

Tiny Timber

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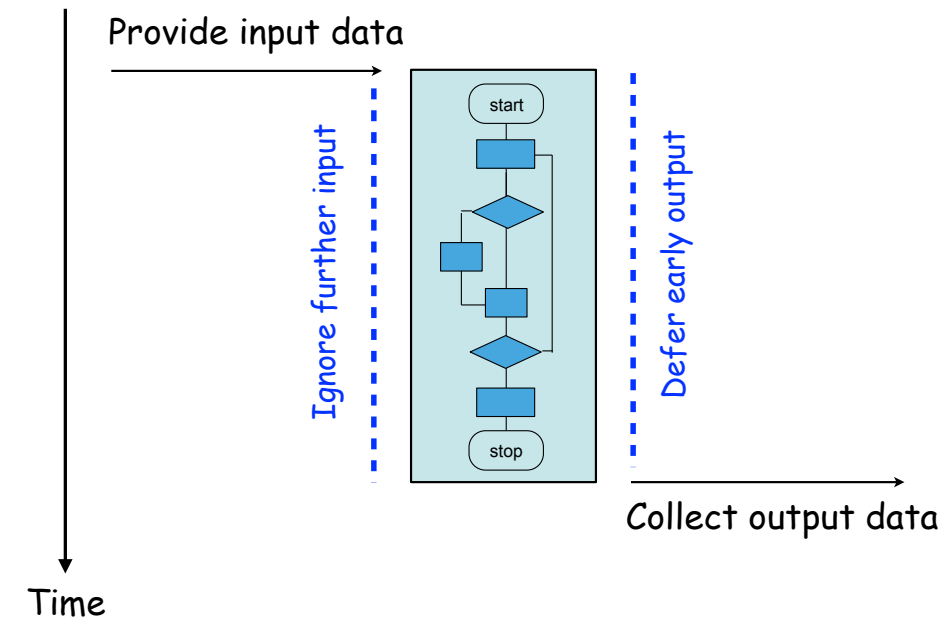
Data Ductus AB / Chalmers

Real-Time Systems EDA223

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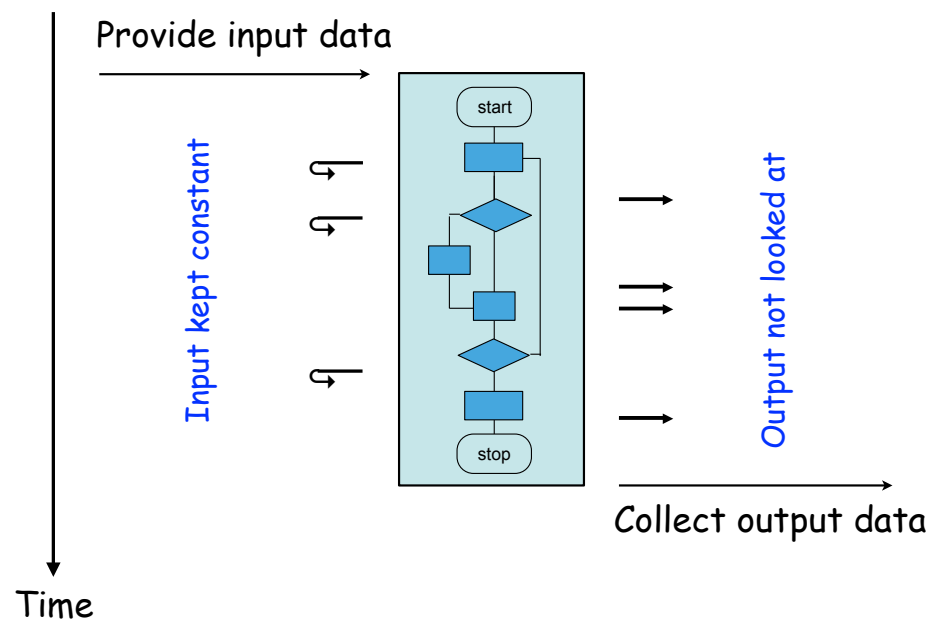
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The classical program



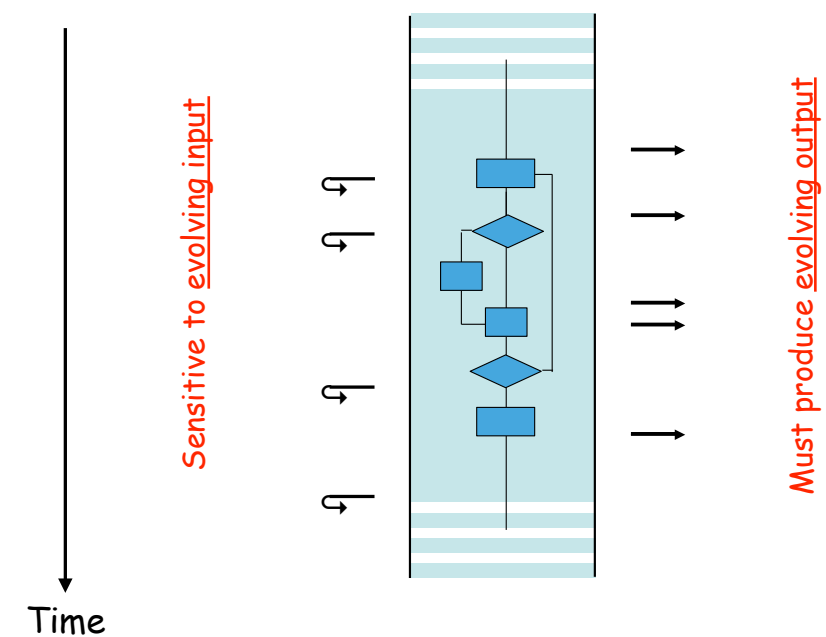
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In practice



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Modern programs



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Why?

- Because modern computers are **components among other evolving components** like
 - Keyboards, mice and displays
 - Human users behind these components
 - Network interfaces
 - Other computers behind these components
 - Sensors and actuators
 - Real physical objects behind these components
- Because a modern computer program is very **rarely in superior control** of its environment

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Dealing with evolving input

- Approach 1: New input is **read** from the environment at the initiative of the **program**
 - (As often as "possible"...)
 - (Or in an ad hoc fashion...)
 - Or at **well-defined times!**
- Approach 2: New input is **written** into the program at the initiative of the **environment**
 - (Just to be stored somewhere...)
 - Or guaranteed to trigger an associated **reaction!**

