

Mining Streaming Data

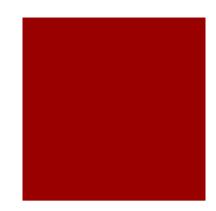


To understand the **importance** of mining methods for streaming data, and learn about existing **methods** handling streaming data

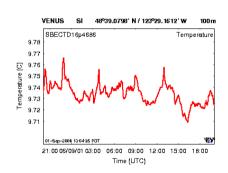


- Stream data sets are...
  - Continuous
  - Massive
  - Unbounded
  - Possibly infinite
- Fast changing and requires fast, real-time response
  - Examples:

Life threatening: collision avoidance Lost revenue/transactions: hung-up networks









### Sizing the challenge

- WalMart Records > 20 Million Transactions
- Google Handles > 100 Million Searches
- AT&T produces >275 million call records
- Earth sensing satellite produces GBs of data
- Twitter handles millions of tweets in a second

This just in a day!

### The Stream Model

- Input tuples enter at a rapid rate, at one or more input ports.
- Impractical to store the whole streaming data
- How do you make critical calculations about the stream using a limited amount of (primary or secondary) memory?
- Simple calculation per data due to time and space constraints

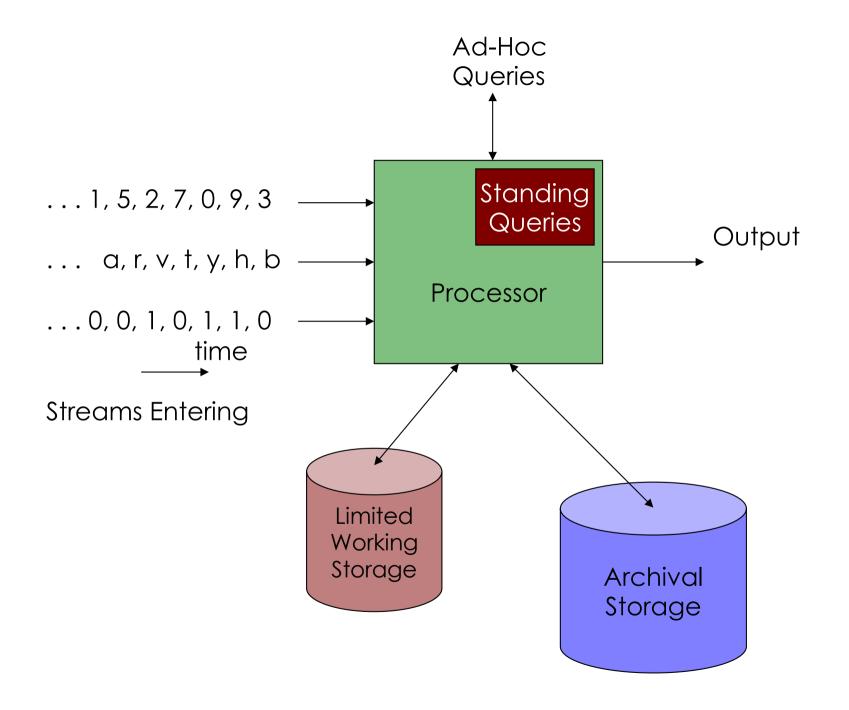


- Not enough memory
- Can't afford storing/revisiting the data
  - Single pass computation
- External memory algorithms for handling data sets larger than main memory cannot be used.
  - Do not support continuous queries
  - Too slow real-time response



# Two Forms of Query

- Ad-hoc queries: Normal queries asked one time about streams.
  - Example: What is the maximum value seen so far in stream S?
- 2. Standing queries: Queries that are, in principle, asked about the stream at all times.
  - Example: Report each new maximum value ever seen in stream S.



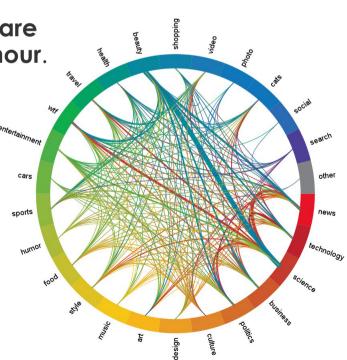
### Example Applications

- Mining query streams.
  - E.g.: Google wants to know what queries are more frequent today than yesterday.
- Mining click streams.

E.g.: Yahoo wants to know which of its pages are getting an unusual number of hits in the past hour.

 Often caused by annoyed users clicking on a broken page.

