

LSI Design (fundamentals)

BF001

**To learn behavior of MOS transistors
and circuits is essential before
starting LSI designs**

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(add my email to your report today)

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Technology Planning Div.
Technology Development Unit

Rev. 5.7- RVC 00000-A

Contents

- 1. Introduction**
- 2. Components in LSI**
- 3. MOS Circuit Design**

Guideline of this course

1. Intended audience

h/w and s/w engineers who have mastered science and engineering

2. Purpose of this course

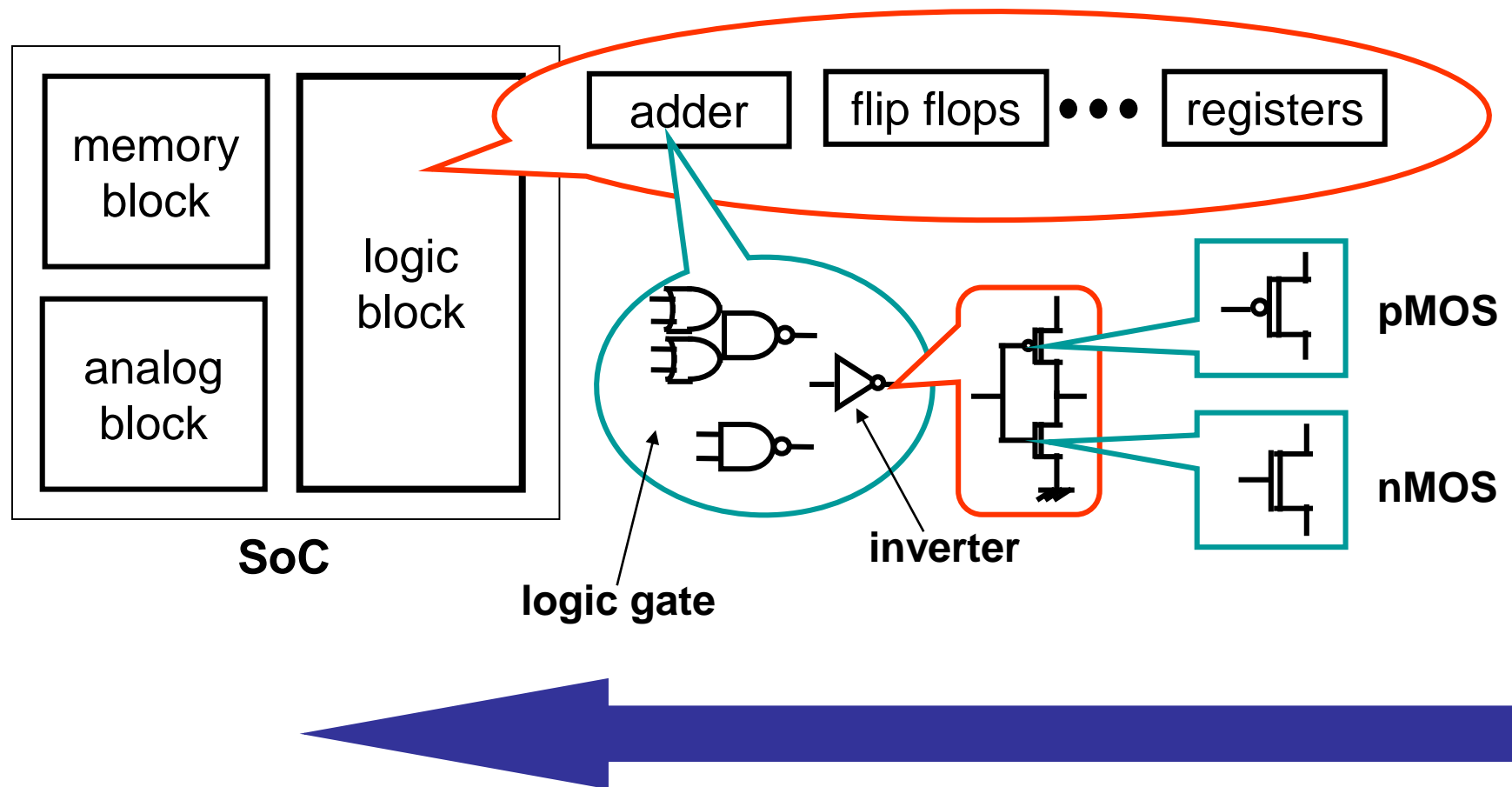
- * to understand common sense (basic, but much information)
- * to fill knowledge gap between automated designs and actual device behavior

3. Recommendations

- * to memorize every information in this course is NOT necessary
- * but to recall it in your future design activities
- * **the light symbol indicates the important slide**



SoC Hierarchy



BF001

What is LSI design?