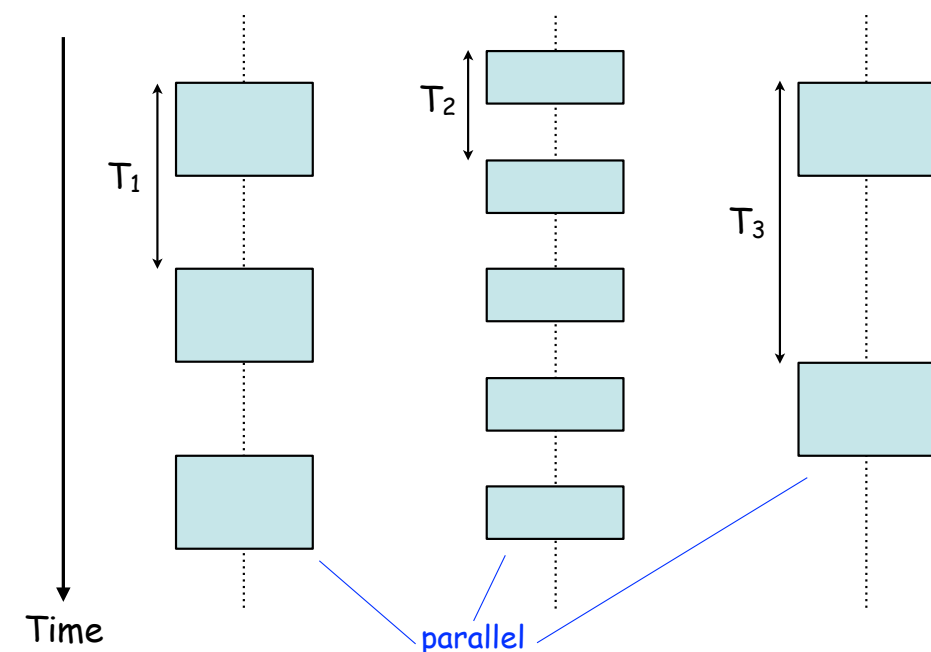
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Approach 1: Time-triggered systems

- Idea: **read** input at **pre-defined times**, chosen to match the expected variations in input
- Obvious special case: read input every T time units (the periodic process)
- What happens between the computations? Nothing - the CPU can just shut down!
- How choose T ? Use Nyquist's sampling theorem!
- What if there are multiple inputs?
 - Let the highest frequency input determine T ...
 - Or run **multiple periodic processes in parallel!**

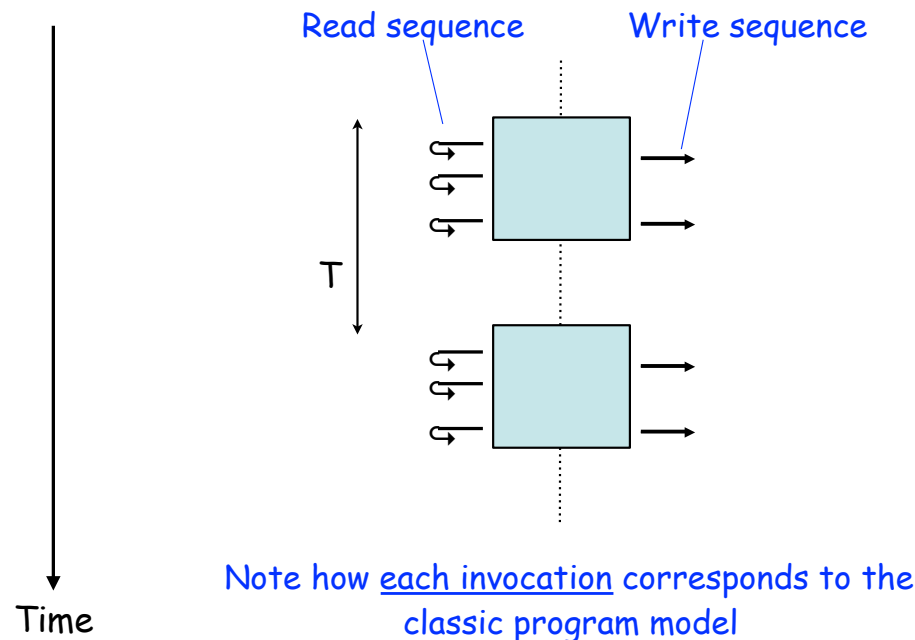
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Periodic time-triggered systems



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Adding input/output



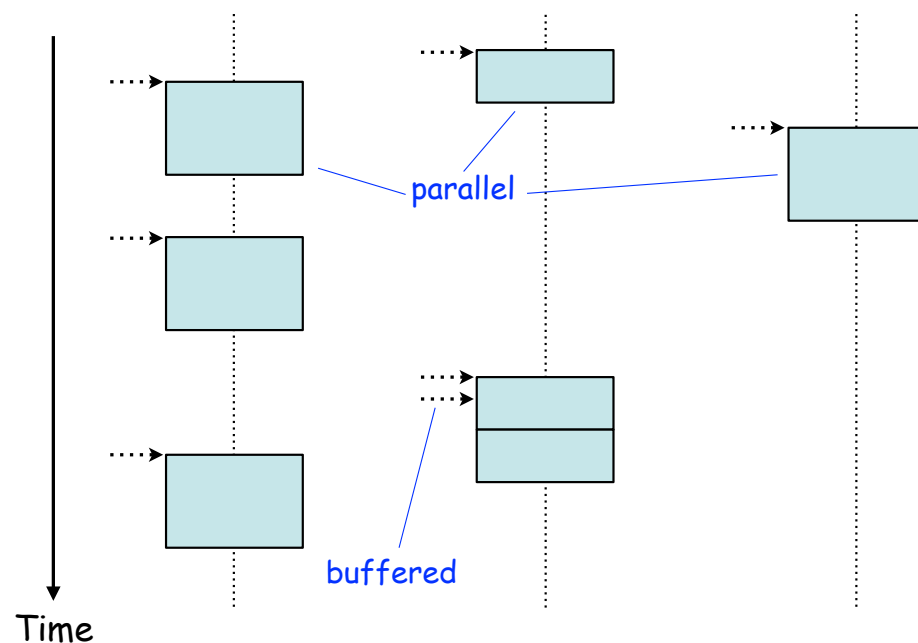
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Approach 2: Event-triggered systems

- Idea: let the environment decide when input has changed enough to require some program action; i.e., when an **event has occurred**
- Well-known concept on the computer hardware level: the external interrupt!
- What happens between the event processing phases? Nothing - the CPU can just shut down!
- What if there are events with overlapping reactions?
 - Buffer up the events...
 - Or run **multiple event-handlers in parallel!**

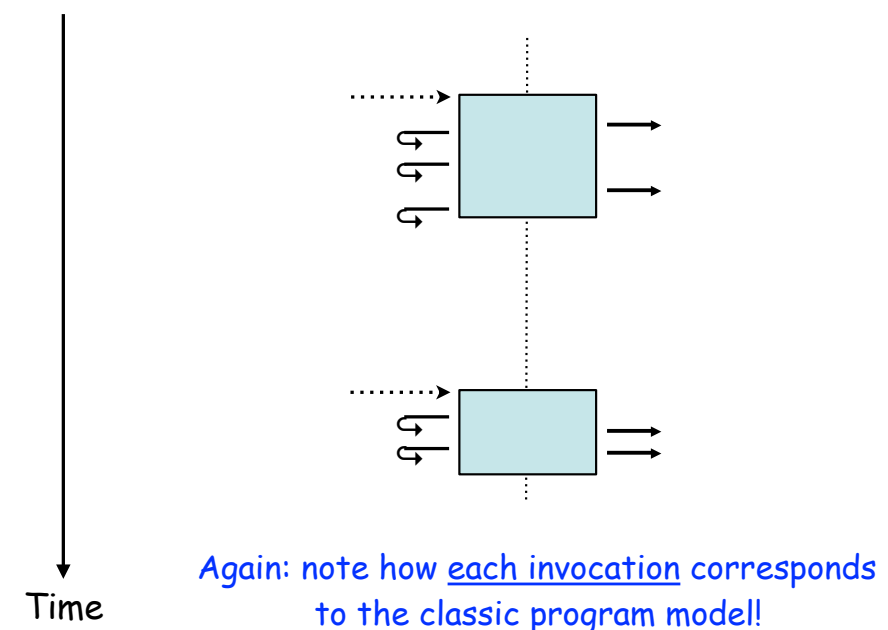
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Event-triggered systems



