Lecture 19: Timing Analysis – I

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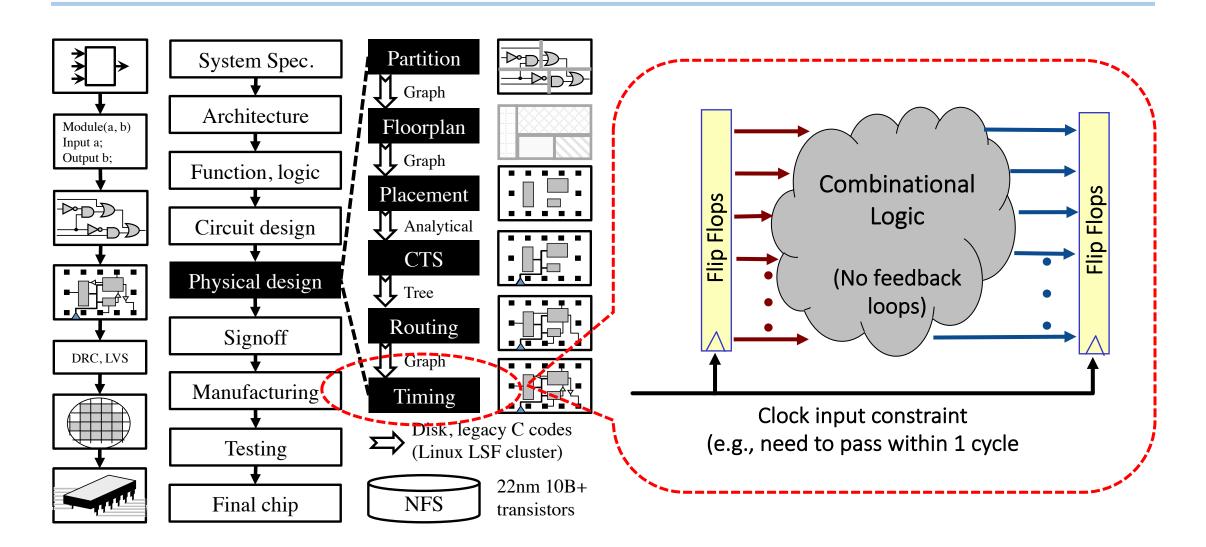
University of Utah, Salt Lake City, UT



In-class Presentation: 12/7

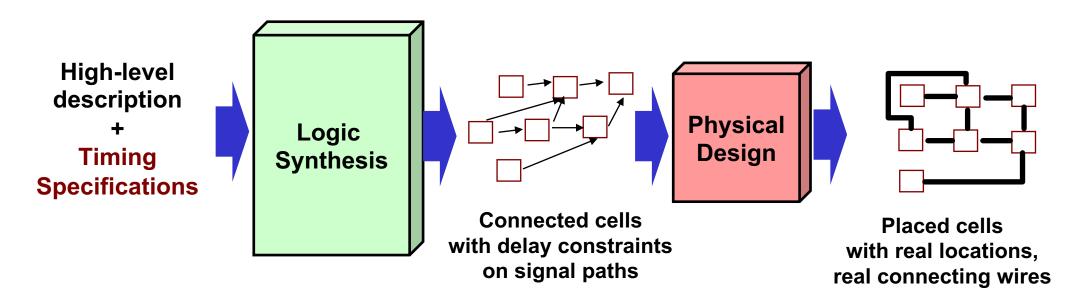
- Circuit partition research presentation on 9/14 (in class)
 - Shiju Lin, Jinwei Liu, and Martin D F Wong, "GAMER: GPU-accelerated Maze Routing", IEEE/ACM ICCAD, 2021
 - Zizheng Guo, Feng Gu, and Yibo Lin, "GPU-Accelerated Rectilinear Steiner Tree Generation," IEEE/ACM ICCAD, 2022
 - Siting Liu, Yuan Pu, Peiyu Liao, Hongzhong Wu, Rui Zhang, Zhitang Chen, Wenlong Lv, Yibo Lin, Bei Yu, "FastGR: Global Routing on CPU-GPU with Heterogeneous Task Graph Scheduler," *IEEE TCAD*, 2022.
- Upload your pptx to https://github.com/tsung-wei-huang/ece5960-physical-design/issues/14 before presentation

Physical Design Flow



Timing Analysis in Design Automation

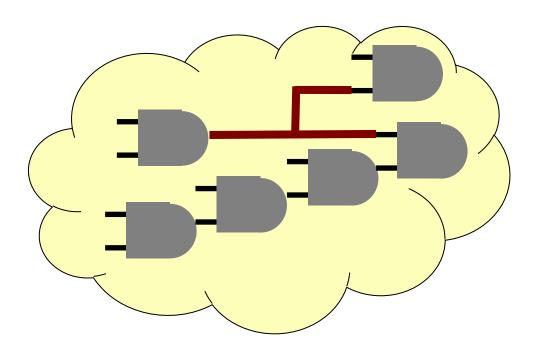
Deep interactions between logic synthesis and layout



- Important facts
 - Logic-side tools estimate delays through unplaced/unrouted logic
 - Layout tools estimate delays through placed/routed logic

