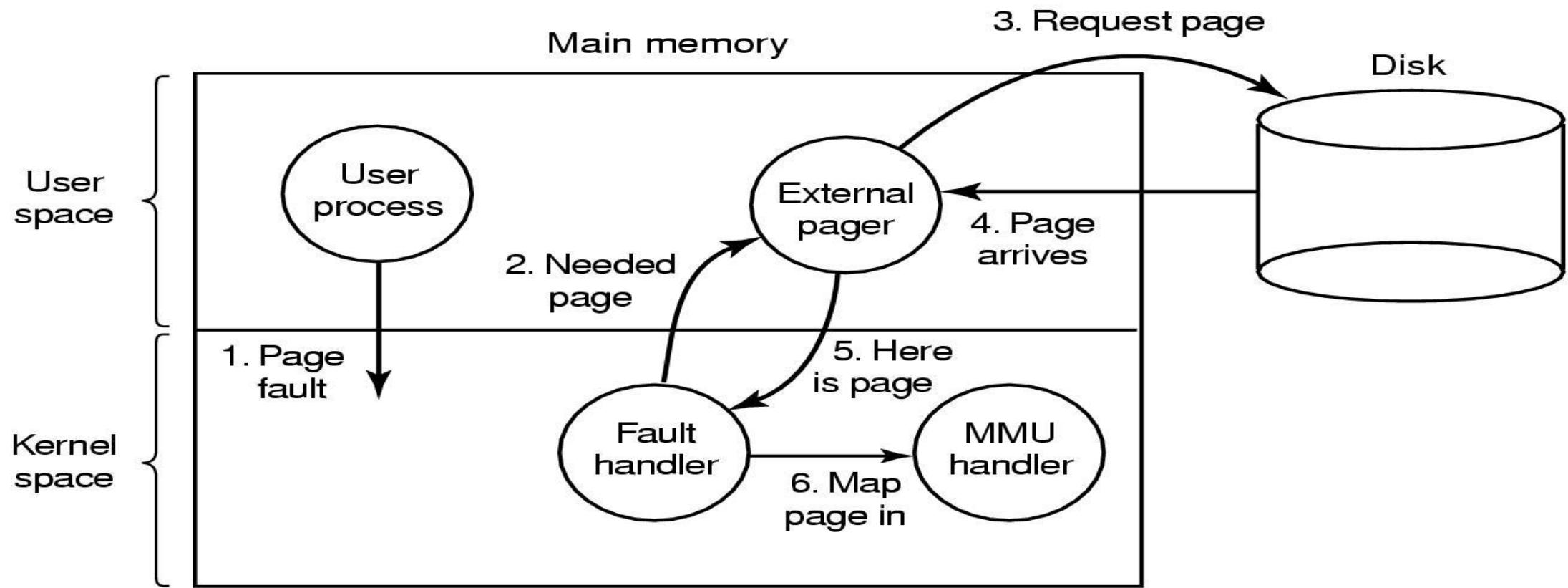


Virtual Memory

Implementation Issues

Separation of Policy and Mechanism

Page fault handling with an external pager

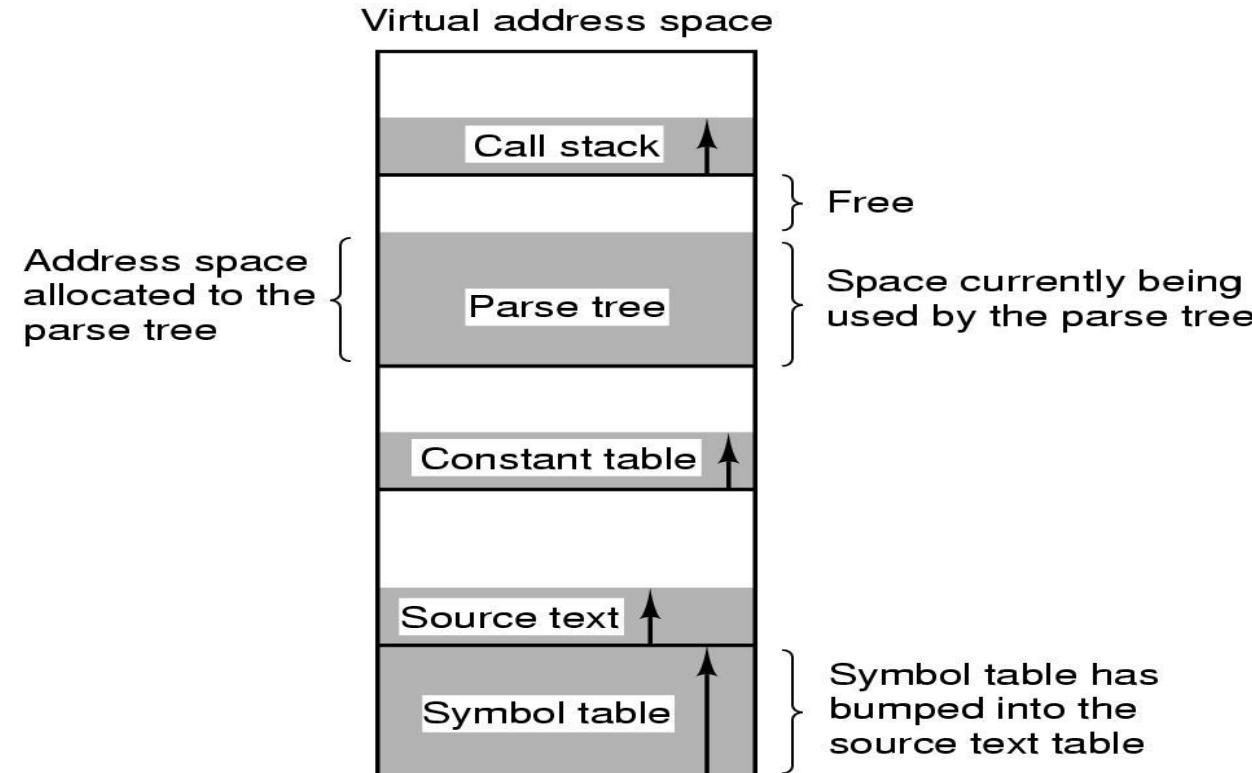




Virtual Memory Segmentation

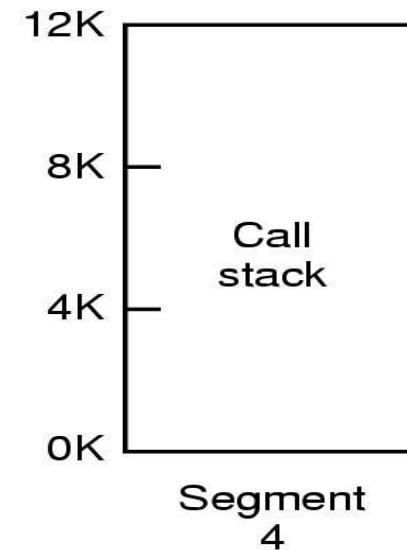
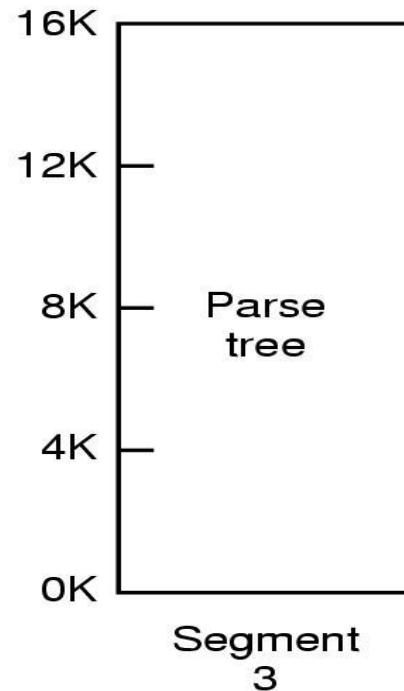
