```
depth clustering::Identifiable
       kld
    # UniqueIdCounter
    + Identifiable()
    + ~Identifiable()
    + id()
    + guess_class_name()
    + get_current_id_counter()
    # DemangleName()
                   depth_clustering::Abstract
                     Sender< ObjSendType >
                   # clients
                   #_type
                   + AbstractSender()
                   + ~AbstractSender()
                   + type()
                   + AddClient()
                   + RemoveClient()
                   + RemoveClient()
                   + client_count()
                   + ShareDataWithAllClients()
                         < Cloud >
 depth_clustering::Abstract
       Sender< Cloud >
   clients
 #_type
 + AbstractSender()
 + ~AbstractSender()
 + type()
 + AddClient()
 + RemoveClient()
 + RemoveClient()
 + client_count()
 + ShareDataWithAllClients()
              Δ
depth_clustering::CloudOdom
        RosSubscriber
#_node_handle
#_subscriber_clouds
#_subscriber_odom
#_sync
#_topic_clouds
#_topic_odom
#_params
# _msg_queue_size
+ CloudOdomRosSubscriber()
+ ~CloudOdomRosSubscriber()
+ Callback()
+ CallbackVelodyne()
+ StartListeningToRos()
# RosOdomToPose()
```

# RosCloudToCloud()