

Explainability AND Common Robustness

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School of Computer Science, Fudan University

Autumn, 2022

Reminder

Course page:

https://trustworthymachinelearning.github.io/

Textbook:

下载链接: https://pan.baidu.com/s/1kybxud_tz0xshWpMEORAhg?pwd=tauu

提取码: tauu



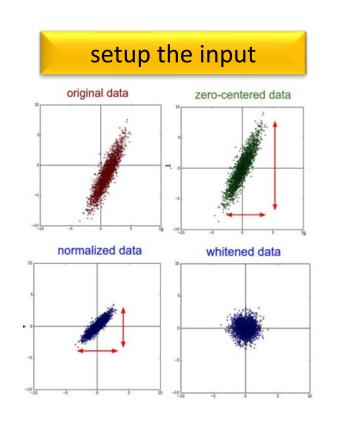
Recap: week 1

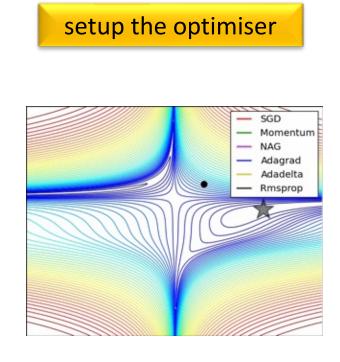
- 1. What is Machine Learning
- 2. Machine Learning Paradigms
- 3. Loss Functions