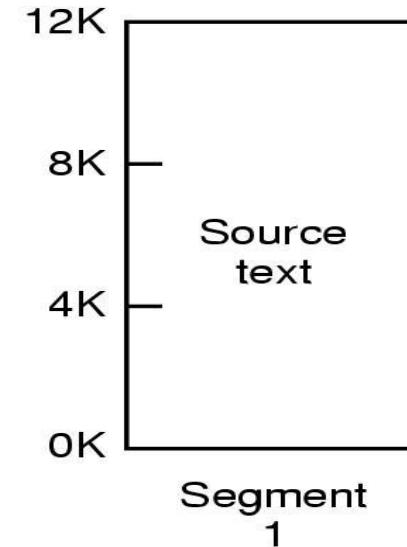
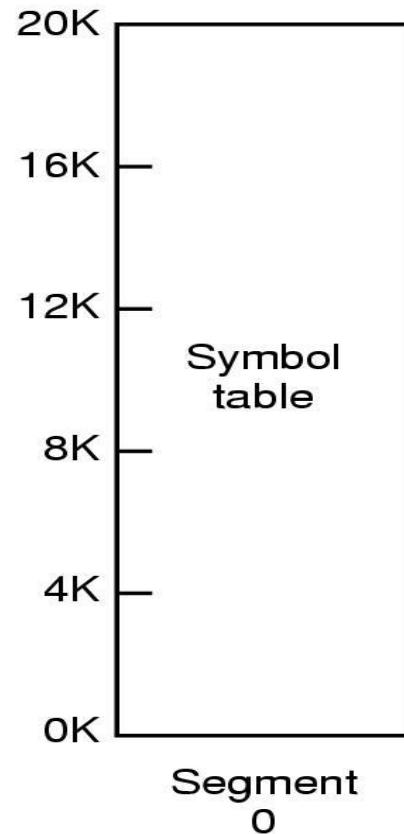
Virtual Memory Segmentation (1)

- One-dimensional address space with growing tables
- One table may bump into another



Virtual Memory Segmentation (2)

Allows each table to grow or shrink, independently





Virtual Memory

Segmentation (3)

