

## Hardware Solutions to Critical Sections

- Recap: Critical Sections and Locks
- Disabling Interrupts
- Atomic Instructions (TAS, XCHG, FAA, CAS)
- Performance Analysis of TAS based locks
- Improving the basic algorithms

## Recall: Critical Sections & Locks

- Execution of **critical section** by threads must be **mutually exclusive**.
- Need protocol to **enforce mutual exclusion**.
- Easy to do with **locks**.

```
class Lock {  
    public void lock() {???}  
    public void unlock() {???}  
};
```

```
Lock lck;  
while (TRUE) {  
    lck.lock();  
    critical section;  
    lck.unlock();  
    remainder section;  
}
```

## Simple Hardware Support: Disable Interrupts

By disallowing interrupts the **current thread cannot be interrupted**.

This “turns the entire executable into **one critical section**”.

### Cons:

- interrupt **service latency**
- **contention** for the one critical section
- what about **multiprocessors**?

### Pros:

- simplicity!

## Hardware Support: Atomic Operations

**Atomic operations:** Operations that **check and modify** memory areas **in a single step** (i.e. operation can not be interrupted)

- Test-And-Set
- Fetch-And-Add
- Exchange, Compare-And-Swap
- Load-Link/Store Conditional

In a **multiprocessor**, atomicity is achieved by **locking the bus** for the length of the operation.

In this way, the memory locations cannot be accessed by other threads on the current or on other processor.

## Hardware Support: Test-and-Set (TAS)

```

bool TAS(bool * var) { /* Test-And-Set */
    bool temp;
    temp = *var;
    *var = true;
    return temp;
}

```

↑  
atomic!  
↓

The function **bool TAS(bool \* var)** **atomically** stores **true** in the given memory location and **returns** previous value.

## Locks with Test-and-Set

```

class TASLock {
    private bool locked = false; /* locked? */

    public void lock() {
        while (TAS(&locked)); /* loop until not locked */
    }
    public void unlock() {
        locked = false; /* mark lock as free */
    }
};

```

Recall: **bool TAS(bool \* var)** stores **true** in memory location and **returns** previous value.

## Locks with TAS: Assembly Implementation

```

lock_acquire:      ; function entry point
    tas reg, locked ; Test-and-set; 'locked' is the
                    ; shared variable; is is copied
                    ; into register reg and 'locked'
                    ; then atomically set to 1.

    cmp reg, 0      ; Was 'locked zero' on entry?
    jnz lock_acquire ; Jump to lock_acquire if reg is non-zero;
                    ; i.e, 'locked' was non-zero on entry.

    ret             ; Exit; 'locked' was zero on entry.
                    ; If we get here, tas will have set it
                    ; to non-zero; thus, we have acquired the
                    ; lock associated with variable 'locked'.

lock_release:      ; function entry point for unlock
    mov locked, 0   ; store 0 in 'locked'
    ret             ; return to caller