- IP packets can be monitored at a switch.
  - E.g.:
    - Gather information for optimal routing.
    - Detect denial-of-service attacks.



# Sliding Windows

- A useful model of stream processing
  - queries are about a window of length N the N most recent elements received.
  - **Alternative**: elements received within a time interval *T*.

### Interesting case:

- N too large to be stored in main memory
- Or, too many streams that windows for all do not fit in main memory.

### Sliding Windows

```
qwertyuio pasdfghjklzxcvbnm
qwertyuiopasdfghjklzxcvbnm
qwertyuiopasdfghjklzxcvbnm
qwertyuiopa<mark>sdfgh</mark>jklzxcvbnm
   —— Past
                    Future
```

### Example: Averages

- Stream of integers, window of size N.
- Standing query: what is the average of the integers in the window?
- For the first N inputs, sum and count to get the average.

### Question:

What do we do now for the next input i?

### Example: Averages

#### **Answer:**

- When a new input *i* arrives:
  - change the average by adding (i j)/N, where j is the oldest integer in the window before i arrived.

- Good: O(1) time per input.
- Bad: Requires the entire window in main memory.



# Counting 1's

Approximating Counts
Exponentially Growing Blocks
DGIM Algorithm

### Approximate Counting

- Can show that an exact sum or count of the elements in a window:
  - Cannot use less space than the window itself.
- If willing to accept an **approximation**:
  - Can use much less space.
- Consider the simple case of counting bits
- Sums are a fairly straightforward extension.

### Counting Bits

- Problem: given a stream of 0's and 1's, be prepared to answer queries of the form "how many 1's in the most recent k bits?" where  $k \le N$ .
- Obvious solution: store the most recent N bits
- But answering the query will take O(k) time
  - Very possibly too much time.
- And the space requirements can be too great.
  - Especially if many streams to be managed in main memory at once, or N is huge.

### Example: Bit Counting

- Count recent hits on URL's belonging to a site.
- Stream is a sequence of URL's.
- Window size N = 1 billion.
- Think of the data as many streams one for each URL.
- Bit on the stream for URL x is 0 unless the actual stream has x.

### DGIM Method

- Name refers to the inventors:
  - Datar, Gionis, Indyk, and Motwani.
- Store only  $O(log_2N)$  bits per stream.
  - $\blacksquare$  N = window size.
- Gives approximate answer, never off by more than 50%.
  - Error factor can be reduced to any ε > 0, with more complicated algorithm and proportionally more stored bits.

### Timestamps

- Each bit in the stream has a timestamp, starting
   0, 1, ...
- Record timestamps modulo N (the window size), so we can represent any *relevant* timestamp in  $O(log_2N)$  bits.

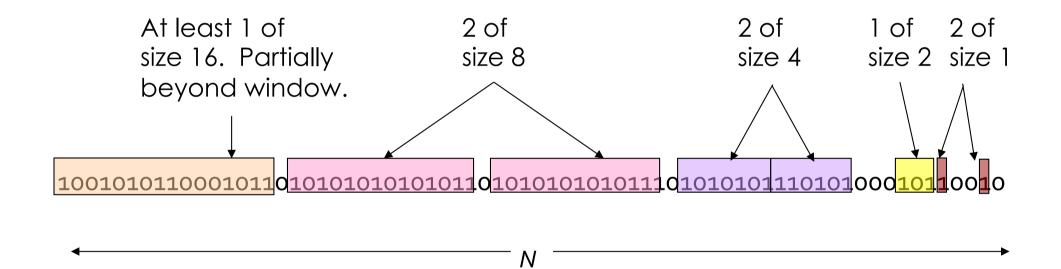
### **Buckets**

- A segment of the window, represented by a record consisting of:
  - The **timestamp** of its end [O(log N) bits].
  - The number of 1's between its beginning and end.
    - Number of 1's = size of the bucket.
- Constraint on bucket sizes: number of 1's must be a power of 2.
  - Thus, only O(log log N) bits are required for this count.

# Representing a Stream by Buckets

- Either one or two buckets with the same powerof-2 number of 1's.
- Buckets do not overlap.
- Buckets sorted by size.
  - Older buckets not smaller than newer buckets.
- Buckets disappear when their end-time is > N time units in the past.

## Example: Bucketized Stream



### Updating Buckets

- New bit in, drop the last (oldest) bucket if its endtime is prior to N time units before the current time.
- If the current bit is 0, no other changes are needed.