Comparison of paging and segmentation

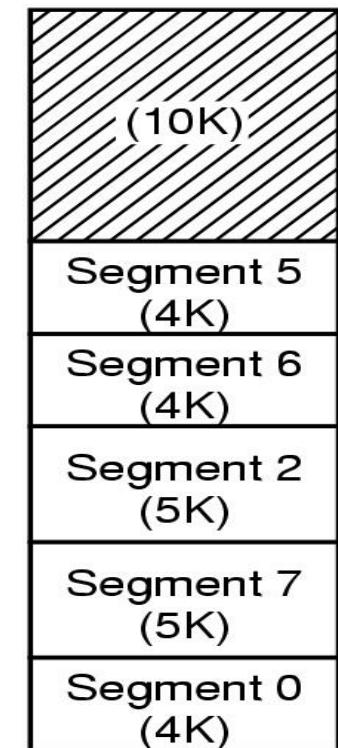
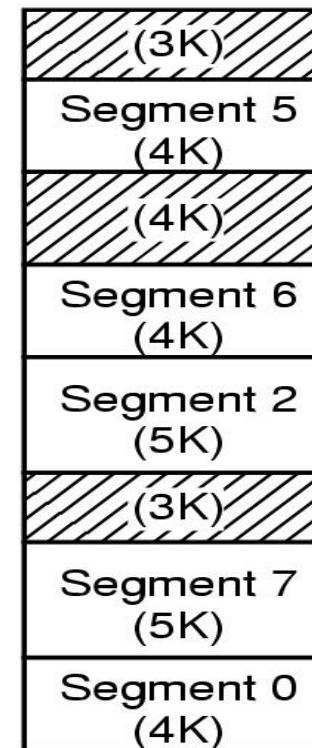
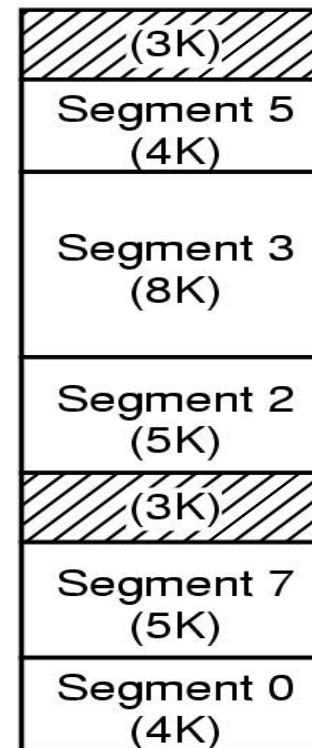
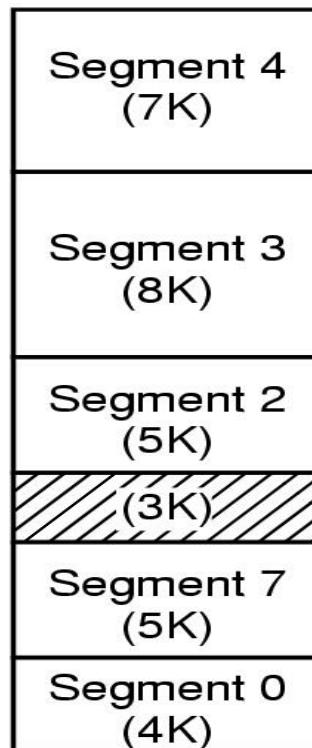
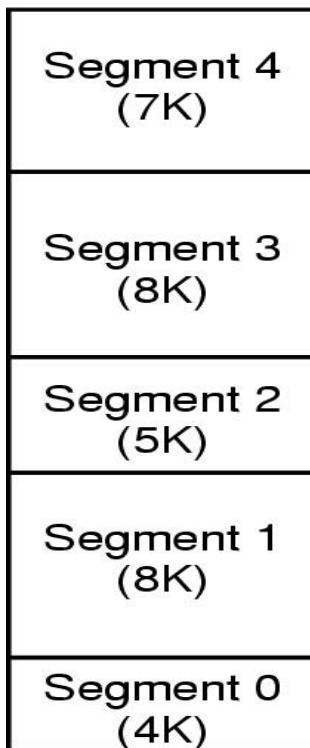
Consideration	Paging	Segmentation
Need the programmer be aware that this technique is being used?	No	Yes
How many linear address spaces are there?	1	Many
Can the total address space exceed the size of physical memory?	Yes	Yes
Can procedures and data be distinguished and separately protected?	No	Yes
Can tables whose size fluctuates be accommodated easily?	No	Yes
Is sharing of procedures between users facilitated?	No	Yes
Why was this technique invented?	To get a large linear address space without having to buy more physical memory	To allow programs and data to be broken up into logically independent address spaces and to aid sharing and protection

Virtual Memory

Implementation of Pure Segmentation (4)

(a)-(d) Development of checkerboarding

(e) Removal of the checkerboarding by compaction



(a)

(b)

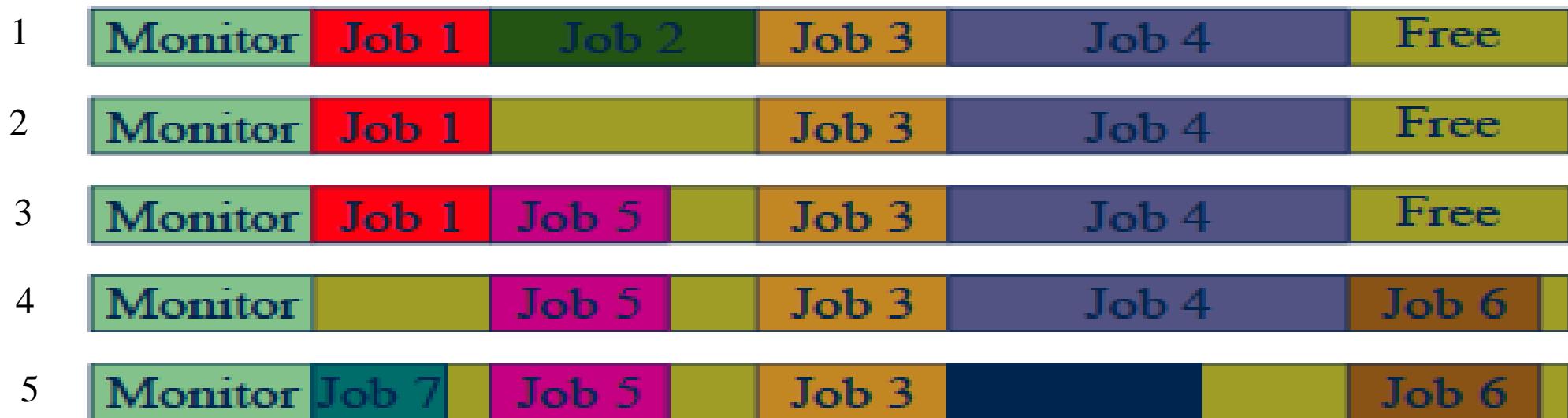
(c)

(d)

