PHIL 3something - Logic II

Scott Saunders - 10163541

Winter 2016

Misc. Notation

- The set of positive integers $\{x : x \text{ is a positive integer }\}$
- The set of positive integers less than $\{x: x \text{ is a positive integer and } x \text{ is less than } 3\}$. = $\{1, 2\}$.
- The empty set: \emptyset or Δ
- Member of: $A \subseteq B$ iff $\forall X (x \in A \implies x \in B)$
- Union of A and B: $A \cup B$ iff $\{x : x \in A \lor x \in B\}$
- Intersection of A and B: $A \cap B$ iff $\{x : x \in A \land x \in B\}$
- Difference of A and B: $\{x : x \in A \land x \notin B\}$
- For any non-empty sets A, B: Cartesian product: A of B: $A \times B$: $\{ \langle x, y \rangle : x \in A \land y \in B \}$ (ALL OF THE POSSIBILITIES)
- TOTAL FUNCTION: Every element in the domain is valid
- PARTIAL FUNCTION: Not every element in the domain is valid.
- for any set of sets A:

$$- \ \, \cup A = \{x : \exists y (y \in A \land x \in y)\}$$
$$- \ \, \cap A = \{x : \forall y (y \in A \rightarrow x \in y)\}$$

- Relations: R is
 - reflexive : $\forall x R x x$
 - symmetric : $\forall x \forall y (Rxy \implies Ryx)$
 - transitive : $\forall x \forall y \forall z ((Rxy \land Ryz) \implies Rxz)$
 - Euclidean : $\forall x \forall y \forall z ((Rxy \land Rxz) \implies Ryz)$
 - a equivalence relation : it's symmetric, reflexive, transitive.
 - a equivalence relation (alt): it's symmetric, and euclidean.
 - a (partial) function: $\exists x$ and there is at most one y: Rxy: denoted f
 - a (partial) function¹: $\exists x, \exists y | Rxy$: denoted f.
 - a (total) function: assigns a value to each number of A: denoted f
 - a (total) function²: $\forall x, \exists y | Rxy$: denoted f.
- Domain: The set of a functions arguments.
- Range: The set of its values. (Results)

- f is a function from a set A iff the domain of f is included in A
- f is a function to a set B iff its range is included in B.
- f^{-1} is the inverse of the function f from the set A to the set B iff:if for every member $b \in B$, there is exactly one member of $a \in A$ such that f(a) = b, then $f^{-1}(b) = a$, otherwise $f^{-1}(b)$ is undefined.
- f is onto B iff B is the range of f (Surjective) Alt: (Wikipedia) : $\forall y \in Y, \exists x \in X | y = f(x)$
- f is one-to-one iff $\forall x \forall y (f(x) = f(y) \implies x = y)$ (Injective)
- f is a bijection iff f is onto and one-to-one.
- \bullet f is a correspondence iff f is total, one-to-one and onto.
- Sets A and B are equinumerous iff there is a correspondence from A to B.

Equinumerous is transitive. Prove: if A is equinumerous with B and B is equinumerous wit C, then A is equinumerous with C. Proof: Suppose A is equinumerous to B, and B is equinumerous to C. Then: There is a total, one-to-one function f from A onto B, and a total one-to-one function g from B to C. Prove equinumerous via h=g(f), such that h(n)=g(f(n))

- h is total: Let a be a member of A. h(a) = g(f(a)). Since f is total there is a member of b of B such that f(a) = b). since g is total, there is a member of $c \in C$ such that g(b) = c. Hence, h is total.
- h is onto C. WLOG Let c be a member of C, as g is onto, $\exists b \in B$ such that g(b) = c. As f is onto, then $\exists a \in A$ such that f(a) = b. Hence, the composition of h = f(g) is onto C.
- h is one-to-one: Suppose h is not one-to-one. Then there $\exists a_1, a_2 \in A$ such that $h(a_1) = h(a_2), a_1 \neq a_2$. Giving $g(f(a_1)) = g(f(a_2)), a_1/not = a_2$ Since g is one-to-one $g(b_1) = g(b_2)$ iff $b_1 = b_2$. So the issue must lie in f. However f is one-to-one $f(a_1) = f(a_2)$ iff f(a) = f(b). Which is a contradiction, giving us that h is one-to-one.