Logic-Side Timing Analysis

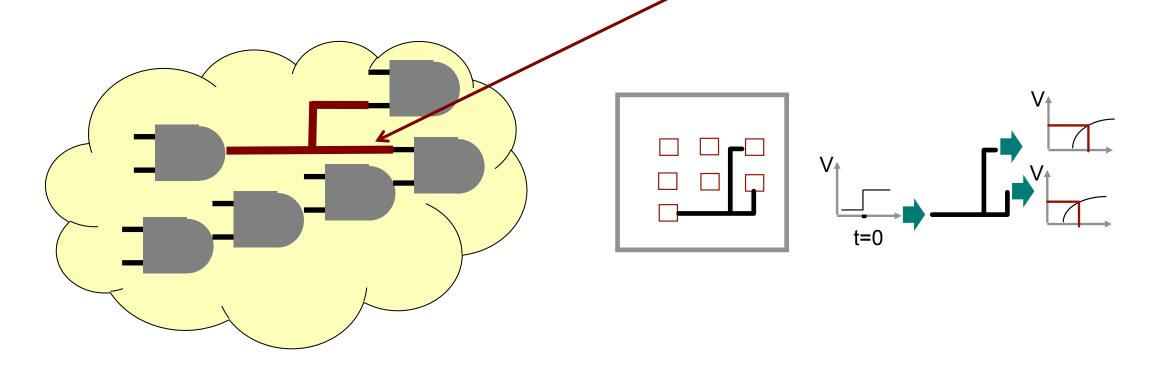
Logic-side: How do we estimate the worst-case timing through a logic network?



Layout-Side Timing Analysis

Logic-side: How do we estimate the worst-case timing through a logic network?

Layout-side: We place the gates, route the wires: how do we estimate wire delays?



Big Picture

On the logic side:

 All problems look like longest (or shortest) paths through a graph that properly models the gates, and (maybe) the wires

On the layout side:

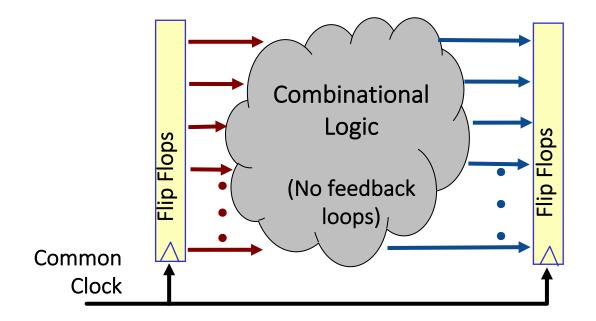
- The problem starts as an electrical circuit model (this is unavoidable)
- However, we skip circuit details, and just show key results
- Surprisingly, both problems can be <u>easily and efficiently</u> solved using shortest path algorithms!

Timing Analysis at Logic Level

- Goal: Verify timing behavior of our logic design
 - I give you a gate-level netlist
 - I give you some timing models of the gates and (after place/route) the wires too
 - You tell me:
 - When signals arrive at various points in the network
 - Longest delays through gate network
 - Does the netlist satisfy the timing requirement? If not where are key problems?
- Challenge: How do you estimate the timing correctly?
 - We can't! But we know the worst and best-case timing

Analyze Design Performance

- Practical designs are synchronous
 - All storage is in explicit sequential elements, e.g., flip-flop elements
 - We can just focus on delays through combinations gates



Can't We Just Simulate Logic?

What logic simulation does

- Determine how a system will behave, simulates the logical function
- Gives the most **accurate** answer (with good simulation models)
- ... but it is (practically) impossible to give a complete answer especially timing

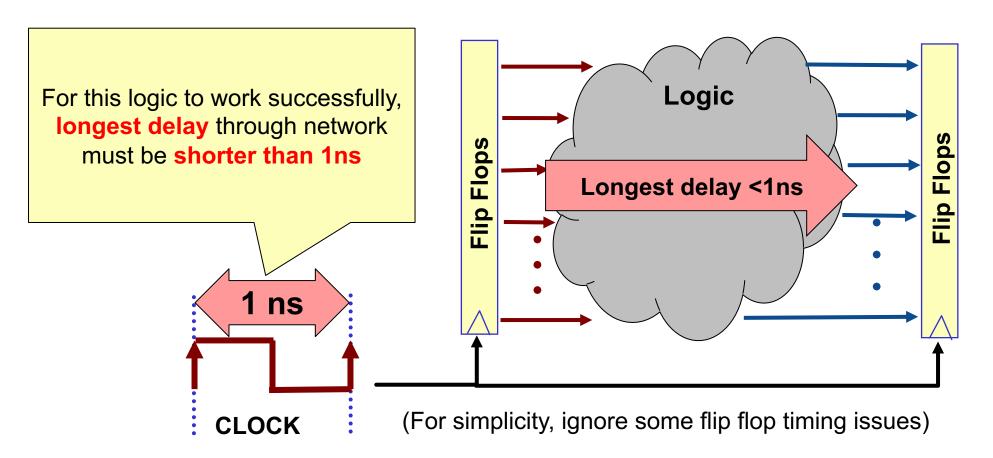
Requires examination of an exponential number of cases

- All possible input vectors ...
- With all possible relative timings ...
- Under all possible manufacturing variations ...

