

CSE 6730 Final Project

## LLM-Empowered Kudzu Modeling and Simulation

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GitHub repository:  
<https://github.gatech.edu/jbeck73/CSE6730Project>

1 **PROJECT FINAL REPORT: LLM-Empowered Kudzu Modeling and Simulation**

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4 **SM1. Abstract.** We develop an LLM-empowered simulator for managing the spread of  
5 kudzu, a fast-growing invasive vine in the southeastern United States. Our model couples  
6 a spatial Cellular Automata (CA) representation of kudzu dynamics with a Large Language  
7 Model (LLM) that plays the role of a budget-constrained manager. The CA tracks four  
8 life-cycle stages on a land-cover grid derived from NLCD data and parametrized following  
9 Aurambout and Endress. Each week, the CA updates local growth and spread; at the start of  
10 each month, the manager receives a compact field observation of the landscape and remaining  
11 budget and chooses spatially targeted treatment actions. We implemented three baselines (no  
12 intervention, a greedy hotspot rule, and a simple heuristic policy) and compared them against  
13 the LLM policy over a three-year (156-week) horizon in Clark County, Washington. In this  
14 scenario, the LLM eradicates kudzu (zero final abundance) while spending a moderate fraction  
15 of the available budget, whereas baseline policies either underspend and allow widespread  
16 infestation or overspend and still fail to eradicate.

17 **SM2. Project Description.** The overarching goal of this project is to build a simulation  
18 testbed in which an AI decision maker manages an ecological invasion under realistic con-  
19 straints. We focus on kudzu (*Pueraria montana*), an invasive vine that spreads rapidly and  
20 can smother trees, infrastructure, and native vegetation. Kudzu is interesting from a modeling  
21 perspective because it has a clear life-cycle structure, spreads through both local vegetative  
22 growth and long-distance dispersal, and is notoriously expensive to control once established.  
23 Land managers must decide where and when to intervene, often with limited budgets and  
24 incomplete information.

25 Our simulation is designed to capture several features of this real-world phenomenon that  
26 we consider most relevant. First, the spread of kudzu is inherently spatial. Patches occupy  
27 some parcels of land but not others, and both spread and management actions are local. To  
28 represent this, we model the landscape as a two-dimensional grid derived from Clark County  
29 land-cover data, where each cell represents an area on the ground and carries a land-cover label  
30 such as forest, developed land, or water. The land-cover type determines how suitable the cell  
31 is for kudzu, which we encode as a carrying capacity. Second, kudzu passes through distinct  
32 life-cycle stages that differ in growth, mortality, and management response. We therefore track  
33 seeds in a seed bank, early seedlings, saplings, and adults. Third, spread is driven by both  
34 local expansion of vines into neighboring cells and less common long-distance dispersal events  
35 that create satellite infestations away from the origin patch. Finally, managers operate under  
36 budget constraints: each treatment costs money and they must balance current suppression  
37 against future risk.

38 The central question we ask is how a large language model behaves when placed in the  
39 role of such a manager. At a high level, our simulator runs forward in weekly steps. The CA  
40 updates the spatial kudzu every week using programmed ecological rules. Once per month,  
41 the simulation pauses and constructs a simplified field report summarizing what is happening

**SM2**

42 on the landscape: total kudzu, the locations and intensities of the worst hotspots, and the  
43 remaining budget. This observation is sent to a policy, which can be either a hand-coded  
44 heuristic or the LLM. The policy chooses a set of actions such as treating a list of cells at a  
45 given intensity, removing seeds from particularly risky locations, or surveying a specific region  
46 of land to identify potential Kudzu establishment. These actions are then applied to the CA  
47 state subject to a fixed budget. In this way, we can compare an LLM-driven manager to  
48 simpler rule-based strategies in a controlled, transparent environment.

49 A video summary of the following project is also available [here](#).

50 **SM3. Literature Review.**

51 **SM3.1. Introduction and Background.** Agent-based modeling and simulation (ABMS)  
52 has long been used to study how complex collective phenomena arise from the interactions  
53 of autonomous entities. Traditional ABMS systems rely on manually designed behavioral  
54 rules or statistical models, which restrict adaptability and realism. The recent emergence of  
55 large language models (LLMs) introduces a transformative opportunity: these models can act  
56 as cognitive cores for agents, capable of reasoning, communication, and contextual decision-  
57 making. The two papers reviewed here—Gao et al. (2024) [SM2] and Wu et al. (2025)  
58 [SM6]—together provide both a comprehensive overview and a critical assessment of this new  
59 research direction. We will utilize an LLM-based approach for a specific Kudzu application  
60 discussed later.

