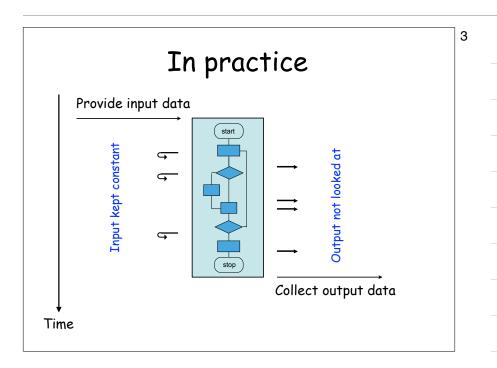
TinyTimber

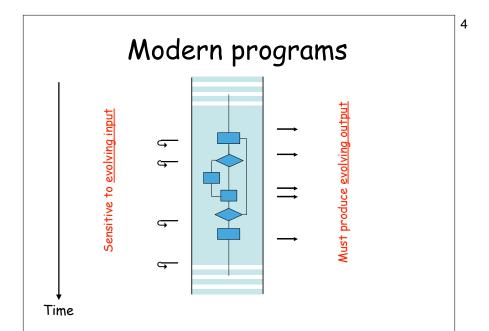
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Real-Time Systems EDA223

Jan 15, 2018

Provide input data Provide input data Collect output data Time





Why?

- Because modern computers are components among other evolving components like
 - Keyboards, mice and displays
 - Human users behind these components
 - Network interfaces
 - Other computers behind these components
 - Sensors and actuators
 - Real physical objects behind these components
- Because a modern computer program is very rarely in superior control of its environment

Dealing with evolving input

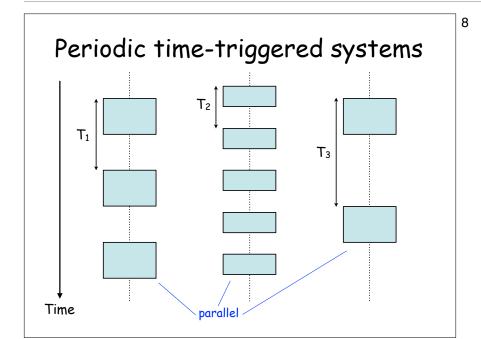
- Approach 1: New input is read from the environment at the initiative of the program
 - (As often as "possible"...)
 - (Or in an ad hoc fashion...)
 - Or at well-defined times!
- Approach 2: New input is written into the program at the initiative of the environment
 - (Just to be stored somewhere...)
 - Or guaranteed to trigger an associated reaction!

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Approach 1: Time-triggered systems

- Idea: read input at pre-defined times, chosen to match the expected variations in input
- Obvious special case: read input every T time units (the periodic process)
- What happens between the computations? Nothing the CPU can just shut down!
- How choose T? Use Nyqvist's sampling theorem!
- What if there are multiple inputs?
 - Let the highest frequency input determine T...
 - Or run multiple periodic processes in parallel!



