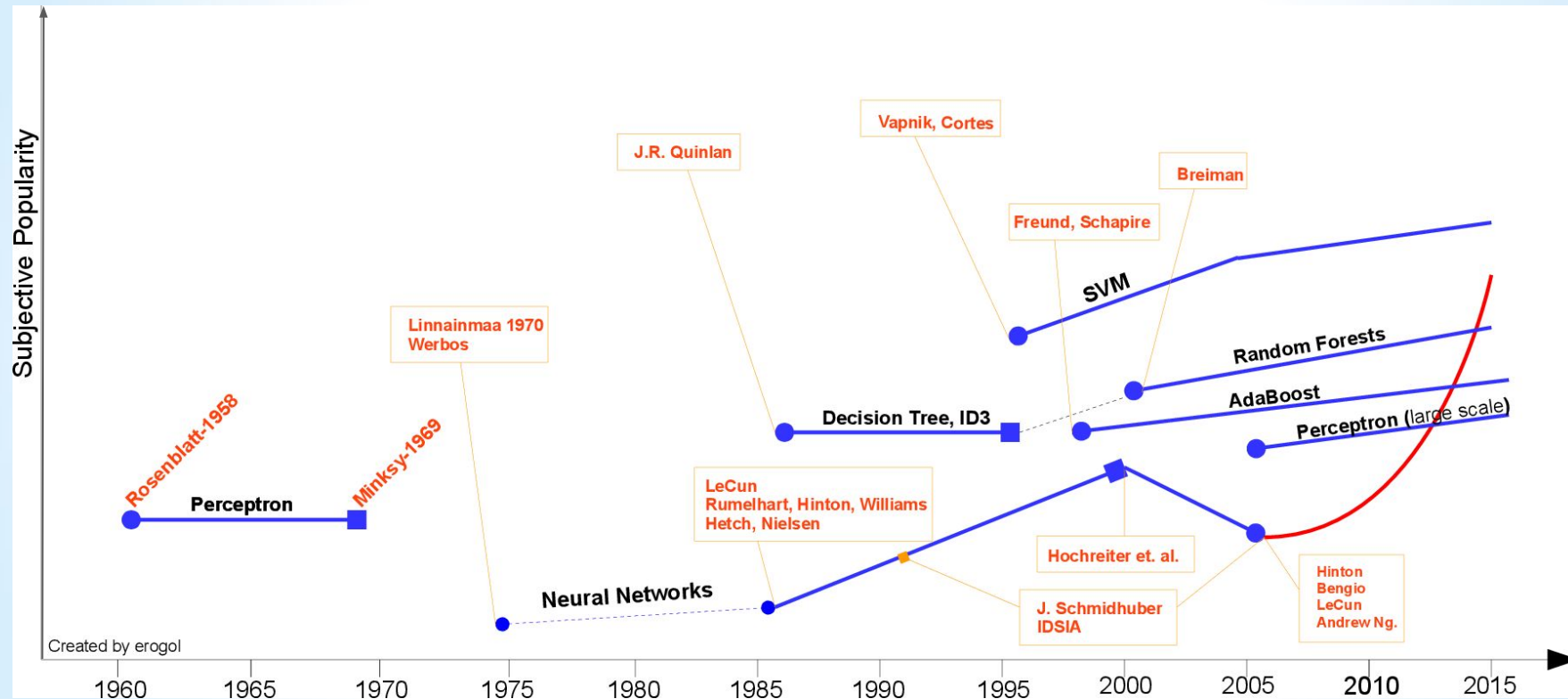


Support Vector Machines

Lior Sidi & Noa Lubin



Models History



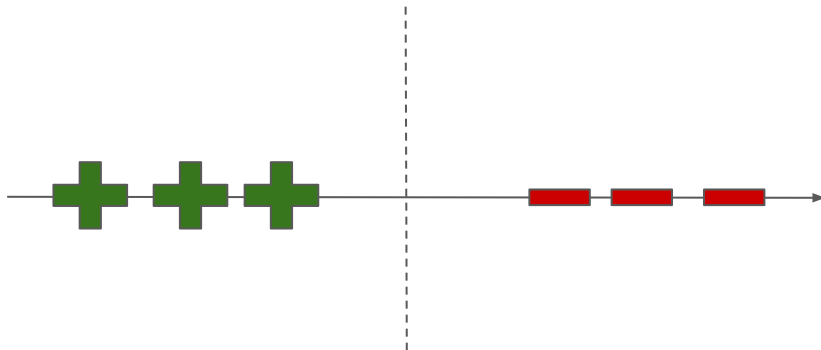
Motivation

Good for difficult problems with limited data (<10K data points)

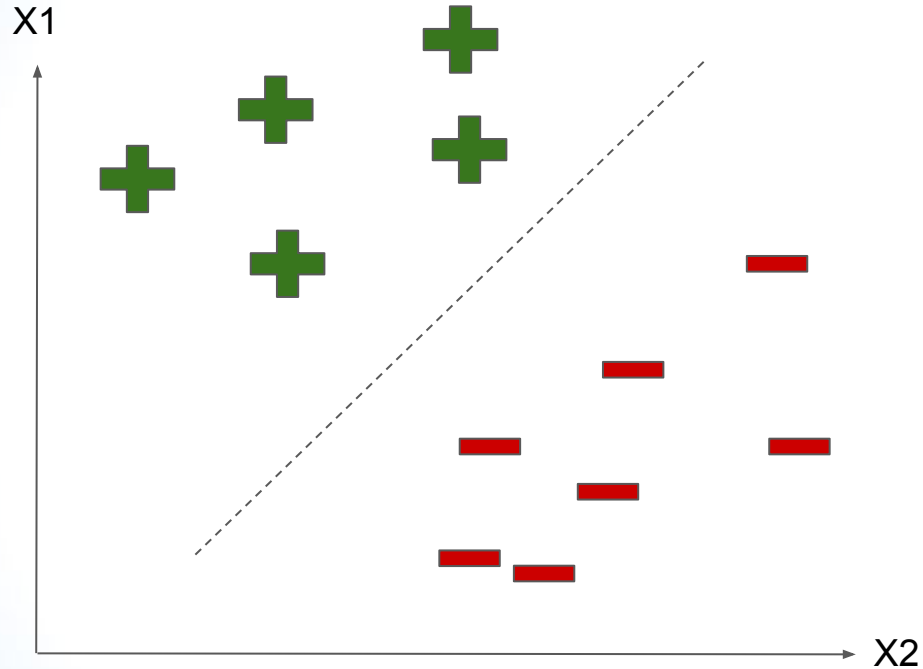
- Face Detection
- Text Classification
- Protein Fold and Remote Homology Detection
- Handwriting Recognition



