# Thomas J. Stastny

Ph.D Candidate · Research Assistant

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2014 - Present

2012 - 2014

2011

2008 - 2009

2016 - Present

2014 - Present

2014 - Present

2014 - 2015

2014

2012 - 2014

2015

### Academic History \_\_\_\_\_

# Swiss Federal Institute of Technology (ETH Zürich)

Zürich, Switzerland Ph.D IN ROBOTICS Expected 2018

#### **University of Kansas**

Lawrence, KS, USA

M.S. with Honors in Aerospace Engineering 2012 - 2014

### **Delft University of Technology**

Delft, Netherlands

SEMESTER ABROAD

Spring 2012

#### **University of Kansas**

Lawrence, KS, USA

B.S. IN AEROSPACE ENGINEERING

2008 - 2012

### **Professional Skills**

**Robotics** Flight instrumentation – avionics and senors. Basics of electronic components, circuits, soldering, crimping techniques. Basics of structural design/fabrication. Radio controlled piloting experience on small fixedwing platforms.

**Software** MATLAB/Simulink, MSC Nastran/Patran (Finite Element Analysis), National Instruments LabVIEW, Unigraphics NX (CAD), Linux / Mac / Windows OS

**Programming** C/C++, Python (limited), Robotic Operating System (ROS), version control (Git), microcontroller programming (ARM), HTML

### **Honors & Affiliations**

Awarded United States Department of Defense Antarctica Service Medal (2014)

Sigma Gamma Tau, National Aerospace Honors Society (2010 - 2014)

C&C Chaffee Engineering School Scholarship (2012 - 2013)

Univserity of Kansas Aerospace Undergraduate Researcher Award (2012)

### **Research Positions**

#### Autonomous Systems Lab, ETH Zürich

Zürich, Switzerland

RESEARCH ASSISTANT

# Center for Remote Sensing of Ice Sheets (CReSIS), University of Kansas

Lawrence, KS, USA

RESEARCH ASSISTANT

#### Autonomous Flight Systems Group, University of Kansas

Lawrence, KS, USA

Undergraduate Research Assistant

## Aerospace Adaptive Structures and Materials Laboratory, University of Kansas

Lawrence, KS, USA

Undergraduate Research Assistant

### Research Projects \_\_\_\_\_

# SolAIR: Solar-powered Automated Aerial Imaging and Reconnaissance using Infrared Cameras

SUPPORTED BY ARMASUISSE SCIENCE & TECHNOLOGY CENTER

### Adventura AtlantikSolar@Brazil

Supported by Swissnex Brazil, Swissando, and ETH Global

☐ http://www.swissnexbrazil.org/atlantiksolar/

## AtlantikSolar: A UAV for the first-ever autonomous solar-powered crossing of the Atlantic Ocean

SUPPORTED BY PRIVATE INVESTORS AND INTERNAL LABORATORY BUDGET 

This://www.atlantiksolar.ethz.ch/

# SHERPA: Smart collaboration between Humans and ground-aErial Robots for imProving rescuing activities in Alpine environments

SUPPORTED BY THE EUROPEAN COMMISSION UNDER THE 7TH EUROPEAN FRAMEWORK PROGRAMME (#600958)

☑ http://www.sherpa-project.eu/

#### **ICARUS: Robotic Search and Rescue**

SUPPORTED BY THE EUROPEAN COMMISSION UNDER THE 7TH EUROPEAN FRAMEWORK

PROGRAMME (#285417)

☐ http://www.fp7-icarus.eu/

### Multi-Agent Airborne Laboratory for Cryospheric Remote Sensing

SUPPORTED BY THE PAUL G. ALLEN FAMILY FOUNDATION

#### **CReSIS: Center for Remote Sensing of Ice Sheets**

SUPPORTED BY THE NATIONAL SCIENCE FOUNDATION (NSF) UNDER GRANT ANT-0424589

Thttps://www.cresis.ku.edu/

### **Publications**

References available upon request.