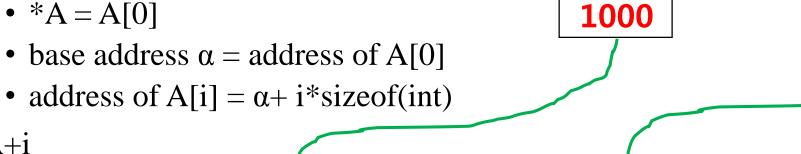
# Chap 2. Arrays and Structures

#### Arrays in C

- int A[7];
- A[0] = 30; ....

| A[0] | A[1] | A[2] | A[3] | A[4] | A[5] | A[6] |
|------|------|------|------|------|------|------|
| 30   | 40   | 10   | 70   | 20   | 60   | 50   |

- A:
  - name of array
  - pointer to A[0]
  - \*A = A[0]



- A+i
  - pointer to A[i]
  - A+i = &A[i]
  - \*(A+i) = A[i]

| 1000 | 1004 | 1008 | 1012 | 1016 | 1020 | 1024 |  |
|------|------|------|------|------|------|------|--|
| 30   | 40   | 10   | 70   | 20   | 60   | 50   |  |
| A[0] | A[1] | A[2] | A[3] | A[4] | A[5] | A[6] |  |

address

A+3 = 1012

#### Dynamic memory allocation of Array

• Static memory allocation

```
int A[7];
A[0] = 30; A[1] = 40; ....
```

| A[0] | A[1] | A[2] | A[3] | A[4] | A[5] | A[6] |
|------|------|------|------|------|------|------|
| 30   | 40   | 10   | 70   | 20   | 60   | 50   |

- Dynamic memory allocation
  - Size of array is variable
  - Avoid waste of space

```
int *A;
A = (int *) malloc(7*sizeof(int));
A[0] = 30; A[1] = 40; ...
```

## Array and structure

```
typedef struct {
                                                  point[]
       int x;
       int y;
} POINT;
                                    point[0]
POINT point[5];
                         3
point[0].x = 2;
point[0].y = 3;
                                                        5
                                      2
                                                                               9
                                                     X
```

# Polynomial

- Example
  - $A(x) = 2x^5 3x^3 + 7x^2 + 10x 1$
- Term
  - Coefficient
  - Exponent
  - Polynomial
    - Collection of terms
    - Collection of <coefficient, exponent> pairs
- Operations on polynomials
  - Add
  - Multiply
  - etc.
- Polynomial representations
  - Array of coefficients with degree (max. exponent)
  - Array of terms

## Array of coefficients with degree

#### Example

• 
$$A(x) = 2x^5 - 3x^3 + 7x^2 + 10x - 1$$

#### Degree

- max. exponent
- degree of A(x) = 5

#### Array of coefficients

• 
$$A(x) = 2x^5 - 3x^3 + 7x^2 + 10x - 1$$
  
=  $2x^5 + 0x^4 - 3x^3 + 7x^2 + 10x^1 - 1x^0$ 

- Values of coefficient array =
  - increasing order {-1, 10, 7, -3, 0, 2} or
  - decreasing order {2, 0, -3, 7, 10, -1}

#### Polynomial

- Degree
- Array of coefficients

| degree | coef[0] | coef[1] | coef[2] | coef[3] | coef[4] | coef[5] |
|--------|---------|---------|---------|---------|---------|---------|
| 5      | -1      | 10      | 7       | -3      | 0       | 2       |

#### Array of coefficients with degree

- Assumption
  - Coefficient⊆ data type: integer
  - Maximum degree to be supported = X
- Type definition 1: static allocation of coefficient array

```
typedef struct {
    int degree;
    int coef[X+1];
} Polynomial;
```

Type definition 2: dynamic allocation of coefficient array

```
typedef struct {
    int degree;
    int *coef;
} Polynomial;
```

#### Static allocation of coefficient array

Example

```
• A(x) = 2x^5 - 3x^3 + 7x^2 + 10x - 1
```

Representation

```
#define MAX_DEGREE 100
typedef struct {
    int degree;
    int coef[MAX_DEGREE +1];
} Polynomial;

Polynomial A;

A.degree = 5;
A.coef[5] = 2; A.coef[4] = 0; ..., A.coef[0] = -1;
```

## Dynamic allocation of coefficient array

Example

```
• A(x) = 2x^5 - 3x^3 + 7x^2 + 10x - 1
```

Representation

```
typedef struct {
    int degree;
    int *coef;
} Polynomial;

Polynomial A;

A.degree = 5;
A.coef = (int *) malloc((A.degree+1)*sizeof(int));
A.coef[5] = 2; A.coef[4] = 0; ..., A.coef[0] = -1;
```

