Dokumentation STARTHack Asimov

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1 Getting Started

1.1 Challenges

There were 8 different challenges which you could apply. We were mainly interested in the Challenges from the following partners:

- Autosense (Crash Visualization)
- SBB (Recylce)
- Laica (AR)
- BOSCH IOT-Lab (Sensor Car)

Alls case descriptions can be viewed here: http://live.starthack.ch/case-descriptions/

We applied for the Autosense challenge and got it (limit of 15 Teams per challange).
The challenge is as follow:

1.2 AUTOSENSE / VOLVO Challenge

Generate Car Crash Image, visualize impact and direction using sensor data

Your challenge if you choose to accept:

Build Microservice(s) to generate Image with 3D object simulating impact forces for given time offset (from crash). Deploy Microservice(s) on Swisscom Application Cloud (cloud foundry). Provide API(s) for submitting Input data (stream) and getting the Result. Generate output for each submitted Crash Record : Direction of the impact (Impact angle and energy), visualize the damage show expected place of impact on car

Winner is the Team who:

Has identified the maximum number of crashes correctly providing - Correct impact direction & Most accurate 3D simulation (compared to real crash picture)

How it will be measured:

For each submitted Crash Record AND time offset, generate Image with Direction of the impact (Impact angle and energy), Visualized damage and Time offset with the maximum force/damage on the object. Crash Record is submitted to the service. The calculated impact direction will be compared with pictures from real crash.

Restrictions:

Service must be deployable on cloud infrastructure (AWS/Cloud Foundry/Kubernetes/Docker). Service should use as few as possible external APIs. Given Data Models and API POST Requests structure must be used.

1.3 Setup

xxxxx

```
pwd
```

2 Tasks

- Data Parsing (transform in more structured way -> acceleration, calibration)
  - define useful functions
  - implement functions
  - crash_record.py
- Webserver
  - create webserver (sanic)
  - implement requests
  - return some dummy data for the moment
  - webserver.py (rename main.py)
  - docker container
- Image
  - define interface
  - library to draw arrows
  - library to draw circles
  - image.py
- Visualization & Math
  - jupyter notebook visualization
  - define functions to calculate angles & impact
  - start crash_record_calculator.py

3 Tasks

yes

4 Damage drawer

4.1 Funktionsumfgang

sads asd

4.2 Funktiondesign

Print-Screen Tablet Skizze

Skizze Damage drawer

4.3 Umsetzung

Klassendiagramm und Beschreibung der einzelnen Methoden

Klasse DamageImage

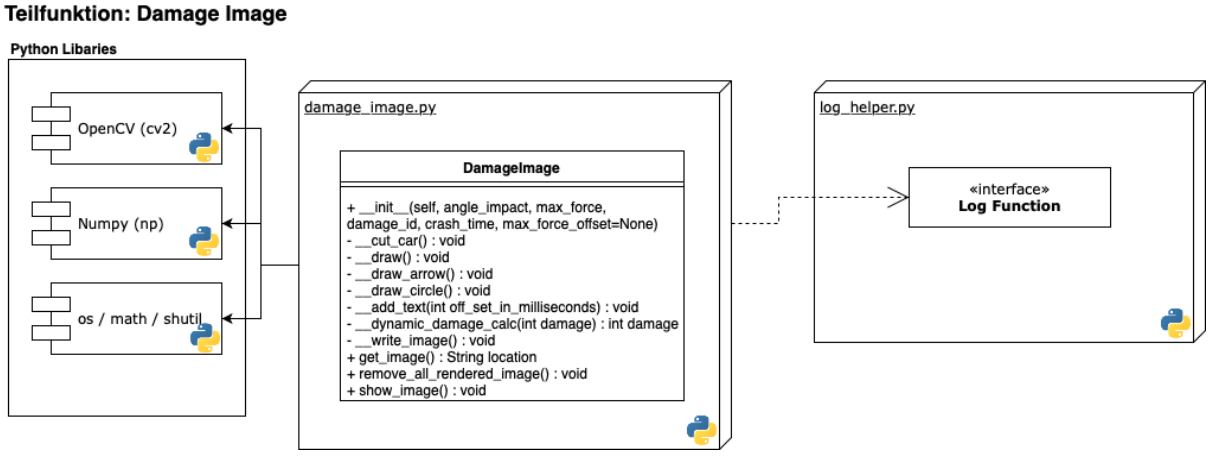

Abbildung 4.1: Klassendiagramm Damage drawer

4.3.1 Init

```
def __init__(self, angle_impact, max_force, damage_id, crash_time, max_force_offset=None):
```

4.3.2 Kulturen Auto

```
def __cut_car(self):
```

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4.3.3 Zeichnen

```
def __draw(self):
```

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4.3.4 Zeichnen - Pfeil

```
def __draw_arrow(self):
```