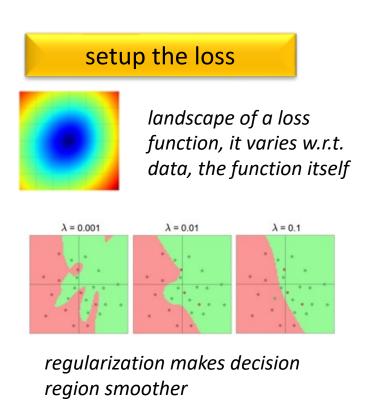
4. Optimization Methods



Machine Learning Pipeline

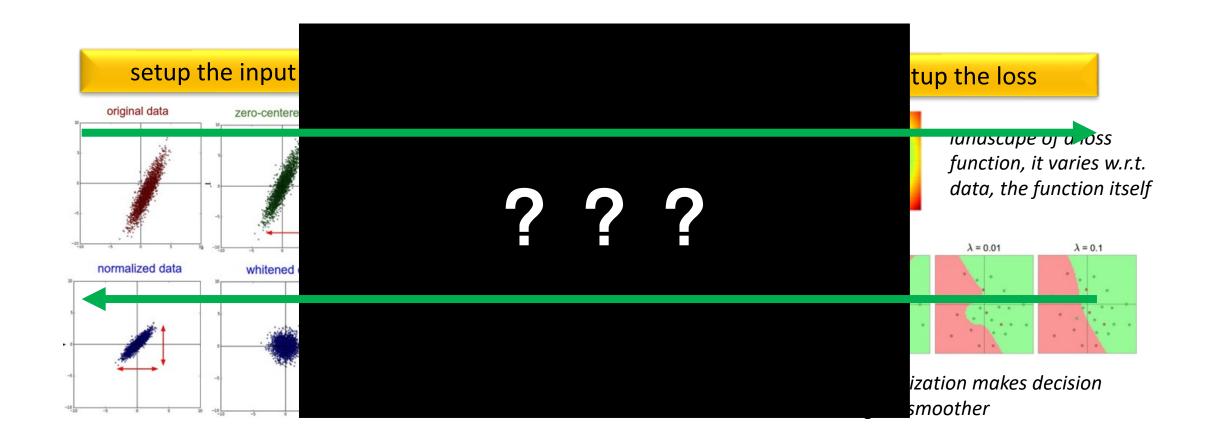






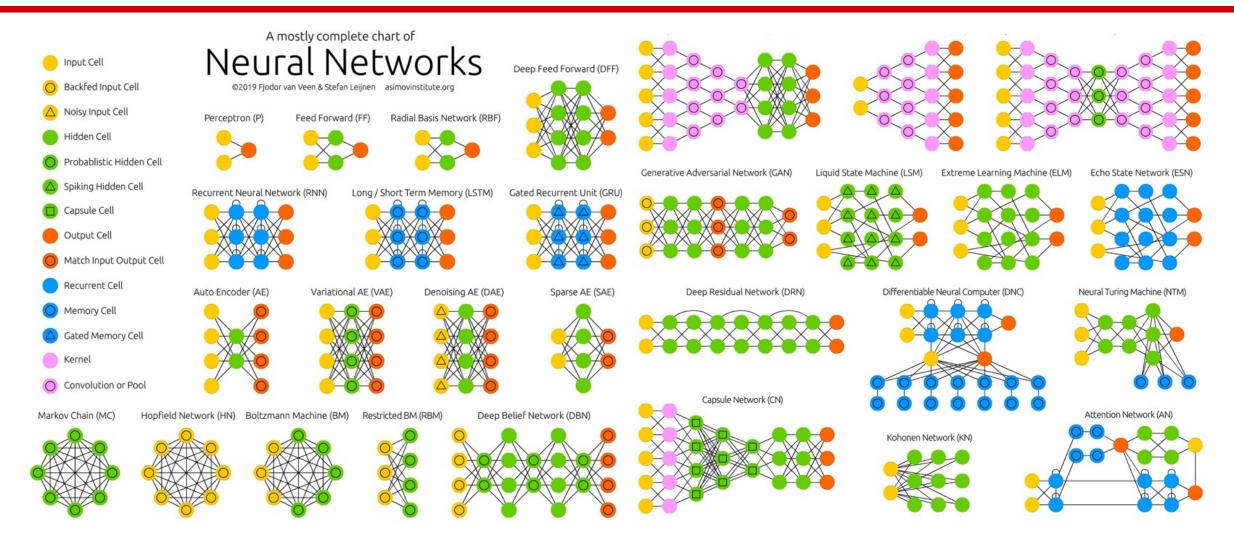


Machine Learning Pipeline





Deep Neural Networks

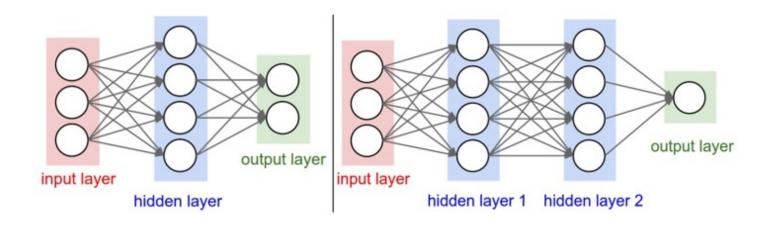


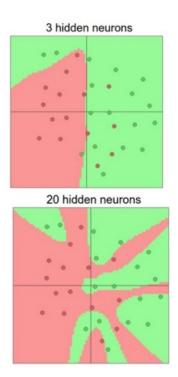
https://www.asimovinstitute.org/neural-network-zoo/; https://developer.ibm.com/articles/cc-machine-learning-deep-learning-architectures/



Feed-Forward Neural Networks

Feed-Forward Neural Networks (FNN)
Fully Connected Neural Networks (FCN)
Multilayer Perceptron (MLP)



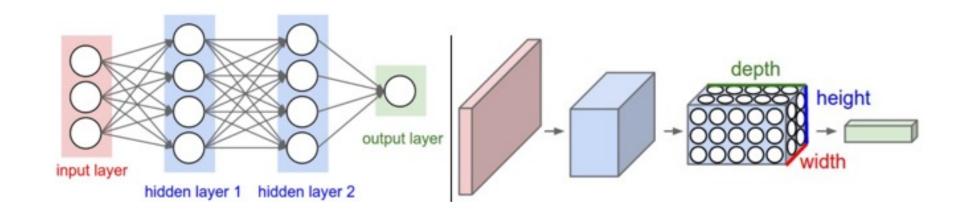


- The **simplest** neural network
- Fully-connected between layers
- For data that has NO temporal or spatial order

http://cs231n.stanford.edu/



Convolutional Neural Networks



Neurons in one flat layer

Neurons in 3 dimensions

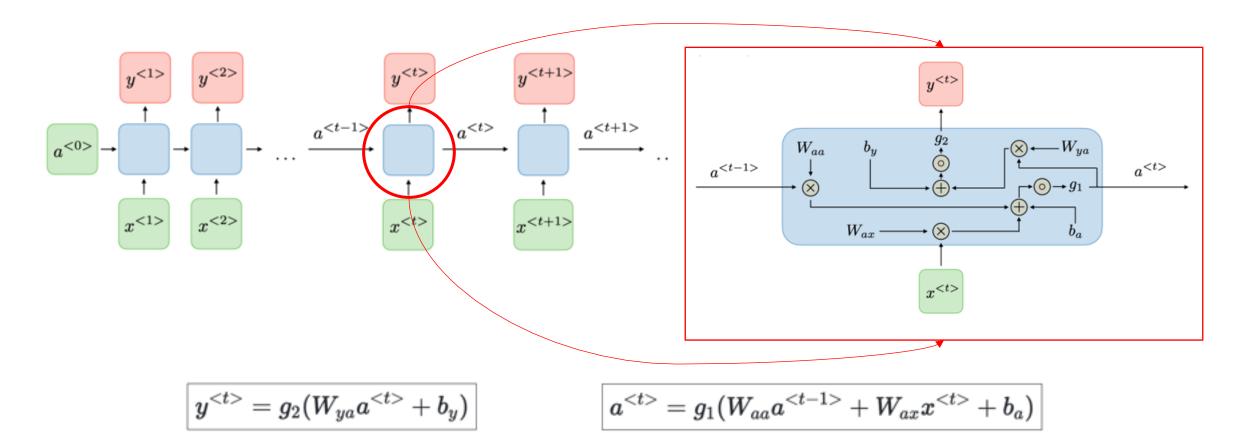
- For images or data with spatial order
- Can stack up to >100 layers

http://cs231n.stanford.edu/



Recurrent Neural Networks

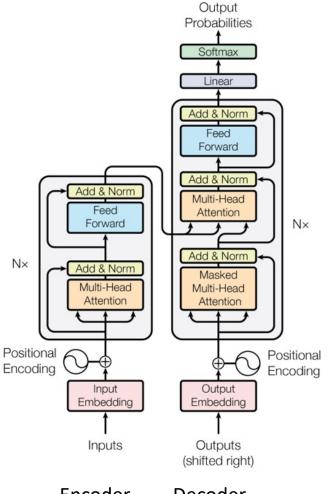
Traditional RNN



https://stanford.edu/~shervine/teaching/cs-230/cheatsheet-recurrent-neural-networks

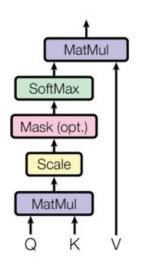


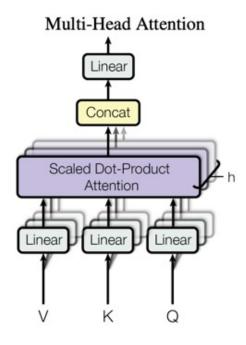
Recurrent Neural Networks



Transformer: a new type of DNNs based on attention







Encoder

Decoder

Vaswani, Ashish, et al. "Attention is all you need." Advances in neural information processing systems 30 (2017)