#### Array of terms

- coefficient array
  - Inefficient for sparse polynomials
  - Waste of memory
  - Example:  $A(x) = 2x^{500} + 10x 1$
- Array of terms

```
typedef struct {
    int coef;
    int exp;
} Term;
```

Term A[3];

| A[0].coef = 2; A[0].exp = 500; |
|--------------------------------|
| A[1].coef = 10; A[1].exp = 1;  |
| A[2].coef = -1; A[2].exp = 0;  |

|      | A[0] | A[1] | A[2] |
|------|------|------|------|
| coef | 2    | 10   | -1   |
| ехр  | 500  | 1    | 0    |

## Array of terms

• Type definition 1: static allocation of terms array typedef struct { int coef; int exp; } Term; typedef struct { int num\_terms; Term term[MAX\_TERMS]; } Polynomial; Type definition 2: dynamic allocation of terms array typedef struct { int num\_terms; Term \*term; } Polynomial;

#### Polynomial addition

#### Example

• 
$$A(x) = 2x^5 - 3x^3 + 7x^2 + 10x - 1$$

• 
$$B(x) = 5x^4 + 2x^3 - 7x^2 + 10$$

• 
$$C(x) = A(x) + B(x)$$
  
=  $2x^5 + 5x^4 - x^3 + 10x + 9$ 

#### • Implementation

- Dependent on polynomial representation
- Representations
  - Array of coefficients
  - Array of terms

# Polynomial addition: Array of coefficients

```
#define MAX_DEGREE 10
typedef struct {
    int degree;
    int coef[MAX_DEGREE +1];
} Polynomial;
Polynomial A, B, C; //C = A + B
A.degree \leftarrow 5;
A.coef[] \leftarrow {-1, 10, 7, -3, 0, 2};
B.degree \leftarrow 4;
A.coef[] \leftarrow {10, 0, -7, 2, 5};
Poly_add(&A, &B, &C);
```

$$A(x) = 2x^5 - 3x^3 + 7x^2 + 10x - 1$$

$$B(x) = 5x^4 + 2x^3 - 7x^2 + 10$$

$$C(x) = 2x^5 + 5x^4 - x^3 + 10x + 9$$



C.degree = 
$$5$$
  
C.coef[] =  $\{9, 10, 0, -1, 5, 2\}$ 

#### Polynomial addition: Array of terms

Polynomial A, B, C; //C = A + B

• • • • •

Poly\_add(&A, &B, &C),

|      | A[0] | A[1] | A[2] | A[3] | A[4] |
|------|------|------|------|------|------|
| coef | 2    | -3   | 7    | 10   | -1   |
| exp  | 5    | 3    | 2    | 1    | 0    |
|      |      |      |      |      |      |
|      | B[0] | B[1] | B[2] | B[3] |      |
| coef | 5    | 2    | -7   | 10   |      |
| exp  | 4    | 3    | 2    | 0    |      |
|      |      |      |      |      |      |
|      | C[0] | C[1] | C[2] | C[3] | C[4] |
| coef | 2    | 5    | -1   | 10   | 9    |
| ехр  | 5    | 4    | 3    | 1    | 0    |



#### Matrix

- Row, column, element
- Example: 2 by 3 Matrices

$$A\begin{bmatrix} 5 & 10 & 0 \\ -1 & 2 & 9 \end{bmatrix} B\begin{bmatrix} 10 & 10 & 10 \\ 10 & 10 & 10 \end{bmatrix}$$

- Matrix representation
  - 2-dim array int A[2][3]; //A[num\_rows][num\_cols] A[0][1] = 10;
- Sparse matrix
  - 2-dim array is inefficient

#### Representation of sparse matrix

- Array of
  - non-zero elements
  - triples <row, col, value>
- Example: matrix B

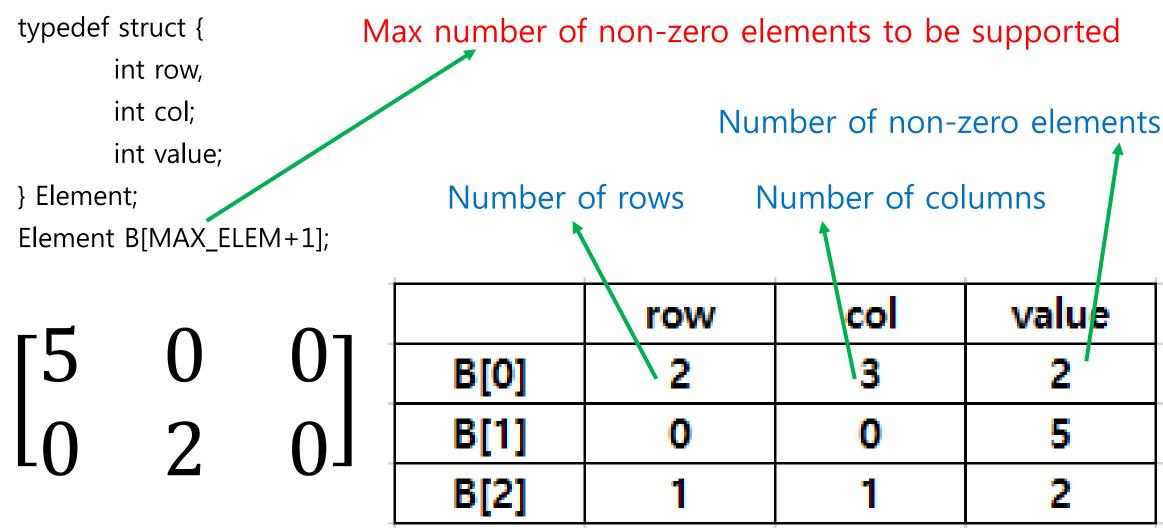
 Declaration typedef struct { int row, int col; int value;

