Table S1. Comparison of improved UniSO-N with MLP and with in-context Transformer neural processes (TNP; Nguyen & Grover, 2022) on unconstrained tasks from Design-Bench and SOO-Bench, where the best and runner-up results on each task are **Blue** and **Violet**. \mathcal{D} (best) denotes the best score in the offline dataset. Here, UniSO-N + TNP-UCB maximizes the UCB acquisition function for one epoch on trained TNP to obtain final candidates, following Nguyen et al. (2024), and UniSO-N + TNP-ED directly regresses the score values and maximizes the model output, following Section 3.2.2 in Nguyen et al. (2023).

Task	$\mathcal{D}(\text{best})$	UniSO-N + MLP	UniSO-N + TNP-UCB	UniSO-N + TNP-ED
Ant	165.326	269.691 ± 77.425	110.143 ± 229.571	292.098 ± 229.171
D'Kitty	199.363	173.911 ± 46.662	-226.316 ± 317.276	129.005 ± 41.107
Superconductor	74.000	67.333 ± 10.838	58.653 ± 20.171	64.544 ± 2.888
TF Bind 8	0.439	0.833 ± 0.005	0.638 ± 0.000	0.713 ± 0.000
TF Bind 10	0.005	0.959 ± 0.115	0.674 ± 0.000	0.397 ± 0.000
GTOPX 2	-195.586	-124.995 ± 56.170	-183.413 ± 81.862	-181.144 ± 11.685
GTOPX 3	-151.190	-62.622 ± 22.261	-180.053 ± 93.678	-99.735 ± 2.637
GTOPX 4	-215.716	-110.284 ± 17.559	-130.988 ± 38.336	-178.791 ± 79.623
GTOPX 6	-112.599	-57.435 ± 18.832	-108.859 ± 25.493	-195.184 ± 40.626
Avg. Rank	N/A	1.111 ± 0.314	2.667 ± 0.471	2.222 ± 0.629

Table S2. Few-shot experimental results of improved UniSO-N with MLP and with in-context TNP (Nguyen & Grover, 2022) on RobotPush, Rover, and LunarLander, where the best and runner-up results on each task are **Blue** and **Violet**. \mathcal{D} (best) denotes the best score in the offline dataset. Here, UniSO-N + TNP-UCB maximizes the UCB acquisition function for one epoch on trained TNP to obtain final candidates, following Nguyen et al. (2024), and UniSO-N + TNP-ED directly regresses the score values and maximizes the model output, following Section 3.2.2 in Nguyen et al. (2023). UniSO-N + MLP utilizes few-shot data to fine-tune MLP regressor, while UniSO-N + TNP-UCB and UniSO-N + TNP-ED directly view the few-shot data as context points.

Task	$\mathcal{D}(\text{best})$	UniSO-N + MLP	UniSO-N + TNP-UCB	UniSO-N + TNP-ED
RobotPush	0.102	7.014 ± 0.000	3.769 ± 1.969	0.877 ± 1.041
Rover	-16.148	-8.488 ± 0.003	-12.593 ± 1.891	-12.038 ± 1.142
LunarLander	7.038	287.038 ± 0.000	-113.493 ± 129.223	-79.885 ± 91.442
Avg. Rank	N/A	1.000 ± 0.000	2.667 ± 0.471	2.333 ± 0.471