We need a different, faster solution

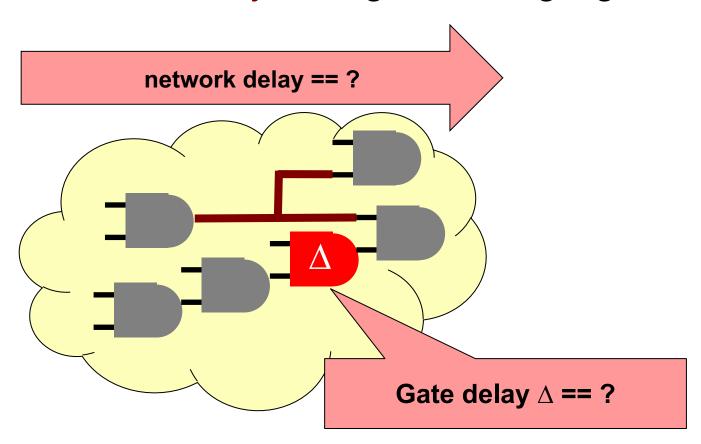
Timing Analysis: Basic Model

• Assume we know clock cycle: e.g., 1GHz clock, cycle = 1ns



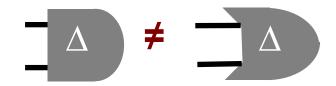
Timing Analysis: Basic Model (cont'd)

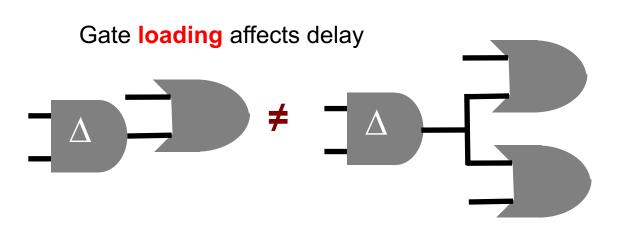
We need a model of delay through each logic gate



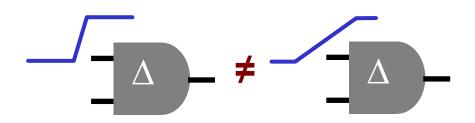
In the Real World ...

Gate type affects delay

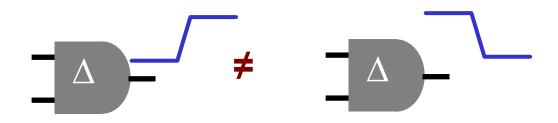




Waveform shape affects delay

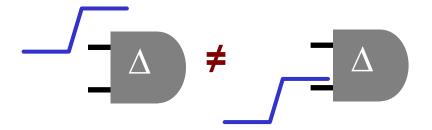


Transition direction affects delay

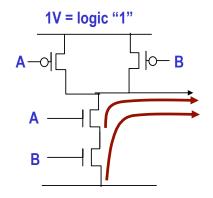


In the Real World ... (cont'd)

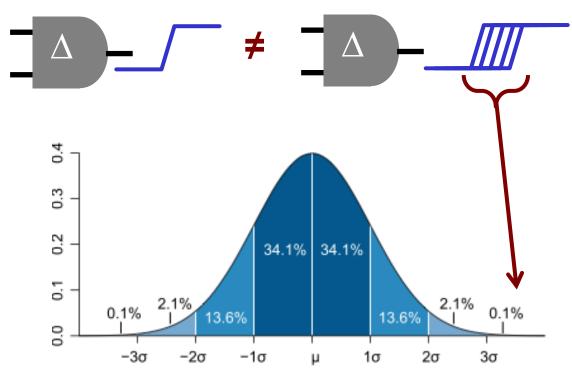
Gate input pin affects delay



Why? Different transistor-level circuit paths input to output Simple ex: NAND



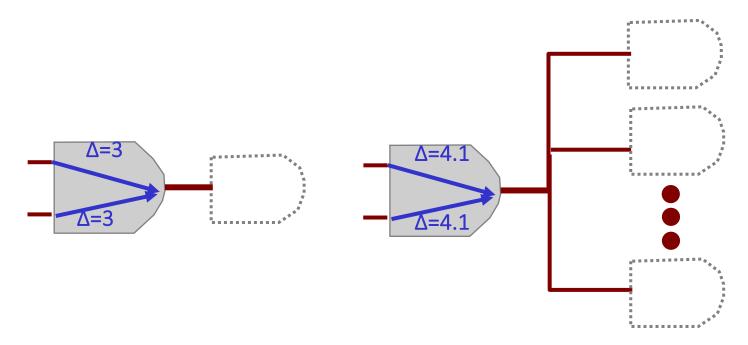
At nanoscale, delays are really statistical



http://upload.wikimedia.org/wikipedia/commons/8/8c/Standard deviation diagram.svg

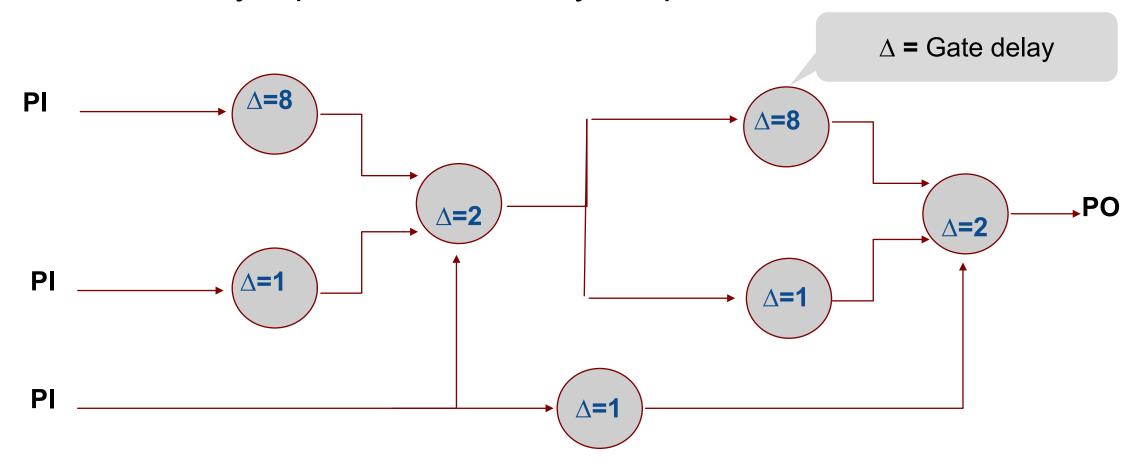
Our Model: Pin-to-Pin Delay

- We will keep it simple: Fixed, pin-to-pin delay model
 - No slopes, electricity, distributions, etc. Just gate delay itself!
 - Per-pin delays are essential, but we'll use just 1 value per gate
 - Turns out this is enough to see all the interesting algorithm ideas