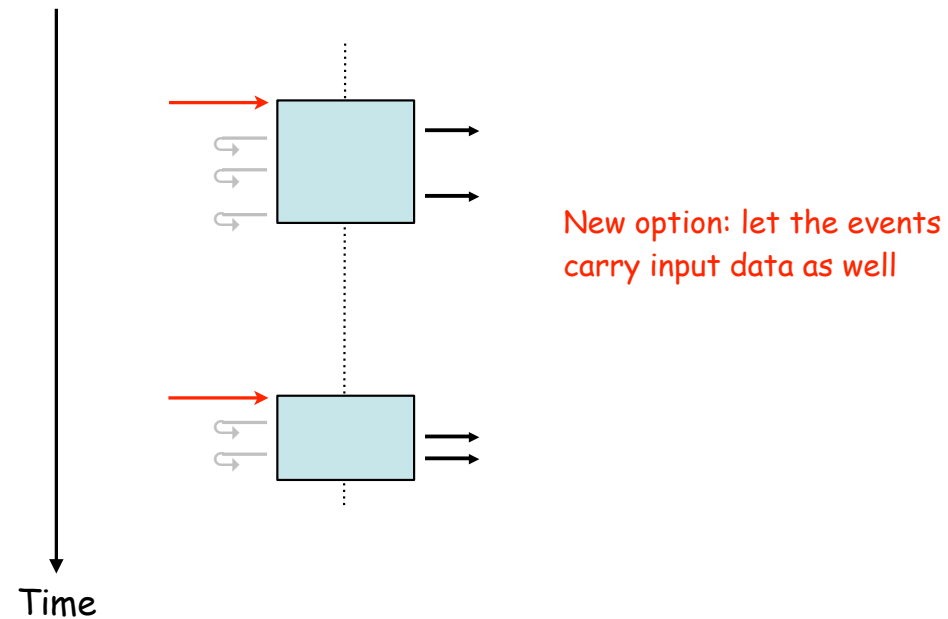
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Adding input/output



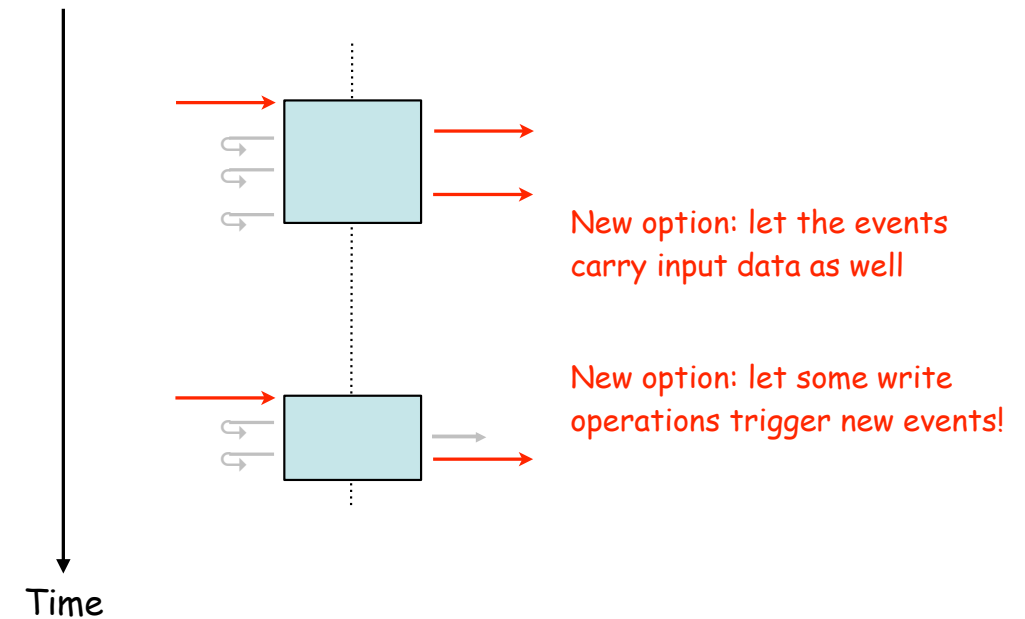
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Adding input/output



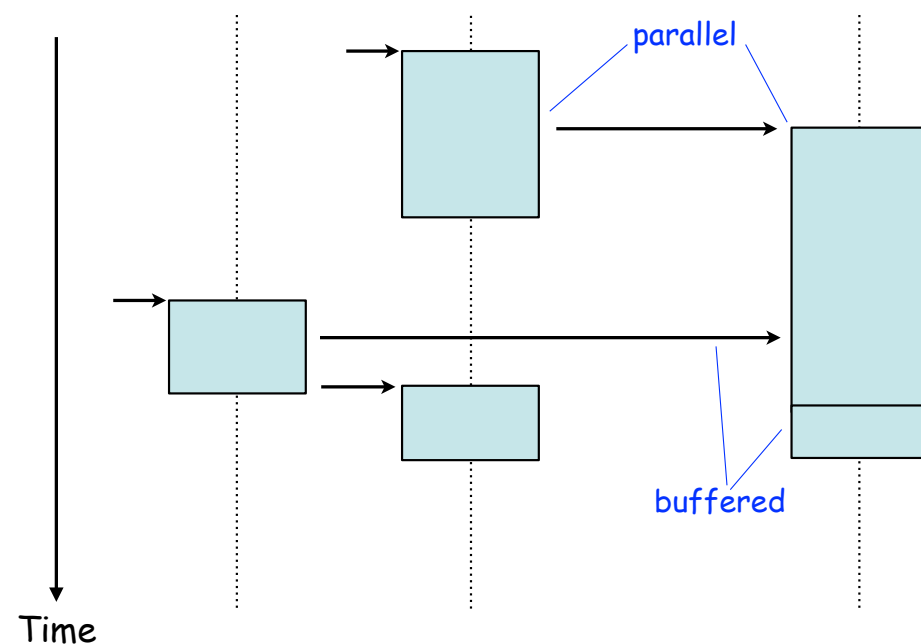
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Adding input/output



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Chains of events



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Time- vs. event-triggered systems

Time-triggered systems **observe** the environment and take action on basis of the changes they see.

