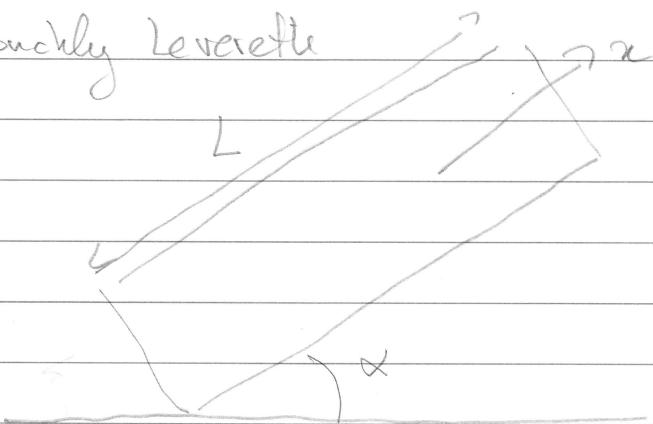


①

Buckley Leverette

Darcy's equations:

$$g_o = -\frac{k kro A}{\mu_o} \left(\frac{\partial P_o}{\partial x} + g_o g \sin \alpha \right)$$

$$g_w = -\frac{k krw A}{\mu_w} \left(\frac{\partial P_w}{\partial x} + g_w g \sin \alpha \right)$$

$$\begin{aligned} P_w &= P_o - P_{cow} \\ \therefore g_w &= -\frac{k krw A}{\mu_w} \left(\frac{\partial (P_o - P_{cow})}{\partial x} + g_w g \sin \alpha \right) \end{aligned}$$

After some rearranging:

$$\left. \begin{aligned} -g_o \frac{\mu_o}{k kro A} &= \frac{\partial P_o}{\partial x} + g_o g \sin \alpha \end{aligned} \right\}$$

$$\left. \begin{aligned} -g_w \frac{\mu_w}{k krw A} &= \frac{\partial P_o}{\partial x} - \frac{\partial P_{cow}}{\partial x} + g_w g \sin \alpha \end{aligned} \right\}$$

$$\Rightarrow -\frac{1}{k A} \left(g_w \frac{\mu_w}{k krw} - g_o \frac{\mu_o}{k kro} \right) = -\frac{\partial P_{cow}}{\partial x} + \Delta g g \sin \alpha$$

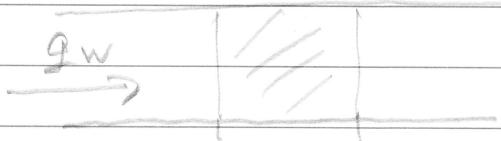
where $\Delta g = g_w - g_o$

(2)

Introducing $q = q_o + q_w$

$$f_w = \frac{g_w}{g} = \frac{\frac{k_w \mu_w}{\mu_w + \mu_o}}{1 + \frac{k_w k_o A}{g \mu_o} \left(\frac{\partial P_{con} - \Delta g S_{max}}{\partial x} \right)}$$

Derivation Buckley Leverett equation:



Mass balance:

$$\begin{aligned} & [(q_w \beta_w)_x - (q_w \beta_w)_{x+\Delta x}] \cdot \Delta t \\ &= A \Delta x \phi \left[(S_w \beta_w)_{t+\Delta t} - (S_w \beta_w)_t \right] \end{aligned}$$

$$\Rightarrow A \phi \frac{\partial (S_w \beta_w)}{\partial t} + \frac{\partial (q_w \beta_w)}{\partial x} = 0$$

Assuming incompressible fluids: $\frac{\partial \beta_w}{\partial x} = 0$; $\frac{\partial \beta_w}{\partial t} = 0$

$$\Rightarrow A \phi \frac{\partial S_w}{\partial t} + \frac{\partial q_w}{\partial x} = 0$$

$$q_w = f_w \cdot q ; q = \text{constant}$$

$$\Rightarrow A \phi \frac{\partial S_w}{\partial t} + \frac{\partial f_w(S_w)}{\partial x} = 0$$

$$\Rightarrow \boxed{A \phi \frac{\partial S_w}{\partial t} + \frac{\partial f_w}{\partial S_w} \frac{\partial S_w}{\partial x} = 0}$$

(3)