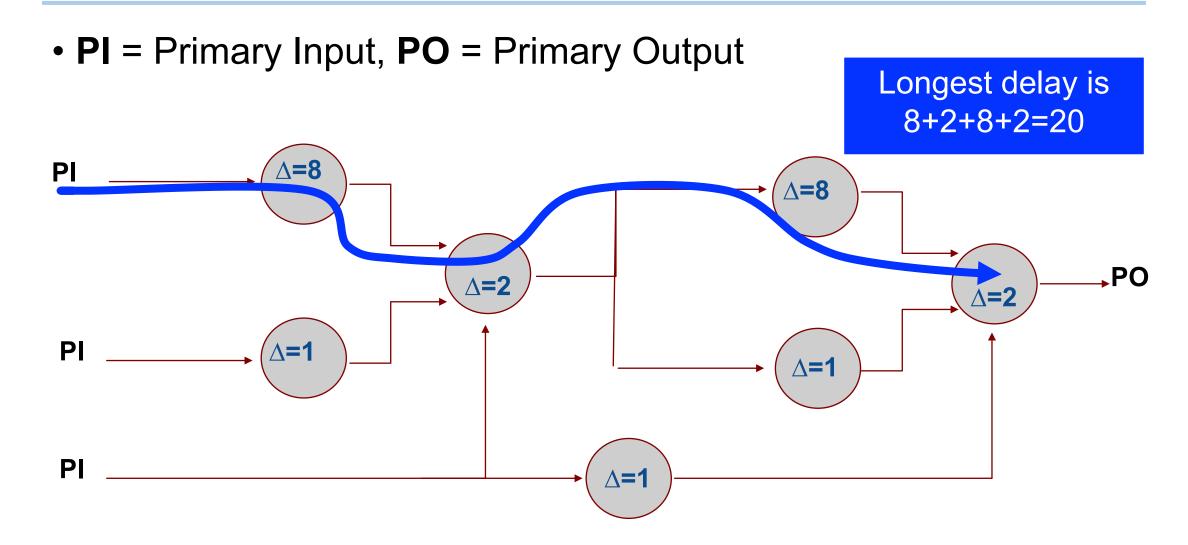


Example

• PI = Primary Input, PO = Primary Output



Example (cont'd)

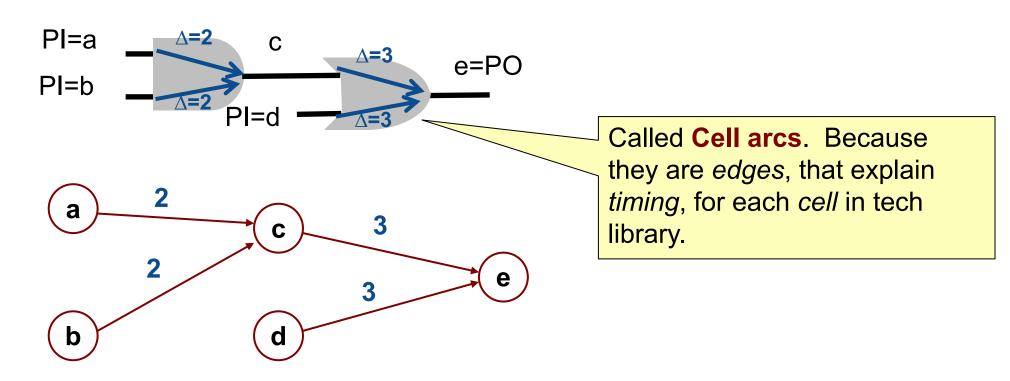


Static Timing Analysis (STA)

- When we ignore logic, this is called Topological Analysis
 - We only work with the graph and the delays don't consider the logic
 - We can get wrong answers: what we found was called a False Path
- Going forward: we ignore the logic
 - Assume that all paths are statically sensitizable
 - **Means**: Can find a constant pattern of inputs to *other* PIs that makes some output sensitive to some input
- This timing analysis is called Static Timing Analysis (STA)
 - Consider only the best- and worst-case timing results
 - Consider no logic (otherwise called dynamic timing analysis)

STA Representation: Delay Graph

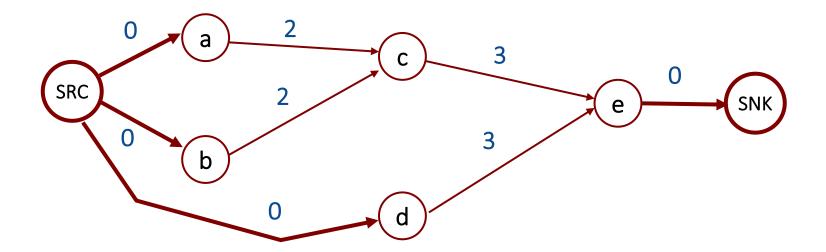
- From gate-level network, we build a delay graph
 - Vertices: Wires in gate network, 1 per gate output, 1 for each PI and PO
 - Edges: Gates, input pin to output pin (1 edge per input). Put gate delays on edges