 A^n : the *n*th Cartesian product of A with itself.

Suppose that the set of real Numbers r, r < r < 1, is enumerable. Then $L_r : r_1, r_2, r_3...$ written in a notation of $0.n_1n_2n_3.(nbeing natural numbers)$

The set of functions form the set of positive integers to positive integers is not enumerable.

Proof. Suppose S is enumerable.

Then there is a list L_s of the members of S.

$$L_s = \{s_1, s_2, s_3, \cdots\}$$

Let $\forall n \in \mathbb{N}, n \in k \iff n \notin S_n$

k is a set of positive integers.

so There is a number j such that $k = s_i$. So $j \in S_i \iff j / nS_i$

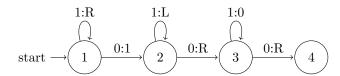
Hence S is not enumerable.

The set of total nomadic functions from the set of positive integers, F^1 , is not enumerable. It's a Proof by contradiction.

Turing machines are in the following form: $q_n, S_{1/0}, S_{1/0}/R/L, q_m$ where q_n is our current state, and you see $S_{1/0}$, perform function $S_{1/0}/R/$ and move to state q_m . If there is no operation specified on the current state for a scan, then it halts. (Also Called the Turing Alphabet)

ex: (These are the same)

 $Q_1S_1RQ_1, Q_1S_0S_1Q_2, Q_2S_1LQ_2, Q_2S_0RQ_3, Q_3S_1S_0Q_3, Q_3S_0RQ_4$



Remark (Turing Machines). • Each Turing machine is a finite set of Turing instructions.

- Each instruction is a 4 letter word of the Turing Alphabet.
- The set of Turing machine is enumerable. (Proof: exercise)

Definition (Standard inital configuration). A Turing machine is in a standard Initial configuration \iff

- for some positive integer k, there are k blocks of 1's on the tape.
- separated by a blank,
- and the rest of the tape is blank.
- the machine is scanning the left-most 1 on the tape.
- the machine is in it's lowest numbered state.

ex: $\cdots 0010110111000 \cdots$ is a SIC. (if it's in lowest state) ex: $\cdots 00010000 \cdots$ is a SIC.

Definition (Standard final configuration). A Turing machine is in a standard final configuration \iff

- there is a single block of k 1's
- and the rest of the tape is blank.
- the machine is scanning the left-most 1 on the tape.

ex: $\cdots 001111111000 \cdots$ is a SIC. (if it's in lowest state) ex: $\cdots 00010000 \cdots$ is a SIC.

Definition (Computes a one-place function f^1). A Turing M computes a one-place function f^1 : if M is started in a SIC with a single block of k 1's and

- if f^1 is defined for the argument k, then M eventually halts in a SFC
- or if f^1 is not defined for the argument k, then either M never halts or it halts in a non-standard final configuration.

Remark. Every Turing machine computes exactly one function of two arguments.

Remark. For any n, each Turing Machine computes exactly one function of n arguments. The set of one-place Turing computable functions is enumerable

The set of Turing computable functions is enumerable.

Definition (The halting problem). The problem of finding an effective method to determine whether a Turing macine will eventually ahlt or not after it is started with some input.

The halting problem is unsolvable. Ex: $L_M: M_1, \ldots$

h(m,n) =

1 if M_m eventually ahlts after starting with input n

2 if M_m never halts after starting with input n

The halting problem is solvable iff h is computable. Show: h is not Turing computable.

Let C be a copying machine.

Let F be $\frac{1}{2}$ flipper.

Suppose h is Turing Computable.

Let H be a Turing machine that computes h.

