MATLAB Tutorial for Differential Equations

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DISCLAIMER Almost everything you can do in MATLAB, you can do in Python, for free, with the addition of the packages NumPy, SciPy, and Matplotlib (and SymPy for the symbolic stuff). While MATLAB may be free to you now while you're a student, it may not be once you graduate. MATLAB is, as its name suggests, best suited to matrix computations. It is not a very good general-purpose programming language, and many of its misfeatures are baked in by a need for backwards compatibility with 32 years worth of legacy scripts. While MATLAB is still the most commonly used language in many regions of academia, you may want to investigate other languages if you decide you want to do any programming outside of this class.

The script which generates this document is uploaded at http://github.com/tsbertalan/matlabTutorial.

Basics

Statements can be closed with a semicolon,

$$x = 3*4;$$

or left unclosed, in which case they will print when evaluated.

$$x = 3*4$$

x =

12

Most basic operations act as you'd expect.

ans =

8.3333

However, you may sometimes want to use elementwise operations with matrix arguments, particularly for multiplication and exponentiation. This is done by preceding the operations with a period.

```
x = [1, 2, 3];
y = [4, 5, 6];
%x^y % fails
x .^ y

ans =
1 32 729
```

Longer statements can be broken across several lines with an ellipsis Whitespace is not syntactic.

```
x = 3 * 9 + 4 ...
/32 + (...
5 / 3 + 6 ...
);
```

Loops can be written with for or while. You'll probably find for more useful.

```
for x=1:10
    y = x*2;
end

x = 1;
while x <= 10
    y = x*2;
    x = x + 1;
end

xvalues = [1 4 12 6];
total = 0;
for x=xvalues
    total = total + x;
end</pre>
```

The disp command can be used for explicitly printing things. Or fprintf can be used for more control.

In the MATLAB Desktop, you can get help for most commands and functions by placing your edit cursor in the command and pressing F1. The help for fprintf looks like this on my machine:



Standard flow control constructs are available.

```
x = sqrt(2);
if x < 2
    disp('less');
elseif true == false
    disp('impossible');
else
    disp('greater');
end

less</pre>
```

You can also use switch statements if you think they're warranted.

```
option = 'abcdefg';
switch option
   case 'abcdefg'
        disp('alphabet');
   case 42
        disp('meaning of life');
end

alphabet
```

Arrays

Matlab arrays are always at least two-dimensional. So, "vectors" are always either single-row or single-column matrices. You can inspect the dimensions of an array with the size command.

```
nValues = 1:10;
size(nValues)

ans =
1 10
```

You can transpose a matrix with either an apostrophe or the transpose command.

```
size(nValues')
%size(transpose(nValues)) % (same thing)
ans =
10 1
```

You can compose arrays explicitly with commas, spaces, and semicolons. Commas and spaces are used to separate values within the same row, and semicolons are used to separate values in different rows.

```
A = [1 \ 2 \ 3; \ 4 \ 5 \ 6]
B = [7, 8, 9; 1, 2, 3]
C = [4, 6 2; 5, 8 2] % This is pretty ugly.
         A =
               1
                      2
                      5
                             6
         B =
               7
                      8
                             9
               1
                      2
                             3
         C =
                             2
               4
                      6
               5
```

Ranges of values can be generated with the START: INCREMENT: STOP syntax.

2:3:12

MATLAB Tutorial for Differential Equations

ans = 2 5 8 11

If you leave out INCREMENT, it defaults to one.

2:12

ans = 2 3 4 5 6 7 8 9 10 11 12

You can reshape arrays, possibly changing the number of dimensions.

reshape(1:12, 3, 4) reshape(1:12, 4, 3)

ans =

1 4 7 10 2 5 8 11 3 6 9 12

Higher-dimensional arrays are also possible, if its useful for the organization of your problem.

threeDeeArray = reshape(1:12, 2, 3, 2)

4

6

threeDeeArray(:,:,2) =

7 9 11 8 10 12

You can index an array explicitly.

threeDeeArray(1, 3, 2) = 42;