# Updating Buckets: Input = 1

- If the current bit is 1:
  - Create a new bucket of size 1, for just this bit.
    - End timestamp = current time.
  - If there are now three buckets of size 1, combine the oldest two into a bucket of size 2.
  - If there are now three buckets of size 2, combine the oldest two into a bucket of size 4.
  - And so on ...

# Example: Managing Buckets

Initial

```
1 arrives; makes third block of size 1.
Combine oldest two 1's into a 2.
Later, 1, 0, 1 arrive. Now we have 3 1's again.
                101011101010101110101000101100
01011000101101010101010101010101
            Combine two 1's into a 2.
```

The effect ripples all the way to a 16.

### Querying

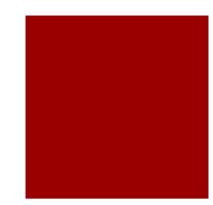
- To estimate the number of 1's in the most recent k < N bits:</p>
  - Restrict your attention to only those buckets whose end time stamp is at most k bits in the past.
  - Sum the sizes of all these buckets but the oldest.
  - Add half the size of the oldest bucket.
- Remember:
  - we don't know how many 1's of the last bucket are still within the window.

### **Error Bound**

- Suppose the oldest bucket within range has size 2i.
- Then by assuming 2*i* -1 of its 1's are still within the window, we make an error of at most 2*i* -1.
- Since there is at least one bucket of each of the sizes less than 2i, and at least 1 from the oldest bucket, the true sum is no less than 2i.
- Thus, error at most 50%.

### Space Requirements

- Can represent one bucket in O(log N) bits.
  - It's just a timestamp needing log N bits and a size, needing log log N bits.
- No bucket can be of size greater than N.
- There are at most two buckets of each size 1, 2, 4, 8,...
- That's at most log N different sizes, and at most 2 of each size, so at most 2log N buckets.



- Bloom Filters
- Sampling Streams
- Counting Distinct Items

## Filtering Stream Content

- To motivate the **Bloom-filter** idea, consider a web crawler.
- It keeps, centrally, a list of all the URL's it has found so far.
- It assigns these URL's to any of a number of parallel tasks
  - these tasks stream back the URL's they find in the links they discover on a page.
- It needs to filter out those URL's it has seen before.

### Role of the Bloom Filter

- A Bloom filter placed on the stream of URL's will declare that certain URL's have been seen before.
- Others will be declared new, and will be added to the list of URL's that need to be crawled.
- Unfortunately, the Bloom filter can have false positives.
  - It can declare a URL seen before when it hasn't.
- But if it says "never seen," then it is truly new.
- Solution: restart the filter periodically.

### Example: Filtering Chunks

- Suppose we have a database relation stored in a DFS, spread over many chunks.
- We want to find a particular value v, looking at as few chunks as possible.
- A Bloom filter on each chunk will tell us certain values are there, and others aren't.
  - As before, false positives possible
- But now things are exactly right: if the filter says v is not at the chunk, it surely isn't.
  - Occasionally, we retrieve a chunk we don't need, but can't miss an occurrence of value v.

### How a Bloom Filter Works

- A Bloom filter is an array of bits, together with a number of hash functions.
- The argument of each hash function is a stream element, and it returns a position in the array.
- Initially, all bits are 0.
- When input x arrives, we set to 1 the bits h(x), for each hash function h.

### Example: Bloom Filter

- Use N = 11 bits for our filter.
- Stream elements = integers.
- Use two hash functions:
  - h1(x) =
    - Take **odd-numbered bits from the right** in the binary representation of x.
    - Treat it as an integer i.
    - Result is i modulo 11.
  - h2(x) = same, but take even-numbered bits.

# Example - Continued

Stream element	$h_{1}$	h <sub>2</sub>	Filter contents
			000000000
25 = <b>11</b> 0 <b>0</b> 1	5	2	00100100000
159 = <b>1</b> 0 <b>0</b> 1 <b>1</b> 1 <b>1</b> 1	7	0	10100101000
585 = <b>1</b> 001001001	9	7	10100101010
			Note: bit 7 was already 1.

### Bloom Filter Lookup

- Suppose element y appears in the stream, and we want to know if we have seen y before.
- Compute h(y) for each hash function y.
- If all the resulting bit positions are 1, say we have seen y before.
  - We could be wrong.
    - Different inputs could have set each of these bits.
- If at least one of these positions is 0, say we have not seen y before.
  - We are certainly right.