| <0, 0, 5><br><1, 1, 2>                       |      |
|--|------|
| Declaration                                  | В    |
| typedef struct {                             | В    |
| int row,<br>int col;                         | В    |
| int value;                                   | _    |
| <pre>} Element;<br/>Element B[MAX_ELEM</pre> | +1]; |

| D | [5             | 0 | 0  |
|---|----------------|---|----|
| D | $\int_{2}^{0}$ | 2 | 0- |

|      | row | col | value |
|------|-----|-----|-------|
| B[0] | 2   | 3   | 2     |
| B[1] | 0   | 0   | 5     |
| B[2] | 1   | 1   | 2     |

#### Representation of sparse matrix



# Sorting of non-zero elements

| Α        | 5          | 0 | 0  |
|----------|------------|---|----|
| <b>A</b> | 0          | 2 | 0  |
|          | 0          | 1 | 0  |
|          | <b>L</b> 7 | 0 | 4_ |

|      | row | col | value |
|------|-----|-----|-------|
| A[0] | 4   | 3   | 5     |
| A[1] | 0   | 0   | 5     |
| A[2] | 1   | 1   | 2     |
| A[3] | 2   | 1   | 1     |
| A[4] | 3   | 0   | 7     |
| A[5] | 3   | 2   | 4     |

- Sorted on row first
- Sorted on col for the same rows

#### Transpose a matrix

- Interchange rows and columns
- Example:

| 5<br>0<br>0<br>7 | 0<br>2<br>1      | 0<br>0<br>0<br>4  |  | 0<br>2<br>0   | 0<br>1<br>0  | 7<br>0<br>4   |
|------------------|------------------|---|--|---|--|---|
| 7                | O                | 4   |  |   |  |   |
|                  | 5<br>0<br>0<br>7 | <ul><li>5</li><li>0</li><li>2</li><li>0</li><li>1</li><li>7</li><li>0</li></ul> | <ul> <li>[5] 0 0</li> <li>[0] 2 0</li> <li>[0] 1 0</li> <li>[7] 0 4</li> </ul> | $\begin{bmatrix} 5 & 0 & 0 \\ 0 & 2 & 0 \\ 0 & 1 & 0 \\ 7 & 0 & 4 \end{bmatrix} \begin{bmatrix} 5 \\ 0 \\ 0 \\ 0 \end{bmatrix}$ | $\begin{bmatrix} 5 & 0 & 0 \\ 0 & 2 & 0 \\ 0 & 1 & 0 \\ 7 & 0 & 4 \end{bmatrix} \begin{bmatrix} 5 & 0 \\ 0 & 2 \\ 0 & 0 \end{bmatrix}$ | $\begin{bmatrix} 5 & 0 & 0 \\ 0 & 2 & 0 \\ 0 & 1 & 0 \\ 7 & 0 & 4 \end{bmatrix} \begin{bmatrix} 5 & 0 & 0 \\ 0 & 2 & 1 \\ 0 & 0 & 0 \\ 0 & 0 & 0 \end{bmatrix}$ |

#### Transpose a matrix: 2-dim array

- Interchange rows and columns
  - A: input matrix
  - B: transposed matrix
  - A[i][j] → B[j][i]
- A simple nested loop: n x m matrix

```
for i \leftarrow 1 to n do //row:1..n
for j \leftarrow 1 to m do //col:1..m
B[j][i] \leftarrow A[i][j]
```

Complexity: O(numCols \* numRows)

