



# Indian Institute of Technology Mandi भारतीय प्रौद्योगिकी संस्थान मण्डी

MA-201: B.Tech. II year

Odd Semester: 2011-12

Exercise-8 Linear Algebra

1. Which of the following maps are linear ?

- (a)  $T : \mathbb{R}^1 \rightarrow \mathbb{R}^3$  defined by  $T(x) = (x, x^2, x^3)$
- (b)  $T : \mathbb{R}^3 \rightarrow \mathbb{R}^3$  defined by  $T(x, y, z) = (x^2 + xy, xy, yz)$
- (c)  $T : \mathbb{R}^3 \rightarrow \mathbb{R}^2$  defined by  $T(x, y, z) = (x + y + z, 0)$ ,  $\alpha \neq 0$
- (d)  $T : \mathcal{P} \rightarrow \mathcal{P}$  defined by  $T(\mathbf{p})(x) = x\mathbf{p}(x) + \mathbf{p}(1)$
- (e)  $T : \mathcal{P}[0, 1] \rightarrow \mathbb{R}^2$  defined by  $T(f) = (f(0), f(1))$
- (f)  $T : P \rightarrow P$  defined by  $T(p) = p(0)$

2. For the following Linear Transformations

- (a) Determine the range of the linear transformations. Also find the rank of  $T$ , where it exists.
- (b) Determine the kernel of the linear transformations. Also find the nullity of  $T$ , where it exists.
- (c) Pick out the maps that are one-one, onto, one-one and onto.
  - i.  $T : \mathbb{R}^2 \rightarrow \mathbb{R}^3$  defined by  $T(x_1, x_2) = (x_1, x_1 + x_2, x_2)$ .
  - ii.  $T : \mathbb{R}^3 \rightarrow \mathbb{R}^3$  defined by  $T(x_1, x_2, x_3) = \left(\frac{1}{2}x_1 + x_2 + x_3, x_1 - \frac{1}{3}x_2, x_3\right)$ .
  - iii.  $T : \mathbb{R}^3 \rightarrow \mathbb{R}^4$  defined by  $T(x_1, x_2, x_3) = (x_1, x_1 + x_2, x_1 + x_2 + x_3, x_3)$ .
  - iv.  $T : \mathcal{P} \rightarrow \mathcal{P}$  defined by  $T(\mathbf{p})(x) = \mathbf{p}''(x) - 2\mathbf{p}(x)$ .

3. Find a linear transformation  $T : \mathbb{R}^3 \rightarrow \mathbb{R}^3$  such that the set of all vectors  $(x_1, x_2, x_3)$  satisfying the equation  $4x_1 - 3x_2 + x_3 = 0$  is the kernel of  $T$ .

4. Find a trace and determinant of the following Linear Transformation on  $\mathbb{R}^3$

- (a)  $T(x_1, x_2, x_3) = (x_1 + 3x_2, 3x_1 - 2x_3, x_1 - 4x_2 - 3x_3)$
- (b)  $T(x_1, x_2, x_3) = (x_2 + x_3, 2x_1 - 4x_3, 5x_1 + 7x_2)$

5. Find the change of basis matrix  $P$  from the usual basis  $E = (e_1, e_2, e_3)$  to  $\mathbb{R}^3$  to a basis  $S$ , the change of basis matrix  $Q$  from  $S$  back to  $E$ , and the coordinate of  $v = (a, b, c)$  relative to  $S$ , for the following bases  $S$ :

- (a)  $u_1 = (1, 0, 0), u_2 = (0, 1, 2), u_3 = (0, 0, 1)$
- (b)  $u_1 = (1, 0, 1), u_2 = (1, 1, 2), u_3 = (1, 2, 4)$
- (c)  $u_1 = (1, 2, 1), u_2 = (1, 3, 4), u_3 = (2, 5, 6)$

6. Let  $T : \mathbb{R}^2 \rightarrow \mathbb{R}^2$  be defined by matrix  $T = \begin{bmatrix} 1 & -1 \\ 3 & 2 \end{bmatrix}$ . Find the matrix  $B$  that represents the linear operator  $T$  relative to each of the following bases:

- (a)  $B = \{(1, 3), (2, 5)\}$

(b)  $B = \{(1, 3), (2, 4)\}$

7. Let  $T : \mathbb{R}^3 \rightarrow \mathbb{R}^3$  be defined by matrix  $T = \begin{bmatrix} 1 & 3 & 1 \\ 2 & 7 & 4 \\ 1 & 4 & 3 \end{bmatrix}$ . Find the matrix  $A$  that represents the linear operator  $T$  relative to the basis  $T = \{(1, 1, 1), (0, 1, 1), (1, 2, 3)\}$

8. Find the matrix representation of each of the following linear maps relative to the usual basis for  $\mathbb{R}^n$ :

(a)  $F : \mathbb{R}^3 \rightarrow \mathbb{R}^2$  defined by  $F(x, y, z) = (2x - 4y + 9z, 5x + 3y - 2z)$ .

(b)  $F : \mathbb{R}^2 \rightarrow \mathbb{R}^4$  defined by  $F(x, y) = (3x + 4y, 5x - 2y, x + 7y, 4x)$ .

(c)  $F : \mathbb{R}^4 \rightarrow \mathbb{R}$  defined by  $F(x, y, z, w) = 2x + y - 7z - w$ .

9. let  $G : \mathbb{R}^3 \rightarrow \mathbb{R}^2$  be defined by  $G(x, y, z) = (2x + 3y - z, 4x - y + 2z)$

(a) Find the matrix  $A$  representing  $G$  relative to the bases  $S = \{(1, 1, 0), (1, 2, 3), (1, 3, 5)\}$  and  $S' = \{(1, 2), (2, 3)\}$

(b) For any  $v = (a, b, c)$  in  $\mathbb{R}^3$ , find  $[v]_S$  and  $[G(v)]_{S'}$

(c) verify that  $A[v]_S = [G(v)]_{S'}$

10. Consider the following linear operator  $G$  on  $\mathbb{R}^2$  and basis  $S$  given by  $G(x, y) = (2x - 7y, 4x + 3y)$  and  $S = (1, 3), (2, 5)$ .

(a) Find the matrix representation of  $[G]_S$  of  $G$  relative to  $S$ .

(b) Verify  $[G]_S[v]_S = [G(v)]_S$  for the vector  $v = (4, -3)$  in  $\mathbb{R}^2$ .

11. let  $H : \mathbb{R}^2 \rightarrow \mathbb{R}^2$  be defined by  $H(x, y) = (2x + 7y, x - 3y)$  and consider the following bases of  $\mathbb{R}^2$  (i)  $S = \{(1, 1), (1, 2)\}$  and (ii)  $S' = \{(1, 4), (1, 5)\}$

(a) Find the matrix  $A$  representing  $H$  relative to the bases  $S$  and  $S'$

(b) Find the matrix  $B$  representing  $H$  relative to the bases  $S'$  and  $S$

12. Find the characteristic and minimal polynomial of each of the following matrices if possible

$$A = \begin{bmatrix} 2 & 5 & 0 & 0 & 0 \\ 0 & 2 & 0 & 0 & 0 \\ 0 & 0 & 4 & 2 & 0 \\ 0 & 0 & 3 & 5 & 0 \\ 0 & 0 & 0 & 0 & 7 \end{bmatrix}, A = \begin{bmatrix} 4 & -1 & 0 & 0 & 0 \\ 1 & 2 & 0 & 0 & 0 \\ 0 & 0 & 3 & 1 & 0 \\ 0 & 0 & 0 & 3 & 1 \\ 0 & 0 & 0 & 0 & 3 \end{bmatrix}, A = \begin{bmatrix} 3 & 2 & 0 & 0 & 0 \\ 1 & 4 & 0 & 0 & 0 \\ 0 & 0 & 3 & 1 & 0 \\ 0 & 0 & 1 & 3 & 0 \\ 0 & 0 & 0 & 0 & 4 \end{bmatrix}, A = \begin{bmatrix} 4 & 1 & 0 & 0 & 0 \\ 0 & 4 & 1 & 0 & 0 \\ 0 & 0 & 4 & 1 & 0 \\ 0 & 0 & 0 & 4 & 1 \\ 0 & 0 & 0 & 0 & 4 \end{bmatrix},$$

$$A = \begin{bmatrix} 2 & 7 & 0 & 0 \\ 0 & 2 & 0 & 0 \\ 0 & 0 & 1 & 1 \\ 0 & 0 & -2 & 4 \end{bmatrix}$$