## 1 Maxwell's Equations

Gauss's Law for Electricity (GLE)

$$\iint \vec{E} \cdot d\vec{a} = \frac{Q}{\epsilon_0}$$

$$\iint (\nabla \cdot \vec{E}) \ dV = \frac{\iiint \rho \, dV}{\epsilon_0}$$

$$\nabla \cdot \vec{E} = \frac{\rho}{\epsilon_0}$$

Faraday's Law of Induction (FLI)

$$\int \vec{E} \cdot d\vec{l} = -\frac{d\Phi_B}{dt}$$

$$\int \int (\nabla \times \vec{E}) \cdot d\vec{a} = -\frac{d}{dt} \iint \vec{B} \cdot d\vec{a}$$

$$\nabla \times \vec{E} = -\frac{\partial \vec{B}}{\partial t}$$

Lorentz Force Law (LFL)

$$\vec{F} = q\vec{E} + q\vec{v} \times \vec{B}$$
 
$$\vec{f} \equiv \frac{\partial \vec{F}}{\partial V} = \rho \vec{E} + \vec{J} \times \vec{B}$$

Gauss's Law for Magnetism (GLM)

$$\iint \vec{B} \cdot d\vec{a} = 0$$

$$\iint (\nabla \cdot \vec{B}) \ dV = 0$$

$$\nabla \cdot \vec{B} = 0$$

Maxwell-Ampere's Law (MAL)

$$\oint \vec{B} \cdot d\vec{l} = \mu_0 \left( I + \epsilon_0 \frac{d\Phi_E}{dt} \right)$$

$$\iint (\nabla \times \vec{B}) \cdot d\vec{a} = \mu_0 \iint \vec{J} \cdot d\vec{a} + \mu_0 \epsilon_0 \frac{d}{dt} \iint \vec{E} \cdot d\vec{a}$$

$$\nabla \times \vec{B} = \mu_0 \left( \vec{J} + \epsilon_0 \frac{\partial \vec{E}}{\partial t} \right)$$

Jefimenko Equations:

$$\vec{E}(\vec{\mathbf{r}},t) = k_{\epsilon} \int \left[ \frac{\rho(\vec{\mathbf{r}},t_r)}{\boldsymbol{\imath}^2} \hat{\boldsymbol{\imath}} + \frac{\dot{\rho}(\vec{\mathbf{r}},t_r)}{c \,\boldsymbol{\imath}} \hat{\boldsymbol{\imath}} - \frac{\dot{\vec{J}}(\vec{\mathbf{r}},t_r)}{c^2 \,\boldsymbol{\imath}} \right] d\tau'$$

$$\vec{B}(\vec{\mathbf{r}},t) = k_{\mu} \int \left[ \frac{\vec{J}(\vec{\mathbf{r}},t_r)}{\boldsymbol{\imath}^2} + \frac{\dot{\vec{J}}(\vec{\mathbf{r}},t_r)}{c \,\boldsymbol{\imath}} \right] \times \hat{\boldsymbol{\imath}} d\tau'$$

#### Conservation of Charge (COC)

$$\frac{|0=0|}{\left[\frac{\partial}{\partial t}\right] \left(\nabla \cdot B = 0\right)} \leftarrow \left(\nabla \times E = -\frac{\partial B}{\partial t}\right)$$

$$\left[\nabla \cdot\right] \left(\nabla \times E = -\frac{\partial B}{\partial t}\right) \leftarrow \left(\nabla \cdot B = 0\right)$$

#### Laplacian

$$\nabla^2 B = -\mu_0(\nabla \times J) - \nabla \times \frac{\partial E}{\partial t}$$
$$\nabla \left(\nabla \cdot B = 0\right) \leftarrow \left(\nabla \times B = \mu_0 J + \frac{1}{c^2} \frac{\partial E}{\partial t}\right)$$

#### D'alambertian

$$\begin{aligned}
& \Box^2 B = \nabla^2 B - \frac{1}{c^2} \frac{\partial^2 B}{\partial t^2} = -\mu_0(\nabla \times J) \\
& \left[ \nabla \times \right] \left( \nabla \times B = \mu_0 J + \frac{1}{c^2} \frac{\partial E}{\partial t} \right) \leftarrow \begin{pmatrix} \nabla \cdot B = 0 \\ \nabla \times E = -\frac{\partial B}{\partial t} \end{pmatrix} \\
& \left[ \frac{\partial}{\partial t} \right] \left( \nabla \times E = -\frac{\partial B}{\partial t} \right) \\
& \left[ \nabla \times \frac{\partial E}{\partial t} + \frac{\partial^2 B}{\partial t^2} = 0 \right] \\
\end{aligned}
\leftarrow \begin{pmatrix} \frac{\partial E}{\partial t} = c^2 (\nabla \times B - \mu_0 J) \end{pmatrix}$$

#### Special Cases 1.1

Zero Fields:

$$\frac{\text{Zero Fields}:}{\partial_t B = 0 = \nabla \times E} \Rightarrow \begin{bmatrix} \nabla^2 E = \frac{\nabla \rho}{\epsilon_0} \end{bmatrix}, \begin{bmatrix} \nabla^2 B = -\mu_0(\nabla \times J) \end{bmatrix} \\
, \begin{bmatrix} \epsilon_0 \frac{\partial^2 E}{\partial t^2} = -\frac{\partial J}{\partial t} \end{bmatrix} \\
\frac{\partial}{\partial t} E = 0 = \nabla \times B - \mu_0 J \Rightarrow \begin{bmatrix} \frac{\partial}{\partial t} = 0 \end{bmatrix}, \begin{bmatrix} \nabla^2 B = -\mu_0(\nabla \times J) \end{bmatrix} \\
\frac{\partial^2 B}{\partial t^2} = 0 \end{bmatrix}, \begin{bmatrix} \nabla^2 E = \mu_0 \frac{\partial J}{\partial t} + \frac{\nabla \rho}{\epsilon_0} \end{bmatrix}$$

•  $\partial_t B$ ,  $\partial_t E = 0 \Rightarrow \frac{\partial J}{\partial t}$ ,  $\frac{\partial \rho}{\partial t} = 0$  •  $\rho$ ,  $J = 0 \Rightarrow \Box^2 E$ ,  $\Box^2 B = 0$ 

From Jefimenko:

$$\frac{\partial J}{\partial t} = 0 \implies \left[ \partial_t B = 0 \right] \implies \begin{pmatrix} \frac{\partial^2 E}{\partial t^2} = 0 \\ \nabla^2 E = \frac{\nabla \rho}{\epsilon_0} \end{pmatrix}$$

$$\frac{\partial \rho}{\partial t} = 0 , \quad \frac{\partial^2 J}{\partial t^2} = 0 \implies \left[ \partial_t E = 0 \right]$$

$$\bullet \quad \frac{\partial \rho}{\partial t} , \quad \frac{\partial J}{\partial t} = 0 \implies \partial_t B , \quad \partial_t E = 0$$

Slight rationalization:

If 
$$\frac{\partial \rho}{\partial t} = 0$$
:  $-\frac{\partial Q}{\partial t} = \oiint J \cdot da = I|_a = 0 = \frac{\partial I}{\partial a}$ 

If  $\frac{\partial J}{\partial t} = 0$ :  $\iint \frac{\partial J}{\partial t} \cdot da = \frac{\partial I}{\partial t} = 0$ 

•  $I(a,t) = I_0$ 

•  $\partial_t \left( E = k \int \frac{\rho \hat{\imath} dV}{\|\hat{\imath}\|^2} \right) = 0$ 

•  $\nabla \times B = \mu_0 J \to B = k_\mu \int \frac{I d\vec{l} \times \hat{\imath}}{\|\vec{\imath}\|^2}$ 

•  $\partial_t B = 0$ 

 $** \boxed{rac{\partial E}{\partial t} \; , \; rac{\partial B}{\partial t} = 0 \; \Leftrightarrow \; rac{\partial 
ho}{\partial t} \; , \; rac{\partial J}{\partial t} = 0} **$ 

Single charges do not constitute a current. Free charges (unaffected by external forces holding them) will always, by selfinteraction through their E-field, create an unconstant current and thus unconstant B-field. Under static conditions, a free space must have a  $\rho = 0$ . See below for more info.

## Electrostatic Metal Conductors (when J=0=B)

- Suppose there is a finite set of positive point charges  $\{\delta_i \mid i \leq n, \ v_i = 0, \ E(x_i) = 0\}$ , such as a charge at every integer coordinate in  $\mathbb{R}^3$ . If  $\delta_i$  is a free charge only to move by electrical forces, by Gauss's Law the only way  $x_i$  is a stable critical point is if there is a negative charge at  $x_i$ , which there isn't.  $\forall n > 1$ , any free charge in  $\mathbb{R}^3$ cannot be in stable equilibrium. See below for neutral equilibrium.
- On a surface/boundary where movement is restricted to lower dimensions (perhaps by mechanical forces), Gauss's Law won't apply, so these lesser free charges can be in stable equilibrium, such as charges evenly distributed over a sphere. Note that E = 0 at  $x_i$  and symmetric points in between  $x_i$ . In the  $\lim n \to \infty$  then  $E_{\parallel}=0$  for the entire boundary.
- If a surface dist. creates a neutral equi. inside the surface (see right) and a point charge were inside the boundary at  $x_i$ , the surface charges will polarize and make  $E(x_i)$  unstable.

$$\begin{split} \bullet & \; \rho(\vec{r}_m) = 0 \; \Rightarrow \; E = E_{!m} \\ \left[ \underline{\vec{E}_{!m\parallel}(\vec{b}) = 0} \; \Rightarrow \; \oint_{l \in B} \vec{E} \cdot d\vec{l} = 0 \right] \Leftrightarrow \underline{\left[ \phi_{!m}(\vec{b}) = \phi_0 \right]} \\ \wedge & \; \vec{E}_{!m}(\vec{r}_m) \neq 0 \; \Rightarrow \; \oint_{l \in B, V_m} \vec{E} \cdot d\vec{l} \neq 0 \quad \boxed{\mathbf{X}} \\ \Rightarrow & \; \underline{\vec{E}_{!m}(\vec{r}_m) = 0} \; , \; \phi_{!m}(\vec{r}_m) = \phi_0 \quad \text{(neutr. equi.)} \\ \vec{E}_{!m\parallel}(\vec{b}) \neq 0 \; \wedge \; \vec{E}_{!m}(\vec{r}_m) \neq 0 \\ \wedge & \; J = J_0 \neq 0 \quad \text{(circuit wire)} \end{aligned}$$

