



Generative Adversarial Positive-Unlabelled Learning

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Outline



Background

Generative PU learning

Experimental results

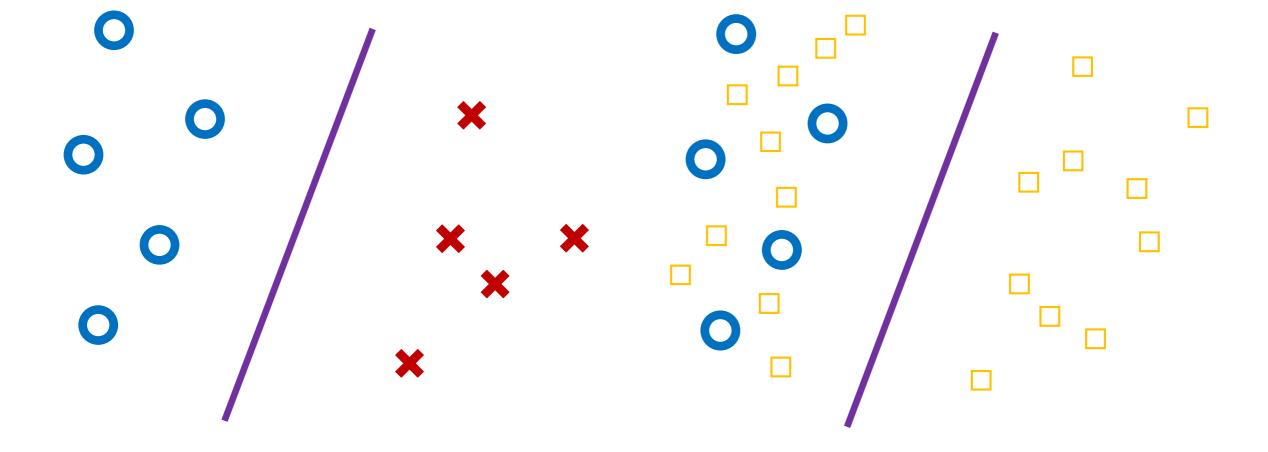


Problem Setting





PU learning



- O: positive data
- ★ : negative data
- □: unlabeled data



Why PU learning?



- PN learning usually requires a large amount of training data
- PU learning is useful in context where
 - √ negative data are too expensive
 - √ negative data are too diverse
 - √ negative data are impure
- PU learning has been applied to applications
 - ✓ binary classification [Liu et al ICML02] [Li and Liu IJCAI03] [Elkan and Noto KDD08] [du Plessis NIPS14]
 - √ matrix completion [Hsieh et al ICML15]
 - ✓ sequential data [Li et al SDM09] [Nguyen et al IJCAI11]



Notations



- Input & output random variables: $\mathbf{x} \in \mathbb{R}^d \ y \in \{\pm 1\}$
- Underlying joint density: $p(\mathbf{x}, y)$
- P marginal & N marginal: $p_p(\mathbf{x}) = p(\mathbf{x}|y=1)$ $p_n(\mathbf{x}) = p(\mathbf{x}|y=-1)$
- U marginal: $p(\mathbf{x}) = \pi_p p(\mathbf{x}|y=1) + \pi_n p(\mathbf{x}|y=-1)$
- Class-prior probability: $\pi_p = p(y=1)$ assume to be known
- P data & N data: $\mathcal{X}_p=\{\mathbf{x}_p^i\}_{i=1}^{n_p}\sim p_p(\mathbf{x})$ $\mathcal{X}_n=\{\mathbf{x}_n^i\}_{i=1}^{n_n}\sim p_n(\mathbf{x})$
- U data: $\mathcal{X}_u = \{\mathbf{x}_u^i\}_{i=1}^{n_u} \sim p(\mathbf{x})$