Adding input/output

Read sequence

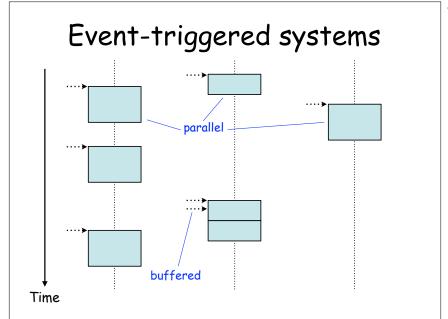
Write sequence

Time

Note how each invocation corresponds to the classic program model

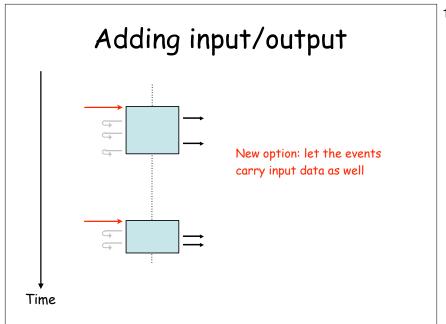
Approach 2: Event-triggered systems

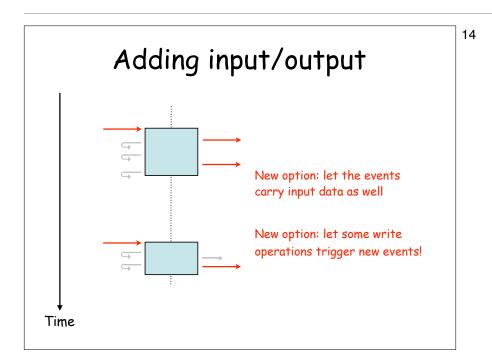
- Idea: let the environment decide when input has changed enough to require some program action; i.e., when an event has occurred
- Well-known concept on the computer hardware level: the external interrupt!
- What happens between the event processing phases? Nothing - the CPU can just shut down!
- What if there are events with overlapping reactions?
 - Buffer up the events...
 - Or run multiple event-handlers in parallel!

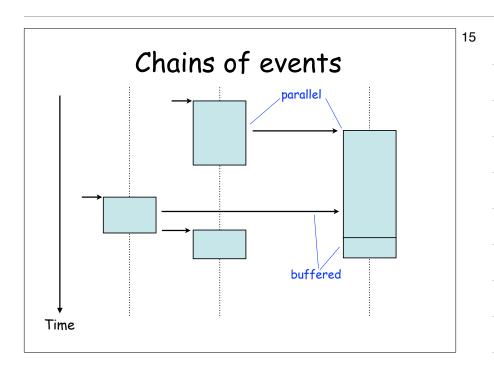


Adding input/output

Again: note how each invocation corresponds to the classic program model!







Time- vs. event-triggered systems

Time-triggered systems observe the environment and take action on basis of the changes they see.

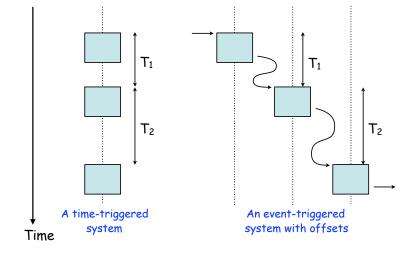
Suitable when input may be constantly changing and all value are equally interesting, like in control systems

Event-triggered systems are controlled by the environment, and take action when the environment so decides.

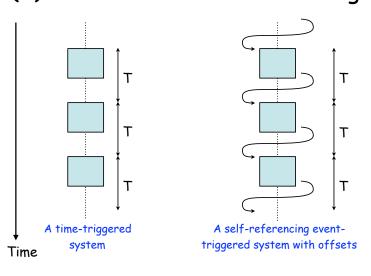
Suitable when interesting input values are highly irregular, or when it is already discrete, like in communication systems

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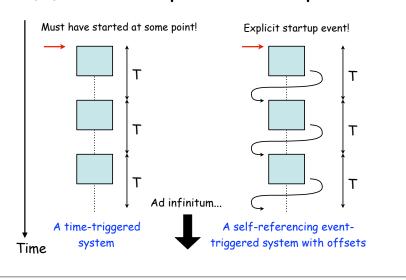
(1) If we allow events with offsets...



(2) If we allow self-referencing...

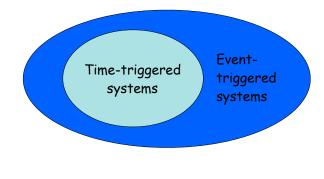


(3) If startup is made explicit...



Then:

Time-triggered behavior emerges as a special case of an event-triggered system!



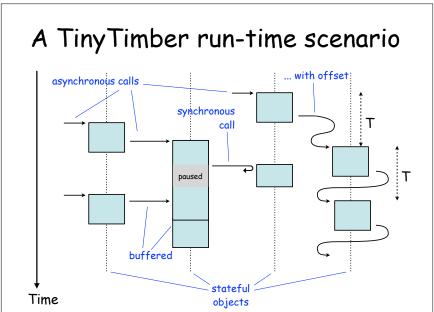
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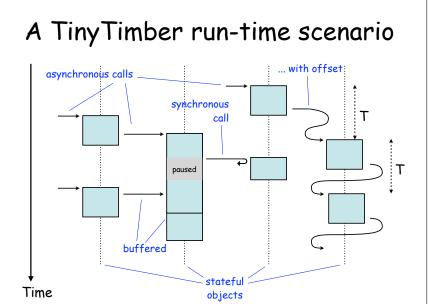
Time-triggerering as a special case

