CS101 Algorithms and Data Structures

Hash Table
Textbook Ch 11



Outline

- Introduction
- Hash function
- Mapping down to 0, ..., M − 1
- Dealing with collisions
 - Chained hash tables
 - Open addressing

Suppose we have a system which is associated with approximately 150 error conditions where

- Each of which is identified by an 16-bit number from 0 to 65535, and
- When an identifier is received, a corresponding error-handling function must be called

We could create an array of 150 function pointers and to then call the appropriate function....

```
#include <iostream>
                                    int main() {
                                        void (*function_array[150])();
                                        unsigned int error_id[150];
void a() {
    std::cout
                                        function_array[0] = a;
        << "Calling 'void a()'"
                                        error_id[0] = 3;
                                        function_array[1] = b;
        << std::endl;
                                        error_id[1] = 8;
}
                                        function_array[0]();
void b() {
                                        function array[1]();
    std::cout
        << "Calling 'void b()'"
                                        return 0;
        << std::endl;
}
```

Given an error-condition identifier, e.g., id = 198, how shall we determine which of the 150 slots corresponds to it?

– Binary search!

Problems

- This is slow: it would require approximately 7 comparisons per error condition
- Slow to dynamically add new error conditions or remove defunct conditions

A better solution:

- Create an array of size 65536
- Assign those entries corresponding to valid error conditions

```
int main() {
    void (*function_array[65536])();
    for ( int i = 0; i < 65536; ++i ) {
        function_array[i] = nullptr;
    }

    function_array[3] = a;
    function_array[8] = b;

    function_array[3]();
    function_array[8]();

    return 0;
}</pre>
```

Problem: additional memory usage

Examples:

Suppose we want to associate IP addresses and any corresponding domain names

Recall that a 32-bit IP address are often written as four byte values from 0 to 255

- Consider 10000001 01100001 00001010 10110011₂
- This can be written as 129.97.10.179
- We use domain names because IP addresses are not human readable

Given an IP address, sometimes we wanted to *quickly* find any associated domain name.

We could create an array of size 2^{32} = 4,294,967,296 of strings!

```
string domain_name[4294967296];
```

For example, the IP address of shanghaitech.edu.cn is 10.15.42.202

- As
$$202 + 42 \times 2^8 + 15 \times 2^{16} + 10 \times 2^{24} = 168766154$$
, it follows that

```
domain_name[168766154] = "shanghaitech.edu.cn";
```

Given an IP address, sometimes we wanted to *quickly* find any associated domain name.

We could create an array of size 2^{32} = 4,294,967,296 of strings!

string domain_name[4294967296];

As of 2017, the number of domain names is 330 million. So most part of the array is empty!

Under IPv6, IP addresses are 128 bits

- It combines what is now implemented as subnets as well as allowing for many more IP addresses
- We cannot allocate an array of size 2¹²⁸!

DNS

Given a domain name, we wanted to *quickly* find the associated IP address.

- A domain name can have a maximum of 253 characters!
- The number of possible domain names is huge!
- Again, we cannot allocate an array for that.

Goal

Our goal:

- Store data so that all operations are $\Theta(1)$ time
- The memory requirement should be $\Theta(n)$

Keys

In our example, we:

- Created an array of size 65536
- Store each of 150 objects in one of the 256 entries
- The error code indicated which bin the corresponding function pointer was stored

In general, we would like to:

- Create an array of size M
- Store each of *n* objects in one of the *M* bins
- Have some means of determining the bin in which an object is stored

Let's try a simpler problem

– How do I store your examination grades so that I can access your grades in $\Theta(1)$ time?

Assume that each student is issued an 8-digit number

- How do I store your examination grades so that I can access your grades in $\Theta(1)$ time?
- Create an array of size $10^8 \approx 1.5 \times 2^{26}$?

I could create an array of size 1000

- How could you convert an 8-digit number into a 3-digit number?
- Idea: the last three digits, which seem random

Therefore, I could store the examination grade of student "10105456" by:

```
grade[456] = 86;
```

Question:

- What is the likelihood that in a class of size 100 no two students have the same last three digits?
- Not very high:

$$1 \cdot \frac{999}{1000} \cdot \frac{998}{1000} \cdot \frac{997}{1000} \cdot \dots \cdot \frac{901}{1000} \approx 0.005959$$

Consequently, I have a function that maps a student onto a 3-digit number

- I can store the examination grade in that location
- Storing it, accessing it, and erasing it is $\Theta(1)$
- Problem: two or more students may map to the same number:
 - Student A has ID 20173456 and scored 85
 - Student B has ID 20234456 and scored 87

454	
455	
456	86
457	
458	
459	
460	
461	
462	
463	79
464	
465	

The hashing problem

The process of mapping an object or a number onto an integer in a given range is called *hashing*

Problem: multiple objects may hash to the same value

Such an event is termed a collision

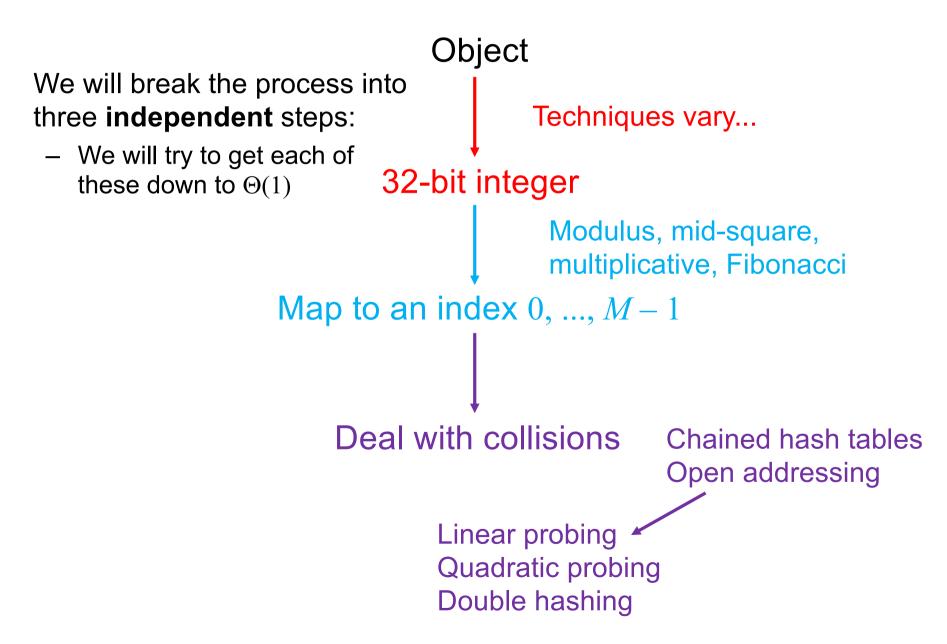
Hash tables use a hash function together with a mechanism for dealing with collisions

Going back to the problem with IP addresses

- We need a hash function to map an IP address to a smaller range
- We need a hash function to map a domain name to a smaller range

Mapping 129.97.10.179 onto a smaller range may seem easier, but a mechanism for mapping churchill.uwaterloo.ca onto a small range of integers may be more interesting

The hash process



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Definitions

What is a hash of an object?

From Merriam-Webster:

a restatement of something that is already known

The ultimate goal is to map onto an integer range

$$0, 1, 2, \ldots, M-1$$

Properties

Necessary properties of such a hash function *h* are:

- 1a. Should be fast: ideally $\Theta(1)$
- 1b. The hash value must be deterministic
 - It must always return the same 32-bit integer each time
- 1c. Equal objects hash to equal values
 - $x = y \Rightarrow h(x) = h(y)$
- 1d. If two objects are randomly chosen, there should be only a one-in- 2^{32} chance that they have the same hash value

Types of hash functions

We will look at two classes of hash functions

- Predetermined hash functions (explicit)
- Arithmetic hash functions (implicit)

The easiest solution is to give each object a unique number

For example, an auto-incremented static member variable

```
class Class name {
    private:
        unsigned int hash value;
        static unsigned int hash count;
    public:
        Class name();
        unsigned int hash() const;
                                              Class name::Class name() {
};
                                                  hash value = hash count;
                                                  ++hash count;
                                              }
unsigned int Class_name::hash_count = 0;
                                              unsigned int Class name::hash() const {
                                                  return hash value;
                                              }
```

If we only need the hash value while the object exists in memory, use the address:

```
unsigned int Class_name::hash() const {
    return reinterpret_cast<unsigned int>( this );
}
```

This fails if an object may be stored in secondary memory

It will have a different address the next time it is loaded

- Problem with predetermined hash functions?
 - Strings with the same characters:

```
string str1 = "Hello world!";
string str2 = "Hello world!";
```

Objects which are conceptually equal:

```
Rational x(1, 2);
Rational y(3, 6);
```

- The previous two methods would give them different hash values.
- But, a hash function should "hash equal objects to equal values"
- These hash values must depend on the member variables
 - Usually this uses arithmetic functions

Arithmetic Hash Values

An arithmetic hash value is a deterministic function that is calculated from the relevant member variables of an object

We will look at arithmetic hash functions for:

- Rational numbers, and
- Strings

What if we just add the numerator and denominator?

```
class Rational {
    private:
        int numer, denom;
    public:
        Rational( int, int );
};

unsigned int Rational::hash() const {
    return static_cast<unsigned int>( numer ) +
        static_cast<unsigned int>( denom );
}
```

Very likely to collide!