Recent Related Work

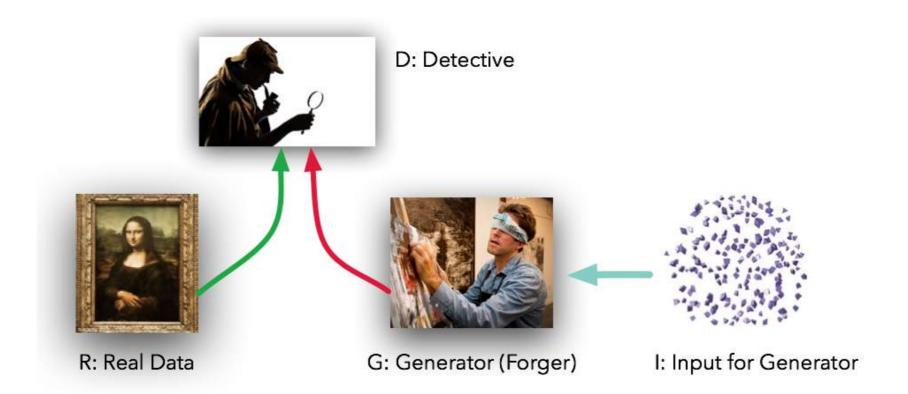


- Unbiased risk estimator for PU (UPU) [du Plessis et.al ICML15]
 - ✓ UPU is an unbiased & consistent estimator
 - ✓ UPU is nice for training linear-in-parameter
 - ✓ UPU seriously overfit to training deep neural networks
- Non-negative risk estimator for PU (NNPU) [Kiryo et.al NIPS17]
 - ✓ NNPU overcomes overfitting to some extent
 - ✓ NNPU is consistent but biased estimator
 - ✓ NNPU has a bias in $\mathcal{O}(exp(-\frac{1}{1/n_p+1/n_u}))$ performance might not be good for small P data



Generative Adversarial Nets (GAN)





The minimax objective function of GAN [Goodfellow et.al NIPS14]

$$\begin{aligned} \min_{G} \max_{D} \mathcal{V}(G, D) &= \min_{G} \max_{D} \ \mathbb{E}_{\mathbf{x} \sim p_{x}(\mathbf{x})} \log(D(\mathbf{x})) \\ &+ \mathbb{E}_{\mathbf{z} \sim p_{z}(\mathbf{z})} \log(1 - D(G(\mathbf{z}))) \end{aligned}$$

- ✓ binary classifier $D(\mathbf{x}) : \mathbf{x} \to [\pm 1]$
- \checkmark transformation function $G(\mathbf{z}) \colon \mathbf{z} \to \mathbf{x}$

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General Idea

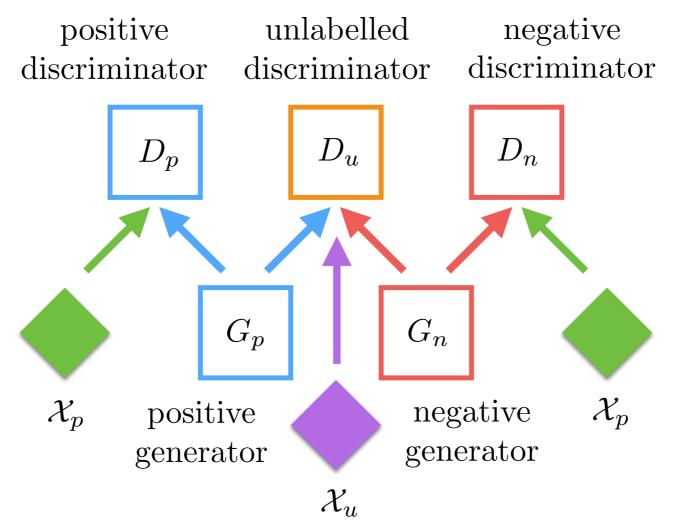


- The goal of generative PU learning
 - ✓ to solve binary PU classification via generative model by leveraging GAN
 - √ to learn both positive and negative marginal distributions from P and U data
- The purposed solution
 - couple multiple GANs to learn generator distributions using large U data and limited P data
 - 2. train deep PN classier on generated samples to find optimal decision boundary