61 **SM3.2. Existing Models and Techniques in LLM-Based ABMS.** Gao et al. (2024) [SM2]  
62 provide the first comprehensive survey of LLM-integrated ABMS systems. The authors cate-  
63 gorize applications across social, physical, cyber, and hybrid domains, illustrating how LLMs  
64 extend the traditional ABMS pipeline by endowing agents with richer cognitive functions.  
65 They emphasize four major areas where LLMs significantly enhance agent design: perception,  
66 reasoning and decision-making, adaptation and memory, and heterogeneity. In LLM-based  
67 ABMS, agents are not limited to rule-based reactions; instead, they interpret environmental  
68 or text inputs in natural language, generate context-aware actions through chain-of-thought  
69 reasoning, reflect on past experiences to adapt over time, and express diverse personalities  
70 and communication styles.

71 Several representative frameworks, such as Generative Agents, CAMEL, and Voyager,  
72 demonstrate how LLM-powered agents can exhibit realistic social behavior, negotiation, and  
73 collaboration. These systems commonly integrate prompt templates, memory modules, re-  
74 flection loops, and planner-executor architectures to simulate autonomous, interacting pop-  
75 ulations. Despite these innovations, Gao et al. identify several persistent limitations in the  
76 literature, including challenges in scaling simulations to large populations, the lack of stan-  
77 dardized quantitative evaluation metrics, limited reproducibility, and ethical or alignment  
78 concerns arising from uncontrolled model behavior. Consequently, the current body of work  
79 establishes a strong architectural foundation but remains primarily qualitative, exploratory,  
80 and small-scale in nature.

81 **SM3.3. Application Domain: Kudzu Invasion Modeling.** First introduced from Japan,  
82 Kudzu is an aggressive and invasive species that causes ecological damage and reduces biodi-  
83 versity. It costs billions of dollars annually to contain, maintain, and eradicate the species.

84 Aurambout & Endress (2018) [SM1] proposed a model to simulate the spread and man-  
85 agement cost of Kudzu. They modeled the spread utilizing Cellular Automata on the NetLogo  
86 multi-agent programmable modeling environment. They ran many experiments utilizing dif-  
87 ferent defined management policies to simulate the prevention/slowing of the Kudzu. After  
88 simulating the spread of Kudzu in each geographic patch, the cost of the management was  
89 calculated to determine the performance of the management policy. We could expand on their  
90 approach, utilizing their research on the behavior of Kudzu. However, we would implement an  
91 LLM-approach as a replacement for the management policies, analyzing the difference between  
92 hard defined policies between a flexible and dynamic LLM policy that will have potentially  
93 higher saved costs and reduced Kudzu spread.

94 Furthermore, Harron et al., 2020 [SM3] models the spread rate of Kudzu in the next five  
95 years using Monte Carlo simulation with data from Oklahoma, USA. The study also estimated  
96 the economic loss due to Kudzu using a replacement cost approach with a sensitivity analysis.  
97 For our project, this gives an additional method, Monte Carlo, to simulate the Kudzu spread  
98 other than the Cellular Automata method described before.

99 **SM3.4. Intelligent Conservation Management.** Silvestro et al. (2022) [SM5] demon-  
100 strates how a monitored, actuated loop can outperform static plans. Their method, CAPTAIN  
101 shows conservation as a monitor-decide-act loop optimized by RL under explicit budgets and  
102 unfolding over time, the cadence we'll mirror with monthly CA state reads followed by LLM  
103 management actions. Recurrent monitoring even with presence/absence noise improves out-  
104 comes, so our pipeline should accept low-fidelity surveillance and still update decisions each  
105 cycle. CAPTAIN also warns that choosing the wrong objective (e.g., maximizing area) can  
106 worsen biodiversity outcomes; for Kudzu we should reward spread suppression/eradication  
107 per dollar rather than acreage.

108 In Parker et al. (2003) [SM4], the hybrid multi-agent systems model and land-use/cover  
109 change (MAS/LUCC) framework is proposed as a way to couple a cellular landscape with  
110 agent-based decision makers, linked by explicit feedbacks between people and environment.  
111 This overcomes plain CA's limits, as CA can capture spatial diffusion/transition rules but  
112 cannot represent heterogeneous, decentralized human decisions or institutional behaviors that  
113 determine where, when, and how land is managed. MAS/LUCC adds agents (e.g., farmers,  
114 landowners, agencies) whose autonomous, interacting decisions operate on different patches  
115 over time, enabling complex social-spatial responses. The paper positions MAS/LUCC for  
116 both the explanation of social phenomenon and empirical policy analysis. It also offers a val-  
117 idation approach that combines the use of spatial/landscape metrics rather than totals alone,  
118 separate quantity accuracy (how much change) from location accuracy (where change occurs),  
119 and resolution-scale sensitivity tests to guard against nonlinearity and path dependence. For  
120 our Kudzu project, this directly motivates our hybrid design – CA for ecological spread with  
121 LLM-based management agents for human response.