We could improve on this: multiply the denominator by a large prime:

```
class Rational {
    private:
        int numer, denom;
    public:
        Rational(int, int);
};

unsigned int Rational::hash() const {
    return static_cast<unsigned int>( numer ) +
        429496751*static_cast<unsigned int>( denom );
}
```

This hash function does not generate unique values

– The following pairs have the same hash values:

0/1	1327433019/800977868
1/2	534326814/1480277007
2/3	820039962/1486995867

- Finding rational numbers with matching hash values is very difficult:
- Finding these required the generation of 1 500 000 000 random rational numbers
- It is fast: $\Theta(1)$
- It does produce an even distribution

Problem:

- The rational numbers 1/2 and 2/4 have different values
- The output of

```
cout << Rational( 1, 2 ).hash();
cout << Rational( 2, 4 ).hash();</pre>
```

is

858993503

1717987006

```
Solution: divide through by the greatest common divisor
     Rational::Rational( int a, int b ):numer(a), denom(b) {
         int divisor = gcd( numer, denom );
         numer /= divisor;
         denom /= divisor;
                             int gcd( int a, int b) {
                                 while( true ) {
                                    if ( a == 0 ) {
                                        return (b >= 0) ? b : -b;
                                    b %= a;
                                    if ( b == 0 ) {
                                        return (a >= 0) ? a : -a;
                                    a %= b;
```

```
Problem:

- The rational numbers \frac{1}{2} and \frac{-1}{-2} have different values

- The output of

int main() {

    cout << Rational( 1, 2).hash();

    cout << Rational( -1, -2).hash();

    return 0;

}

is

858993503

3435973793
```

Solution: define a normal form

Require that the denominator is positive

```
Rational::Rational( int a, int b ):numer(a), denom(b) {
   int divisor = gcd( numer, denom );
   divisor = (denom >= 0) ? divisor : -divisor;
   numer /= divisor;
   denom /= divisor;
}
```

Two strings are equal if all the characters are equal and in the identical order

A string is simply an array of bytes:

Each byte stores a value from 0 to 255

Any hash function must be a function of these bytes

We could, for example, just add the characters:

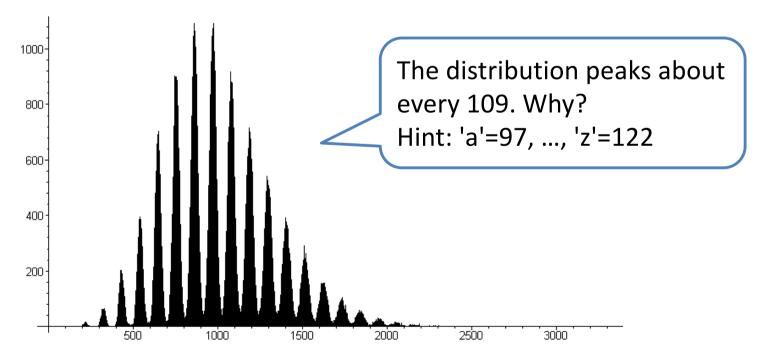
```
unsigned int hash( const string &str ) {
   unsigned int hash_value = 0;

for ( int k = 0; k < str.length(); ++k ) {
    hash_value += str[k];
  }

return hash_value;
}</pre>
```

Not very good:

- Slow run time: $\Theta(n)$
- Words with the same characters hash to the same code:
 - "form" and "from"
- A poor distribution, e.g., all words in MobyTM Words II by Grady Ward:



Let the individual characters represent the coefficients of a polynomial in *x*:

$$p(x) = c_0 x^{n-1} + c_1 x^{n-2} + \dots + c_{n-3} x^2 + c_{n-2} x + c_{n-1}$$

Use Horner's rule to evaluate this polynomial at a prime number, e.g., x = 12347:

```
unsigned int hash( string const &str ) {
   unsigned int hash_value = 0;

for ( int k = 0; k < str.length(); ++k ) {
    hash_value = 12347*hash_value + str[k];
  }

return hash_value;
}</pre>
```

```
Problem, Horner's rule runs in Θ(n)
    "A Elbereth Gilthoniel,\n
    Silivren penna miriel\n
    O menal aglar elenath!\n
    Na-chaered palan-diriel\n
    O galadhremmin ennorath,\n
    Fanuilos, le linnathon\n
    nef aear, si nef aearon!"
```

Suggestions?

```
Use characters in locations 2^k - 1 for k = 0, 1, 2, ...:
```

```
"A_Elbereth Gilthoniel,\n
Silivren_penna miriel\n
O menal aglar elenath!\n
Na-chaered palan-diriel\n
O galadhremmin ennorath,\n
Fanuilos, le linnathon\n
nef aear, si nef aearon!"
```

J.R.R. Tolkien

The run time is now $\Theta(\ln(n))$:

```
unsigned int hash( const string &str ) {
   unsigned int hash_value = 0;

for ( int k = 1; k <= str.length(); k *= 2 ) {
     hash_value = 12347*hash_value + str[k - 1];
   }

return hash_value;
}</pre>
```

Arithmetic hash functions

In general, any member variables that are used to uniquely define an object may be used as coefficients in such a polynomial

```
class Person {
    string surname;
    string given_name;
    unsigned short birth_year;
    unsigned char birth_month;
    unsigned char birth_day;
    unsigned int salary;
    // ...
};
```

Arithmetic hash functions

In general, any member variables that are used to uniquely define an object may be used as coefficients in such a polynomial

```
class Person {
    string surname;
    string given_name;
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    unsigned char birth_day;
    unsigned int salary;
    // ...
};
```

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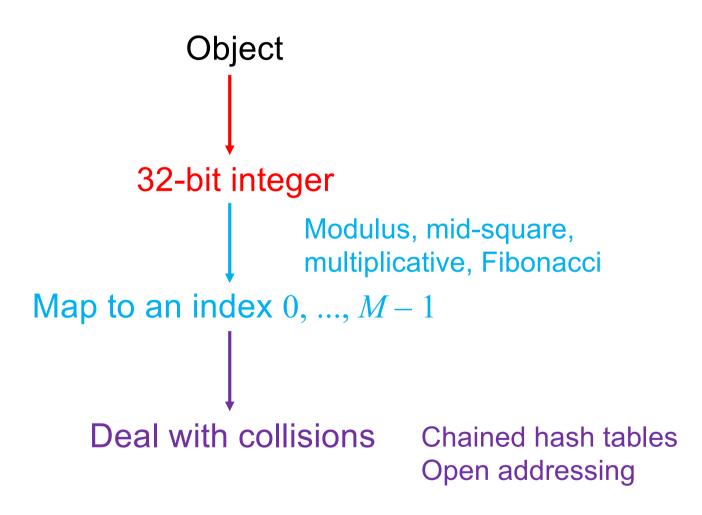
Previously, we considered means for calculating 32-bit hash values

- Explicitly defined hash values
- Implicitly calculated hash values

Practically, we will require a hash value on the range 0, ..., M-1:

- The modulus operator %
- Review of bitwise operations
- The multiplicative method

The hash process



Properties

Necessary properties of this mapping function h_M are:

- 2a. Must be fast: $\Theta(1)$
- 2b. The hash value must be deterministic
 - Given n and M, $h_M(n)$ must always return the same value
- 2c. If two objects are randomly chosen, there should be only a one-in-M chance that they have the same value from 0 to M-1

Modulus operator

Easiest method: return the value modulus M

```
unsigned int hash_M( unsigned int n, unsigned int M ) {
   return n % M;
}
```

Unfortunately, calculating the modulus (or remainder) is expensive

- If $M = 2^m$, we can simplify the calculation by bitwise operations
 - · left and right shift and bit-wise and

Suppose I want to calculate

7985325 % 100

The modulo is a power of ten: $100 = 10^2$

In this case, take the last two decimal digits: 25

Similarly, $7985325 \% 10^3 = 325$

We set the appropriate digits to 0:

0000025 and 0000325

The same works in base 2:

100011100101₂ % 10000₂

The modulo is a power of 2: $10000_2 = 2^4$

In this case, take the last four bits: 0101

Similarly, 100011100101_2 % 1000000_2 == 100101,

— We set the appropriate digits to 0:

000000000101 and 000000100101

To zero all but the last *n* bits, select the last *n* bits using *bitwise and*:

```
1000 1110 0101_2 & 0000 0000 1111_2 \rightarrow 0000 0000 0101_2
1000 1110 0101_2 & 0000 0011 11111_2 \rightarrow 0000 0010 0101_2
```

Similarly, multiplying or dividing by powers of 10 is easy: 7985325 * 100

The multiplier is a power of ten: $100 = 10^2$

In this case, add two zeros: 798532500

Similarly, $7985325 / 10^3 = 7985$

 Just add the appropriate number of zeros or remove the appropriate number of digits

The same works in base 2:

100011100101₂ * 10000₂

The modulo is a power of 2: $10000_2 = 2^4$

In this case, add four zeros: 1000111001010000

Similarly, 100011100101_2 / 1000000_2 == 100011

This can be done mechanically by shifting the bits appropriately:

$$1000\ 1110\ 0101_2 << 4 == 1000\ 1110\ 0101\ 0000_2$$
 $1000\ 1110\ 0101_2 >> 6 == 10\ 0011_2$

Powers of 2 are now easy to calculate:

Modulo a power of two

The implementation using the modulus/remainder operator:

```
unsigned int hash_M( unsigned int n, unsigned int m ) {
    return n & ((1 << m) - 1);
}</pre>
```

Modulo a power of two

Problem:

- Suppose that the hash function h is always even
- An even number modulo a power of two is still even

Example: memory allocations are multiples of word size

- On a 64-bit computer, addresses returned by new will be multiples of 8
- The probability that $h_M(h(x)) = h_M(h(y))$ is one in M/8
 - This is not one in M

We need to obfuscate the bits

- The most common method to obfuscate bits is multiplication
- Consider how one bit can affect an entire range of numbers in the result:

```
10100111

× 11010011

10100111

10100111

10100111

+ 10100111

1000101110100101
```

The avalanche effect: changing one bits has the potential of affecting all bits in the result: 10100011 × 11010011 = 1000011001011001

Multiplying by a fixed constant is a reasonable method

- Take the middle *m* bits of *Cn*:

```
unsigned int const C = 581869333; // some number

unsigned int hash_M( unsigned int n, unsigned int m ) {
   unsigned int shift = (32 - m)/2;
   return ((C*n) >> shift) & ((1 << m) - 1);
}</pre>
```

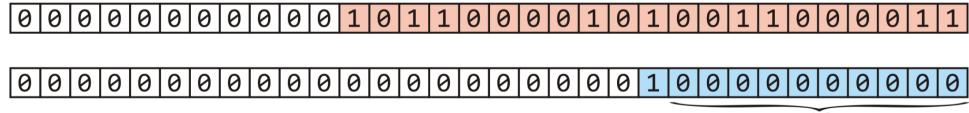
```
Suppose that the value m=10 (M=1024) and n=42 const unsigned int C = 581869333; // some number unsigned int hash_M( unsigned int n, unsigned int m ) { unsigned int shift = (32 - m)/2; return ((C*n) >> shift) & ((1 << m) - 1); }
```

```
First calculate the shift m=42 const unsigned int C = 581869333; // some number unsigned int hash_M( unsigned int n, unsigned int m ) { unsigned int shift = (32 - m)/2; return ((C*n) >> shift) & ((1 << m) - 1); } shift = 11
```

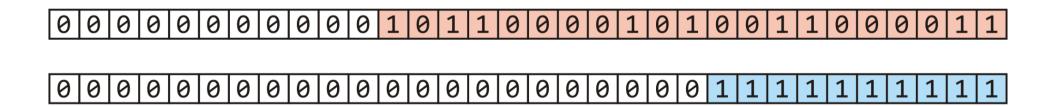
```
Calculate Cn n=42 const unsigned int C = 581869333; // some number unsigned int hash_M( unsigned int n, unsigned int m ) { unsigned int shift = (32 - m)/2; return ((C*n) >> shift) & ((1 << m) - 1); } shift = 11
```

```
m = 10
                                                       n = 42
  Right shift this value 11 bits—equivalent to dividing by 2<sup>11</sup>
      const unsigned int C = 581869333; // some number
      unsigned int hash M( unsigned int n, unsigned int m ) {
          unsigned int shift = (32 - m)/2;
          return ((C*n) >> shift) & ((1 << m) - 1);
shift = 11
                 0|1|0|0|1
                           1 0 0 0 0 0 1 1 0 0 1 0 1
1|0|0|0|0|1
        11
```

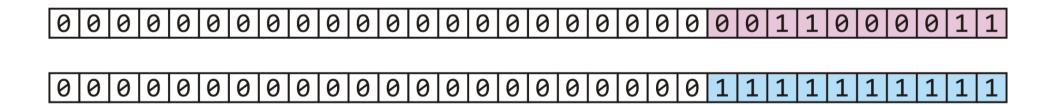
```
Left shift 1 m=10 bits yielding 2^{10} n=42 const unsigned int C = 581869333; // some number unsigned int hash_M( unsigned int n, unsigned int m ) { unsigned int shift = (32 - m)/2; return ((C*n) >> shift) & ((1 << m) - 1); }
```



```
Subtracting 1 yields m=10 ones n=42 const unsigned int C = 581869333; // some number unsigned int hash_M( unsigned int n, unsigned int m ) { unsigned int shift = (32 - m)/2; return ((C*n) >> shift) & ((1 << m) - 1); }
```



```
Taken the bitwise to clear all but the last 10 bits n=42 const unsigned int C = 581869333; // some number unsigned int hash_M( unsigned int n, unsigned int m ) { unsigned int shift = (32 - m)/2; return ((C*n) >> shift) & ((1 << m) - 1); }
```



```
We have extracted the middle m=10 bits—a number in 0, \ldots, 1023 const unsigned int C=581869333; // some number unsigned int hash_M( unsigned int n, unsigned int m ) { unsigned int shift = (32 - m)/2; return ((C*n) >>  shift) & ((1 << m) - 1); }
```

 $h_M(42) = 195$

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Outline

We have:

- Discussed techniques for hashing
- Discussed mapping down to a given range 0, ..., M-1

Now we must deal with collisions

- Numerous techniques exist
- Containers in general
 - Specifically linked lists

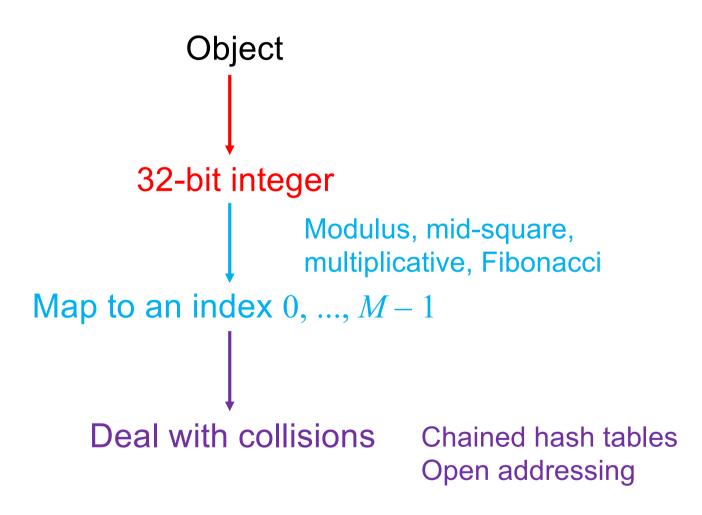
Hashing

First, a review:

- We want to store objects in an array of size M
- We want to quickly calculate the bin where we want to store the object
 - We came up with hash functions—hopefully $\Theta(1)$
 - Perfect hash functions (no collisions) are difficult to design

We will look at some schemes for dealing with collisions

The hash process



Chained hash table

Associating each bin with a linked list.

For any object assigned to the bin by the hash function, finding, inserting, and erasing the object is done on the linked list.

As an example, let's store hostnames and allow a fast look-up of the corresponding IP address

- We will choose the bin based on the host name
- Associated with the name will be the IP address
- *E.g.*, ("optimal", 129.97.94.57)

Suppose the hash value of a string is the last 3 bits of the first character in the host name

- The hash of "optimal" is based on "o"

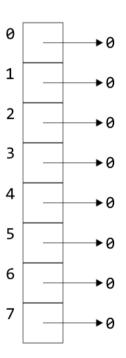
```
01100001
                        01101110
a
b
    01100010
                        01101111
    01100011
                        01110000
C
d
    01100100
                         01110001
    01100101
                        01110010
    01100110
                        01110011
    01100111
                        01110100
                    t
h
    01101000
                        01110101
                    u
    01101001
                         01110110
    01101010
                         01110111
                        01111000
    01101011
                    Χ
    01101100
                        01111001
    01101101
                         01111010
                    7
m
```

Our hash function is

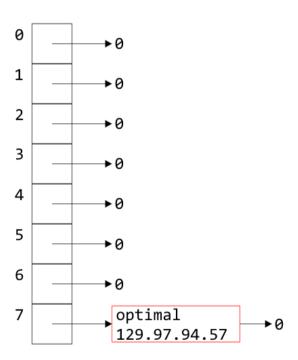
```
unsigned int hash( string const &str ) {
    // the empty string "" is hashed to 0
    if str.length() == 0 ) {
        return 0;
    }

    return str[0] & 7;
}
```

Starting with an array of 8 empty linked lists

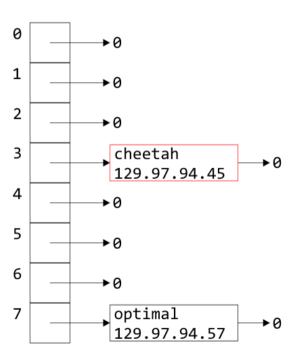


The pair ("optimal", 129.97.94.57) is entered into bin 01101111 = 7



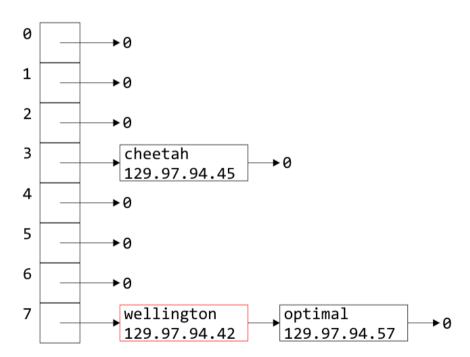
Similarly, as "c" hashes to 3

- The pair ("cheetah", 129.97.94.45) is entered into bin 3



The "w" in Wellington also hashes to 7

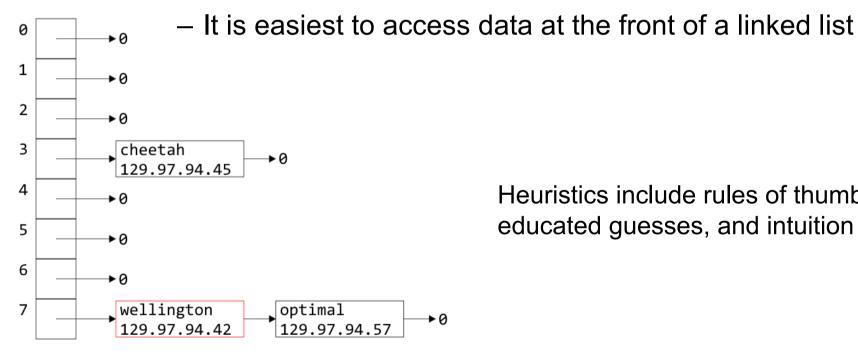
- ("wellington", 129.97.94.42) is entered into bin 7



Why did I use push front from the linked list?