Linear Classification - 1 dim



Linear Classification - 2 dim

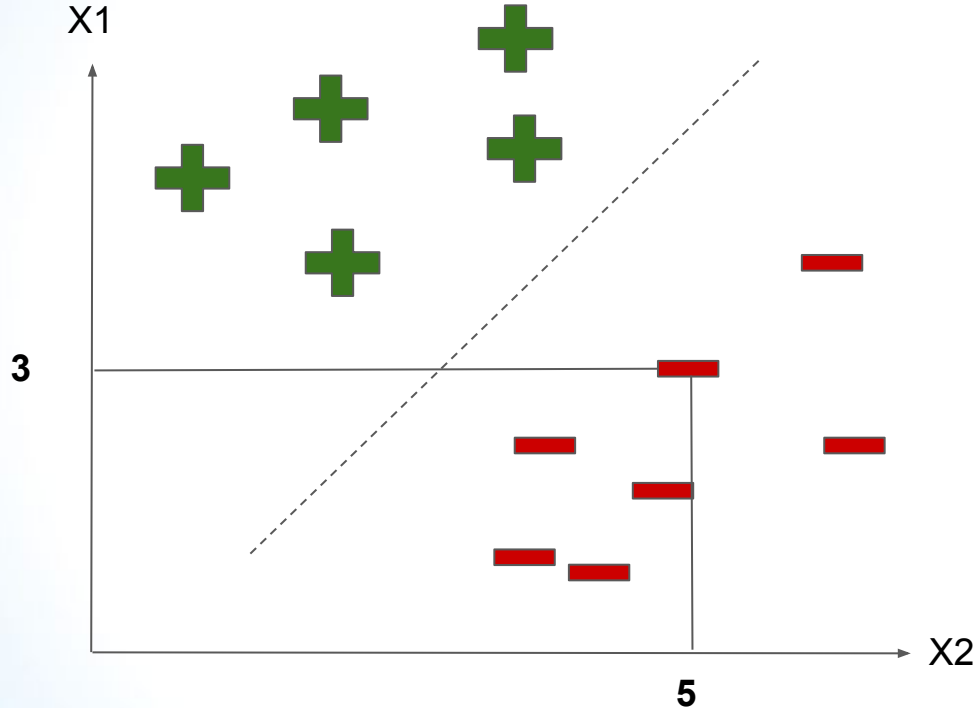


$$w_1 \cdot x_1 = w_2 \cdot x_2 + b$$

$$2 \cdot x_1 = 4 \cdot x_2 - 3$$

$$2 \cdot x_1 - 4 \cdot x_2 + 3 = 0$$

Linear Classification - 2 dim



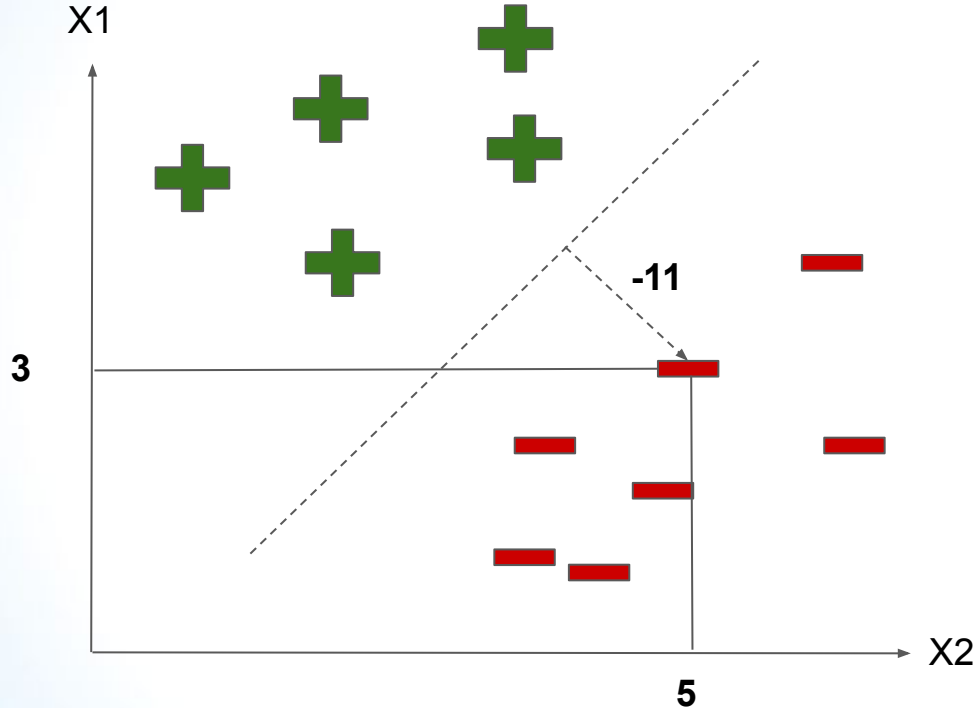
$$w_1 \cdot x_1 = w_2 \cdot x_2 + b$$

$$2 \cdot x_1 = 4 \cdot x_2 - 3$$

$$2 \cdot x_1 - 4 \cdot x_2 + 3 = 0$$

$$2 \cdot 3 - 4 \cdot 5 + 3 =$$

Linear Classification - 2 dim



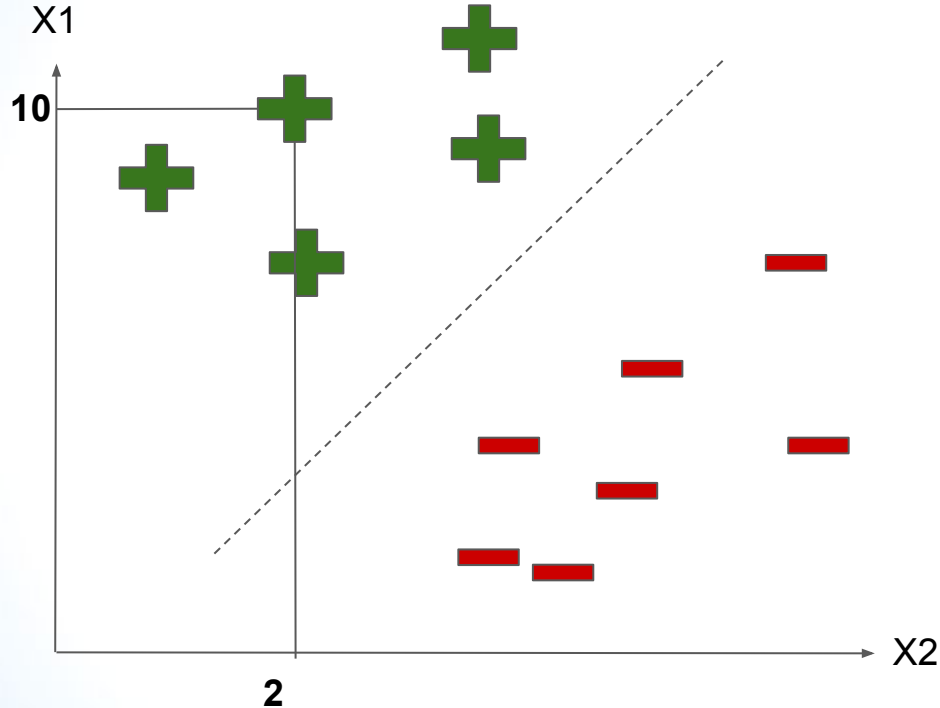
$$w_1 \cdot x_1 = w_2 \cdot x_2 + b$$

$$2 \cdot x_1 = 4 \cdot x_2 - 3$$

$$2 \cdot x_1 - 4 \cdot x_2 + 3 = 0$$

$$2 \cdot 3 - 4 \cdot 5 + 3 = 6 - 20 + 3 = -11$$

Linear Classification - 2 dim



$$w_1 \cdot x_1 = w_2 \cdot x_2 + b$$

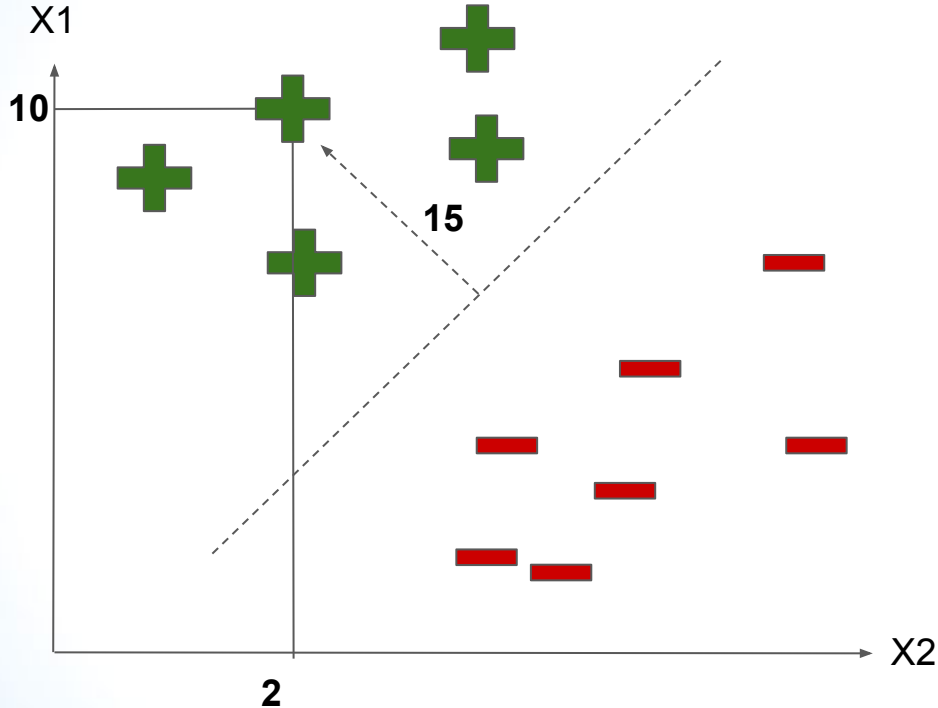
$$2 \cdot x_1 = 4 \cdot x_2 - 3$$

$$2 \cdot x_1 - 4 \cdot x_2 + 3 = 0$$

$$2 \cdot 3 - 4 \cdot 5 + 3 = 6 - 20 + 3 = -11$$

$$2 \cdot 10 - 4 \cdot 2 + 3 = 20 - 8 + 3 = 15$$

Linear Classification - 2 dim



$$w_1 \cdot x_1 = w_2 \cdot x_2 + b$$

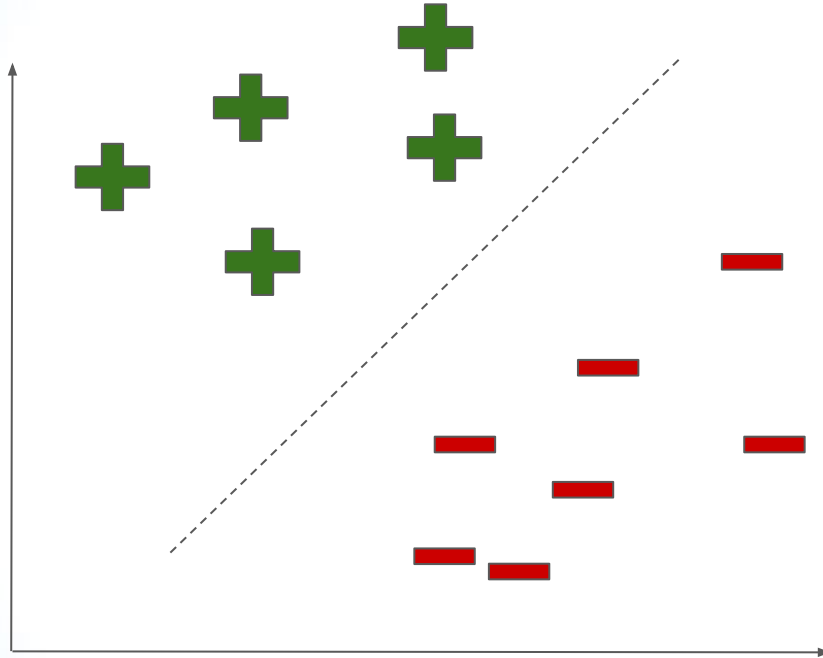
$$2 \cdot x_1 = 4 \cdot x_2 - 3$$

$$2 \cdot x_1 - 4 \cdot x_2 + 3 = 0$$

$$2 \cdot 3 - 4 \cdot 5 + 3 = 6 - 20 + 3 = -11$$

$$2 \cdot 10 - 4 \cdot 2 + 3 = 20 - 8 + 3 = 15$$

Linear Classification - 2 dim

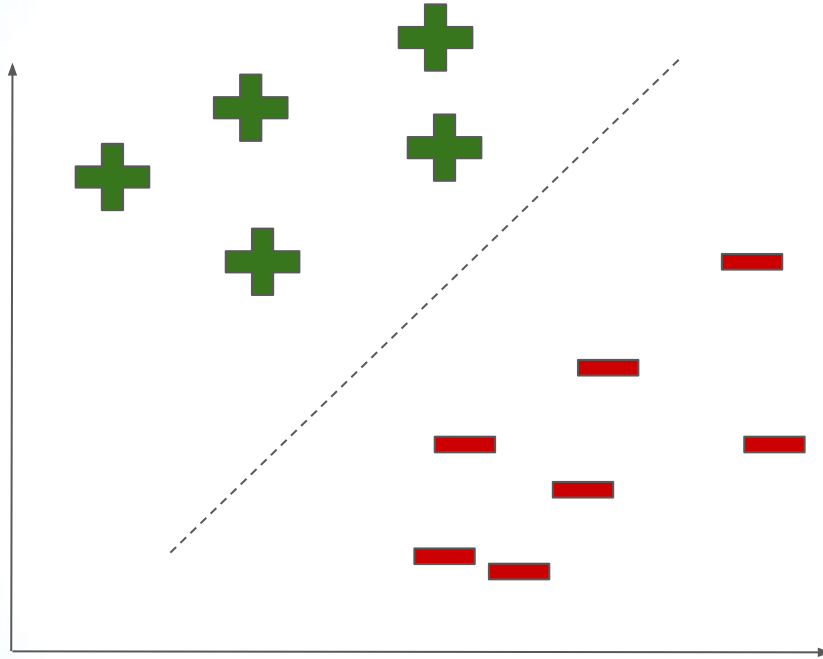


$$w_1 \cdot x_1 = w_2 \cdot x_2 + b$$

$$f(X, W) = w_1 \cdot x_1 + w_2 \cdot x_2 =$$

For simplicity We are going to eliminate the bias term
Which can be added as a vectors of ones