Source and Sink in Delay Graph

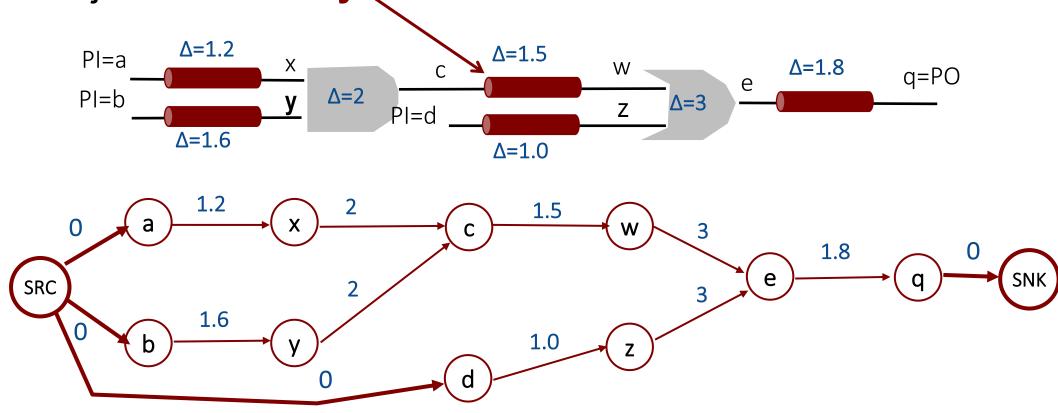
Common convention: Add Source / Sink nodes

- Add 1 "source" (SRC) node that has a 0-weight edge to each PI
- Add1 "sink" (SNK) node with 0-weight edge from each PO
- Why do this?
 - Now, the network has exactly 1 "entry" node, and 1 "exit" node
 - All the longest (or shortest) path question have same start / end nodes



What about Interconnect among Gates?

• Can still use delay graph: model each wire as a "special" gate that just has a delay



Operations on Delay Graph

- So how do we use this graph to do timing analysis?
 - What we do **not** do: Try to *enumerate* all the source-to-sink paths
 - Why not? Exponential explosion in number of paths, even for small graph

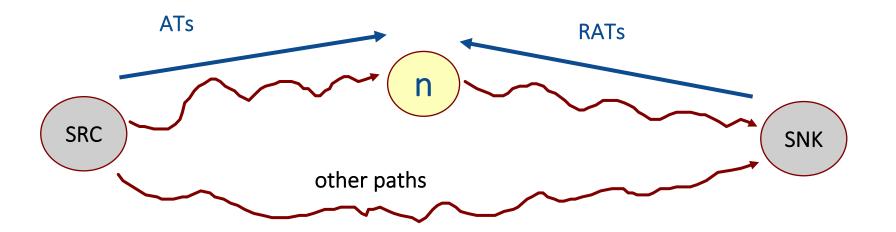


- There's a smarter answer: Node-oriented timing analysis
 - Find, for each node in delay graph, worst delay to the node along any path

Define Values on Nodes in Delay Graph

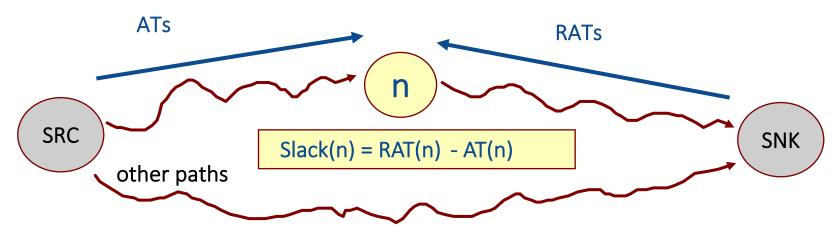
- Arrival Time at a node (AT)
 - AT(n) = Latest time the signal can become stable node n
 - Think: Longest path from source
 - Called: Delays TO node

- Required Arrival Time at node (RAT)
 - RAT(n)=Latest time the signal is allowed to become stable at node n
 - Think: Longest path to sink (sort of...)
 - Called: Delays FROM node



Measure Timing Margin at a Node

- Slack at node n: Slack(n) = RAT(n) AT(n)
 - Amount of timing "margin" for the signal: positive is good, negative is bad
 - Determined by longest path through node
 - Amount by which a signal can be delayed at node and not increase the longest path through the network
 - Can increase delay at node (to minimize power, circuit area) with positive slack and not degrade overall performance



Slack is Important in Timing Analysis

About slacks

- Defined so negative slack always bad --, it indicates a timing problem
- Measures "sensitivity" of network to this node's delay