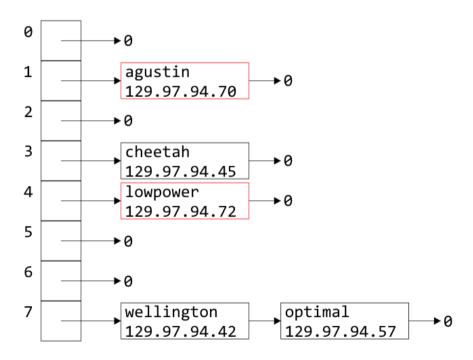
A good heuristic is

"unless you know otherwise, data which has been accessed recently will be accessed again in the near future"

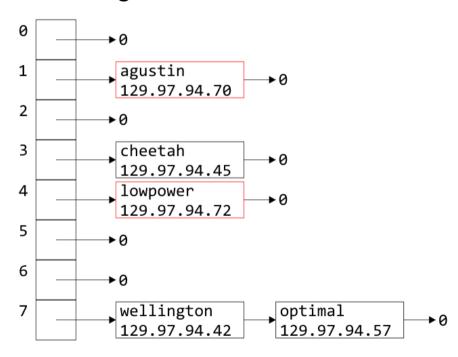


Heuristics include rules of thumb, educated guesses, and intuition

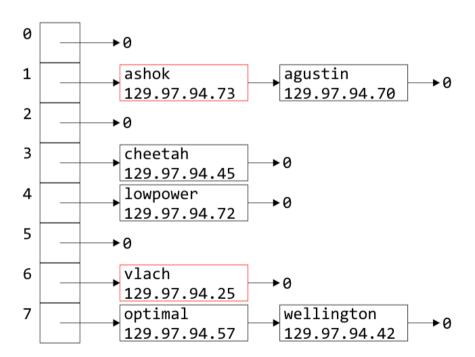
Similarly we can insert the host names "augustin" and "lowpower"



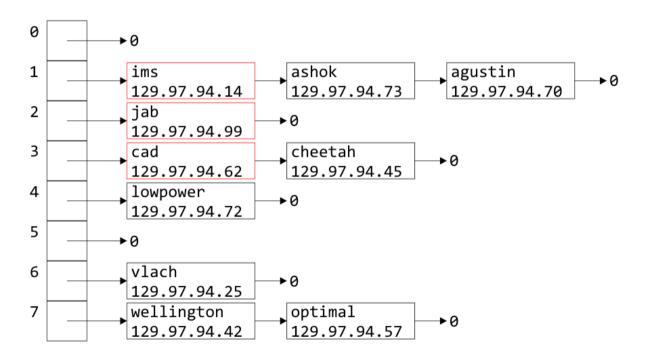
If we now wanted the IP address for "optimal", we would simply hash "optimal" to 7, walk through the linked list, and access 129.97.94.57 when we access the node containing the relevant string



Similarly, "ashok" and "vlach" are entered into bin 1 and 6

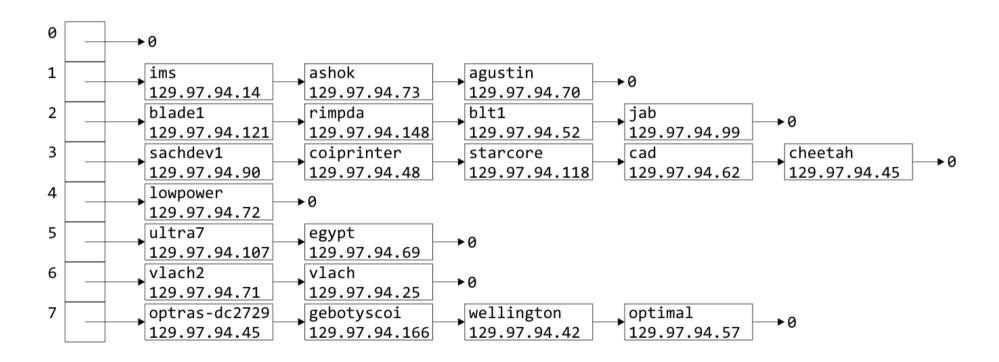


Inserting "ims", "jab", and "cad" doesn't even out the bins



Indeed, after 21 insertions, the linked lists are becoming rather long

- We were looking for $\Theta(1)$ access time, but accessing something in a linked list with k objects is O(k)



Load Factor

To describe the length of the linked lists, we define the *load factor* of the hash table:

$$\lambda = \frac{n}{M}$$

This is the average number of objects per bin

This assumes an even distribution

Right now, the load factor is $\lambda = 21/8 = 2.625$

The average bin has 2.625 objects

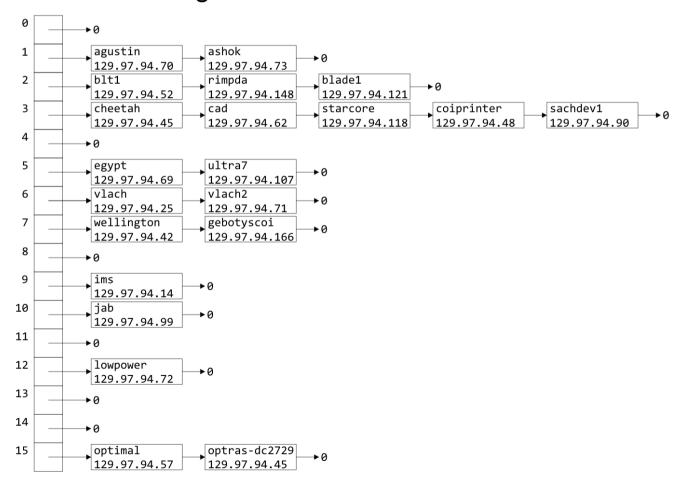
Load Factor

If the load factor becomes too large, access times will start to increase: $\mathbf{O}(\lambda)$

The most obvious solution is to double the size of the hash table and re-insert every object (*rehashing*)

Doubling Size

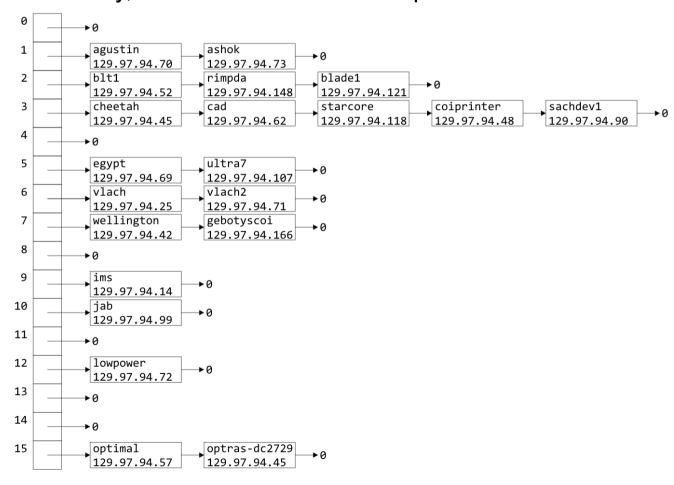
In our example, suppose we take the last four bits as the hash function after doubling the hash table size



Doubling Size

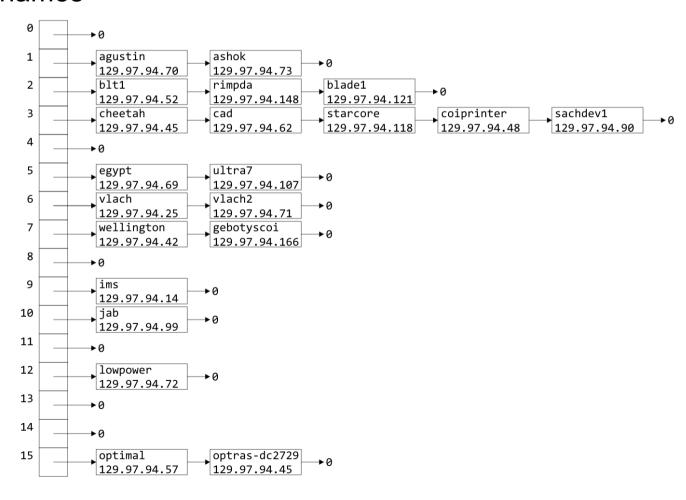
The load factor is now $\lambda = 1.3125$

Unfortunately, the distribution hasn't improved much



Doubling Size

There is significant *clustering* in bins 2 and 3 due to the choice of host names



We choose a very poor hash function:

We looked at the first letter of the host name

Unfortunately, all these are also actual host names:

ultra7 ultra8 ultra9 ultra10 ultra11 ultra12 ultra13 ultra14 ultra15 ultra16 ultra17 blade1 blade2 blade3 blade4 blade5