#### Transpose a sparse matrix

- Representation: 1-dim array of non-zero elements
- Array A: original matrix
- Array B: transposed matrix

| A | <b>[</b> 5 | 0 | 0] | B [ | 5  | 0           | 0 | 7] |
|---|------------|---|----|-----|----|-------------|---|----|
|   | 0          | 2 | 0  |     | 0  | 2           | 1 | 0  |
|   | 0          | 1 | 0  |     | _0 | 0<br>2<br>0 | 0 | 4  |
|   |            | Λ |    |     |    |             |   |    |

|      | row | col | value |
|------|-----|-----|-------|
| A[0] | 4   | 3   | 5     |
| A[1] | 0   | 0   | 5     |
| A[2] | 1   | 1   | 2     |
| A[3] | 2   | 1   | 1     |
| A[4] | 3   | 0   | 7     |
| A[5] | 3   | 2   | 4     |

|      | row | col | value |
|------|-----|-----|-------|
| B[0] | 3   | 4   | 5     |
| B[1] | 0   | 0   | 5     |
| B[2] | 0   | 3   | 7     |
| B[3] | 1   | 1   | 2     |
| B[4] | 1   | 2   | 1     |
| B[5] | 2   | 3   | 4     |

# Algorithm 1

- For each column of A, makes rows of B
- For each column of A, the array A is fully scanned
- Example: for column 0,

|      | row | col | value |          |          | row         | col          | value    |
|------|-----|-----|-------|----------|----------|-------------|--------------|----------|
| A[0] | 4   | 3   | 5     |          | B[0]     | 3           | 4            | 5        |
| A[1] | 0   | 0   | 5     |          | B[1]     | 0           | 0            | 5        |
| A[2] | 1   | 1   | 2     |          | B[2]     | 0           | 3            | 7        |
| A[3] | 2   | 1   | 1     | <b>→</b> | Next nor | n-zero elem | nent will be | put here |
| A[4] | 3   | 0   | 7     |          |          |             |              |          |
| A[5] | 3   | 2   | 4     |          |          |             |              |          |

#### Algorithm 1 (cont'd)

• Example: for the next column, i.e., column 1,

|      | row | col | value |          |          | row        | col         | value    |
|------|-----|-----|-------|----------|----------|------------|-------------|----------|
| A[0] | 4   | 3   | 5     |          | B[0]     | 3          | 4           | 5        |
| A[1] | 0   | 0   | 5     |          | B[1]     | 0          | 0           | 5        |
| A[2] | 1   | 1   | 2     |          | B[2]     | 0          | 3           | 7        |
| A[3] | 2   | 1   | 1     |          | B[3]     | 1          | 1           | 2        |
| A[4] | 3   | 0   | 7     |          | B[4]     | 1          | 2           | 1        |
| A[5] | 3   | 2   | 4     | <b>—</b> | Next non | -zero elem | ent will be | put here |

Complexity: O(numCols \* numNonZeroElements)

## Algorithm 2

- Faster transpose of a sparse matrix than Algo 1
- Step 1: For each column of A, count non-zero elements
- Step 2: For each row of B, compute the start position in array B
- Step 3: For each element in array A, move it to array B
- Complexity: O(numCols + numNonZeroElements)

#### Step 1

• For each column of A, count non-zero elements

|      | row | col | value |
|------|-----|-----|-------|
| A[0] | 4   | 3   | 5     |
| A[1] | 0   | 0   | 5     |
| A[2] | 1   | 1   | 2     |
| A[3] | 2   | 1   | 1     |
| A[4] | 3   | 0   | 7     |
| A[5] | 3   | 2   | 4     |

| count[0] | count[1] | count[2] |                |
|----------|----------|----------|----------------|
| 0        | 0        | 0        | initialization |
| 1        | 0        | 0        |                |
| 1        | 1        | 0        |                |
| 1        | 2        | 0        |                |
| 2        | 2        | 0        |                |
| 2        | 2        | 1        | final counts   |

#### Step 2

• For each row of B, compute the start position in array B

| count[0]    | count[1]    | count[2]    |                |
|-------------|-------------|-------------|----------------|
| 2           | 2           | 1           |                |
| startPos[0] | startPos[1] | startPos[2] |                |
| 1           |             |             | initialization |
|             | 1+2=3       | 3+2=5       |                |
| 1           | 3           | 5           |                |

#### Step 3

• For each element in array A, move it to array B

|      | row | col | value |      | row | col | value |
|------|-----|-----|-------|------|-----|-----|-------|
| A[0] | 4   | 3   | 5     | B[0] | 3   | 4   | 5     |
| A[1] | 0   | 0   | 5     | B[1] | 0   | 0   | 5     |
| A[2] | 1   | 1   | 2     | B[2] |     |     |       |
| A[3] | 2   | 1   | 1     | B[3] | 1   | 1   | 2     |
| A[4] | 3   | 0   | 7     | B[4] |     |     |       |
| A[5] | 3   | 2   | 4     | B[5] |     |     |       |

- Where in Array B ??
  - startPos[]

| startPos[0] | startPos[1] | startPos[2] |
|-------------|-------------|-------------|
| 1           | 3           | 5           |
| 2           | 4           | 5           |