Linear Classification - 2 dim

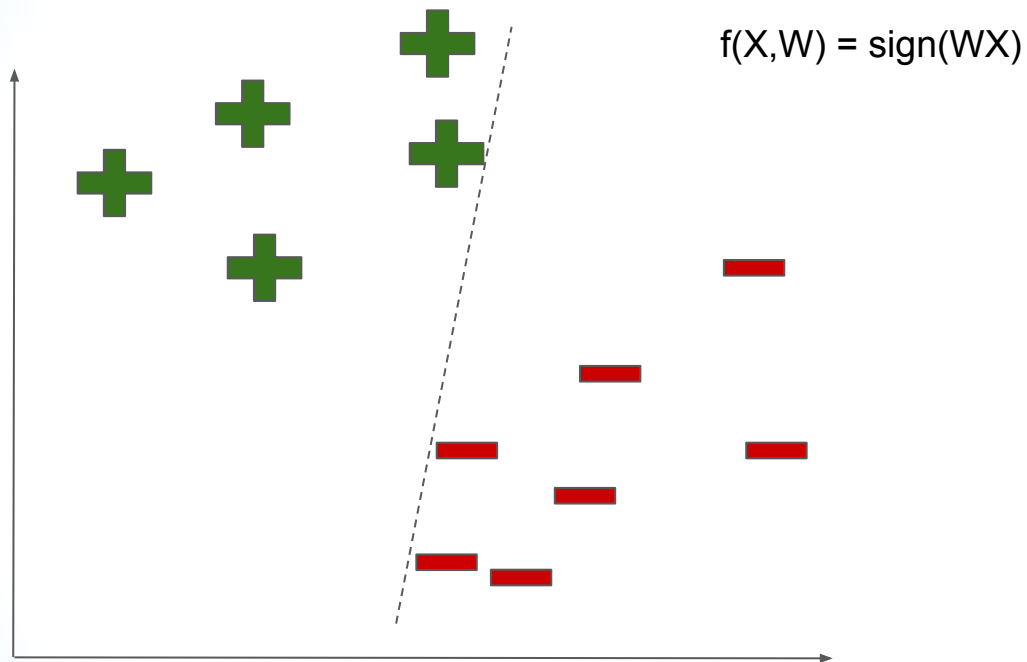


$$w_1 \cdot x_1 = w_2 \cdot x_2 + b$$

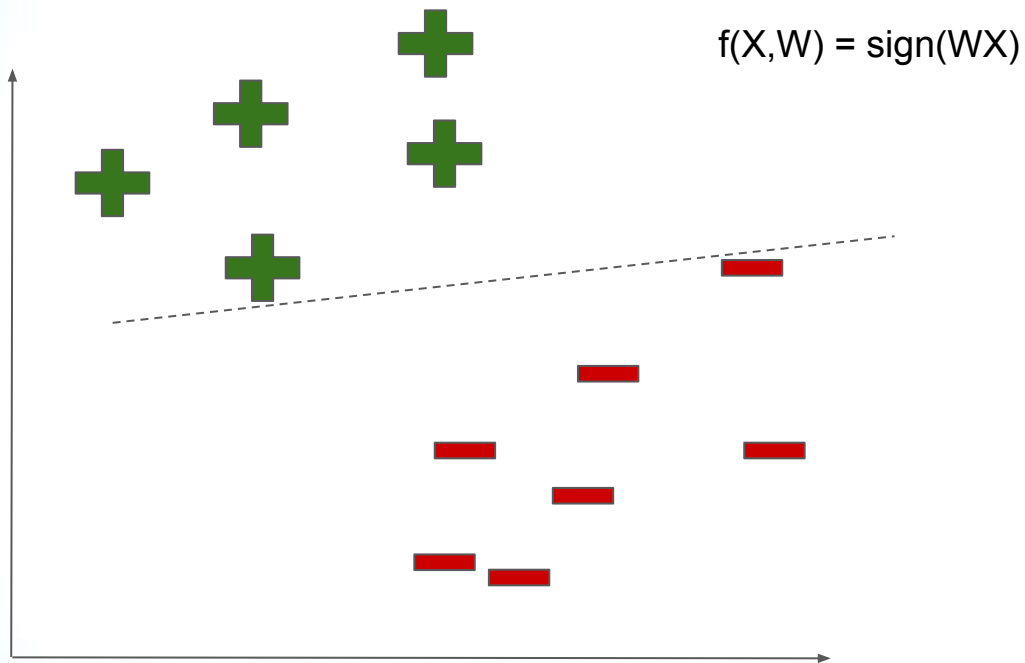
$$\begin{aligned} f(X, W) &= w_1 \cdot x_1 + w_2 \cdot x_2 = \\ &= \sum W X = W^t X = 0 \\ &\Rightarrow \text{sign}(W X) \end{aligned}$$

For simplicity We write
 $W^t X$ as $W X$

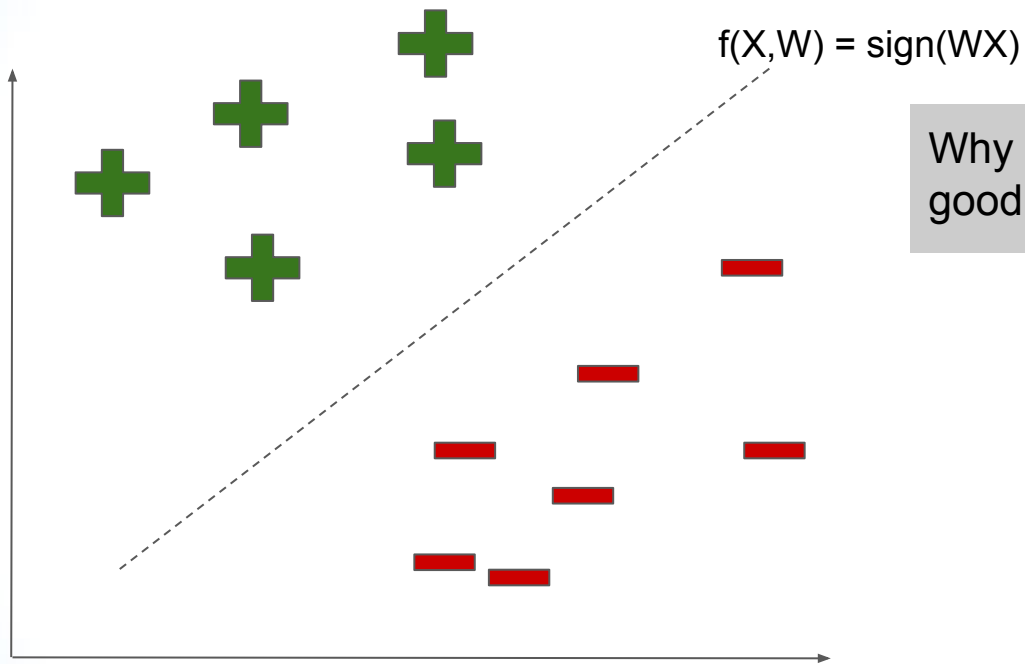
Linear Classification



Linear Classification

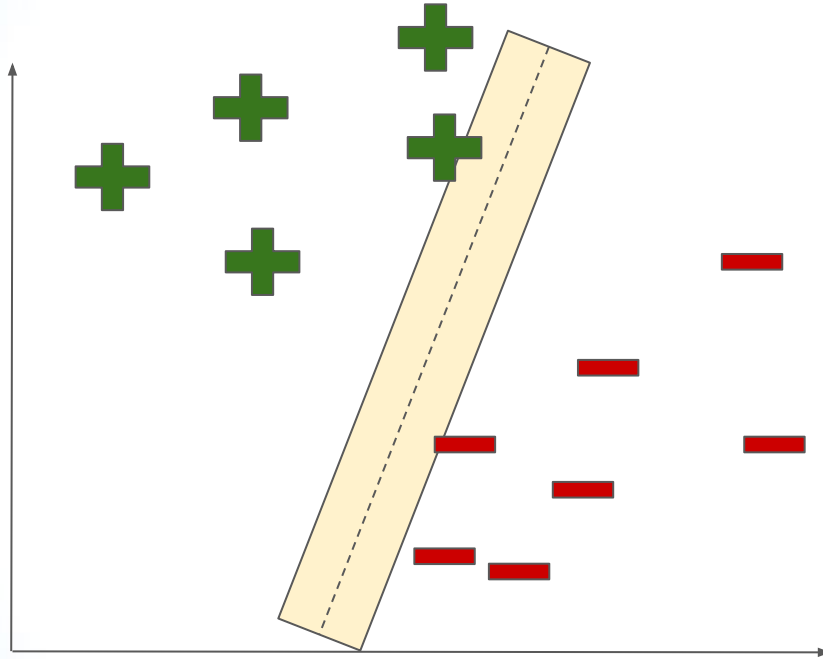


Linear Classification



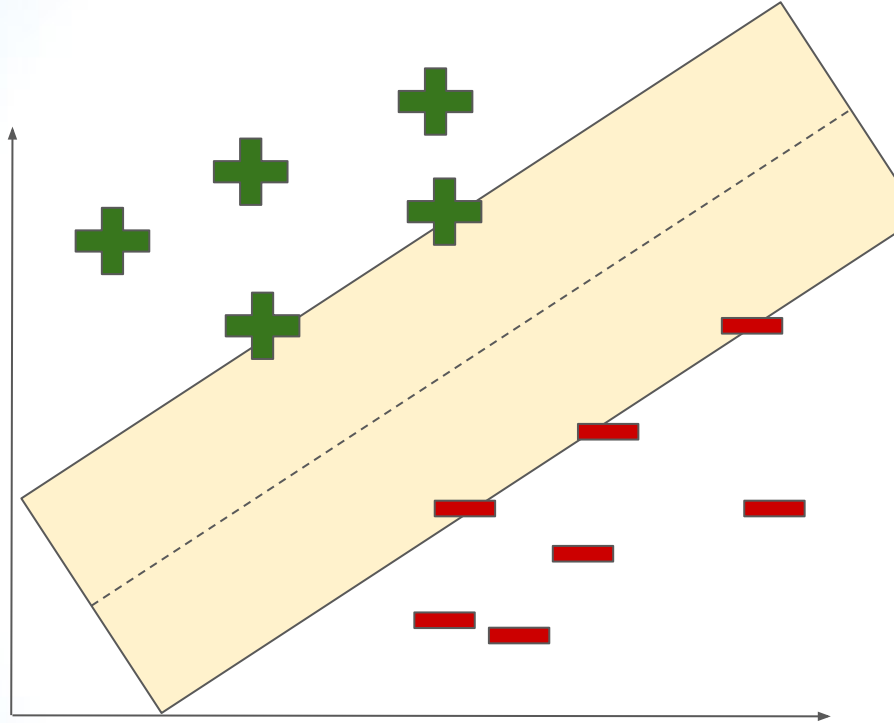
Why is this seems as a good separator?