122 **SM3.5. Project Uniqueness.** In order to make our project unique, we will connect the  
123 ideas from Kudzu research and the LLM-powered agent model. Currently, instead of the  
124 Monte Carlo simulation, we are thinking of connecting the ecological Cellular Automata model  
125 with the LLM-powered agent model. The connection would be a feedback loop that runs at  
126 each month or season.

127     **SM4. Conceptual Model.** Conceptually, our ecological model is a spatially explicit, stage-■  
128 structured CA defined on a regular grid. Each cell in the grid represents a land parcel with a  
129 fixed land-cover type. We map NLCD land-cover categories to carrying capacities for kudzu:  
130 forests and similar natural covers have high capacities, agricultural areas have moderate ca-  
131 pacities, developed areas have low capacities, and water and some urban types have effectively  
132 zero capacity. Within each cell we track four kudzu state variables corresponding to the life-  
133 cycle stages: the number of seeds in a seed bank, the number of seedlings, the number of  
134 saplings, and the number of adults. Time advances in weekly steps.

135     The within-cell dynamics follow a set of simple stochastic rules inspired by Aurambout  
136 and Endress. Each week, individuals in each stage experience mortality with a stage-specific  
137 probability. We use a binomial distribution using these probabilities to calculate how many  
138 individuals survive to the next time stamp. For example, if there are 10 adult Kudzu with a  
139 mortality rate of 0.01, the simulation runs a binomial trial with  $n = 10$ ,  $p = 0.99$  to determine  
140 how many remain. This simulates real world Kudzu death from events like disease, age,  
141 or other factors. At certain recruitment times of year, seeds may germinate into seedlings,  
142 seedlings may become saplings, and saplings may become adults, subject to the constraint that  
143 the total biomass in the cell cannot exceed its carrying capacity. These life stage promotion  
144 or maturation functions using binomial distributions through binomial trials similar to the  
145 previously mentioned mortality functionality since there is a chance that Kudzu won't mature.  
146 Adults also contribute to the seed bank at a rate that depends on their abundance described  
147 in a later paragraph. These processes capture the seasonal structure of kudzu growth: there  
148 are months where seedlings and saplings rapidly advance into larger, more impactful stages.

149     Spatial spread is modeled through two mechanisms. Local spread represents vegetative  
150 growth into neighboring cells. This is Kudzu's primary means of spread. We define a Moore  
151 neighborhood of eight neighboring cells around each cell, and at each weekly step, saplings  
152 and adults in a cell can colonize neighboring cells with a probability that increases with local  
153 density on a binomial distribution, again capped by the receiving cell's carrying capacity.  
154 This spread directly increases the sapling count in the cell and not seedlings because of the  
155 biological nature of asexual reproduction that Kudzu performs. On the other hand, long-  
156 distance dispersal represents rare events where actual seeds or propagules are transported  
157 farther afield by animals, humans, or water. In our conceptual model, each adult has a small  
158 probability of producing a small number of seeds based on a Poisson distribution which is  
159 ideal for a variable number of seeds. Then each seed travels from the origin parent to a  
160 location determined by an exponential distribution. This is because the seeds will realistically  
161 land close by. Once the distance has been calculated, each seed will be assigned a direction  
162 uniformly between  $0\pi$  and  $2\pi$ , since each direction is relative equal. Based on direction and  
163 distance, the new cell for seeds will be identified and the new cell will increase the amount  
164 of seeds that it currently has. The combination of local spread and LDD produces invasion  
165 patterns with expanding fronts and scattered satellite infestations.

166     The management agent interacts with this ecological process on a slower, monthly timescale.■  
167 At the beginning of each month (after four or five weekly updates), we aggregate the CA state  
168 into a compact observation. This observation includes the current year and month, total  
169 counts in each life-cycle stage, the remaining budget and budget duration, and a ranked list  
170 of the worst hotspots defined by a weighted sum of adult, sapling, and seedling density. The

171 observation also includes seed bank hotspots. The hotspots are not deterministic in order  
172 to simulate reporting of Kudzu which could be random and non-deterministic. The agent's  
173 action space consists of a small set of treatment types that can be applied to specific cells:  
174 generic treatments that proportionally reduce all stages, more targeted seed-bank removal that  
175 aggressively reduces seeds with some effect on other stages, and survey actions that spend a  
176 small amount of budget without changing the state but could, in extensions, reveal hidden  
177 infestations deterministically. The LLM commonly uses the survey action based on hotspot  
178 information to identify neighboring cells that need to also be treated or could potentially  
179 spread further. Each action type has an associated cost per cell. The agent's conceptual ob-  
180 jective is to choose actions that reduce future kudzu spread and abundance while respecting  
181 a fixed total budget over the entire planning horizon.