2

The end keyword stands for last entry.

```
threeDeeArray(1, end, 2)
         ans =
             42
You can also flatten multidimensional arrays back to a column-vector (transposed here for space).
flattened = threeDeeArray(:)'
flattened(11)
%%hold all;
% Arrays can also be indexed by slices
threeDeeArray(1, :, :)
         flattened =
              1
                     2
                            3
                                        5
                                                6
                                                                     9
                                                                           10
         ans =
             42
         ans(:,:,1) =
              7
                     3
                            5
         ans(:,:,2) =
              7 9
                           42
or by an array of indices.
indices = find(threeDeeArray(1, 3, :) == 42)
threeDeeArray(1, 3, indices)
         indices =
              2
         ans =
             42
```

42

12

One of the major shortcomings of MATLAB is its lack of true lists--the closest you can come is by extending an array row-by-row or colum-by-column. This imposes a performance penalty, as the entire array is recopied every time. But it can sometimes be worth it for assembling small "stacks"hold all;.

```
x = [];
y = [];
for i=1:10
    x = [x; i];
    y = [y, i*2];
end
size(x)
size(y)

ans =
    10    1

ans =
    1    10
```

Multiplying two matrices the * operator rather than the . * operator performs matrix multiplication, so the number of columns of the first matrix must match the number of rows of the second.

```
A = [1 2; 3 4];

u = [5; 6];

b = A * u

b =

17

39
```

Basic plotting

It's good practice to initialize a figure with a call to figure. This command will return a handle that you can use later as in input to the same command to make the same figure active again.

To put multiple objects on the same plot, issue a hold on command after making your figure active. This prevents new plotted objects from replacing the previous ones.

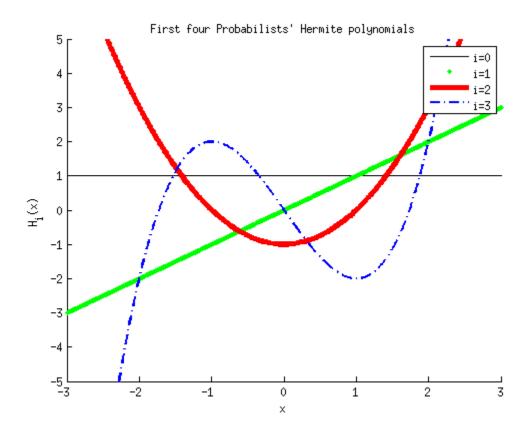
2D line plots can be made with the plot command. Like all commands in this tutorial, nice documentation for this command is available with F1. Plots can be decorated with commands like title, xlabel, ylabel, ylim, or legend. Again, the built in help browser, or just Google, can be very useful for finding the names and syntax for less commonly\used commands.

```
figureHandle = figure();
hold all;

x = -3:.01:3;
plot(x, ones(size(x)), 'k-');
plot(x, x, 'g.');
plot(x, x.^2 - 1, 'Color', 'red', 'LineWidth', 4);
```

```
plot(x, x.^3 - 3*x, 'b-.', 'LineWidth', 2);
ylim([-5, 5]);

title('First four Probabilists'' Hermite polynomials');
xlabel('x');
ylabel('H_i(x)');
legend('i=0', 'i=1', 'i=2', 'i=3');
```



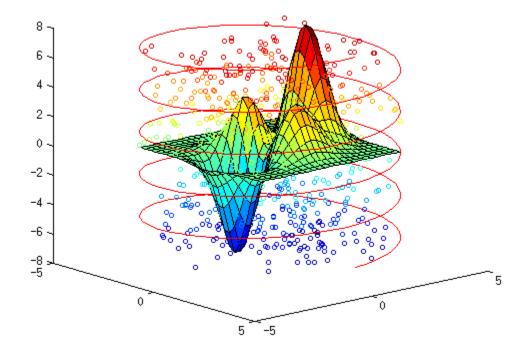
You can make scatterplots with the scatter command.

3D plots are possible with commands such as scatter3, or surf

```
figure(); hold all;
[X,Y,Z] = peaks(25);
surf(X,Y,Z);
view(49, 18); % Set the view angle.

% We can make a 3D scatterplot fairly intuitively, though formatting
% options can get Byzantine.
Zrand = rand(numel(Z), 1);
Zrand = Zrand * (max(Z(:)) - min(Z(:)));
Zrand = Zrand - mean(Zrand);
% Arguments are (x, y, z, size, (variable for color mapping)):
scatter3(X(:), Y(:), Zrand, 12, Zrand)

% You can also plot curves in 3D, FWIW.
theta = 0:.1:10*pi;
```



Functions vs scripts

This file us a MATLAB script--a series of statments, perhaps separated into cells by comment lines beginning with two % symbols. Incidentally, these cells can be evaluated one-by-one with the default Ctrl +Enter keyboard shortcut, similar to the Shift+Enter shortcut in Mathematica.

