q4

Suppose $\tau_n \uparrow \infty$ and for all $\epsilon > 0$, there exists B > 0, such that

$$\inf_{n} Pr(|\tau_n(\hat{\theta} - \theta)| \le B) \ge 1 - \epsilon$$

Equivalently, we have $\inf_{n} Pr(|\hat{\theta} - \theta| \leq \frac{B}{|\tau_n|}) \geq 1 - \epsilon$.

Now, we can choose some $N \in \mathbb{N}$ such that, for all n > N, $\frac{B}{\tau_n} < \delta$ as B is a constant and $\tau_n \uparrow \infty$. Then, we have that, for all n > N,

$$1 - \epsilon \le \inf_{n} (Pr(|\hat{\theta} - \theta)| \le \frac{M}{|\tau_{n}|})$$

$$\le \inf_{n > N} (Pr(|\hat{\theta} - \theta)| \le \frac{M}{|\tau_{n}|})$$

$$\le \inf_{n > N} (Pr(|\hat{\theta} - \theta)| \le \delta)$$

This equivalently states that tightness of $\tau_n(\hat{\theta} - \theta)$ implies that $Pr(|\hat{\theta} - \theta)| \leq \delta) \to 1$

98

0.1 a

Noting that f(y|x) = 0 if $f_X = 0$, we know the integral over $\mathbb{R}^k \times \mathbb{R}$ simplifies to the integral over the area where $f_X(x) > 0$ (as it is 0 everywhere else).

$$E[m^{*2}(X)] = \int (\int y f(y|x) dy)^2 f_X(x) dx$$

$$\leq \int (\int |y| \frac{f(y,x)}{f_X(x)} dy)^2 f_X(x) dx$$

Knowing that $\int \frac{f(y,x)}{f_X(x)} dy = 1$, we know (i.e by Cauchy -Schwartz):

$$\int y \frac{f(y,x)}{f_X(x)} dy \le (\int y^2)^{.5} (\int \frac{f(y,x)}{f_X(x)} dy)^{.5}$$

Thus, we can write out

$$E[m^{*2}(X)] \le \int \left(\int y^2 \frac{f(y,x)}{f_X(x)} dy\right) f_X(x) dx$$

$$= \int \int \left(y^2 \frac{f(y,x)}{f_X(x)} f_X(x)\right) dy dx$$

$$\le \int \int y^2 f(x,y) dy dx \le E(Y^2) < \infty$$

as, again, f_X is zero everywhere else.

0.2 b

Recall, from class that

$$E[(y - m(x))^{2}] = E[(y - m(x) + m^{*}(x) - m^{*}(x))^{2}]$$

$$= E[(y - m^{*}(x))^{2}] + 2E[(y - m^{*}(x))(m^{*}(x) - m(x))] + E[(m^{*}(x) - m(x))^{2}]$$

$$\geq E[(Y - m^{*}(X))^{2}]$$

Thus, we found that $\min E[(Y - m^*(X))] \Leftrightarrow E[(Y - m^*(X))m(X)] = 0$ for all m(X). Now, see that

$$E[(y - m^{*}(x))m(x)] = \int \int (y - m^{*}(x))m(x)f(y,x)dydx$$

$$= \int (\int (y - m^{*}(x))m(x)f(y,x)dy)dx$$

$$= \int m(x)f_{X}(x)(\int yf(y|x) - m^{*}(x)f(y|x)dy)dx$$

$$= \int m(x)m^{*}(x)f_{X}(x)dx - \int m(x)m^{*}(x)(\int f(y|x)dy)f_{X}(x)dx$$

As $\int f(y|x)dy$ just integrates to 1, these two terms on the left and right are equal (namely $E[(y-m^*(x))m(x)]=0$

q12

0.3 a

Take

$$Y = \beta_0 + \beta_1 X + U$$

Now, consider

$$\beta_1 = \frac{Cov(X, Y)}{\sigma_X^2} \tag{1}$$

$$=\rho_{X,Y}\frac{\sigma_Y}{\sigma_X} \tag{2}$$

Thus, the $|\beta_1| < 1$ does not necessarily mean $\frac{Var(X)}{Var(Y)} < 1$ as we need $\frac{\beta_1}{\rho_{X,Y}} < 1$. Note, you can also see that $|\beta| < 1$ doesn't imply the claim from just writing out

$$\frac{var(Y)}{var(X)} = \frac{\beta_1^2 var(X) + var(U)}{var(X)}$$

0.4 b

As $\sigma_X = \sigma_Y$, the above equation (2) implies that we have $\beta_1 = \rho_{X,Y}$, so $\beta_1 = 1$ iff $\rho_{X,Y} = 1$. Also, as $\sigma_Y^2 = \beta_1^2 \sigma_X^2 + \sigma_U^2$, we require that, if Cov(X, U) = 0, $\sigma_U^2 = 0$

0.5 c

Again, as we have

$$\beta_1 = \rho_{X,Y} \frac{\sigma_Y}{\sigma_X}$$
$$= \rho_{X,Y} \frac{\sigma_X}{\sigma_Y}$$
$$= \alpha_1$$

as the distributions (and variances) are equal. The equality of α_1 and β_1 requires, either $\rho_{X,Y} = 0$ or $\sigma_X = \sigma_Y$

q16

Intuitively, we have that since E(V) = 0 and $V \in \{0, 1\}$, we cannot have the measurement error to "cancel out" in the case of classical measurement error as if X = 1, the measurement error must be negative and if X = 0, the measurement error must be positive, so it must be negatively correlated with X.

Note that if E(V) = 0,

$$Cov(X, V) = E((X - E(X))(V - E(V)))$$
$$= E(XV) - E(X)E(V)$$
$$= E(XV)$$

Now, looking at variance of \hat{X} , we see that if Cov(X, V) = E(XV) = 0, $Var(\hat{X}) = Var(X)$

$$\begin{split} Var(\hat{X}) = & E(X^2) + E(V^2) + E(XV) - E(\hat{X})^2 \\ = & E(X^2) - E(X)^2 + E(V^2) \\ = & Var(X) + Var(V) \end{split}$$

Here, as $E(X^2) = E(X)$,

$$var(\hat{X}) = E(\hat{X})(1 - E(\hat{X})) = var(X)$$

so Var(V) = 0 so V = 0 and \hat{X} is just X.