# 1.2 Electrostatic/Magnetostatic Examples Using GLE

#### 1. Point Charges

$$\vec{E} = E(r)\hat{r}$$

$$\frac{Q}{\epsilon_0} = \oiint E(r)\hat{r} \cdot d\vec{a}$$

$$= E(r)\hat{r} \cdot \oiint r^2 \sin \phi \ |d\vec{\phi} \times d\vec{\theta}|$$

$$= E(r)\hat{r} \cdot 4\pi r^2 \hat{r}$$

$$\vec{E}(r) = \frac{Q}{4\pi\epsilon_0 r^2} \hat{r} \implies \frac{1}{4\pi\epsilon_0} \sum_i \frac{Q_i}{|\vec{z}_i|^2} \hat{z}_i$$

#### Coulomb's Law (CL):

$$\vec{E}(\vec{\mathbf{r}}) = \frac{1}{4\pi\epsilon_0} \int \frac{dQ}{|\vec{\boldsymbol{z}}|^2} \hat{\boldsymbol{z}} \qquad \vec{\mathbf{r}} \in \mathbb{R}^3, \ \vec{\boldsymbol{z}} = \vec{\mathbf{r}} - \vec{l'}$$

$$\vec{F}(\vec{\mathbf{r}}) = q\vec{E}$$

#### Using MAL

Biot-Savart Law (BSL):

(see potential,  $\vec{A}$ , for derivation)

$$\vec{B}(\vec{\mathbf{r}}) = k_{\mu} \int \frac{\vec{J}dV \times \hat{\boldsymbol{\imath}}}{|\vec{\boldsymbol{\imath}}|^2}, \qquad \vec{\mathbf{r}} \in \mathbb{R}^3, \quad \vec{\boldsymbol{\imath}} = \vec{\mathbf{r}} - \vec{l'}$$
$$= k_{\mu} \int \frac{I(\vec{v}) \ d\vec{l'} \times \hat{\boldsymbol{\imath}}}{|\vec{\boldsymbol{\imath}}|^2}$$

$$\vec{F} = q\hat{v} \times \vec{B}$$

1. Infinite Line w/ Steady Current (SC)

$$\vec{B} = B(r)\hat{\theta}$$

Use MAL

$$\mu_o I = \oint B(r)\hat{\theta} \cdot d\vec{L}$$
$$= B(r)\hat{\theta} \cdot \oint r d\vec{\theta}$$
$$= B(r)\hat{\theta} \cdot 2\pi r \hat{\theta}$$

$$\vec{B}(r) = \frac{\mu_0 I}{2\pi r} \hat{\theta}$$

cont.

## 2. Sphere w/ Constant Charge Density (CCD)

Let R be the radius.

$$\vec{E}(r) = \frac{Q(r)}{4\pi\epsilon_0 r^2} \hat{r}$$

$$Q(r) = \begin{cases} Q & (r > R) \\ Q_{r < R} = \iiint_0^r \frac{dQ}{dV} dV & (r < R) \end{cases}$$

• Conductor

$$Q_{r < R} = 0$$
  $\Rightarrow$   $\vec{E}(r) = \begin{cases} \frac{Q}{4\pi\epsilon_0 r^2} \hat{r} & (r > R) \\ 0 & (r < R) \end{cases}$ 

• Insulator w/ CCD and  $\epsilon = \epsilon_0$ 

$$Q_{r < R} = \int \frac{Q}{V} dV = Q \frac{\int dV}{V} = Q \frac{r^3}{R^3}$$

$$\Rightarrow \vec{E}(r) = \begin{cases} \frac{Q}{4\pi\epsilon_0 r^2} \hat{r} & (r > R) \\ \frac{Qr}{4\pi\epsilon_0 R^3} \hat{r} & (r < R) \end{cases}$$

Use BSL

$$\vec{B}(r) = \frac{\mu_0 I}{4\pi} \int \frac{d\vec{z} \times \hat{\boldsymbol{\imath}}}{|\vec{\boldsymbol{\imath}}|^2}$$

$$= \frac{\mu_0 I}{4\pi} \int_{-\infty}^{\infty} \frac{d\vec{z} \times \hat{\boldsymbol{\imath}}}{r^2 + z^2}$$

$$= \frac{\mu_0 I}{4\pi} \int_{-\infty}^{\infty} \frac{d\vec{z} \times (r\hat{r} - z\hat{z})}{(r^2 + z^2)^{3/2}}$$

$$= \frac{\mu_0 I r}{4\pi} \int_{-\infty}^{\infty} \frac{dz}{(r^2 + z^2)^{3/2}} \hat{\theta}$$

$$= \frac{\mu_0 I r}{4\pi} \frac{z}{r^2 \sqrt{r^2 + z^2}} \Big|_{-\infty}^{\infty} \hat{\theta}$$

$$= \frac{\mu_0 I}{2\pi r} \hat{\theta}$$

#### Constant Field Solutions (Capacitor/Solenoid)

# 3. Two Infinite Parallel Planes Capacitor w/ CCD (+Q, -Q)

$$\vec{E} = E(z)\hat{z}$$

$$\frac{Q}{\epsilon_0} = \oiint E(z)\hat{z} \cdot d\vec{a}$$

$$= E(z)\hat{z} \cdot \oiint xy |d\vec{x} \times d\vec{y}|$$

$$= E(z)\hat{z} \cdot xy\hat{z}$$

$$\vec{E}(z) = \frac{1}{\epsilon_0} \frac{dQ}{dA} \hat{z} = \frac{\sigma}{\epsilon_0} \hat{z}$$

#### 4. One Infinite Plane w/ CCD

$$\vec{E} = E(z)\hat{z}$$

$$\frac{Q}{\epsilon_0} = \iint E(z)\hat{z} \cdot d\vec{a}$$

$$= E(z)\hat{z} \cdot 2 \iint xy |d\vec{x} \times d\vec{y}|$$

$$= E(z)\hat{z} \cdot 2xy\hat{z}$$

$$\vec{E}(z) = \frac{1}{2\epsilon_0} \frac{dQ}{dA} \hat{z} = \frac{\sigma}{2\epsilon_0} \hat{z}$$

#### 2. Infinite Long Solenoid Coil w/ SC

Let R be the coil radius.  $\vec{B} = B(r)\hat{z} = B(r < R)\hat{z}$ 

$$\mu_o NI = \oint B(r)\hat{z} \cdot d\vec{L}$$
$$= (B_{r < R})\hat{z} \cdot \oint d\vec{L}$$
$$= (B_{r < R})\hat{z} \cdot L\hat{z}$$

$$\vec{B}(r) = \begin{cases} \frac{\mu_0 IN}{L} \hat{z} = \mu_0 I n_l \ \hat{z} & (0 < r < R) \\ 0 & (r > R) \end{cases}$$

#### 3. Closed, Thin Solenoid Ring w/SC

Let  $R_l$  be the ring radius and  $R_c$  be the coil radius.

$$\vec{B} = B(r)\hat{\theta} = B(R_l - R_c < r < R_l + R_c)\hat{\theta} \approx B(R_l)\hat{\theta}$$

$$\mu_o NI = \oint B(r)\hat{\theta} \cdot d\vec{L}$$
$$= B(r)\hat{\theta} \cdot 2\pi R_l \ \hat{\theta}$$

$$\vec{B}(r) = \begin{cases} \frac{\mu_0 I N}{2\pi R_l} \hat{\theta} & (R_{l-c} < r < R_{l+c}) \\ 0 & \text{else} \end{cases}$$

#### Integrate w/ CFL and BSL

#### 5. Ring w/ CCD centered at origin O

Let R be the ring radius,  $\lambda$  the charge density, and  $\phi$  be  $\angle OzR$ .

$$E(0,0,z)\hat{z} = \frac{1}{4\pi\epsilon_0} \int \frac{dq}{z^2} \vec{z}$$

$$\vec{E}(0,0,z) = \frac{1}{4\pi\epsilon_0} \int \frac{\lambda(Rd\theta)}{\imath^2} \vec{\imath}$$

$$= \frac{k\lambda}{z^2 + R^2} \int_0^{2\pi} Rd\theta \cos\phi \,\hat{z}$$

$$= \frac{k\lambda(2\pi R)z}{(z^2 + R^2)^{3/2}} \hat{z}$$

$$= \frac{k\lambda}{D} \frac{2\pi R}{D} \cos\phi \ \hat{z}$$

#### 4. Ring w/ SC centered at origin O

Let R be the ring radius and  $\phi$  be  $\angle OzR$ .

$$B(0,0,z)\hat{z} = \frac{\mu_0 I}{4\pi} \int \frac{d\vec{l} \times \hat{z}}{|\vec{z}|^2}$$

$$\vec{B}(0,0,z) = \frac{\mu_0 I}{4\pi} \int \frac{Rd\vec{\theta} \times \hat{z}}{z^2}$$

$$= \frac{k_\mu I}{z^2 + R^2} \int Rd\theta \,\, \hat{\theta} \times \frac{z\hat{z} - R\hat{r}}{\sqrt{z^2 + R^2}} \qquad \text{or} \quad \frac{k_\mu I}{z^2 + R^2} \int_0^{2\pi} Rd\theta \,\, \sin\phi \,\, \hat{z}$$

$$= \frac{k_\mu I R}{(z^2 + R^2)^{3/2}} \left[ 2\pi R\hat{z} + z \int_0^{2\pi} \hat{r}d\theta \right] \quad \text{or} \quad \frac{k_\mu I}{z^2 + R^2} \int_0^{2\pi} Rd\theta \,\, \frac{R}{\sqrt{z^2 + R^2}} \,\, \hat{z}$$

$$= \frac{k_\mu I (2\pi R) R}{(z^2 + R^2)^{3/2}} \,\, \hat{z}$$

# 6. Line Charge w/ CCD and one edge at the origin O

Let L be the line length,  $\lambda$  the charge density, and  $\theta_0$  be  $\angle OyL$ .

$$E_y(0,0,y)\hat{y} = \frac{1}{4\pi\epsilon_0} \int \frac{dq}{\boldsymbol{\imath}^2} \vec{\boldsymbol{\imath}}_y$$

$$E_y(0,0,y) = k \int \frac{\lambda dx}{\boldsymbol{\imath}^2} \vec{\boldsymbol{\imath}}_y$$

$$= \frac{k\lambda}{y^2} \int_0^{\theta_0} \frac{y \sec^2 \theta \, d\theta}{1 + \tan^2 \theta} \cos \theta$$

 $=k\lambda \int \frac{dx}{y^2 + x^2} \cos \theta$  ,  $x = y \tan \theta$ 

$$= \frac{k\lambda}{y} \int_0^{\theta_0} \cos\theta \, d\theta = \frac{k\lambda}{y} \sin\theta_0$$

$$= \frac{k\lambda L}{y\sqrt{y^2 + L^2}} = \frac{k\lambda}{y}\sin\theta_0$$

Use this result to find Finite Line, Square Ring, and Infinite Line.