General Framework





- In the viewpoint of G_p
 - \checkmark guided by D_u to generate positive samples alike \mathcal{X}_u
 - \checkmark guided by D_p to generate positive samples alike \mathcal{X}_p
- In the viewpoint of G_n
 - \checkmark guided by D_u to generate negative samples alike \mathcal{X}_u
 - \checkmark guided by D_n to generate negative samples unlike \mathcal{X}_p



Overall Objective Function



• The overall objective function can be decomposed, in the views of generators, as

$$\Psi(G_p, G_n, D_p, D_u, D_n) = \pi_p \Phi_{G_p, D_p, D_u} + \pi_n \Phi_{G_n, D_u, D_n}$$

• The first part corresponds to G_p can be split into two standard GAN components

$$\Phi_{G_p, D_p, D_u} = \lambda_p \min_{G_p} \max_{D_p} \mathcal{V}_{G_p, D_p}(G, D) + \lambda_u \min_{G_p} \max_{D_u} \mathcal{V}_{G_p, D_u}(G, D)$$

✓ The value function of the first GAN_{G_p,D_p}

$$\mathcal{V}_{G_p,D_p}(G,D) = \mathbb{E}_{\mathbf{x} \sim p_p(\mathbf{x})} \log(D_p(\mathbf{x})) + \mathbb{E}_{\mathbf{z} \sim p_z(\mathbf{z})} \log(1 - D_p(G_p(\mathbf{z})))$$

✓ The value function of the second GAN_{G_p,D_u}

$$\mathcal{V}_{G_p,D_u}(G,D) = \mathbb{E}_{\mathbf{x} \sim p_u(\mathbf{x})} \log(D_u(\mathbf{x})) + \mathbb{E}_{\mathbf{z} \sim p_z(\mathbf{z})} \log(1 - D_u(G_p(\mathbf{z})))$$



Overall Objective Function Cont



• The overall objective function can be decomposed, in the views of generators, as

$$\Psi(G_p, G_n, D_p, D_u, D_n) = \pi_p \Phi_{G_p, D_p, D_u} + \pi_n \Phi_{G_n, D_u, D_n}$$

• The second part corresponds to G_n can be split into two GAN components

$$\Phi_{G_n,D_u,D_n} = \lambda_u \min_{G_n} \max_{D_u} \mathcal{V}_{G_n,D_u}(G,D) + \lambda_n \max_{G_n} \max_{D_n} \mathcal{V}_{G_n,D_n}(G,D)$$

✓ The value function of the first GAN_{G_n,D_u}

$$\mathcal{V}_{G_n,D_u}(G,D) = \mathbb{E}_{\mathbf{x} \sim p_u(\mathbf{x})} \log(D_u(\mathbf{x})) + \mathbb{E}_{\mathbf{z} \sim p_z(\mathbf{z})} \log(1 - D_u(G_n(\mathbf{z})))$$

✓ The value function of the second GAN_{G_n,D_n}

$$\mathcal{V}_{G_n,D_n}(G,D) = \mathbb{E}_{\mathbf{x} \sim p_p(\mathbf{x})} \log(D_n(\mathbf{x})) + \mathbb{E}_{\mathbf{z} \sim p_z(\mathbf{z})} \log(1 - D_n(G_n(\mathbf{z})))$$

$$D_n^{\star} = \arg \max_{D_n} \mathbb{E}_{\mathbf{x} \sim p_p(\mathbf{x})} \log(D_n(\mathbf{x})) + \mathbb{E}_{\mathbf{z} \sim p_z(\mathbf{z})} \log(1 - D_n(G_n(\mathbf{z})))$$

$$G_n^{\star} = \arg \min_{G_n} -\mathcal{V}_{G_n, D_n^{\star}}(G, D_n^{\star})$$