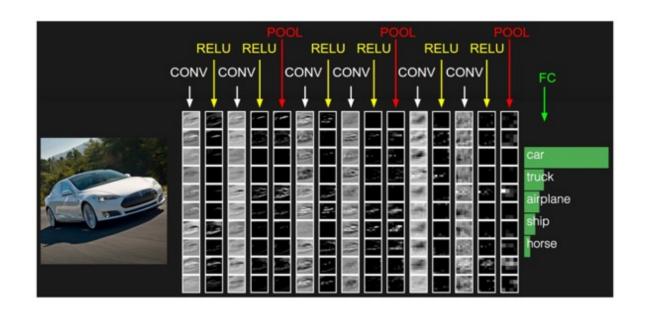
Self-Attention Explained



https://towardsdatascience.com/illustrated-self-attention-2d627e33b20a



CNN Explained



Learns different levels of representations

A brief history of CNNs:

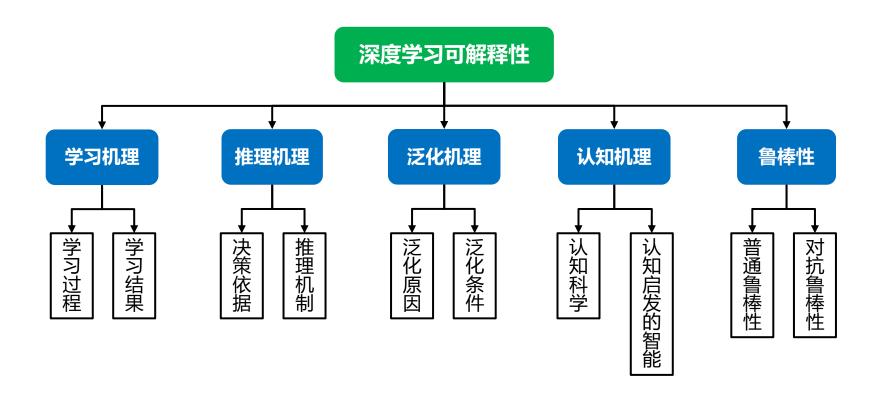
- LeNet, 1990s
- AlexNet, 2012
- ZF Net, 2013
- GoogLeNet, 2014
- VGGNet, 2014
- ResNet, 2015
- Inception V4, 2016
- ResNeXt, 2017
- ViT, 2021





http://cs231n.stanford.edu/

Explainable Machine Learning



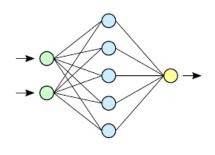
我们想要弄清楚下列问题:

- DNN是怎么学习的、学到了什么、靠什么泛化、在什么情况下行又在什么情况下不行?
- 深度学习是否是真正的智能,与人类智能比谁更高级,它的未来是什么?
- 是否存在大一统的理论,不但能解释而且能提高?

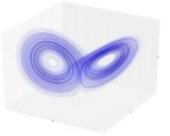


Methodological Principles









♦ Visualization

Model

Superclass

Training

◆Ablation

- Component
 Class

Inference

◆Contrast

Layer

- Training/Test set
- Transfer

Reverse

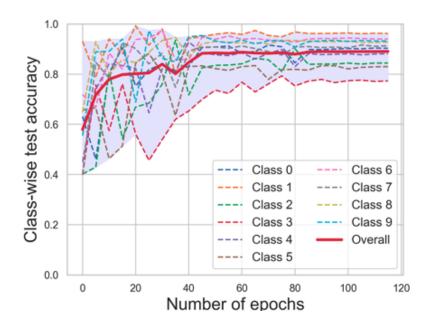
- Operation
- Subset

Neuron

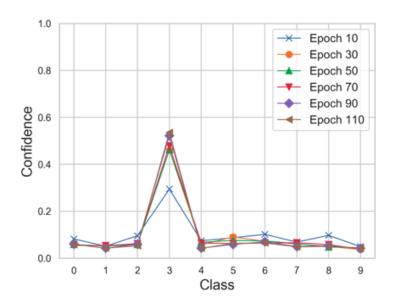
Sample



☐ Training/Test Error/Accuracy



■ Prediction Confidence

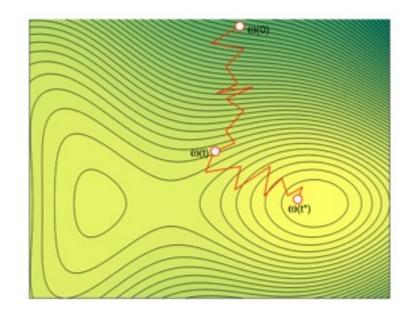


Explanation via observation: just plot!

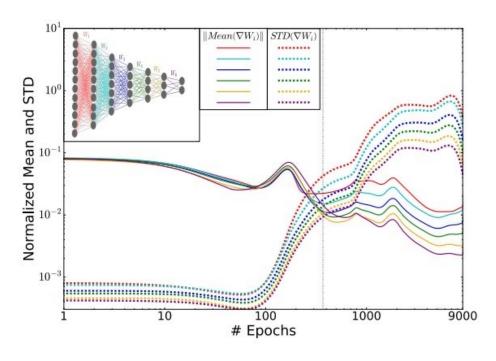
Wang et al. Symmetric Cross Entropy for Robust Learning with Noisy Labels, ICCV 2019.



□ Parameter dynamics



□ Gradient dynamics

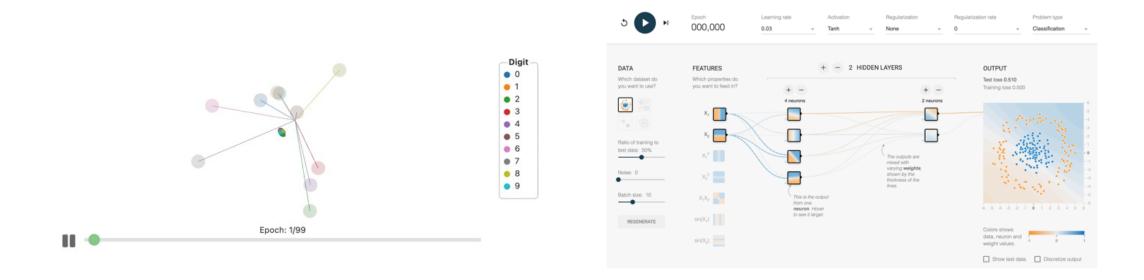


Explanation via dynamics and information

TRADI: Tracking deep neural network weight distributions, ECCV 2020; Shwartz-Ziv R, Tishby N. Opening the black box of deep neural networks via information[J]. arXiv:1703.00810, 2017.



