Norwegian University of Science and Technology

TDT4300 — Solution to Assignment 3

CLUSTERING

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1 k-Means Clustering

1.1 Assignment

This is a programming part of the assignment. Your task is to implement the k-means clustering algorithm and assess the quality of the outputs by calculating Silhouette Coefficient. You are given a Jupyter Notebook¹ (formerly known as the IPython Notebook) file k_means_clustering.ipynb in which you have to implement only two functions: kmeans() and silhouette_score(). Everything else has already been prepared for you. As you have maybe already guessed, the programming language of our choice is Python.

Before you start, you need to install Jupyter Notebook and Python 3. Having that done, open your terminal, navigate to a folder with the k_means_clustering.ipynb file, and execute the command jupyter notebook. A window of your Internet browser should pop-up with the Jupyter Notebook interface. Open the k_means_clustering.ipynb notebook, read it carefully through, and execute it line by line. If this is new to you, get yourself familiar with the Jupyter Notebook and Python.

The assignment is very easy as you do not have to worry about anything else except the core k-means algorithm and Silhouette Coefficient. If you consider yourself a good programmer but without knowledge of Python, you should not have struggles, and you can add a new programming language to your portfolio. If you consider yourself a rather unexperienced programmer and without knowledge of Python, it is a good chance to learn new beginner friendly programming language, and gain more practice in programming. If programming scares you, seek help from other students. Use Piazza to find help if you do not know anyone. We do not have to remind you that plagiarism is not tolerable.

¹https://jupyter.org/

1.2 Solution

An example implementation of the k-means clustering algorithm will not be provided.

2 Hierarchical Agglomerative Clustering (HAC)

2.1 Assignment

- (a) Explain the Hierarchical Agglomerative Clustering (HAC) and the difference between MIN-link and MAX-link.
- (b) You are given a two-dimensional dataset shown in Table 1. Perform HAC (for both MIN-link and MAX-link) and present the results in the form of dendrogram. Use the Euclidean distance. **Describe thoroughly the process and the outcome of each step.**
- (c) Verify your results using the KNIME data analytics platform. For clarification, MIN-link and MAX-link is in KNIME referred as SINGLE and COMPLETE linkage methods. We provide you the file hac_dataset.csv containing the very same data. Present a picture of your workflow and the dendrograms.

ID	x	y
A	5	7
В	4	3
С	9	8
D	5	6
Е	11	3

Table 1: Dataset for HAC.

2.2 Solution

(a) Hierarchical Agglomerative Clustering is described in detail in Section 8.3 of "Introduction to Data Mining" by Tan at al. The clustering algorithm starts with individual data points as the initial clusters and in each step merges the closest clusters. The proximity of two clusters can be defined in several ways; MIN-link and MAX-link are two of them.

MIN-link, MAX-link. From the Section 8.3.1 of the book: Min-link (single-link) defines cluster proximity as the proximity between the closest two points that are in different

clusters, or using graph terms, the shortest edge between two nodes in different subsets of nodes. Max-link (complete link) takes the proximity between the farthest two points or using graph terms, the longest edge between two nodes in different subsets of nodes.



Figure 1: MIN-link

Figure 2: MAX-link

(b) Using the Euclidean distance, we first calculate the distance matrix for the initial data points:

d	A	В	С	D	E
A	0.00	-	-	-	-
В	5.66	0.00	-	-	-
C	4.12	9.43	0.00	-	-
D	1.00	5.00	4.47	0.00	-
E	7.21	10.00	5.39	6.70	0.00

Table 2: Distance matrix (A and D will be merged into a cluster).

MIN-link We see that A,B and C are the closest points and therefor they form a new cluster. In the MIN-link version, we select one of the cluster's points so that the distance to the other points is shortest possible. Following tables illustrate present result after each iteration of the algorithm.

d	A, D	В	С	E
A, D	0.00	-	-	-
В	5.00	0.00	-	-
C	4.12	9.43	0.00	-
E	6.70	10.00	5.39	0.00

Table 3: Distance matrix (A, D and C will be merged into a cluster).

d	A, D, C	В	E
A, D, C	0.00	-	-
В	5.00	0.00	-
E	5.39	10.00	0.00

Table 4: Distance matrix (A,D,C) and B will be merged into a cluster).

d	A, D, C, B	E
A, D, C, B	0.00	-
E	5.39	0.00

Table 5: Final distance matrix.