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4.3.5 Zeichnen - Kreis

```
    def __draw_circle(self):
```

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4.3.6 Text auf das Bild

```
def __add_text(self, off_set_in_milliseconds):
```

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4.3.7 Berechnung Beschädigung

```
def __dynamic_damage_calc(self, damage):
```

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4.3.8 Schreiben der Bilddatei

```
def __write_image(self):
```

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4.3.9 Pfad der geschriebene Datei

```
def get_image(self):
```

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4.3.10 Löschen von allen gerendert Dateien

```
def remove_all_rendered_image(self):
```

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4.3.11 Anzeige der Datei auf dem Bildschirm

```
def show_image(self):
```

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4.4 Implementierung im Projekt

Aufruf bei /api/v1/getCrashImage wie auch bei /api/v1/play

4.5 Mögliche Darstellung der Datei in einem Protal

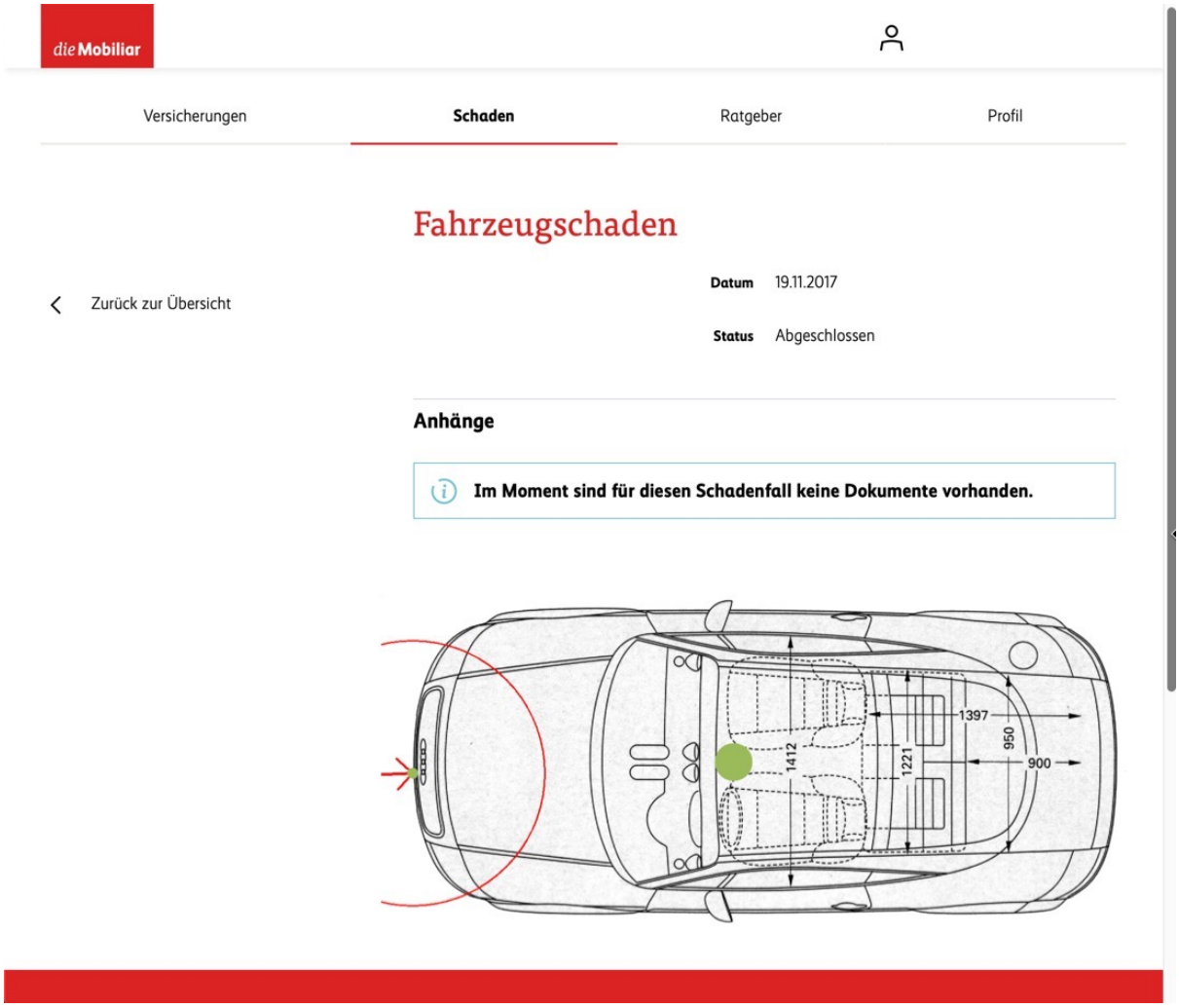

Abbildung 4.2: Anzeige in einem Portal

5 Tasks

yes