Classifier Margin



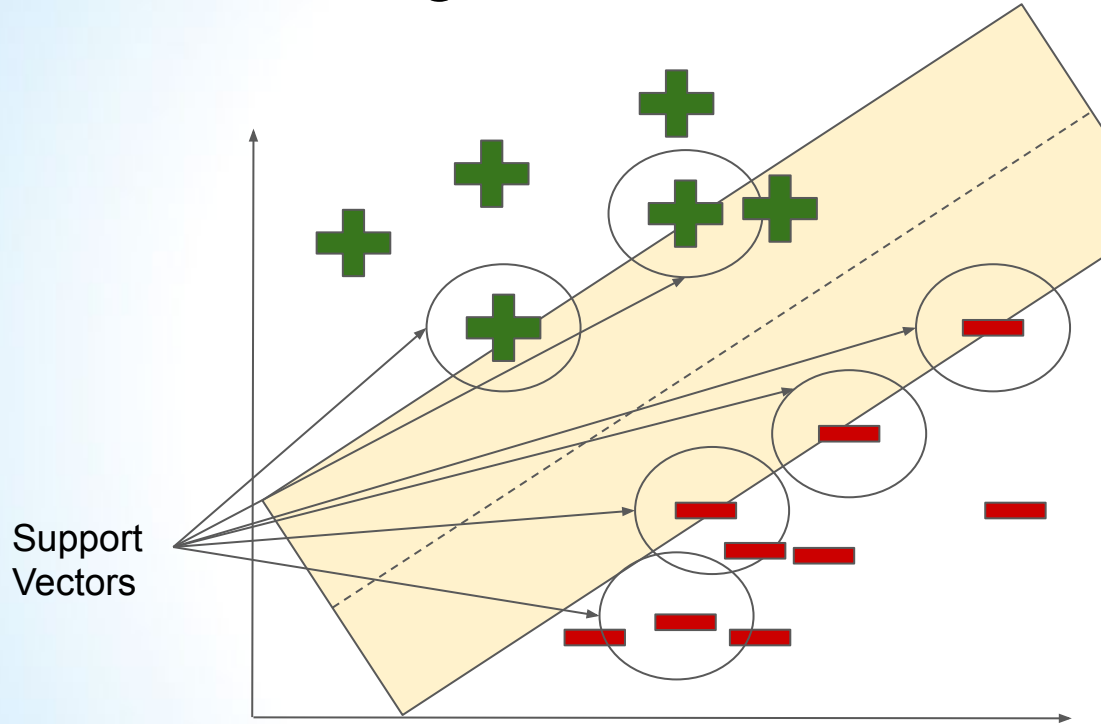
A margin in linear classifiers is the boundary width the touches the datapoint

Maximum margin



A maximum margin in linear classifiers is the Max boundary width the touches the datapoint

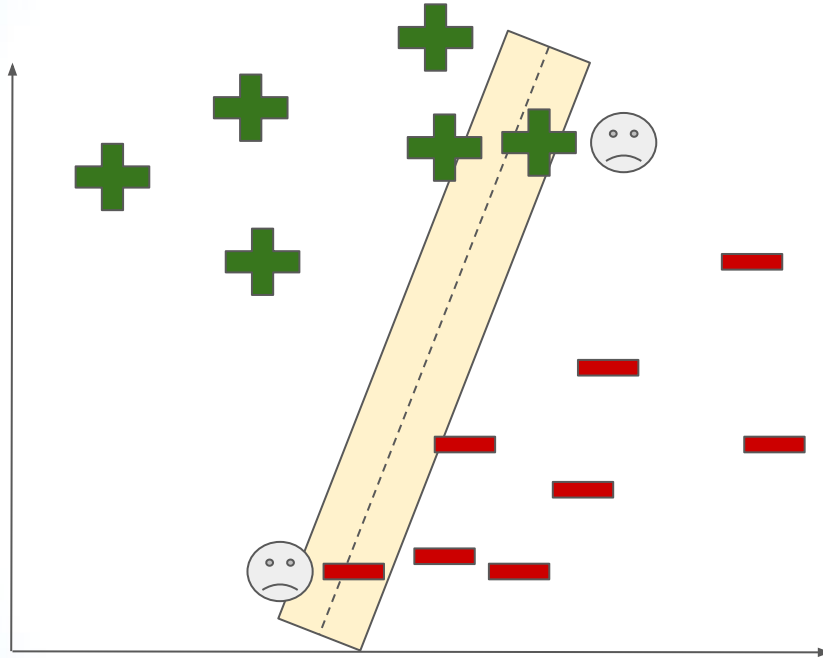
Maximum Margin



A maximum margin in linear classifiers is the Max boundary width the touches the datapoint

The points on the margins are called Support Vectors

Classifier Margin

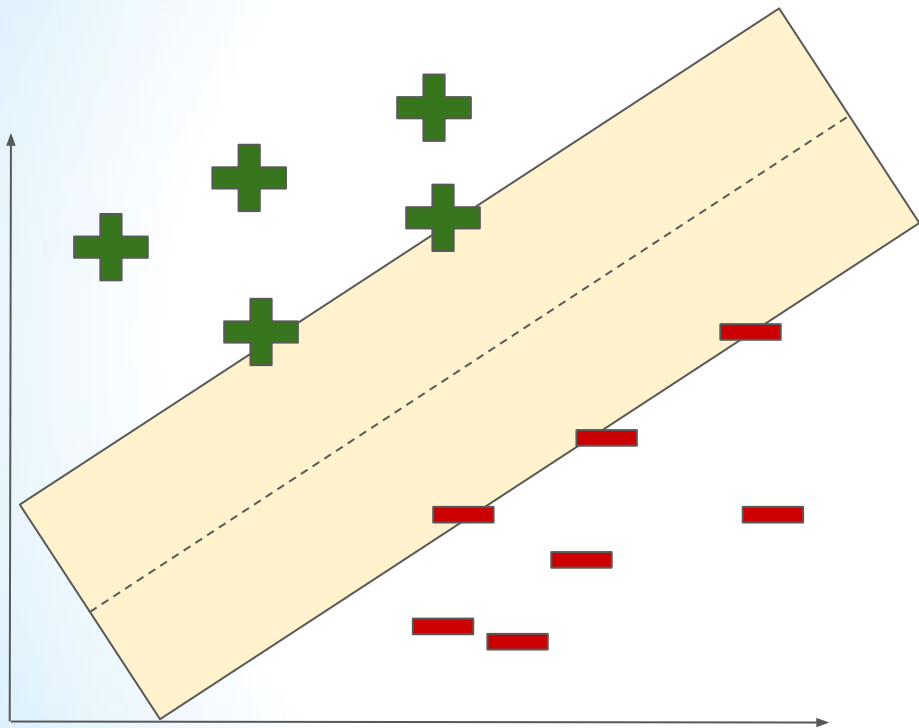


A maximum margin in linear classifiers is the Max boundary width the touches the datapoint

The points on the margins are called Support Vectors

Allows a more flexibility around the decision boundary

Classifier Margin



A maximum margin in linear classifiers is the Max boundary width the touches the datapoint

The points on the margins are called Support Vectors

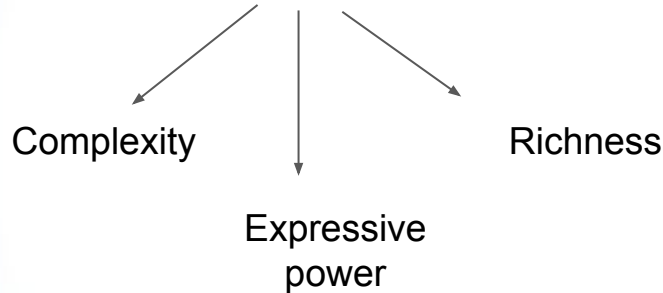
Allows a more flexibility around the decision boundary

VC dimension can show that the maximum margin is a good approach to linearly separable problems.

VC Dimension - Vapnik-Chervonenkis (60-90)

Explain learning from a statistical view

VC-dim measure the **capacity** of a learner

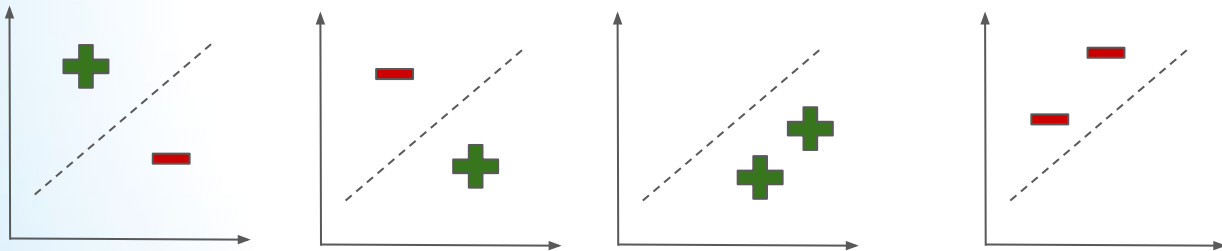


VC Dimension - Vapnik-Chervonenkis (60-90)

VC-dim is the maximum number of points the learner can **Shatter**

A learner can **Shatter** points if all y 's can achieve Zero error on the train set

Perceptron / logistic regression for 2 points:



1. Lets try 3 points And 4..

2. What is the VC-dim of the learner? **dim + 1**

3. What happened with 3 points same line..

VC Dimension - Vapnik-Chervonenkis (60-90)

VC-dim can predict the probabilistic upper bound of the test error (!)

N: The training-set size

$$\Pr \left(\text{test error} \leq \text{training error} + \sqrt{\frac{1}{N} \left[D \left(\log \left(\frac{2N}{D} \right) + 1 \right) - \log \left(\frac{\eta}{4} \right) \right]} \right) = 1 - \eta,$$

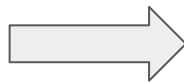
Valid When $N \gg D$

$0 < \eta \leq 1$

D: The VC-dim of a learner

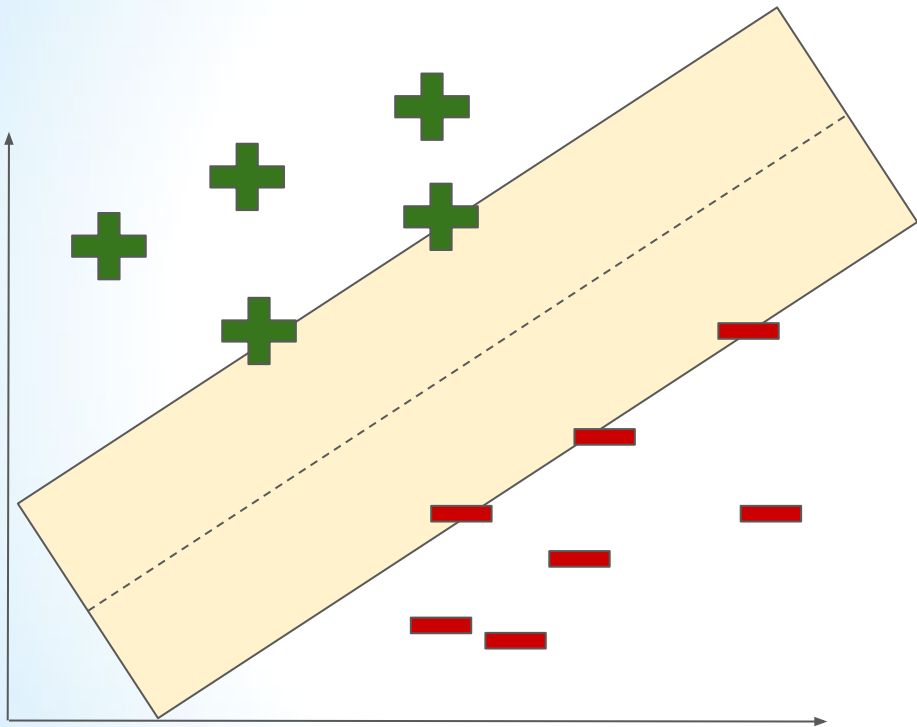
$$D_{svm} = 1 + \frac{1}{\text{margin}^2}$$

In the linear
separable case



Higher margin, lower
D, lower test error

Classifier Margin



A maximum margin in linear classifiers is the Max boundary width the touches the datapoint

The points on the margins are called Support Vectors

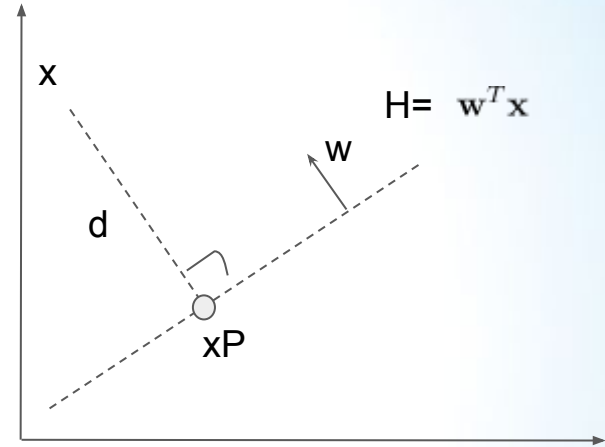
Allows a more flexibility around the decision boundary

VC dimension can show that the maximum margin is a good approach to linearly separable problems.