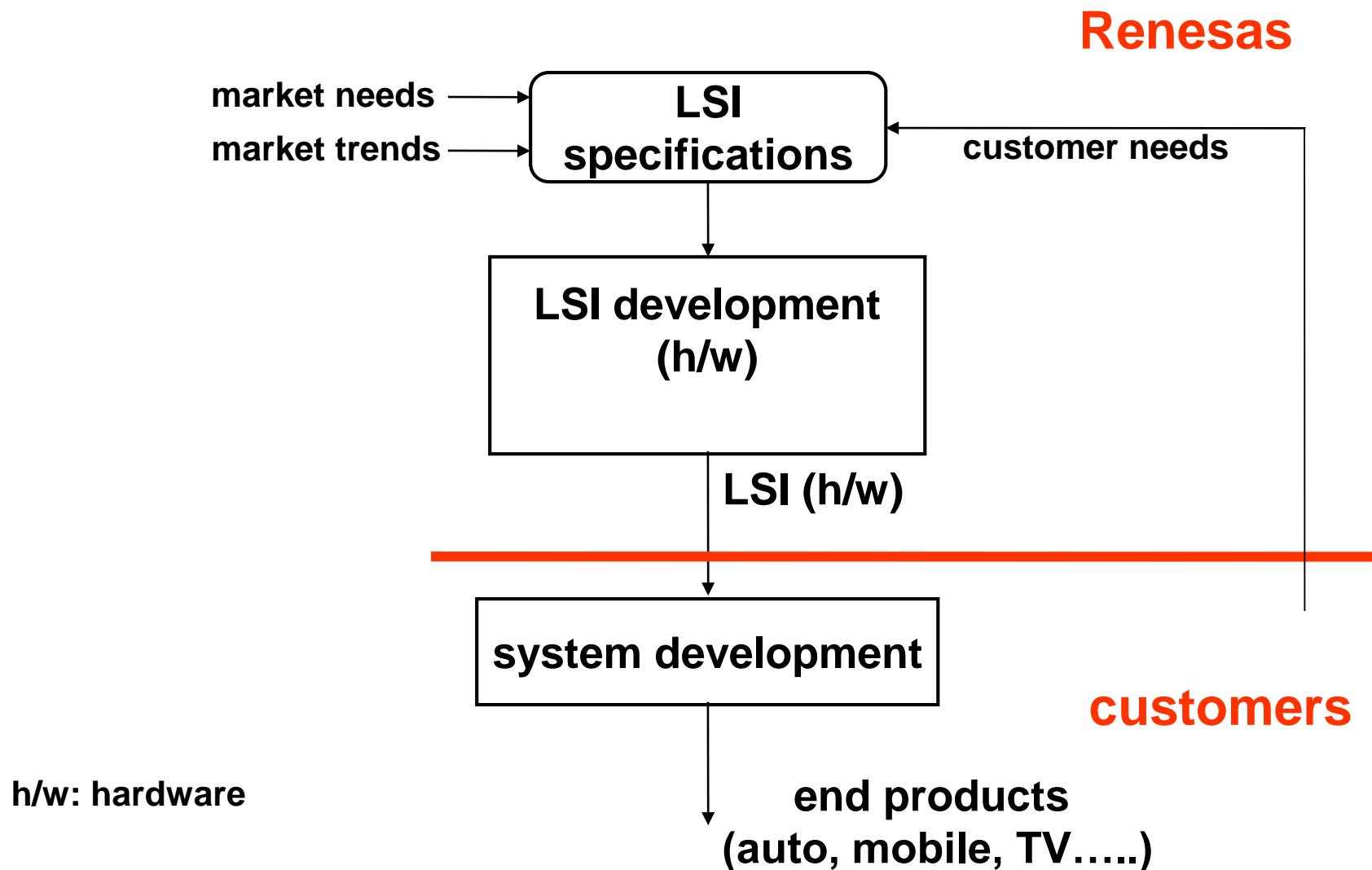
LSI design is intended to form semiconductor circuits on a silicon chip to meet growing **market needs** for performance and features within reasonable **time frame** and **price** range.

Design goals

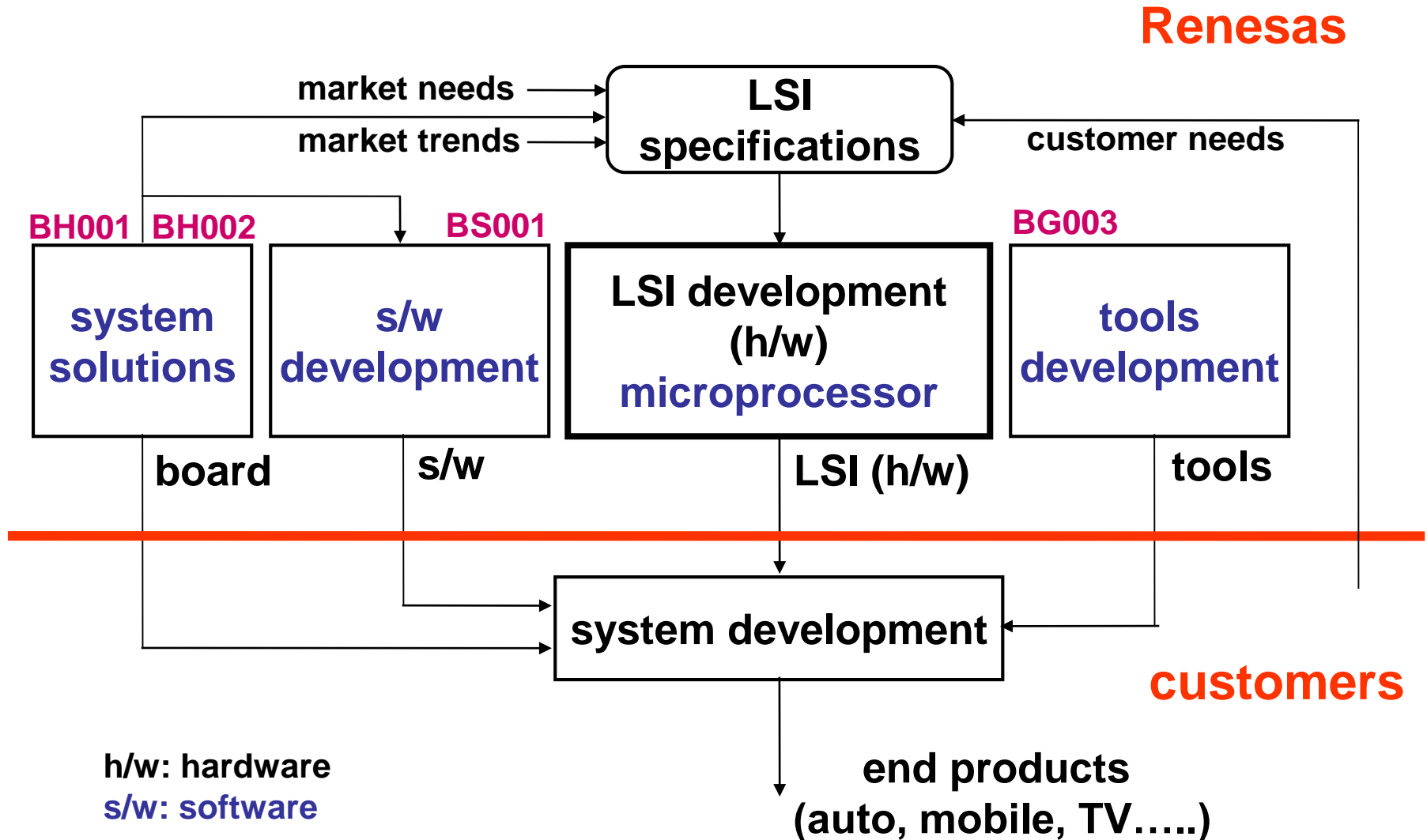
- functional
- performance
- time-to-market
- profitable