This will cause clustering in bins 2 and 5

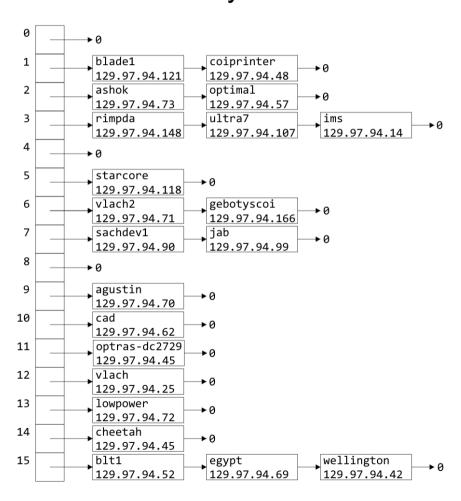
Let's go back to the hash function defined previously:

```
unsigned int hash( string const &str ) {
   unsigned int hash_value = 0;

for ( int k = 0; k < str.length(); ++k ) {
    hash_value = 12347*hash_value + str[k];
  }

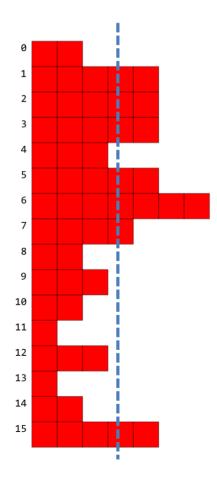
return hash_value;
}</pre>
```

This hash function yields a much nicer distribution:

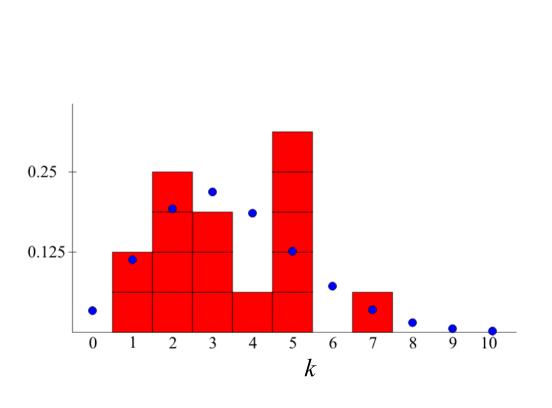


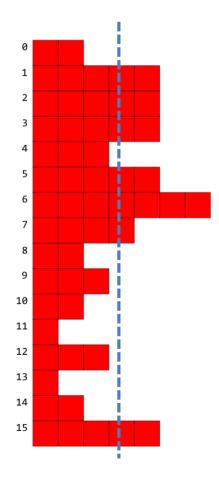
When we insert 55 names, we would have a load factor $\lambda = 3.4375$

- Clearly there are not exactly
 3.4375 objects per bin
- How can we tell if this is a good hash function?
- Can we expect exactly 3.4375 objects per bin?
 - · Clearly no...
- The answer is with statistics...



We would expect the number of bins which hold k objects to approximately follow a Poisson distribution





Problems with Linked Lists

One significant issue with chained hash tables using linked lists

- It requires extra memory
- It uses dynamic memory allocation

Another issue is the $O(\lambda)$ time complexity

For faster access, we could replace each linked list with an AVL tree (assuming we can order the objects)

- The access time drops to $O(\ln(\lambda))$
- The memory requirements are increased by $\Theta(n)$, as each node will require two pointers

Black Board Example

Use the hash function unsigned int hash(unsigned int n) { return n % 10; } to enter the following 15 numbers into a hash table with 10 bins:

534, 415, 465, 459, 869, 442, 840, 180, 450, 265, 23, 946, 657, 3, 29

Summary

The easiest way to deal with collisions is to associate each bin with a container

We looked at bins of linked lists

- The example used host names and IP addresses
- We defined the load factor $\lambda = n/M$
- Discussed doubling the number of bins
- Our goals are to choose a good hash function and to keep the load factor low
- We discussed alternatives

Next we will see a different technique using only one array of bins: open addressing

Outline

- Introduction
- Hash function
- Mapping down to 0, ..., M − 1
- Dealing with collisions
 - Chained hash tables
 - Open addressing

Background

Chained hash tables require special memory allocation

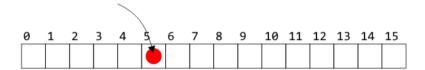
– Can we create a hash table without significant memory allocation?

We will deal with collisions by storing collisions elsewhere

We will define an implicit rule which tells us where to look next

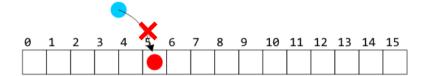
Suppose an object hashes to bin 5

If bin 5 is empty, we can copy the object into that entry



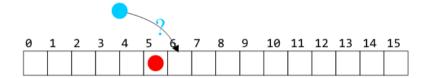
Suppose, however, another object hashes to bin 5

Without a linked list, we cannot store the object in that bin



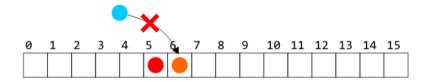
We need a rule to tells us where to look next

For example, look in the next bin to see if it is occupied

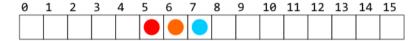


The rule must be:

- simple to follow—i.e., fast
- general enough to deal with the fact that the next cell could also be occupied: e.g., continue searching until the first empty bin is found

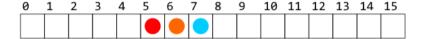


Of course, whatever rule we use in placing an object must also be used when searching for or removing objects



Recall, however, that our goal is $\Theta(1)$ access times

We cannot, on average, be forced to access too many bins



There are numerous strategies for defining the order in which the bins should be searched:

- Linear probing
- Quadratic probing
- Double hashing

There are many alternate strategies, as well:

- Last come, first served
 - Always place the object into the bin moving what may be there already
- Cuckoo hashing

Outline

- Introduction
- Hash function
- Mapping down to 0, ..., M − 1
- Dealing with collisions
 - Chained hash tables
 - Open addressing
 - Linear probing
 - Quadratic probing

Linear Probing

The easiest method to probe the bins of the hash table is to search forward linearly

Assume we are inserting into bin *k*:

- If bin k is empty, we occupy it
- Otherwise, check bin k + 1, k + 2, and so on, until an empty bin is found
 - If we reach the end of the array, we start at the front (bin 0)

Linear Probing

Consider a hash table with M = 16 bins

Given a 3-digit hexadecimal number:

- The least-significant digit is the primary hash function (bin)
- Example: for $72A_{16}$, the initial bin is A

Insertion

Insert these numbers into this initially empty hash table: 19A, 207, 3AD, 488, 5BA, 680, 74C, 826, 946, ACD, B32, C8B, DBE, E9C

0	1	2	3	4	5	6	7	8	9	Α	В	C	D	E	F

Start with the first four values:

19A, 207, 3AD, 488

0	1	2	3	4	5	6	7	8	9	Α	В	C	D	E	F

Start with the first four values:

19A, 207, 3AD, 488

0	1	2	3	4	5	6	7	8	9	Α	В	C	D	Ε	F	
							207	7 488	3	19/	1		3AE			

Next we must insert 5BA

0	1	2	3	4	5	6	7	8	9	Α	В	C	D	Ε	F
							20	7 48	ΧI	194	A		3AE		

Next we must insert 5BA

- Bin A is occupied
- We search forward for the next empty bin

0	1	2	3	4	5	6	7	8	9	A	В	C	D	E	F
							20	7 48	8	19	4 5B		3AD		

Next we are adding 680, 74C, 826

0	1	2	3	4	5	6	7	8	9	Α	В	C	D	E	F
							20	7 48	8	19A	5BA		3AD		

Next we are adding 680, 74C, 826

All the bins are empty—simply insert them

0	1	2	3	4	5	6	7	8	9	Α	В	C	D	E	F
680						826	207	488		19A	5BA	74C	3AD		

Next, we must insert 946

0		1	2	3	4	5	6	7	8	9	Α	В	C	D	E	F
6	80						826	207	488		19A	5BA	74C	3AD		

Next, we must insert 946

- Bin 6 is occupied
- The next empty bin is 9

0		1	2	3	4	5	6	7	8	9	Α	В	C	D	Е	F
6	580						826	207	488	946	19A	5BA	74C	3AD		

Next, we must insert ACD

0	1	2	3	4	5	6	7	8	9	Α	В	С	D	E	F
680						826	207	488	946	19A	5BA	74C	3AD		

Next, we must insert ACD

- Bin D is occupied
- The next empty bin is E

0	1	2	3	4	5	6	7	8	9	Α	В	C	D	E	F
68	0					826	207	488	946	19A	5BA	74C	3AD	ACD	

Next, we insert B32

0	1	2	3	4	5	6	7	8	9	Α	В	С	D	E	F
68	0					826	207	488	946	19A	5BA	74C	3AD	ACD	

Next, we insert B32

- Bin 2 is unoccupied

0	1	2	3	4	5	6	7	8	9	Α	В	С	D	E	F
680		B32				826	207	488	946	19A	5BA	74C	3AD	ACD	

Next, we insert C8B

0		1	2	3	4	5	6	7	8	9	Α	В	C	D	E	F
ϵ	580		B32				826	207	488	946	19A	5BA	74C	3AD	ACD	

Next, we insert C8B

- Bin B is occupied
- The next empty bin is F

0	1	2	3	4	5	6	7	8	9	Α	В	С	D	E	F
680		B32				826	207	488	946	19A	5BA	74C	3AD	ACD	C8B

Next, we insert D59

0	1	2	3	4	5	6	7	8	9	Α	В	С	D	E	F
680		B32				826	207	488	946	19A	5BA	74C	3AD	ACD	C8B

Next, we insert D59

- Bin 9 is occupied
- The next empty bin is 1

0	1	2	3	4	5	6	7	8	9	Α	В	C	D	E	F
680	D59	B32				826	207	488	946	19A	5BA	74C	3AD	ACD	C8B

Finally, insert E9C

0	1	2	3	4	5	6	7	8	9	Α	В	C	D	E	F
680	D59	B32				826	207	488	946	19A	5BA	74C	3AD	ACD	C8B

Finally, insert E9C

- Bin C is occupied
- The next empty bin is 3

0	1	2	3	4	5	6	7	8	9	Α	В	C	D	E	F
680	D59	B32	E9C			826	207	488	946	19A	5BA	74C	3AD	ACD	C8B

Having completed these insertions:

- The load factor is $\lambda = 14/16 = 0.875$
- The average number of probes is $38/14 \approx 2.71$

0	1	2	3	4	5	6	7	8	9	Α	В	С	D	E	F
680	D59	B32	E93			826	207	488	946	19A	5BA	74C	3AD	ACD	C8B

To double the capacity of the array, each value must be rehashed

- We use the least-significant five bits for the initial bin
- 680, B32, ACD, 5BA, 826, 207, 488, D59 may be immediately placed

0	1	2	3	4	5	6	7	8	9	Α	В	С	D	Ε	F	10	11	12	13	14	15	16	17	18	19	1A	1B	1C	1D	1E	1F
680						826	207	488					ACD)				B32							D59	5BA					

To double the capacity of the array, each value must be rehashed

19A resulted in a collision

0	1	2	3	4	5	6	7	8	9	Α	В	С	D	E	F	10	11	12	13	14	15	16	17	18	19	1A	1B	1C	1D	1E	1F	_
68	30					826	207	488					ACD)				B32	2						D59	5BA	194	\				

To double the capacity of the array, each value must be rehashed

- 946 resulted in a collision

0	1	1	2	3	4	5	6	7	8	9	Α	В	С	D	E	F	10	11	12	13	14	15	16	17	18	19	1A	1B	1C	1D	1E	1F	
6	80						826	207	488	946	5			ACD)				B32	2						D59	5BA	194					

To double the capacity of the array, each value must be rehashed

- 74C fits into its bin

0	1	2	3	4	5	6	7	8	9	Α	В	C	D	Ε	F	10	11	12	13	14	15	16	17	18	19	1A	1B	1C	1D	1E	1F
68	80					826	207	488	946			740	ACD				946	B32	2						D59	5BA	194				

To double the capacity of the array, each value must be rehashed

3AD resulted in a collision

0	1	1	2	3	4	5	6	7	8	9	Α	В	С	D	E	F	10	11	12	13	14	15	16	17	18	19	1A	1B	1C	1D	1E	1F	
6	80						826	207	488	946	5		740	ACE	3AE			946	B32							D59	5BA	194					

To double the capacity of the array, each value must be rehashed

- Both E9C and C8B fit without a collision
- The load factor is $\lambda = 14/32 = 0.4375$
- The average number of probes is $18/14 \approx 1.29$

0	1	2	3	4	5	6	7	8	9	Α	В	C	D	Е	F	10	11	12	13	14	15	16	17	18	19	1A	1B	1C	1D	1E	1F
680						826	207	488	946		C8B	74C	ACD	3AD			946	B32	2						D59	5BA	194	E9C			

Testing for membership is similar to insertions:

Start at the appropriate bin, and searching forward until

- 1. The item is found,
- 2. An empty bin is found, or
- 3. We have traversed the entire array

The third case will only occur if the hash table is full (load factor of 1)

Searching for C8B

0	1	2	3	4	5	6	7	8	9	Α	В	C	D	E	F
680	D59	B32	E93			826	207	488	946	19A	5BA	74C	3AD	ACD	C8B

Searching for C8B

- Examine bins B, C, D, E, F
- The value is found in F

0	1	2	3	4	5	6	7	8	9	Α	В	С	D	E	F
680	D59	B32	E93			826	207	488	946	19A	5BA	74C	3AD	ACD	C8B

Searching for 23E

0	1	2	3	4	5	6	7	8	9	Α	В	C	D	E	F
680	D59	B32	E93			826	207	488	946	19A	5BA	74C	3AD	ACD	C8B

Searching for 23E

- Search bins E, F, 0, 1, 2, 3, 4
- The last bin is empty; therefore, 23E is not in the table

0	1	2	3	4	5	6	7	8	9	Α	В	C	D	E	F
680	D59	B32	E93	×		826	207	488	946	19A	5BA	74C	3AD	ACD	C8B

Erasing

Can we simply remove elements from the hash table?

0	1	2	3	4	5	6	7	8	9	Α	В	C	D	E	F
680	D59	B32	E93			826	207	488	946	19A	5BA	74C	3AD	ACD	C8B

Erasing

We cannot simply remove elements from the hash table

For example, consider erasing 3AD

0	1	2	3	4	5	6	7	8	9	Α	В	С	D	E	F
680	D59	B32	E93			826	207	488	946	19A	5BA	74C	3AD	ACD	C8B

We cannot simply remove elements from the hash table

- For example, consider erasing 3AD
- If we just erase it, it is now an empty bin
 - By our algorithm, we cannot find ACD, C8B and D59

0	1	2	3	4	5	6	7	8	9	Α	В	С	D	Е	F
680	D59	B32	E93			826	207	488	946	19A	5BA	74C		ACD	C8B

Instead, we must attempt to fill the empty bin

0	1	2	3	4	5	6	7	8	9	Α	В	C	D	E	F
680	D59	B32	E93			826	207	488	946	19A	5BA	74C		ACD	C8B

Instead, we must attempt to fill the empty bin

- We can move ACD into the location
- Are we done?

0	1	2	3	4	5	6	7	8	9	Α	В	С	D	E	F
680	D59	B32	E93			826	207	488	946	19A	5BA	74C	ACB	ACD	C8B

Now we have another bin to fill

0	1	2	3	4	5	6	7	8	9	Α	В	C	D	E	F
680	D59	B32	E93			826	207	488	946	19A	5BA	74C	ACD		C8B

Now we have another bin to fill

We can move C8B into the location

0	1	2	3	4	5	6	7	8	9	Α	В	С	D	E	F
680	D59	B32	E93			826	207	488	946	19A	5BA	74C	ACD	C8B	€8B

Now we must attempt to fill the bin at F

- We cannot move 680

0	1	2	3	4	5	6	7	8	9	Α	В	С	D	E	F _	
680	D59	B32	E93			826	207	488	946	19A	5BA	74C	ACD	C8B		

Now we must attempt to fill the bin at F

- We cannot move 680
- We can, however, move D59

0	1	2	3	4	5	6	7	8	9	Α	В	С	D	E	F
680	D59	B32	E93			826	207	488	946	19A	5BA	74C	ACD	C8B	Ð 59

At this point, we cannot move B32 or E93 and the next bin is empty

We are finished

0	1	2	3	4	5	6	7	8	9	Α	В	С	D	E	F
680		B32	E93			826	207	488	946	19A	5BA	74C	ACD	C8B	D59

Suppose we delete 207

0	1	2	3	4	5	6	7	8	9	Α	В	C	D	E	F
680		B32	E93			826	207	488	946	19A	5BA	74C	ACD	C8B	D59

Suppose we delete 207

- Cannot move 488

0	1	2	3	4	5	6	7	8	9	Α	В	С	D	E	F
680		B32	E93			826		488	946	19A	5BA	74C	ACD	C8B	D59

Suppose we delete 207

We could move 946 into Bin 7

0	1	2	3	4	5	6	7	8	9	Α	В	С	D	E	F
680		B32	E93			826	946	488	946	19A	5BA	74C	ACD	C8B	D59

Suppose we delete 207

We cannot move any of the next five entries

0	1	2	3	4	5	6	7	8	9	Α	В	С	D	E	F
680		B32	E93			826	946	488		19A	5BA	74C	ACD	C8B	D59

Suppose we delete 207

We could move D59

0	1	2	3	4	5	6	7	8	9	Α	В	С	D	Е	F
680		B32	E93			826	946	488	D59	19A	5BA	74C	ACD	C8B	D59

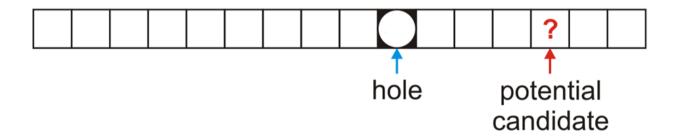
Suppose we delete 207

- We cannot fill this bin with 680, and the next bin is empty
- We are finished

0	1	2	3	4	5	6	7	8	9	Α	В	C	D	E	F_	
680		B32	E93			826	946	488	D59	19A	5BA	74C	ACD	C8B		

In general, assume:

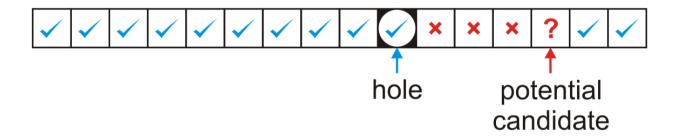
- The currently removed object has created a hole at index hole
- The object we are checking is located at the position index and has a hash value of hash



