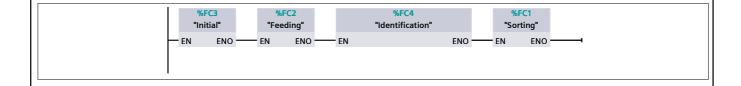
Totally Integrated Automation Portal		
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# Main [OB1]

<b>Main Propert</b>	ies :				
General					
Name	Main	Number	1	Туре	OB
Language	LAD	Numbering	Automatic		
Information					
Title	"Main Program Sweep (Cycle)"	Author		Comment	
Family		Version	0.1	User-defined ID	

Name	Data type	Default value	Supervi- sion	Comment
<b>▼</b> Input				
Initial_Call	Bool			Initial call of this OB
Remanence	Bool			=True, if remanent data are available
Temp				
Constant				

## Network 1:



•

## Feeding [FC2]

Feeding Prop	perties				
General					
Name	Feeding	Number	2	Туре	FC
Language	LAD	Numbering	Automatic		
Information					
Title		Author		Comment	
Family		Version	0.1	User-defined	
				ID	

Name	Data type	Default value	Supervi- sion	Comment
Input				
Output				
InOut				
Temp				
Constant				
<b>▼</b> Return				
Feeding	Void			

#### Network 1:

#### Network 2:

```
%IO.3

"A-Piece_In__
Forward"

SR

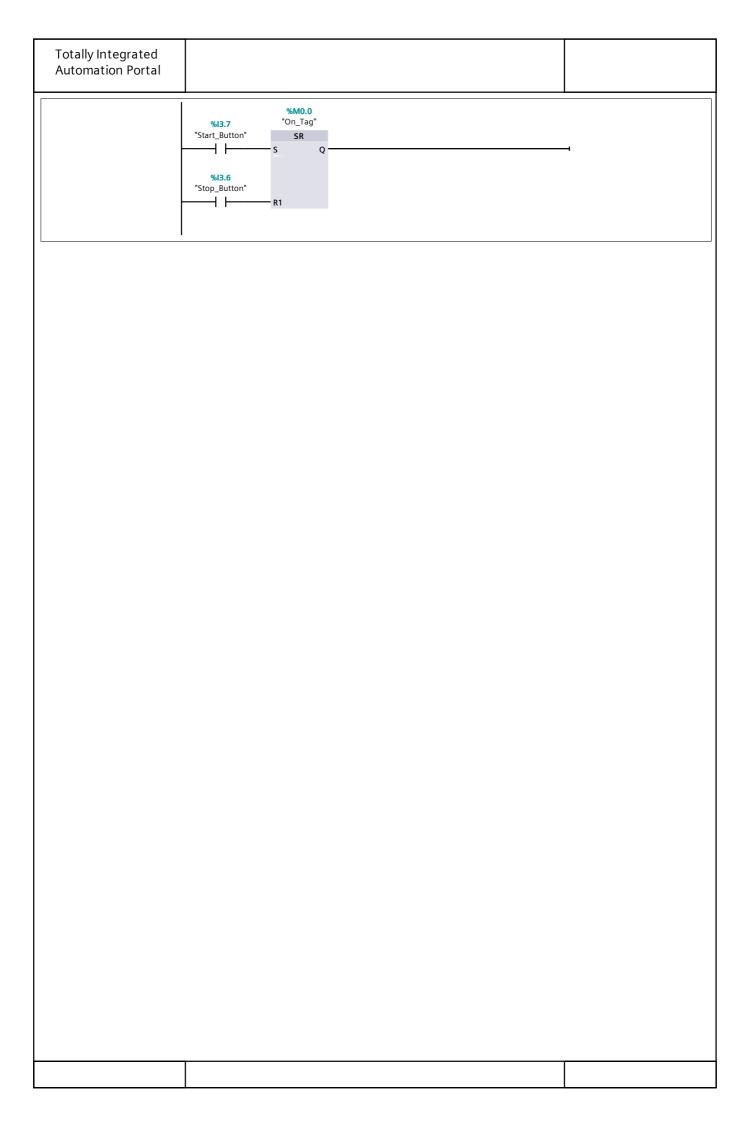
S Q

WIO.0

"A-Sens_Pos__
Back"

R1
```

## Network 3:



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## **Identification [FC4]**

Identification	n Properties				
General					
Name	Identification	Number	4	Туре	FC
Language	LAD	Numbering	Automatic		
Information					
Title		Author		Comment	
Family		Version	0.1	User-defined ID	

Name	Data type	Default value	Supervi- sion	Comment
Input				
Output				
InOut				
Temp				
Constant				
▼ Return				
Identification	Void			

#### Network 1: Set White\_Tag for White piece

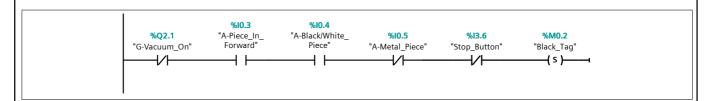
```
%IO.3 %IO.4

%Q2.1 "A-Piece_In_ "A-Black/White_ %IO.5 %I3.6 %MO.1

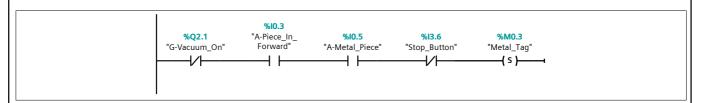
"G-Vacuum_On" Forward" Piece" "A-Metal_Piece" "Stop_Button" "White_Tag"

( s )
```