#### 5. Finite Wire w/ SC and one edge at the origin O

Let L be the wire length and  $\theta_0$  be  $\angle OyL$ .

$$B_z(0,0,y)\hat{z} = k_{\mu}I\int \frac{d\vec{l}\times\hat{z}}{|\vec{z}|^2}$$

$$B_{z}(0,0,y)\hat{z} = k_{\mu}I \int \frac{d\vec{x} \times \hat{z}}{|\vec{z}|^{2}}$$

$$= k_{\mu}I \int \frac{dx\hat{z}}{y^{2} + x^{2}} \sin(\theta + 90) , \quad x = y \tan \theta$$

$$= \frac{k_{\mu}I}{y^{2}} \int_{0}^{\theta_{0}} \frac{y \sec^{2}\theta d\theta}{1 + \tan^{2}\theta} \cos \theta \hat{z}$$

$$= \frac{k_{\mu}I}{y} \int_{0}^{\theta_{0}} \cos \theta d\theta \hat{z} = \frac{k_{\mu}I}{y} \sin \theta_{0} \hat{z}$$

$$= \left[ \frac{k_{\mu}IL}{y\sqrt{y^{2} + L^{2}}} \hat{z} \right] = \left[ \frac{k_{\mu}I}{y} \sin \theta_{0} \hat{z} \right]$$

Use this result to find Finite Wire, Square Wire, and Infinite Wire.

#### 1.3 Field Energies

The sum of the work to move a collection of charges considering the potential from each other charge comes out to be

$$W = rac{1}{2} \sum_i q_i V(r_i)$$

E-field Energy (electrostatic...)

$$E = \frac{1}{2}CV^2 = \frac{1}{2}VQ$$

$$\boxed{W_{\text{vol}} = \frac{1}{2}\iiint V\rho \ d\tau} = \frac{\epsilon_0}{2}\iiint V(\nabla \cdot \vec{E}) \ d\tau$$

$$= \frac{\epsilon_0}{2}\iiint \vec{E} \cdot (\vec{E}) + \nabla \cdot (V\vec{E}) \ d\tau$$

$$= \left[\frac{\epsilon_0}{2}\iiint \vec{E}^2 \ d\tau + \frac{\epsilon_0}{2}\iint (V\vec{E}) \cdot d\vec{a}\right]$$

$$\boxed{W_E = \frac{\epsilon_0}{2}\iiint \vec{E}^2 \ d\tau} \quad (\text{if } \rho = 0 \text{ at } \infty)$$

B-field Energy

$$E = \frac{1}{2}LI^{2} = \frac{1}{2}\Phi_{B}I = \frac{1}{2}\oint I\vec{A} \cdot d\vec{l}$$

$$W_{\text{vol}} = \frac{1}{2}\iiint \vec{A} \cdot \vec{J} \, d\tau = \frac{1}{2\mu_{0}}\iiint \vec{A} \cdot (\nabla \times \vec{B}) \, d\tau$$

$$= \frac{1}{2\mu_{0}}\iiint \vec{B} \cdot (\vec{B}) - \nabla \cdot (\vec{A} \times \vec{B}) \, d\tau$$

$$= \frac{1}{2\mu_{0}}\iiint \vec{B}^{2} \, d\tau - \frac{1}{2\mu_{0}}\oiint (\vec{A} \times \vec{B}) \cdot d\vec{a}$$

$$W_{B} = \frac{1}{2\mu_{0}}\iiint \vec{B}^{2} \, d\tau \quad (\text{if } \vec{I} = 0 \text{ at } \infty)$$

## Circuits/Ohm's Law

Open Circuit:  $R = \infty$ Short Circuit: R = 0

#### AC Filters

Low Pass (Non-Zero  $\overline{\text{Probe}}$ ): High Pass (Non-Zero  $\overline{\text{Probe}}$ ):

 $\bullet$   $R\overline{C}$ 

•  $L\overline{R}$ 

 $\bullet$   $C\overline{R}$ 

 $\bullet$   $R\overline{L}$ 

Band Pass (Zero Probe):

 $\bullet$   $R\overline{LC}$ 

• Bandwidth =  $\left(\text{FWHM} = 2\beta = \frac{b}{m}\right) = \frac{R}{L}$ 

#### Other Components

$$->|-\>$$
 Diode | One Way Voltage (if > Bias Voltage)   
= | > - Op-Amp |  $V_1-V_2 \propto V_{\rm OA}$  (Clipping If Too Large  $V_{\rm OA}$ )   
= |)- And   
=) > - Or

#### De Morgan's Law

$$\bullet \ \overline{A \cdot B} = \overline{A} + \overline{B}$$

$$\bullet \ \overline{A+B} = \overline{A} \cdot \overline{B}$$

#### 1.5 Quasistatic (FLI)

Force on Wire in B-Field :

EMF:

Mutual Inductance:

$$F = qv \times B$$

$$F = LI \times B$$

$$\mathcal{E} = -\frac{d\Phi_B}{dt} = \oint \vec{E} \cdot d\vec{l}$$

Flux Through B:  $\Phi_B = M \cdot I_A$ 

Flux Through A:  $\Phi_A = M \cdot I_B$ 

### Faraday's Law

1. Lorentz:

Square Circuit with  $\vec{v}(t)$  leaving Constant B-Field (out)

I is out

2. Faraday:

Constant B-Field (out) with  $-\vec{v}(t)$ leaving Square Circuit

I is out

3. Faraday:

Square Circuit in Increasing B-Field (out)

I is in

## **Examples:**

B-Field Work:

$$(\vec{v} \cdot \vec{l} = 0) \rightarrow W_B = \int \vec{F} \cdot d\vec{l}$$
  
=  $\int (q\vec{v} \times \vec{B}) \cdot d\vec{l}$ 

(magnetic fields do no work)

Velocity of wire in (1.): 
$$I(t)R = V(t) = \left| \frac{d\Phi_B}{dt} \right| = Bhv(t)$$

$$F_B(t) = -hI(t)B$$
$$= -\frac{B^2h^2v(t)}{R}$$

$$F = ma(t)$$

$$m\frac{dv}{dt} = F_B + F_{\text{ext}} = F_{\text{ext}} - \frac{B^2 h^2 v(t)}{R}$$

## 2 Potentials and Fields

### 2.1 Maxwell's Equations for Potentials

#### 1. GLM for Potentials (GLMP)

$$\nabla \cdot \vec{B} = 0$$

$$\nabla \cdot (\nabla \times \vec{A}) = 0 , \qquad \vec{A'} = \vec{A} + \nabla \lambda$$

$$\vec{B} = \nabla \times \vec{A} \Rightarrow \Phi_B = \oint \vec{A} \cdot d\vec{l}$$

#### 3. GLE for Potentials (GLEP)

$$\nabla \cdot \vec{E} = \frac{\rho}{\epsilon_0}$$
$$-\nabla^2 V - \frac{\partial (\nabla \cdot \vec{A})}{\partial t} = \frac{\rho}{\epsilon_0}$$
$$-\Box^2 V - \frac{\partial}{\partial t} (\partial_\mu A^\mu) = \frac{\rho}{\epsilon_0}$$

# Field Energy (see Capacitor/Solenoid in Circuits):

$$\boxed{W_E = \frac{1}{2} \iiint V \rho \ d\tau} = \frac{\epsilon_0}{2} \int E^2 \ d\tau \ (\text{if } \rho = 0 \text{ at } \infty)$$

#### 2. FLI for Potentials (FLIP)

$$\nabla \times \vec{E} = -\frac{\partial \vec{B}}{\partial t}$$

$$\nabla \times \vec{E} = \nabla \times \left(0 - \frac{\partial \vec{A}}{\partial t}\right) , \qquad V' = V + \frac{\partial \lambda}{\partial t}$$

$$\vec{E} = -\nabla V - \frac{\partial \vec{A}}{\partial t} \Rightarrow V \Big|_a^b = -\int_a^b \vec{E} \cdot d\vec{l} - \frac{\partial}{\partial t} \int_a^b \vec{A} \cdot d\vec{l}$$

#### 4. MAL for Potentials (MALP)

$$\nabla \times \vec{B} - \frac{1}{c^2} \frac{\partial \vec{E}}{\partial t} = \mu_0 \vec{J}$$

$$\frac{1}{c^2} \frac{\partial^2 \vec{A}}{\partial t^2} - \nabla^2 \vec{A} + \nabla \left( \frac{1}{c^2} \frac{\partial V}{\partial t} + \nabla \cdot \vec{A} \right) = \mu_0 \vec{J}$$

$$\boxed{-\Box^2 \vec{A} + \nabla (\partial_\mu A^\mu) = \mu_0 \vec{J}}$$

$$\boxed{W_B = \frac{1}{2} \iiint \vec{A} \cdot \vec{J} \, d\tau} = \frac{1}{2\mu_0} \int B^2 \, d\tau \quad (\text{if } \vec{J} = 0 \text{ at } \infty)$$

#### 2.2 Cases and Freedoms

$$\vec{E} = -\nabla V - \frac{\partial \vec{A}}{\partial t}$$

 $\vec{B} = \nabla \times \vec{A}$ 

In the electrostatic case,

Electrostatics:  $\nabla \times E = \partial_t B = 0$ 

GLEP and MALP say that

$$-\nabla^2 V - \frac{\partial (\nabla \cdot \vec{A})}{\partial t} = \frac{\rho}{\epsilon_0}$$
$$\frac{1}{c^2} \frac{\partial^2 \vec{A}}{\partial t^2} - \nabla^2 \vec{A} + \nabla \left( \frac{1}{c^2} \frac{\partial V}{\partial t} + \nabla \cdot \vec{A} \right) = \mu_0 \vec{J}$$

Freedom may be chosen to what  $\nabla \cdot \vec{A}$  equals:

Coulomb Gauge: 
$$\nabla \cdot \vec{A} = 0$$

• Magnetostatics:  $\partial_t E = 0 \Leftrightarrow \nabla \times B = \mu_0 J$ 

$$egin{aligned} ext{Lorenz Gauge:} & oldsymbol{
abla} \cdot ec{A} = -rac{1}{c^2}rac{\partial V}{\partial t} \iff \partial_{\mu}A^{\mu} = 0 \end{aligned}$$

In general,  $\vec{A}$  and V can be [gauge] transformed while keeping  $\vec{E}$  and  $\vec{B}$  the same by

$$V' = V - \frac{d\lambda}{dt}$$
 (\lambda is a scalar function) 
$$\vec{A'} = \vec{A} + \nabla \lambda$$

#### **Electrostatic Potentials**

Electrostatics:  $\partial_t \vec{B} = 0$ .

$$\nabla \times \vec{E} = 0 \implies \oint \vec{E} \cdot d\vec{l} = 0$$

Choose  $\frac{\partial A}{\partial t} = 0 \implies E = -\nabla V$ 

$$\int_{a}^{b} \nabla \vec{V} \cdot d\vec{l} = \left[ V(\vec{\mathbf{r}}) \right]_{a}^{b} = -\int_{a}^{b} \vec{E} \cdot d\vec{l} = W_{E}/q$$

$$V(\vec{\mathbf{r}}) = -\int \vec{E} \cdot d\vec{l} + V_0$$

and from this (or GLEP)

Poisson Equation: 
$$\nabla^2 V = -\frac{\rho(\vec{r'})}{\epsilon_0}$$
$$\rho_{\infty} = 0 \implies \vec{V}(\vec{r}) = \frac{1}{4\pi\epsilon_0} \int \frac{\rho(\vec{r'})}{\imath} d\tau'$$

$$ho_{\infty} = 0 \ \Rightarrow \ \vec{V}(\vec{\mathbf{r}}) = \frac{1}{4\pi\epsilon_0} \int \frac{
ho(\vec{r'})}{\imath} \ d au'$$

PE Uniqueness Theorem: Given  $\rho$  and V at the boundary, V is unique in the space containing  $\rho$ enclosed by the surface.