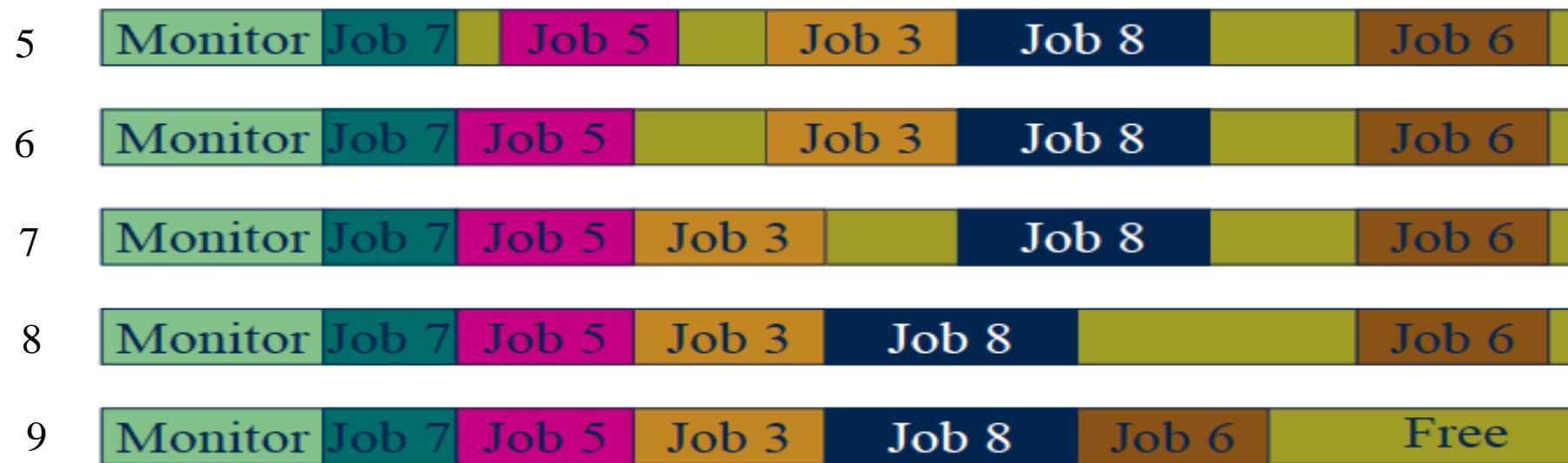
(e)

Variable Partitions and Fragmentation

Memory wasted by External Fragmentation

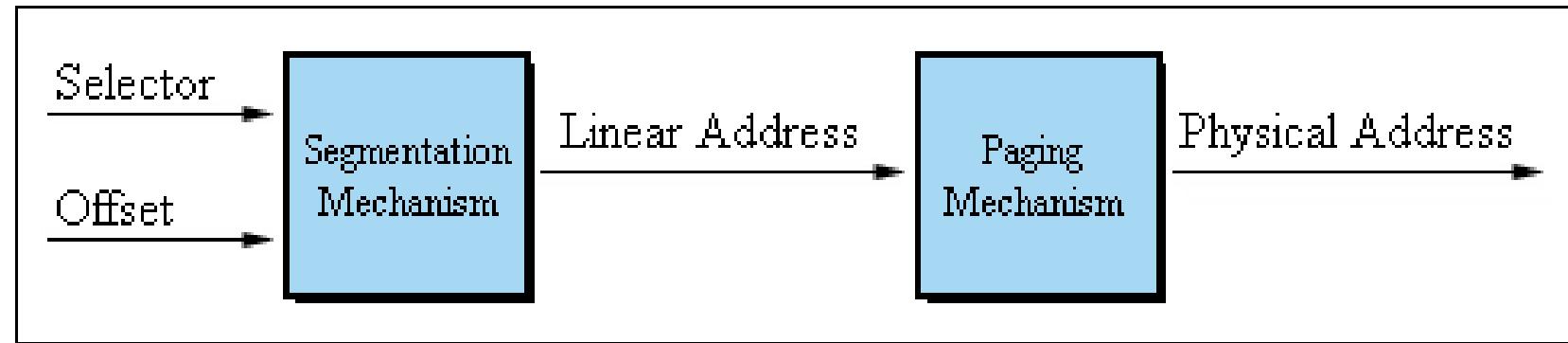


- Processes must be suspended during compaction
- Need be done only when fragmentation gets very bad



Virtual Memory

Segmentation with Paging: Pentium (1)

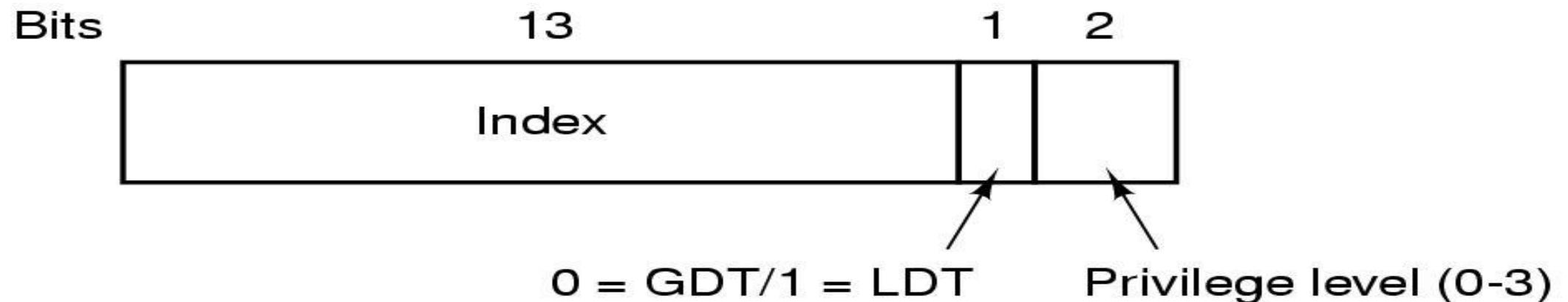


Virtual Memory

Segmentation with Paging: Pentium (2)