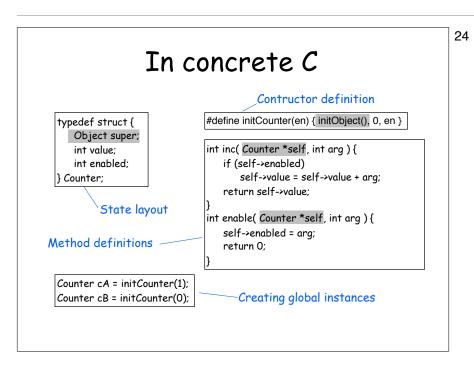
- A time-triggered behavior is just a chain of event reactions, separated by well-defined time offsets
- A periodic process is such a chain-reaction that oscillates (produces as many new events as those it reacts to)
- Many hybrid variants exist between the extremes of one single reaction and the oscillating periodic behavior
- Allows us to seamlessly study trade-offs between the basic approaches
- Note: not the commonly taught real-time systems view!
- It is however the view we find in TinyTimber!

TinyTimber

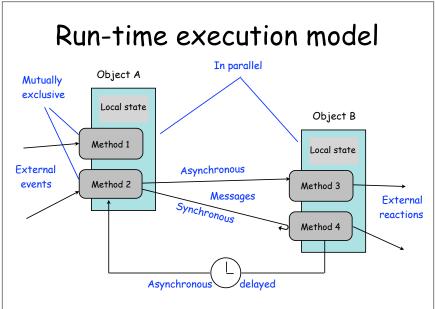
- A run-time kernel + a design style for programming embedded real-time systems in C
- Also a cut-down variant of the programming language Timber (timber-lang.org)
- Basic ideas:
 - Events can be triggered with time offsets
 - Events = asynchronous method calls
 - Methods belong to objects
 - Objects = protected sets of state variables
 - Also: synchronous method calls (mimic read/write)