However, to do something a little more like real programming in Matlab, you'll want functions. Functions need to be defined in a separate *.m file. (Nested functions are possible, but not in scripts. It appears that classes can only be defined in their own files, not nested.)

I made a small example file to accompany this tutorial, called squareInputValue.m. It looks something like this:

```
function outputValue = squareInputValue(inputValue)
    outputValue = inputValue .^ 2;
end
```

```
squareInputValue(2)
```

```
ans =
```

4

If you have to do slightly larger-scale programming in MATLAB, you may be interested in reading about its rudimentary object-orientation (look up classdef in the help), and package management (see import, and Google) capabilities.

Functions that can operate without arguments, such as the built-in rand, can be called without parenthases, although I personally dislike this style.

```
x = rand();
y = rand;
z = x - y;
```

If your function can be performed in a single statement, like our squareInputValue example, you can write it as an anonymous function

```
f = @(x) x.^2;

f(2)

ans =
```

The syntax is

```
| IDENTIFIER = @(ARG1 [, ARG2, ARG3, etc]) (statement with the given value(
```

This is similar to Python's lambda keyword, where this function would be

```
f = lambda x: x**2
```

In some contexts, such as when integrating ODEs (see below) a function handle is desired. Unlike in Python, where both squareInputValue and f would be callable objects at this point, attempts to use squareInputValue as an object at this point would be interpreted as calls without arguments (due to the previously mentioned regrettable no-parenthases no-arguments optional syntax), and would result in the error

```
Error using squareInputValue (line 2)
Not enough input arguments.
```

You can create a function handle to pass to other functions by prepending an @ symbol. The anonymous function f is already a function handle.

```
squaringHandle = @squareInputValue;
squaringHandle(2)

ans =
```

4

Numerical integration of systems of ODEs

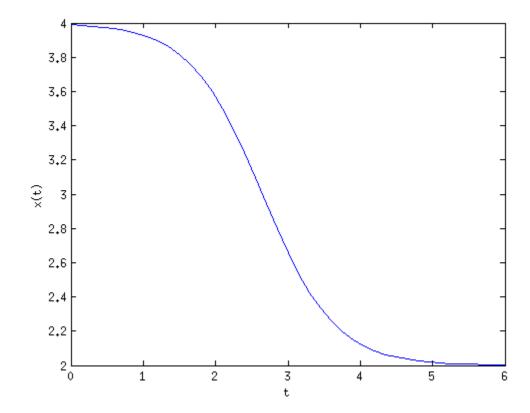
While you can write your own numerical integration routines, and schemes like forward Euler can be implemented directly in your script without much difficulty, MATLAB includes several built-in integrators to make your life easier. These are particularly useful when integrating stiff systems of ODEs, where error or stepsize control is required, and schemes such as forward Euler might fail spectacularly.

Lets define a simple 1D ODE. The built-in integrators expect your right-hand-side (RHS) function to take two arguments, the current time, and the current state. This allows you to have time-dependent effects, such as nonautomous forcing. For now, we'll just ignore the t argument.

```
dxdt = @(t, x) (4 - x) * (2 - x);
```

Integrators vary in their required arguments, but they generally require a handle to a RHS function, a time range, and an initial condition, and return a set trajectory as a sequence of points, and corresponding times (or or however you interpret the independent variable). Here, we'll use a Runge-Kutta method of order 4(5), and plot the resulting trajectory.

```
timeRange = [0, 6];
initialCondition = 3.99;
[T, X] = ode45(dxdt, timeRange, initialCondition);
figure();
plot(T, X);
xlabel('t');
ylabel('x(t)');
```



We can also use a pair of linear ODEs.

