

Let's consider binary function

$$f: \{0, 1\} \rightarrow \{0, 1\}$$

There are 4 such functions:

input:

	$f_1$	$f_2$	$f_3$	$f_4$
0	0	0	1	1
1	0	1	0	1

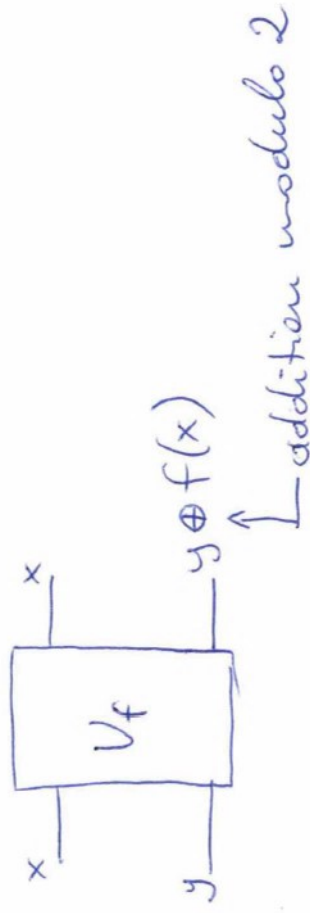
$f(0) = f(1) \Rightarrow$  function is constant  
 $f(0) \neq f(1) \Rightarrow$  function is "balanced"

$\Downarrow$

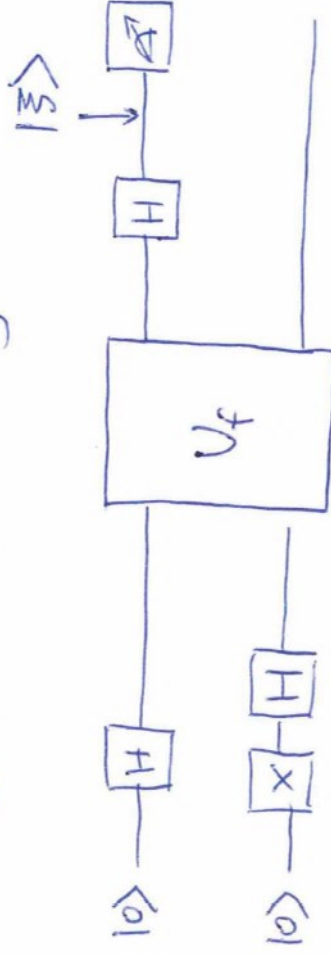
$f_1, f_4$  - constant  
 $f_2, f_3$  - balanced

- Let's imagine we have "black box" implementing one of these functions.
- To understand if it is balanced or constant, classically we need to compute both  $f(0)$  and  $f(1) \Rightarrow$  query the black box twice
- Deutsch algorithm allows to do this on quantum computer calculating function value only once.
- simplest algorithm demonstrating gain from quantum computers  $\downarrow$

Block box (oracle):



Let's consider following circuit:



We can show, that state  $|\Xi\rangle$  of the first qubit will have the following form:

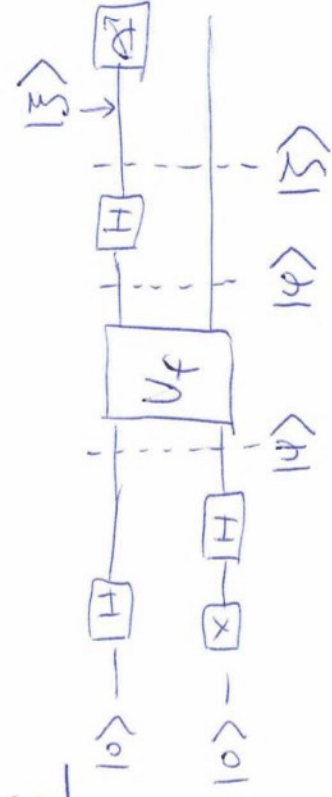
$$|\Xi\rangle = \text{const.} \left[ \left( (-1)^{f(0)} + (-1)^{f(1)} \right) |0\rangle + \left( (-1)^{f(0)} - (-1)^{f(1)} \right) |1\rangle \right]$$

Interpretation:

- if we measure first qubit in state  $|0\rangle$ , then it means that  $f(0)=f(1) \Rightarrow f$  is const
- if we measure first qubit in state  $|1\rangle$ , then it means, that  $f(0) = -f(1) \Rightarrow f$  balanced