MAX-link

In the MAX-link algorithm, we still select the closest points to form a cluster. The difference from the MIN-link is that when we recalculate the distance matrix, we keep the longest distance between a newly formed cluster and the rest of data points.

d	A, D	В	C	E
A, D	0.00	-	-	-
В	5.66	0.00	-	-
C	4.47	9.43	0.00	-
E	7.21	10.00	5.39	0.00

Table 6: Distance matrix (A,D) and C will be merged into a cluster).

d	A, D, C	В	E
A, D, C	0.00	-	-
В	9.43	0.00	-
E	7.21	10.00	0.00

Table 7: Distance matrix (A,D,C) and E will be merged into a cluster).

d	A, D, C, E	В	
A, D, C, E	0.00	-	-
В	10.00	0.00	-

Table 8: Final distance matrix.

The resulting dendrograms are shown in Figures 4 and 5.

(c) Following figures show the Knime workflow and resulting dendograms.

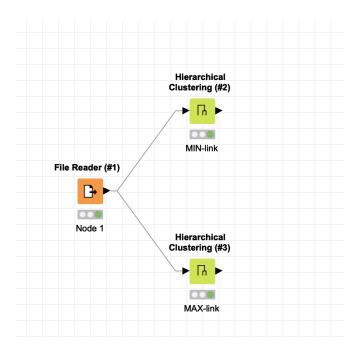


Figure 3: KNIME workflow.

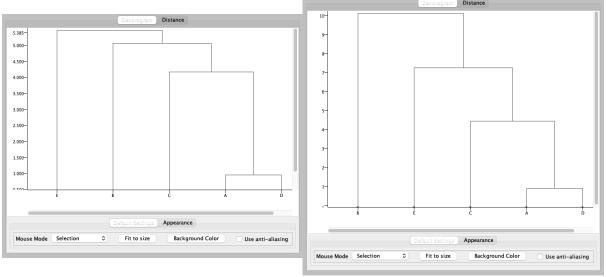


Figure 4: Dendrogram for MIN-link. ((((A + D) + C) + B) + E)

Figure 5: Dendrogram for MAX-link. ((((A + D) + C) + E) + B)

3 DBSCAN Clustering

3.1 Assignment

You are given following points: $P_0 = (14,1)$, $P_1 = (1,8)$, $P_2 = (3,12)$, $P_3 = (5,1)$, $P_4 = (13,11)$, $P_5 = (12,6)$, $P_6 = (4,12)$, $P_7 = (1,8)$, $P_8 = (8,3)$, $P_9 = (5,1)$, $P_{10} = (14,12)$, $P_{11} = (12,9)$, $P_{12} = (4,5)$, $P_{13} = (8,4)$, $P_{14} = (2,3)$.

- (a) Your task is to perform DBSCAN clustering given the parameters Eps = 4 (Euclidean metric) and MinPts = 3 (including the analyzed point). Identify core, border and noise points. Identify clusters. **Describe thoroughly the process and the outcome of each step.**
- (b) Verify your results using the KNIME data analytics platform. We provide you the file $dbscan_dataset.csv$ containing the very same data. Present a picture of your workflow and the scatter plot with marked clusters and outliers.

Describe thoroughly the process and the outcome of each step.

3.2 Solution

First, we are going to label the points as core, border or noise points. For the labeling we need to know the neighborhood N of each point considering Eps = 4. The Euclidean distance between each point must be calculated in order to explore the neighborhood.

