

EM 1/ 1 D.E. Brown

Expectation Maximization

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Mixture Models and Expectation Maximization

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A mixture model

$$p(\mathbf{x}|\boldsymbol{\theta}) = \sum_{k=1}^{K} p(\mathbf{x}|\boldsymbol{\theta}, k) p(k)$$

- How do we estimate the model parameters and K?
 Expectation Maximation (EM) Algorithm.
- Combination of EM with Gaussian Mixtures is often used for clustering or unsupervised learning: Gaussian Mixture Models (GMM) or Model-Based Clustering
- Can use mixture models with any distributions or models - e.g., used with binomials for text analysis
- EM is used for many more problems than clustering



Multivariate Mixture Models

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- Assume the data come from N independent samples on K distributions: $f_i(\mathbf{x}|\boldsymbol{\theta}_i), i=1,\ldots,K$, and $\boldsymbol{\theta}$ is the vector of parameters.
- If the probability the data come from distribution, ϕ_i is π_i then

$$f(\mathbf{x}) = \sum_{i=1}^{K} \pi_i \phi_i(\mathbf{x}|\boldsymbol{\theta}_i)$$

- For GMM, assume $\phi_i(\mathbf{x}|\boldsymbol{\theta}_i) \sim N(\mathbf{x}|\boldsymbol{\mu}_i, \boldsymbol{\Sigma}_i), i = 1, \dots, K$.
- Let **z** be a K dimensional r.v. with $z_i \in \{0, 1\}, i = 1, \dots, K$.
- So, $Pr(z_i = 1) = \pi_i, i = 1, \dots, K$.



Multivariate Mixture Model Fitting

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- The parameters are $\theta = \{\pi_2, \dots, \pi_K, \mu_1, \dots, \mu_K, \Sigma_1, \dots, \Sigma_K\}$
- The log-likelihood is

$$\ell(\boldsymbol{\theta}|\boldsymbol{x}) = \sum_{i=1}^{N} log \left(\sum_{k=1}^{K} \pi_k \phi(\mathbf{x}|\boldsymbol{\mu}_i, \boldsymbol{\Sigma}_i) \right)$$



Multivariate Mixture Model Estimation

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• $Pr(z_k = 1 | x_i) \equiv \gamma_i(z_k)$ or responsibility.

$$\gamma_i(z_k) = \frac{\pi_k \phi(\mathbf{x}_i | \boldsymbol{\mu}_k, \boldsymbol{\Sigma}_k)}{\sum_{j=1}^K \pi_j \phi(\mathbf{x}_i | \boldsymbol{\mu}_j, \boldsymbol{\Sigma}_j)}$$

Parameters

$$N_k = \sum_{i=1}^N \gamma_i(z_k)$$

$$\boldsymbol{\mu}_k = \frac{1}{N_k} \sum_{i=1}^N \gamma_i(z_k) x_i$$

$$\boldsymbol{\Sigma}_k = \frac{1}{N_k} \sum_{i=1}^N \gamma_i(z_k) (\mathbf{x}_i - \boldsymbol{\mu}_k) (\mathbf{x}_i - \boldsymbol{\mu}_k)^T$$

$$\pi_k = N_k/N$$



Multivariate Gaussian EM

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- Initialize θ.
- E Step. Responsibilities with current parameter estimates.

$$\gamma_i(z_k) = \frac{\pi_k \phi(\mathbf{x}_i | \boldsymbol{\mu}_k, \boldsymbol{\Sigma}_k)}{\sum_{j=1}^K \pi_j \phi(\mathbf{x}_i | \boldsymbol{\mu}_j, \boldsymbol{\Sigma}_j)}$$



Multivariate Gaussian EM

EM 7/ 1 D.E. Brown

 M Step. Estimate parameters with current responsibilities.

$$N_k = \sum_{i=1}^N \gamma_i(z_k)$$

$$\boldsymbol{\mu}_k = \frac{1}{N_k} \sum_{i=1}^N \gamma_i(z_k) \mathbf{x}_i$$

$$\boldsymbol{\Sigma}_k = \frac{1}{N_k} \sum_{i=1}^N \gamma_i(z_k) (\mathbf{x}_i - \boldsymbol{\mu}_k) (\mathbf{x}_i - \boldsymbol{\mu}_k)^T$$

$$\pi_k = N_k / N$$



Multivariate Gaussian EM

EM 8/ 1 D.E. Browi

> Stopping. Check for change in parameters or likelihood, and stop if change is less than the threshold.

$$\ell(\boldsymbol{\theta}|\boldsymbol{x}) = \sum_{i=1}^{N} \log \left(\sum_{k=1}^{K} \pi_k \phi(\mathbf{x}|\boldsymbol{\mu}_i, \boldsymbol{\Sigma}_i) \right)$$



Comments on EM for Gaussian Mixtures

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- Poor starting points can lead to poor solutions
- Select starting points randomly from the data, use K-means or use stratified sampling
- Selection of K is by testing
- EM is a heuristic and can get stuck in local optima



Example 1 Data

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Data from three Gaussians

$$\mu_1 = [10, 3]$$

$$\mu_2 = [1, 1]$$

$$\mu_3 = [5, 4]$$

$$\sigma_1^2 = 1$$

$$\sigma_1^2 = 1.5$$

$$\sigma_1^2 = 2$$



Example 1 Initialization

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Initial values

$$\mu_{1} = [3, 5]$$

$$\mu_{2} = [2, .4]$$

$$\mu_{3} = [4, 3]$$

$$\sigma_{1}^{2} = 1$$

$$\sigma_{1}^{2} = 1$$

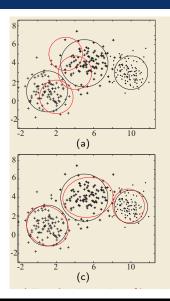
$$\sigma_{1}^{2} = 1$$

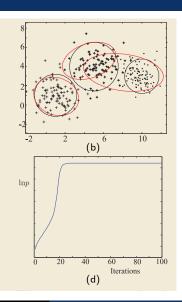
$$P_{k} = \frac{1}{3}$$



Example 1 Results

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Example 2 Initialization

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Initial values

$$\mu_1 = [10.13]$$

$$\mu_2 = [11, 12]$$

$$\mu_3 = [13, 11]$$

$$\sigma_1^2 = 1$$

$$\sigma_1^2 = 1$$

$$\sigma_1^2 = 1$$

$$P_k = \frac{1}{3}$$



Example 1 Results

EM 14/ 1 .E. Brown