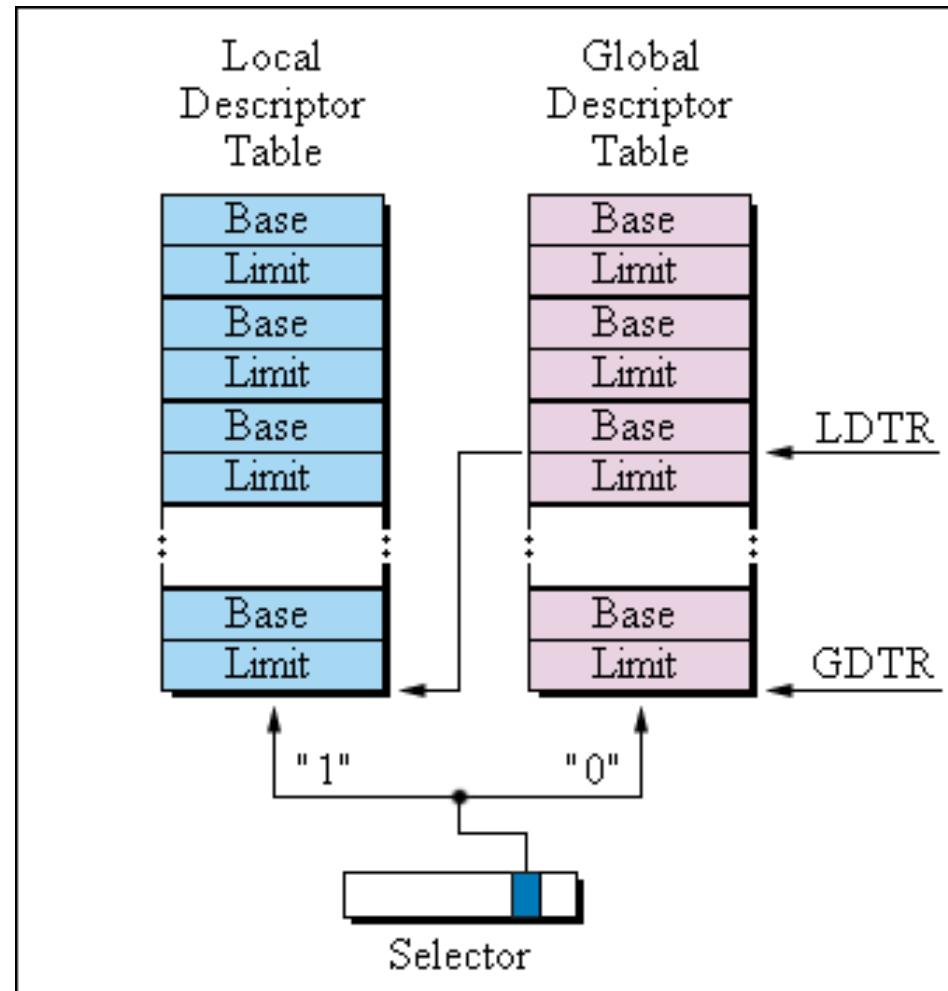
A Pentium selector

GDT (Global Descriptor Table), LDT (Local Descriptor Table)



Virtual Memory

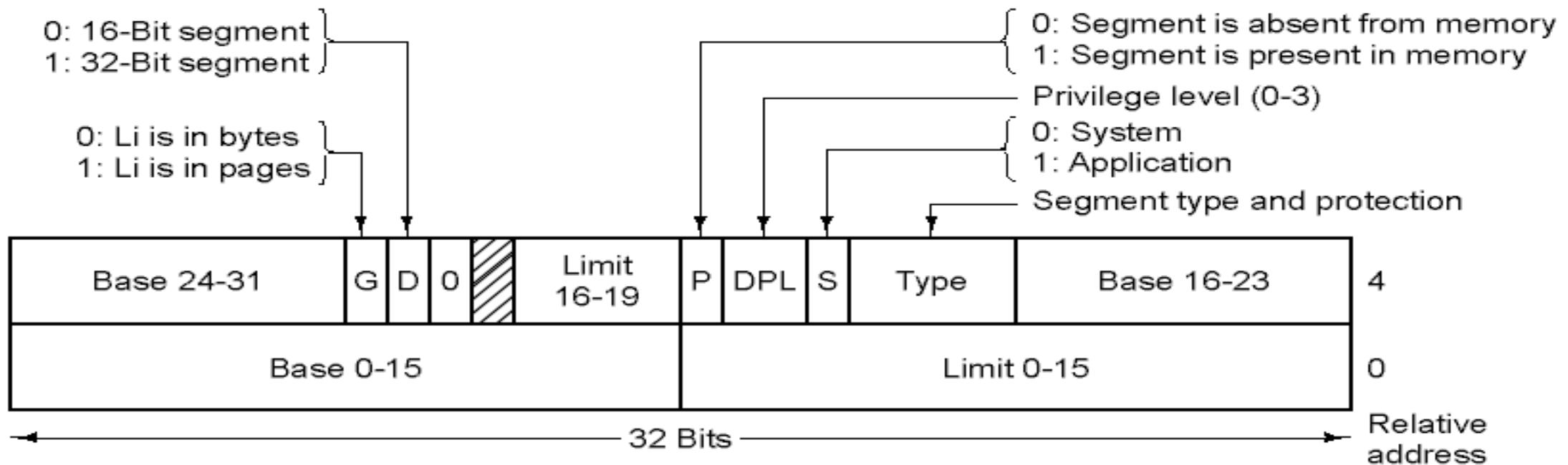
Segmentation with Paging: Pentium (3)