□ Decision boundary, learning process visualization

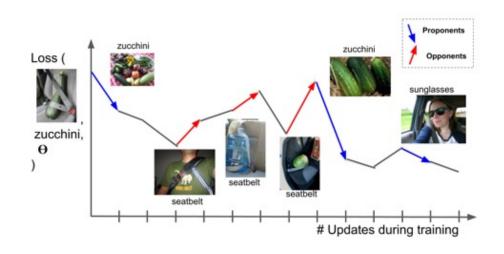


Explanation via dynamics and information

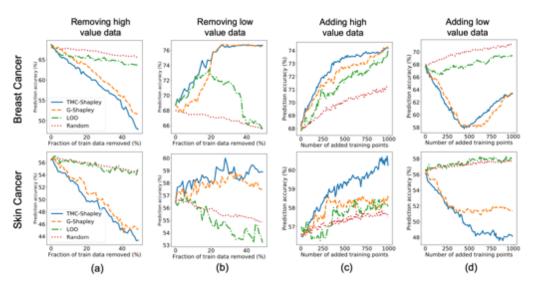
https://distill.pub/2020/grand-tour/ (March 16, 2020); https://playground.tensorflow.org/



□ Data influence/valuation: how a training sample impacts the learning outcome?



Influence Function



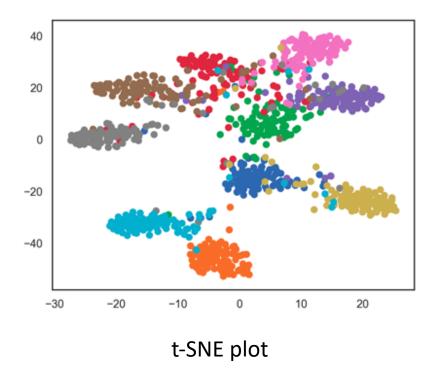
Data Shapley

Understanding Black-box Predictions via Influence Functions, ICML, 2018; Pruthi G, Liu F, Kale S, et al. Estimating training data influence by tracing gradient descent. NeurIPS, 2020. Data shapley: Equitable valuation of data for machine learning, ICML, 2019.

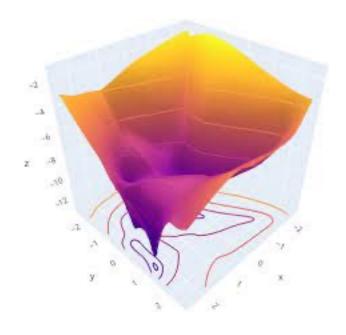


Understanding the Learned Model

□ Deep features



□ Loss Landscape

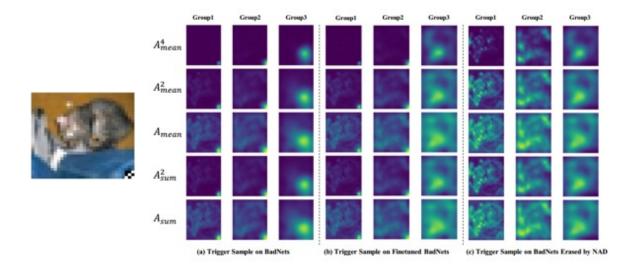


Maaten et al. Visualizing data using t-SNE. JMLR, 2008. https://distill.pub/2016/misread-tsne/?_ga=2.135835192.888864733.1531353600-1779571267.1531353600



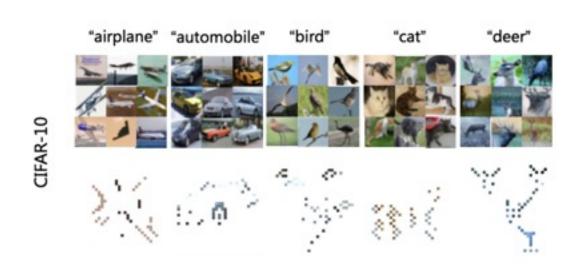
Understanding the Learned Model

□ Intermediate Layer Activation Map



Activation/Attention Map

□ Class-wise Patterns



One predictive pattern for each class

Li et al. Neural Attention Distillation: Erasing Backdoor Triggers from Deep Neural Network, ICLR 2021; Zhao et al. What do deep nets learn? class-wise patterns revealed in the input space. arXiv:2101.06898 (2021).



Inference Mechanism

□ Guided Backpropagation

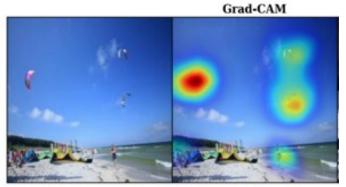


(a) Original Image



(b) Guided Backprop 'Cat'

□ Class Activation Map (Grad-CAM)



A group of people flying kites on a beach



A man is sitting at a table with a pizza

Selvaraju et al. Grad-cam: Visual explanations from deep networks via gradient-based localization. ICCV 2017. Springenberg et al. Striving for Simplicity: The All Convolutional Net, ICLR 2015.