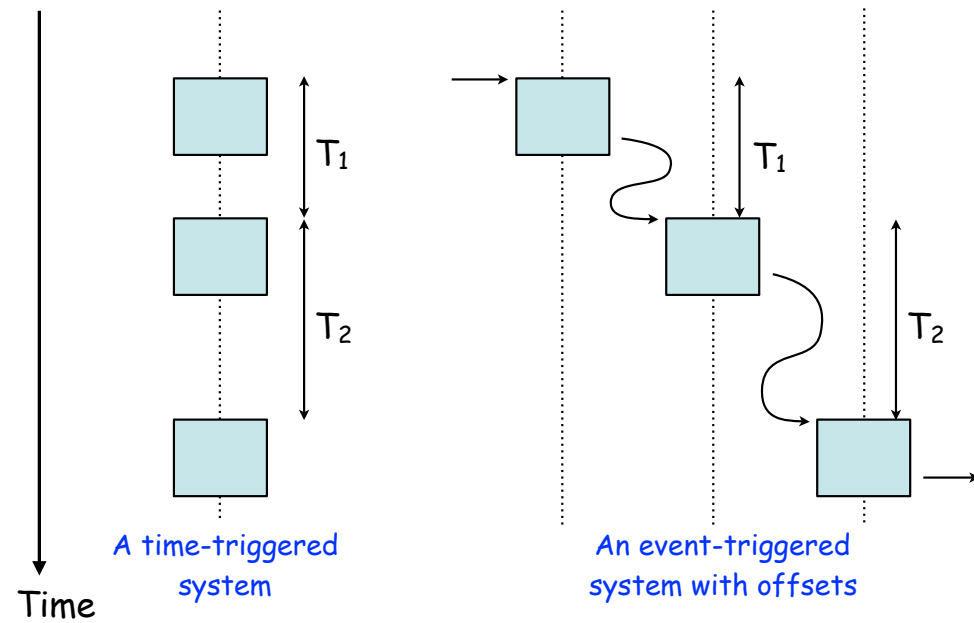
Suitable when input may be **constantly changing** and all value are equally interesting, like in control systems

Event-triggered systems are **controlled by** the environment, and take action when the environment so decides.

Suitable when interesting input values are highly **irregular**, or when it is already **discrete**, like in communication systems

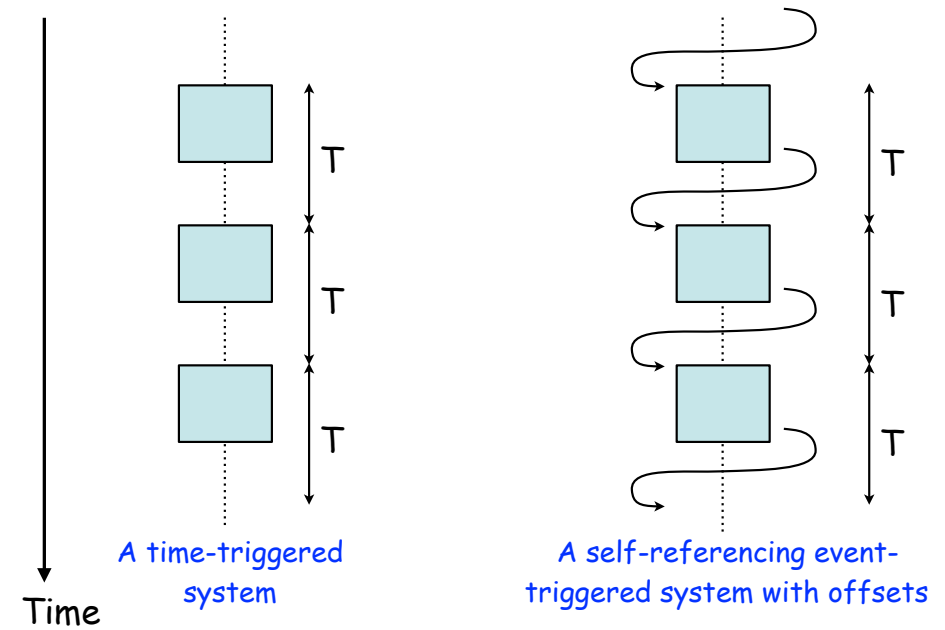
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(1) If we allow events with offsets...



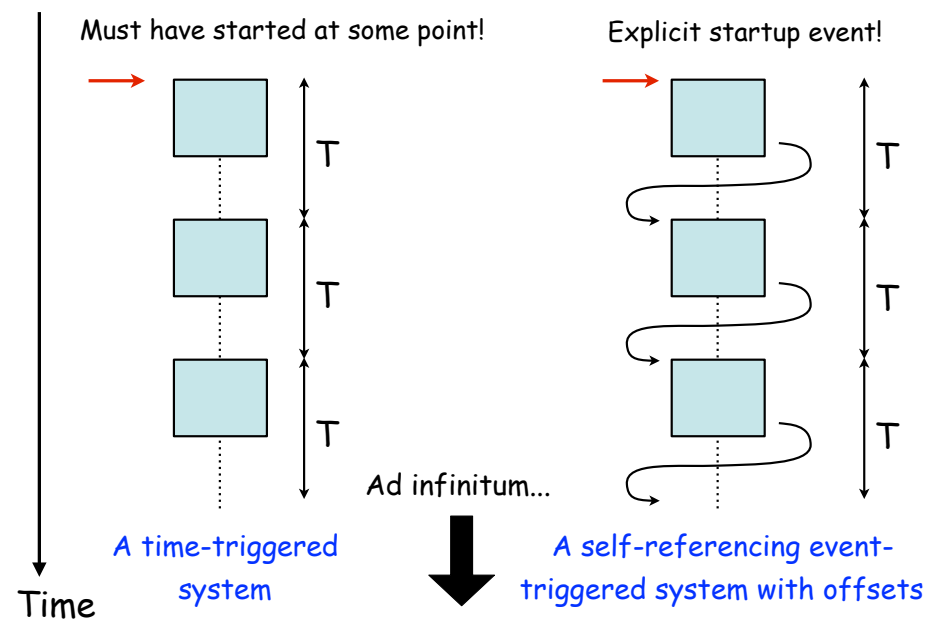
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(2) If we allow self-referencing...



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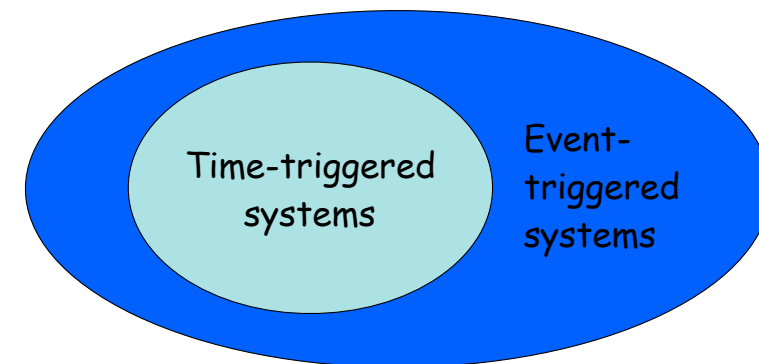
(3) If startup is made explicit...



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Then:

Time-triggered behavior emerges as a special case of an event-triggered system!



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Time-triggering as a special case

- A time-triggered behavior is just a **chain of event reactions**, separated by well-defined **time offsets**
- A **periodic** process is such a chain-reaction that **oscillates** (produces as many new events as those it reacts to)
- Many hybrid variants exist between the extremes of one single reaction and the oscillating periodic behavior
- Allows us to seamlessly study trade-offs between the basic approaches
- Note: not the commonly taught real-time systems view!
- It is however the view we find in **TinyTimber**!