#### Coulomb Gauge & Magnetostatic Potentials

Coulomb Guage: Choose  $\left( \nabla \cdot \vec{A} = 0 \right)$ 

Using GLEP,

Poisson Equation: 
$$\nabla^2 V = -\frac{\rho(\vec{r'},t)}{\epsilon_0}$$

$$\rho_{\infty} = 0 \implies V(\vec{r}) = \frac{1}{4\pi\epsilon_0} \int \frac{\rho(\vec{r'},t)}{\imath} d\tau'$$

$$ho_{\infty} = 0 \; \Rightarrow \; V(ec{\mathbf{r}}) = rac{1}{4\pi\epsilon_0} \int rac{
ho(ec{r'},t)}{\imath} \; d au'$$

If charges move, V updates immediately - not at light speed. Only  $\vec{E}$  can be physically measured, and updates at light speed.  $\vec{A}$  is difficult to find using MALP except for special cases like Magnetostatics.

As always, GLMP says

$$\Phi_B = \oint ec{A} \cdot dec{l}$$

Magnetostatics:  $\partial_t \vec{E} = 0$ 

Using MALP,

Poisson Equation: 
$$\nabla^2 \vec{A} = -\mu_0 \vec{J}(\vec{r'})$$

Poisson Equation: 
$$abla^2 \vec{A} = -\mu_0 \vec{J}(\vec{r'})$$

$$\vec{J}_{\infty} = 0 \Rightarrow \vec{A}(\vec{r}) = k_{\mu} \int \frac{\vec{J}(\vec{r'})}{\imath} d\tau'$$

#### 2.2.1 Electrostatic Potential Examples

#### 1. Point Charges

Reference Choice:  $V(\infty) = 0$ 

$$V(r) = -\int_{\infty}^{r} \frac{kQ}{(r')^2} dr' = \frac{Q}{4\pi\epsilon_0} \frac{1}{r}$$

$$V(ec{\mathbf{r}}) \; = \; rac{1}{4\pi\epsilon_0} \sum_i rac{Q_i}{\imath_i}$$

Coulomb Potential:  $V(\vec{\mathbf{r}}) = \frac{1}{4\pi\epsilon_0} \int \frac{dq}{|\vec{\mathbf{z}_i}|}$ 

Work:  $W = \frac{1}{2} \sum q_i V(\vec{\mathbf{r}}_i)$ 

#### 2. Sphere

Reference Choice:  $V(\infty) = 0$ 

Let R be the radius.

$$V(r) = -\int_{\infty}^{r} \vec{E}(r') \cdot d\vec{r'}$$

• Conductor

$$E(r) = \begin{cases} \frac{kQ}{r^2} & \Rightarrow & V(r) = \begin{cases} \frac{Q}{4\pi\epsilon_0 r} & (r > R) \\ \frac{Q}{4\pi\epsilon_0 R} & (r < R) \end{cases}$$

• Insulator w/ CCD and  $\epsilon = \epsilon_0$ 

$$E(r) = \begin{cases} \frac{kQ}{r^2} & \Rightarrow V(r) = \begin{cases} \frac{Q}{4\pi\epsilon_0 r} & (r > R) \\ \frac{kQr}{R^3} & \end{cases} \qquad (r < R)$$

#### Charges at $\infty$

## 3. (Infinite) Parallel Plate Capacitor

Reference Choice: V(h) = 0

Let the Capacitor Height be h

$$V(z) = -\int_{h}^{z} \frac{\sigma}{\epsilon_{0}} \hat{z} \cdot d\vec{z} = \frac{\sigma(h-z)}{\epsilon_{0}} \quad (0 \le z \le h)$$

#### 4. (Infinite) Single Plate w/ CCD

Reference Choice: V(0) = 0

$$V(z) = -\int_0^z \frac{\sigma}{2\epsilon_0} \hat{z} \cdot d\vec{z} = -\frac{\sigma z}{2\epsilon_0} \quad (0 \le z < \infty)$$

Try  $V(\infty) = 0$ . (A charge distribution stretching to infinity DNE, so choose a diff. reference point.)

#### 5. Infinite Line w/ CCD

Reference Choice: V(1) = 0

$$V(r) = -\int_{1}^{r} \frac{\lambda}{2\pi r \epsilon_{0}} \hat{r} \cdot d\vec{r}$$
$$= -\frac{\lambda}{2\pi \epsilon_{0}} \ln r$$

Try  $V(\infty) = 0$  (same problem above).

#### Method of Images (Uniqueness Theorem)

**6.** 
$$\begin{bmatrix} \bullet & \delta_q \text{ at } x_0 \\ \bullet & V(0, y, z) = 0 \end{bmatrix} == \begin{bmatrix} \bullet & \delta_q \text{ at } x_0 \\ \bullet & \delta_{-q} \text{ at } -x_0 \end{bmatrix}$$

7. 
$$\begin{bmatrix} \bullet & \delta_q \text{ at } x_0 \\ \bullet & \text{Conductive sphere at origin O, of radius } R < x_0 \\ \text{and charge } Q \end{bmatrix}$$

$$==\begin{bmatrix} \bullet & \delta_q \text{ at } x_0 \\ \bullet & \delta_{-q\lambda} \text{ at } \left\{ x_1 \middle| \frac{R}{x_0} = \frac{x_1}{R} = \lambda \right\} \\ \bullet & \delta_{q\lambda+Q} \text{ at } \mathbf{O} \quad (V=0 \text{ grounded sphere} \to Q=-q\lambda) \end{bmatrix}$$

8. 
$$\begin{bmatrix} \bullet & \delta_q \text{ at } x_0 \\ \bullet & \text{Conductive sphere at origin O, of radius } R > x_0 \\ \text{and charge } Q. \end{bmatrix}$$

$$==\begin{bmatrix} \bullet & \delta_q \text{ at } x_0 \\ \bullet & \delta_{-q/\lambda} \text{ at } \left\{ x_1 \left| \frac{R}{x_0} = \frac{x_1}{R} = \lambda \right. \right\} \\ \bullet & \delta_{q+Q} \text{ at } \mathbf{O} \quad (V=0 \text{ grounded sphere} \to Q=-q) \end{bmatrix}$$

#### 2.3 Multipole Expansion

$$\begin{aligned}
\mathbf{z}^{2} &= r^{2} + (r')^{2} - 2(\vec{\mathbf{r}} \cdot \vec{r'}) \\
&= r^{2} \left[ 1 + \frac{r'}{r} \left( \frac{r'}{r} - 2 \frac{\vec{\mathbf{r}} \cdot \vec{r'}}{r'r} \right) \right] \Rightarrow \frac{1}{\mathbf{z}} = \frac{1}{r} (1 + \epsilon)^{-1/2} \\
&= r^{2} (1 + \epsilon)
\end{aligned}$$

$$\Rightarrow \frac{1}{\mathbf{z}} = \frac{1}{r} (1 + \epsilon)^{-1/2} \\
&= \frac{1}{r} \sum_{n=0}^{\infty} \left( \frac{r'}{r} \right)^{n} \mathbf{P}_{n} \left( \hat{\mathbf{r}}' \cdot \hat{\mathbf{r}} \right) \quad \text{(Legendre Polynomials)}$$

$$V(\vec{\mathbf{r}}) = \frac{1}{4\pi\epsilon_0} \int \frac{1}{\imath} \rho(\vec{r'}) d\tau'$$
$$= \left[ \frac{1}{4\pi\epsilon_0} \sum_n \frac{1}{r^{n+1}} \int (r')^n P_n(\cos\alpha) \rho(\vec{r'}) d\tau' \right]$$

$$= \frac{1}{4\pi\epsilon_0} \begin{bmatrix} \frac{1}{r} \int \rho(\vec{r'}) d\tau' + \frac{1}{r^2} \int \vec{r'} \cdot \hat{\mathbf{r}} \ \rho(\vec{r'}) d\tau' \\ + \frac{1}{r^3} \int (r')^2 P_2(\hat{r'} \cdot \hat{\mathbf{r}}) \ \rho(\vec{r'}) d\tau' + \frac{1}{r^4} \int \dots \end{bmatrix}$$

$$V_{\text{mon}} = \frac{1}{4\pi\epsilon_0 r} \int \rho(\vec{r'}) d\tau'$$

$$V_{\text{dip}} = \frac{1}{4\pi\epsilon_0 r^2} \left( \int \vec{r'} \ \rho(\vec{r'}) d\tau' \right) \cdot \hat{\mathbf{r}} = \frac{\vec{\mathbf{p}} \cdot \hat{\mathbf{r}}}{4\pi\epsilon_0 r^2}$$

V is the dipole term.  $\mathbf{p}$  is the dipole moment.

$$\vec{A}(\vec{\mathbf{r}}) = k_{\mu} \int \frac{1}{\imath} \vec{J}(\vec{r'}) d\tau'$$

$$= k_{\mu} \sum_{n} \frac{1}{r^{n+1}} \int (r')^{n} P_{n}(\cos \alpha) \vec{J}(\vec{r'}) d\tau'$$

$$= k_{\mu} \begin{bmatrix} \frac{1}{r} \int \vec{J}(\vec{r'}) d\tau' + \frac{1}{r^2} \int \vec{r'} \cdot \hat{\mathbf{r}} \ \vec{J}(\vec{r'}) d\tau' \\ + \frac{1}{r^3} \int (r')^2 P_2(\hat{r'} \cdot \hat{\mathbf{r}}) \ \vec{J}(\vec{r'}) d\tau' + \frac{1}{r^4} \int \dots \end{bmatrix}$$

Steady current: 
$$A_{\text{mon}} = \frac{\mu_0 I}{4\pi r} \oint dl' = 0$$
$$A_{\text{dip}} = \frac{k_{\mu}}{r^2} I \int \vec{r'} \cdot \hat{\mathbf{r}} \ dl' = \frac{k_{\mu}}{r^2} I \int d\vec{a'} \times \hat{\mathbf{r}}$$
$$= \frac{k_{\mu}}{r^2} (I\vec{a}) \times \hat{\mathbf{r}} = \frac{\mu_0 \vec{\mathbf{m}} \times \hat{\mathbf{r}}}{4\pi r^2}$$

A is the dipole term.  $\mathbf{m}$  is the dipole moment.