Guided Backpropagation

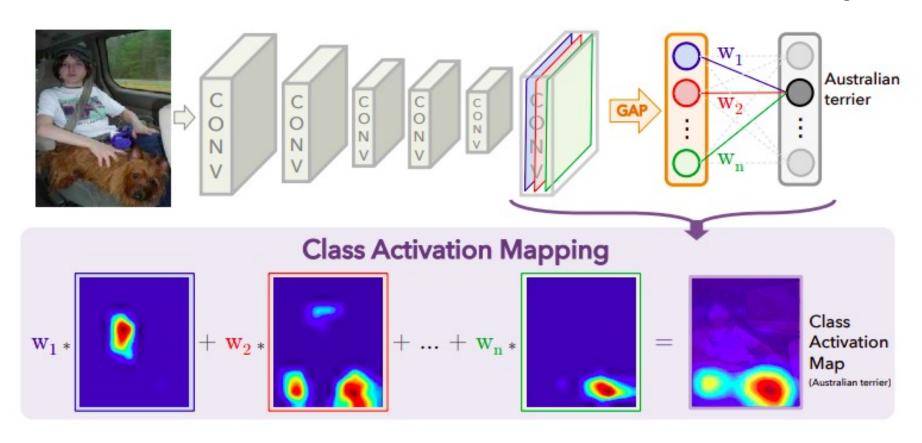
ReLU forward pass
$$h^{l+1} = \max\{0, h^l\} \text{ Forward pass } h^l \begin{array}{c} 1 & 1 & 5 \\ 2 & 5 & 7 \\ \hline 3 & 2 & 4 \end{array} \rightarrow \begin{array}{c} 1 & 0 & 5 \\ 2 & 0 & 0 \\ \hline 0 & 2 & 4 \end{array} h^{l+1}$$
 ReLU backward pass:
$$\frac{\partial L}{\partial h^l} = \begin{bmatrix} h^l > 0 \end{bmatrix} \frac{\partial L}{\partial h^{l+1}} \text{ Backward pass: backpropagation} \begin{array}{c} -2 & 0 & -1 \\ 6 & 0 & 0 \\ \hline 0 & -1 & 3 \end{array} \rightarrow \begin{array}{c} -2 & 3 & -1 \\ 6 & -3 & 1 \\ \hline 2 & -1 & 3 \end{array}$$
 Deconvolution for ReLU
$$\frac{\partial L}{\partial h^l} = \begin{bmatrix} h^{l+1} > 0 \end{bmatrix} \frac{\partial L}{\partial h^{l+1}} \text{ Backward pass: } \begin{array}{c} 0 & 3 & 0 \\ 6 & 0 & 1 \\ \hline 2 & 0 & 3 \end{array} \rightarrow \begin{array}{c} -2 & 3 & -1 \\ 6 & -3 & 1 \\ \hline 0 & 0 & 1 \end{array}$$
 Guided Backpropagation
$$\frac{\partial L}{\partial h^l} = \begin{bmatrix} (h^l > 0) \& \& (h^{l+1} > 0) \end{bmatrix} \text{ Backward pass: } \begin{array}{c} 0 & 0 & 0 \\ 6 & 0 & 1 \\ \hline 2 & 0 & 3 \end{array} \rightarrow \begin{array}{c} -2 & 3 & -1 \\ 6 & -3 & 1 \\ \hline 0 & 0 & 1 \end{array}$$

Springenberg et al. Striving for Simplicity: The All Convolutional Net, ICLR 2015. https://medium.com/@chinesh4/generalized-way-of-interpreting-cnns-a7d1b0178709



Class Activation Mapping (CAM)

GAP: Global Average Pooling



Zhou et al. Learning Deep Features for Discriminative Localization. CVPR, 2016. https://medium.com/@chinesh4/generalized-way-of-interpreting-cnns-a7d1b0178709



Grad-CAM

Grad-CAM is a generalization of CAM

global average pooling

Compute **neuron importance**:

$$\alpha_k^c = \overbrace{\frac{1}{Z}\sum_i\sum_j}^{2}\underbrace{\frac{\partial y^c}{\partial A_{ij}^k}}_{\text{gradients via backprop}}$$

 y^c : logits of class c (before softmax) A^k : k-th channel activation map

Weighted combination of activation map, then **interpolation**:

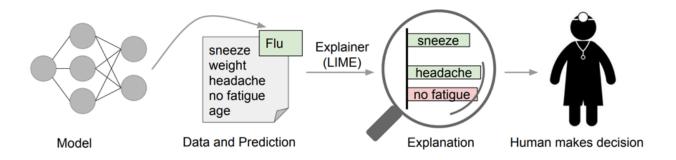
$$L_{\text{Grad-CAM}}^{c} = ReLU \left(\sum_{k} \alpha_{k}^{c} A^{k} \right)$$
linear combination

B. Zhou, A. Khosla, L. A., A. Oliva, and A. Torralba. Learning Deep Features for Discriminative Localization. In CVPR, 2016; https://medium.com/@chinesh4/generalized-way-of-interpreting-cnns-a7d1b0178709



LIME

□ Local Interpretable Model-agnostic Explanations (LIME)











(b) Explaining Electric guitar (c) Explaining Acoustic guitar

(d) Explaining Labrador

$$\xi(x) = \underset{g \in G}{\operatorname{argmin}} \ \mathcal{L}(f, g, \pi_x) + \Omega(g)$$

$$\mathcal{L}(f, g, \pi_x) = \sum_{z, z' \in \mathcal{Z}} \pi_x(z) \left(f(z) - g(z') \right)^2$$

 π_x : local neighborhood of x

z: sampled neighbor points

g: explainer e.g a linear model

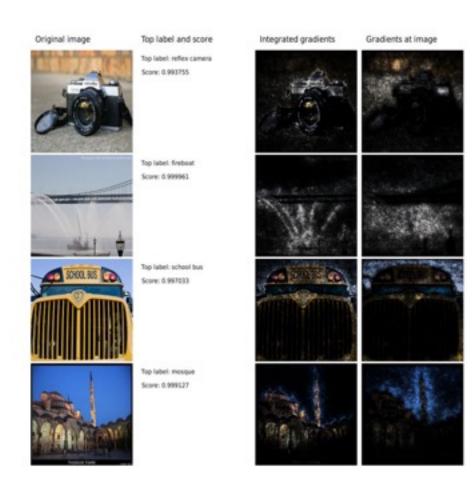
 z^\prime : a binary vector for interpretable

representation(e.g. patch)