#### Example: Lookup

- Suppose we have the same Bloom filter as before, and we have set the filter to 10100101010.
- Lookup element y = 118 = 1110110 (binary).
- $h_1(y) = 14 \text{ modulo } 11 = 3.$
- $h_2(y) = 5 \text{ modulo } 11 = 5.$
- Bit 5 is 1, but bit 3 is 0, so we are sure y is not in the set.

#### Performance of Bloom Filters

- Probability of a false positive depends on the density of 1's in the array and the number of hash functions.
  - = (fraction of 1's) # of hash functions.
- The number of 1's is approximately the number of elements inserted times the number of hash functions.
  - But collisions lower that number slightly.

### Sampling a Stream

## When Sampling Doesn't Work

- Suppose Google would like to examine its stream of search queries for the past month to find out what fraction of them were unique – asked only once.
- But to save time, we are only going to sample 1/10th of the stream.
- The fraction of unique queries in the sample != the fraction for the stream as a whole.
  - In fact, we can't even adjust the sample's fraction to give the correct answer.

# Example: Unique Search Queries

- The length of the sample is 10% of the length of the whole stream.
- Suppose a query is unique.
  - It has a 10% chance of being in the sample.
- Suppose a query occurs exactly twice in the stream.
  - It has an 18% chance of appearing exactly once in the sample.
- And so on ... The fraction of unique queries in the stream is unpredictably large.

#### Sampling by Value

- My mistake: I sampled based on the position in the stream, rather than the value of the stream element.
- The right way: hash search queries to 10 buckets 0, 1,..., 9.
- Sample = all search queries that hash to bucket0.
  - All or none of the instances of a query are selected.
  - Therefore the fraction of unique queries in the sample is the same as for the stream as a whole.

#### Controlling the Sample Size

- Problem: What if the total sample size is limited?
- Solution: Hash to a large number of buckets.
- Adjust the set of buckets accepted for the sample, so your sample size stays within bounds.

#### Example: Fixed Sample Size

- Suppose we start our search-query sample at 10%, but we want to limit the size.
- Hash to (say) 100 buckets, 0, 1,..., 99.
  - Take for the sample those elements hashing to buckets 0 through 9.
- If the sample gets too big, get rid of bucket 9.
- Still too big, get rid of 8, and so on.

#### Sampling Key-Value Pairs

- This technique generalizes to any form of data that we can see as tuples (K, V), where K is the "key" and V is a "value."
- Distinction: We want our sample to be based on picking some set of keys only, not pairs.
  - In the search-query example, the data was "all key."
- Hash keys to some number of buckets.
- Sample consists of all key-value pairs with a key that goes into one of the selected buckets.

#### Example: Salary Ranges

- Data = tuples of the form (EmpID, Dept, Salary).
- Query: What is the average range of salaries within departments?
- Key = Dept.
- Value = (EmpID, Salary).
- Sample picks some departments, has salaries for all employees of that department, including its min and max salaries.
- Result will be an unbiased estimate of the average salary range.

#### Counting Distinct Elements

- Problem: a data stream consists of elements chosen from a set of size n. Maintain a count of the number of distinct elements seen so far.
- Obvious approach: maintain the set of elements seen.

#### Application Examples

- How many different words are found among the Web pages being crawled at a site?
  - Unusually low or high numbers could indicate artificial pages (spam?).
- How many unique users visited Facebook this month?
- How many different pages link to each of the pages we have crawled.
  - Useful for estimating the PageRank of these pages.
    - Which in turn can tell a crawler which pages are most worth visiting.

#### Estimating Counts

- Real Problem: what if we do not have space to store the complete set?
  - Or we are trying to count lots of sets at the same time.
- Estimate the count in an unbiased way.
- Accept that the count may be in error, but limit the probability that the error is large.



- A probabilistic counting algorithm
- Used to estimate number of distinct elements in a large file originally
- Use little memory
- Single pass only
- Based on statistical observation made on bits of hashed values

#### Flajolet-Martin Approach (2)

Estimating the cardinality of a multiset M:

```
for i :=0 to N - 1 do BITMAP[i] :=0;

for all x in M do
    begin
    index := p(hash(x));
    if BITMAP[index] = 0 then BITMAP[index] := 1;
    end;

R := the largest index in BITMAP whose value equals to 1
Estimate := 2<sup>R</sup>
```

### Flajolet-Martin Approach (3)

- If the final BITMAP looks like this: 0000,0000,1100,1111,1111,1111
- The left most 1 at position 15
- Thus, have around 2<sup>15</sup> distinct elements in the stream