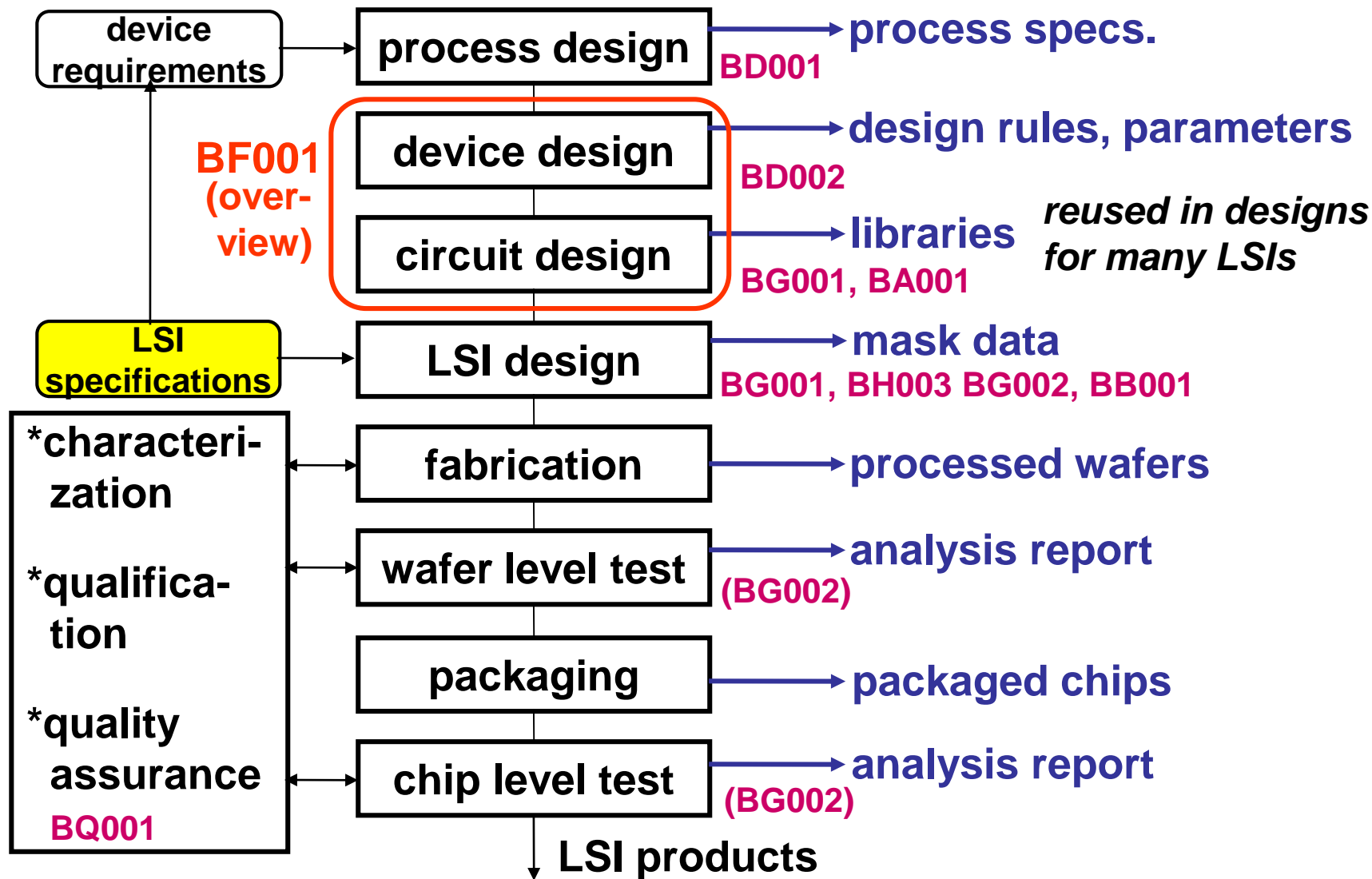
Activities of Renesas (1)



Activities of Renesas (2)



LSI Development



Contents

1. Introduction

2. Components in LSI

Devices in LSI

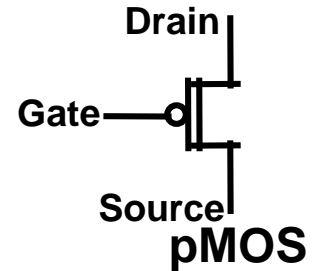
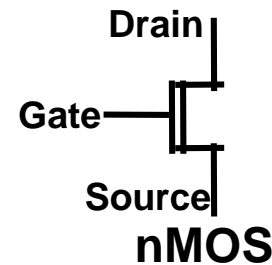
Circuits in LSI

3. MOS Circuit Design

Devices Implemented in LSI

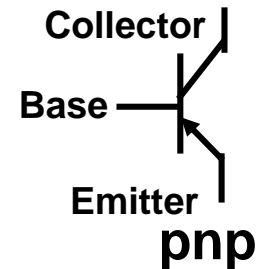
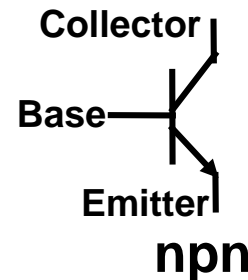
○ MOS Transistor

Broadly used owing to the properties of high-speed, low-voltage, and high-integration.



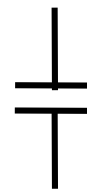
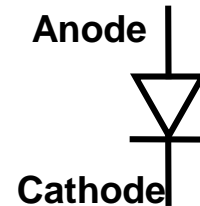
○ Bipolar Transistor

Used in RF and analog applications owing to its high-driveability.