Ribeiro et al. "Why should i trust you?" Explaining the predictions of any classifier. "SIGKDD, 2016. https://github.com/marcotcr/lime



Integrated Gradients



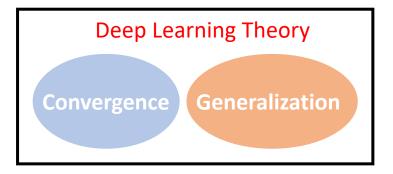
$$\mathsf{IntegratedGrads}_i(x) ::= (x_i - x_i') \times \int_{\alpha = 0}^1 \tfrac{\partial F(x' + \alpha \times (x - x'))}{\partial x_i} \ d\alpha$$

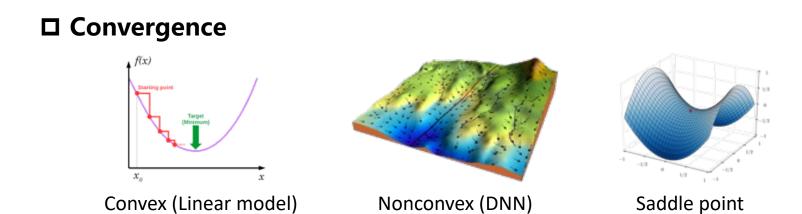
- There is a path: $x_i \rightarrow x_i'$
- Traverse the path using α
- Integrate the gradients along the way

Sundararajan M, Taly A, Yan Q. Axiomatic attribution for deep networks, ICML, 2017. https://github.com/TianhongDai/integrated-gradient-pytorch

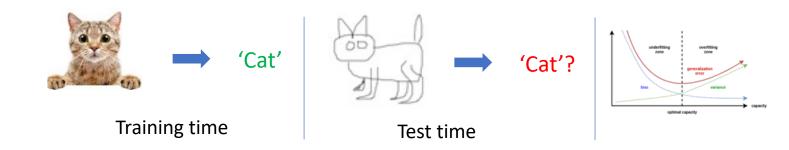


Generalization Mechanism





□ Generalization



Traditional theory: simpler model is better, more data is better



Generalization Theory

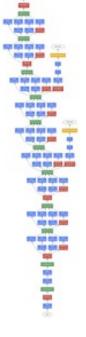
□ Components of Generalization Error Bounds

$$\operatorname{err}_D(h) \leq \widehat{\operatorname{err}}_S(h) + R_m(\mathcal{H}) + \sqrt{\frac{\ln{(1/\delta)}}{m}}$$
 generalization empirical hypothesis confidence error class complexity

RHS: for all terms, the lower the better:

- small training error
- simpler model class
- more samples
- less confidence



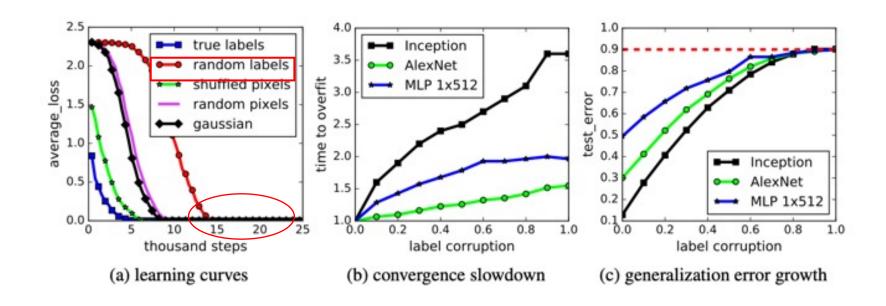


https://www.cs.cmu.edu/~ninamf/ML11/lect1117.pdf; https://www.youtube.com/watch?v=zlqQ7VRba2Y



Generalization Theory

□ Small training error ≠ low generalization error



Zero training error was achieved on **purely random labels** (meaningless learning)

0 training error vs. 0.9 test error

Zhang et al. Understanding deep learning requires rethinking generalization. ICLR 2017.



List of Existing Theories

- Rademacher Complexity bounds (Bartlett et al. 2017)
- PAC-Bayes bounds (Dziugaite and Roy 2017)
- Information bottleneck (Tishby and Zaslavsky 2015)
- Neural tangent kernel/Lazy training (Jacot et al. 2018)
- Mean-field analysis (Chizat and Bach 2018)
- Doule Descent (Belkin et al. 2019)
- Entropy SGD (Chaudhari et al. 2019)

A few interesting questions:

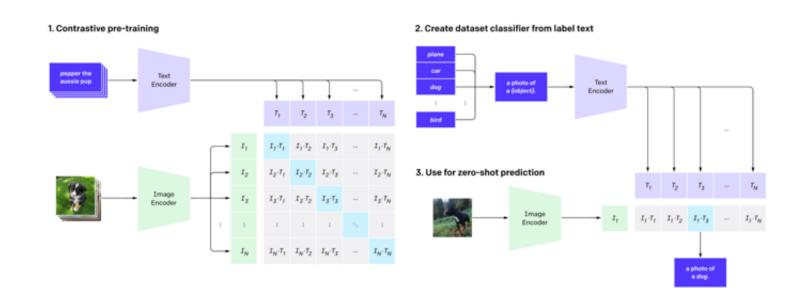
- > Should we consider the role of data in generalization analysis?
- > Should representation quality appear in the generalization bound?
- Generalization is about math (the function of the model) or knowledge?



How to visualize generalization?

- **□** Existing approaches
 - test error
 - Visualization: loss landscape, prediction attribution, etc.
 - Training -> test: distribution shift, out-of-distribution analysis
 - Noisy labels in test data questioning data quality and reliable evaluation
- **□** The remaining questions:
 - **□** how generalization happens?
 - **□** Math ≠ Knowledge
 - □ Computation = finding patterns or understanding the underlying knowledge
 - What is the relation of computational generalization to human behavior?