If h is a Turing computable, then H exists.

If H exists, then D(C - H - F) exists.

Let $D = M_k$, for some k. $M_k \in L_M$.

Start D with input k. The C-part of D will produce a copy of k, Then the H-part will do its job:

- If M_k will eventually halt after starting with input k, then H will produce output 1.
- If M_k will never halt after starting with input k, then H will produce output 2.

Then the F-part will do it's job.

- If output from H is 1, F will never halt.
- If output from H is 2, F will eventually halt.

Giving us:

- If M_k will eventually halt after starting with input k, then D will never halt attr starting with input k.
- If M_k will never halt atter starting with input k, then D will eventually halt after starting with input k.

So M_k will halt, after starting with input k, \iff D will nver halt after starting with input k. Then M_k isn't identical with D, which is a contradiction! Hence D doesn't exist. So H does not exists. So h is not turing computable.

Another halting problem..? $L_M: M_1, \cdots L_F: F_1, \cdots$

g(n) = 1, if $f_n(n) = 2$

g(n) = 2, otherwise.

 $g \neq f_k \forall k$

h(m,n) = 1if M_m eventual halfs after starting with input n.

h(m,n)=2 if M_m never halts after starting with input n.

s(m) = 1, if M_m eventually halts after starting with input m.

s(m) = 2, if M_m never halts after starting with input m.

- 1. The halting problem is solvable iff h is computable.
- 2. If h is computable, then s is computable.
- 3. If s is computable, and TT's is true, then g is computable.
- 4. g is not Turing computable.
- 5. Turing Thesis is true (Whatever is not Turing Computable is not computable)

- 6. The halting problem is not solvable.
- 3. Suppose S is computable and TT is true.

Then: There is a Turing machine S* that computes s.

Suppose that we are to calculate g(n), for some n.

Start S* with input n.

• Case 1: S* eventually halts with output 1

We know that M_n will eventually ahlt after it is started with input n Start M_n with input n, when it halts, inspect the tape.

- Case 1.1: Halted in SFC $f_n(n) = 2$ g(n) = 1
- Case 1.2: Halted in non-SFC: f_n is undefined. $f_n(n) \neq 2$

And then Blake broke it:

As it's a halting problem to figure out if it's in SFC?

g(n) = 2

• Case 2: S* eventually halts with output 2 We know that M_n will never halt after it is started with input n.

So we know that f_n is undefined for the argument n.

So we know that g(n) = 2

0.1 Sentental logic

Some symbols n things:

- (
-)
- Successor : '
- Not: -
- And: \(\triangle \text{(Conjunction)}\)
- Or: \vee (Disjunction)
- Exists: ∃
- Forall: \forall
- Variables: v_1, v_2, v_3, \ldots
- Equality: =

$$A_1^1$$
 A_2^1 ...

• Constant names: a_1, \ldots

• Functions:
$$f_1^1 f_2^1 \dots$$
• Functions:
$$\vdots \vdots \ddots$$

$$f_1^n f_2^n \dots$$

Definition (Term). • Every variable is a(n atomic) (open) term.

- Every constant is a(n atomic) (closed) term.
- If t_1, \ldots, t_n are terms, then $f^n(t_1, \ldots, t_n)$ is a term.
- Nothing else is a term.

Definition (Formula). • $A^n(t_1, ..., t_n)$ is a formula where A^n is an n-place predicate and t_i are terms. (This is an atomic formula).

- If F is a formula then -F is a formula
- If F and G are formulas then $(F \wedge G)$ is a formula.
- If F and G are formulas then $F(\vee G)$ is a formula.
- If F is a formula, then $\exists vF$ is a formula.
- If F is a formula then $\forall vF$ is a formula.
- NOTHING ELSE IS A FORMULA.

Definition (Bound). An occurrence of variable x is bound if it is part of a subformula beginning $\forall x$ or $\exists x$, in which case the quantifier \forall or \exists in question is said to bind that occurrence of the variable x, and otherwise the occurrence of the variable x is free.