○ Other devices

Diode, resistors, capacitors etc.

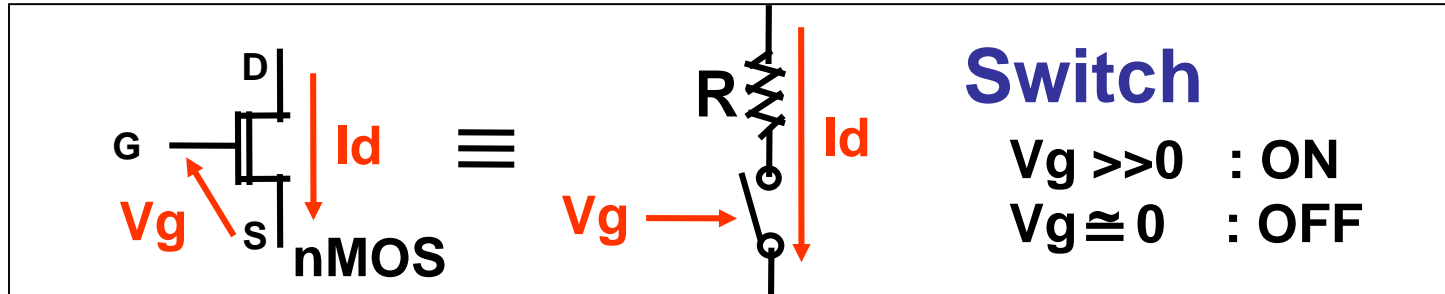


MOS: Metal Oxide Semiconductor

Simplified Operations of semiconductors

MOS Transistor

“s” is eliminated: V_g , V_d , I_d
 $V_g = V_{gs}$; $V_d = V_{ds}$; $I_d = I_{ds}$

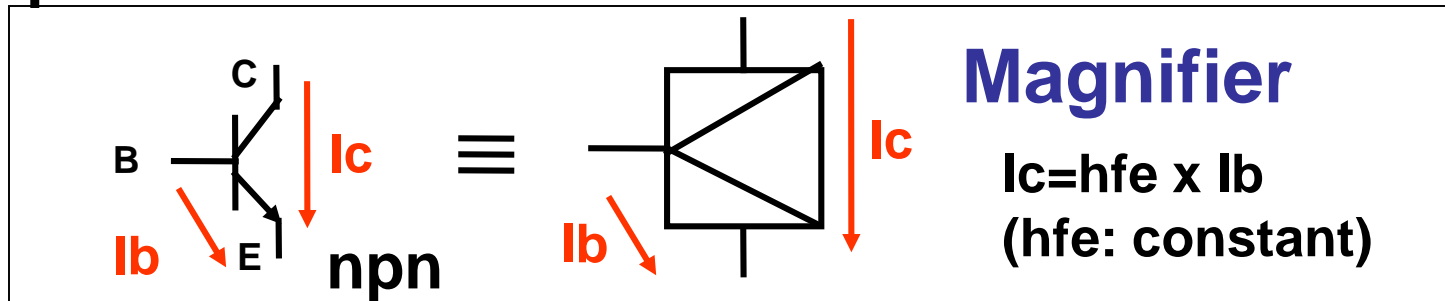


Switch

$V_g \gg 0$: ON

$V_g \cong 0$: OFF

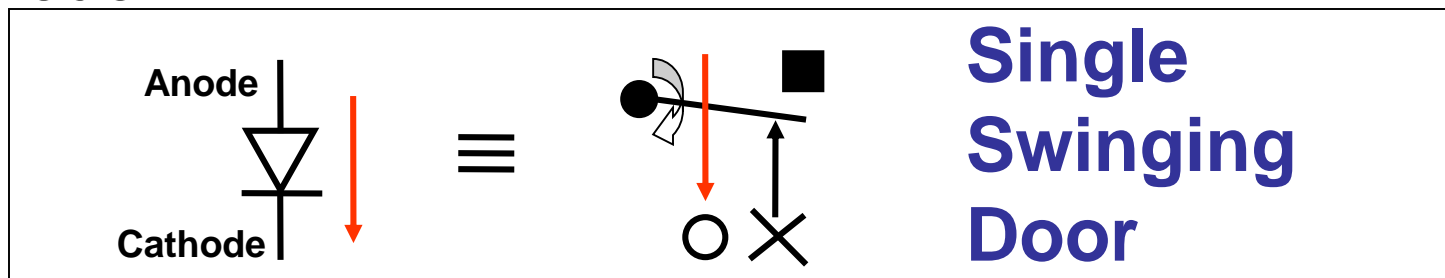
Bipolar Transistor



Magnifier

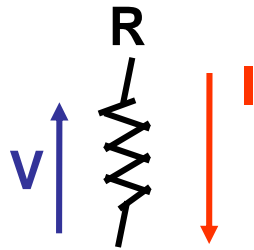
$I_c = h_{fe} \times I_b$
(h_{fe} : constant)

