

Making Decisions with Reinforcement Learning

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Outline

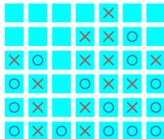
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- 2 Neural Networks
 - Simple Perceptron
 - Multilayer Perceptron
 - Convolutional Neural Network
- 3 Reinforcement Learning
 - Temporal Difference Method
 - Stochastic Gradient Descent
- 4 Results
- 5 Future Directions

Supervised Learning vs Reinforcement Learning

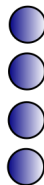
- Supervised Learning
 - Have access to a large set of data with known desired results.
 - Adjust model parameters to minimize an objective function.
- Reinforcement Learning
 - Have access to an environment that can be modeled.
 - Typically a reward function is used as a signal for how to adjust model parameters.
 - Board games present a natural environment that is easily modeled and can provide a reward whenever a game completes.

Simple Perceptron

Input



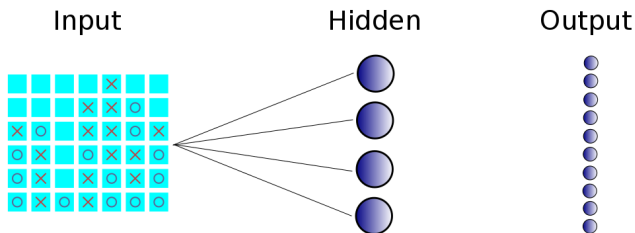
Hidden



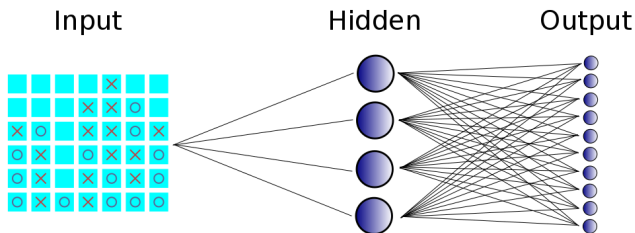
Output



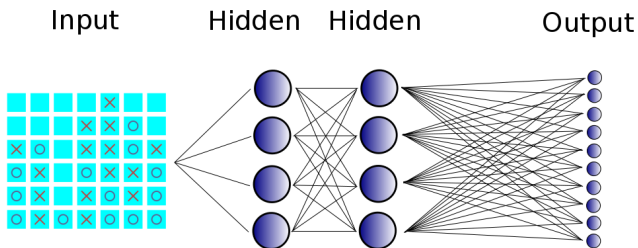
Simple Perceptron



Simple Perceptron

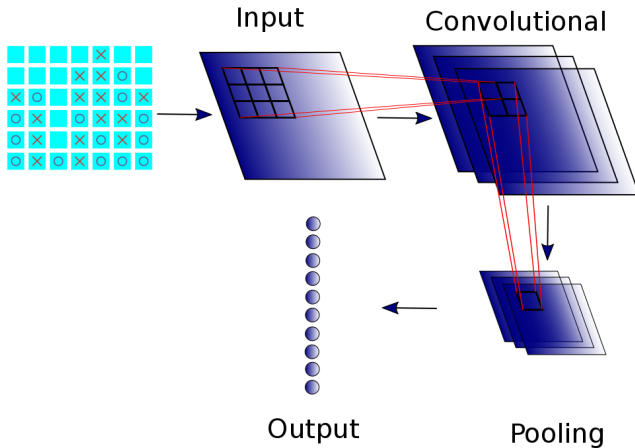


Multilayer Perceptron





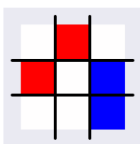
Convolutional Neural Network



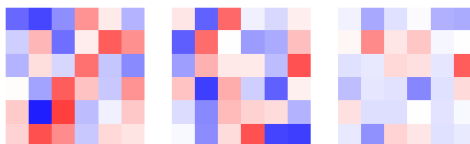
Value Network

- A value network is a neural network that evaluates an environment and determines a value to associate to it.
- In the case of board games, a value network can be used to determine the probability of winning from any given position.