Buckley leverett (assuming $\frac{\partial P_{\text{cow}}}{\partial x} = 0$)

$$\left\{ \begin{array}{l} \frac{d}{dt} \frac{\partial S_w}{\partial t} + \frac{\partial f_w}{\partial S_w} \frac{\partial S_w}{\partial x} = 0 \quad x \in [0, L] \\ q \end{array} \right.$$

$$S_w(x, 0) = S_{wi} \quad x \in [0, L]$$

$S_w(0, t) = S_{wij}$ such that $f_w(S_{wij}) = \text{injected water cut}$

$$\text{with } f_w(S_w) = \frac{q_w}{q} = \frac{k_{rw}/\mu_w}{k_{rw} + k_{ro}} \left\{ 1 - \frac{k_{ro} A}{q \mu_o} \Delta p_{\text{smx}} \right\}$$

$$\Delta p = f_w - f_o$$

N.B.: q_w and q are subsurface water and total rates

Parametrization of relperms:

$$\left\{ \begin{array}{l} k_{rw}(S_w) = k_{rw}^e S^{nw} ; \quad k_{ro} = k_{ro}^e (1-S)^{no} \\ \text{with } S = \frac{S_w - S_{ow}}{1 - S_w - S_{ro}} \end{array} \right.$$

Introduce:

$$\text{End point mobility ratio : } M = \frac{k_{rw}^e}{\mu_w} / \left(\frac{k_{ro}^e}{\mu_o} \right)$$

$$\text{Dimensionless gravity number : } N_A = \frac{k \cdot k_{ro}^e g \Delta p}{\mu_o} \frac{A}{q}$$

$$f_w(S_w) = \frac{M S^{nw}}{(1-S)^{no} + M S^{nw}} \left\{ 1 - N_A (1-S)^{no} \Delta p_{\text{smx}} \right\}$$

$$\text{with } S = \frac{S_w - S_{ow}}{1 - S_{ow} - S_{ro}}$$

(4)

Introducing dimensionless variables:

$$x_p = \frac{x}{L} \rightarrow t_p = \frac{q \cdot t}{q A L} = \frac{\beta}{V_p} ; V_p = q A L$$

$\beta = \text{pore volume}$
 $V_p = \text{injected volume}$

$$\left\{ \begin{array}{l} \frac{\partial S_w}{\partial t_p} + \frac{\partial f_w}{\partial S_w} \frac{\partial S_w}{\partial x_p} = 0 \end{array} \right.$$

$$\left\{ \begin{array}{l} S_w(x_p, 0) = S_{wi} \\ S_w(0, t_p) = S_{wini} \end{array} \right.$$

We absorb smax into N_A : $\tilde{N}_A = N_A \cdot s_{max}$

$$f_w(S_w) = \frac{MS^{nw}}{(1-S)^{no} + MS^{nw}} \left\{ 1 - \tilde{N}_A (1-S)^{no} \right\}$$

$$\frac{\partial f_w(S_w)}{\partial S_w} = \frac{\partial S}{\partial S_w} \frac{\partial f_w}{\partial S} = \frac{1}{1-S_{wini}-S_{wini}} \frac{\partial f_w}{\partial S}$$

$$\frac{\partial f_w}{\partial S} = \frac{MS^{nw-1} (1-S)^{no-1} f_{nw} (1-S) + noS^1 \left\{ 1 - \tilde{N}_A (1-S)^{no} \right\}}{(1-S)^{no} + MS^{nw}/2}$$

$$+ \frac{MS^{nw}}{(1-S)^{no} + MS^{nw}} \tilde{N}_A no (1-S)^{no-1}$$

(5)

$$\frac{\partial^2 f_w}{\partial S_w^2} = \left(\frac{\partial f_w}{\partial S_w} \right)^2 \frac{\partial^2 f_w}{\partial S^2} = \frac{1}{(1-S_w-S_{nw})^2} \frac{\partial^2 f_w}{\partial S^2}$$