182 **SM5. Simulation Model.** We implemented the conceptual CA in Python using a modular  
183 structure. The core ecological dynamics are encapsulated in a `KudzuField` class that loads  
184 the Clark County land-cover raster, maps each land-cover class to a carrying capacity, and  
185 initializes arrays for seeds, seedlings, saplings, and adults at every cell. Weekly updates apply  
186 mortality, recruitment, local spread, and long-distance dispersal using the parameters chosen  
187 from the literature and tuned for numerical stability. All counts are kept as integers, and we  
188 ensure that no cell ever exceeds its carrying capacity. A set of helper methods allows us to  
189 snapshot the current state, compute summaries such as total kudzu or hotspot locations, and  
190 apply treatment actions by decrementing counts in the targeted cells.

191 A separate `Runner` script orchestrates the interplay between the CA and the management  
192 policies. It seeds the landscape with an initial configuration consisting of four clusters of  
193 infested cells, mirroring the NetLogo model we used for inspiration. The runner then advances  
194 the simulation week by week. On weeks that correspond to the beginning of a new month, it  
195 constructs the observation summary, passes it to the selected policy, and receives back a list  
196 of actions. These actions are checked and priced by a `BudgetManager` object, which tracks  
197 remaining funds, computes the total cost of each proposed action list, and removes or scales  
198 actions that would exceed the budget. Valid actions are then applied to the `KudzuField`  
199 before the next block of weekly CA updates. Throughout the run, we log key metrics and  
200 write history files that record the state and management actions at each month.

201 The policies themselves are implemented in a separate module. We provide three non-LLM  
202 policies for comparison: a trivial no intervention policy that always returns an empty action  
203 list, a greedy policy that treats the single densest hotspot each month, and a simple heuristic  
204 policy that treats a fixed number of top hotspots at full intensity regardless of budget efficiency.  
205 The LLM policy constructs a detailed text prompt that describes the current observation,  
206 the definitions and costs of each action type, and instructions about budget discipline and  
207 formatting. It then calls a Gemini model through an OpenRouter-compatible API, expects a  
208 JSON-formatted list of actions, and parses that output. Basic error handling and retry logic  
209 are used to guard against malformed responses or temporary API failures. The policies and  
210 budget manager are written so that their interfaces match, allowing us to swap policies in and  
211 out while leaving the rest of the simulator unchanged.

212 We performed several verification steps to ensure that the simulation code matched our  
213 conceptual model. With management turned off and spread probabilities set to zero, we