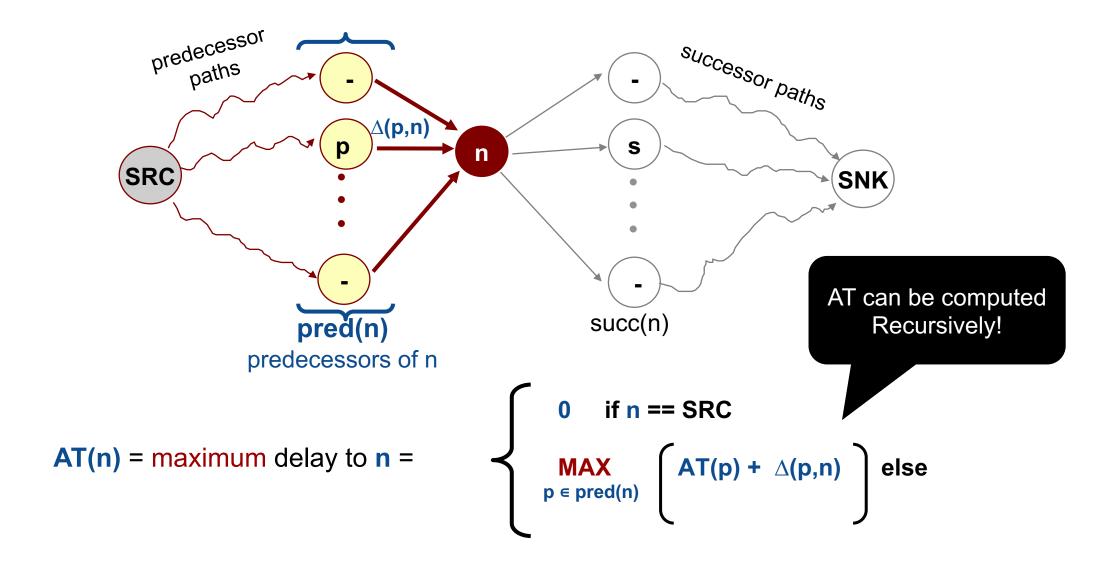
Positive slack

- Good: I can change something at this node, and not hurt network's overall timing
- Example: I can make this node slower, maybe save some power, not hurt timing

Negative slack

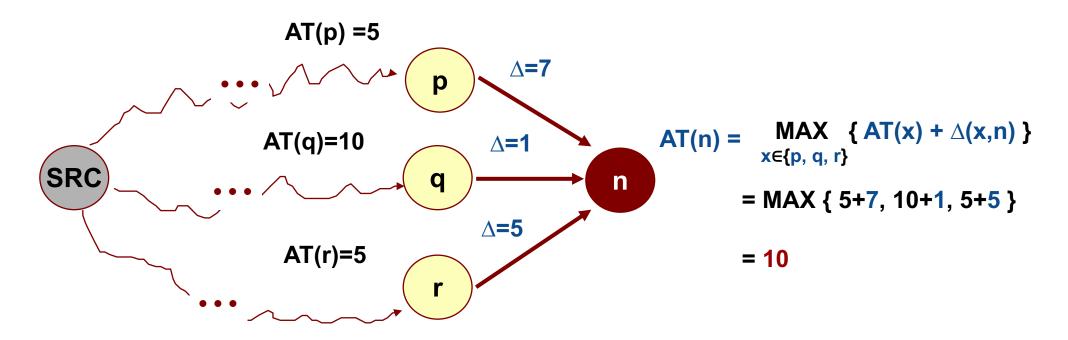
- Bad: I have problem at this node; more negative the slack, bigger the problem
- Looking for a node to "fix" to help timing? These nodes are where to look first. These affect my critical paths the most

How to Compute Arrival Time (AT)?

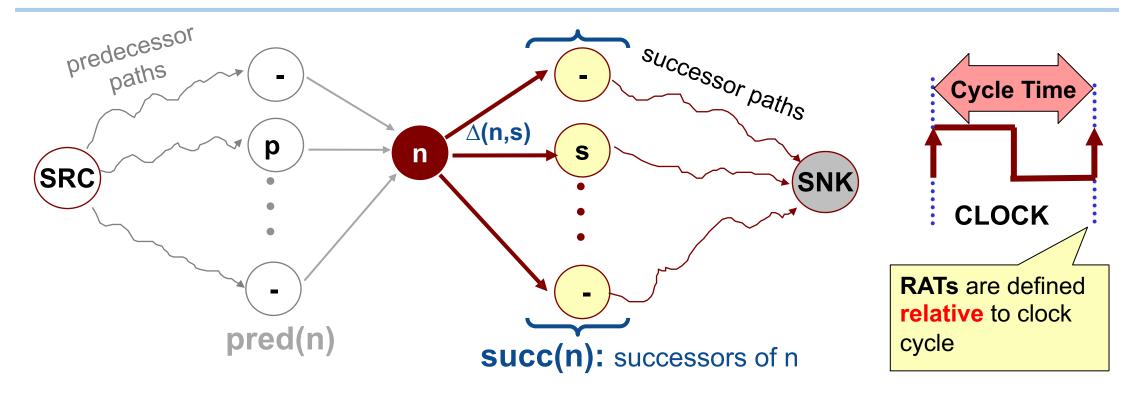


Example: Compute AT

• If we know the longest path to each predecessor of **n**, it's a simple "Maximum" operation to compute the longest path to **n** itself—Yes, it is shortest-path algorithm again!



How to Compute Required Arrival Time (RAT)?



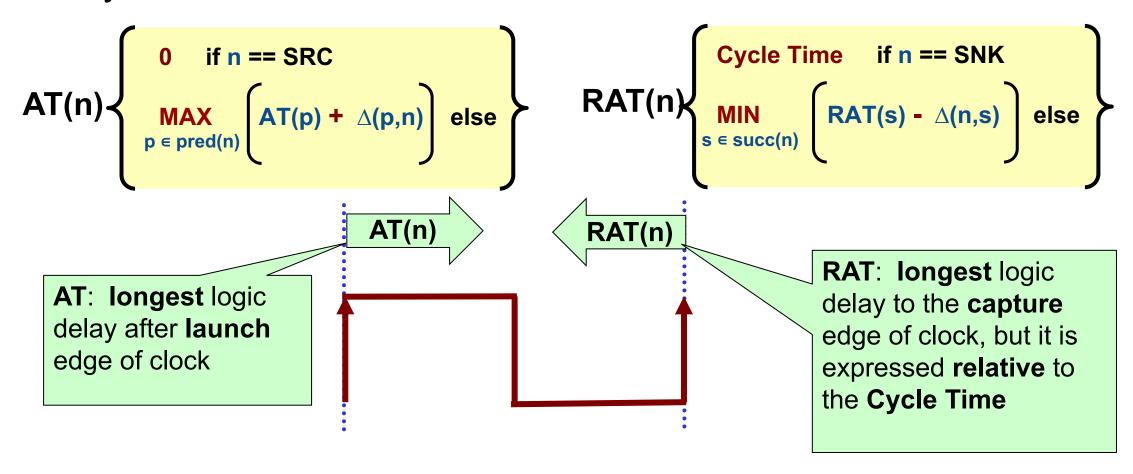
RAT(n) =

Latest time in cycle where n could change and signal would still propagate to sink before end of cycle

