# STATS305B – Lecture 7

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## 1 Binary GLMs

## 1.1 Fitting

Let F be a CDF with density f. The deviance for a binary GLM with link function  $g = F^{-1}$  is,

$$\mathrm{DEV}(\beta|Y) = 2\sum_{i=1}^{n} -Y_i \frac{F(X_i^T \beta)}{F(X_i^T \beta)(1 - F(X_i^T \beta))} - \log\left(1 - F(X_i^T \beta)\right).$$

Thus,

$$\nabla \operatorname{DEV}(\beta|Y) = 2 \sum_{i=1}^n X_i \frac{f(X_i^T \beta)^2}{F(X_i^T \beta)(1 - F(X_i^T \beta))} \left[ \frac{Y_i - F(X_i^T \beta)}{f(X_i^T \beta)} \right].$$

Since  $X_i^T \beta = F^{-1}(\mathbb{E}_{\beta}[Y_i])$ , we have that  $\mathbb{E}_{\beta}[F(X_i^T \beta) - Y_i] = 0$ . Thus, we have

$$\mathbb{E}[\nabla^2 \operatorname{DEV}(\beta|Y)] = 2\sum_{i=1}^n X_i X_i^T \frac{f(X_i^T \beta)^2}{F(X_i^T \beta)(F(X_i^T \beta) - 1)} = 2X^T W_{\beta} X,$$

where  $W_{\beta} = \operatorname{diag}\left(\frac{f(X_i)^2}{F(X_i^T\beta)(1-F(X_i^T\beta))}\right)$ . We can also rewrite  $\nabla \operatorname{DEV}(\beta|Y)$  in terms of the  $W_{\beta}$ ,

$$\nabla \operatorname{DEV}(\beta|Y) = 2X^T W_{\beta} \left( \frac{Y - F(X\beta)}{f(X\beta)} \right).$$

To fit a binary glm, we can use Fisher scoring. Fisher scoring is an iterative quasi-Newton method given by

$$\begin{split} \widehat{\beta}^{(k+1)} &= \widehat{\beta}^{(k)} - \mathbb{E}_{\beta^{(k)}} [\nabla^2 \operatorname{DEV}(\beta^{(k)}|Y)]^{-1} \nabla \operatorname{DEV}(\widehat{\beta}^{(k)}|Y) \\ &= (X^T W_{\widehat{\beta}^{(k)}} X)^{-1} X^T W_{\widehat{\beta}^{(k)}} \left( X \widehat{\beta}^{(k)} + \frac{Y - F(X \widehat{\beta}^{(k)})}{f(X \widehat{\beta}^{(k)})} \right). \end{split}$$

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Note that the above method is a form of iterative re-weighted least squares. This was important for historical reasons since least squares was one of the main algorithms implemented on early computers. When we view Fisher scoring as iterative re-weighted least squares, the response at step k + 1 is,

$$Z^{(k+1)} = X\widehat{\beta}^{(k)} + \frac{Y - F(X\widehat{\beta}^{(k)})}{f(X\widehat{\beta}^{(k)})} = g(\mathbb{E}_{\beta^{(k)}}(Y)) + g'(\mathbb{E}_{\widehat{\beta}^{(k)}}(Y))(Y - \mathbb{E}_{\widehat{\beta}^{(k)}}[Y]).$$

This is because if  $\mu = F(X^T\beta)$ , then  $g(\mu) = F^{-1}(\mu) = X^T\beta$  and  $g'(\mu) = \frac{1}{F'(F^{-1}(\mu))} = \frac{1}{f(X\beta)}$ . The weight matrix at time k+1 is,

$$\begin{split} W^{(k+1)} &= \operatorname{diag} \left( \frac{f(X_i^T \widehat{\beta}^{(k)})^2}{F(X_i^T \widehat{\beta}^{(k)})(1 - F(X_i^T \widehat{\beta}^{(k)}))} \right) \\ &= \operatorname{diag} \left( \frac{F(X_i^T \widehat{\beta}^{(k)})(1 - F(X_i^T \widehat{\beta}^{(k)}))}{f(X_i^T \widehat{\beta}^{(k)})^2} \right)^{-1} \\ &= \frac{1}{f(X \widehat{\beta}^{(k)})^2} \operatorname{Var}_{\widehat{\beta}^{(k)}}(Y)^{-1} \\ &= g'(\widehat{\mu}^{(k)})^2 V(\widehat{\mu}^{(k)})^{-1}, \end{split}$$

where  $\widehat{\mu}^{(k)} = \mathbb{E}_{\widehat{\beta}}[Y]$ . This shows how Fisher scoring can be generalized to other glms. Instead of minimizing the deviance, we simply run iterative re-weighted least squares with features X, iterative response

$$Z^{(k)} = g(\widehat{\mu}^{(k)}) + g'(\widehat{\mu}^{(k)})(Y - \widehat{\mu}^{(k)})$$

and iterative weights  $W^{(k)} = g'(\widehat{\mu}^{(k)})^2 V(\widehat{\mu}^{(k)})^{-1}$ . This is important because in general for glms we do not have a full model from which we can calculate and optimize a likelihood. We just have the functions g and V. Note that, in the binary case, if the model is true, then

$$\widehat{\beta} \approx \mathsf{N}(\beta^*, (X^T W_{\widehat{\beta}} X)^{-1}).$$