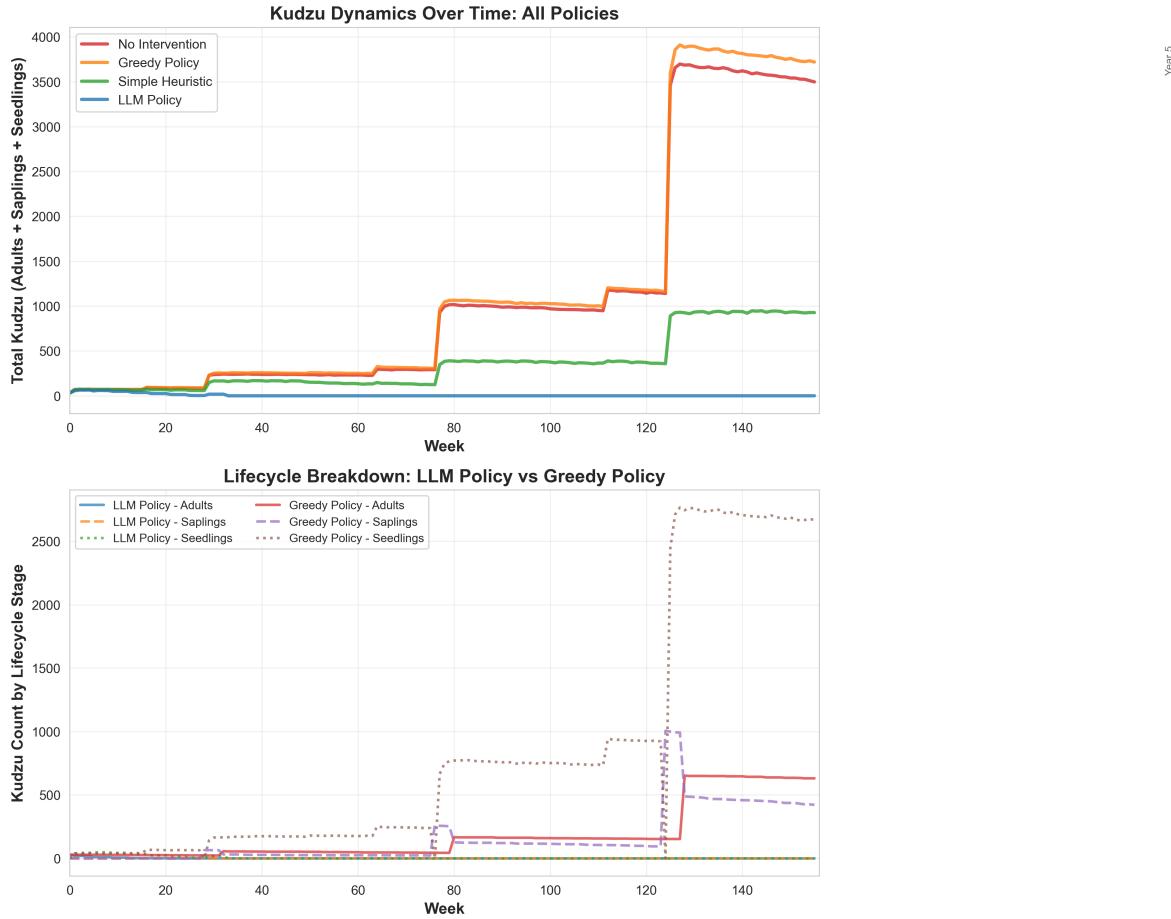
214 confirmed that the kudzu population declined over time purely due to mortality and that no  
215 new infestations appeared. With local spread turned on but long-distance dispersal disabled,  
216 we observed smooth expanding fronts around the initial clusters and no remote satellites, as  
217 expected. With both spread mechanisms active, the simulated invasion exhibited expanding  
218 clusters and scattered satellites similar to published figures. We also included consistency  
219 checks in the code to ensure that all counts remain non-negative and do not exceed cell  
220 capacities after each update, and we tested the budget manager with controlled action lists  
221 to verify that budget totals never became negative.

222 **SM6. Experimental Results and Validation.** To evaluate how different management  
223 strategies perform in our simulator, we designed a baseline experiment in which four poli-  
224 cies manage the same kudzu invasion. In every run, the simulation horizon was 156 weeks,  
225 corresponding to three years. The landscape started with thirty infested cells arranged in  
226 several clusters in suitable habitat, and each policy was given a total budget of \$30,000 to  
227 spend over the three-year period. Management decisions were made at the beginning of each  
228 simulated month. We fixed the random seed at 42 so that the underlying stochastic mortality,  
229 recruitment, and dispersal processes were identical across policies, ensuring that differences  
230 in outcomes are due to the management strategy rather than random variation.

231 The time-series trajectories show how the invasion unfolds under each strategy. Under  
232 no intervention, total kudzu grows steadily for roughly two years and then experiences large  
233 surges during recruitment periods, ending the simulation at a high level. The greedy policy,  
234 which treats only the single densest hotspot each month, stays very close to the no-intervention  
235 curve and even overshoots it at times, indicating that this naive strategy does not meaningfully  
236 slow the invasion. The simple heuristic policy, which treats multiple hotspots every month,  
237 holds the population to a much lower level than the first two policies but never eliminates it;  
238 the time series settles at a non-zero equilibrium. In contrast, the LLM policy quickly drives  
239 kudzu down: the total abundance peaks at a small value and then declines to zero, after which  
240 the system remains eradicated for the rest of the three-year period.

241 We summarize the performance of each policy using several metrics: peak total kudzu  
242 observed at any time, final total kudzu at week 156, the number of distinct cells that were  
243 ever infested (a measure of spatial spread), the total dollars spent, and the number of months  
244 with at least one management action. Under no intervention, the invasion reaches a peak of  
245 about 3,697 individuals and ends with approximately 3,498 individuals spread across 968 cells,  
246 with zero cost. The greedy policy spends \$3,900 but performs slightly worse, with a peak of  
247 3,910, a final total of 3,719, and 996 cells ever infested. The simple heuristic policy is far more  
248 aggressive: it reduces the peak to roughly 948 and the final total to 927 individuals, and it  
249 limits spread to 308 cells, but it spends \$19,500 and still fails to eradicate kudzu. The LLM  
250 policy is the only one that achieves eradication in this scenario. It reaches a peak of just 64  
251 individuals, ends with zero individuals, and allows infestation in only 32 cells total. It spends  
252 about \$16,360, leaving a substantial fraction of the budget unused, and it intervenes in only  
253 nine months over the three years.