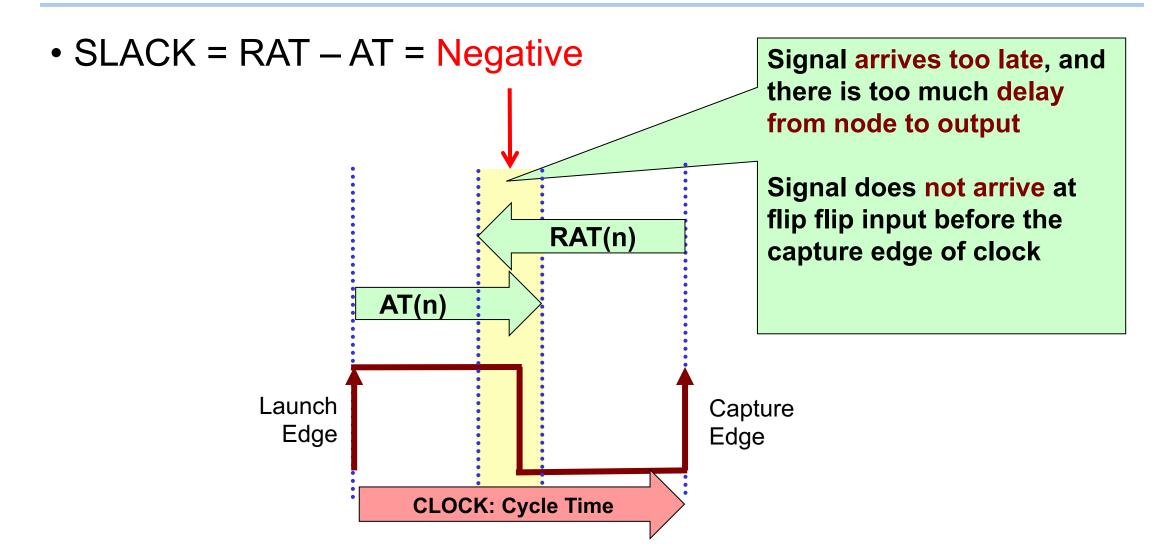
$$= \left\{ \begin{array}{ll} \text{Cycle Time} & \text{if n == SNK} \\ \\ \text{MIN} \\ \text{s \in succ(n)} \end{array} \right. \left(\begin{array}{ll} \text{RAT(s) - } \Delta(\text{n,s}) \\ \end{array} \right) \text{else}$$

ATs vs RATs: Look at the Clock Cycle

Why the difference between ATs and RATs?