Diode

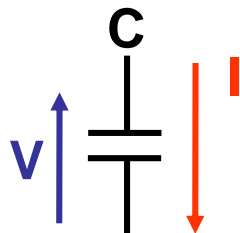


**Single
Swinging
Door**

Passive Devices

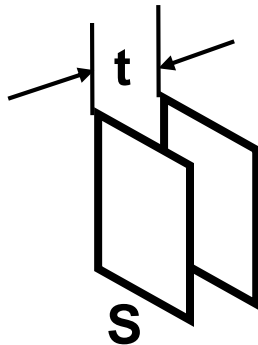


$$V = I \times R$$



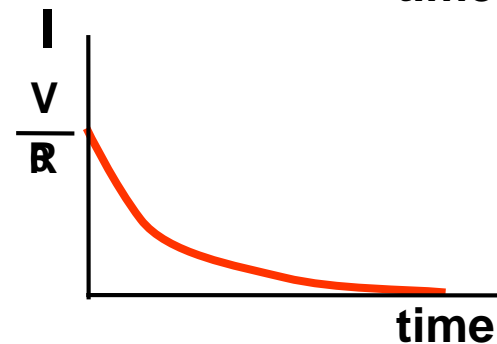
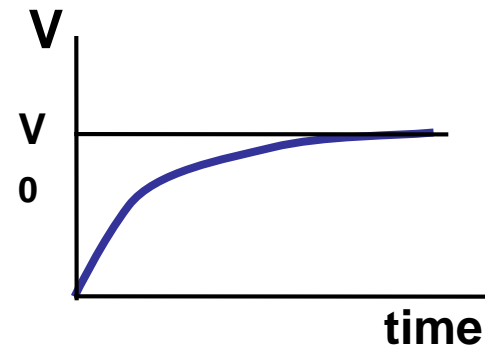
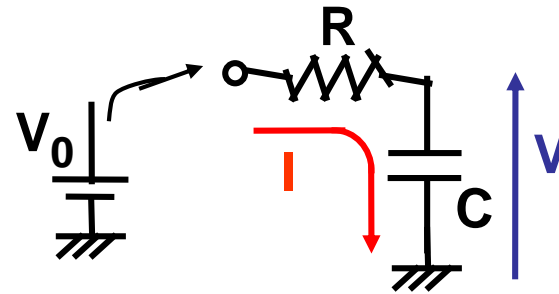
$$Q = C \times V$$

$$I = \frac{dQ}{dt} = C \frac{dV}{dt}$$

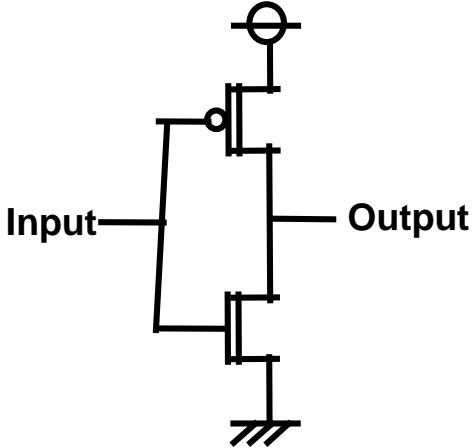
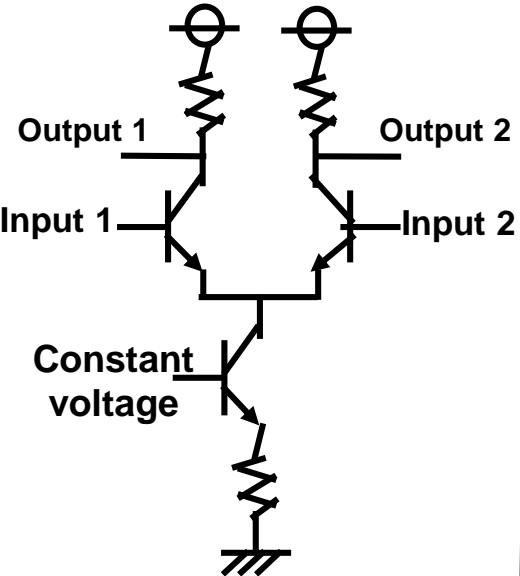
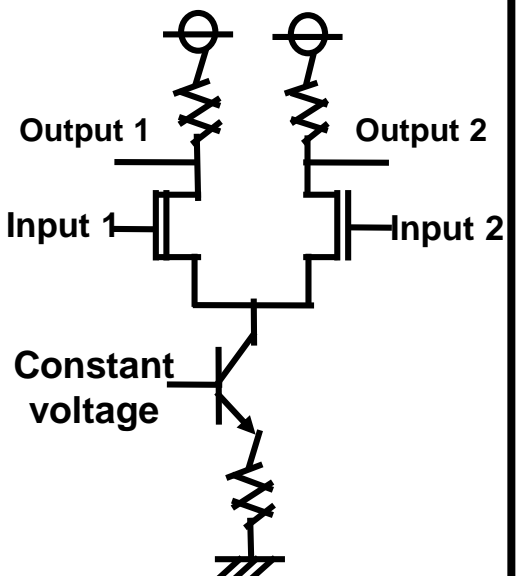


$$C = a \times \frac{S}{t}$$

(a: constant)



Circuits configured in LSI

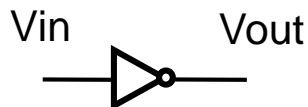
CMOS Circuit	Bipolar Circuit	BiCMOS Circuit
		
Entirely applicable to any LSI	Applicable to analog, ultra-high speed (RF) LSI	Applicable to analog, ultra-high speed (RF) LSI