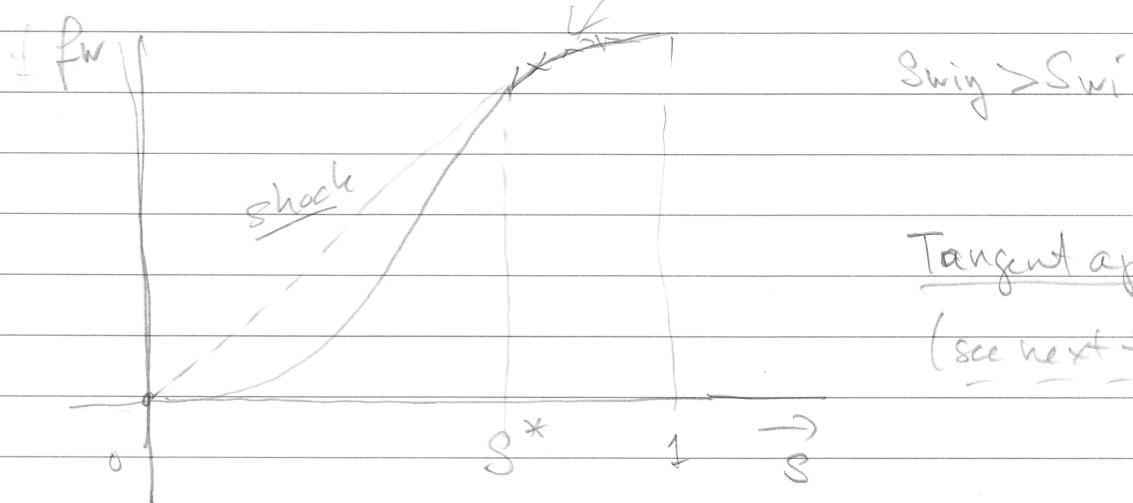
$$\frac{\partial^2 f_w}{\partial S^2} = \frac{M}{\{(1-s)^{n_0} + M s^{n_w}\}^3} \cdot (1-s)^{n_0-2} s^{n_w-2} \times \{ 1 - \tilde{N}_A (1-s)^{n_0} \}$$

$$\begin{aligned} & \times \left\{ (1-s)^{n_0} \left[n_w^2 (1-s)^2 + n_0 (1+n_0) s^2 + n_w (1-s) (-1 + (1+2n_0)s) \right] \right. \\ & \left. - M s^{n_w} \left[n_w^2 (1-s)^2 + n_0 (n_0-1) s^2 + n_w (1-s) (1 + (2n_0-1)s) \right] \right\} \\ & + 2 M s^{n_w-1} (1-s)^{n_0-1} \{ n_w (1-s) + n_0 s \} \cdot \tilde{N}_A \cdot n_0 (1-s)^{n_0-1} \end{aligned}$$

$$\frac{- M s^{n_w}}{(1-s)^{n_0} + M s^{n_w}} \tilde{N}_A n_0 (n_0-1) (1-s)^{n_0-2}$$

(6)

Solution : ($\nu_{\infty} = 0$) rarefaction



$$\text{Shock: } \frac{\partial f(s^*)}{\partial s} = \frac{f(s^*) - f(s_{w_i})}{s^* - s_{w_i}} = N : \text{shock velocity.}$$

$$\text{Rarefaction: } s_{w_i}(x, t) = R(\gamma), \quad \gamma = \frac{x}{t}$$

can be found by inverting the relation: $\frac{\partial f}{\partial s_{w_i}}(R(\gamma)) = \gamma$

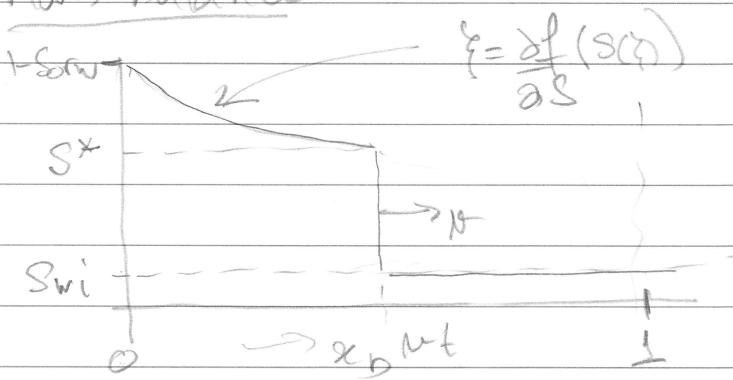
or by solving

$$\frac{ds_{w_i}(\gamma)}{d\gamma} = \left(\frac{\partial^2 f_w}{\partial s^2} \right)^{-1}$$

(7)

Why tangent condition for Buckley Leverett?