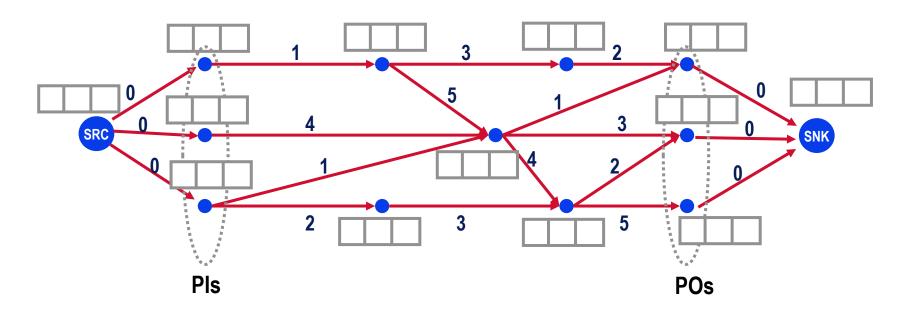


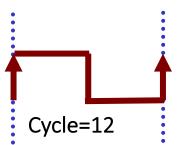
Bad Things Happen When We See This



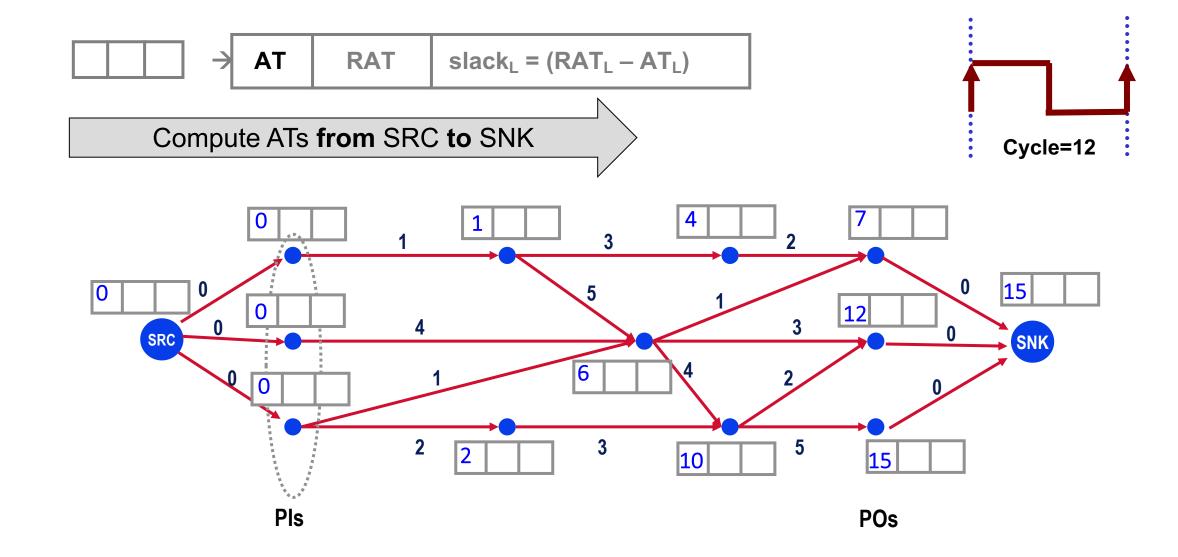
Let's Do a Bigger Example

- Delays are on edges; let clock cycle be 12
 - Compute the min/max delays "by eye" for now
 - AT=longest path from SRC TO node;
 - RAT=(cycle time 12) (longest path FROM node to SNK)
 - Slack = RAT AT

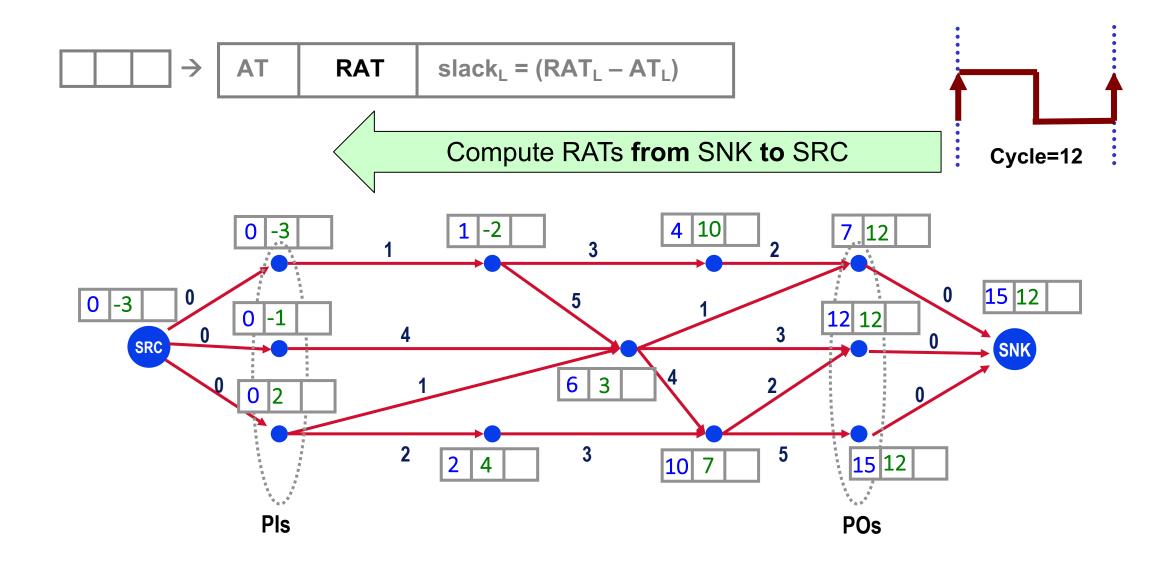




Compute ATs ...



Compute RATs ...

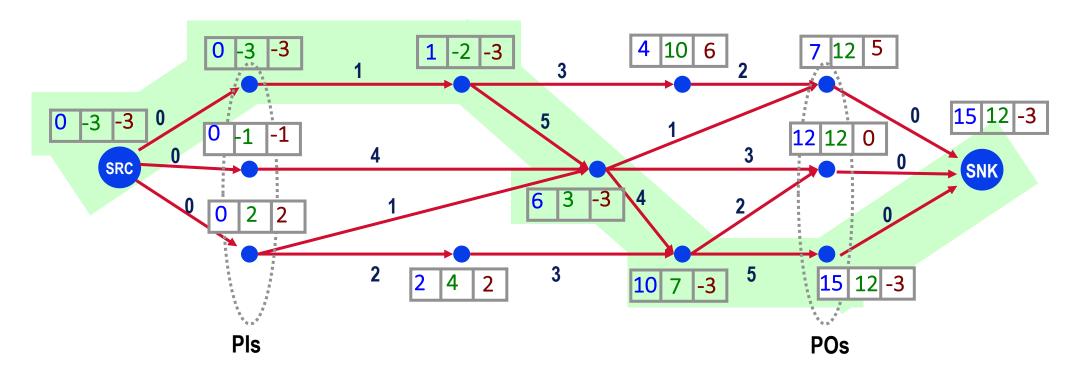


Compute Slacks ...



Cycle=12

Worst (most negative slack) is -3. Trace worst path, SRC→SNK



Debrief

Look at those slacks

- A negative slack at an output (PO) means a missed requirement
- A negative slack on internal node n means it feeds a problem PO
 - So, there is a path from n to some problem PO

Key: negative slack appears along this entire worst path

- Your worst timing violation at an output (PO) = the most negative slack value
- You can always trace a path with this slack value back to a PI

So, slacks are hugely useful

 Beyond just knowing what is the worst path; slacks tell us problem gates on this path

Summary

- We have discussed the timing analysis problem
- We have discussed the static timing analysis (STA) model
- We have discussed computational models to STA
- We have discussed measurement of STA results