

$$\begin{array}{l}
\boxed{\vec{\nabla} = \left[\vec{\nabla}(r, \theta, \phi) \right] \bar{\partial}_o} \\
d = [dx \ dy \ dz] \vec{\nabla} = d\vec{l}^T \vec{\nabla} \\
d(r, \theta, \phi) = [dx \ dy \ dz] \vec{\nabla}(r, \theta, \phi) \\
\boxed{\partial \bar{l}_o^T = d\vec{l}^T \vec{\nabla}(r, \theta, \phi)} \\
\partial \bar{l}_o^T \bar{\partial}_o = d\vec{l}^T \left[\vec{\nabla}(r, \theta, \phi) \right] \bar{\partial}_o \\
\boxed{d = \partial \bar{l}_o^T \bar{\partial}_o = d\vec{l}^T \vec{\nabla}}
\end{array}
\left| \begin{array}{l}
\vec{\nabla} = \begin{bmatrix} \frac{\partial}{\partial x} \\ \frac{\partial}{\partial y} \\ \frac{\partial}{\partial z} \end{bmatrix} = \begin{bmatrix} | & | & | \\ \nabla r & \nabla \theta & \nabla \phi \\ | & | & | \end{bmatrix} \begin{bmatrix} \frac{\partial}{\partial r} \\ \frac{\partial}{\partial \theta} \\ \frac{\partial}{\partial \phi} \end{bmatrix} \\
\frac{\partial \bar{l}_o}{\partial} = \begin{bmatrix} dr \\ d\theta \\ d\phi \end{bmatrix} = \begin{bmatrix} -\nabla r - \\ -\nabla \theta - \\ -\nabla \phi - \end{bmatrix} \begin{bmatrix} dx \\ dy \\ dz \end{bmatrix}
\end{array} \right| \begin{array}{l}
\theta = \theta(x, y, z) \quad (x^2 + y^2 = z^2 \tan^2 \theta) \\
\phi = \phi(x, y, z) \quad (y = x \tan \phi) \\
d\theta = dx \frac{\partial \theta}{\partial x} + dy \frac{\partial \theta}{\partial y} + dz \frac{\partial \theta}{\partial z} \\
\frac{\partial}{\partial x} = \frac{\partial r}{\partial x} \frac{\partial}{\partial r} + \frac{\partial \theta}{\partial x} \frac{\partial}{\partial \theta} + \frac{\partial \phi}{\partial x} \frac{\partial}{\partial \phi}
\end{array}$$

$$\begin{aligned}
d &= dx \frac{\partial}{\partial x} + dy \frac{\partial}{\partial y} + dz \frac{\partial}{\partial z} = d\vec{l} \cdot \vec{\nabla} &= \left[\frac{dr}{\|\nabla r\|}, \frac{d\theta}{\|\nabla \theta\|}, \frac{d\phi}{\|\nabla \phi\|} \right] \left[\|\nabla r\| \frac{\partial}{\partial r}, \|\nabla \theta\| \frac{\partial}{\partial \theta}, \|\nabla \phi\| \frac{\partial}{\partial \phi} \right]^T \\
&= dr \frac{\partial}{\partial r} + d\theta \frac{\partial}{\partial \theta} + d\phi \frac{\partial}{\partial \phi} = \partial \bar{l}_o^T \bar{\partial}_o &= [dr, r d\theta, r \sin \theta d\phi] \left[\frac{\partial}{\partial r}, \frac{1}{r} \frac{\partial}{\partial \theta}, \frac{1}{r \sin \theta} \frac{\partial}{\partial \phi} \right]^T \\
&= \frac{dr}{\|\nabla r\|} \|\nabla r\| \frac{\partial}{\partial r} + \frac{d\theta}{\|\nabla \theta\|} \|\nabla \theta\| \frac{\partial}{\partial \theta} + \frac{d\phi}{\|\nabla \phi\|} \|\nabla \phi\| \frac{\partial}{\partial \phi} \quad \dots = d\bar{l}_o^T \vec{\nabla}_o = d\vec{l}_o^T \vec{\nabla}_o
\end{aligned}$$

$$\begin{array}{l}
d\vec{l} = d\vec{r} = [dr \frac{\partial}{\partial r} + d\theta \frac{\partial}{\partial \theta} + d\phi \frac{\partial}{\partial \phi}](x, y, z)^T \\
d(x, y, z) = \left[\frac{dr}{\|\nabla r\|} \|\nabla r\| \frac{\partial}{\partial r} + \frac{d\theta}{\|\nabla \theta\|} \|\nabla \theta\| \frac{\partial}{\partial \theta} + \frac{d\phi}{\|\nabla \phi\|} \|\nabla \phi\| \frac{\partial}{\partial \phi} \right] (x, y, z) \\
(dx, dy, dz) = dr \hat{r}^T + r d\theta \hat{\theta}^T + r \sin \theta d\phi \hat{\phi}^T
\end{array}
\left| \begin{array}{l}
(\hat{r}, \hat{\theta}, \hat{\phi}) = \overline{\left(\|\nabla r\| \frac{\partial \vec{r}}{\partial r}, \|\nabla \theta\| \frac{\partial \vec{r}}{\partial \theta}, \|\nabla \phi\| \frac{\partial \vec{r}}{\partial \phi} \right)} \\
= \left(\frac{\partial}{\partial r}, \frac{1}{r} \frac{\partial}{\partial \theta}, \frac{1}{r \sin \theta} \frac{\partial}{\partial \phi} \right) \otimes (x, y, z)^T \\
= \vec{\nabla}_o^T \otimes \vec{r}
\end{array} \right.$$