end

$$\frac{dx}{dt} = 3(1/2-x) + 1/2(-1/4-y)$$

$$\frac{dy}{dt} = 1/3(1/2-x) + 6(-1/4-y)$$

$$A = [3, 1/2; ... 1/3, 6];$$

$$XYfixed = [1/2; -1/4];$$

$$rhs = @(t, XY) A * (XYfixed - reshape(XY, 2, 1));$$

$$Let's start with a bunch of random initial conditions.$$

$$numTrajectories = 80;$$

$$times = 0:.01:10;$$

$$trajectories = zeros(numel(times), 2, numTrajectories);$$

$$for replicate=1:numTrajectories$$

$$initialCondition = rand(2, 1) * 2 - 1;$$

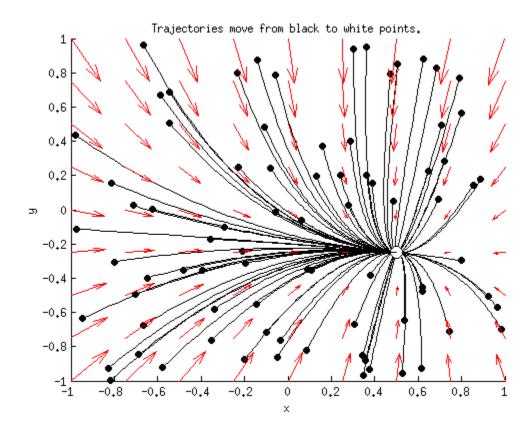
$$[times, states] = ode45(rhs, times, initialCondition);$$

$$trajectories(:, :, replicate) = states;$$

Let's plot those trajectories. However, we're going to add an extra feature--to visualize the vector field, we'll plot a quiver of arrows pointing in the direction of the vector field for a grid of points in the X-Y plane. Note that we use the function meshgrid to create a repeating grid of rows of \boldsymbol{x} values and columns of \boldsymbol{y} values, then evaluate the intersections of these rows and values to get u=dx/dt and v=dy/dt.

```
figure(); hold on;
for replicate=1:numTrajectories
    states = trajectories(:, :, replicate);
    scatter(states(1, 1), states(1, 2), 32, 'Marker', 'o', ...
            'MarkerEdgeColor', 'black', 'MarkerFaceColor', 'black');
    scatter(states(end, 1), states(end, 2), 100, 'Marker', 'o', ...
            'MarkerEdgeColor', 'black', 'MarkerFaceColor', 'white'...
    plot(states(:, 1), states(:, 2), 'k');
end
[X, Y] = meshgrid(-1:.25:1, -1:.25:1);
gridShape = size(X);
U = zeros(size(X));
V = zeros(size(X));
for i=1:gridShape(1)
    for j=1:gridShape(2)
        uv = rhs(0, [X(i,j); Y(i,j)]);
        U(i,j) = uv(1);
        V(i,j) = uv(2);
    end
quiver(X, Y, U, V, 'Color', 'red');
xlabel('x');
```

```
ylabel('y');
title('Trajectories move from black to white points.');
```



Symbolic computation

Your version of MATLAB might include support for symbolic computation. While Mathematica is a more common choice for doing symbolic computations, we'll go through a couple examples here to introduce the MATLAB equivalent.

using syntax which is strangely divergent from normal MATLAB code, we can declare an abstract function.

```
syms f(x)

f

x

f(x) = f(x)
x = x
```

If we had done this with the command

```
syms f(x)
```

instead, the function f would have been declared, but not x.

Note that our function does not yet have an associated expression. We can add that with a new syntax that looks disturbingly like the illegal action of assigning to a function evaluation.

```
f(x) = x^3*\sin(x)
f(x) = x^3*\sin(x)
```

We can differentiate this.

```
diff(f, x, 2)
ans(x) =
6*x^2*cos(x) - x^3*sin(x) + 6*x*sin(x)
```

(Note that, usually, the diff function is used for computing successive differences in a vector of values. Because MATLAB packages and namespaces are a relatively "new" feature (added in version 2008a), much of the MATLAB standard libraries simply dump their functions into the global namespace, and use complicated contextual rules to decide precedence, if they don't simply shadow each other.)

```
vec = [1 5 6];
diff(vec)

ans =
4 1
```

