마이크로프로세서

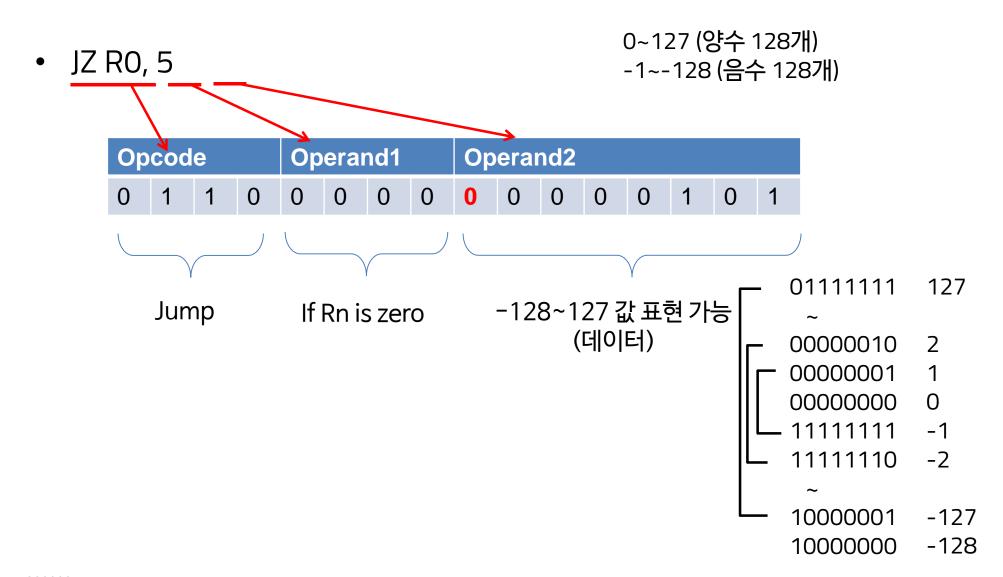
- Conditional Branch (JZ) -

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Conditional Branch: JZ



Decode 일부수정

Opcode: 6

CDecode.h

```
enum { MOV0=0, MOV1, MOV2, MOV3, ADD, SUB, JZ, MUL };
```

CDecode.cpp

```
void
CT1DecodeDirectFetch::show_instruction() {
   if(m_instruction.OPCODE == MOV3) {
        cout << "MOV3 " << "R" << m_instruction.OP1 << ", #" << m_instruction.OP2 << endl;
   } else if(m_instruction.OPCODE == ADD ) {
        unsigned int op2 = (m_instruction.OP2 >> 4) & 0xF;
        cout << "ADD " << "R" << m_instruction.OP1 << ", R" << op2 << end];
   } else if(m_instruction.OPCODE == SUB ) {
        unsigned int op2 = (m_instruction.OP2 >> 4) & 0xF;
        cout << "SUB " << "R" << m_instruction.OP1 << ", R" << op2 << endl;
   } else if(m_instruction.OPCODE == MOVO) {
        unsigned int op2 = m_instruction.OP2 & 0xFF;
        cout << "MOVO " << "R" << m_instruction.OP1 << ", [" << op2 << "]" << end];
   } else if(m_instruction.OPCODE == MOV1) {
        unsigned int op2 = m_instruction.OP2 & 0xFF;
        cout << "MOV1 " << "[" << op2 << "], R" << m_instruction.OP1 << end];</pre>
   } else if(m_instruction.OPCODE == MUL ) {
        unsigned int op2 = (m_instruction.OP2 >> 4) & 0xF;
        cout << "MUL " << "R" << m instruction.OP1 << ". R" << op2 << end1:
     else if(m_instruction.OPCODE == JZ ) {
        cout << "JZ " << "R" << m_instruction.OP1 << ", " << m_instruction.OP2 << endl;</pre>
```

Register File에 PC 추가

PC (Program Counter) Register

현재 코드 메모리에 접근중인 주소

```
2 #include <iostream>
  #pragma once
 6 using namespace std;
 8 class CRegister {
 9 public:
       CRegister() { }
      virtual ~CRegister() { }
12
13 };
15 class C16RegisterFile : public CRegister {
16 public:
       C16RegisterFile() : m_PC(0) {}
18
       virtual ~C16RegisterFile() {}
19
20
       void write_on_reg(unsigned int index, int data) { m_regs[index] = data; },
       int read_from_reg(unsigned int index)
21
                                                        { return m_reqs[index]; }
22
       int get_PC() { return m_PC; }
23
       void set_PC(int pc) { m_PC = pc; }
24
       void show_regs();
   private:
28
       int m_regs[16];
29
       int m_PC;
30
```