If the model is not true, then we have the sandwich form

$$\widehat{\beta} - \beta^* \approx \mathsf{N}(0, Q_{\beta^*}^{-1} \Sigma_{\beta^*} Q_{\beta^*}^{-1}),$$

where  $Q_{\beta^*} = \mathbb{E}_{\beta^*}[X^T W_{\beta^*} X]$  and  $\Sigma_{\beta^*} = \text{Var}(X^T (Y - \pi_{\beta^*}(X)))$ . In practice, we can estimate  $Q_{\beta^*}$  with  $X^T W_{\widehat{\beta}} X$  and bootstrap for  $\Sigma_{\beta^*}$  or we can bootstrap directly for  $\text{Var}(\widehat{\beta})$ .

#### 1.2 Inference

The difference of deviance can be used as a likelihood ratio test. If  $M_R \subseteq M_F$  are two models, then if  $M_R$  contains the true model

$$\mathrm{DEV}(M_R) - \mathrm{DEV}(M_F) \overset{n \to \infty}{\sim} \chi^2_{df_R - df_F}.$$

Unlike in linear regression, this test is different to the Wald test for a single predictor (i.e. when  $M_F$  is  $M_R$  plus one additional predictor).

#### 2 Poisson data

Suppose  $Y \sim \mathsf{Poisson}(\lambda)$ , then for  $y = 0, 1, 2, \ldots$ , we have

$$\mathbb{P}_{\lambda}(Y=y) = \frac{\lambda^{y}}{y!} \exp(-\lambda) = \exp(y \log(\lambda) - \lambda) \frac{1}{y!}.$$

The canonical link for this family is  $g = \log$ , giving the model  $\log(\lambda_i) = X_i^T \beta$  where  $\lambda_i = \mathbb{E}[Y_i | X_i]$ . This model is called the *log-linear model*. The variance function for this model is  $\operatorname{Var}(Y_i | X_i) = \lambda_i$ . The deviance is

$$DEV(\beta|Y) = 2\sum_{i=1}^{n} -Y_{i}X_{i}^{T}\beta + e^{X_{i}^{T}\beta} + Y_{i}\log(Y_{i}) - Y_{i},$$

the terms  $Y_i \log(Y_i) - Y_i$  come from the saturated model where we have  $\lambda_i = Y_i$ . The gradient and Hessian of the deviance are thus,

$$\nabla \operatorname{DEV}(\beta|Y) = 2X^{T}(\exp(X\beta) - Y) = 2X^{T}(\mathbb{E}_{\beta}[Y] - Y),$$

and

$$\nabla^2 \operatorname{DEV}(\beta | Y) = 2X^T W_{\beta} X,$$

where  $W_{\beta} = \operatorname{Var}_{\beta}(Y) = \exp(X\beta)$ . Thus, we can fit this model by using Newton-Raphson. This gives us the iterative rule,

$$\widehat{\beta}^{(k+1)} = \widehat{\beta}^{(k)} - \nabla^2 \operatorname{DEV}(\widehat{\beta}^{(k)}|Y)^{-1} \left( \nabla \operatorname{DEV}(\widehat{\beta^{(k)}}|Y) \right)$$

$$= \widehat{\beta}^{(k)} - \left( X^T W_{\beta} X \right)^{-1} X^T (\mathbb{E}_{\widehat{\beta}^{(k)}}[Y] - Y)$$

$$= \widehat{\beta}^{(k)} + \left( X^T \exp(X\beta) X \right)^{-1} X^T (Y - \exp(X\beta)).$$

This iterative algorithm once again corresponds to a form of iterative re-weighted least squares, with response,

$$Z^{(k+1)} = X\widehat{\beta}^{(k)} + (Y - \exp(X\widehat{\beta}^{(k)})) / \exp(X\widehat{\beta}^{(k)})$$
$$= g(\widehat{\lambda}^{(k)}) + g'(\widehat{\lambda}^{(k)})(Y - \widehat{\lambda}^{(k)})$$

where  $\widehat{\lambda}^k = \exp(X\widehat{\beta}^{(k)}) = \mathbb{E}_{\widehat{\beta}^{(k)}}[Y]$ . and weight matrix,

$$W^{(k+1)} = \exp(X\widehat{\beta}^{(k)})$$
  
=  $\operatorname{Var}_{\widehat{\beta}^{(k)}}(Y)$ .