```

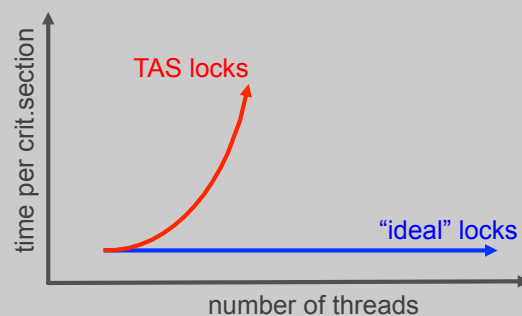
## Analysis of TAS Locks

```

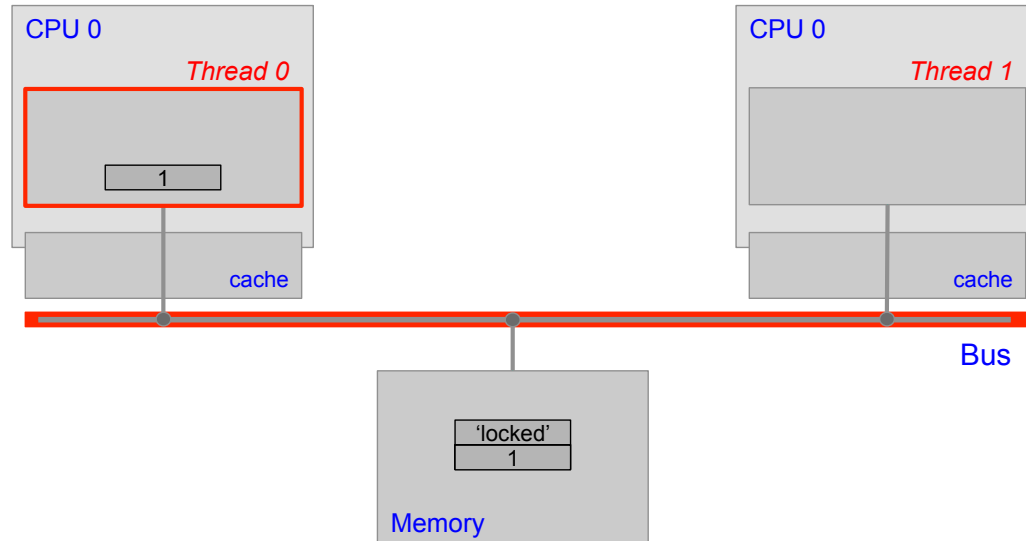
class TASLock {
    private bool locked = false; /* locked? */

    public void lock() {
        while (TAS(&locked));
    }
    public void unlock() {
        locked = false;
    }
};

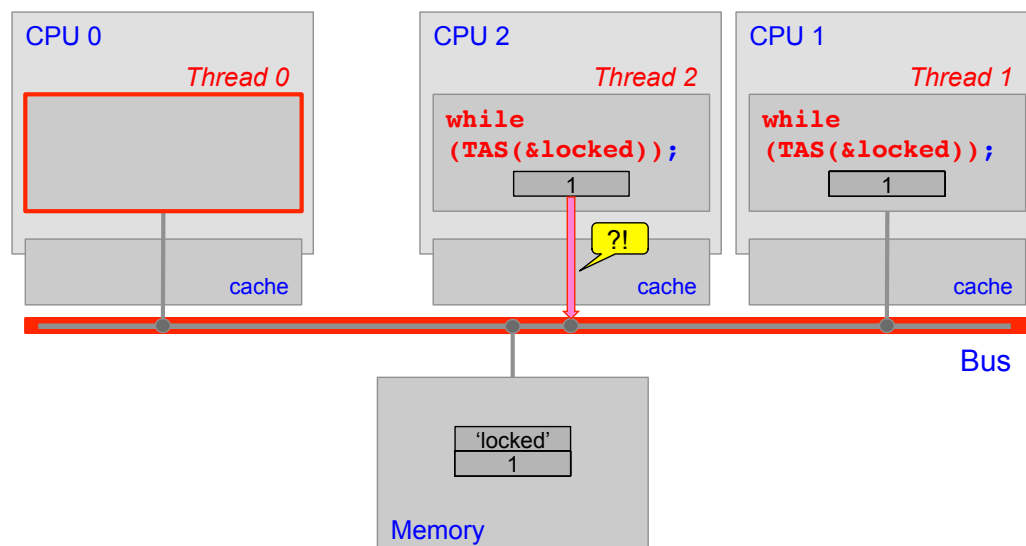
```