Tic Tac Toe Position



Network Node Activations



Predicted Winner



Reinforcement Learning

TD(λ) Equation:

When a terminal state occurs, the reward propagates to previous states and the targets are updated.

$$T_n = (1 - \lambda) V_n + \lambda r$$

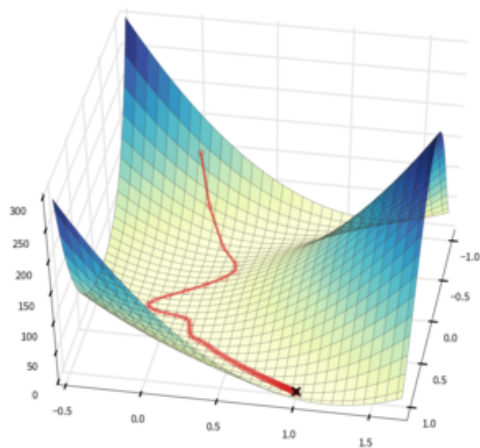
Reinforcement Learning

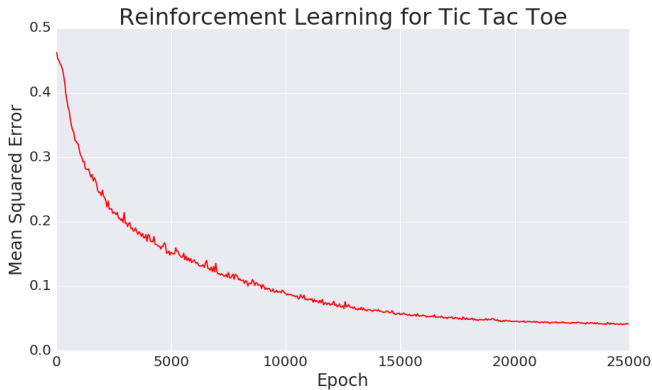
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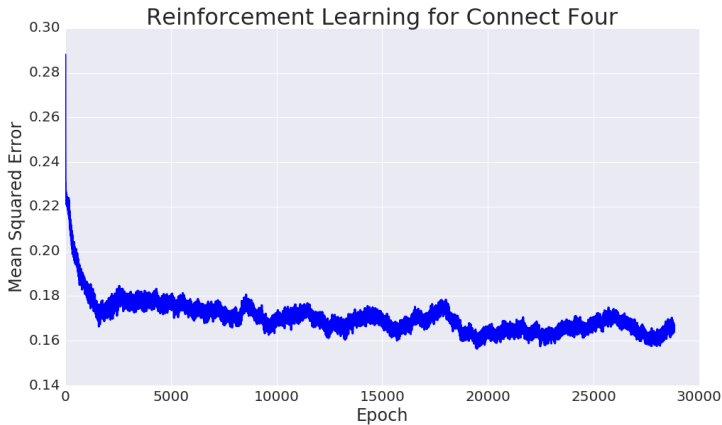
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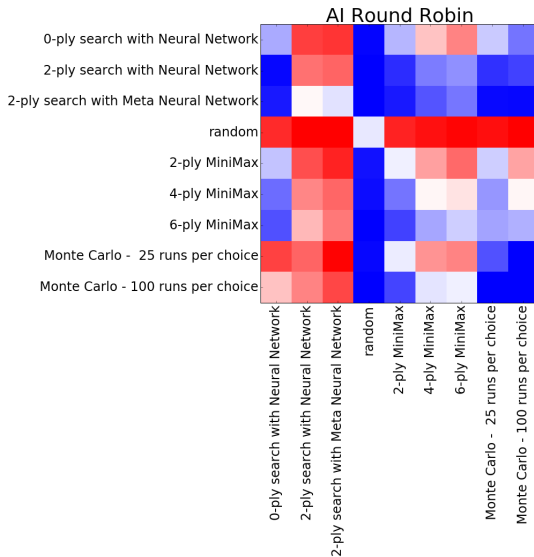
$$T_n = \sum_{n=0}^{N_0} (1 - \lambda) \lambda^n V_n + \lambda^{N_0} r$$

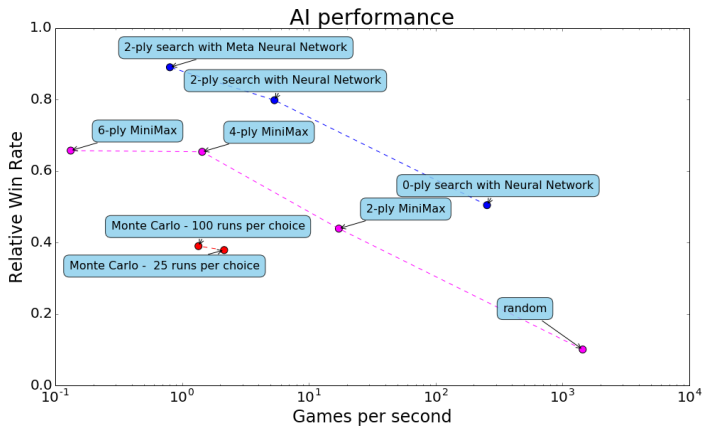
Stochastic Gradient Descent











Future Directions

- Route finding app
- Traffic prediction analysis
- Control (robots, self-driving cars, etc.)
- Prediction (stock prices, sports betting, etc.)