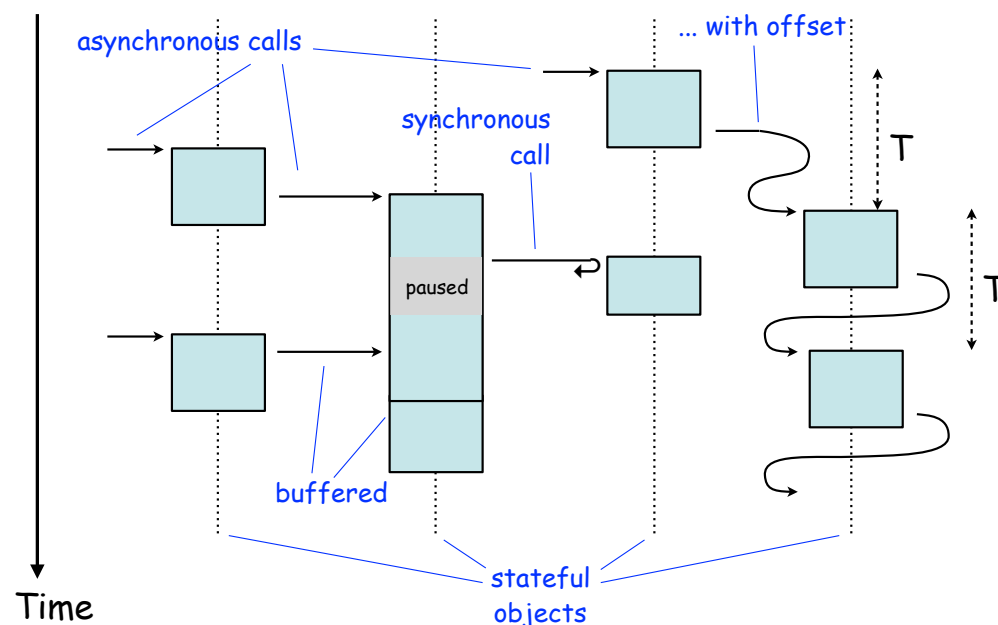
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TinyTimber

- A run-time kernel + a design style for programming embedded real-time systems in C
- Also a cut-down variant of the programming language **Timber** (timber-lang.org)
- Basic ideas:
 - Events can be triggered with time offsets
 - Events = **asynchronous method calls**
 - Methods belong to **objects**
 - Objects = protected sets of state variables
 - Also: **synchronous** method calls (mimic read/write)

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A TinyTimber run-time scenario



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In concrete C

Constructor definition

```
#define initCounter(en) { initObject(), 0, en }
```

State layout

```
typedef struct {
    Object super;
    int value;
    int enabled;
} Counter;
```

Method definitions

```
int inc( Counter *self, int arg ) {
    if (self->enabled)
        self->value = self->value + arg;
    return self->value;
}

int enable( Counter *self, int arg ) {
    self->enabled = arg;
    return 0;
}
```

Creating global instances

```
Counter cA = initCounter(1);
Counter cB = initCounter(0);
```

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Calling methods

```
... ASYNC( &cA, inc, 1 ); ...
```

— Asynchronous call

```
... int r = SYNC( &cA, inc, 0 ); ...
```

— Synchronous call

```
... AFTER( SEC(2), &cB, enable, 1 ); ...
```

— Asynchronous call with offset

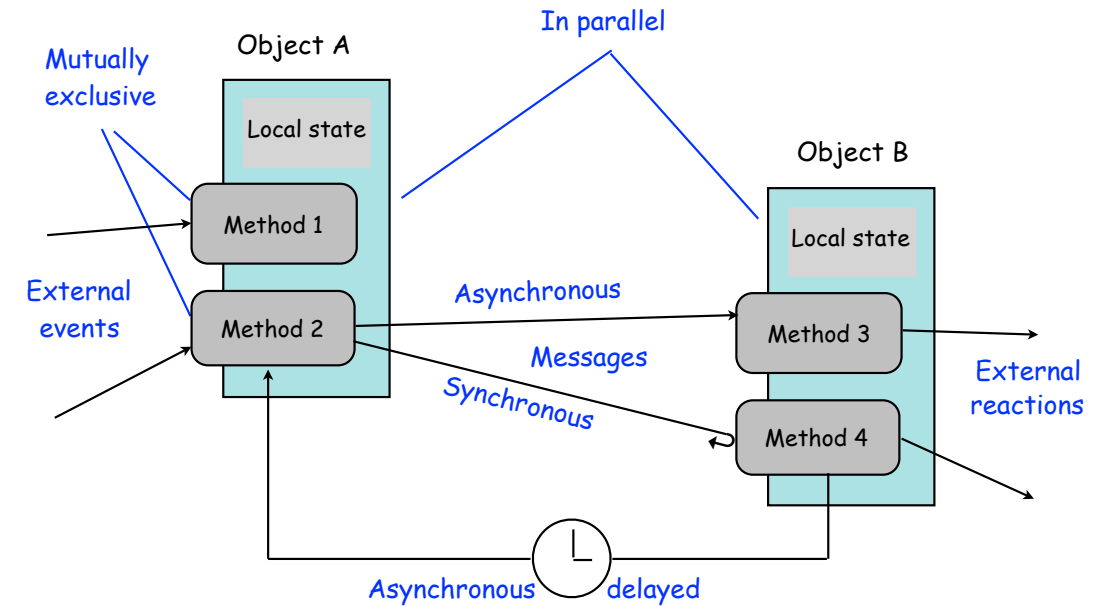
Top-level application setup

```
MyApplication app = initMyApplication();
```

```
int main() {
  INSTALL( &app, compute, IRQ1 );
  INSTALL( &cB, inc, IRQ2 );
  return TINYTIMBER( &app, reset, 0 );
}
```

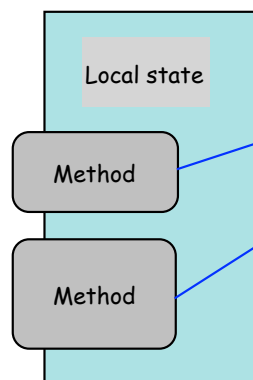
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Run-time execution model



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Methods



Finite sequences that

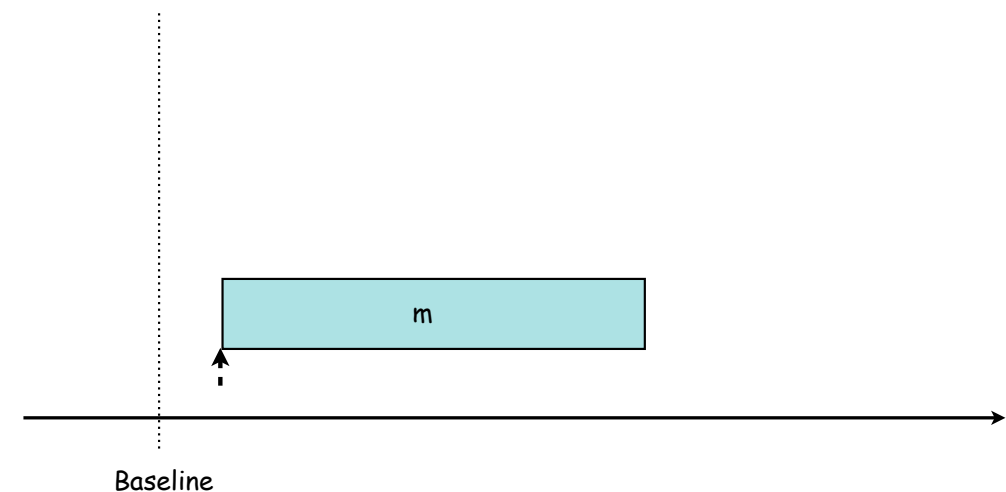
- Read and write local state
- Call other methods
- Perform local computations

No indefinitely blocking operations,
no infinite loops:
objects sleep between temporary activity

The classical OO intuition recast to a concurrent setting!