Hard SVM - the separable case

What is the distance between point x and the hyperplane?

- x is a point
- d vector from H to x with minimum length
- xP is the projection of x on H



Defining the Margin

$$\mathbf{w}^T \mathbf{x}^P = 0 \quad \mathbf{x}^P = \mathbf{x} - \mathbf{d} \quad \mathbf{d} = \alpha \mathbf{w} \quad \alpha \in \mathbb{R}$$

\mathbf{x}^P is a point on H

\mathbf{d} is parallel to \mathbf{w}

$$\mathbf{w}^T \mathbf{x}^P = \mathbf{w}^T (\mathbf{x} - \mathbf{d}) = \mathbf{w}^T (\mathbf{x} - \alpha \mathbf{w}) = 0$$

$$\alpha = \frac{\mathbf{w}^T \mathbf{x}}{\mathbf{w}^T \mathbf{w}}$$

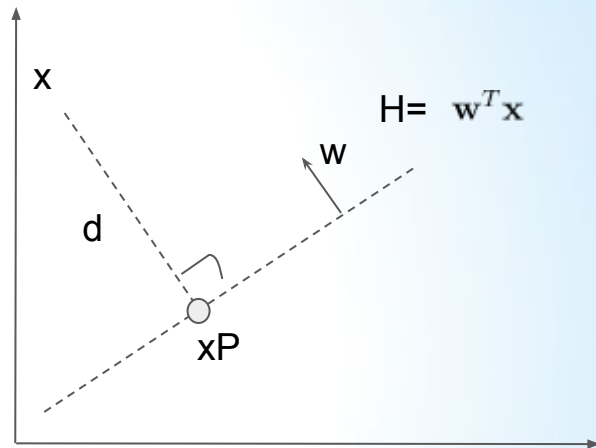
The length of \mathbf{d} :

$$\|\mathbf{d}\|_2 = \sqrt{\mathbf{d}^T \mathbf{d}} = \sqrt{\alpha^2 \mathbf{w}^T \mathbf{w}} = \frac{|\mathbf{w}^T \mathbf{x}|}{\sqrt{\mathbf{w}^T \mathbf{w}}} = \frac{|\mathbf{w}^T \mathbf{x}|}{\|\mathbf{w}\|_2}$$

Margin of H with respect to D : $\gamma(\mathbf{w}) = \min_{\mathbf{x} \in D} \frac{|\mathbf{w}^T \mathbf{x}|}{\|\mathbf{w}\|_2}$

By definition, the margin and hyperplane are scale invariant:

$$\gamma(\beta \mathbf{w}) = \gamma(\mathbf{w}), \forall \beta \neq 0$$



Defining the Maximum Margin

$$\underbrace{\max_{\mathbf{w}} \gamma(\mathbf{w}, b)}_{\text{maximize margin}} \text{ such that } \underbrace{\forall i \ y_i(\mathbf{w}^T \mathbf{x}_i) \geq 0}_{\text{separating hyperplane}}$$

$$\underbrace{\max_{\mathbf{w}} \frac{1}{\|\mathbf{w}\|_2} \min_{\mathbf{x}_i \in D} |\mathbf{w}^T \mathbf{x}_i|}_{\gamma(\mathbf{w})} \text{ s.t. } \underbrace{\forall i \ y_i(\mathbf{w}^T \mathbf{x}_i) \geq 0}_{\text{separating hyperplane}}$$

maximize margin

Because the hyperplane is scale invariant, we can fix the scale of \mathbf{w} anyway we want. Let's be clever about it, and choose it such that

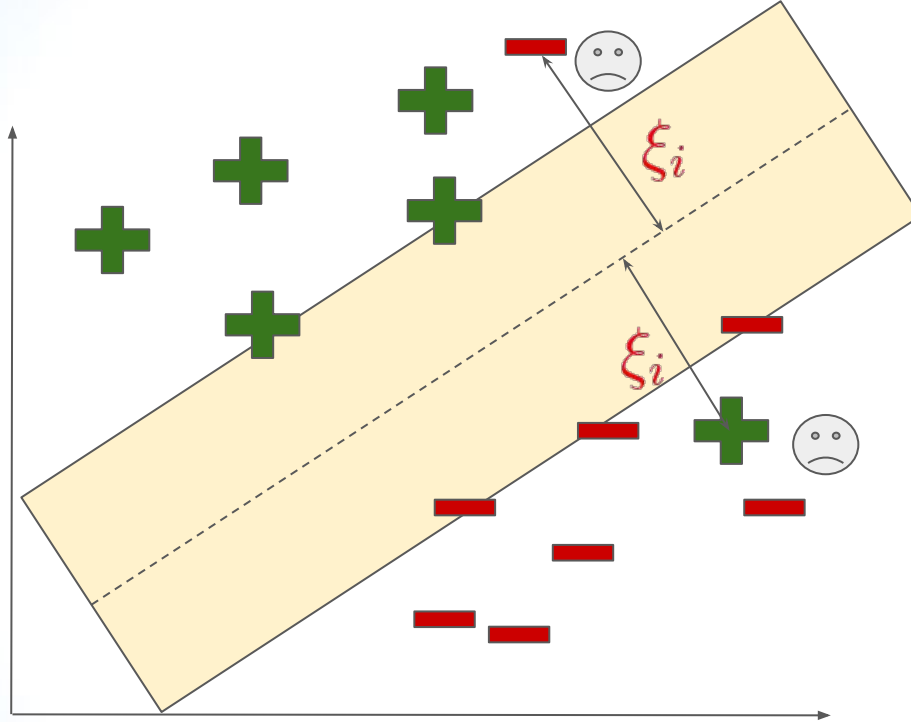
$$\min_{\mathbf{x} \in D} |\mathbf{w}^T \mathbf{x}| = 1.$$

$$\max_{\mathbf{w}} \frac{1}{\|\mathbf{w}\|_2} \cdot 1 = \min_{\mathbf{w}} \|\mathbf{w}\|_2 = \min_{\mathbf{w}} \mathbf{w}^T \mathbf{w} \quad \text{s.t.} \quad \forall i \ y_i(\mathbf{w}^T \mathbf{x}_i) \geq 1$$

$$\min_{\mathbf{w}} \|\mathbf{w}\|^2 \text{ s.t. } \forall i, y_i \mathbf{w}^T \mathbf{x}_i \geq 1$$

*Assumes full separability

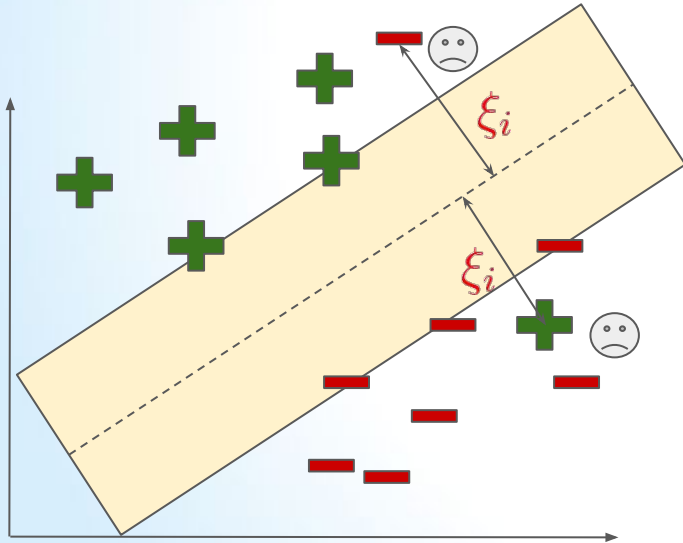
What if there is no linear separability?



Soft SVM - Supporting error data points

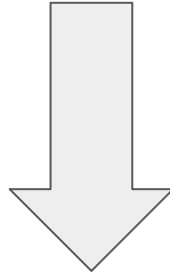
$$\operatorname{argmin}_{w, \xi} \left(\lambda \|w\|^2 + C \frac{1}{m} \sum_{i=1}^m \xi_i \right)$$

$$\text{s.t. } \forall y_i (wx_i) \geq 1 - \xi_i$$



Soft SVM - Supporting error data points

$$\operatorname{argmin}_{w, \xi} \left(\lambda \|w\|^2 + C \frac{1}{m} \sum_{i=1}^m \xi_i \right)$$

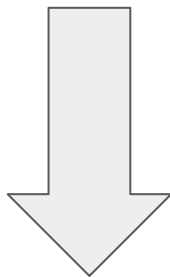


$$s.t \ \forall y_i (wx_i) \geq 1 - \xi_i$$

$$\operatorname{argmin}_{w, \xi} \left(\lambda \|w\|^2 + \underset{\max \{0, 1 - ywx\}}{\text{hinge}(wx, y)} \right)$$