CMOS: Complementary MOS

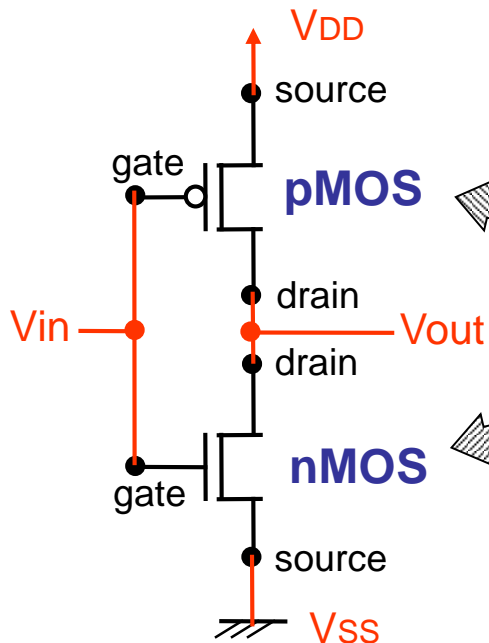
Logic Circuit on Silicon Chip

Inverter

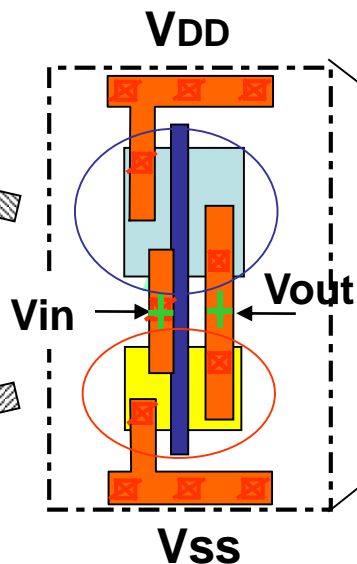
<cell symbol>



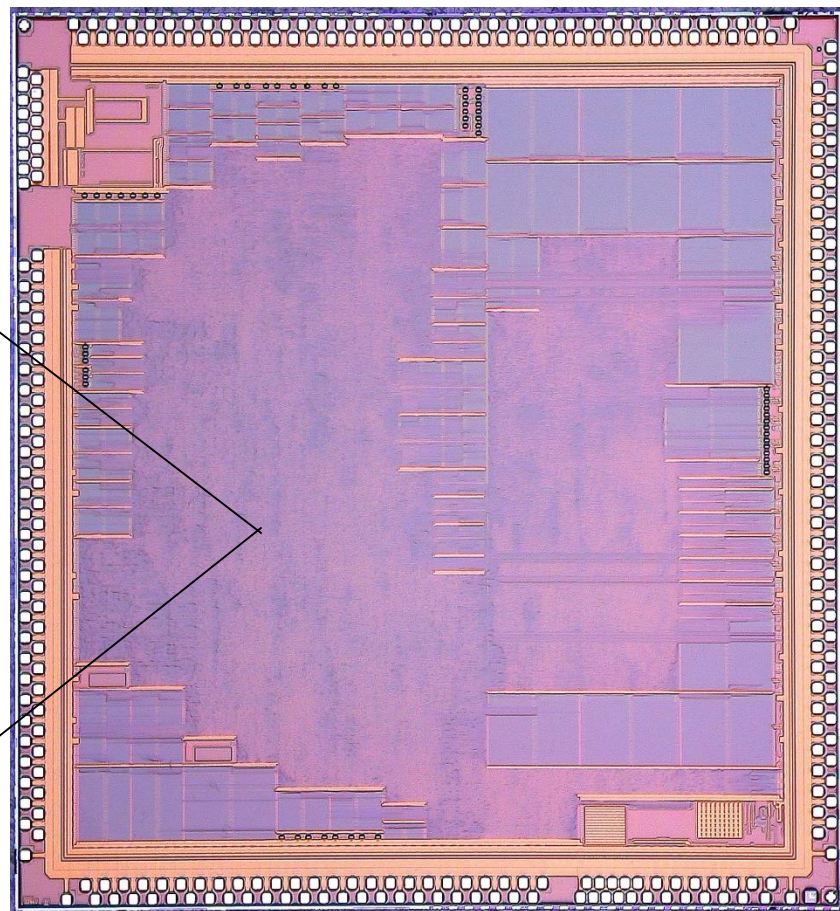
<circuit schematics>



<layout pattern>

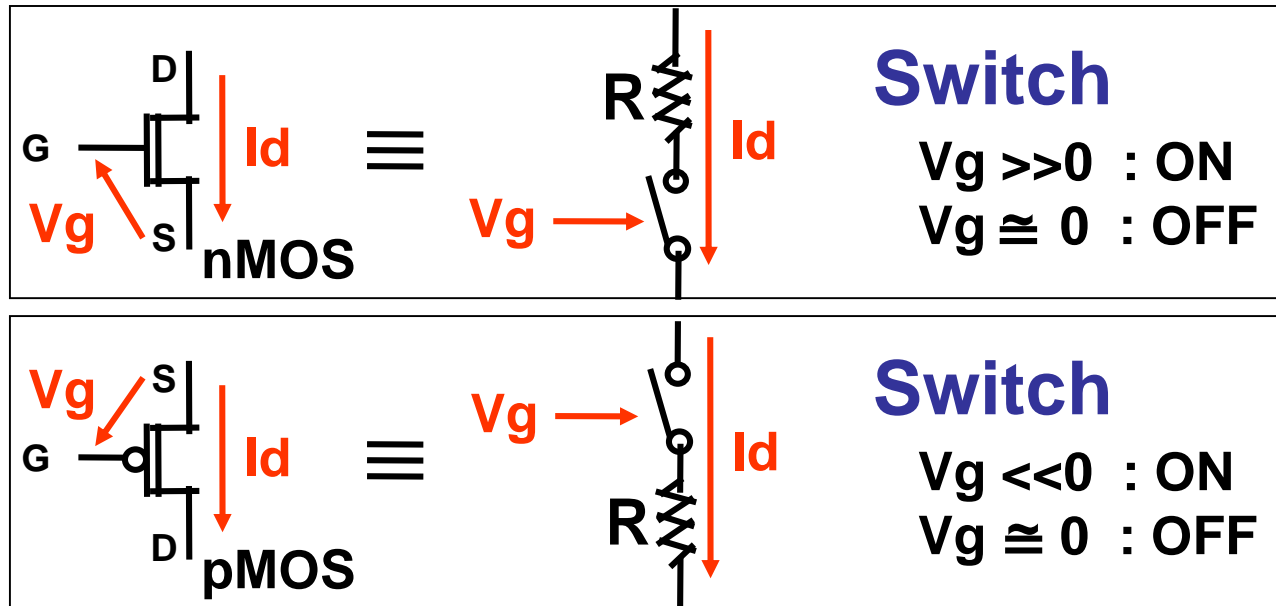


<CMOS die photo>