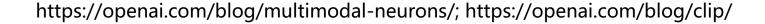








OpenAI reveals the multimodal neurons in CLIP









shape match = prob means
shape bias

cognitive psychology inspired evaluation of DNNs

Ritter et al. Cognitive Psychology for Deep Neural Networks: A Shape Bias Case Study, ICML, 2017









Article: Super Bowl 50

Paragraph: "Peython Manning became the first quarterback ever to lead two different teams to multiple Super Bowls. He is also the oldest quarterback ever to play in a Super Bowl at age 39. The past record was held by John Elway, who led the Brancos to victory in Super Bowl XXXIII at age 38 and is currently Denver's Executive Vice President of Football Operations and General Manager. Quarterback Jeff Dean had a jersey number 37 in Champ Bowl XXXIV."

Question: "What is the name of the quarterback who was 38 in Super Bowl XXXIII?"

Original Prediction: John Elway

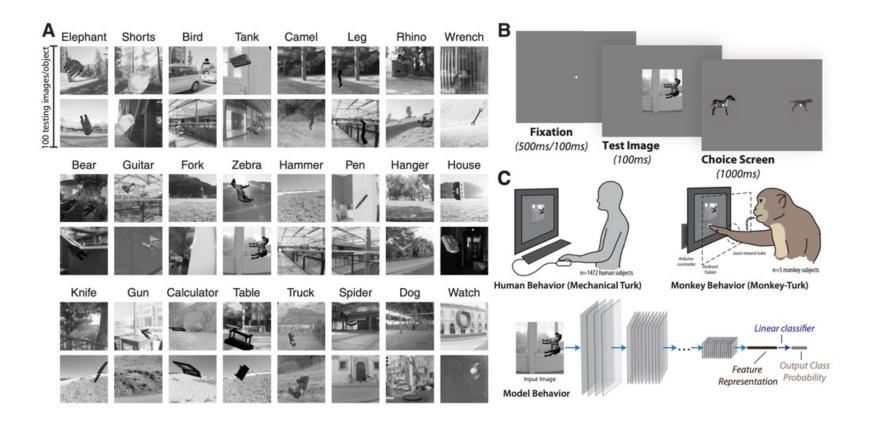
Prediction under adversary: Jeff Dean

Task for DNN	Caption image	Recognise object	Recognise pneumonia	Answer question
Problem	Describes green hillside as grazing sheep	Hallucinates teapot if cer- tain patterns are present	Fails on scans from new hospitals	Changes answer if irrelevant information is added
Shortcut	Uses background to recognise primary object	Uses features irrecognisable to humans	Looks at hospital token, not lung	Only looks at last sentence and ignores context

Deep neural networks solve problems by taking shortcuts

Geirhos, Robert, et al. "Shortcut learning in deep neural networks." *Nature Machine Intelligence* 2.11 (2020): 665-673.





Behavioral Prediction Task: Human vs. Monkey vs. Deep Nets

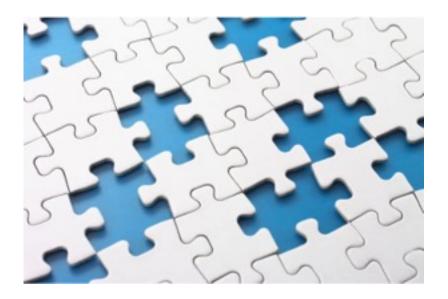
Rajalingham, Rishi, et al. "Large-scale, high-resolution comparison of the core visual object recognition behavior of humans, monkeys, and state-of-the-art deep artificial neural networks." *Journal of Neuroscience* 38.33 (2018): 7255-7269. Rajalingham, Rishi, Kailyn Schmidt, and James J. DiCarlo. "Comparison of object recognition behavior in human and monkey." Journal of Neuroscience 35.35 (2015): 12127-12136.



What is Missing

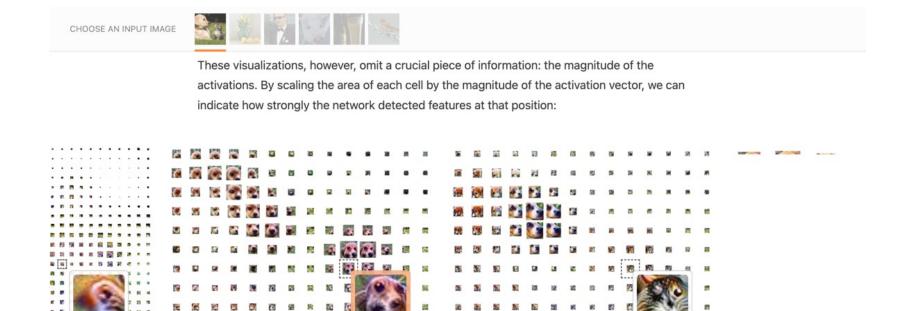
Many theoretical work or interpretation tools have been proposed

Yet, we don't have an all-in-one system to explain everything.