Soft SVM - Supporting error data points

$$\operatorname{argmin}_{w, \xi} \left(\lambda \|w\|^2 + C \frac{1}{m} \sum_{i=1}^m \xi_i \right)$$



$$s.t \ \forall y_i (wx_i) \geq 1 - \xi_i$$

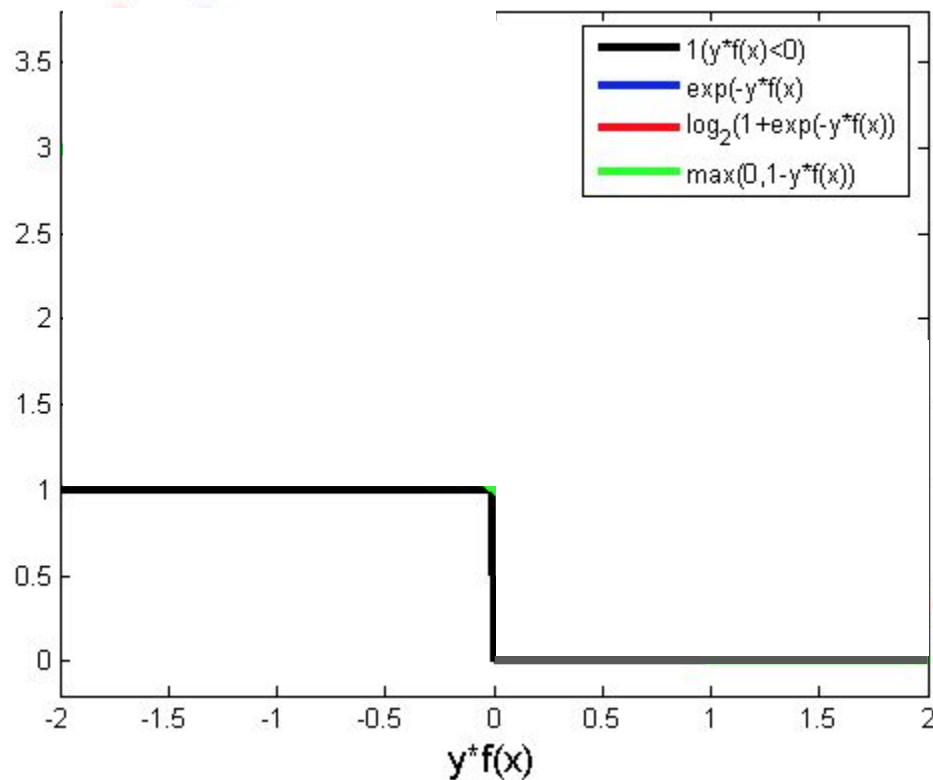
$$\operatorname{argmin}_{w, \xi} \left(\lambda \|w\|^2 + \underbrace{\max\{0, 1 - ywx\}}_{\text{hinge}(wx, y)} \right)$$

regularization

objective

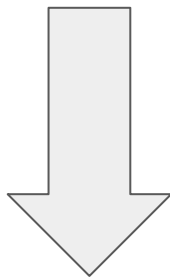
But came from problem definition

Draw me a function



Soft SVM - Supporting error data points

$$\operatorname{argmin}_{w, \xi} \left(\lambda \|w\|^2 + C \frac{1}{m} \sum_{i=1}^m \xi_i \right)$$



$$s.t \ \forall y_i (wx_i) \geq 1 - \xi_i$$

$$\operatorname{argmin}_{w, \xi} \left(\lambda \|w\|^2 + \underbrace{\max\{0, 1 - ywx\}}_{\text{hinge}(wx, y)} \right)$$

regularization

objective

But came from problem definition

How we can solve it?

Gradient descent

Quadratic Programing

SGD for solving Soft-SVM

goal: Solve $\operatorname{argmin}_{\mathbf{w}} \left(\frac{\lambda}{2} \|\mathbf{w}\|^2 + \frac{1}{m} \sum_{i=1}^m \max\{0, 1 - y\langle \mathbf{w}, \mathbf{x}_i \rangle\} \right)$

parameter: T

initialize: $\boldsymbol{\theta}^{(1)} = \mathbf{0}$

for $t = 1, \dots, T$

Let $\mathbf{w}^{(t)} = \frac{1}{\lambda t} \boldsymbol{\theta}^{(t)}$

Choose i uniformly at random from $[m]$

If $(y_i \langle \mathbf{w}^{(t)}, \mathbf{x}_i \rangle < 1)$

Set $\boldsymbol{\theta}^{(t+1)} = \boldsymbol{\theta}^{(t)} + y_i \mathbf{x}_i$

Else

Set $\boldsymbol{\theta}^{(t+1)} = \boldsymbol{\theta}^{(t)}$

output: $\bar{\mathbf{w}} = \frac{1}{T} \sum_{t=1}^T \mathbf{w}^{(t)}$

Homework

1. **Implementing SVM called Pegasos (2011) - 55 (+ 10 bonus)**
 1. Implement Class - 35
 2. Test - 10
 3. Analyze param - 5
 4. Analyze learning - 5
 5. Mini-batch bonus - 10*
2. **The effect of imbalance on SVM - 15**
3. **Practical SVM in scikit-learn & hypertune - 10**
4. **Using different Kernels - 20**

Another Way to Solve SVM

And other tricks

From Primal to Dual

Primal

$$\min f_0(x)$$

$$s.t \ f_i(x) \leq 0 \quad \forall i = 1..m$$

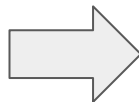
Original SVM definition

From Primal to Dual

Primal

$$\begin{aligned} \min f_0(x) \\ \text{s.t. } f_i(x) \leq 0 \quad \forall i = 1..m \end{aligned}$$

Original SVM definition



Dual

$$\begin{aligned} L(x, \alpha) &= f_0(x) + \sum_{i=1} \alpha_i f_i(x) \\ \alpha &\geq 0 \\ g(\alpha) &= \min_x L(x, \alpha) \end{aligned}$$

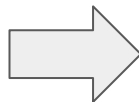
Dual definition that
solvable with
linear solvers

From Primal to Dual

Primal

$$\begin{aligned} \min & f_0(x) \\ \text{s.t.} & f_i(x) \leq 0 \quad \forall i = 1..m \end{aligned}$$

Original SVM definition



Dual

$$\begin{aligned} L(x, \alpha) &= f_0(x) + \sum_{i=1} \alpha_i f_i(x) \\ \alpha &\geq 0 \\ g(\alpha) &= \min_x L(x, \alpha) \end{aligned}$$

Dual definition that
solvable with
linear solvers

From Primal to Dual

Primal

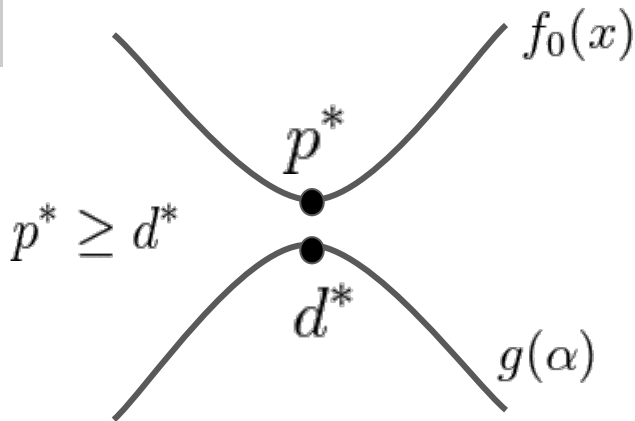
$$\begin{aligned} \min f_0(x) \\ \text{s.t. } f_i(x) \leq 0 \quad \forall i = 1..m \end{aligned}$$

Original SVM definition

Dual

$$\begin{aligned} L(x, \alpha) &= f_0(x) + \sum_{i=1} \alpha_i f_i(x) \\ g(\alpha) &= \min_x L(x, \alpha) \end{aligned}$$

Dual definition that
solvable with
linear solvers

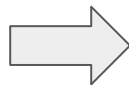


From Primal to Dual

Primal

$$\min f_0(x)$$

$$s.t \ f_i(x) \leq 0 \quad \forall i = 1..m$$



Dual

$$L(x, \alpha) = f_0(x) + \sum_{i=1}^m \alpha f_i(x)$$

$$g(x) = \min_x L(x, \alpha)$$

**SVM
definition**

$$\min \|w\|^2$$

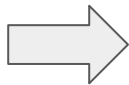
$$s.t \quad y_i w x_i \geq 1 \quad \forall i = 1..m$$

From Primal to Dual

Primal

$$\min f_0(x)$$

$$s.t \ f_i(x) \leq 0 \quad \forall i = 1..m$$



Dual

$$L(x, \alpha) = f_0(x) + \sum_{i=1}^m \alpha f_i(x)$$

$$g(x) = \min_x L(x, \alpha)$$

**SVM
definition**

$$\min \|w\|^2$$

$$s.t \ y_i w x_i \geq 1 \quad \forall i = 1..m$$

Modify

$$\min \frac{1}{2} \|w\|^2$$

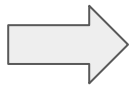
$$s.t \ 1 - y_i w x_i \leq 0 \quad \forall i = 1..m$$

From Primal to Dual

Primal

$$\min f_0(x)$$

$$s.t \ f_i(x) \leq 0 \quad \forall i = 1..m$$



Dual

$$L(x, \alpha) = f_0(x) + \sum_{i=1}^m \alpha f_i(x)$$

$$g(x) = \min_x L(x, \alpha)$$

**SVM
definition**

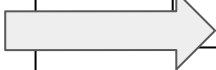
$$\min \|w\|^2$$

$$s.t \ y_i w x_i \geq 1 \quad \forall i = 1..m$$

Modify

$$\min \frac{1}{2} \|w\|^2$$

$$s.t \ 1 - y_i w x_i \leq 0 \quad \forall i = 1..m$$



$$L(x, \alpha) = \frac{1}{2} \|w\|^2 - \sum_{i=1}^m \alpha_i (y_i w x_i - 1)$$

$$g(\alpha) = \min_x \frac{1}{2} \|w\|^2 - \sum_{i=1}^m \alpha_i (y_i w x_i - 1)$$

From Dual to Primal

$$L(x, \alpha) = \frac{1}{2} \|w\|^2 - \sum_{i=1}^m \alpha_i (y_i w x_i - 1)$$

$$g(\alpha) = \min_x \frac{1}{2} \|w\|^2 - \sum_{i=1}^m \alpha_i (y_i w x_i - 1)$$

From Dual to Primal

$$L(x, \alpha) = \frac{1}{2} \|w\|^2 - \sum_{i=1}^m \alpha_i (y_i w x_i - 1)$$

$$g(\alpha) = \min_x \frac{1}{2} \|w\|^2 - \sum_{i=1}^m \alpha_i (y_i w x_i - 1)$$

$$\frac{\partial L}{\partial w} = 0$$

From Dual to Primal

$$L(x, \alpha) = \frac{1}{2} \|w\|^2 - \sum_{i=1}^m \alpha_i (y_i w x_i - 1)$$

$$g(\alpha) = \min_x \frac{1}{2} \|w\|^2 - \sum_{i=1}^m \alpha_i (y_i w x_i - 1)$$

$$\frac{\partial L}{\partial w} = 0$$

$$w - \sum_{i=1}^m \alpha_i y_i x_i = 0$$

$$w^* = \sum_{i=1}^m \alpha_i y_i x_i$$

$$\alpha_i \geq 0$$

Lagrange coefficients for each sample in the training set

**Optimization
Definition**

$$\max_{\alpha_k} \sum_{k=1}^R \alpha_k - \frac{1}{2} \sum_{k=1}^R \sum_{l=1}^R \alpha_k \alpha_l y_k y_l x_k x_l$$

All possible
pairs in the
training set

Constraints

$$s.t \quad 0 \leq \alpha_k \leq C \quad \sum_{k=1}^R \alpha_k y_k = 0$$

**Optimization
Definition**

$$\max_{\alpha_k} \sum_{k=1}^R \alpha_k - \frac{1}{2} \sum_{k=1}^R \sum_{l=1}^R \alpha_k \alpha_l y_k y_l x_k x_l$$