Theoretical Result



Theorem suppose the data distribution in the standard PU learning setting take the form of $p(x) = \pi_p p_p(x) + \pi_n p_n(x)$, where $p_p(x)$ and $p_n(x)$ are well-separated. Given the optimal discriminators, the minimax optimization problem with the overall objective function obtains its optimal solution if

$$p_{gp}(\mathbf{x}) = p_p(\mathbf{x})$$

$$p_{gn}(\mathbf{x}) = p_n(\mathbf{x})$$

with the objective value of $-(\pi_p \lambda_p + \lambda_u) \log(4)$

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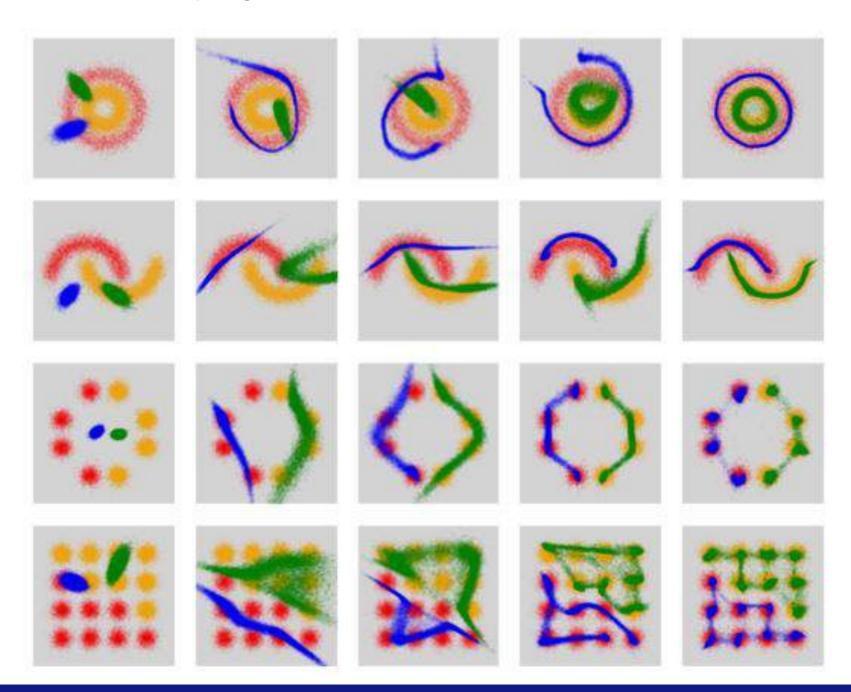
Experimental results



Simulation Result



- Evolution of positive and negative samples produced by GenPU through time with 500 labeled P data and 9500 U data
- Adopt MLP as underlying GAN component