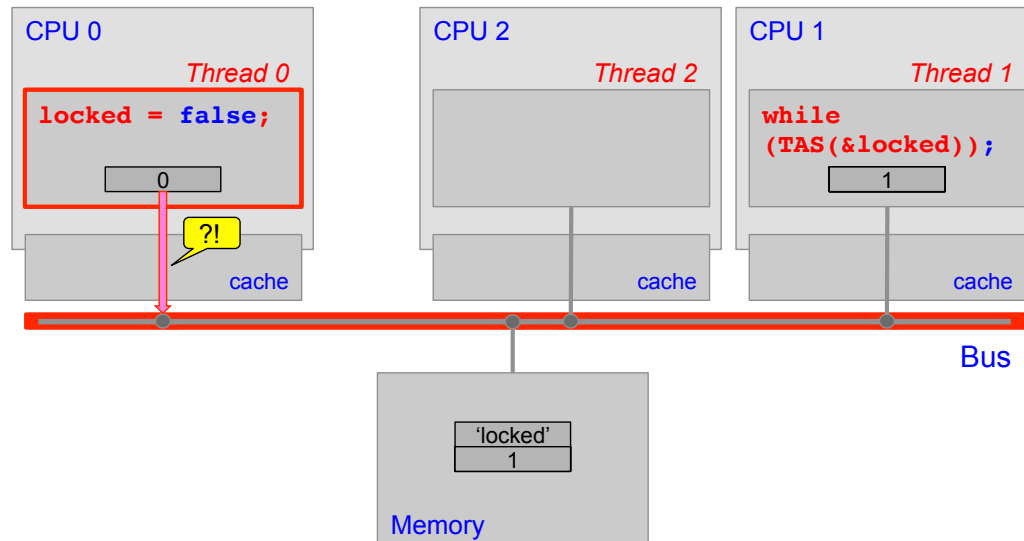
## Analysis of TAS Locks



## Analysis of TAS Locks



## Analysis of TAS Locks



## Improving Locks with Test-and-Set

```
class TASLock {
    private bool locked = false; /* locked? */

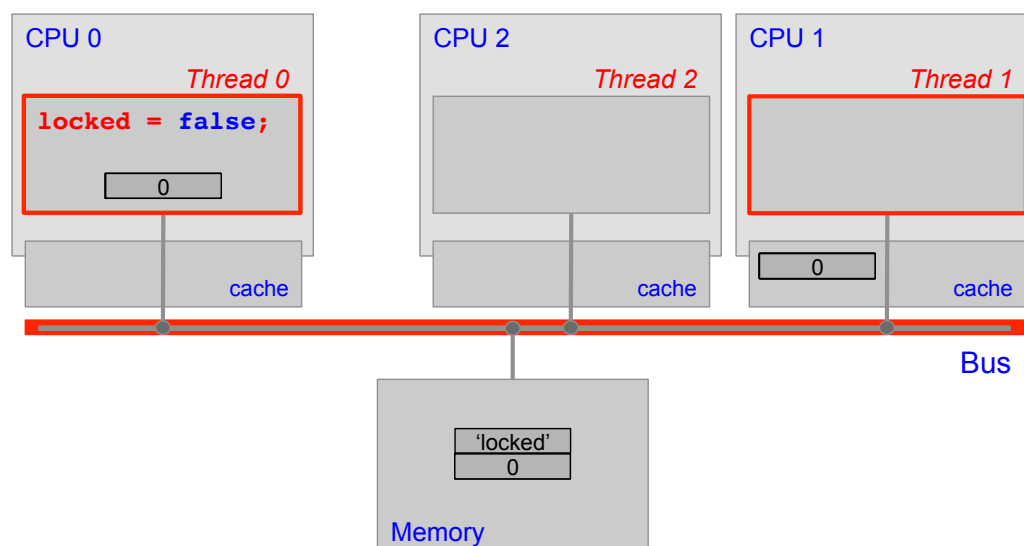
    public void lock() {
        while (TAS(&locked)); /* loop until not locked */
    }
    public void unlock() {
        locked = false; /* mark lock as free */
    }
};
```

Recall: **bool TAS(bool \* var)** stores **true** in memory location and returns previous value.

## Locks with Test-and-Test-and-Set

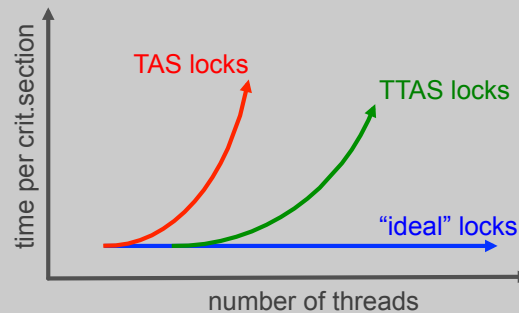
```
class TTASLock {
    private bool locked = false; /* locked? */
    public void lock() {
        for(;;) {
            while (locked){};          /* certainly locked */
            if (!TAS(&locked)) break; /* appears free; check! */
        }
    }
    public void unlock() {...}
};
```

## Analysis of TAS Locks



## Locks with Test-and-Test-and-Set

```
class TTASLock {
    private bool locked = false; /* locked? */
    public void lock() {
        for(;;) {
            while (locked){};
            if (!TAS(&locked)) break;
        }
    }
    public void unlock() {...}
};
```



## Hardware Support: Exchange (XCHG)

```
void XCHG(bool * a, bool * b) { /* Exchange */
    bool temp;
    temp = *a;
    *a = *b;
    *b = temp;
}
```

atomic!