Constraints

$$s.t \quad 0 \leq \alpha_k \leq C \quad \sum_{k=1}^R \alpha_k y_k = 0$$

**Back to
Primal**

$$w = \sum_{k=1}^R \alpha_k y_k x_k$$

**Optimization
Definition**

$$\max_{\alpha_k} \sum_{k=1}^R \alpha_k - \frac{1}{2} \sum_{k=1}^R \sum_{l=1}^R \alpha_k \alpha_l y_k y_l x_k x_l$$

Constraints

$$s.t \quad 0 \leq \alpha_k \leq C \quad \sum_{k=1}^R \alpha_k y_k = 0$$

**Back to
Primal**

$$w = \sum_{k=1}^R \alpha_k y_k x_k$$

Predict

$$f(x, w) = \text{sign}(w, x)$$

**Optimization
Definition**

$$\max_{\alpha_k} \sum_{k=1}^R \alpha_k - \frac{1}{2} \sum_{k=1}^R \sum_{l=1}^R \alpha_k \alpha_l y_k y_l x_k x_l$$

Constraints

$$s.t \quad 0 \leq \alpha_k \leq C \quad \sum_{k=1}^R \alpha_k y_k = 0$$

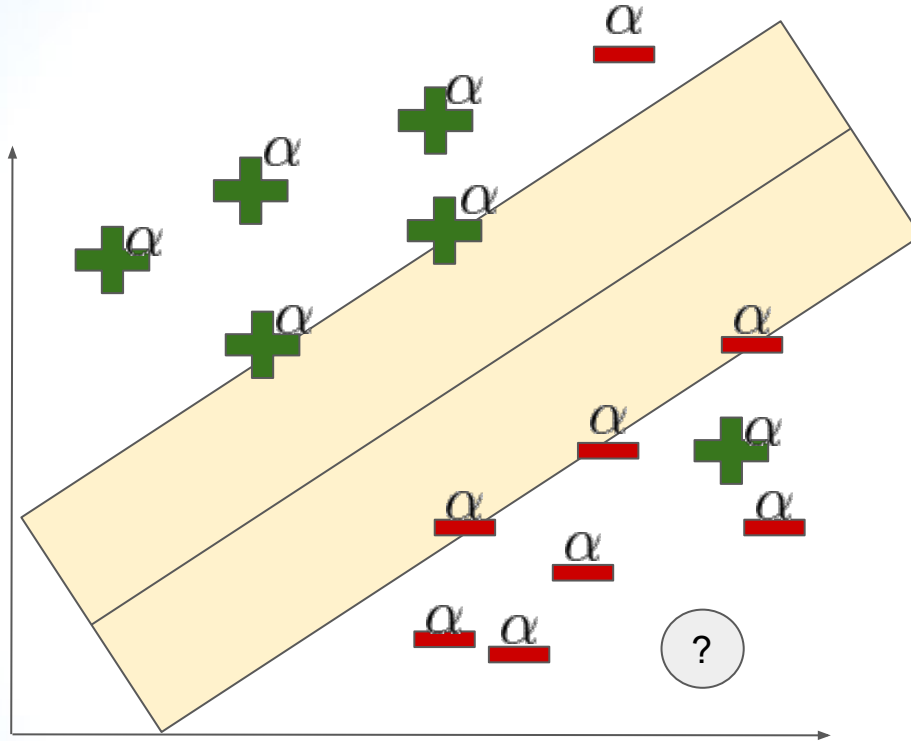
**Back to
Primal**

$$w = \sum_{k=1}^R \alpha_k y_k x_k$$

Predict

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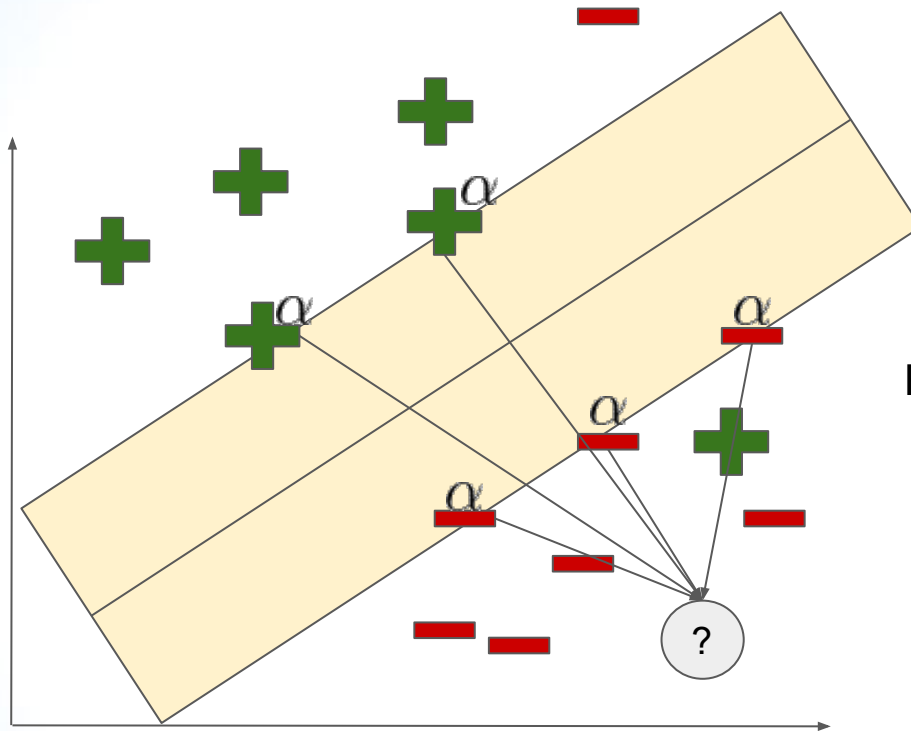
Applying



$$f(x, w) = \text{sign}\left(\sum_{k=1}^R \alpha_k y_k x_k x\right)$$

- What is the alpha values on the margin?
- Outside the margin?

Applying

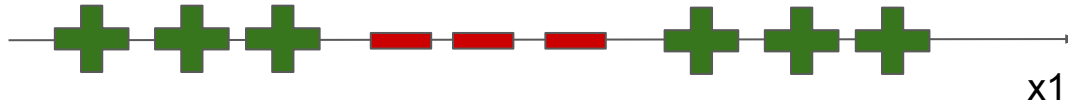


$$f(x, w) = \text{sign}\left(\sum_{k=1}^R \alpha_k y_k x_k x\right)$$

Reminds you something?

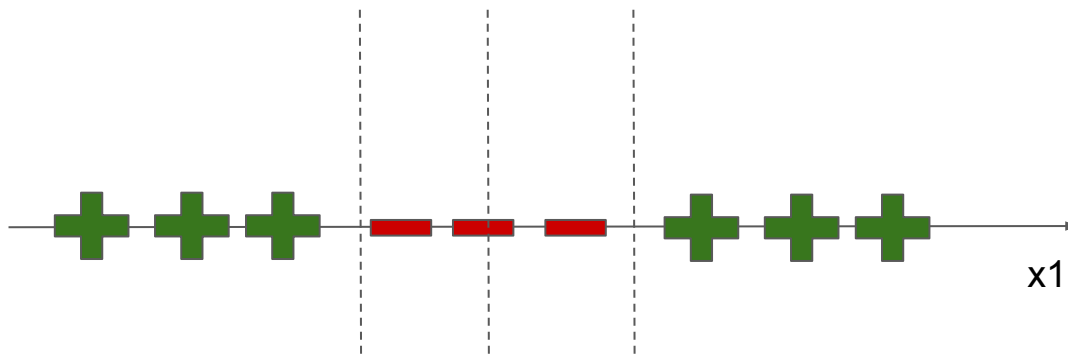
Dealing with non-linearity

How to separate with linear classifier?



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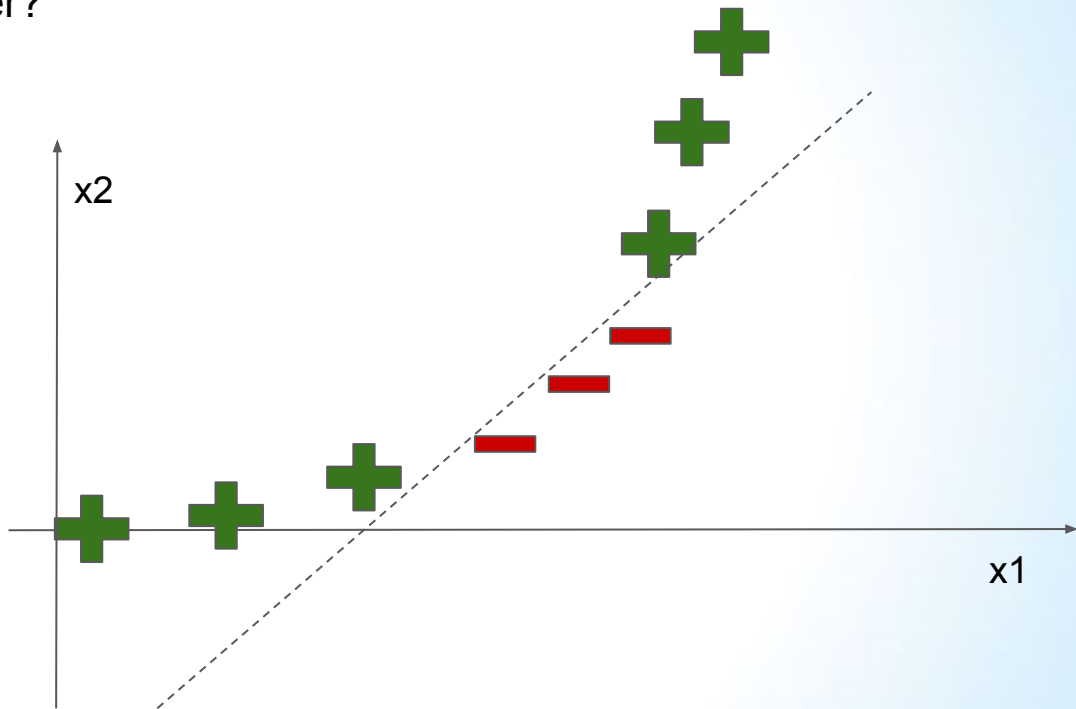


Dealing with non-linearity

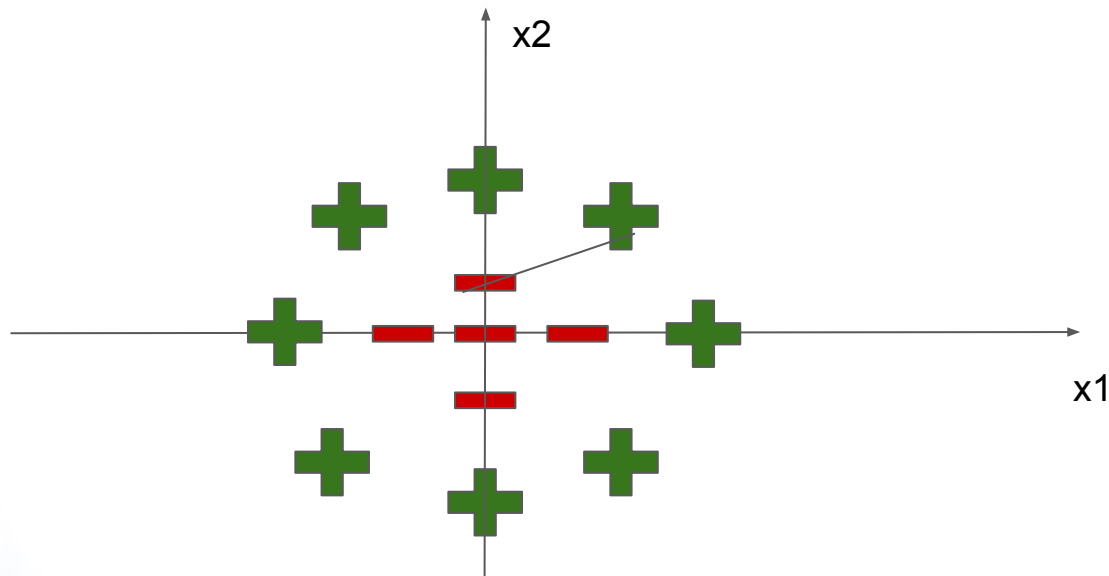
How to separate with linear classifier?