Mass balance:



$$\bar{S}_{wf}(t) = \int_0^{x_b^vt} S(x,t) dx = \int_0^{x_b^vt} S(x,t) dx + \int_{S_wi}^{S(x,t)} S_{wi} dx$$

$$= t \int_{\gamma=0}^{\gamma=v} S(\gamma) d\gamma + S_{wi}(1-vt)$$

$$\gamma = \frac{x}{t} \quad \gamma = v$$

$$S(\gamma=0) \parallel \frac{df}{ds}$$

$$= t S(\gamma=0) v - t \int_{S(\gamma=0)=1-S_{wi}}^{\gamma} \gamma dS + S_{wi}(1-vt) =$$

$$= t S(\gamma=v) v - t \int_{S(\gamma=0)=1-S_{wi}}^v \frac{df}{ds} dS + S_{wi}(1-vt)$$

$$= t S(\gamma=v) v + t [1 - f(S(\gamma=v))] + S_{wi}(1-vt)$$

Net injected water: $V_w = [1 - f(S_{wi})] \cdot V_{pt} = [1 - f(S_{wi})] V_{pt}$

$$\bar{S}_{wf}(t) = \frac{S_{wi} V_p + V_w}{V_p} = S_{wi} + [1 - f(S_{wi})] t$$

(8)

Equating the two expressions:

$$S_{wi} + (S(\gamma=0) - S_{wi}) \nu + [1 - f(S(\gamma=0))] +$$

$$= S_{wi} + [1 - f(S_{wi})] +$$

$$\Rightarrow (S(\gamma=0) - S_{wi}) \nu = f(S(\gamma=0)) - f(S_{wi})$$

$$\Rightarrow \nu = \frac{f(S(\gamma=0)) - f(S_{wi})}{e(\gamma=0) - f(S_{wi})}$$

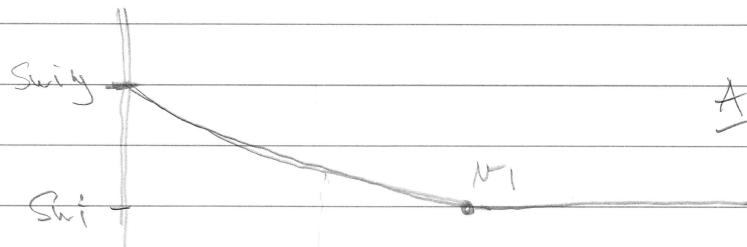
$$\text{we also have } \gamma = \nu = \frac{df(S(\gamma=0))}{ds}$$

$$\Rightarrow \frac{df(s)}{ds} = \frac{f(s) - f(S_{wi})}{s - S_{wi}} : \text{tangent condition}$$

(9)

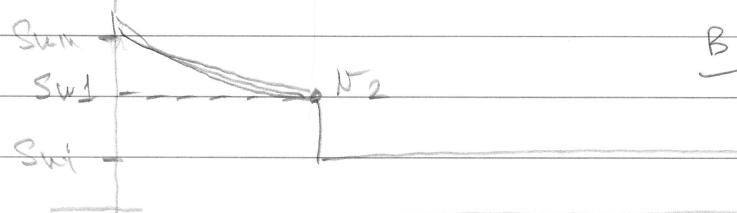
Types of possible solutions

Case 1:



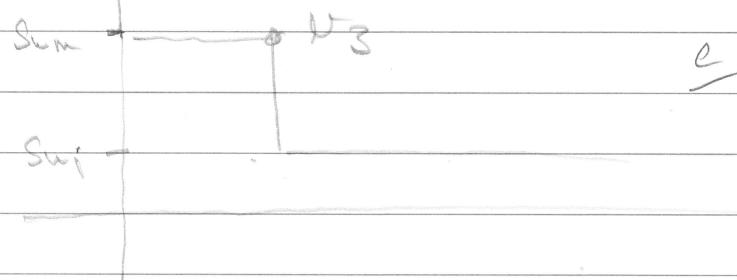
A

$$n_1 = \frac{\partial f(Sw)}{\partial Sw}$$



B

$$n_2 = \frac{f(Sw_1) - f(Sw_i)}{Sw_1 - Sw_i} = \frac{\partial f(Sw)}{\partial Sw}$$