#### **Ideal Dipoles**

Let dipole (2 charges)  $\vec{\mathbf{p}} = p\hat{z} = 2dq\hat{z}$  and centered at the origin.

 $\lim d \to 0, \ q \to \infty$ :

$$V(\vec{\mathbf{r}}) = \frac{1}{4\pi\epsilon_0} \sum_{n=0}^{\infty} \frac{d^n P_n(\cos\alpha)q + (-d)^n P_n(\cos\alpha)(-q)}{4\pi\epsilon_0 r^{n+1}}$$

$$= \frac{1}{4\pi\epsilon_0} \sum_{n=0}^{\infty} \frac{P_n(\cos\alpha)qd^n}{r^{n+1}} [1 + (-1)^n]$$

$$= \frac{1}{4\pi\epsilon_0} \sum_{m=0}^{\infty} \frac{P_m(\cos\alpha)}{r^{2m+2}} (2qd)d^{2m}$$

$$= \frac{1}{4\pi\epsilon_0} \sum_{m=0}^{\infty} \frac{P_m(\cos\alpha)}{r^{2m+2}} pd^{2m}$$

 $= \frac{1}{4\pi\epsilon_0} \frac{P_0(\cos \alpha)}{r^2} p + 0 + 0 + \dots$ 

Ideal Dip: 
$$V_{\text{dip}}(\vec{\mathbf{r}}) = \frac{1}{4\pi\epsilon_0} \frac{\vec{\mathbf{p}} \cdot \hat{\boldsymbol{\imath}}}{\boldsymbol{\imath}^2}$$

Let dipole (ring)  $\vec{\mathbf{m}} = m\hat{z} = Ia\hat{z}$  and centered at the origin.

 $\lim a = \pi d^2 \to 0, \ I \to \infty :$ 

$$\vec{A}(\vec{\mathbf{r}}) = k_{\mu} \sum_{n=0}^{\infty} \frac{Id^n}{r^{n+1}} \int P_n(\cos \alpha) \ d\vec{l'}$$

$$= k_{\mu} \left( \begin{array}{c} \frac{I}{r} \int d\vec{l}' + \frac{I}{r^2} \int (d\hat{r'} \cdot \hat{\mathbf{r}}) d\vec{l}' \\ + \frac{Id^2}{r^3} \int \left[ \frac{3}{2} \left( 1 + 2 \frac{d\hat{r'} \cdot \hat{\mathbf{r}}}{d} + 1 \right) - \frac{1}{2} \right] d\vec{l}' \\ + Id^2 \sum_{n=3}^{\infty} \frac{d^{n-2}}{r^{n+1}} \int P_n(\hat{r'} \cdot \hat{\mathbf{r}}) d\vec{l}' \end{array} \right)$$

$$= k_{\mu} \left( 0 + \frac{I\pi d^{2}}{r^{2}} (\hat{z} \times \hat{\mathbf{r}}) + \frac{3I\pi d^{3}}{r^{3}} (\hat{z} \times \hat{\mathbf{r}}) + \frac{m}{\pi} (0 + ...) \right)$$
$$= k_{\mu} \left( 0 + \frac{m}{r^{2}} (\hat{z} \times \hat{\mathbf{r}}) + 0 + 0 + ... \right)$$

Ideal Dip: 
$$\vec{A}_{\text{dip}}(\vec{\mathbf{r}}) = k_{\mu} \frac{\vec{\mathbf{m}} \times \hat{\boldsymbol{\imath}}}{{\boldsymbol{\imath}}^2}$$

## 2.3.1 Multipole Examples

3.

4.

5.

## 3 Electrodynamics in Matter

## 3.1 Ideal Dipoles

$$\vec{\mathbf{p}} = \int r' \cdot \rho(r') \ d\tau'$$

$$\vec{F}_{\text{dip}} = qE \Big|_{\vec{r}}^{\vec{r}+\vec{d}} = q\Delta\vec{E}$$

$$\approx \left[ q \sum_{i} \left( \nabla E_{i} \cdot \vec{d} \right) \hat{i} \right] \qquad U_{\text{ES dip}} = qV \Big|_{\vec{r}}^{\vec{r}+\vec{d}} = q\Delta V$$

$$= q \int_{\vec{r}}^{\vec{r}+\vec{d}} -\vec{E} \cdot d\vec{l}$$

$$\boxed{\vec{F}_{\text{dip}} = (\vec{\mathbf{p}} \cdot \nabla) \vec{E}}$$

$$\boxed{U_{\text{ES dip}} = -\vec{\mathbf{p}} \cdot \vec{E}}$$

$$\vec{N}_{\text{center}} = r \times F = \vec{d} \times q\vec{E}$$
 
$$\vec{N}_{\text{dip}} = \vec{\mathbf{p}} \times \vec{E}$$

Polarization: 
$$\vec{P} = \frac{d\vec{\mathbf{p}}}{d\tau}$$
  $\left(\frac{\hat{\boldsymbol{\imath}}}{\boldsymbol{\imath}^2} = \nabla' \frac{1}{\boldsymbol{\imath}}\right)$ 

$$V(\vec{\mathbf{r}}) = \frac{1}{4\pi\epsilon_0} \int_{\nu} \frac{\vec{P}(\vec{r'}) \cdot \hat{\boldsymbol{\imath}}}{\hat{\boldsymbol{\imath}}^2} d\tau'$$

$$= \frac{1}{4\pi\epsilon_0} \int_{\nu} \frac{-\nabla' \cdot \vec{P}(\vec{r'})}{\hat{\boldsymbol{\imath}}} d\tau' + \frac{1}{4\pi\epsilon_0} \int_{S} \frac{\vec{P}(\vec{r'}) \cdot \hat{\boldsymbol{n}}}{\hat{\boldsymbol{\imath}}} da'$$

$$[\rho_b = -\nabla \cdot \vec{P}] \qquad [\sigma_b = \vec{P} \cdot \hat{\boldsymbol{n}}]$$

$$|\vec{\mathbf{m}} = \sum I\vec{a}|$$

$$\vec{F}_{\text{sqr. dip}} = q\vec{v} \times \vec{B}$$

$$= \pm IL\vec{x} \times B\hat{z}$$

$$= \pm ILB \hat{y}$$

$$\vec{N}_{\text{sqr. dip}} = 2 \left[ \frac{\pm \vec{W}}{2} \times \pm I L B \hat{y} \right]$$

$$= I(LW) \sin \theta B \hat{x}$$

$$\vec{N}_{
m dip} = \vec{\mathbf{m}} \times \vec{B}$$

$$\vec{F}_{\text{dip}} = \nabla(\vec{\mathbf{m}} \cdot \vec{B})$$
????

$$U_{\rm dip} = -\vec{\mathbf{m}} \cdot \vec{B}$$

Magnetization: 
$$\vec{M} = \frac{d\vec{\mathbf{m}}}{d\tau}$$
  $\left(\frac{\hat{\boldsymbol{\imath}}}{\boldsymbol{\imath}^2} = \nabla' \frac{1}{\boldsymbol{\imath}}\right)$ 

$$\vec{A}(\vec{\mathbf{r}}) = k_{\mu} \int_{\nu} \frac{\vec{M}(\vec{r'}) \times \hat{\boldsymbol{\imath}}}{\boldsymbol{\imath}^{2}} d\tau'$$

$$= k_{\mu} \int_{\nu} \frac{\nabla' \times \vec{M}(\vec{r'})}{\boldsymbol{\imath}} d\tau' + k_{\mu} \int_{S} \frac{\vec{M}(\vec{r'}) \times \hat{n}}{\boldsymbol{\imath}} da'$$

$$\vec{J}_{b} = \nabla \times \vec{M} \qquad \vec{K}_{b} = \vec{M} \times \hat{n}$$

### 3.2 Maxwell's Equations in Matter

GLE in Matter (GLEM)

$$\nabla \cdot \epsilon_0 \vec{E} = \rho = \rho_b + \rho_f$$
$$= -\nabla \cdot \vec{P} + \nabla \cdot D$$

$$\nabla \cdot \left( \epsilon_0 \vec{E} + \vec{P} \right) = \nabla \cdot D$$

$$\vec{D} = \epsilon_0 \vec{E} + \vec{P}$$
 
$$-\nabla \cdot \vec{P} = \rho_b$$
 
$$\nabla \cdot \vec{D} = \rho_f$$
 
$$\vec{P} \cdot \hat{n} = \sigma_b$$

COC in Matter (COCM)

$$\nabla \cdot \vec{J}_p = -\frac{\partial \rho_b}{\partial t}$$
$$= \frac{\partial}{\partial t} \left( \nabla \cdot \vec{\mathbf{P}} \right)$$

$$\boxed{\frac{\partial \vec{\mathbf{P}}}{\partial t} = \vec{J}_p}$$

MAL in Matter (MALM)

$$\nabla \times \frac{1}{\mu_0} \vec{B} = \vec{J} + \epsilon_0 \frac{\partial \vec{E}}{\partial t} = \vec{J}_b + \vec{J}_f + \vec{J}_p + \epsilon_0 \frac{\partial \vec{E}}{\partial t}$$
$$= \nabla \times M + \vec{J}_f + \frac{\partial \vec{\mathbf{P}}}{\partial t} + \epsilon_0 \frac{\partial \vec{E}}{\partial t}$$

$$\nabla \times \left( \frac{1}{\mu_0} \vec{B} - M \right) = \vec{J}_f + \frac{\partial}{\partial t} \left( \epsilon_0 \vec{E} + \vec{\mathbf{P}} \right)$$

$$\vec{H} = \frac{1}{\mu_0} \vec{B} - \vec{M}$$
 
$$\nabla \times \vec{H} = \vec{J}_f + \frac{\partial \vec{D}}{\partial t}$$
 
$$\nabla \times \vec{M} = \vec{J}_b$$
 
$$\vec{M} \times \hat{n} = \vec{K}_b$$

Faraday's Law of Induction (FLI)

$$\nabla \times \vec{E} = -\frac{\partial \vec{B}}{\partial t}$$

Electrostatics:  $\nabla \times \vec{D} = \nabla \times \vec{P}$ 

Gauss's Law for Magnetism (GLM)

$$\nabla \cdot \vec{B} = 0$$

$$\nabla \cdot \vec{H} = -\nabla \cdot \vec{M}$$

#### 3.3 Linear Matter

Electric Susceptibility:  $\chi_e$ 

$$\vec{P} = \chi_e \epsilon_0 \vec{E}$$

Susceptibility Tensor:

$$\vec{P} = \begin{pmatrix} \chi_{e_{xx}} & \chi_{e_{xy}} & \chi_{e_{xz}} \\ \chi_{e_{yx}} & \chi_{e_{yy}} & \chi_{e_{yz}} \\ \chi_{e_{zx}} & \chi_{e_{zy}} & \chi_{e_{zz}} \end{pmatrix} \epsilon_0 \vec{E}$$