Using a further unintuitive abuse of notation, we can use the Symbolic Math Toolbox to integrate, for example, a first-order linear ODE.

```
syms y(t) b

y(t) = dsolve(diff(y) == -t*y, y(0) == b)

f = symfun(y(t), [b, t])

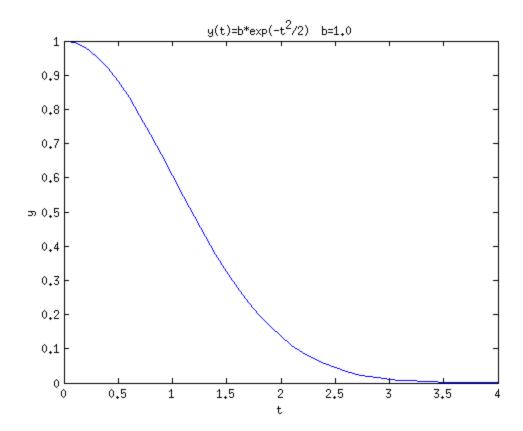
y(t) =
b*exp(-t^2/2)
```

$$f(b, t) =$$

$$b*exp(-t^2/2)$$

Plot this function.

```
figure();
tvals = 0:.1:4;
bval = 1.0;
plot(tvals, f(bval, tvals));
title(strcat('y(t)=', char(y(t)), sprintf(' b=%.1f', bval)));
xlabel('t');
ylabel('y');
```



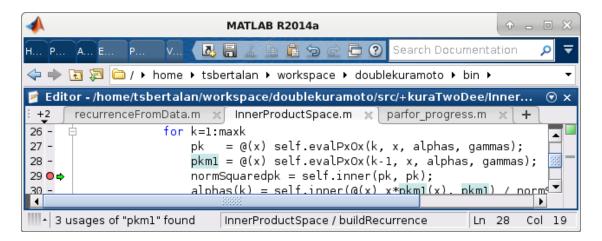
This example is taken nearly directly from the help files; for more information and tutorials, open the MATLAB desktop Help Browser, and search for "Symbolic Computation".

Debugging

It's often useful to inspect the state of a program at a particular point deep in a called function. To this end, you can set break points in the by clicking the – sign in the left margin of a line in the editor, to the right of the line numbers.

```
MATLAB R2014a
                                                    2
                             4
                                       Search Documentation
                                                                                 ۵
💠 🔷 🔁 🔁 🗀 / ト home ト tsbertalan ト workspace ト doublekuramoto ト bin ト
🌌 Editor - /home/tsbertalan/workspace/doublekuramoto/src/+kuraTwoDee/InnerProd...
      recurrenceFromData.m × InnerProductSpace.m × parfor_progress.m × +
16 -
                    for i=1:self.n;
17 -
                        pr = pr + f(self.data(i)) * g(self.data(i));
18 -
19 -
                end
20
21
                function recurrence = buildRecurrence(self, maxk)
22 -
                    alphas = zeros(maxk, 1); % maxk+1?
23
                    gammas = zeros(maxk, 1);
24
25 -
                    normSquaredpkm1 = self.inner(@(x) 1, @(x) 1);
26 -
                    for k=1:maxk
27 -
                             = @(x) self.evalPxOx(k, x, alphas, gammas);
28 -
                        pkm1 = @(x) self.evalPxOx(k-1, x, alphas, gammas);
29 0
                        normSquaredpk = self.inner(pk, pk);
                        alphas(k) = self.inner(@(x) x*pkml(x), pkml) / normSquar
30
  Line: 29. Status: enabled ammas(k) = normSquaredpk / normSquaredpkml;
31
32
                        normSquaredpkml = normSquaredpk;
33
34
35 -
                    recurrence = {alphas, gammas};
36 -
                end
37
                function pkx = evalPx0x(self, k, x, alphas, gammas)
38
39 -
                    if k<0
|||||
                                 InnerProductSpace / evalPx0x
                                                                      Ln 47
```

When you run a script which calls this code, assuming you did not call clear all, which clears both variables and breakpoints, the interpreter will stop when this line is reached, and indicate this state with both a green arrow in the margin of this code ...



... and a K before your interactive prompt in the Command Window.

At this point, you can disp out or modify variables and expressions. In newer versions of MATLAB, the "EDITOR" tab will contain buttons for continuing to the next breakpoint, stepping to the next line of code, stepping into the function about to be called, etc.



To quit debug mode, either prese the continue button (or keyboard shortcut) (and possibly also clear your breakpoints), press the "Quit Debugging" button, or enter the command dbquit in thie Command Window.

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