

# Tomer Sedan

3313 Kipling Street  
Palo Alto, CA 94306

**Email:** [tk5686@psu.edu](mailto:tk5686@psu.edu)

**Phone:** (650) 733 3326

**Website:** [tsedan.github.io](https://tsedan.github.io)

## EDUCATION

### The Pennsylvania State University

**August 2021 - December 2024**

*Bachelor of Science in Computer Science, Minors in Statistics and Computer Engineering*

**4.00 GPA**

*Schreyer Honors College scholar, completing honors thesis in graph compiler optimization*

*Relevant courses: Operating Systems, Algorithms, Microprocessors, Computer Architecture, Computer Security*

### Stanford University

**June 2022 - August 2022**

*CS 161, Design and Analysis of Algorithms, as part of accredited on-campus visit program*

## TECHNICAL SKILLS

**Languages** C++, C, Python, Bash, ARM & x86 ASM, Perl, Verilog, Javascript, SQL, Java

**Software & Tools** ROS 2, LLVM, OpenCV, ONNX Runtime, SDL2, Git, AWS Lambda & EC2, Linux, Cython, Snowflake

**Knowledge Areas** Autonomous vehicles, operating systems, embedded microcontrollers, memory allocators, multithreaded systems, optimizing compilers, computer vision and graphics

## WORK EXPERIENCE

### Undergraduate Research Assistant, Stanford

**May 2024 - Present**

- Combining traditional video compression techniques (H.264) with modern ML-based image compression models using IDR-frame replacement, to obtain lower bitrates at high performance and visual fidelity.
- Working in Professor Tsachy Weissman's lab at Stanford; paper in progress.

### Project Management Lead, PSU Advanced Vehicle Team

**January 2024 - Present**

- Leading the competition planning and execution efforts to build an L4 self-driving vehicle for SAE's AutoDrive Challenge II. Coordinating and managing work for over 50 students across 6 departments.
- Secured 2nd place autonomous route finish by building an object avoidance system using fused LiDAR.

### Sensor Fusion Engineer, PSU Advanced Vehicle Team

**August 2023 - January 2024**

- Coordinated the efforts of the Advanced Vehicle Team's Perception department, covering object detection and reaction software using ROS.
- Stitched three camera and two LiDAR sensor feeds to obtain depth and velocity data for objects with a 150 degree field of view, up 67% from the original 90 degrees.

### Data Science Intern, Wurl

**May 2022 - August 2022**

- Developed a reporting framework, giving 100+ content partners data-driven insight into their advertising performance with Wurl across streamers, channels, and providers.

## RELEVANT PROJECTS

### Optimizing LLVM Backed Compiler

**January 2023 - August 2023**

- Built a bespoke compiled systems programming language in C++ using LLVM.
- Architected language features such as type coercion, intrinsics, and a just-in-time compilation mode.

### Education-focused Cython Game Engine

**October 2021 - February 2023**

- Led creation of an Entity-Component (ECS) game development library aimed towards young students.
- Designed rigid-body physics and a hardware accelerated 2D graphics model in C and Python using SDL.

## AWARDS

**Evan Pugh Scholar Award, The Pennsylvania State University**

**February 2024**