$$\begin{array}{l}
\boxed{d\vec{l} = (dx, dy, dz) \cdot (\hat{x}, \hat{y}, \hat{z})} = \boxed{(dr, r d\theta, r \sin \theta d\phi) \cdot (\hat{r}, \hat{\theta}, \hat{\phi})} = d\bar{l}_o^T = d\bar{l}_o^T \cdot (\hat{r}, \hat{\theta}, \hat{\phi}) \\
\boxed{\vec{\nabla} = (\hat{x}, \hat{y}, \hat{z}) \cdot \left(\frac{\partial}{\partial x}, \frac{\partial}{\partial y}, \frac{\partial}{\partial z} \right)} = \boxed{(\hat{r}, \hat{\theta}, \hat{\phi}) \cdot \left(\frac{\partial}{\partial r}, \frac{1}{r} \frac{\partial}{\partial \theta}, \frac{1}{r \sin \theta} \frac{\partial}{\partial \phi} \right)} = \vec{\nabla}_o = \left(\frac{\partial \vec{r}}{\partial r}, \frac{1}{r} \frac{\partial \vec{r}}{\partial \theta}, \frac{1}{r \sin \theta} \frac{\partial \vec{r}}{\partial \phi} \right) \vec{\nabla}_o^T
\end{array}$$

$$\begin{aligned}
\vec{\nabla} &= [\vec{\nabla}_o^T \otimes \vec{r}] \vec{\nabla}_o = [\vec{\nabla}_o^T \otimes (x, y, z)^T] \begin{bmatrix} \frac{\partial}{\partial r} \\ \frac{1}{r} \frac{\partial}{\partial \theta} \\ \frac{1}{r \sin \theta} \frac{\partial}{\partial \phi} \end{bmatrix} \Rightarrow \frac{\partial}{\partial x} = \frac{\partial x}{\partial r} \frac{\partial}{\partial r} + \|\nabla \theta\|^2 \frac{\partial x}{\partial \theta} \frac{\partial}{\partial \theta} + \|\nabla \phi\|^2 \frac{\partial x}{\partial \phi} \frac{\partial}{\partial \phi} \\
&= [\vec{\nabla}(r, \theta, \phi)] \bar{\partial}_o = [\vec{\nabla}(r, \theta, \phi)] \begin{bmatrix} \frac{\partial}{\partial r} \\ \frac{\partial}{\partial \theta} \\ \frac{\partial}{\partial \phi} \end{bmatrix} \Rightarrow \frac{\partial}{\partial x} = \frac{\partial r}{\partial x} \frac{\partial}{\partial r} + \frac{\partial \theta}{\partial x} \frac{\partial}{\partial \theta} + \frac{\partial \phi}{\partial x} \frac{\partial}{\partial \phi}
\end{aligned}$$

$$\begin{array}{l}
\hat{r} = (\hat{r}_x, \hat{r}_y, \hat{r}_z) = \frac{\partial}{\partial r} \vec{r} = \boxed{\frac{\vec{r}}{r}} = \|\nabla r\| \frac{\partial \vec{r}}{\partial r} = \frac{\nabla r}{\|\nabla r\|} = \nabla r \\
\hat{\theta} = (\hat{\theta}_x, \hat{\theta}_y, \hat{\theta}_z) = \frac{1}{r} \frac{\partial}{\partial \theta} \vec{r} = \boxed{\frac{\partial \vec{r}}{\partial \theta}} = \|\nabla \theta\| \frac{\partial \vec{r}}{\partial \theta} = \frac{\nabla \theta}{\|\nabla \theta\|} = r \nabla \theta \\
\hat{\phi} = (\hat{\phi}_x, \hat{\phi}_y, \hat{\phi}_z) = \frac{1}{r \sin \theta} \frac{\partial}{\partial \phi} \vec{r} = \boxed{\frac{1}{\sin \theta} \frac{\partial \vec{r}}{\partial \phi}} = \|\nabla \phi\| \frac{\partial \vec{r}}{\partial \phi} = \frac{\nabla \phi}{\|\nabla \phi\|} = r \sin \theta \nabla \phi
\end{array}$$

