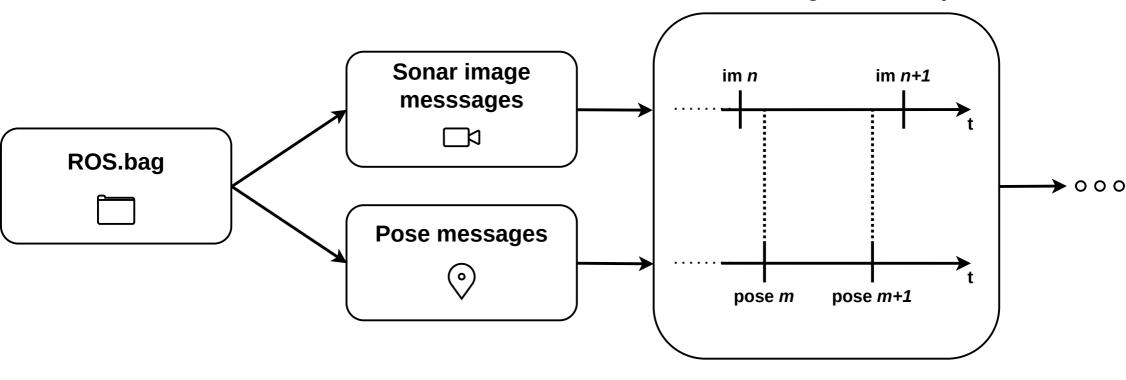
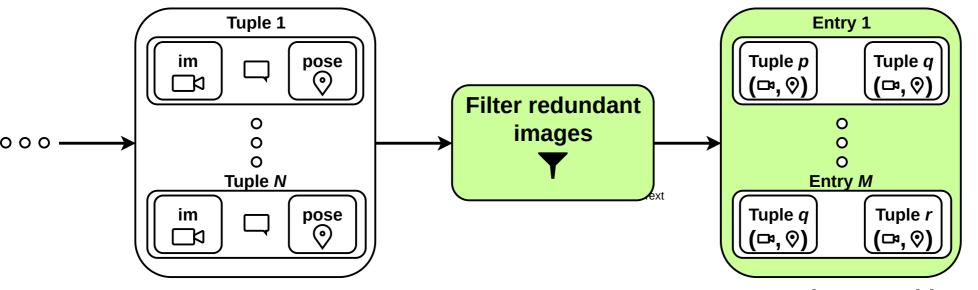
## Linearly interpolate poses according to sonar image timestamp





Keep images with sufficient image overlap and store as (Entry, Entry) pairs