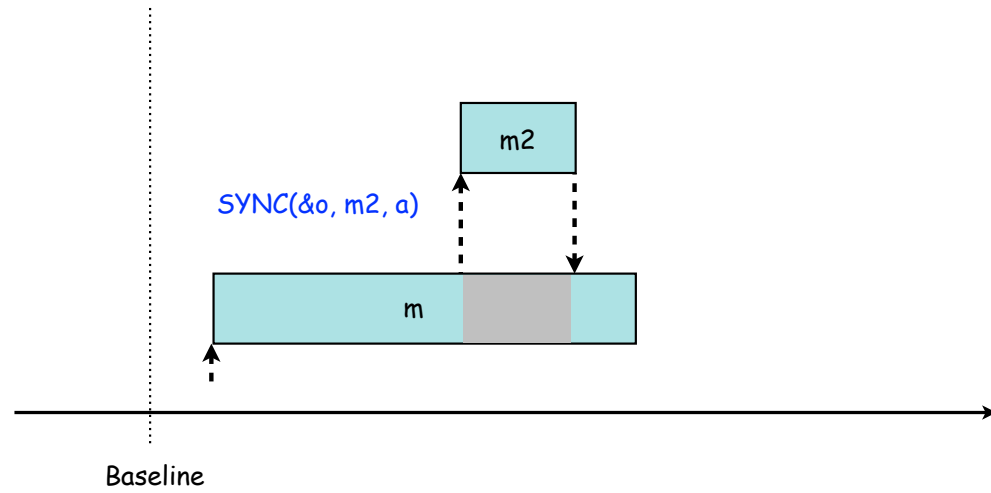
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Timing reference



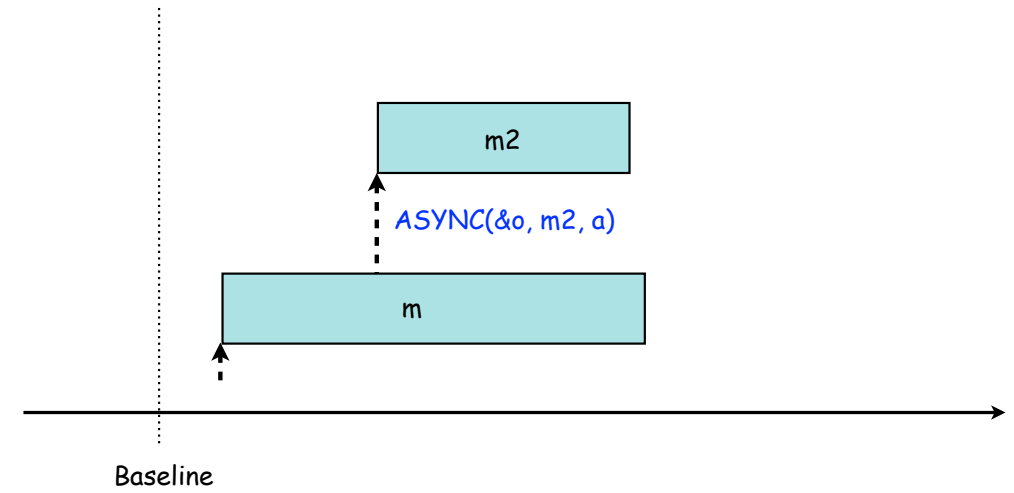
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Timing reference



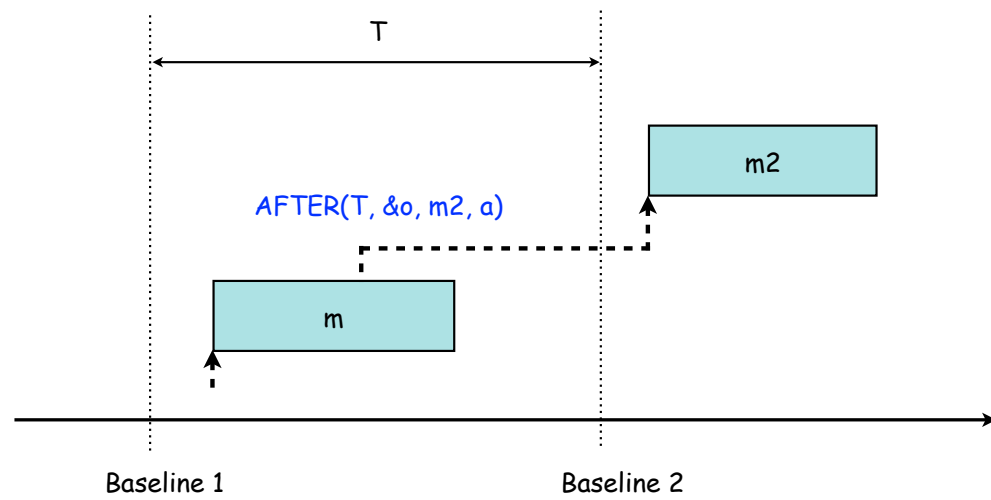
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Timing reference



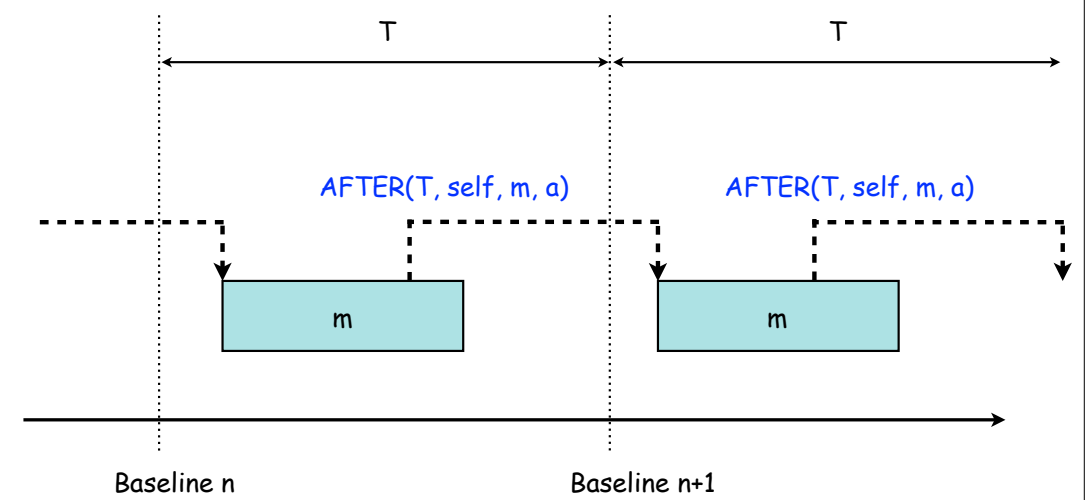
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Baseline move