Ex: $Fx \to \forall xFx$: The first x is free, and the second is bound.

Ex: $x < y \land -\exists z (x < z \land z < y)$: all occurrences of x and y are free, and all the occurrences of z are bound.

Remark. When we write something like "Let F(x) be a formula", we are to be understood as meaning "Let F be a formula in which no variables occur free except x".

Definition (Instance). An *instance* of a formula F(x) is any formula of the form F(t) for t a closed term. Simmilar notations apply where there is more than one free variale, and to terms as well as formulas.

Definition (Sentence). a formula is a sentence if no occurrence of any variable in it is free.

Definition (Model). A model M (interpretation) of a language L is $\{|M|v\}$ Where |M| is a non-empty set and v is a valuation function that assigns values (extensions/denotations) to the mebers of L in such a way that

- $\forall v(a) \in |M|$
- $v(A^n) \subseteq \text{the } n\text{th caresian product of } |M| \text{ with itself: } |M| \times \dots |M|.$
- $v(f^n)$ is a total function from $|M| \times \dots |M|$ to |M|.

Definition (Truth). • $M \models F^n(t_1, \ldots, t_n)$ iff $\langle M(t_1), \ldots, M(t_n) \rangle \in M(F^n)$.

- $M \vDash -SiffM \neq S$.
- $M \vDash (K \land L)iffM \vDash KandM \vDash L$
- $M \models \forall x F$
- $M \models \exists x F(c) iff$ there is an object $o \in |M|$ and given a name c (that is not interpreted by M), $M \models F(c)$

Definition. of the denoteizan/extension of a closed term in a model M. If T is a name M(t) = v(t) If t is $f^n(t_1, \ldots, t_n)$ then

$$M(f^n(t_1,\ldots,t_n)\ M(f^n)(M(t_1),\ldots,M(t_n)).$$

Validy = Satisfiability = Implication.

Misc-crap:

• $A \models B$ is $-(A \land -B)$

Lemma 1. Extensionality Lemma

- Let M be a model of a language L.
- Let S be a sentence of L.
- Let L^+ be an extension of L. $L \subseteq L^+$
- Let M^+ be a model of L^+
- So: M^+ is an extension of M.
- $M \vDash S$ iff $M^+ \vDash S$

Example:

If $A \vDash B$ and $B \vDash C$, then $A \vdash C$. Suppose $A \vDash B$, and $B \vDash C$.

In every interpretation of A and B in which A is true, B is true, In every interpretation of B and C in which B is true, C is true. Shows: In every interpretation of A and C in which A is true, C is true. Let M be an interpretation of A and C such that $M \models A$.

- Case 1: M is an interpretation of B. Then $M \vDash B$ So $M \vDash C$.
- M is not an interpretation of B.

Then there is an extension M^+ that interprets B as well as A and C.

so: $M^+ \models B$

So: $M^+ \models C$

So $M \vdash C$ (By the ext, llemma)

Lemma 2 (Undecibality). If the decision problem (for implication) is solvable, then the halting problem is solvable. There is an effective methoid for specifing for any Turing machine M and any input N a finite set of setences Δ and a sentence H such that $\Delta \vDash H$ iff M eventually halts after starting with input n. $\Delta \vDash H$ iff M eventually alts after start with input n.

Define the one place predicate Q_{ij} as: At time j, M is in state i. Define the two place predicate @js as At time j, M, is scanning square s. Define the two place predicate Mjs as: At time j, square s is marked with a 1.

A description D for a start state could then be: $D: [Q_10 \wedge @_{0,0} \wedge M_{0,0} \wedge M_{0,1} \wedge M_{0,2} \wedge \forall y ((y \neq 0 \wedge y \neq 1 \wedge y \neq 2) \implies -M_{0,y}]$ Time = 0, [...01110...] Square #, [...-10123...]