254 The bar-chart comparison highlights these trade-offs visually. The no-intervention and  
255 greedy policies occupy the high infestation, low cost corner: they are cheap but ineffective.  
256 The simple heuristic sits in a moderate infestation, high cost region, reflecting that it spends

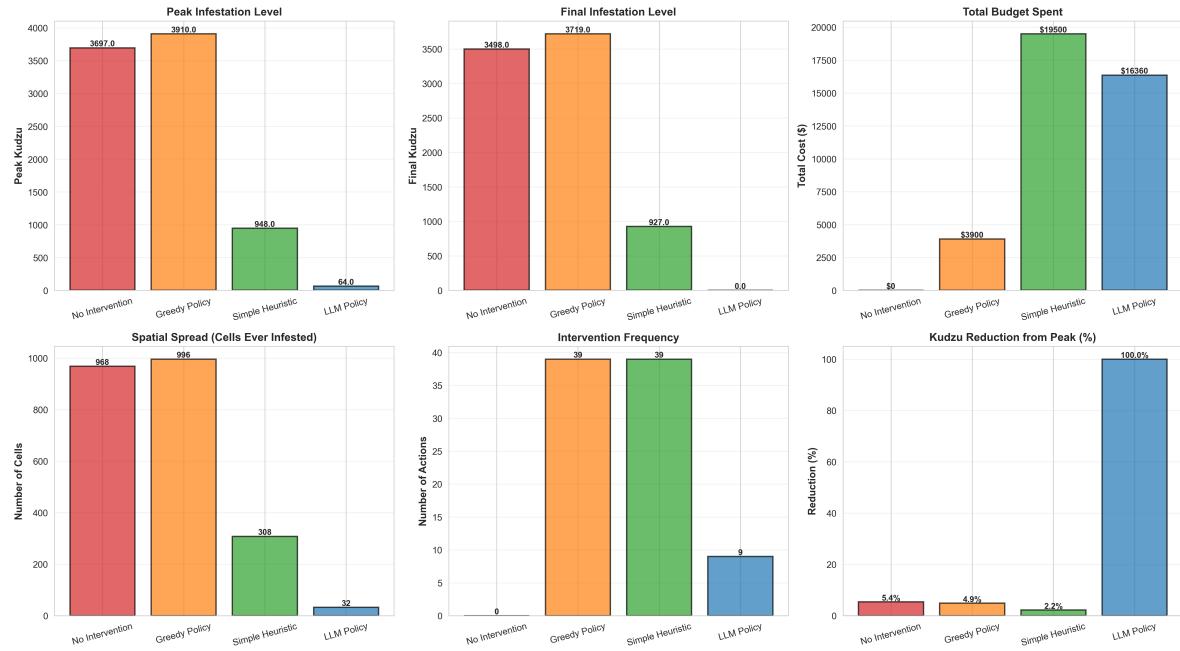


**Figure SM1.** Kudzu over time by policy

heavily to partially suppress the invasion. The LLM policy stands out by combining very low peak and final infestation and limited spatial spread with a mid-range cost and relatively few intervention months.

To examine cost-effectiveness more directly, we also compared final kudzu abundance against total budget spent. In this two-dimensional space, the most desirable region is low cost and low final infestation. No intervention appears at zero cost but high final abundance, and the greedy policy lies slightly to the right with essentially the same poor outcome. The simple heuristic moves toward the high-cost, moderate-abundance region: it buys some reduction at the expense of most of the budget. The LLM policy occupies the most favorable position, with moderate cost and zero final infestation.

Beyond these aggregate metrics, the policies differ in how they use the budget over time. The simple heuristic spends steadily throughout most of the three years, treating multiple hotspots almost every month and quickly consuming the majority of the available budget. The LLM policy instead front-loads its actions, focusing treatment and seed-bank removal in

