

# BUU TRUONG PHAN

[truongbuu.github.io](https://truongbuu.github.io) - [truongbuu94@gmail.com](mailto:truongbuu94@gmail.com) - [Google Scholar](#) - [LinkedIn](#)

About me: I am a researcher in deep learning and computer vision, specialized in 3D object detection, uncertainty and adversarial robustness. Other interested research topics include: graph-based learning, matrix methods, information theory, optimization and probability.

Main toolkits and libraries: Python, Tensorflow, Pytorch, scikit-learn, C/C++, Git/Github, OpenCV, Docker.

## PROFESSIONAL EXPERIENCES

### LG Electronics AI Lab

*AI Research Engineer*

May 2021 - Now

Canada

- Developed a novel and occlusion-aware neural architecture for human pose estimation.
- Fast-prototype multiple AI solutions and export deep learning models for production.
- Research on out-of-distribution detection and graph-based learning.

### Algolux

*Research Scientist - Deep Learning and Computer Vision*

Oct 2019 - May 2021

Canada

- My role is to research and implement computer vision technologies for self-driving cars (3D stereo object detection, segmentation, tracking, etc.)
- Formulated and developed a new optimization algorithm for black-box adversarial attack that targets a specific ISP module.
- Proposed and developed a neural network model for the hidden objects tracking problem using radar (non-line-of-sight imaging). [Project Link](#).
- Developed and benchmarked different object detection architectures.
- Developed active learning algorithms for object detection.

### Waterloo Intelligent Systems Engineering Lab, University of Waterloo

*Graduate Research Assistant*

Sep 2017 - Sep 2019

Canada

- Researched in the area of Bayesian deep learning, image segmentation, active learning and anomaly detection. My thesis studies different aspects of Bayesian deep learning model in the context of road-scene image segmentation. [Thesis Link](#).
- Formulated and developed a distillation technique for Bayesian neural networks.
- Developed a camera obstruction detection model and integrated it from Tensorflow to C++.
- Developed functionalities for the Autonomoose self-driving car platform ([Project Autonomoose](#)).

### BlueSeed Digital

*Data Scientist Intern*

Dec 2016 - Jul 2017

Vietnam

- I developed machine learning models for market segmentation and topic modelling. I also integrated the model into production using Spark technologies.

## EDUCATION

### University of Waterloo

Master of Applied Science, Advisor: Prof. Krzysztof Czarnecki

Specialization: Pattern Analysis and Machine Intelligence

Sep 2017 - Sep 2019

Overall GPA: 93.17/100

### International University - Vietnam National University

B.Eng in Electrical Engineering (summa cum laude)

Sep 2012 - Sep 2016

Overall GPA: 91.5/100

## PUBLICATIONS

1. **Buu Phan**, Fahim Mannan and Felix Heide. "Adversarial Imaging Pipelines." CVPR, 2021.
2. Nicolas Scheiner, Florian Kraus, Fangyin Wei, **Buu Phan**, Fahim Mannan, Nils Appenrodt, Werner Ritter et al. "Seeing Around Street Corners: Non-Line-of-Sight Detection and Tracking In-the-Wild Using Doppler Radar." In Proceedings of the IEEE/CVF Conference on Computer Vision and Pattern Recognition, pp. 2068-2077. 2020. <https://www.cs.princeton.edu/~fheide/DopplerNLOS/>.
3. **Buu Phan**, Samin Khan, Rick Salay, and Krzysztof Czarnecki. "Bayesian uncertainty quantification with synthetic data." In International Conference on Computer Safety, Reliability, and Security, pp. 378-390. Springer, Cham, 2019. **Best paper award at the Second International Workshop on Artificial Intelligence Safety Engineering.**

4. Samin Khan, **Buu Phan**, Rick Salay, and Krzysztof Czarnecki. “ProcSy: Procedural Synthetic Dataset Generation Towards Influence Factor Studies Of Semantic Segmentation Networks.” In CVPR Workshops, pp. 88-96. 2019.
5. Sachin Vernekar, Ashish Gaurav, Taylor Denouden, **Buu Phan**, Vahdat Abdelzad, Rick Salay, and Krzysztof Czarnecki. “Analysis of confident-classifiers for out-of-distribution detection.” ICLR SafeML Workshop 2019.
6. **Buu Phan**, Rick Salay, Krzysztof Czarnecki, Vahdat Abdelzad, Taylor Denouden, Sachin Vernekar, “Calibrating Uncertainties in Object Localization Task”, NeurIPS Bayesian Deep Learning Workshop, 2018.
7. Ian Colwell, **Buu Phan**, Shahwar Saleem, Rick Salay, and Krzysztof Czarnecki. “An automated vehicle safety concept based on runtime restriction of the operational design domain.” In 2018 IEEE Intelligent Vehicles Symposium (IV), pp. 1910-1917. IEEE, 2018.

**PREPRINTS**

1. Abdelzad, Vahdat, Krzysztof Czarnecki, Rick Salay, Taylor Denouden, Sachin Vernekar, and **Buu Phan**. “Detecting Out-of-Distribution Inputs in Deep Neural Networks Using an Early-Layer Output.” arXiv preprint arXiv:1910.10307 (2019).
2. Denouden Taylor, Rick Salay, Krzysztof Czarnecki, Vahdat Abdelzad, **Buu Phan**, and Sachin Vernekar. “Improving reconstruction autoencoder out-of-distribution detection with mahalanobis distance.” arXiv preprint arXiv:1812.02765 (2018).

**AWARDS, SCHOLARSHIPS & ACHIEVEMENTS**

• Best paper award, Workshop on Artificial Intelligence Safety Engineering	2019
• Toyota Canada Graduate Scholarship	2018-2019
• NSERC CREATE, Student Grant	2018-2019
• Faculty of Engineering Awards for top graduate students, University of Waterloo	2018, 2019
• International Master’s Student Awards, University of Waterloo	2017-2019
• Graduate Research Studentship, University of Waterloo	2017
• Honor Student Award, Vietnam National University	2016
• Valedictorian, International University	2016