Relative Permittivity:  $\epsilon_r = 1 + \chi_e$ 

$$\vec{D} = (1 + \chi_e)\epsilon_0 \vec{E}$$
$$= \epsilon_r \epsilon_0 \vec{E}$$
$$= \epsilon \vec{E}$$

Magnetic Susceptibility:  $\chi_m$ 

$$\vec{M} = \chi_m \vec{H}$$

Susceptibility Tensor:

$$\vec{M} = \begin{pmatrix} \chi_{m_{xx}} & \chi_{m_{xy}} & \chi_{m_{xz}} \\ \chi_{m_{yx}} & \chi_{m_{yy}} & \chi_{m_{yz}} \\ \chi_{m_{zx}} & \chi_{m_{zy}} & \chi_{m_{zz}} \end{pmatrix} \vec{H}$$

Bound Current:

$$\vec{J}_b = \nabla \times \left( \chi_m \vec{H} \right)$$
$$= \chi_m \left( \vec{J}_f + \partial_t \vec{D} \right)$$

Relative Permeability:  $\mu_r = 1 + \chi_m$ 

$$\vec{B} = (1 + \chi_m)\mu_0 \vec{H}$$
$$= \mu_r \mu_0 \vec{H}$$
$$= \mu \vec{H}$$

## **Boundary Conditions**

$$\Delta \vec{E} = \frac{\sigma}{\epsilon_0} \hat{n}$$

1. 
$$\Delta E_{\parallel} = 0$$
 
$$\oint \vec{E} \cdot d\vec{L} = - \oiint_{0-}^{0+} \frac{\partial \vec{B}}{\partial t} \cdot d\vec{a}$$
 
$$(E_{\parallel}^{+} - E_{\parallel}^{-})L = 0$$

2. 
$$\Delta E_{\perp} = \frac{\sigma}{\epsilon_0}$$
 
$$\int \vec{E} \cdot d\vec{a} = Q/\epsilon_0$$
 
$$(E_{\perp}^+ - E_{\perp}^-)a = \frac{\sigma a}{\epsilon_0}$$

Electrostatics:  $\nabla \times \vec{E} = 0$ 

$$\Delta V = 0 \qquad V \Big|_{0-}^{0+} = -\int_{0-}^{0+} \vec{E} \cdot dL$$

$$\Delta \frac{\partial V}{\partial n} = -\frac{\sigma}{\epsilon_0} \qquad \Delta(\nabla V) \cdot \hat{n}$$

$$oxed{\Delta ec{D}_{\parallel} = \Delta ec{P}_{\parallel}} \quad egin{equation} 
abla imes ec{D} = 
abla imes ec{P} \end{aligned}$$

$$\left| \Delta \vec{B} = \mu_0 \vec{K} \times \hat{n} \right|$$

1. 
$$\Delta B_{\perp} = 0$$
 
$$B \cdot d\vec{a} = 0$$
$$(B_{\perp}^{+} - B_{\perp}^{-})a = 0$$

2. 
$$\Delta \vec{B}_{\parallel} = \mu_0 \vec{K} \times \hat{n}$$

$$\Delta \vec{H}_{\parallel} = \vec{K}_f \times \hat{n}$$

$$\Delta B_{\parallel} L = \mu_0 K L = (\mu_0 \vec{K} \times \hat{n}) \cdot \vec{L}$$

$$\Delta A_{\parallel} = 0 \qquad \oint \vec{A} \cdot d\vec{l} = \Phi_B = 0$$

Magnetostatic:  $\nabla \cdot \vec{A} = 0$ 

$$\Delta A_{\perp} = 0$$
  $\iint_{0-}^{0+} \vec{A} \cdot d\vec{a} = 0$ 

$$\Delta A_{\perp} = 0 \qquad \left| \oint_{0-}^{0+} \vec{A} \cdot d\vec{a} = 0 \right|$$

$$\Delta \frac{\partial \vec{A}}{\partial n} = -\mu_0 \vec{K} \qquad \left| \Delta (\nabla \times \vec{A}) = \left( -\frac{\partial A_y^+}{\partial z} + \frac{\partial A_y^-}{\partial z} \right) \hat{x} + \left( \frac{\partial A_x^+}{\partial z} - \frac{\partial A_x^-}{\partial z} \right) \hat{y} \right|$$

$$= -\mu_0 K \hat{y}$$

## 5 Energy, Radiation, and Momentum

### 5.1 Energy Conservation

$$\begin{split} \frac{dW_{mech}}{dt} &= \vec{F} \cdot \vec{v} = q\vec{E} \cdot \vec{v} + q\vec{v} \times \vec{B} \cdot \vec{v} \\ &= \int \vec{E} \cdot \vec{J} \ d\tau \qquad (J = \rho_+ v_+ + \rho_- v_-) \\ &= \int -\frac{1}{2} \frac{\partial}{\partial t} \left( \epsilon_0 E^2 + \frac{1}{\mu_0} B^2 \right) - \nabla \cdot \left( \frac{1}{\mu_0} \vec{E} \times \vec{B} \right) d\tau \\ \hline \frac{dW_{mech}}{dt} &= -\frac{d}{dt} \int u_{em} \ d\tau - \int \nabla \cdot \vec{S} \ d\tau \\ &= -\int \frac{\partial u_{em}}{\partial t} \ d\tau - \oint \vec{S} \cdot d\vec{a} \end{split}$$

#### 5.1.1 Radiation

#### Accelerating Charge

Larmor Formula 
$$(v \ll c)$$
:  $P_{\text{ow}} = \left(\frac{2k_{\epsilon}}{3c^3}\right)q^2a^2$ 

#### Electric Dipole Radiation

Dipole Moment:  $\vec{\mathbf{p}}(t) = p_0 \cos(\omega t)\hat{z}$ 

Intensity: 
$$\langle S \rangle = \left(\frac{k_{\epsilon}}{8\pi c^3}\right) p_0^2 \omega^4 \frac{\sin^2 \theta}{r^2}$$

Power: 
$$\langle P \rangle_E = \left(\frac{k_{\epsilon}}{3c^3}\right) p_0^2 \omega^4$$

Magnetic Dipole Radiation: 
$$\langle P \rangle_B = \left(\frac{k_\mu}{3c^3}\right) m_0^2 \omega^4$$

Field Energy : 
$$u_{em} = \frac{dW_e}{d\tau} + \frac{dW_m}{d\tau} = \frac{\epsilon_0}{2}E^2 + \frac{1}{2\mu_0}B^2$$

Poynting Vector : 
$$\vec{S} = \frac{1}{\mu_0} (\vec{E} \times \vec{B}) = \frac{1}{2\mu_0} \text{Re}(\tilde{\mathbf{E}} \times \tilde{\mathbf{B}}^*)$$

$$\int \vec{S} \cdot d\vec{a} = -\left(\frac{dW_{mech}}{dT} + \frac{dU_{em}}{dt}\right) = P_{ow}$$

$$\nabla \cdot \vec{S} = -\frac{\partial}{\partial t}(u_{mech} + u_{em})$$

$$I = \langle P_{\text{ow}}/A \rangle = \langle S \rangle = \frac{1}{2}c\epsilon_0 E^2$$

#### 5.2 Momentum Conservation

$$\frac{\partial \vec{F}}{\partial \tau} = \vec{f} = \rho \vec{E} + \vec{J} \times \vec{B}$$

$$= \epsilon_0 \left[ (\nabla \cdot \vec{E}) \vec{E} + (\vec{E} \cdot \nabla) \vec{E} \right] + \frac{1}{\mu_0} \left[ (\nabla \cdot \vec{B}) \vec{B} + (\vec{B} \cdot \nabla) \vec{B} \right]$$

$$- \frac{1}{2} \nabla \left( \epsilon_0 E^2 + \frac{1}{\mu_0} B^2 \right) - \frac{\partial}{\partial t} \left( \epsilon_0 \vec{E} \times \vec{B} \right)$$

$$= \nabla \cdot \overrightarrow{T} - \frac{\partial}{\partial t} \left( \epsilon_0 \mu_0 \vec{S} \right) = \nabla \cdot \overrightarrow{T} - \frac{\partial \vec{g}_{em}}{\partial t}$$

$$\frac{dp_{mech}}{dt} = \int \nabla \cdot \overrightarrow{T} d\tau - \frac{d}{dt} \int \vec{g}_{em} d\tau$$

$$= \oint \overrightarrow{T} \cdot d\vec{a} - \int \frac{\partial \vec{g}_{em}}{\partial t} d\tau = \vec{F}$$

$$\oint \overrightarrow{T} \cdot d\vec{a} = \frac{d\vec{p}_{mech}}{dt} + \frac{d\vec{p}_{em}}{dt}$$

Field Momentum Density: 
$$\vec{g}_{em} = \epsilon_0 \mu_0 \vec{S} = \epsilon_0 (\vec{E} \times \vec{B})$$

Maxwell Stress Tensor:  $\overrightarrow{T}$ ,

(Force per Area on Surface):  $\overrightarrow{T}$ ,

 $T_{ij} = \epsilon_0 \left( E_i E_j - \frac{1}{2} \delta_{ij} E^2 \right) + \frac{1}{\mu_0} \left( B_i B_j - \frac{1}{2} \delta_{ij} B^2 \right)$ 
 $= \epsilon_0 E_i E_j + \frac{1}{\mu_0} B_i B_j - \delta_{ij} u_{em}$ 
 $T_{xx} = \epsilon_0 E_x^2 + \frac{1}{\mu_0} B_x^2 - u_{em}$ ,  $T_{xy} = \epsilon_0 E_x E_y + \frac{1}{\mu_0} B_x B_y$ 

Field Angular

Momentum Density:  $\vec{l}_{em} = \vec{r} \times \vec{g}_{em} = \epsilon_0 \vec{r} \times (\vec{E} \times \vec{B})$ 

$$abla \cdot \overrightarrow{T} = \vec{f} + rac{\partial \vec{g}_{em}}{\partial t} = rac{\partial}{\partial t} \left( \vec{g}_{mech} + \vec{g}_{em} 
ight)$$

#### 5.2.1 Examples (including hidden momentum)

- A circuit has momentum  $\int \epsilon_0(\vec{E} \times \vec{B}) d\tau$ , as it provides energy (center of energy) from the battery to the resistor.
- Hidden momentum is always relativistic.
- A magnetic dipole alone has no hidden momentum; in an electric field, the hidden momentum is  $-\int \epsilon_0(\vec{E} \times \vec{B}) d\tau$ .
- A spinning shell of charge / a long solenoid alone has no hidden momentum; an electric dipole in the middle will give the moving charges hidden momentum of  $-\int \epsilon_0(\vec{E} \times \vec{B}) d\tau$ .
- When one of the fields is removed/changes (discharge, etc.), the hidden momentum goes into the B-field creating charges, along with any mechanical EM response impulse; the impulsed applied on removal doesn't really depend on the initial field momentum or hidden momentum.
- When a field changes, any angular momentum stored in the fields is transferred to the other objects in the predictable way (as opposed to above, since it has no center of energy equivalent). If there are no other objects then there wouldn't be angular momentum anyway.
- Hidden momentum can exist when center of energy is moving (no examples given).