Use non-linear transformation

$$\phi(X) : \mathbb{R}^k \rightarrow \mathbb{R}^n | n > k$$

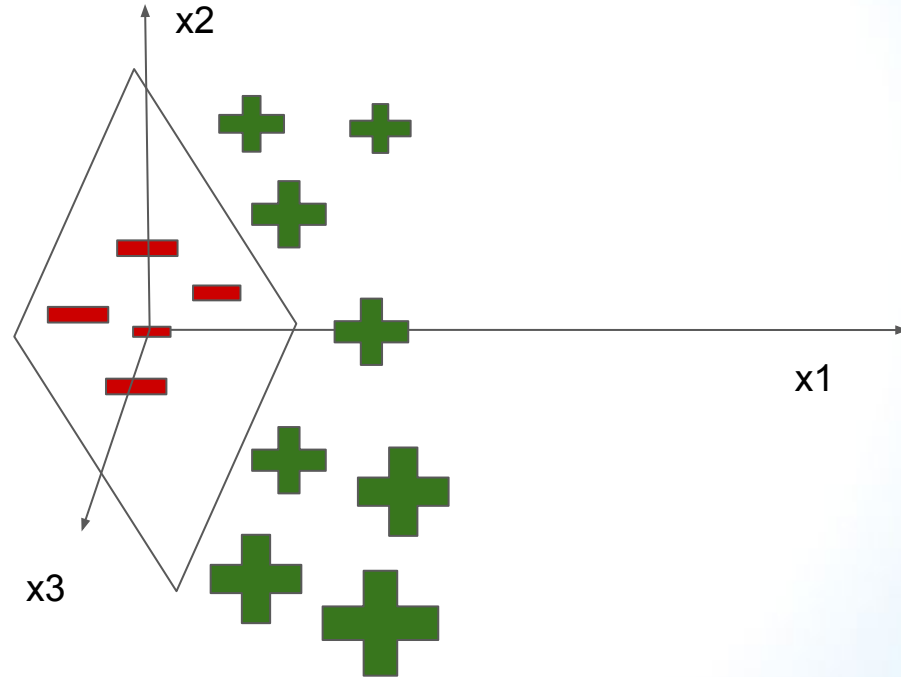


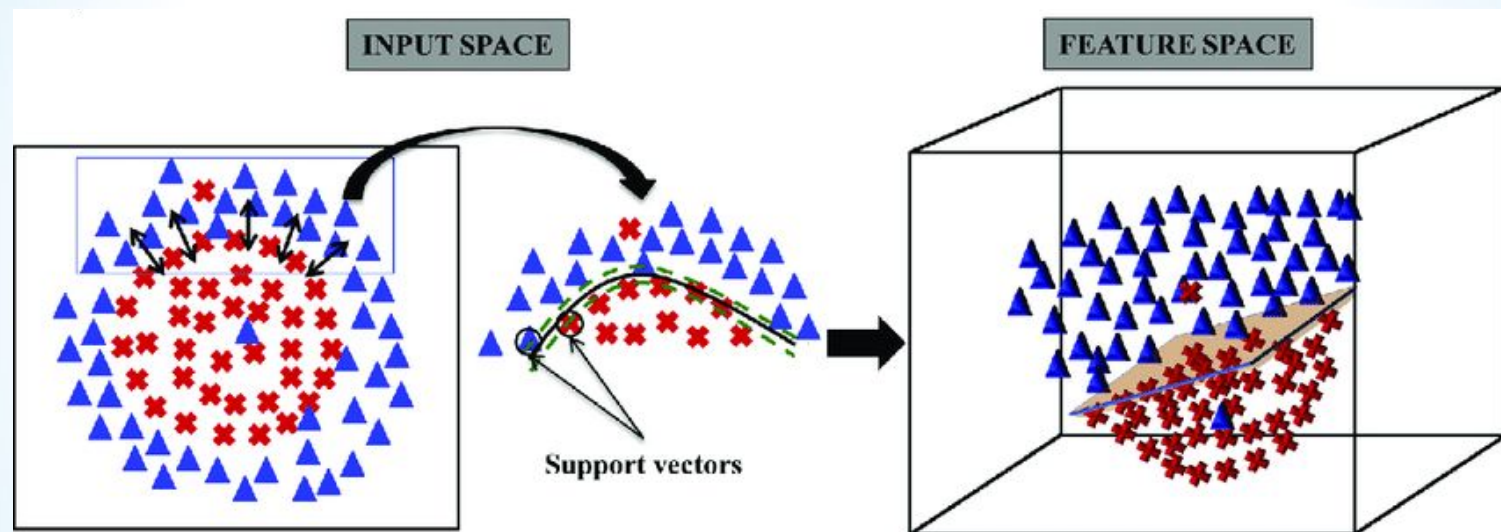
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Dealing with non-linearity

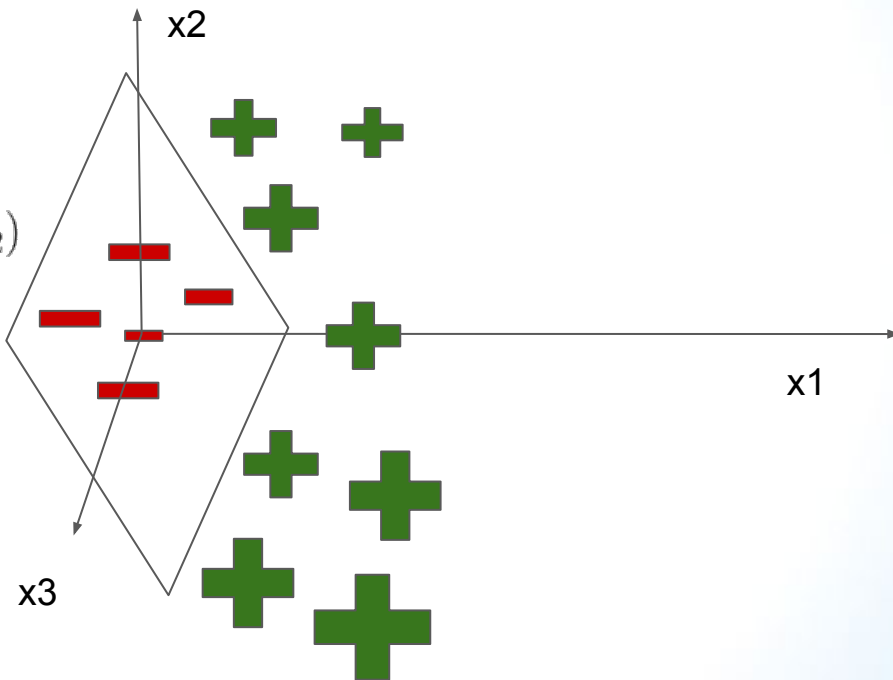
How to separate with linear classifier?

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$$(x_1, x_2) \mapsto \theta(X) = (x_1^2, x_2^2, \sqrt{2}x_1x_2)$$



A capital X = a datapoint



The Kernel Trick

To support this transformation We would need to compute all these features for each sample

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The Solution: the Kernel trick!

Use a dot product in feature space can be computed as kernel function

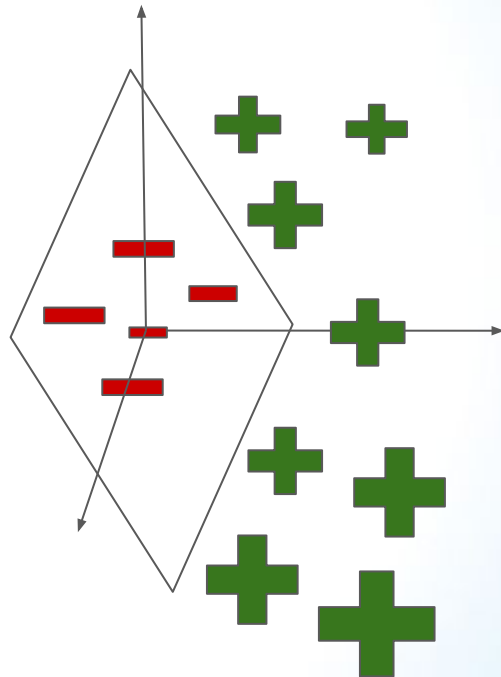
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$$K(X_i, X_j) = \phi(X_i)\phi(X_j) = (X_iX_j)^2$$

$$= (X_{i_1}^2, X_{i_2}^2, \sqrt{2}X_{i_1}X_{i_2})(X_{j_1}^2, X_{j_2}^2, \sqrt{2}X_{j_1}X_{j_2})^T = (X_{i_1}X_{j_1} + X_{i_2}X_{j_2})^2 = (X_iX_j)^2$$



The Kernel Trick

We would need to compute all these features!

The Solution: the Kernel trick!

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Where do we have dot product in SVM?

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We still need to compute all the kernels pairs, but we don't need to maintain the feature space

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Predict

$$f(x, w) = \text{sign}(w, x) \qquad f(x, w) = \text{sign}\left(\sum_{k=1}^R \alpha_k y_k x_k x\right)$$

Good Kernel Functions for SVM

On top the polynomial kernel function there are more suitable ones:

Radial Basis Function (RBF):

$$K(X_i, X_j) = \exp \left(-\frac{(X_i - X_j)^2}{2\sigma^2} \right)$$

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hypertune



SVM Pros & Cons

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Bad

- $O(n^2-3)$ runtime depends on C and the kernel (n number of datapoints)
- $O(n^2)$ memory to compute all the pairwise kernels - 5-10K datapoints
- different values for the Kernel prams

Q&A

VC Dimension - <https://www.youtube.com/watch?v=puDzy2XmR5c>

<https://winvector.github.io/margin/margin.pdf>

<https://youtu.be/LceLJvKMbBk?t=7311>

<https://youtu.be/fB47g3QM0sk?t=839>

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<https://www.cs.cornell.edu/courses/cs4780/2018fa/lectures/lecturenote09.html>