Virtual Memory

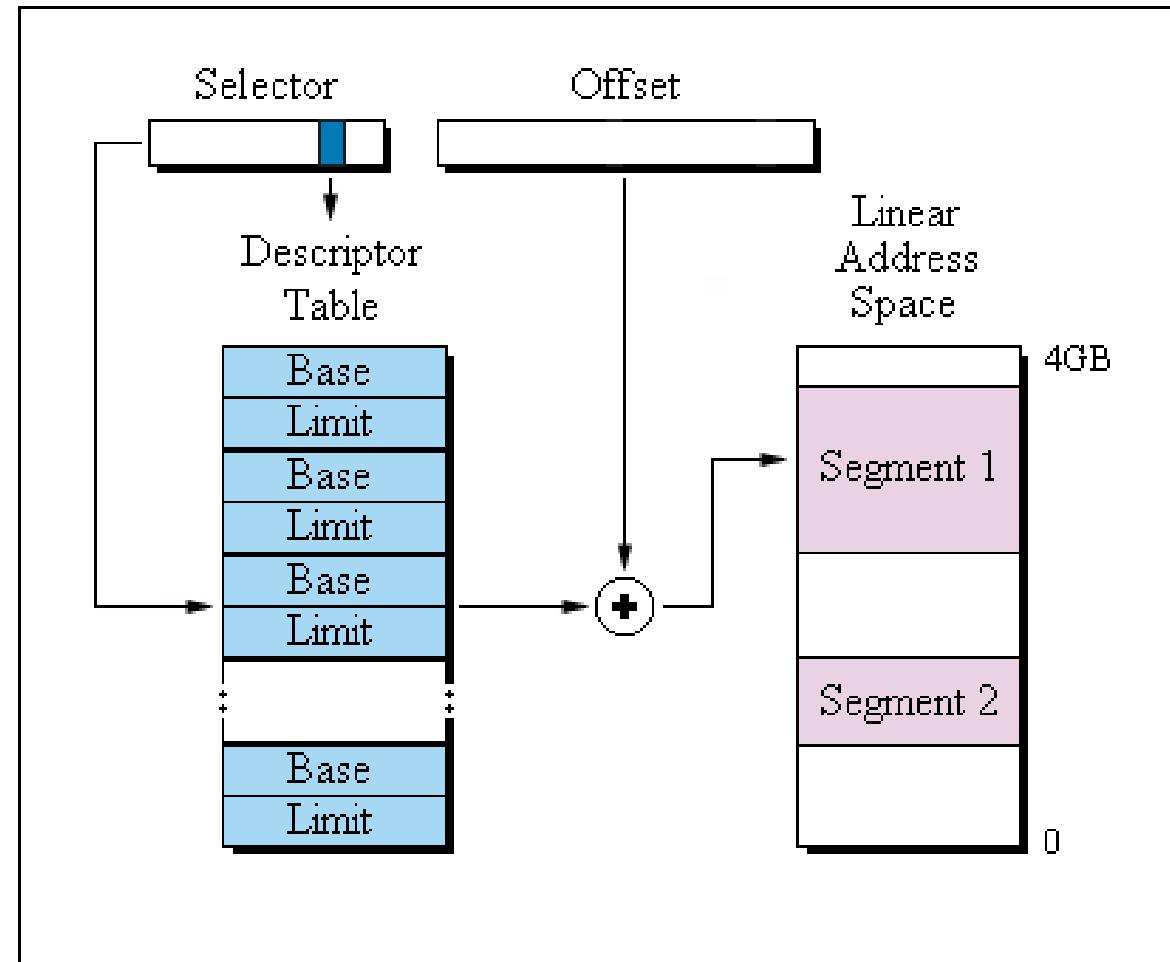
Segmentation with Paging: Pentium (4)

- Pentium code segment descriptor
- Data segments differ slightly



Virtual Memory

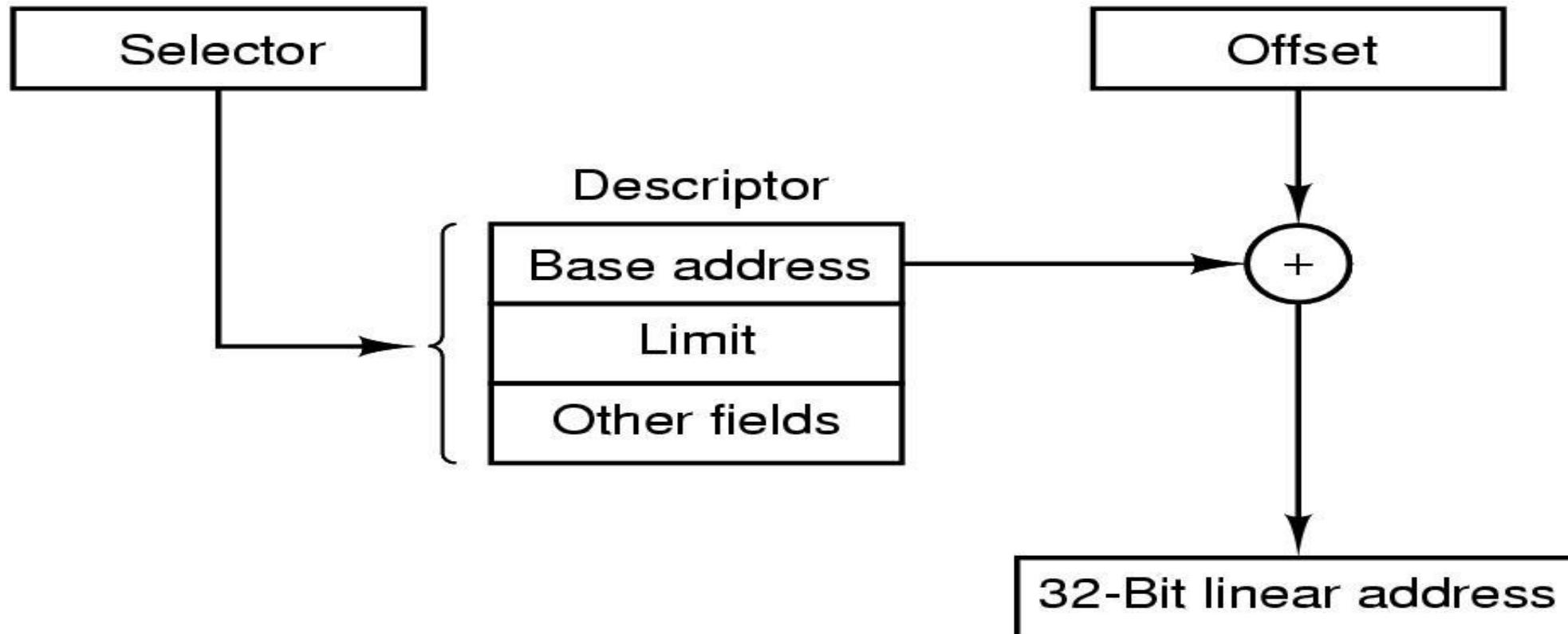
Segmentation with Paging: Pentium (5)