## Network 2: Set Black\_Tag for Black Piece



## Network 3: Set Metal\_Tag for metallic piece



#### Network 4: Reset tag

Totally Integrated Automation Portal						
	%Q2.1 "G-Vacuum_On"	%M1.1 "is_at_Dropoff_ Location"	%M0.2 "Black_Tag" { R }	%M0.1 "White_Tag" 	%M0.3 "Metal_Tag" 	-

Totally Integ	grated									
Automation	Portal									
Initial [FC3	R1									
mada ji Ca	<b>,</b> 1									
Initial Propertie	es									
General Name	Initial			<b>N</b> 1		3			T	FC
	LAD					Automatic			Туре	FC
Information						7.14.04.10				
Title				_	thor				Comment	
Family				Ve	rsion	0.1			User-defined ID	
Name			Data type	•	Default val	ue	Supervi- sion	Cor	nment	
Input							31011			
Output										
InOut										
Temp										
Constant										
▼ Return										
Initial			Void							
Network 1:										
		"C+a	<b>%I3.7</b> rt_Button"						<b>%Q0.1</b> "A-Cyl_Backward'	
		Stal	п_вишоп <b>—</b>						A-Cyl_Backward	
	ı									
	1								П	

ties Sorting LAD								
Sorting								
Sorting								
LAD		Nu	mber	1			Туре	FC
			mbering	Automatic			.,,,,	į. C
			thor				Comment	
		Vei	rsion	0.1			User-defined ID	
	Data typ	e	Default va	lue	Supervi-	Cor	nment	
					31011			
	Void							
	Position co		Data type  Void	Void	Data type Default value	Data type Default value Supervision  Void	Data type Default value Supervision  Void	Data type Default value Supervision  Void

CV

#### 22 **— PV** %DB3 "IEC\_Counter\_ O\_DB\_2" **%I2.1** "G-Sens\_ Impuls\_10°" CTU %M0.1 "White\_Tag" Int +**-** | |-- cu Q cv -%Q2.2 "G-Arm\_Turn\_ Right" 25 — PV **%I3.6** "Stop\_Button" %Q2.1

## Network 2: Arm goes right

**%Q2.2** "G-Arm\_Turn\_ Right"

"G-Vacuum\_On"

```
%DB8
                                             "IEC_Timer_0_
DB_2"
                                                                                         %Q2.2
"G-Arm_Turn_
Right"
                                                  TON
     %12.3
                           %Q2.1
"G-Sens_Pos_Left"
                      "G-Vacuum_On"
                                                 Time
                                             · IN
                                                          Q
                                                                                         S
                                                                                                      Q
                             T#2000ms -
                                             PT
                                                         ET -
     %M1.1
 "is_at_Dropoff_
Location"
      H F
```

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#### Network 3: G arm left

```
%DB4
"IEC_Timer_0_DB"
                                                                                                               %Q2.3
                           %10.3
                                                                                                         "G-Arm_Turn_Left"
                                                TON
     %M0.0
                       "A-Piece_In_
Forward"
                                                                    %Q2.1
                                                                                          %I2.3
                                                               "G-Vacuum_On" "G-Sens_Pos_Left"
    "On_Tag"
                                               Time
      + +
                                                                     <del>-</del>1/1-
                                                                                           <del>/</del>/
                                           - IN
                                                       Q-
                                                                                                           - S
                             T#500ms — PT
                                                ET --- ...
     %13.7
 "Start_Button"
      \dashv \vdash
                           %DB5
                      "IEC_Timer_0_
DB_1"
     %M1.1
"is_at_Dropoff_
Location"
                           TON
     \dashv \vdash
                                  Q ·
       T#1500ms — PT
                                  ET -
     %12.3
"G-Sens_Pos_Left"
      \dashv \vdash
     %12.0
"G-Sens_Pos_Up"
     %13.6
 "Stop_Button"
      H F
```

#### Network 4: G down

```
%Q2.0
"G-Down_On"
    %M1.1
"is_at_Dropoff_
Location"
                                                              SR
    \dashv \vdash
    %10.3
 "A-Piece_In_
Forward"
                         %12.3
                   "G-Sens_Pos_Left"
     +
                          4 +
                        %DB7
                     "IEC_Timer_0_
DB_4"
                         TON
   %Q2.0
"G-Down_On"
     \vdash
                     IN
                                Q·
      T#1000ms — PT
                                ET -----
    %I3.6
"Stop_Button"
```

Network 5: G vacuum on

#### Totally Integrated **Automation Portal** %Q2.1 %10.3 "A-Piece\_In\_ Forward" "G-Vacuum\_On" %Q2.0 %I2.3 "G-Down\_On" "G-Sens\_Pos\_Left" SR <del>|</del> | |-+%DB6 "IEC\_Timer\_0\_ DB\_3" %M1.1 TON "is\_at\_Dropoff\_ Time Location" · IN Q· PT ET -**Network 6: Transfering** %M0.4 %Q2.2 "G-Arm\_Turn\_ Right" "is\_Transfering" **%I3.6** %Q2.1 "G-Vacuum\_On" "Stop\_Button" SR $\dashv$ $\vdash$ <del>-</del>1/-+%13.6 "Stop\_Button" <del>|</del> | | %12.3 "G-Sens\_Pos\_Left"

## Network 7: 1 cycle of sorting