FudanNLP TextFlint

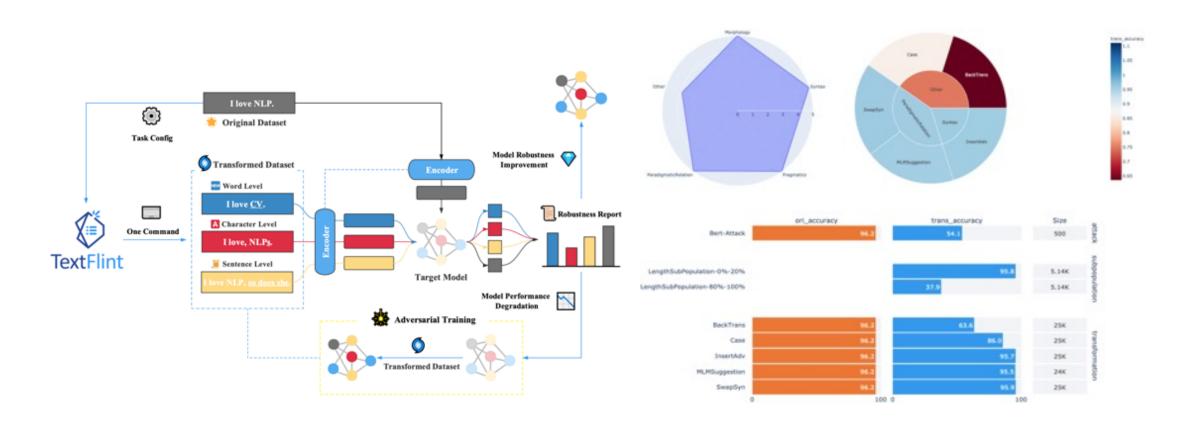


MIXED4A MIXED4D MIXED5A

https://distill.pub/2018/building-blocks/



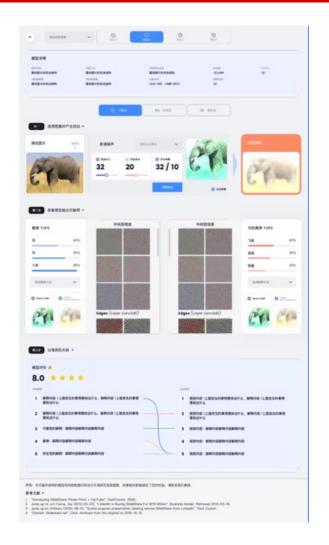
FudanNLP TextFlint

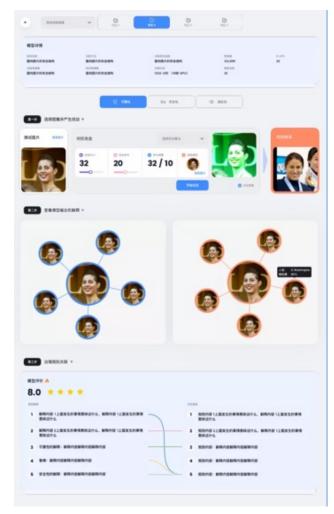


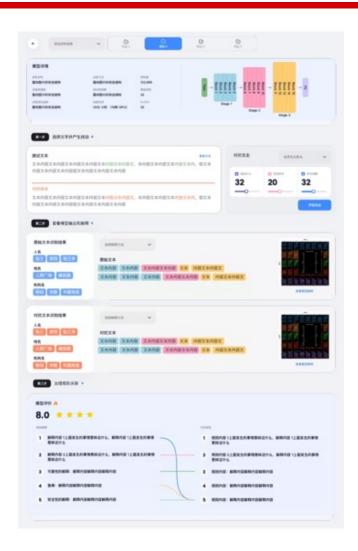




FVL Risk Demo Platform







The Risk Demo Project: https://tech.openeglab.org.cn/dss

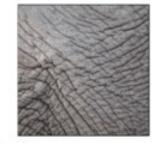


Common Robustness

- **□** Texture bias
- **□** Robustness to common corruptions



Texture bias

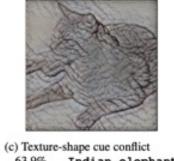


(a) Texture image 81.4% Indian elephant 10.3% indri

8.2% black swan



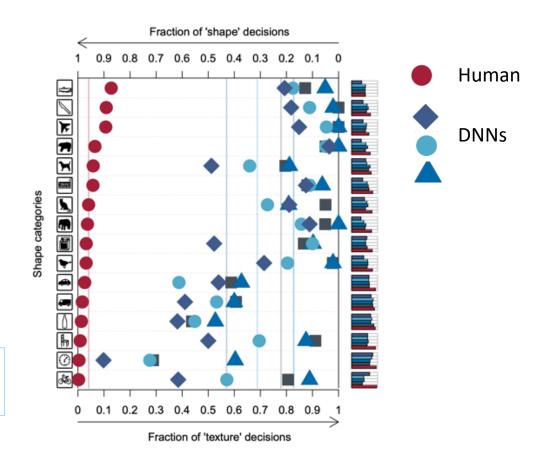
(b) Content image 71.1% tabby cat 17.3% grey fox 3.3% Siamese cat



(c) Texture-shape cue conflict 63.9% Indian elephant 26.4% indri

9.6% black swan

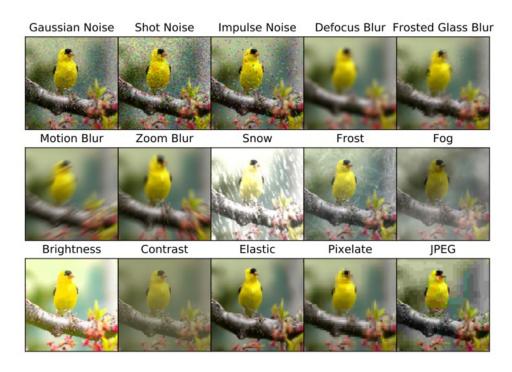
Temporary solution: Data Augmentation (Style Transfer)
ImageNet -> Stylized-ImageNet



Geirhos, Robert, et al. "ImageNet-trained CNNs are biased towards texture; increasing shape bias improves accuracy and robustness." *ICLR*, 2019.

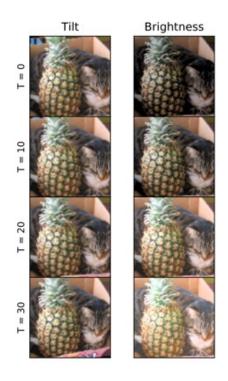


Common Corruptions





- □ 15 types of noise
- 5 severity levels



ImageNet-P:

■ 10 types of perturbation

Temporary solution: Data augmentation vs. Adversarial Logit Pairing

Hendrycks&Dietterich. "Benchmarking Neural Network Robustness to Common Corruptions and Perturbations." ICLR, 2019.



谢谢!下周见!

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