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$$\nabla F = \left(\hat{r} \frac{\partial}{\partial r} + \hat{\theta} \frac{1}{r} \frac{\partial}{\partial \theta} + \hat{\phi} \frac{1}{r \sin \theta} \frac{\partial}{\partial \phi} \right) F$$

$$= \begin{bmatrix} \hat{r} \\ \hat{\theta} \\ \hat{\phi} \end{bmatrix} \cdot \begin{bmatrix} \frac{\partial}{\partial r} \\ \frac{1}{r} \frac{\partial}{\partial \theta} \\ \frac{1}{r \sin \theta} \frac{\partial}{\partial \phi} \end{bmatrix} F = \begin{bmatrix} \cos \phi \sin \theta \hat{x} + \sin \phi \sin \theta \hat{y} + \cos \theta \hat{z} \\ \cos \phi \cos \theta \hat{x} + \sin \phi \cos \theta \hat{y} - \sin \theta \hat{z} \\ -\sin \phi \hat{x} + \cos \phi \hat{y} \end{bmatrix} \cdot \begin{bmatrix} \frac{\partial}{\partial r} \\ \frac{1}{r} \frac{\partial}{\partial \theta} \\ \frac{1}{r \sin \theta} \frac{\partial}{\partial \phi} \end{bmatrix} F$$

$$\begin{bmatrix} \frac{\partial}{\partial x} \\ \frac{\partial}{\partial y} \\ \frac{\partial}{\partial z} \end{bmatrix} F = \begin{bmatrix} \cos \phi \sin \theta \frac{\partial}{\partial r} + \frac{\cos \phi \cos \theta}{r} \frac{\partial}{\partial \theta} - \frac{\sin \phi}{r \sin \theta} \frac{\partial}{\partial \phi} \\ \sin \phi \sin \theta \frac{\partial}{\partial r} + \frac{\sin \phi \cos \theta}{r} \frac{\partial}{\partial \theta} + \frac{\cos \phi}{r \sin \theta} \frac{\partial}{\partial \phi} \\ \cos \theta \frac{\partial}{\partial r} - \frac{\sin \theta}{r} \frac{\partial}{\partial \theta} \end{bmatrix} F = \begin{bmatrix} \frac{\partial r}{\partial x} \frac{\partial}{\partial r} + \frac{\partial \theta}{\partial x} \frac{\partial}{\partial \theta} + \frac{\partial \phi}{\partial x} \frac{\partial}{\partial \phi} \\ \frac{\partial r}{\partial y} \frac{\partial}{\partial r} + \frac{\partial \theta}{\partial y} \frac{\partial}{\partial \theta} + \frac{\partial \phi}{\partial y} \frac{\partial}{\partial \phi} \\ \frac{\partial r}{\partial z} \frac{\partial}{\partial r} + \frac{\partial \theta}{\partial z} \frac{\partial}{\partial \theta} + \frac{\partial \phi}{\partial z} \frac{\partial}{\partial \phi} \end{bmatrix} F = \begin{bmatrix} \hat{x} \\ \hat{y} \\ \hat{z} \end{bmatrix} \cdot \begin{bmatrix} \frac{\partial}{\partial x} \\ \frac{\partial}{\partial y} \\ \frac{\partial}{\partial z} \end{bmatrix} F$$

$$\nabla \cdot \vec{A} = \frac{1}{r} \frac{1}{r \sin \theta} \left\langle \frac{\partial}{\partial r}, \frac{\partial}{\partial \theta}, \frac{\partial}{\partial \phi} \right\rangle \cdot [r \cdot r \sin \theta] \left\langle A_r, \frac{1}{r} A_\theta, \frac{1}{r \sin \theta} A_\phi \right\rangle$$

$$\nabla \times \vec{A} = \frac{1}{r} \frac{1}{r \sin \theta} \begin{vmatrix} \hat{r} & r\hat{\theta} & r \sin \theta \hat{\phi} \\ \frac{\partial}{\partial r} & \frac{\partial}{\partial \theta} & \frac{\partial}{\partial \phi} \\ A_r & r A_\theta & r \sin \theta A_\phi \end{vmatrix} = \begin{vmatrix} \frac{\partial \vec{r}}{\partial r} & \frac{\partial \vec{r}}{\partial \theta} & \frac{\partial \vec{r}}{\partial \phi} \\ \frac{\partial}{\partial r} & \frac{\partial}{\partial \theta} & \frac{\partial}{\partial \phi} \\ A_r & r A_\theta & r \sin \theta A_\phi \end{vmatrix}$$

$$[\vec{A} \times (\vec{B} \times \vec{C})]_i = \vec{A} \cdot (B_i \vec{C}) - \vec{A} \cdot (\vec{B} C_i)$$

$$\begin{aligned} \vec{A} \times (\vec{B} \times \vec{C}) &= \boxed{(\vec{A} \cdot (\vec{B} \otimes \vec{C})^T)^T - (\vec{A} \cdot \vec{B} \otimes \vec{C})^T} = (\vec{A} \otimes \vec{B}) \cdot \vec{C} - (\vec{A} \cdot \vec{B} \otimes \vec{C})^T \\ &= (A^T (BC^T)^T)^T - (A^T BC^T)^T = (AB^T)^T C - (A^T BC^T)^T \end{aligned}$$