0	1	2	3	4	5	6	7	8	9	10	11	12	13	14
0.00	14.76	15.56	9.00	10.05	5.39	14.87	14.76	6.32	9.00	11.00	8.25	10.77	6.71	12.17
14.76	0.00	4.47	8.06	12.37	11.18	5.00	0.00	8.60	8.06	13.60	11.05	4.24	8.06	5.10
15.56	4.47	0.00	11.18	10.05	10.82	1.00	4.47	10.30	11.18	11.00	9.49	7.07	9.43	9.06
9.00	8.06	11.18	0.00	12.81	8.60	11.05	8.06	3.61	0.00	14.21	10.63	4.12	4.24	3.61
10.05	12.37	10.05	12.81	0.00	5.10	9.06	12.37	9.43	12.81	1.41	2.24	10.82	8.60	13.60
5.39	11.18	10.82	8.60	5.10	0.00	10.00	11.18	5.00	8.60	6.32	3.00	8.06	4.47	10.44
14.87	5.00	1.00	11.05	9.06	10.00	0.00	5.00	9.85	11.05	10.00	8.54	7.00	8.94	9.22
14.76	0.00	4.47	8.06	12.37	11.18	5.00	0.00	8.60	8.06	13.60	11.05	4.24	8.06	5.10
6.32	8.60	10.30	3.61	9.43	5.00	9.85	8.60	0.00	3.61	10.82	7.21	4.47	1.00	6.00
9.00	8.06	11.18	0.00	12.81	8.60	11.05	8.06	3.61	0.00	14.21	10.63	4.12	4.24	3.61
11.00	13.60	11.00	14.21	1.41	6.32	10.00	13.60	10.82	14.21	0.00	3.61	12.21	10.00	15.00
8.25	11.05	9.49	10.63	2.24	3.00	8.54	11.05	7.21	10.63	3.61 ü	0.00	8.94	6.40	11.66
10.77	4.24	7.07	4.12	10.82	8.06	7.00	4.24	4.47	4.12	12.21	8.94	0.00	4.12	2.83
6.71	8.06	9.43	4.24	8.60	4.47	8.94	8.06	1.00	4.24	10.00	6.40	4.12	0.00	6.08
12.17	5.10	9.06	3.61	13.60	10.44	9.22	5.10	6.00	3.61	15.00	11.66	2.83	6.08	0.00

Table 9: Distance matrix.

With MinPts = 3 (we understand it as the minimum count of the neighborhood points, including the analyzed point). The points P_3 , P_8 , P_9 are P_{14} are labeled as the core points of

one cluster with the border points P_{12} and P_{13} . The points P_4 , P_{10} and P_{11} are the core points of the next cluster with the border point P_5 . All other points $(P_0, P_1, P_2, P_6 \text{ and } P_7)$ are the noise points which can be eliminated.

We define a cluster for each group of core points that are within Eps of each other and assign each border point to one of the cluster of its associated core points. This results in two clusters $C_1 = \{P_3, P_8, P_9, P_{12}, P_{13}, P_{14}\}$ and $C_2 = \{P_4, P_5, P_{10}, P_{11}\}$.

It is not really necessary to calculate the distance matrix in this exercise. The dataset is very small and illustrating it in a Cartesian coordinate plane can reveal the distances between the points.

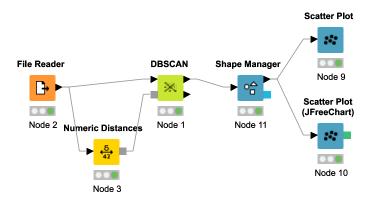


Figure 6: KNIME workflow.

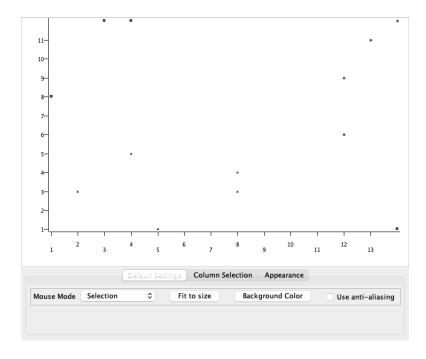


Figure 7: KNIME generated plot.