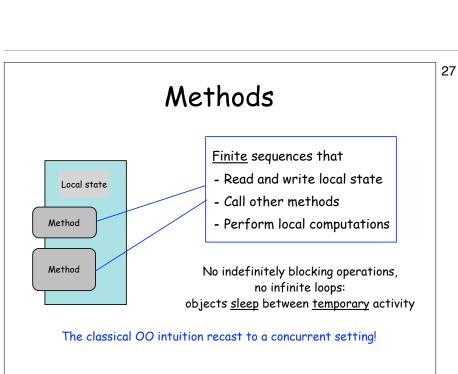


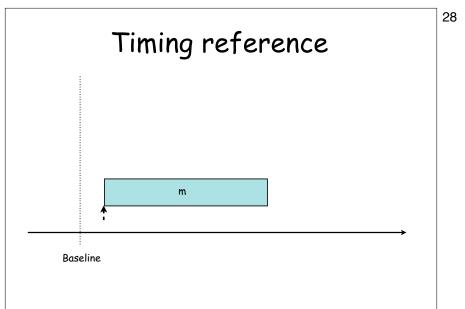


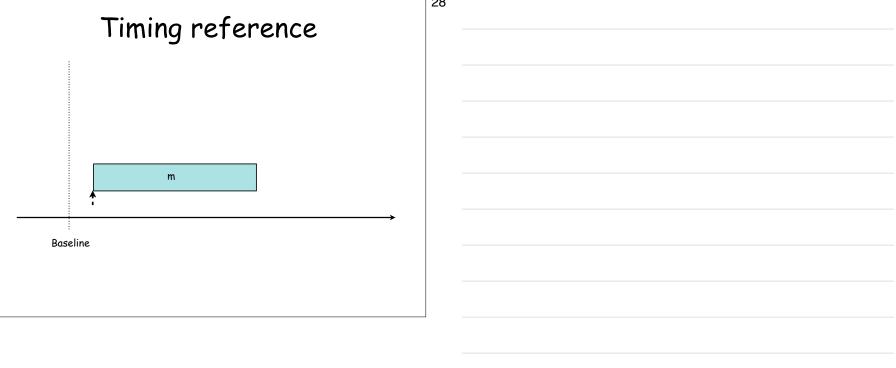


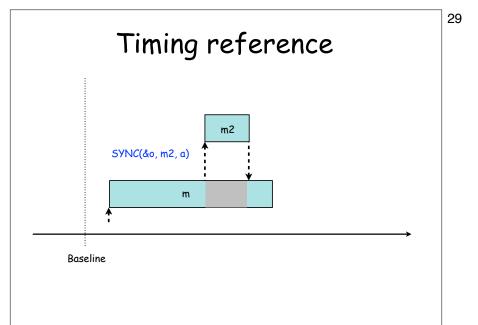
Calling methods ... ASYNC(&cA, inc, 1); int r = SYNC(&cA, inc, 0); AFTER(SEC(2), &cB, enable, 1); ... Top-level application setup MyApplication app = initMyApplication(); int main() { INSTALL(&app, compute, IRQ1); INSTALL(&cB, inc, IRQ2); return TINYTIMBER(&app, reset, 0); }