CExecute.cpp

현재 명령어 실행 후 자동적으로 PC++

```
bool CT1ExecuteTinyUnit::do_execute() {
    // ex. MOV3 RO, #3
    if(m_decode_unit.get_opcode() == MOV3) {
        unsigned int req_index = m_decode_unit.get_op1();
                          data = m_decode_unit.get_op2();
        m_regs.write_on_reg(reg_index, data);
        m_regs.set_PC(m_regs.get_PC()+1);
        return true;
      // ex. ADD RO, R1 --> RO = RO + R1
    } else if( m_decode_unit.get_opcode() == ADD) {
        unsigned int reg_n = m_decode_unit.get_op1();
        unsigned int reg_m = (m_decode_unit.get_op2() >> 4) & 0xF;
        int Rn = m_reqs.read_from_req(req_n);
        int Rm = m_regs.read_from_reg(reg_m);
        Rn = Rn + Rm;
        m_regs.write_on_reg(reg_n, Rn);
        m_regs.set_PC(m_regs.get_PC()+1);
        return true;
```

CExecute.cpp

현재 명령어 실행 후 자동적으로 PC++

```
// ex. SUB RO, R1 --> RO = RO - R1
} else if( m_decode_unit.get_opcode() == SUB) {
    unsigned int reg_n = m_decode_unit.get_op1();
    unsigned int reg_m = (m_decode_unit.get_op2() >> 4) & 0xF;
    int Rn = m_reqs.read_from_req(req_n);
    int Rm = m_regs.read_from_reg(reg_m);
    Rn = Rn - Rm;
    m_regs.write_on_reg(reg_n, Rn);
    m_regs.set_PC(m_regs.get_PC()+1);
    return true;
  // ex. MOVO R1, [3] : R1 <- M[3]
} else if( m_decode_unit.get_opcode() == MOVO ) {
    unsigned int reg_n = m_decode_unit.get_op1();
    unsigned int mem_addr = m_decode_unit.get_op2() & 0xFF;
    int memory_data = m_mems.read_from_memory(mem_addr);
    m_regs.write_on_reg(reg_n, memory_data);
    m_regs.set_PC(m_regs.get_PC()+1);
    return true;
```

CExecute.cpp

현재 명령어 실행 후 자동적으로 PC++

```
// ex. MOV1 [3], R1 : M[3] <- R1
} else if( m_decode_unit.get_opcode() == MOV1 ) {
    unsigned int reg_n = m_decode_unit.get_op1();
    unsigned int mem_addr = m_decode_unit.get_op2() & 0xFF;
    int Rn = m_regs.read_from_reg(reg_n);
    m_mems.write_on_memory(mem_addr, Rn);
   m_regs.set_PC(m_regs.get_PC()+1);
    return true;
  // ex. MUL RO, R1 --> RO = RO * R1
} else if( m_decode_unit.get_opcode() == MUL) {
    unsigned int reg_n = m_decode_unit.get_op1();
    unsigned int reg_m = (m_decode_unit.get_op2() >> 4) & 0xF;
    int Rn = m_regs.read_from_reg(reg_n);
    int Rm = m_reqs.read_from_req(req_m);
    Rn = Rn * Rm:
    m_reqs.write_on_req(req_n, Rn);
    m_regs.set_PC(m_regs.get_PC()+1);
    return true;
```

CExecute.cpp

```
// ex. JZ RO, #3 (RO == 0, then PC+1+3)
} else if(m_decode_unit.get_opcode() == JZ) {
    unsigned int reg_n = m_decode_unit.get_op1();
               int offset = m_decode_unit.get_op2();
    int Rn = m_regs.read_from_reg(reg_n); 현재 명령어 실행 후 m_regs.set_PC(m_regs.get_PC()+1); 자동적으로 PC++
    if( Rn == 0 ) {
         int pc = m_regs.get_PC(); Rn값이 Zero이면, m_regs.set_PC(pc+offset); PC←PC+offset
    return true;
} else {
    cout << "Not executable instruction, not yet implemented, sorry !!. " << endl;
    return false;
```