C

$$n_3 = \frac{f(Sw_m) - f(Sw_i)}{Sw_m - Sw_i}$$

Breakthrough times: $t_{Bi} = \frac{1}{n_i}$

Constrain to cases with $f_n(Swing) = 1$ and $Sw_i < Swing$

Average water saturation:

Before breakthrough: $f_w(Swi) = 1$

$$\text{Influx: } Q_w^m = f_{w,mg} \cdot Q_{tot} = Q_{tot}$$

$$\text{Outflux: } Q_w^{\text{out}} = f_w(Swi) \cdot Q_{tot},$$

$$\text{Net influx} = Q_w^{\text{net}} = Q_w^m - Q_w^{\text{out}} = (1 - f_w(Swi)) \cdot Q_{tot}.$$

$$= (1 - f_w(Swi)) \cdot V_p \cdot t_b$$

$$V_w(t_b) = Sw_i \cdot V_p + Q_w^{\text{net}}(t_b)$$

$$= [Sw_i + (1 - f_w(Swi)) t_b] V_p$$

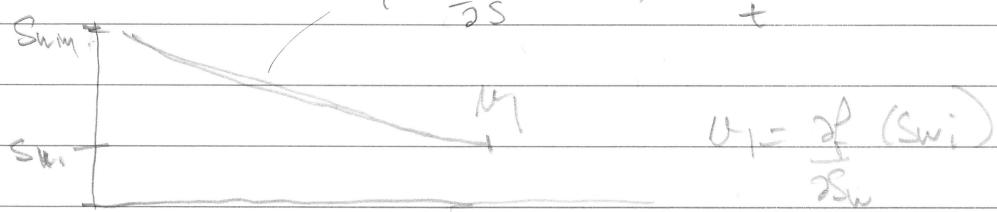
$$\Rightarrow S_w(t_b) = \frac{V_w(t_b)}{V_p} = Sw_i + (1 - f_w(Swi)) \cdot t_b$$

$$\text{NB: if } Sw_i = S_{cw} : S_w(t_b) = Sw_i + t_b$$

(11)

After breakthrough

Case A:



$$\bar{S}_w(t_b) = \int S_w(x, t) dx = t_b \int S(\xi) d\xi =$$

$$= t_b \left[S(\xi=0) \xi \Big|_{\xi=0}^{1/t_b} - \int \xi dS \right]$$

$$= t_b \left[S(\xi=1) \frac{1}{t_b} - \int \frac{dS}{d\xi} d\xi \right]_{\xi=0}$$

$$= t_b \left[\frac{1}{t_b} S(\xi=1) - f(S(\xi=1)) + f(S(\xi=0)) \right]$$

$$= S_w(x=1, t_b) + t_b \left(f(S_w(x=0)) - f(S_w(x=1, t_b)) \right)$$

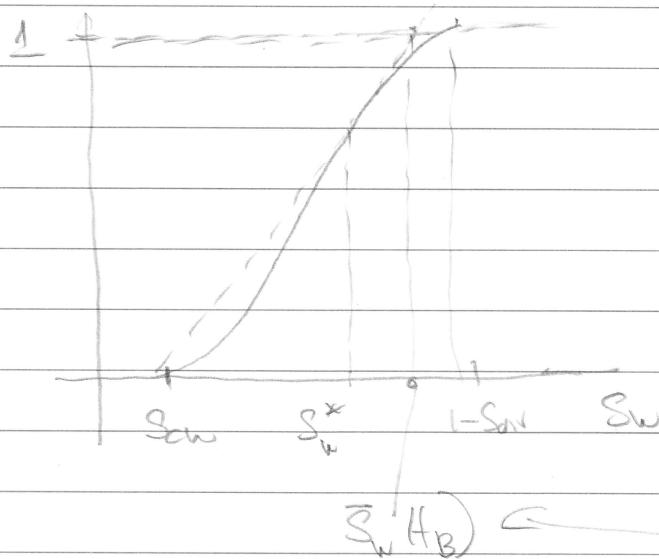
$$= S_w(x_b=1, t_b) + t_b \left[1 - f(S_w(x=1, t_b)) \right]$$