Remember: if we are checking the object? at location index, this
means that all entries between hole and index are both occupied and
could not have been copied into the hole

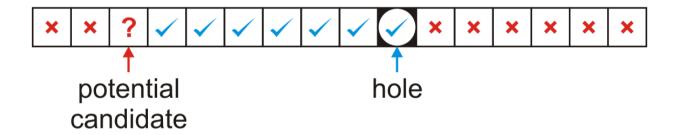
The first possibility is that hole < index

- In this case, we move the object at index only if its hash value is either
 - equal to or less than the hole or
 - greater than the index of the potential candidate



The other possibility is we wrapped around the end of the array, that is, hole > index

- In this case, we move the object at index only if its hash value is both
 - greater than the index of the potential candidate and
 - less than or equal to the hole



In either case, if the move is successful, the ? now becomes the new hole to be filled

Alternative Method: Lazy Erasing

Consider erasing 3AD

0	1	2	3	4	5	6	7	8	9	Α	В	С	D	E	F
680	D59	B32	E93			826	207	488	946	19A	5BA	74C	3AD	ACD	C8B

Alternative Method: Lazy Erasing

- Consider erasing 3AD
 - Mark the bin as ERASED
 - Searching: regard it as occupied
 - Insertion: regard it as unoccupied
 - What if we want to insert ACD?
 - Search before insertion

0	1	2	3	4	5	6	7	8	9	Α	В	С	D	E	F
680	D59	B32	E93			826	207	488	946	19A	5BA	74C	3AQ	ACD	C8B

Black Board Example

Using the last digit as our hash function—insert these nine numbers into a hash table of size M = 10

31, 15, 79, 55, 42, 99, 60, 80, 23

Then, remove 79, 31, 42, and 60, in that order

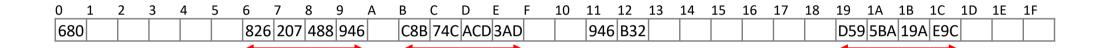
We have already observed the following phenomenon:

With more insertions, the contiguous regions (or *clusters*) get larger

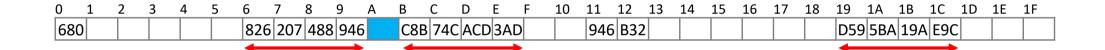
0	1	2	3	4	5	6	7	8	9	Α	В	С	D	E	F	10	11	12	13	14	15	16	17	18	19	1A	1B	1C	1D	1E	1F
680						826	207	488	946	5	C8B	74C	ACD	3AD			946	B32							D59	5BA	19A	E9C	,		

The length of these chains will affect the number of probes required to perform insertions, accesses, or removals

We currently have three clusters of length four

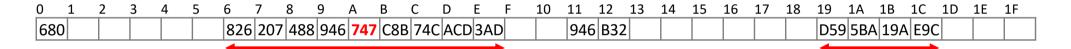


There is a $5/32 \approx 16$ % chance that an insertion will fill A

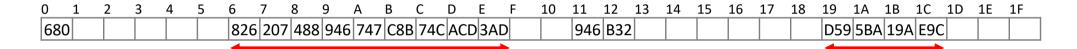


There is a $5/32 \approx 16$ % chance that an insertion will fill A

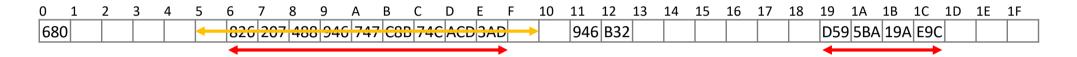
This causes two clusters to coalesce into one larger cluster of length 9



There is now a $11/32 \approx 34$ % chance that the next insertion will increase the length of this cluster



As the cluster length increases, the probability of further increasing the length increases



In general:

- Suppose that a cluster is of length ℓ
- An insertion either into any bin occupied by the chain or into the locations immediately before or after it will increase the length of the chain
- This gives a probability of $\frac{\ell+2}{M}$

It is possible to estimate the average number of probes for a successful search, where λ is the load factor:

$$\frac{1}{2}\left(1+\frac{1}{1-\lambda}\right)$$

For example: if $\lambda = 0.5$, we require 1.5 probes on average

Reference: Knuth, The Art of Computer Programming, Vol. 3, 2nd Ed., Addison Wesley, 1998, p.528.

The number of probes for an unsuccessful search or for an insertion is higher:

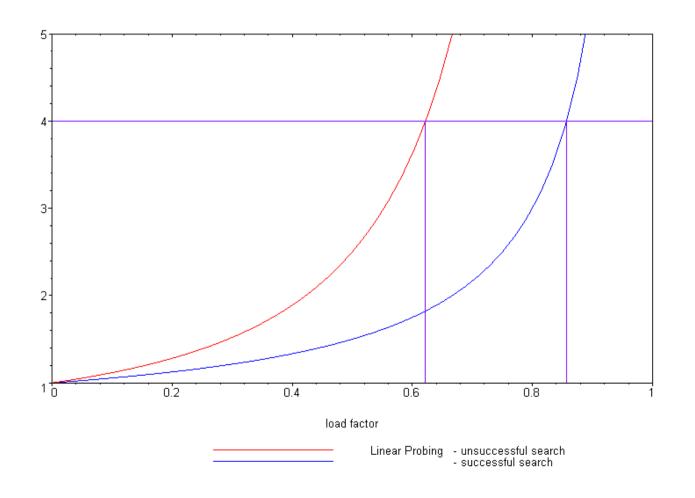
$$\frac{1}{2} \left(1 + \frac{1}{\left(1 - \lambda \right)^2} \right)$$

For $0 \le \lambda \le 1$, we have $(1 - \lambda)^2 \le 1 - \lambda$, and therefore the reciprocal will be larger

- if $\lambda = 0.5$ then we require 2.5 probes on average

Reference: Knuth, The Art of Computer Programming, Vol. 3, 2nd Ed., Addison Wesley, 1998, p.528.

The following plot shows how the number of required probes increases



Our goal was to keep all operations $\Theta(1)$ Unfortunately, as λ grows, so does the run time

One solution is to keep the load factor under a given bound If we choose $\lambda = 2/3$, then the number of probes for either a successful or unsuccessful search is 2 and 5, respectively

Therefore, we have three choices:

- Choose M large enough so that we will not pass this load factor
 - · This could waste memory
- Double the number of bins if the chosen load factor is reached
- Choose a different strategy than linear probing
 - Two possibilities are quadratic probing and double hashing

Summary

This topic introduced linear problem

- Continue looking forward until an empty cell is found
- Searching follows the same rule
- Removing an object is more difficult
- Primary clustering is an issue
- Keep the load factor $\lambda \leq 2/3$

Outline

- Introduction
- Hash function
- Mapping down to 0, ..., M − 1
- Dealing with collisions
 - Chained hash tables
 - Open addressing
 - Linear probing
 - Quadratic probing

Outline

This topic covers quadratic probing

- Similar to linear probing
 - Does not step forward one step at a time
- Primary clustering no longer occurs
- Affected by secondary clustering

Background

Linear probing:

- Look at bins k, k + 1, k + 2, k + 3, k + 4, ...
- Primary clustering

Background

Linear probing causes primary clustering

All entries follow the same search pattern for bins:

```
int initial = hash_M( x.hash(), M );
for ( int k = 0; k < M; ++k ) {
    bin = (initial + k) % M;
    // ...
}</pre>
```



Description

Quadratic probing suggests moving forward by different amounts

```
For example,
    int initial = hash_M( x.hash(), M );

for ( int k = 0; k < M; ++k ) {
    bin = (initial + k*k) % M;
}</pre>
```

Description

Problem:

- Will initial + k*k step through all of the bins?
- Here, the array size is 10:

```
M = 10;
initial = 5

for ( int k = 0; k <= M; ++k ) {
    std::cout << (initial + k*k) % M << ' ';
}</pre>
```

The output is

```
5 6 9 4 1 0 1 4 9 6 5
```

Description

Problem:

- Will initial + k*k step through all of the bins?
- Now the array size is 12:

```
M = 12;
initial = 5

for ( int k = 0; k <= M; ++k ) {
    std::cout << (initial + k*k) % M << ' ';
}</pre>
```

The output is now

```
5 6 9 2 9 6 5 6 9 2 9 6 5
```

Making M Prime

If we make the table size M=p a prime number, quadratic probing is guaranteed to iterates through $\left\lceil \frac{p}{2} \right\rceil$ entries

Problems:

- All operations must be done using %
 - Cannot use &, <<, or >>
 - The modulus operator % is relatively slow
- Doubling the number of bins is difficult:
 - What is the next prime after 2×263 ?