## 6 Potentials in Lorenz Gauge (nonstatic sources)

See Potentials for Recap

If choose  $\left( 
abla \cdot \vec{A} = -rac{1}{c^2} rac{\partial V}{\partial t} \; \Leftrightarrow \; \partial_\mu A^\mu = 0 
ight)$ 

$$-\Box^2 V = rac{
ho}{\epsilon_0} \ -\Box^2 ec{A} = \mu_0 ec{J}$$

Solutions satisfying these three equations (thus satisfying Maxwell's Eq.) are,

$$V(ec{\mathbf{r}},t) = rac{1}{4\pi\epsilon_0}\intrac{
ho(ec{r'},t_r)}{\imath}\;d au'$$
 $ec{A}(ec{\mathbf{r}},t) = k_\mu\intrac{ec{J}(ec{r'},t_r)}{\imath}\;d au'$ 

where  $t_r = t - \frac{\imath}{c}$ .

Notice that charges move, V and  $\vec{A}$  update at the speed of light.  $t_r = t + \frac{z}{c}$  is also a solution, though not physically real.

Using GLMP and FLIP to find the fields,

Jefimenko Equations:

$$ec{E}(ec{\mathbf{r}},t) = rac{1}{4\pi\epsilon_0}\int \left[rac{
ho(ec{\mathbf{r}},t_r)}{\imath^2}\hat{\imath} + rac{\dot{
ho}(ec{\mathbf{r}},t_r)}{c\,\imath}\hat{\imath} - rac{\dot{ec{J}}(ec{\mathbf{r}},t_r)}{c^2\,\imath}
ight]d au'$$

$$ec{B}(ec{\mathbf{r}},t) = k_{\mu} \int \left[ rac{ec{J}(ec{\mathbf{r}},t_r)}{ec{\epsilon}^2} + rac{\dot{ec{J}}(ec{\mathbf{r}},t_r)}{c\, \imath} 
ight] imes \hat{\imath} \ d au'$$

It's usually easier solve for the potentials first instead of fields directly. In the electrostatic and magnetostatic limits, CL and BSL are recovered.

## 7 EM Waves

$$f(z,t) = \operatorname{Re}[\tilde{f}(z,t)] = \operatorname{Re}[Ae^{i(kz-wt+\delta)}]$$

 $\omega$  is the same throughout! (?)

$$\frac{\lambda_1}{\lambda_2} = \frac{k_2}{k_1} = \frac{v_1}{v_2} = \frac{n_2}{n_1}$$

$$\tilde{\mathbf{f}}(\mathbf{z}, \mathbf{t}; \delta = \mathbf{0}) : \tilde{A}_I e^{i(k_1 z - wt)} + \tilde{A}_R e^{i(-k_1 z - wt)} \Rightarrow \tilde{A}_T e^{i(k_2 z - wt)}$$

$$\tilde{A}_I + \tilde{A}_R = \tilde{A}_T; \quad k_1(\tilde{A}_I - \tilde{A}_R) = k_2\tilde{A}_T$$

$$\tilde{A}_R e^{i\delta_R} = \left(\frac{v_2 - v_1}{v_2 + v_1}\right) \tilde{A}_I e^{i\delta_I}; \quad \tilde{A}_T e^{i\delta_T} = \left(\frac{2v_2}{v_2 + v_1}\right) \tilde{A}_I e^{i\delta_I}$$

$$A_R = \left(\frac{|v_2 - v_1|}{v_2 + v_1}\right) A_I; \quad A_T = \left(\frac{2v_2}{v_2 + v_1}\right) A_I$$

## 7.1 Vacuum, $\vec{v}_{||}\vec{E}_{||}\hat{z}$

$$\tilde{B}_0 = \frac{k}{w}(\hat{z} \times \tilde{E}_0) = \frac{1}{c}(\hat{z} \times \tilde{E}_0)$$

$$\vec{S} = cu_{EM}\hat{z} = c\epsilon_0 E_0^2 \cos^2(kw, wt + \delta)\hat{z}$$
$$I_{nt} = \langle S \rangle = \frac{1}{2}c\epsilon_0 E_0^2$$
$$P_{res} = \frac{I_{nt}}{c}$$

#### Linear Media 7.2

$$D = \epsilon E; \quad B = \mu H$$

$$\tilde{B}_0 = \frac{1}{v} (\hat{z} \times \tilde{E}_0)$$

$$\bullet \quad n = \sqrt{\frac{c}{\epsilon}}$$

$$\bullet \quad \boxed{n = \frac{c}{v}}$$

• 
$$n = \sqrt{\frac{\epsilon \mu}{\epsilon_0 \mu_0}} \approx \sqrt{\frac{\epsilon}{\epsilon_0}} = \sqrt{\epsilon_r}$$

$$\bullet \ k_I v_1 = k_R v_1 = k_T v_2 = \omega$$

• 
$$k_I \sin \theta_I = (k_R \sin \theta_R = k_R \sin \theta_I) = k_T \sin \theta_T$$

• Snell's Law: 
$$n_1 \sin \theta_I = n_2 \sin \theta_T$$

Fresnel's Equations Oblique Incidence  $\left(\alpha = \frac{\cos \theta_T}{\cos \theta_L} = \frac{\sqrt{1 - (n_1/n_2)^2 \sin \theta_L^2}}{\cos \theta_L}, \beta = \frac{\mu_1 v_1}{\mu_2 v_2} \approx \frac{v_1}{v_2}\right)$ 

• P-Polarized ( $E_{\parallel}$  to Plane of Incidence):

$$\tilde{E}_R = \left(\frac{\alpha - \beta}{\alpha + \beta}\right) \tilde{E}_I ; \quad \tilde{E}_T = \left(\frac{2}{\alpha + \beta}\right) \tilde{E}_I$$

$$R = \frac{I_R}{I_I} = \left(\frac{E_R}{E_I}\right)^2 = \left(\frac{\alpha - \beta}{\alpha + \beta}\right)^2$$

$$T = \frac{I_T}{I_I} = \frac{\epsilon_2 v_2}{\epsilon_1 v_1} \left(\frac{E_T}{E_I}\right)^2 \frac{\cos \theta_T}{\cos \theta_I} = \alpha \beta \left(\frac{2}{\alpha + \beta}\right)^2$$

Reflection Shift/Angles 
$$\left(\alpha - \beta \stackrel{?}{=} 0\right)$$
:  $\tan^2 \theta_I \stackrel{?}{=} \left(\frac{n_2}{n_1}\right)^2 \frac{1-\beta^2}{1-(n_2/n_1)^2}$ 

In-Phase 
$$(\delta = 0, \ \alpha > \beta)$$
:  $\tan \theta_I > n_2/n_1$   
Out-of-Phase  $(\delta = \pi, \ \alpha < \beta)$ :  $\tan \theta_I < n_2/n_1$ 

Brewster's Angle 
$$(R=0)$$
:  $\tan \theta_{I=b} = n_2/n_1$ ,  $\theta_R + \theta_T = 90$   
Critical Angle  $(T=0)$ :  $\sin \theta_{I=c} = n_2/n_1$ ,  $\theta_R = 90$  (evanescent if  $> \theta_C$ )

• S-Polarized ( $E_{\perp}$  to Plane of Incidence):

$$\tilde{E}_R = \left(\frac{1 - \alpha\beta}{1 + \alpha\beta}\right) E_I ; \quad \tilde{E}_T = \left(\frac{2}{1 + \alpha\beta}\right) E_I$$

$$R = \frac{I_R}{I_I} = \left(\frac{E_R}{E_I}\right)^2 = \left(\frac{1 - \alpha\beta}{1 + \alpha\beta}\right)^2$$

$$T = \frac{I_T}{I_I} = \frac{\epsilon_2 v_2}{\epsilon_1 v_1} \alpha \left(\frac{E_T}{E_I}\right)^2 = \alpha\beta \left(\frac{2}{1 + \alpha\beta}\right)^2$$

Reflection Shift/Angles 
$$\left(1 - \alpha\beta \stackrel{?}{=} 0\right)$$
:  $\alpha\beta \approx \frac{\sqrt{\beta^2 - \sin \theta_I^2}}{\cos \theta_I}$ 

In-Phase 
$$(\delta = 0, 1 > \alpha\beta)$$
:  $n_1 > n_2$   
Out-of-Phase  $(\delta = \pi, 1 < \alpha\beta)$ :  $n_2 > n_1$   
Brewster Angle  $(R = 0)$ :  $n_1 = n_2$  (None)

Critical Angle 
$$(T=0)$$
:  $\sin \theta_{I=c} = n_2/n_1$ ,  $\theta_R = 90$   $(n_1 > n_2)$  (evanescent if  $> \theta_c$ )

#### 7.3 Diffraction and Interference

<u>Double Slit Interference</u>:  $(d \ll L)$ 

Maxima:  $d \sin \theta = m\lambda$ 

Minima:  $d \sin \theta = (m + \frac{1}{2})\lambda$ 

Circular Aperture: (Diameter:  $D \ll L$ )

 $\theta = \text{Twice the normal, vertical angle}$ 

1st Minima :  $D \sin \theta = 1.22\lambda$ 

Optical Path Length:  $(n_1 \to n_2, \lambda \to \frac{\lambda}{n}, v_n = f \frac{\lambda}{n})$ 

- $\delta = \frac{2\pi d}{\lambda/n} = k(nd)$
- $\Delta x_n = nd = nv\Delta t = c\Delta t$  (t, time through medium n) (2dn for thin film reflec.)

## 7.4 Lenses and Mirrors ( $\lambda \ll a$ )

Draw Picture: 1.  $\overline{f, y_{[s]}, L_{\text{ens}}} \to \overline{L_{\text{ens}}, y'_{[s']}, \infty}$ 

2.  $\overline{\infty, y_{[s]}, L_{\text{ens}}} \to \overline{f', L_{\text{ens}}, y'_{[s']}}$ 

Imaging Eq. :  $\frac{n_1}{s} + \frac{n_2}{s'} = \frac{n_2 - n_1}{R}$ 

Thin Lens Eq. :  $\frac{1}{f} = \frac{1}{s} + \frac{1}{s'}$  (Focal Length, f = f')

Lensmaker Eq. :  $\frac{1}{f} = \left(\frac{n_2}{n_1} - 1\right) \left(\frac{1}{R_1} - \frac{1}{R_2}\right)$  ( $R_2$  is [-] for concave lens)

Lens Magnf. :  $M_T \equiv \frac{y'}{y} = -\frac{s'}{s} = \frac{f}{f-s}$  Virtual: f>s Real: s< f

Spherical Mirror: f = R/2

Single Slit Diffraction:  $(a \ll L, a \sim \lambda)$ 

Minima:  $a \sin \theta = m\lambda$ ,  $m \neq 0$ 

Bragg [X-Ray] Diffraction: (Atom Distance :  $d \sim \lambda$ )

 $\theta$  = Angle from Horizontal (not vertical/normal)

• Maxima:  $(2d)\sin\theta = m\lambda$ 

Boundary Reflection:  $(n_1 \to n_2)$ 

 $n_2 < n_1: \delta += 0$ 

 $n_2 > n_1: \delta += \pi$ 

#### 7.5 Other

Rayleigh Scattering  $(\lambda \gg a)$ :  $I \propto I_0 \left(\frac{a^6}{\lambda^4}\right)$  (Dipole Radiation, polarized)

[Sound] Doppler Effect  $(v \ll c)$ :  $f_r = \left(\frac{v + v_r}{v - v_s}\right) f_s$  (frequency, f)  $(v_r, v_s \text{ are } [+] \text{ if } \rightarrow \leftarrow)$ 

Standing Sound Wave

• Open Pipe :  $L = n\left(\frac{\pi}{2}\right)$  (Ends are nodes/infl. pts. of 0 press.)