Case B: same as case A

Case C: $\bar{S}_w(t_b) = S_{wij}$

(12)

Graphical technique



For shock saturation S_w^* :

$$\frac{\partial f_w(S_w^*)}{\partial S_w} = \frac{f_w(S_w^*) - f_w(S_{cw})}{S_w^* - S_{cw}}$$

Breadth through time $t_B = \sqrt{\frac{\partial f_w(S_w^*)}{\partial S_w}}$

From p 10: $S_w(t_B) = S_{cw} + \frac{(1 - f_w(S_{cw}))}{\frac{\partial f_w(S_w^*)}{\partial S_w}}$

$$\Rightarrow \frac{\partial f_w(S_w^*)}{\partial S_w} = \frac{(1 - f_w(S_{cw}))}{(S_w(t_B) - S_{cw})}$$

(13)

Generalizing the average S_w calculation to $\text{Swing} \neq 1$

Before breakthrough: (see p 10)

$$\text{Influx: } Q_w^{\text{in}} = f_w(\text{Swing}) \cdot C_{\text{tot}}$$

$$\text{Outflux: } Q_w^{\text{out}} = f_w(\text{Sw}_i) \cdot Q_{\text{bf}}$$

$$V_w(t_b) = [S_{w_i} + (f_w(\text{Swing}) - f_w(\text{Sw}_i)) t_b] V_p$$

$$\Rightarrow \bar{S}_{w(t_b)} = \frac{V_w(t_b)}{V_p} = S_{w_i} + (f_w(\text{Swing}) - f_w(\text{Sw}_i)) t_b$$

After breakthrough. (p 11)

Cases A+B :

$$\bar{S}_{w(t_b)} = S_w(x_b=1, t_b) + t_b [f_w(\text{Swing}) - f(S_w(x=1, t_b))]$$

Case C :

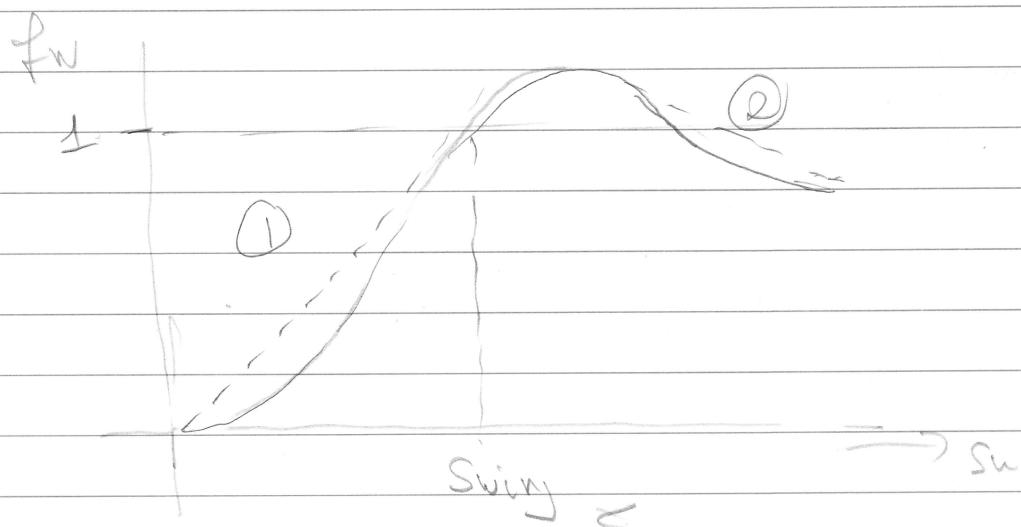
$$\bar{S}_{w(t_b)} = \text{Swing.}$$

Alternative to tangent approach is the convex hull approach:

determine the convex hull of:

$$\{(S_w, y) : S_{wr} \leq S_w \leq S_{wl} \text{ and } y \leq f_w(S_w)\}$$

E.g. for large N_A and negative α :



Two potential shocks.

However: For shock ② we have a negative velocity
 \Rightarrow outflow happens at $x=0$
 \Rightarrow not allowed.

In the code we set Swing such that $f_w(\text{Swing}) = 1$

We have implemented the convex hull approach using ConvexHull from SciPy.