Generalization

More generally, we could consider an approach like:

```
int initial = hash_M( x.hash(), M );
for ( int k = 0; k < M; ++k ) {
   bin = (initial + c1*k + c2*k*k) % M;
}</pre>
```

Using $M = 2^m$

If we ensure $M = 2^m$ then choose

$$c_1 = c_2 = \frac{1}{2}$$

```
int initial = hash_M( x.hash(), M );
for ( int k = 0; k < M; ++k ) {
    bin = (initial + (k + k*k)/2) % M;
}</pre>
```

- Note that k + k*k is always even
- The growth is still $\Theta(k^2)$
- This guarantees that all M entries are visited before the pattern repeats
 - · This only works for powers of two

Using $M = 2^m$

For example:

– Use an array size of 16:

```
M = 16;
initial = 5

for ( int k = 0; k <= M; ++k ) {
    std::cout << (initial + (k + k*k)/2) % M << ' ';
}</pre>
```

The output is now

5 6 8 11 15 4 10 1 9 2 12 7 3 0 14 13 13

Using $M = 2^m$

There is an even easier means of calculating this approach

```
int bin = hash_M( x.hash(), M );
for ( int k = 0; k < M; ++k ) {
   bin = (bin + k) % M;
}</pre>
```

- Recall that $\frac{k^2 + k}{2} = \sum_{j=0}^{k} j$, so just keep adding the next highest value

Consider a hash table with M = 16 bins

Given a 2-digit hexadecimal number:

- The least-significant digit is the primary hash function (bin)
- Example: for 7A₁₆, the initial bin is A

Insert these numbers into this initially empty hash table 9A, 07, AD, 88, BA, 80, 4C, 26, 46, C9, 32, 7A, BF, 9C

0	1	2	3	4	5	6	7	8	9	Α	В	C	D	Ε	F

Start with the first four values:

9A, 07, AD, 88

0	1	2	3	4	5	6	7	8	9	Α	В	C	D	E	F

Start with the first four values:

9A, 07, AD, 88

0	1	2	3	4	5	6	7	8	9	Α	В	C	D	E	F
							07	88		9A			AD		

Next we must insert BA

0	1	2	3	4	5	6	7	8	9	Α	В	C	D	E	F
							07	88		9A			AD		

Next we must insert BA

The next bin is empty

0	1	2	3	4	5	6	7	8	9	Α	В	С	D	Е	F
							07	88		9A	ВА		AD		

Next we are adding 80, 4C, 26

0	1	L	2	3	4	5	6	7	8	9	Α	В	C	D	E	F
								07	88		9A	ВА		AD		

Next we are adding 80, 4C, 26

All the bins are empty—simply insert them

0	1	2	3	4	5	6	7	8	9	Α	В	С	D	E	F
80						26	07	88		9A	ВА	4C	AD		

Next, we must insert 46

0	1	2	3	4	5	6	7	8	9	Α	В	С	D	E	F
80						26	07	88		9A	ВА	4C	AD		

Next, we must insert 46

- Bin 6 is occupied
- Bin 6 + 1 = 7 is occupied
- Bin 7 + 2 = 9 is empty

()	1	2	3	4	5	6	7	8	9	Α	В	С	D	E	F
	80						26	07	88	46	9A	ВА	4C	AD		

Next, we must insert C9

0	1	2	3	4	5	6	7	8	9	Α	В	C	D	E	F
80						26	07	88	46	9A	ВА	4C	AD		

Next, we must insert C9

- Bin 9 is occupied
- Bin 9 + 1 = A is occupied
- Bin A + 2 = C is occupied
- Bin C + 3 = F is empty

0	1	2	3	4	5	6	7	8	9	Α	В	C	D	E	F
80						26	07	88	46	9A	ВА	4C	AD		C9

Next, we insert 32

- Bin 2 is unoccupied

0	1	2	3	4	5	6	7	8	9	Α	В	С	D	Е	F
80		32				26	07	88	46	9A	ВА	4C	AD		C9

Next, we insert 7A

- Bin A is occupied
- Bins A + 1 = B, B + 2 = D and D + 3 = 0 are occupied
- Bin 0 + 4 = 4 is empty

0	1	2	3	4	5	6	7	8	9	A	В	С	D	E	F
80		32		7A		26	07	88	46	9A	ВА	4C	AD		C9

Next, we insert BF

- Bin F is occupied
- Bins $\mathbf{F} + \mathbf{1} = \mathbf{0}$ and $\mathbf{0} + \mathbf{2} = \mathbf{2}$ are occupied
- Bin 2 + 3 = 5 is empty

0	1	2	3	4	5	6	7	8	9	A	В	C	D	E	F
80		32		7A	BF	26	07	88	46	9A	ВА	4C	AD		C9

Finally, we insert 9C

- Bin C is occupied
- Bins C + 1 = D, D + 2 = F, F + 3 = 2, 2 + 4 = 6 and 6 + 5 = B are occupied
- Bin $\mathbf{B} + \mathbf{6} = \mathbf{1}$ is empty

0	1	2	3	4	5	6	7	8	9	Α	В	C	D	E	F
80	9C	32		7A	BF	26	07	88	46	9A	ВА	4C	AD		C9

Having completed these insertions:

- The load factor is $\lambda = 14/16 = 0.875$
- The average number of probes is $32/14 \approx 2.29$

0	1	2	3	4	5	6	7	8	9	Α	В	С	D	E	F
80	9C	32		7A	BF	26	07	88	46	9A	ВА	4C	AD		C9

Erase

Can we erase an object like we did with linear probing?

- Consider erasing 9A from this table
- There are M-1 possible locations where an object which could have occupied a position could be located

0	1	2	3	4	5	6	7	8	9	Α	В	С	D	E	F
80	21		43			76				9A					50

Instead, we use lazy erasing

 Mark a bin as ERASED; however, when searching, treat the bin as occupied and continue

Erase

If we erase AD, we must mark that bin as erased

0	1	2	3	4	5	6	7	8	9	Α	В	С	D	E	F
80	9C	32		7A	BF	26	07	88	46	9A	ВА	4C	AB		C9

Find

When searching, it is necessary to skip over this bin

For example, find AD: D, E

find 5C: C, D, F, 2, 6, B, 1, 8, 0, 9, 3

0	1	2	3	4	5	6	7	8	9	Α	В	С	D	E	F
80	9C	32		7A	BF	26	07	88	46	9A	ВА	4C	AB		C9

Modified insertion

We must modify insert, as we may place new items into either

- Unoccupied bins
- Erased bins

Implementation

```
Storing three states can be achieved using an enumerated type:
    enum bin_state_t {
         UNOCCUPIED,
         OCCUPIED,
         ERASED
     };
Now we can declare and initialize arrays:
    bin_state_t state[M];
    for ( int i = 0; i < M; ++i ) {
         state[i] = UNOCCUPIED;
```

Multiple insertions and erases

One problem which may occur after multiple insertions and removals is that numerous bins may be marked as ERASED

In calculating the load factor, an ERASED bin is equivalent to an OCCUPIED bin

This will increase our run times...

If the load factor λ grows too large, we have two choices:

- If the load factor due to occupied bins is too large, double the table size
- Otherwise, rehash all of the objects currently in the hash table

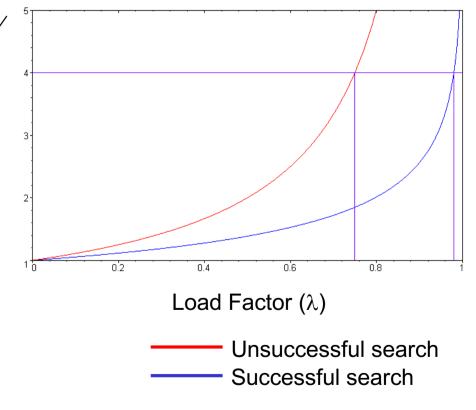
Expected number of probes

It is possible to calculate the expected number of probes for quadratic probing, again, based on the load factor:

- Successful searches: $\ln \left(\frac{1}{1-\lambda} \right)_{\lambda}$ - Unsuccessful searches: $\frac{1}{1-\lambda}$

When $\lambda = 2/3$, we requires 1.65 and 3 probes, respectively

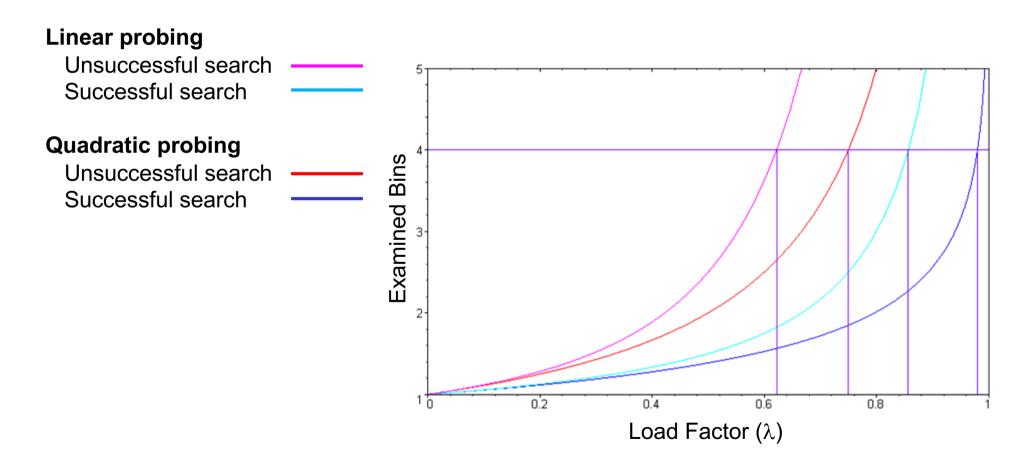
 Linear probing required 3 and 5 probes, respectively



Reference: Knuth, The Art of Computer Programming, Vol. 3, 2nd Ed., 1998, Addison Wesley, p. 530.

Quadratic probing versus linear probing

Comparing the two:



Secondary clustering

Weakness with quadratic problem

- Clustering may still occur: objects placed in the same bin will follow the same sequence
- Less severe than linear probing

Summary

In this topic, we have looked at quadratic probing:

- An open addressing technique
- Steps forward by a quadratically growing steps
- Insertions and searching are straight forward
- Removing objects is more complicated: use lazy deletion
- Still subject to secondary probing

Summary