We can measure just one time and know the answer (classically twice)



$$| \psi \rangle = H | 0 \rangle \otimes H | 1 \rangle = \frac{1}{2} (| 0 \rangle + | 1 \rangle) \otimes (| 0 \rangle - | 1 \rangle) =$$

$$= \frac{1}{2} (| 0 \rangle | 0 \rangle + | 1 \rangle | 0 \rangle - | 0 \rangle | 1 \rangle - | 1 \rangle | 1 \rangle)$$

$$| \varphi \rangle = U_f | \psi \rangle = \left\{ \begin{array}{l} U_f: | x \rangle | y \rangle \rightarrow | x \rangle | y \oplus f(x) \rangle \end{array} \right\} =$$

$$= \frac{1}{2} (| 0 \rangle | 0 \oplus f(0) \rangle + | 1 \rangle | 0 \oplus f(1) \rangle -$$

$$- | 0 \rangle | 1 \oplus f(0) \rangle - | 1 \rangle | 1 \oplus f(1) \rangle) =$$

$$= \frac{1}{2} [ | 0 \rangle (| 0 \oplus f(0) \rangle - | 1 \oplus f(0) \rangle) + | 1 \rangle (| 0 \oplus f(1) \rangle - | 1 \oplus f(1) \rangle) ] =$$

$$= \frac{1}{2} [ | 0 \rangle (| f(0) \rangle - | 1 \oplus f(0) \rangle) + | 1 \rangle (| f(1) \rangle - | 1 \oplus f(1) \rangle) ] =$$

$$= \frac{1}{2} \sum_{x=0}^1 | x \rangle (| f(x) \rangle - | 1 \oplus f(x) \rangle) =$$

$$= \left\{ \begin{array}{l} | f(x) \rangle - | 1 \oplus f(x) \rangle = \begin{cases} | 0 \rangle - | 1 \rangle & \text{for } f(x) = 0 \\ | 1 \rangle - | 0 \rangle & \text{for } f(x) = 1 \end{cases} \end{array} \right\} =$$

$$= \frac{1}{2} \sum_{x=0}^1 | x \rangle (-1)^{f(x)} (| 0 \rangle - | 1 \rangle) =$$

$$= \frac{1}{2} [ (-1)^{f(0)} | 0 \rangle (| 0 \rangle - | 1 \rangle) + (-1)^{f(1)} | 1 \rangle (| 0 \rangle - | 1 \rangle) ] = \rightarrow$$



$$= \frac{1}{2} \left[ (-1)^{f(0)} |0\rangle + (-1)^{f(1)} |1\rangle \right] (|0\rangle - |1\rangle)$$

Now we apply the final H gate on the first qubit:

$$|\bar{3}\rangle = \frac{1}{2} \left[ (-1)^{f(0)} \frac{1}{\sqrt{2}} (|0\rangle + |1\rangle) + (-1)^{f(1)} \frac{1}{\sqrt{2}} (|0\rangle - |1\rangle) \right] (|0\rangle - |1\rangle)$$

state of first qubit  
(only this is of interest  
to us)  $|\bar{3}\rangle$

$$|\bar{3}\rangle = \text{const.} \left[ (-1)^{f(0)} |0\rangle + (-1)^{f(0)} |1\rangle + (-1)^{f(1)} |0\rangle - (-1)^{f(1)} |1\rangle \right] =$$

$$= \text{const.} \left[ (-1)^{f(0)} + (-1)^{f(1)} \right] |0\rangle + \left[ (-1)^{f(0)} - (-1)^{f(1)} \right] |1\rangle$$

cbdo.

□

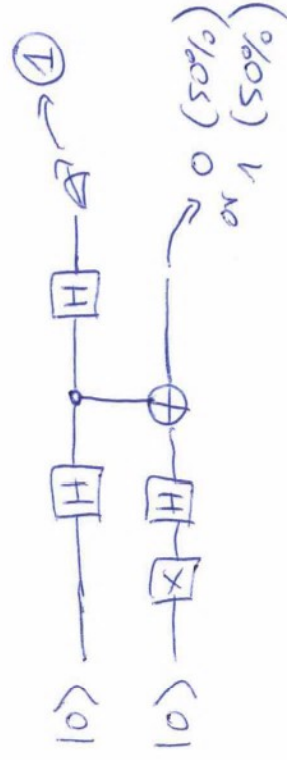
Examples:-

A)  = 

$$\begin{array}{l} \underline{00} \rightarrow \underline{00} \\ \underline{10} \rightarrow \underline{11} \end{array} = f: \begin{array}{l} 0 \rightarrow 0 \\ 1 \rightarrow 1 \end{array} \quad (f_2)$$

balanced

(CNOT is just adding modulo 2)



B)

$$V_f: \begin{array}{l} \underline{00} \rightarrow \underline{01} \\ \underline{10} \rightarrow \underline{11} \end{array} \Rightarrow \begin{array}{l} 0 \rightarrow 1 \\ 1 \rightarrow 1 \end{array}$$

$\Downarrow$   
f constant ( $f_4$ )

c)

$$V_f: \begin{array}{l} \underline{01} \\ \underline{00} \end{array} \xrightarrow{\text{CNOT}} \begin{array}{l} \underline{01} \\ \underline{10} \end{array} \Rightarrow \begin{array}{l} 0 \rightarrow 1 \\ 1 \rightarrow 0 \end{array} \Rightarrow \text{balanced } (f_3)$$

d)

$$\begin{array}{l} \underline{01} \\ \underline{00} \end{array} \xrightarrow{\text{CNOT}} \begin{array}{l} \underline{01} \\ \underline{00} \end{array} \Rightarrow \begin{array}{l} 0 \rightarrow 0 \\ 1 \rightarrow 0 \end{array} \Rightarrow \text{constant } (f_1)$$