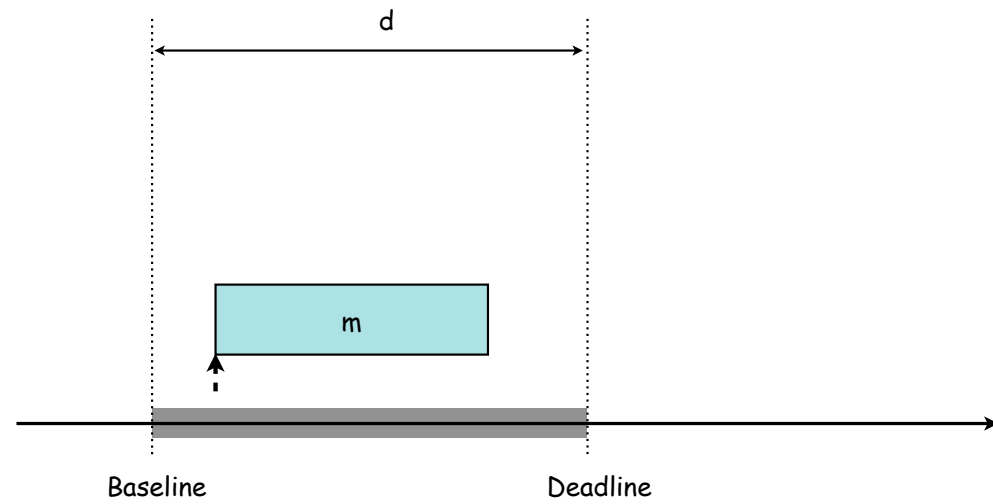
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Periodicity



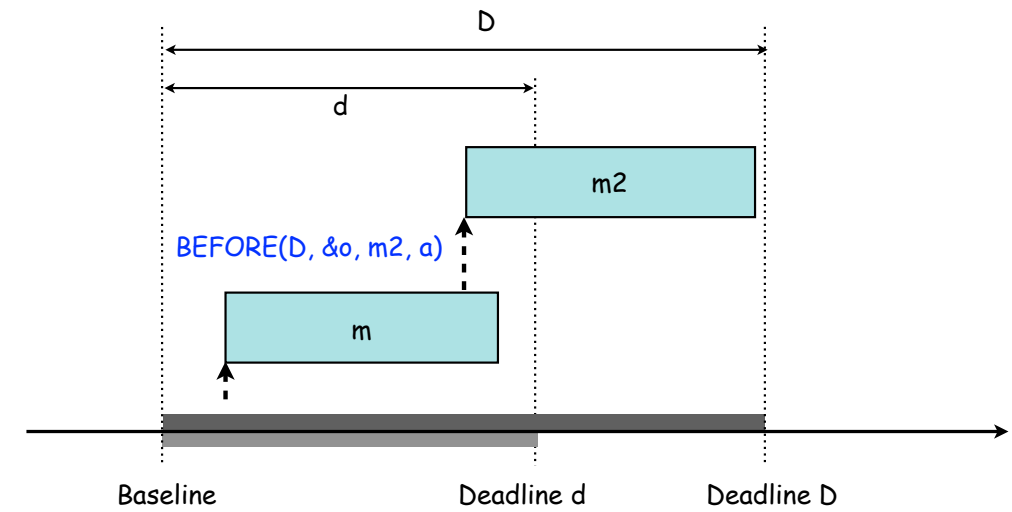
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Timing windows



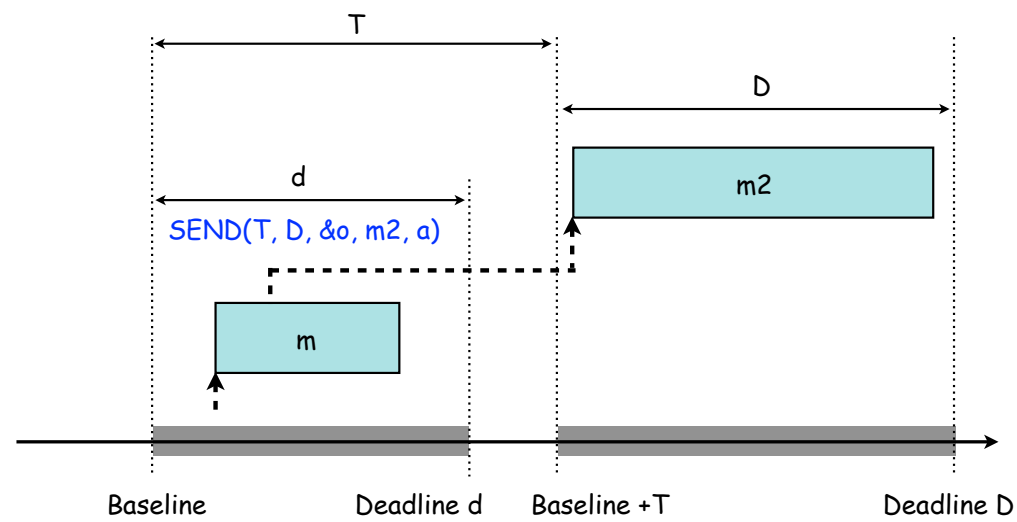
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Window resize



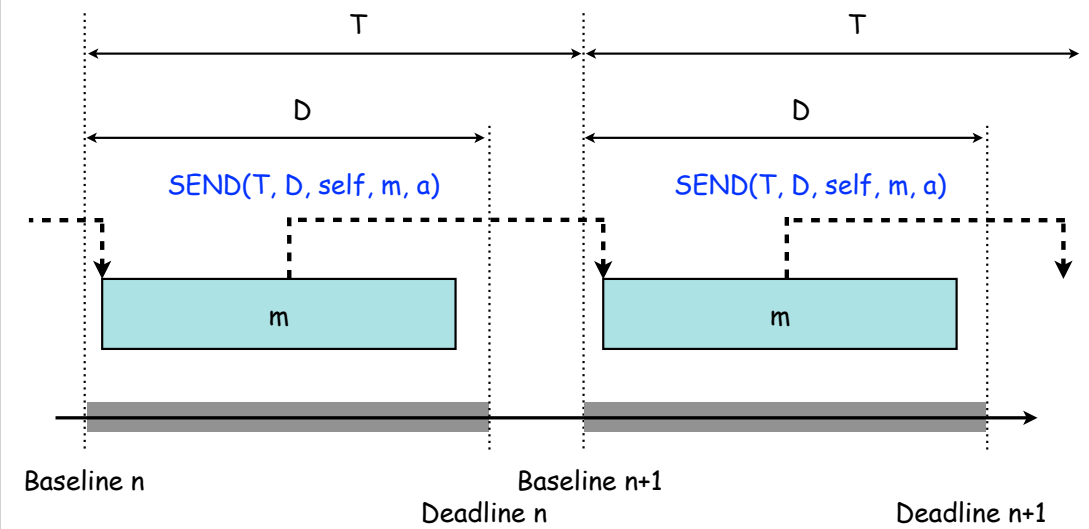
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Window move