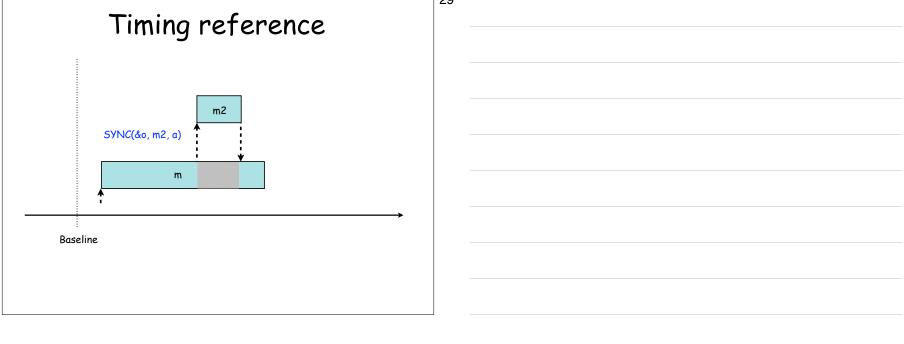


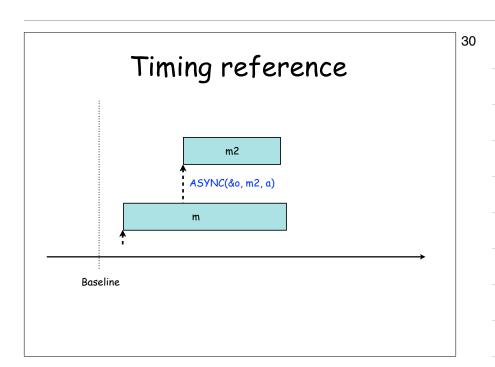




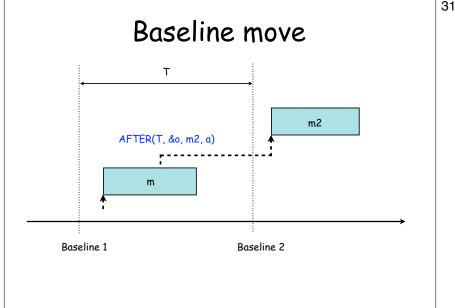






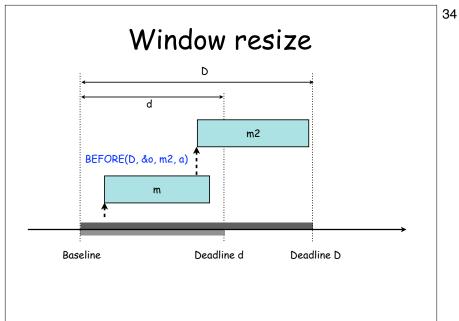


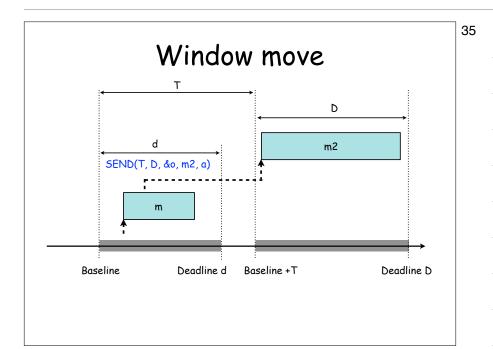


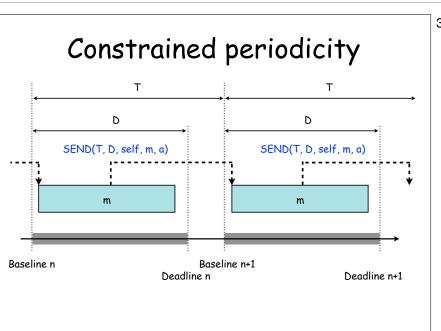


32 Periodicity AFTER(T, self, m, a) AFTER(T, self, m, a) Baseline n Baseline n+1

33 Timing windows Deadline Baseline



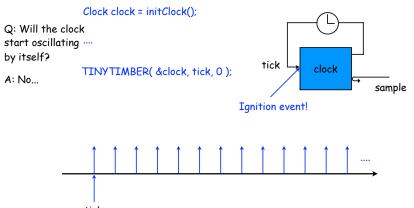




A clock

```
typedef struct {
   Object super;
                                                    typedef struct {
  int sec, min, hour;
                                                      int sec, min, hour;
} Clock;
                                                    } CalendarTime;
#define initClock() \{ initObject(), 0, 0, 0 \}
                                                      Use pointer to
int tick( Clock *self, int arg ) {
                                                      circumvent one-arg-only
                                                      restriction.
   if (self->sec == 60) { self->sec = 0; self->min++; }
  if (self->min == 60) { self->min = 0; self->hour++; } (Only safe with SYNC)
  AFTER( SEC(1), self, tick, 0 )
int sample( Clock *self, CalendarTime *arg ) {
  arg->sec = self->sec; arg->min = self->min; arg->hour = self->hour;
```

A clock



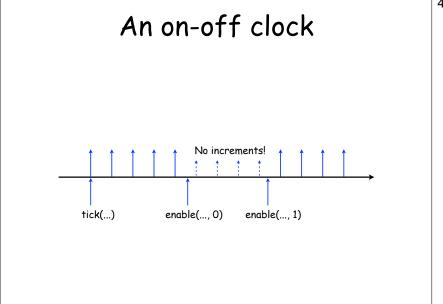
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tick

An on-off clock

```
typedef struct {
  Object super;
  int sec;
  int enabled;
} OnOffClock;
\#define\ initOnOffClock()\quad \{\ initObject(),\, 0,\, 1\, \}
int tick( OnOffClock *self, int arg ) {
  if (self->enabled)
    self->sec = self->sec + 1;
  AFTER( SEC(1), self, tick, 0 )
int sample( OnOffClock *self, int arg ) { return\ self->sec; }
```



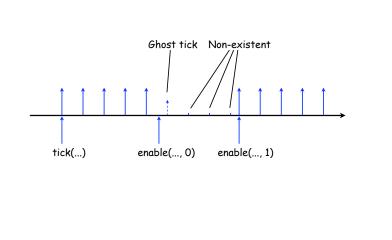


A different on-off clock

```
typedef struct {
  Object super;
  int sec, enabled;
} OnOffClock2;
#define initOnOffClock2() { initObject(), 0, 1 }
int tick( OnOffClock2 *self, int arg ) {
  if (self->enabled) {
    self->val = self->val + 1;
AFTER( SEC(1), self, tick, 0 )
}
int sample( OnOffClock2 *self, int arg ) { \  \, return\ self\rightarrow\!sec;\ \ }
self->enabled = en;
```

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A different on-off clock



Timber

- The big brother of TinyTimber
- Full-featured language:
 - Higher-order & strongly typed
 - Dynamic object creation, garbage-collected heap
 - Haskell-like syntax (but no laziness!)
 - Purely functional computation sub-language
- A real-time successor to O'Haskell (an OO Haskell ext.)
- Developed in part by groups & individuals at Chalmers,
 Luleå U. of T., Oregon Grad. Inst., Kansas State U.

Compiling Timber Timber source code Timber compiler C source code C compiler and linker O11001101 O01000 RTS TinyTimber: C API and programming model C source code

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Wrapping up

TinyTimber offers:

- \bullet Lightweight real-time facilities for ${\it C}$
- · Implicit concurrency
- Implicit state protection
- Object-oriented program structure
- Robust timing semantics

 $\label{lem:main conceptual treshold for programmers: Reactivity!} \\$

The big win of reactivity:

Modular composition of real-time systems with composable timing!