The function **void XCHG(bool \* a, bool \* b)** **atomically exchanges** the values stored in locations a and b.



## Locks with Exchange

```
class XCHGLock {
    private bool locked = false; /* locked? */
    public void lock() {
        bool dummy = true;
        do XCHG(&locked, &dummy);
        while (dummy) /* loop until not locked */
    }
    public void unlock() {
        locked = false; /* mark lock as free */
    }
};
```

The function **XCHG(bool \* a, bool \* b)** **atomically exchanges** the values stored in locations a and b.

## Hardware Support: Fetch-And-Add (FAA)

```
int FAA(int * addr) {
    int value = *addr;
    *location = *addr + 1;
    return value;
}
```

atomic!

The function **int FAA(int \* addr)** **atomically increments** the value stored in location addr and returns value before increment.

## Locks with Fetch-and-Add

(Ticket-Lock Algorithm)

```
class FAALock {
    private int ticketnumber = 0; int turn = 0;

    public void lock() {
        int myturn = FAA(ticketnumber);
        while (turn != myturn); /* wait for our turn */
    }
    public void unlock() {
        FAA(turn);
    }
};
```

Recall: `int FAA(int * loc)` **atomically** increments the value stored in location `loc` and **returns value before increment**.

## Hardware Support: Compare-and-Swap (CAS)

```
int CAS(Type old, Type new, Type * addr) {
    if (*addr == old) {
        *addr = new;
        return true;
    }
    else {
        return false;
    }
}
```

atomic!

The function `int CAS(T o, T n, T * a)` **atomically** compares the value stored in location `addr` with `old`. If they are equal, it assigns `new` to location `addr`, and returns `true`. Returns `false` otherwise.

## Locks with Compare-and-Swap

```
class CASLock {
    private bool locked = false; /* locked? */

    public void lock() {
        while (!CAS(false, true, &locked));
        /* loop until not locked */
    }
    public void unlock() {
        locked = false;
    }
};
```

Recall: `bool CAS(T o, T n, T * a)` **atomically** compares the value stored in location `addr` with `old`. If they are equal, it assigns `new` to location `addr`, and returns `true`. Returns `false` otherwise.

## Compare-and-Swap on the x86 (simplified!)

```
[lock] cmpxchg 'destination', 'source'
```

```
if (accumulator == destination) {
    destination <- source
    zero flag <- 1
}
else {
    accumulator <- destination
    zero flag <- 0
}
```

Prefix 'lock' is used to lock memory bus in multiprocessors.

'Accumulator' is the A, AX, EAX register, depending on size of operands.

## Locks with CAS: Assembly Implementation

```

lock_acquire:                ; function entry point
    mov edx, 1                ; value to set 'locked' to.
lock_retry:
    mov eax, 0                ; value to check 'locked' against.
    ; if (locked == eax): locked    <- edx, zero flag <- 1
    ; else:                        eax    <- edx, zero flag <- 0
    ; If 'locked' is zero, then it will have same value as eax and 'locked' will
    ; be set to edx which is one and we acquire the lock. If the lock was
    ; acquired before the cmpxchg then zero flag will be zero and we spin again.
    cmpxchg [locked], edx    ; CAS(0,1,&locked)
    jz lock_retry            ; Jump to lock_retry if CAS returned false
    ret

lock_release:
    mov [locked], 0          ; use xchg on m-procs
    ret                      ; return to caller

```

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- Disabling Interrupts
- Atomic Instructions (TAS, XCHG, FAA, CAS)
- Performance Analysis of TAS based locks
- Improving the basic algorithms