Virtual Memory

Segmentation with Paging: Pentium (6)

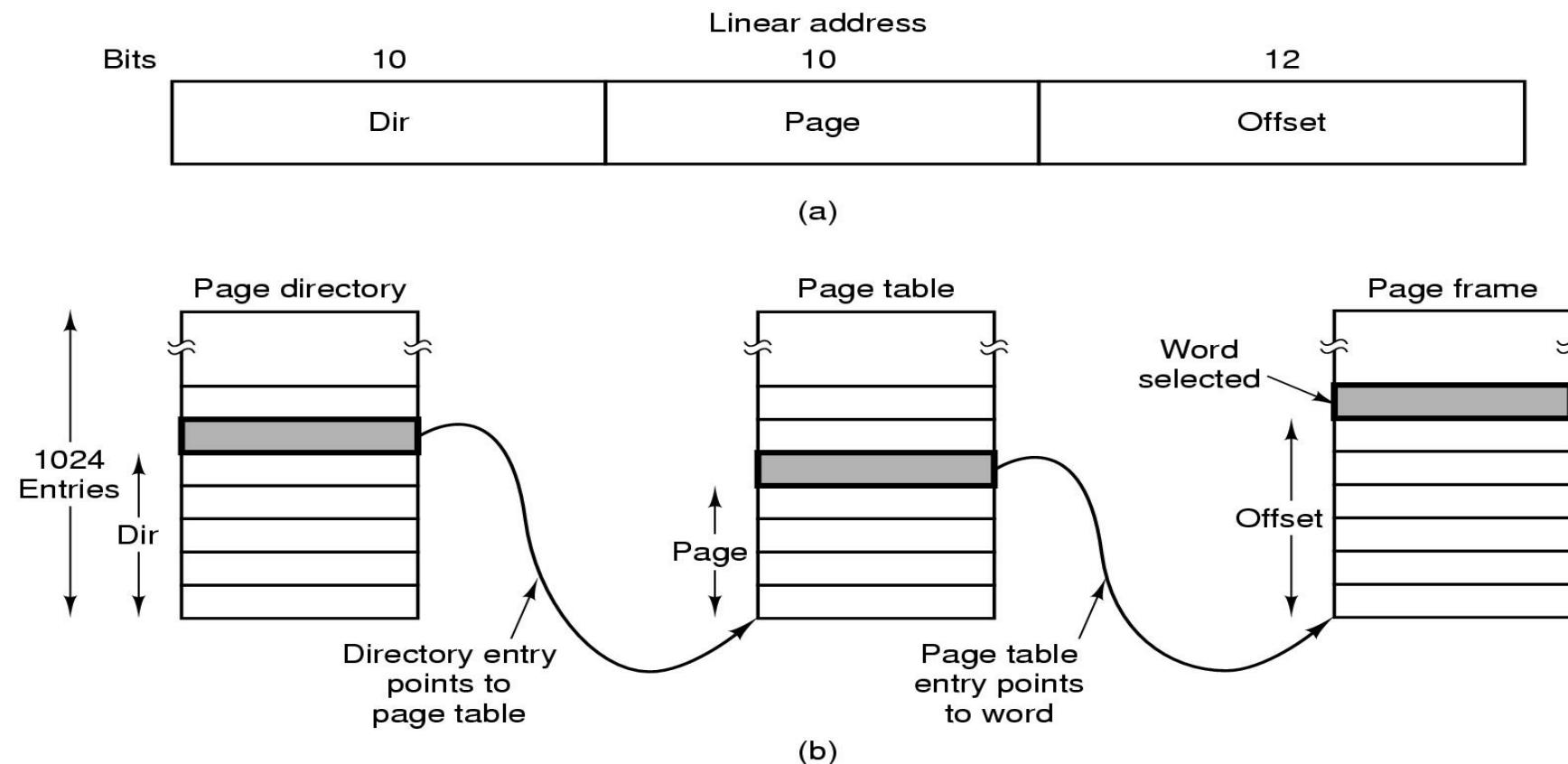
Conversion of a (selector, offset) pair to a linear address