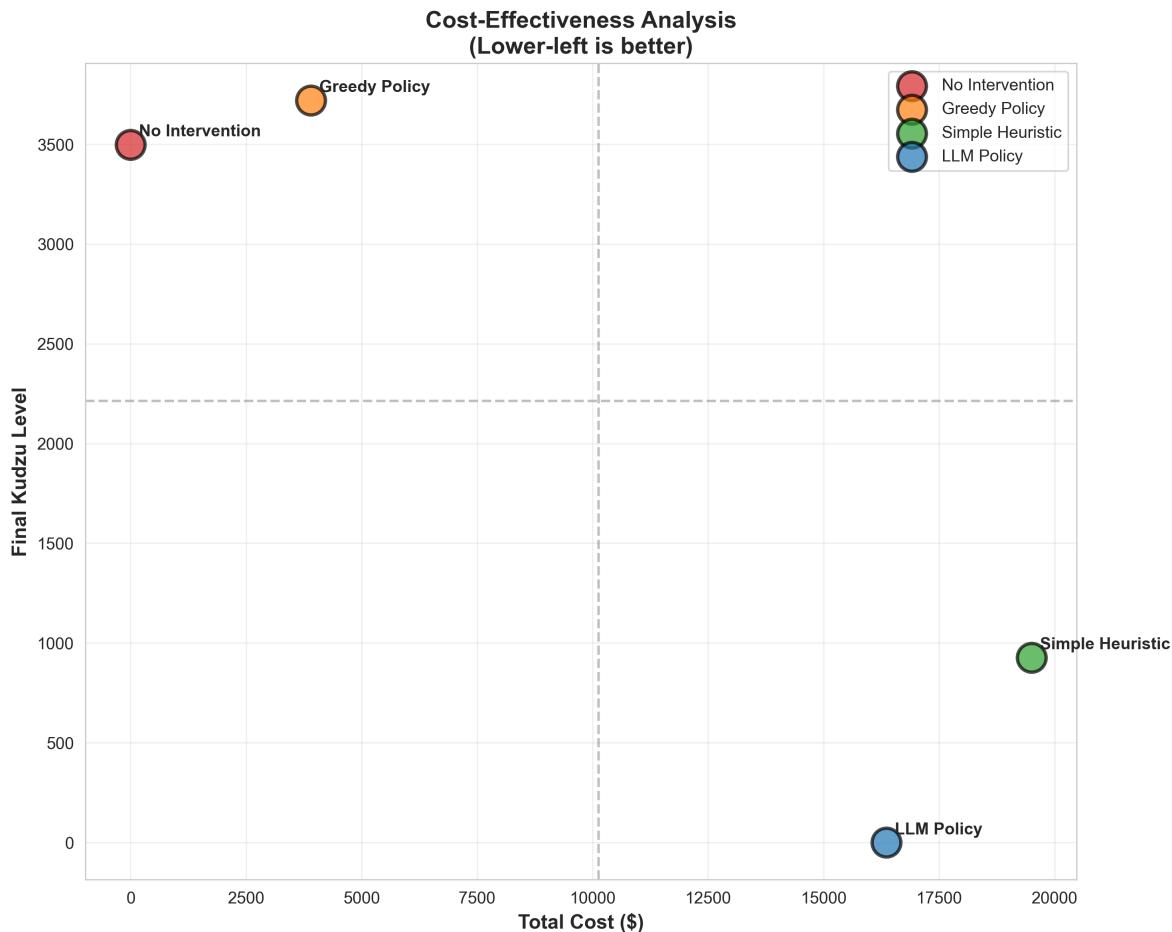


**Figure SM2.** Policy comparison metrics

271 the first one to one and a half years and then largely stopping once the invasion has been  
 272 eradicated. This behavior aligns with the time-series results: early, concentrated intervention  
 273 prevents the large outbreaks seen under the other strategies, which allows the LLM to save  
 274 budget in the later years.

275 Our validation efforts focused on face validity and internal consistency rather than formal  
 276 calibration to field data. Under no intervention and under the simple rules, the simulated  
 277 invasion behaves qualitatively as expected: infestations expand outward from initial clusters,  
 278 preferentially occupy high-capacity land-cover types, and respond strongly to seasonal re-  
 279 cruitment. All four policies share the same pre-management dynamics early in the run, which  
 280 provides a check that the underlying stochastic processes are consistent across runs. We also  
 281 manually inspected samples of the LLM’s proposed actions and their costs. Once given a  
 282 sufficiently detailed prompt and clear constraints, the LLM tends to prioritize heavily infested  
 283 clusters, uses seed-bank removal before key recruitment periods, and respects the budget lim-  
 284 its enforced by the budget manager. However, we only ran a single random seed due to API  
 285 and computational constraints, and we did not fit the model to real time-series data. For these  
 286 reasons, the numerical performance gaps reported here should be interpreted as a case study  
 287 rather than a statistically robust estimate. A more thorough validation, which we identify  
 288 as future work, would involve multiple Monte Carlo runs per policy and comparisons against  
 289 observed kudzu distributions.