#### 2.1 Residuals

Like the binary models, there are two types of residuals for the log-linear model. We have the Pearson residuals,

$$e_i = \frac{Y_i - \widehat{\lambda}_i}{\sqrt{\widehat{\lambda}_i}} = \frac{Y_i - \mathbb{E}_{\widehat{\lambda}_i}[Y]}{\sqrt{\operatorname{Var}_{\widehat{\lambda}_i}(Y)}}.$$

We also have the deviance residuals. Note that

$$\mathrm{DEV}(\widehat{\lambda}|Y) = \sum_{i=1}^{n} \mathrm{DEV}(\widehat{\lambda}_{i}|Y_{i}).$$

Thus, we can define the deviance residuals as

$$d_i = \operatorname{sign}(Y_i - \widehat{\lambda}_i) \sqrt{\operatorname{DEV}(\widehat{\lambda}_i | Y_i)},$$

recall that  $\text{DEV}(\widehat{\lambda}_i|Y_i) = 2\left(\widehat{\lambda}_i - Y_i\log(\widehat{\lambda}_i) - Y_i + Y_i\log(Y_i)\right)$ . We also have a hat matrix for the log-linear model. It is given by

$$H_{\widehat{\beta}} = W_{\widehat{\beta}}^{1/2} X (X^T W_{\widehat{\beta}} X)^{-1} X^T W_{\widehat{\beta}}^{1/2},$$

where  $W_{\widehat{\beta}} = \exp(X\widehat{\beta})$ .

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#### 2.2 "Unnatural" models for Poisson data

We can get other models for Poisson data by changing the link function g. The link function satisfies  $g(\lambda_i) = X_i^T \beta$  and hence  $\lambda_i = g^{-1}(X_i^T \beta)$ . The natural choice if  $g = \log$  but two other choices are identity:  $g(\lambda) = \lambda$  and inverse:  $g(\lambda) = 1/\lambda$ . These can be used in glm() in R by specifying the link function. For a link function g, the deviance is

$$DEV(\beta|Y) = 2\sum_{i=1}^{n} \left[ g^{-1}(X_i^T \beta) - Y_i \log \left( g^{-1}(X_i^T \beta) \right) - Y_i + Y_i \log(Y_i) \right].$$

We can fit a Poisson glm with Fisher scoring which we can present as an IRLS algorithm with

$$Z^{(k+1)} = X\widehat{\beta}^{(k)} + g'(\widehat{\lambda}^{(k)})(Y - \widehat{\lambda}^{(k)}),$$

and

$$W^{(k+1)} = g'(\widehat{\lambda}^{(k)})^2 V(\widehat{\lambda}^{(k)})^{-1},$$

where  $\widehat{\lambda}^{(k)} = g^{-1}(X\widehat{\beta}^{(k)})$  and  $V(\lambda) = \lambda$ . Note that

$$\nabla \operatorname{DEV}(\beta|Y) = 2X^T \left( \frac{\mathbb{E}_{\beta}[Y] - Y}{g'(\mathbb{E}_{\beta}[Y])\mathbb{E}_{\beta}[Y]} \right),$$

and

$$\mathbb{E}_{\beta}[\nabla^2 \operatorname{DEV}(\beta|Y)] = 2X^T \left(\frac{1}{g'(\mathbb{E}_{\beta}[Y])^2 \mathbb{E}_{\beta}[Y]}\right) 2X^T W_{\beta} X,$$

where  $W_{\beta} = \operatorname{diag}\left(\frac{1}{g'(\lambda_i)^2 \operatorname{Var}_{\lambda_i}(Y)}\right) = \operatorname{diag}\left(\frac{1}{g'(\lambda_i)^2 \lambda_i}\right)$ , where  $\lambda_i = g^{-1}(X_i^T \beta)$ . We again have a sandwich estimator for the variance of  $\widehat{\beta}^{(k)}$ ,

$$\widehat{\beta} - \beta^* \approx \mathsf{N}(0, Q^{-1}\Sigma Q^{-1}),$$

where  $Q = X^T W_{\beta^*} X$  and  $\Sigma = \text{Var}(X^T W^{(\infty)} Z^{(\infty)})$ . When the model is correct,  $X^T W_{\beta^*} X \approx \Sigma$ .

# 3 Over-dispersion

The Poisson model requires that  $\mathbb{E}[Y_i] = \operatorname{Var}(Y_i)$  but this may be far from true. In simple clustering models we in fact have  $\operatorname{Var}(Y_i) = \phi \mathbb{E}[Y_i]$  where  $\phi$  has to be estimated from the data. In a Poisson glm we can estimate  $\phi$  with

$$\widehat{\phi} = \frac{1}{n-p} \sum_{i} e_i^2,$$

where p is the number of parameters and  $e_i$  are the Pearson residuals. Another way to incorporate over-dispersion is to work with a negative binomial distribution. Consider the following non-standard parametrization of the negative binomial distribution,  $Y \sim \mathsf{Negativebinomial}(\mu, k)$ 

$$\mathbb{P}(Y=y) = \frac{\Gamma(y+k)}{\Gamma(k)\Gamma(y+1)} \left(\frac{k}{\mu+k}\right)^k \left(1 - \frac{k}{\mu+k}\right)^y.$$

For a fixed k, this is a one-dimensional exponential family with  $\mathbb{E}[Y] = \mu$  and  $\text{Var}(Y) = \mu + \frac{\mu^2}{k}$ . Thus, by varying k, we get different amounts of over-dispersion in our model. The parameter k can be estimated from the data.