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Constrained periodicity



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A clock

```
typedef struct {
    Object super;
    int sec, min, hour;
} Clock;
```

```
#define initClock() { initObject(), 0, 0, 0 }
```

```
int tick( Clock *self, int arg ) {
    self->sec++;
    if (self->sec == 60) { self->sec = 0; self->min++; }
    if (self->min == 60) { self->min = 0; self->hour++; }
    AFTER( SEC(1), self, tick, 0 )
}
```

```
int sample( Clock *self, CalendarTime *arg ) {
    arg->sec = self->sec; arg->min = self->min; arg->hour = self->hour;
}
```

```
typedef struct {
    int sec, min, hour;
} CalendarTime;
```

Use pointer to
circumvent one-arg-only
restriction.
(Only safe with SYNC)

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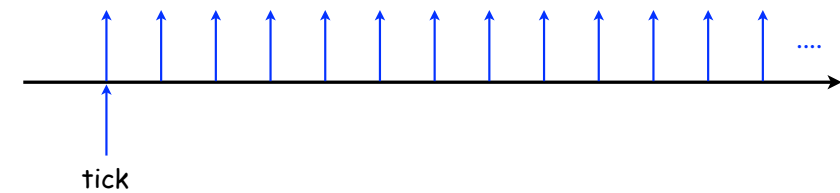
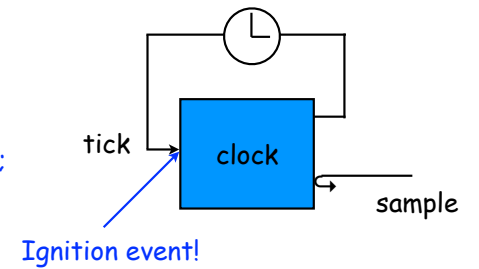
A clock

```
Clock clock = initClock();
```

Q: Will the clock
start oscillating
by itself?

A: No...

```
TINYTIMBER( &clock, tick, 0 );
```



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An on-off clock

```
typedef struct {
    Object super;
    int sec;
    int enabled;
} OnOffClock;
```

```
#define initOnOffClock() { initObject(), 0, 1 }
```

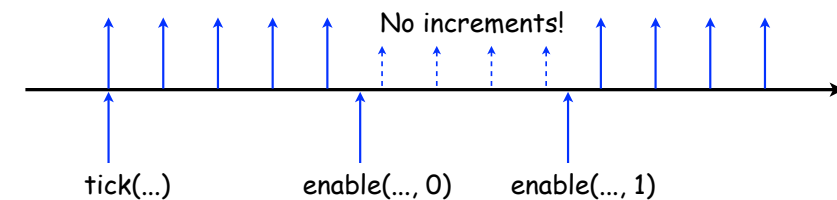
```
int tick( OnOffClock *self, int arg ) {
    if (self->enabled)
        self->sec = self->sec + 1;
    AFTER( SEC(1), self, tick, 0 )
}
```

```
int sample( OnOffClock *self, int arg ) { return self->sec; }
```

```
int enable( OnOffClock *self, int en ) { self->enabled = en; }
```

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An on-off clock



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A different on-off clock

```
typedef struct {
    Object super;
    int sec, enabled;
} OnOffClock2;

#define initOnOffClock2() { initObject(), 0, 1 }

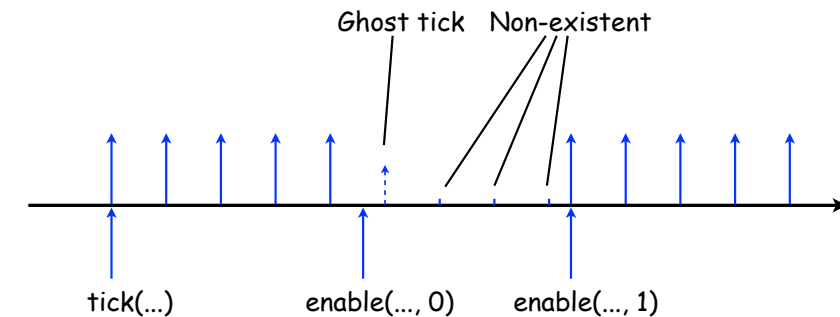
int tick( OnOffClock2 *self, int arg ) {
    if (self->enabled) {
        self->val = self->val + 1;
        AFTER( SEC(1), self, tick, 0 )
    }
}

int sample( OnOffClock2 *self, int arg ) { return self->sec; }

int enable( OnOffClock2 *self, int en ) {
    if (en && !self->enabled) ASYNC( self, tick, 0 );
    self->enabled = en;
}
```

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A different on-off clock



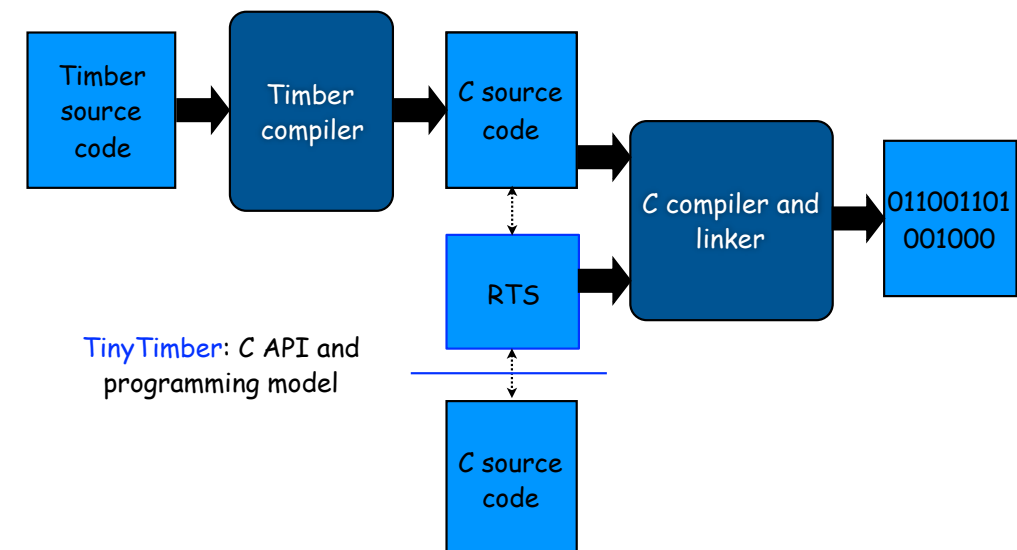
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Timber

- The big brother of TinyTimber
- Full-featured language:
 - Higher-order & strongly typed
 - Dynamic object creation, garbage-collected heap
 - Haskell-like syntax (but no laziness!)
 - Purely functional computation sub-language
- A real-time successor to O'Haskell (an OO Haskell ext.)
- Developed in part by groups & individuals at Chalmers, Luleå U. of T., Oregon Grad. Inst., Kansas State U.

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Compiling Timber



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Wrapping up

TinyTimber offers:

- Lightweight real-time facilities for *C*
- Implicit concurrency
- Implicit state protection
- Object-oriented program structure
- Robust timing semantics

Main conceptual threshold for programmers: [Reactivity!](#)

The big win of reactivity:

[Modular composition of real-time systems
with composable timing!](#)