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1. Which of the following are true about hyperparameter search?

1 / 1 point

- ☐ When using random values for the hyperparameters they must be always uniformly distributed.
- ☐ When sampling from a grid, the number of values for each hyperparameter is larger than when using random values.
- ☒ Choosing random values for the hyperparameters is convenient since we might not know in advance which hyperparameters are more important for the problem at hand.
- ☐ Choosing values in a grid for the hyperparameters is better when the number of hyperparameters to tune is high since it provides a more ordered way to search.

[↗ Expand](#)

✓ **Correct**

Correct. Different problems might be more sensitive to different hyperparameters.

2. Every hyperparameter, if set poorly, can have a huge negative impact on training, and so all hyperparameters are about equally important to tune well. True or False?

1 / 1 point

- ☐ True
- ☒ False

[↗ Expand](#)

✓ **Correct**

Yes. We've seen in the lecture that some hyperparameters, such as the learning rate, are more critical than others.

3. Even if enough computational power is available for hyperparameter tuning, it is always better to babysit one model ("Panda" strategy), since this will result in a more custom model. True/False?

1 / 1 point

- ☐ True
- ☒ False

[↗ Expand](#)

✓ **Correct**

Correct. Although it is possible to create good models using the "Panda" strategy, obtaining better results is more likely using a "caviar" strategy due to the number of tests and the nature of the deep learning process of ideas, code, and experiment.

4. Knowing that the hyperparameter α should be in the range of 0.001 and 1.0. Which of the following is the recommended way to sample a value for α ?

0 / 1 point

- ☐ $r = 4 * np.random.rand()$
 $\alpha = 10 ** r$
- ☒ $r = np.random.rand()$
 $\alpha = 0.001 + r * 0.999$
- ☐ $r = -3 * np.random.rand()$
 $\alpha = 10 ** r$
- ☐ $r = -5 * np.random.rand()$
 $\alpha = 10 ** r$

[Expand](#)

 **Incorrect**

No. This will pick a random value from a uniform scale, which is not the recommended way to choose α .

5. Finding new values for the hyperparameters, once we have found good ones for a model, should only be done if new hardware or computational power is acquired. True/False?

1 / 1 point

- ☐ True
- ☒ False

[Expand](#)

 **Correct**

Correct. As the data changes for the model, it might be beneficial to tune some of the hyperparameters again.

6. When using batch normalization it is OK to drop the parameter $W^{[l]}$ from the forward propagation since it will be subtracted out when we compute $\tilde{z}^{[l]} = \gamma z_{\text{normalize}}^{[l]} + \beta^{[l]}$. True/False?

1 / 1 point

- ☒ False
- ☐ True

[Expand](#)

 **Correct**

Correct. The parameter $W^{[l]}$ doesn't get subtracted during the batch normalization process, although it gets re-scaled.

7. When using normalization:

0 / 1 point

$$z_{\text{norm}}^{(i)} = \frac{z^{(i)} - \mu}{\sqrt{\sigma^2 + \epsilon}}$$

In case σ is too small, the normalization of $z^{(i)}$ may fail since division by 0 may be produced due to rounding errors. True/False?

- ☒ True
- ☐ False

[Expand](#)



Incorrect

Incorrect. The normalization formula uses a smoothing parameter ϵ so in $z_{\text{norm}}^{(i)} = \frac{z^{(i)} - \mu}{\sqrt{\sigma^2 + \epsilon}}$ use of the ϵ parameter prevents that the denominator be 0.

8. Which of the following statements about γ and β in Batch Norm are true?

1 / 1 point

- ☒ They set the variance and mean of the linear variable $\tilde{z}^{[l]}$ of a given layer.

✓ Correct

- ☐ There is one global value of γ and one global value of β for each layer, and these apply to all the hidden units in that layer.
- ☐ β and γ are hyperparameters of the algorithm, which we tune via random sampling.
- ☐ The optimal values are $\gamma = \sqrt{\sigma^2 + \epsilon}$, and $\beta = \mu$.
- ☒ They can be learned using Adam, Gradient descent with momentum, or RMSprop, not just with gradient descent.

✓ Correct

Loading [MathJax]/jax/output/CommonHTML/fonts/TeX/Fraktur-Regular.js momentum, or RMSprop, not just with gradient descent.

↗ Expand

✓ Correct

Great, you got all the right answers.

9. A neural network is trained with Batch Norm. At test time, to evaluate the neural network on a new example you should perform the normalization using μ and σ^2 estimated using an exponentially weighted average across mini-batches seen during training. True/false?

1 / 1 point

- ☐ False
- ☒ True

↗ Expand

✓ Correct

Correct. This is a good practice to estimate the μ and σ^2 to use since at test time we might not be predicting over a batch of the same size, or it might even be a single example, thus using the μ and σ^2 of a single sample doesn't make sense.

10. Which of the following are some recommended criteria to choose a deep learning framework?

1 / 1 point

- ☐ It must run exclusively on cloud services, to ensure its robustness.
- ☐ It must be implemented in C to be faster.
- ☒ Running speed.
- ☐ It must use Python as the primary language.

↗ Expand

✓ Correct

Correct. The running speed is a major factor, especially when working with large datasets.