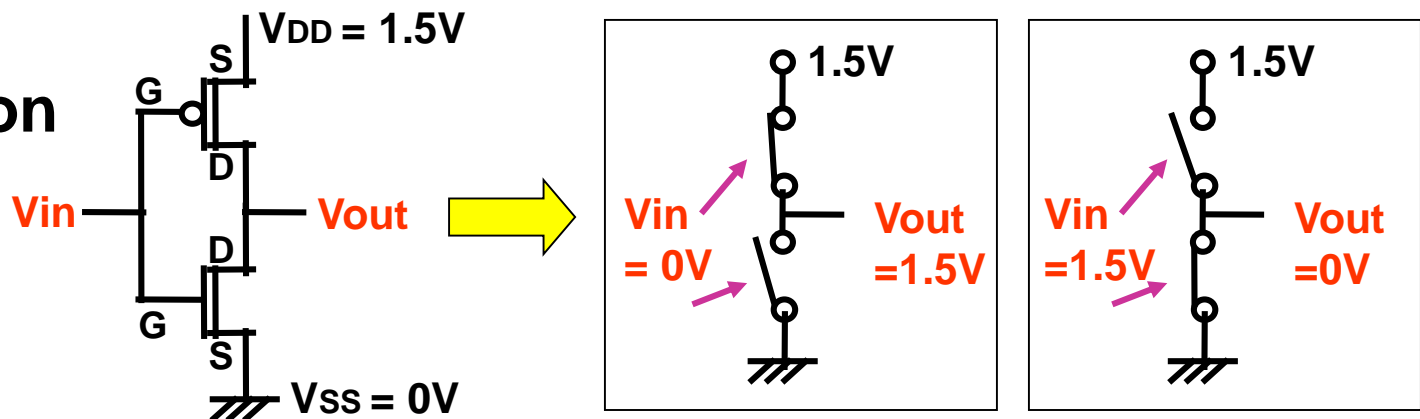


Simplified Operation of Inverter

MOS Switches



Inverter Operation



Contents

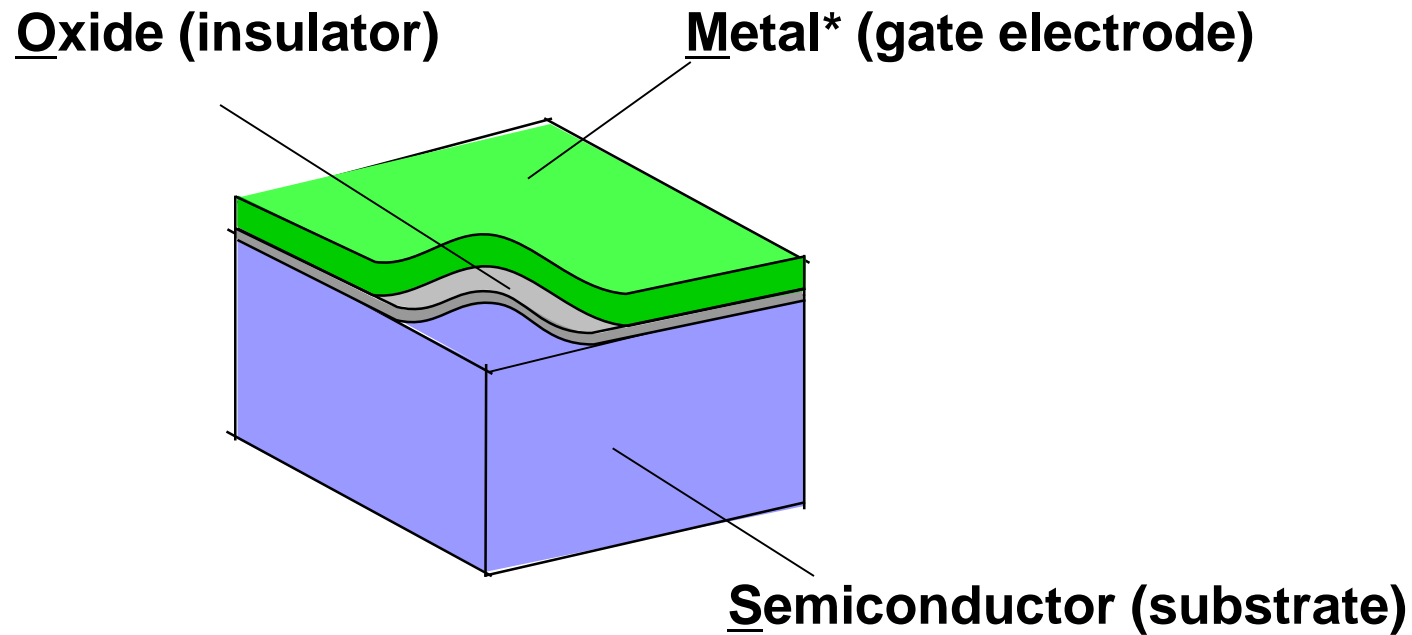
1. Introduction
2. Components in LSI
3. **MOS Circuit Design**
 - 3.1 MOS Physics
 - 3.2 MOS Operations
 - 3.3 Scaling
 - 3.4 Basic CMOS Logic Circuits