테스트 코드

file.bin

```
MOV3 RO, #1
MOV3 R1, #1
MOV3 R2, #2
MOV3 R3, #0
    R3, R2
ADD
ADD R3, R2
SUB
    R3. R1
MOV1 [1]. R3
MOV0 R7, [1]
MOV1 [4], R2
MOV0 R8, [4]
MOV3 R14, #7
MOV3 R15, #1
     R15, R14
MOV3 R13, #-1
MOV3 R12, #-2
MOV1 [255], R12
MOV1 [254], R13
MOV0 R11, [254]
```

```
00110000000000001
0011000100000001
0011001000000010
0011001100000000
0100001100100000
0100001100100000
0101001100010000
0001001100000001
0000011100000001
0001001000000100
0000100000000100
0011111100000001111
00111111100000001
01001111111100000
00111101111111111
0011110011111110
00011100111111
0001110111111110
0000101111111110
```

```
MOV3 RO. #0
     .3 MOV3 R1. #1
PC T
      4 MOV3 R2, #2
      5 MOV3 R3, #0
+5¦
      6 ADD R3, R2
      7 ADD R3, R2
       SUB R3, R1
      9 MOV1 [1], R3
    10 MOV0 R7, [1]
     11 MOV1 [4], R2
     12 MOVO R8, [4]
     13 MOV3 R14, #7
     14 MOV3 R15, #1
     15 ADD R15, R14
     16 MOV3 R13, #-1
     17 MOV3 R12, #-2
     18 MOV1 [255], R12
     19 MOV1 [254], R13
     20 MOVO R11, [254]
```

```
00110000000000000
2 0110000000000101
 3 0011000100000001
 4 0011001000000010
 5 0011001100000000
 6 0100001100100000
7 0100001100100000
8 0101001100010000
9 0001001100000001
10 0000011100000001
11 0001001000000100
12 0000100000000100
13 00111111000000111
14 00111111100000001
15 01001111111100000
16 00111101111111111
17 001111100111111110
18 0001110011111111
  0001110111111110
  0000101111111110
```

TPU 실행

main.cpp

```
28
       CT1DecodeDirectFetch decode(code_memory);
29
       C16RegisterFile
                             regs;
       CSRAM_256W
30
                             mems;
31
32
                             execute(decode, regs, mems);
       CT1ExecuteTinyUnit
33
34
       int size = atoi(argv[2]);
    // for(int i=0; i<atoi(argv[2]); i++) {
       while( regs.get_PC() < size ) {
36
37
           decode.do_fetch_from(regs.get_PC());
38
         //decode.do_fetch_from(i);
39
           decode.do_decode();
40
           decode.show_instruction();
41
42
43
44
45
           execute.do_execute();
       cout << "After executing instruction ..." << endl;</pre>
46
       regs.show_regs();
47
48
       //mems.show_mems(0, 9);
49
       //mems.show_mems(250, 255);
50
51
       mems.show_mems(0, 15);
52 }
```

실행결과

```
MOV3 RO, #1
JZ
     RO, 5
                     JZ
MOV3 R1, #1
                     SUB
MOV3 R2. #2
MOV3 R3, #0
     R3, R2
ADD.
     R3. R2
ADD
SUB
     R3. R1
     [1]. R3
MOV1
MOVO R7, [1]
                     ADD
MOV1 [4], R2
MOVO R8, [4]
MOV3 R14, #7
MOV3 R15, #1
ADD
     R15, R14
MOV3 R13, #-1
                     . .
MOV3 R12, #-2
MOV1
     [255], R12
MOV1
     [254]. R13
MOVO R11, [254]
```

```
MOV3 RO,
         #0
     RO,
     R3,
     Г1].
MOV1
MOVO R7,
MOV1
     [4].
MOVO R8. [4]
MOV3 R14, #7
MOV3 R15, #1
     R15. R14
MOV3
     R13, #-1
|MOV3 R12. #-2
     [255], R12
MOV1
MOV1
     [254].
MOVO R11, [254]
```

Makefile

```
1 all:
2   g++ -o tpu CCode.cpp CDecode.cpp CExecute.cpp CRegist
   er.cpp CMemory.cpp main.cpp
3
4 # ./tpu file.bin 19
5 # ./tpu matrix.bin 40
6   ./tpu file2.bin 20
7
```

Q&A

Thank you for your attention

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