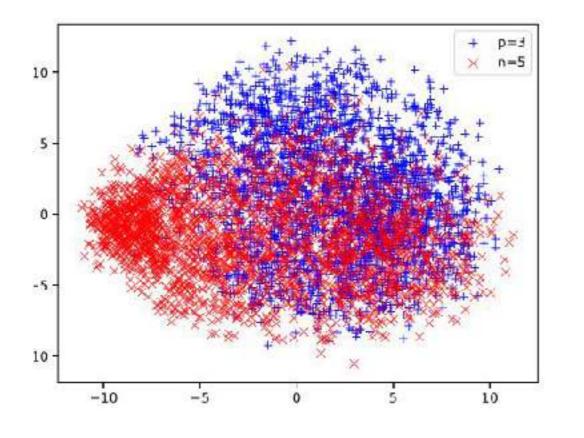


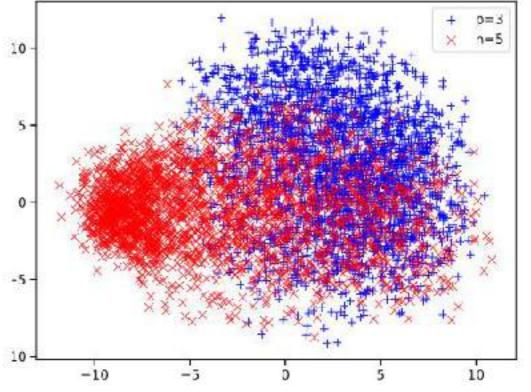
MNIST Result



The best accuracy with positively labeled data from 100 to 1

MNIST	'3' vs. '5'				'8' vs. '3'			
$N_I: N_U$	Oracle PN	UPU	NNPU	GenPU	Oracle PN	UPU	NNPU	GenPU
100 : 9900	.993	.914	.969	.983	.994	.932	.974	.982
50 : 9950	.993	.854	.966	.982	.994	.873	.965	.979
10 : 9990	.993	.711	.866	.980	.994	.733	.907	.978
5 : 9995	.993	.660	.843	.979	.994	.684	.840	.976
1 : 9999	.993	.557	.563	.976	.994	.550	.573	.972



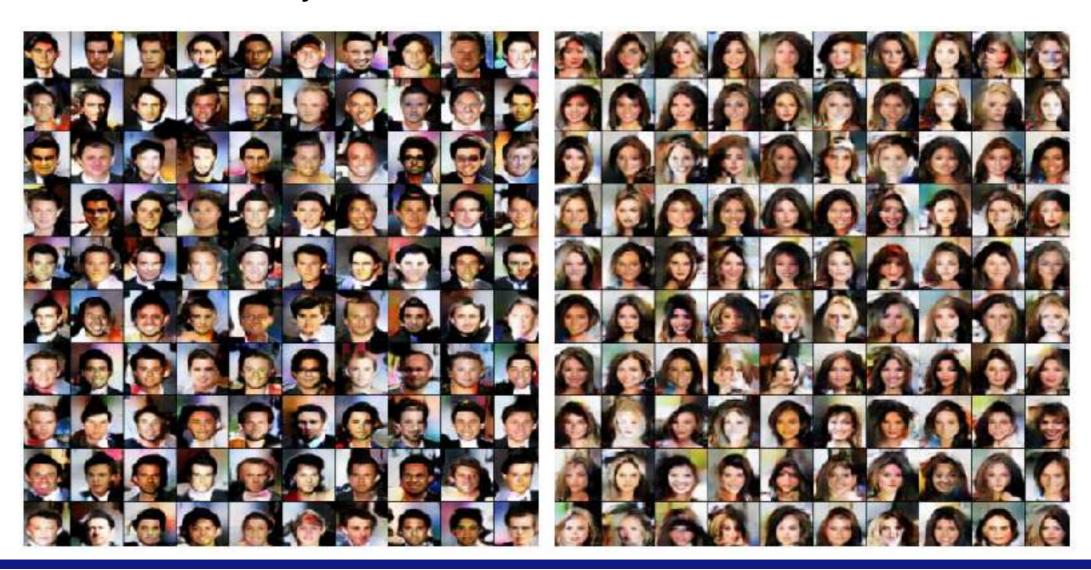




CelebA Result



- Data dimensionality is $64 \times 64 \times 3 = 12288$
- Experiment on 20000 male and 20000 female faces
- Randomly select 2000 male faces as labeled P data, leave rest 38000 as U data
- Adapt the improved WGAN [Gulrajani et al., 2017] as the underlying GANs
- Achieve better accuracy of 87.9 than 86.8 of NNPU and 62.5 of UPU



Conclusion



- Attacking PU task from generative model perspective using ensemble of GANs is novel and promising.
- Performance depends on the underlying GAN realization, and GenPU inherits the weakness of GAN, e.g., mode collapsing, mode oscillation.
- Applying GenPU to high-dimensional data is not easy, network architecture to be carefully designed.





Thank You!