Virtual Memory

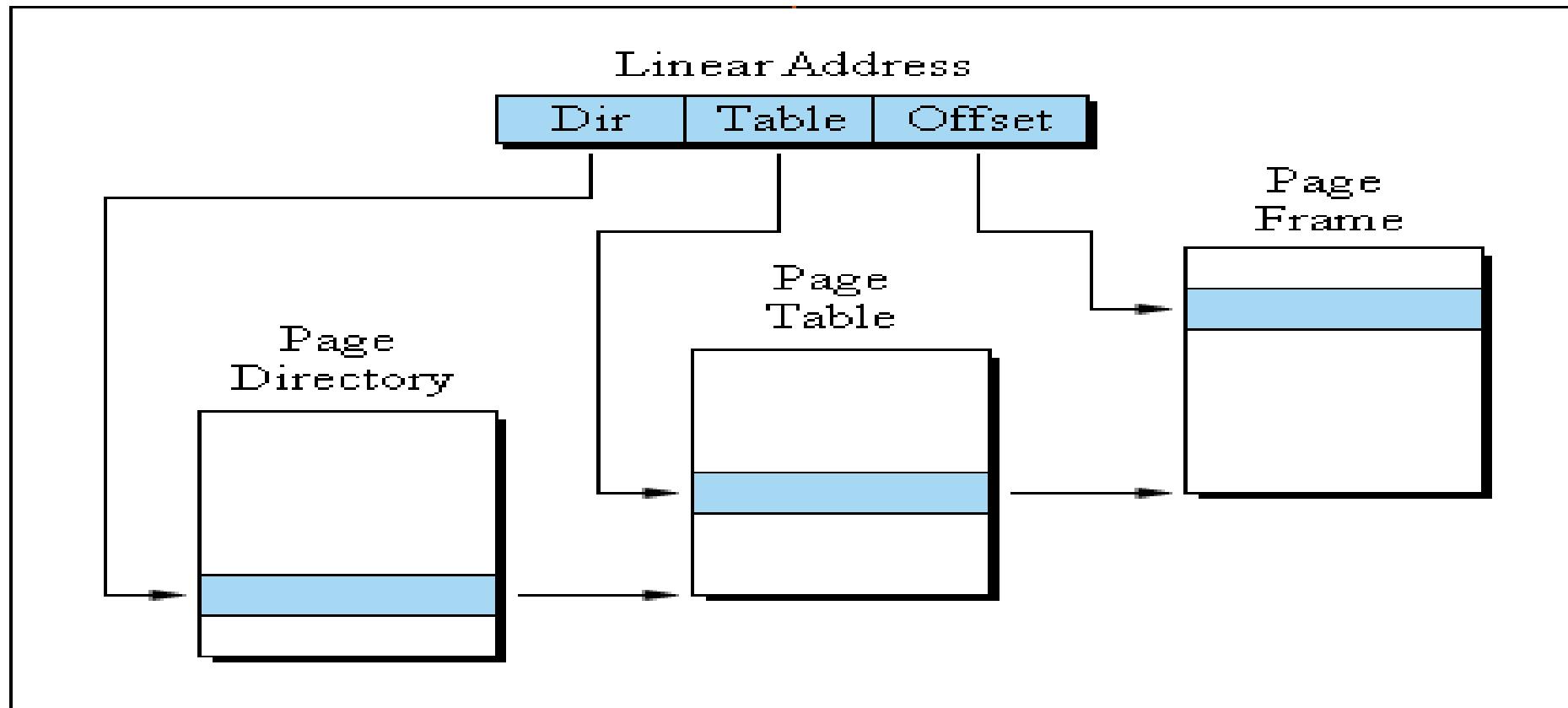
Segmentation with Paging: Pentium (7)

Mapping of a linear address onto a physical address



Virtual Memory

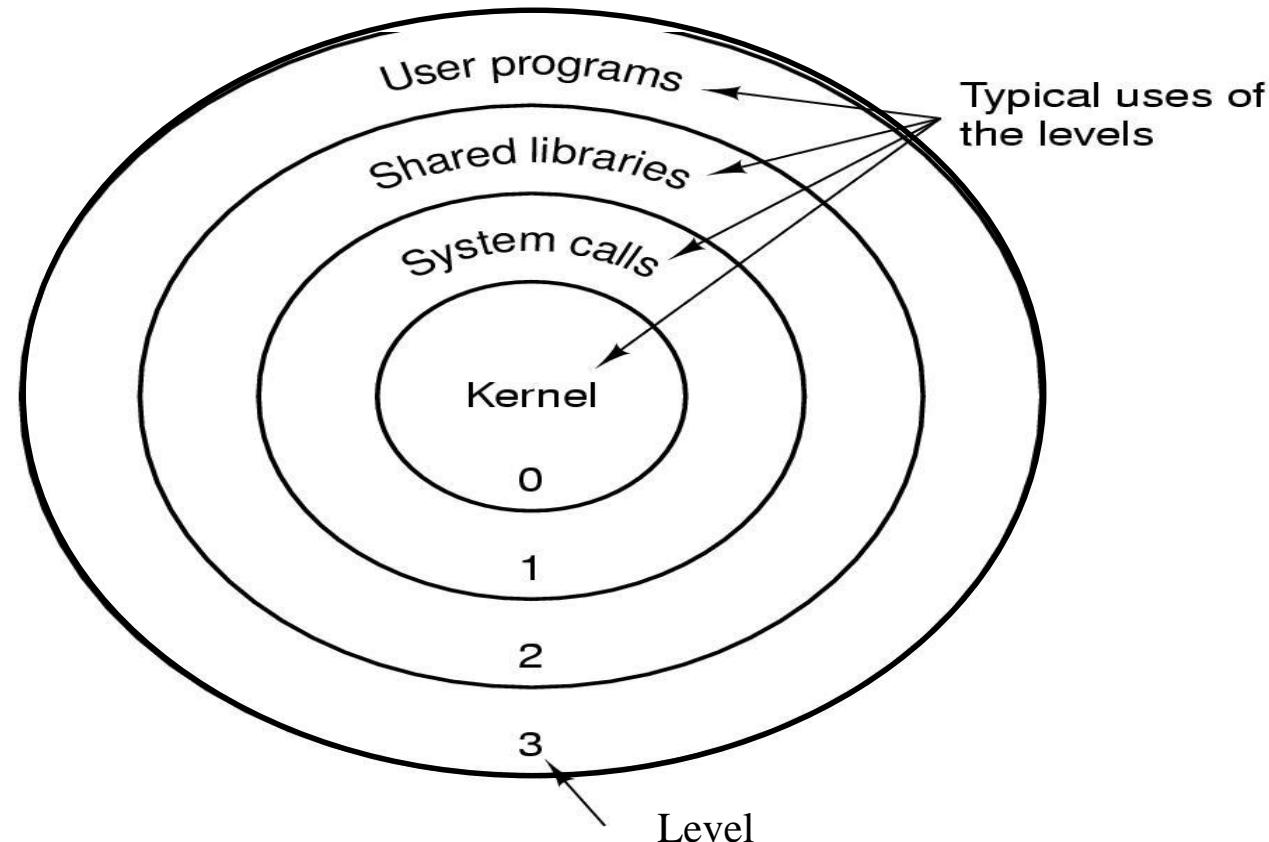
Segmentation with Paging: Pentium (8)



Virtual Memory

Segmentation with Paging: Pentium (9)

Protection on the Pentium





SUMMARY

- Basic memory management
- Swapping
- Virtual memory
- Design issues for paging systems
- Implementation issues
- Segmentation