

## Design Document for IOMUX Driver



## 1 Outline

This document describes the IOMUX driver in Linux kernel of MVF TOWER BOARD (XTWR-VF600) with VF6XX SoC.

## 2 Existing code to be changed

### 2.1 Source

i.MX 6Solo SABRE-A BSP

arch/arm/plat-mxc/include/mach/iomux-mx6q.h

arch/arm/plat-mxc/include/mach/iomux-v3.h

arch/arm/plat-mxc//iomux-v3.c

arch/arm/mach-mx6/board-mx6q\_arm2.c

arch/arm/mach-mx6/board-mx6q\_arm2.h

### 2.2 Modification

- arch/arm/plat-mxc/include/mach/iomux-vfxx.h
1. Source: arch/arm/plat-mxc/include/mach/iomux-mx6q.h
  2. By using IOMUX\_PAD macro, define data combination for MUX\_MODE of each I/O pin. Name of definition will be \_VF6XX\_PAD\_PAD\_XXX and include the data below.
    - IOMUXC\_SW\_MUX\_CTL\_PAD\_XXX Register address/offset value
    - IOMUXC\_SW\_MUX\_CTL\_PAD\_XXX[MUX\_MODE] Bit field value
    - IOMUXC\_XXX\_SELECT\_INPUT Register address/offset value
    - IOMUXC\_XXX\_SELECT\_INPUT[DAISY] Bit field value
  3. Define PAD value for MUX\_MODE of each I/O pin. Combine with the definition mentioned above #1, name it as VF6XX\_PAD\_PAD\_XXX and create resource definition value for external call.

- arch/arm/plat-mxc/include/mach/iomux-vmvf.h
  1. Source: arch/arm/plat-mxc/include/mach/iomux-v3.h
  2. Modify IOMUX\_PAD definition and resource definition for IOMUXC register setting defined in the iomux-v3.h to fit for MVF SoC family.
  3. Change "v3" in the function name to "vmvf".
- arch/arm/plat-mxc/iomux-vmvf.c
  1. Source: arch/arm/plat-mxc/iomux-v3.c
  2. Modify to write definition value that is created with iomux-vfxx.h to IOMUXC register.
  3. Change "v3" in the function name declared in iomux-v3.c to "vmvf".
- arch/arm/mach-mx6/board-twr\_vf600.h
  1. Source: arch/arm/mach-mx6/board-mx6q\_arm2.h
  2. Based on the definition value of iomux-vfxx.h, create PAD setting array for primary/secondary of twr-vf600.  
Functions to be enabled are as follows.  
Primary:  
SDHC, FTM, SAI, SCI, I2C, DSPI, RMII, NFC, QSPI, DCU, ADC and such  
Secondary:  
ENET, SCI, FTM, CAN and such
  3. Switchover of primary/secondary is done by kernel configuration.
- arm/arm/mach-mx6/board-twr\_vf600.c
  1. Source: arch/arm/mach-mx6/board-mx6q\_arm2.c
  2. Implement IOMUXC register initialization processing  
IOMUXC register initialization is carried out by passing setting array made by board-twr\_vf600.h to register setting value implemented for iomux-vmvf.c.

3 API of new functions

None

4 Expected register settings

See attached excel for mode setting of primary/secondary and PAD register setting.

\*TBD for PAD resister setting.

5 Expected functionality and usage

Call at the time of board initialization processing and initialize IOMUXC register.

6 Any other pertinent information

None