• Half Pipe :  $L = (2n+1) \left(\frac{\pi}{4}\right)$  (Open End is a node, Closed is an antinode/maxi. press.)

Malus's Law:  $I = I_0 \cos^2 \theta$  (polarized)  $I = I_0/2$  (unpolarized)

## 7.6 Conductor; $J_{free} \neq 0$

$$J_{free} = \sigma E$$

$$\tilde{E}(z,t) = \tilde{E}_0 e^{i(\tilde{k}z - wt)}; \quad \tilde{B}(z,t) = \tilde{B}_0 e^{i(\tilde{k}z - wt)}$$

$$\tilde{k} = k + i\kappa; \quad \tilde{k}^2 = \mu \epsilon \omega^2 + i\mu \sigma \omega$$

$$k = \omega \sqrt{\frac{\epsilon \mu}{2}} \sqrt{\sqrt{1 + \left(\frac{\sigma}{\epsilon \omega}\right)^2} + 1} \; ; \quad \kappa = \omega \sqrt{\frac{\epsilon \mu}{2}} \sqrt{\sqrt{1 + \left(\frac{\sigma}{\epsilon \omega}\right)^2} - 1}$$

Skin depth: 
$$d = \frac{1}{\kappa}$$

Wave (phase) velocity: 
$$v = \frac{\omega}{k}$$

Group velocity (carries energy): 
$$v_g = \frac{d\omega}{dk} < c$$

Index Ref: 
$$n = \frac{ck}{\omega}$$

$$\frac{B_0}{E_0} = \frac{K}{\omega} = |\tilde{k}|/\omega = \sqrt{\epsilon \mu \sqrt{1 + \left(\frac{\sigma}{\epsilon \omega}\right)^2}}$$

$$\tilde{\beta} = \frac{\mu_1 v_1}{\mu_2 \omega} \tilde{k}$$

$$\tilde{E}_R = \left(\frac{1-\tilde{\beta}}{1+\tilde{\beta}}\right)\tilde{E}_I; \quad \tilde{E}_T = \left(\frac{2}{1+\tilde{\beta}}\right)\tilde{E}_I$$

#### 7.7 Wave Guides

$$E^{||} = 0; \quad B^{\perp} = 0$$

TE Waves:  $E_z = 0$ ; TM Waves:  $B_z = 0$ ; TEM Waves:  $E_z = B_z = 0$ 

$$E_{x} = \frac{i}{(w/c)^{2} - k^{2}} \left( k \frac{\partial E_{z}}{\partial x} + \omega \frac{\partial B_{z}}{\partial y} \right)$$

$$E_{y} = \frac{i}{(w/c)^{2} - k^{2}} \left( k \frac{\partial E_{z}}{\partial y} - \omega \frac{\partial B_{z}}{\partial x} \right)$$

$$B_{x} = \frac{i}{(w/c)^{2} - k^{2}} \left( k \frac{\partial B_{z}}{\partial x} - \frac{\omega}{c^{2}} \frac{\partial E_{z}}{\partial y} \right)$$

$$B_{Y} = \frac{i}{(w/c)^{2} - k^{2}} \left( k \frac{\partial B_{z}}{\partial Y} + \frac{\omega}{c^{2}} \frac{\partial E_{z}}{\partial X} \right)$$

Solving Rectangular Wave Guides:

TE<sub>mn≠00</sub>: 
$$\left[\frac{\partial^2}{\partial x^2} + \frac{\partial^2}{\partial y^2} + (\omega/c)^2 - k^2\right] B_z = 0$$
  
 $B_z = X(x)Y(y)$ 

$$\frac{\partial^2 X}{\partial x^2} = -k_x^2 X; \quad \frac{\partial^2 Y}{\partial y^2} = -k_y^2 Y$$
$$-k_x^2 - k_y^2 + (w/c)^2 - k^2 = 0$$

 $B_z = B_0 \cos(m\pi x/a) \cos(n\pi y/b)$ 

$$\omega < \omega_{mn} = c\pi \sqrt{(m/a)^2 + (n/b)^2}$$

TM: 
$$\left[\frac{\partial^2}{\partial x^2} + \frac{\partial^2}{\partial y^2} + (\omega/c)^2 - k^2\right] E_z = 0$$

## 8 Del

$$\nabla F = \left\langle \frac{\partial}{\partial r}, \frac{1}{r} \frac{\partial}{\partial \theta}, \frac{1}{r \sin \theta} \frac{\partial}{\partial \phi} \right\rangle_{r,\theta,\phi} F = \left( \hat{r}, \hat{\theta}, \hat{\phi} \right) \cdot \left( \frac{\partial}{\partial r}, \frac{1}{r} \frac{\partial}{\partial \theta}, \frac{1}{r \sin \theta} \frac{\partial}{\partial \phi} \right) F$$

$$= \left( \frac{\cos \phi \sin \theta \hat{x} + \sin \phi \sin \theta \hat{y} + \cos \theta \hat{z}}{\cos \phi \cos \theta \hat{x} + \sin \phi \cos \theta \hat{y} - \sin \theta \hat{z}} \right) \cdot \left[ \frac{\partial}{\partial r} \frac{1}{r \frac{\partial}{\partial \theta}} \right] F$$

$$= \left( \frac{\cos \phi \sin \theta \hat{x} + \sin \phi \cos \theta \hat{y} - \sin \theta \hat{z}}{-\sin \phi \hat{x} + \cos \phi \hat{y}} \right) \cdot \left[ \frac{\partial}{\partial r} \frac{1}{r \frac{\partial}{\partial \theta}} \right] F$$

$$= \left( \frac{\cos \phi \sin \theta \frac{\partial}{\partial r} + \frac{\cos \phi \cos \theta}{r} \frac{\partial}{\partial \theta} - \frac{\sin \phi}{r \sin \theta} \frac{\partial}{\partial \phi}}{r \sin \theta} \right) \right\rangle_{x,y,z} F = \begin{bmatrix} \hat{x} \\ \hat{y} \\ \hat{z} \end{bmatrix} \cdot \begin{bmatrix} \frac{\partial}{\partial x} \\ \frac{\partial}{\partial y} \\ \frac{\partial}{\partial y} \end{bmatrix} F$$

$$\nabla \cdot \vec{A} = \frac{1}{r} \frac{1}{r \sin \theta} \left\langle \frac{\partial}{\partial r}, \frac{\partial}{\partial \theta}, \frac{\partial}{\partial \phi} \right\rangle \cdot [r \cdot r \sin \theta] \left\langle A_r, \frac{1}{r} A_\theta, \frac{1}{r \sin \theta} A_\phi \right\rangle$$

$$\nabla \times \vec{A} = \frac{1}{r} \frac{1}{r \sin \theta} \left| \hat{r} - r \hat{\theta} - r \sin \theta \hat{\phi} \right|_{A_r} F \sin \theta A_\phi$$

$$[\vec{A} \times (\vec{B} \times \vec{C})]_i = \vec{A} \cdot (B_i \vec{C}) - \vec{A} \cdot (\vec{B} C_i)$$

$$\vec{A} \times (\vec{B} \times \vec{C}) = [(\vec{A} \cdot (\vec{B} \otimes \vec{C})^T)^T - (\vec{A} \cdot \vec{B} \otimes \vec{C})^T] = (\vec{A} \otimes \vec{B}) \cdot \vec{C} - (\vec{A} \cdot \vec{B} \otimes \vec{C})^T$$

$$= (A^T (BC^T)^T)^T - (A^T BC^T)^T = (AB^T)^T C - (A^T BC^T)^T$$

$$d\vec{r} = d\hat{x} + d\hat{y} + d\hat{z}$$

$$= \partial \hat{r} + r \partial \hat{\theta} + r \sin \theta \partial \hat{\phi}$$

$$\left[\hat{r}, \ \hat{\theta}, \ \hat{\phi}\right] = \left[\frac{\partial}{\partial r}, \ \frac{1}{r} \frac{\partial}{\partial \theta}, \ \frac{1}{r \sin \theta} \frac{\partial}{\partial \phi}\right] \vec{r}$$

$$= \left[\nabla_s \otimes \vec{r}\right]^T$$

$$\theta = \theta(x, y, z) \quad (x^2 + y^2 = z^2 \tan^2 \theta)$$

$$\phi = \phi(x, y, z) \quad (y = x \tan \phi)$$

$$d\theta = \frac{\partial \theta}{\partial x} dx + \frac{\partial \theta}{\partial y} dy + \frac{\partial \theta}{\partial z} dz$$

$$\frac{\partial}{\partial x} = \frac{\partial r}{\partial x} \frac{\partial}{\partial r} + \frac{\partial \theta}{\partial x} \frac{\partial}{\partial \theta} + \frac{\partial \phi}{\partial x} \frac{\partial}{\partial \phi}$$

$$\left[\frac{dr}{d\theta}\right]_{d\phi} = \begin{bmatrix} -\nabla r - \\ -\nabla \theta - \\ -\nabla \theta - \\ -\nabla \phi - \end{bmatrix} \begin{bmatrix} dx \\ dy \\ dz \end{bmatrix}$$

$$\left[\frac{\partial}{\partial r}\right]_{\frac{\partial}{\partial y}} = \begin{bmatrix} | & | & | \\ \nabla r & \nabla \theta & \nabla \phi \\ | & | & | \end{bmatrix} \begin{bmatrix} \frac{\partial}{\partial r} \\ \frac{\partial}{\partial \theta} \\ \frac{\partial}{\partial \phi} \end{bmatrix}$$

$$\left[\frac{dx}{dy}\right]_{dz} = \begin{bmatrix} -\nabla_s x - \\ -\nabla_s y - \\ \nabla^s y - \end{bmatrix} \begin{bmatrix} \partial r \\ r \partial \theta \\ \frac{\partial}{\partial z} \end{bmatrix}$$