For each instruction of a TM, we may write the instruction as a setence:

 $Q_{i1}S_1RQ_{i2}$: Move right seeing 1 in state:

$$\forall x \forall t ((Q_{i,1} \land @_{t,x} \land M_{t,x}) \implies (Q_{i,t+1} \land @_{t,t+1}) \land \forall y ((M_{t,y} \implies M_{t,t+1}), \forall x \land (-M_{t,y} \implies -M_{t,t+1}))$$

Misc-crap that's on the board for some reason:

$$\begin{array}{lll} \Delta & & \\ \mathbb{Q}^1_2: & & \forall x \forall y \forall z ((Sxy \wedge Sxz) \implies y=z) \\ \mathbb{Q}^2: & & \forall x \forall y \forall z ((Sxz \wedge Syz) \implies x=y) \\ M^2: & & \forall x \forall y \forall z ((Sxy \implies x < y) \\ 0: & & \forall x \forall y \forall z ((x < y \wedge y < z) \implies x < z) \\ S^2: & & -\exists x, x < x+1 \\ <^2: & \text{lessthan} \end{array}$$

Some thingelse now too:

$$\forall x \forall t ((Q_1 t \land @tx \land Mtx) \implies \exists u (s_1(t, u) \land Q_2(u) \land @(u, v)) \land \forall y ((M(t, y) \implies M(u, y)) \land (-M(t, y) \implies -M(u, y)))))$$

$$\exists x \exists t (Q_m t \land @tx \land Mtx)$$

Proof. Something about biconditional:

 $\Delta \vDash H$ iff M halts after starting with input n.

- 1. if $\Delta \vDash H$, then M halts.
- 2. if M halts, then $\Delta \vDash H$.
- 1. if $\Delta \vDash H$, then M halts Proof.

Suppuse $\Delta \vDash H$

All members of Δ are true in the standard interpretation I. H is true in I. So: M halts.

2. if M halts, then $\Delta \vDash H$ - Proof.

Suppose M halts. (Show $\Delta \vDash H$).

There is a time t M halts at t.

There is a state q_i , M halts at t in state q_i .

There is a square x, M halts at t in state q_i , scanning square x which is Marked / — Makred

1: $Q_i(t) \wedge @(t,x) \wedge M(t,x)$.

1 is a cojunct of the description of time t, $\mathbb{D}(t)$

 $\mathbb{D}(t) \vDash (i)$

2: $\exists x \exists t (Q_1(t) \land @(t,x) \land (t,x)).$

- $(i) \vDash (ii).$
- (ii) is disjunct of H.
- $(ii) \vDash H$.

So: $\mathbb{D}(t) \models H$.

 Δ implies a description of everytime before which M did not halt. $\forall n (\text{ if } M \text{ has not halted before time n, then } \Delta \models \mathbb{D}(n)$

First-Order Logic Revamp: Some definitions for first-order logic:

• Logical Symbols:

```
Negation: : 'not'
Conjunction: &, ∧: 'and'
Disjunction: ∨: 'or'
Conditional: →: 'if ... then ...'
Biconditional: ↔: 'if and only if'
Universal quantification: ∀x: 'for every x'
Existential quantification: ∃x: 'for some x'
Identity symbol: =: '... is (the very same thing as ) ...'
Variables: x, y, z
Punctuation: '(', ')', ','
```

• Nonlogical Symbols:

- Constants or Individual symbols (a,b,c ..)
- Predicates or Relation symbols: Have a fixed positive number of places
- Function symbols: : Have a fixed positive number of places.

• Other-Definitions:

– language: an enumerable set of nonlogical symbols. Denoted: L Empty Language: L_{\varnothing} , The language with no logical symbols.

• Closure:

- Closed Function: they make a complete statement capable of being true or false
- Closed Term: Has no variables.
- Interpretation: An interpretation M for a language L consists of two components.
 - A nonempty set |M|, called the domain or universe of discourse of the set of things M.
 - For each non-logical symbol, a denotation assigned to it. Noted by x^{M} .