290 **SM7. Discussion, Conclusion, Summary.** This project demonstrates how a classical eco-  
 291 logical simulation framework and modern large language models can be combined to explore



**Figure SM3.** Cost vs final kudzu

management strategies for invasive species. On the modeling side, we implemented a realistic CA of kudzu spread that respects land-cover heterogeneity, life-cycle structure, and both local and long-distance dispersal. On the decision-making side, we constrained a general-purpose LLM to a simple, well-defined action space and embedded it in a loop where it must respect budgets and react to partial summaries of the state. The resulting hybrid simulator provides a transparent environment in which LLM-based policies can be evaluated alongside simple rule-based baselines.

The main empirical finding from our baseline experiment is that the LLM policy substantially outperforms both the greedy and simple heuristic rules in this scenario. It eradicates kudzu within three years, uses fewer intervention months, and does not exhaust the available budget. The greedy policy under-reacts: by focusing only on the single densest cell each month and never addressing the seed bank, it allows the invasion to progress almost as if no management were occurring. The simple heuristic over-reacts: it spends heavily and treats

305 many hotspots each month, limiting spread but never quite driving the system to zero. The  
306 LLM appears to exploit the temporal structure of the invasion, focusing on key clusters and  
307 life-cycle stages at the right times and then relaxing once the invasion is under control.

308 At the same time, the project highlights the limitations and challenges of using LLMs in  
309 this role. The quality of the LLM’s behavior depends crucially on how we construct the prompt  
310 and observation; early versions that omitted important constraints produced unrealistic or  
311 budget-violating plans. API rate limits and query costs constrained the number of experiments  
312 and ablations we could perform. Our ecological model is also simplified: we ignore detection  
313 uncertainty, travel cost between sites, and heterogeneous stakeholder values, all of which  
314 matter in real management situations. Finally, because we relied on a single random seed  
315 and did not perform formal calibration against field data, our conclusions are based on one  
316 stylized case rather than a robust statistical ensemble.

317 If this work were extended, several directions seem most promising. First, repeated Monte  
318 Carlo experiments over different seeds and parameter sets would allow us to quantify vari-  
319 ability and construct confidence intervals for metrics such as final infestation and total cost.  
320 Second, the action space could be enriched to include spatially contiguous treatments, differ-  
321 ent treatment intensities, or priority rules for protecting critical habitats, which would test  
322 whether the LLM can still find efficient policies when given more freedom. Third, the obser-  
323 vation model could be made more realistic by introducing noisy or partial detection and by  
324 making surveys an important information gathering action rather than a placeholder. Finally,  
325 other decision-making agents such as reinforcement learning policies or planning algorithms  
326 could be implemented within the same framework and compared directly to the LLM, helping  
327 to clarify when language-based agents offer unique advantages.

328 Overall, our simulator shows that large language models can be integrated into ecological  
329 CA models as plausible adaptive managers, at least in simplified settings. The approach  
330 offers a flexible way to explore how high-level reasoning and domain knowledge encoded in  
331 LLMs might complement traditional optimization and rule-based strategies in conservation  
332 and invasive species management.

333

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351       **SM8. Appendix A: Division of Labor.** The work on this project was divided among the  
352 team members as follows. Aaron led the ecological modeling and CA implementation. He  
353 implemented the `KudzuField` class, defined land-cover-based carrying capacities, coded the  
354 life-cycle transitions and spatial spread mechanisms, and created the data parser that ini-  
355 tializes infestations from the NetLogo-style data. Tristan focused on the integration between  
356 the CA and the management agent. He designed the structure of the monthly field obser-  
357 vation, specified the action schema, implemented the code that applies actions to the CA at  
358 the beginning of each month, and helped wire these components into the main runner and  
359 experiment scripts.

360       Michael concentrated on the decision-making module and budget logic. He implemented  
361 the `llm_policy` function that constructs prompts and calls the Gemini API, designed and  
362 implemented the `BudgetManager` class that prices and validates actions, and modified the  
363 runners so that different policies could be selected via simple configuration flags. Linyuan led  
364 the analysis and visualization as well as bank seed removal action for the project. She wrote  
365 the scripts that run baseline comparisons, compute summary statistics from the JSON logs,  
366 and generate the full set of plots, including time-series comparisons, bar charts of key metrics,  
367 cost-effectiveness scatter plots, and the comprehensive dashboard figure. Jae initialized and  
368 maintained the GitHub repository, set up the branching structure, and coordinated code  
369 reviews and integration across branches. He also wrote and edited the LaTeX documentation  
370 for the checkpoint reports and this final report, making sure that the written description of  
371 the model, experiments, and results remained consistent with the evolving code.