3.1 MOS Physics

- MOS Capacitor
- MOSFET

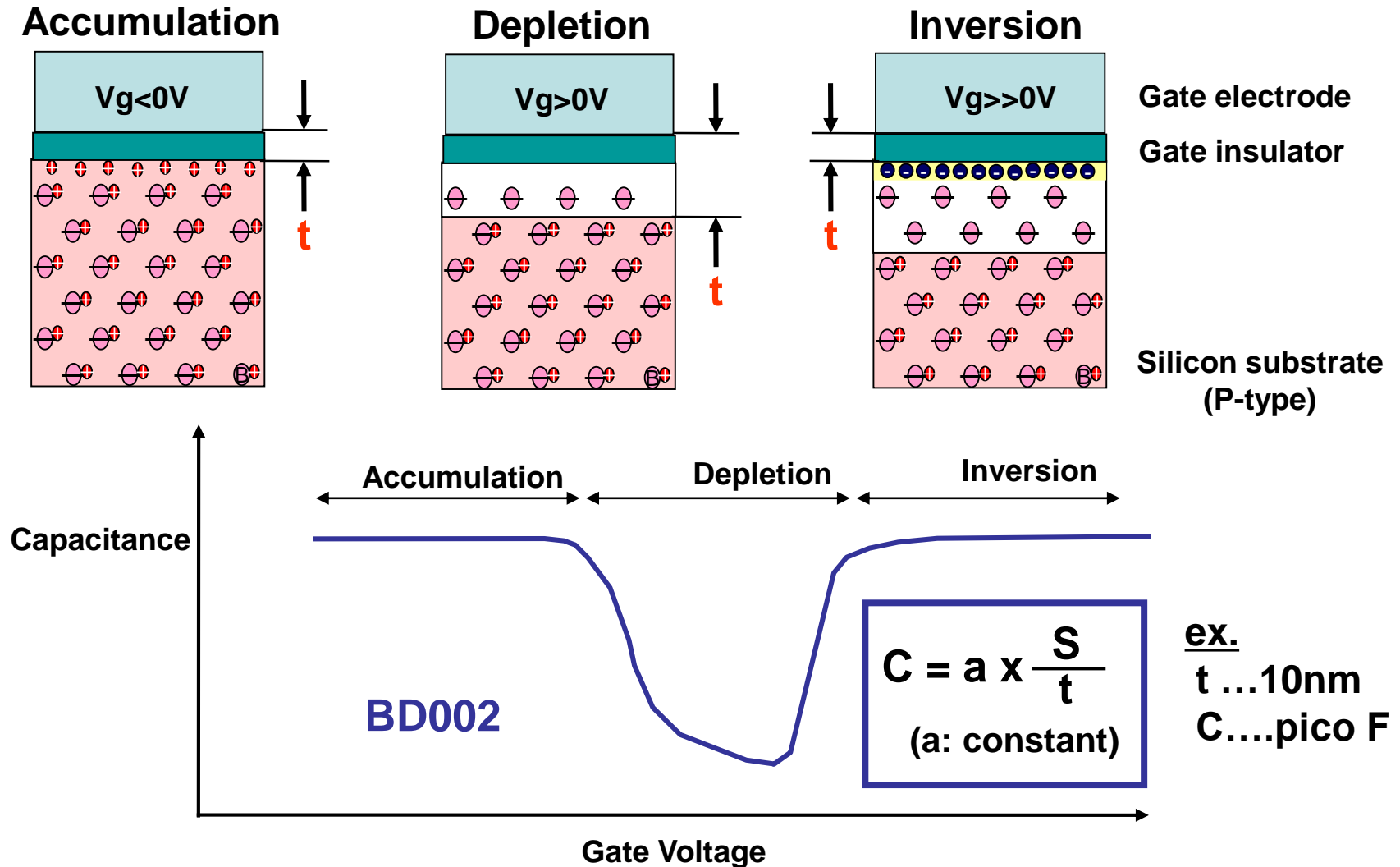
These will be further lectured in BD002.

MOS Capacitor



** actual metal or heavily doped polysilicon*

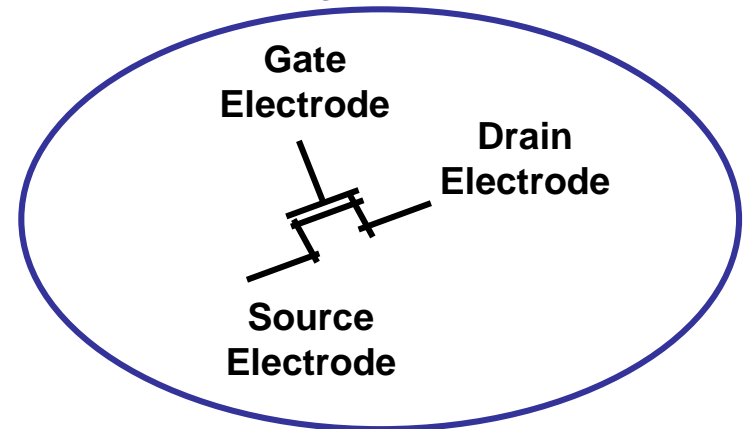
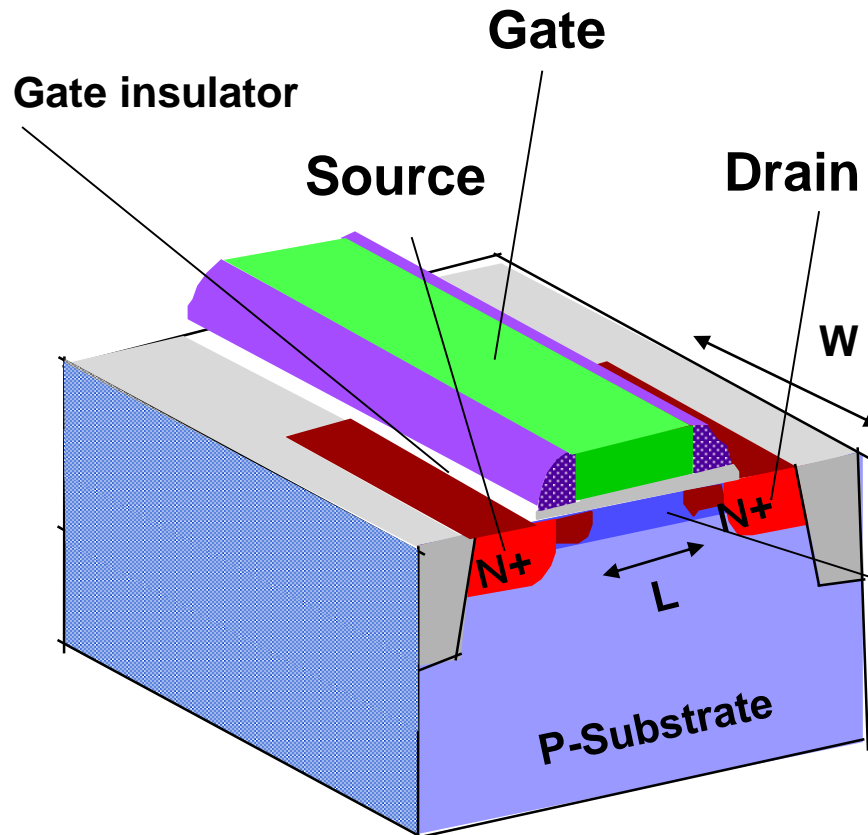
Behavior of MOS Capacitor



MOSFET

*** focusing on n-channel transistor ***

<symbol>

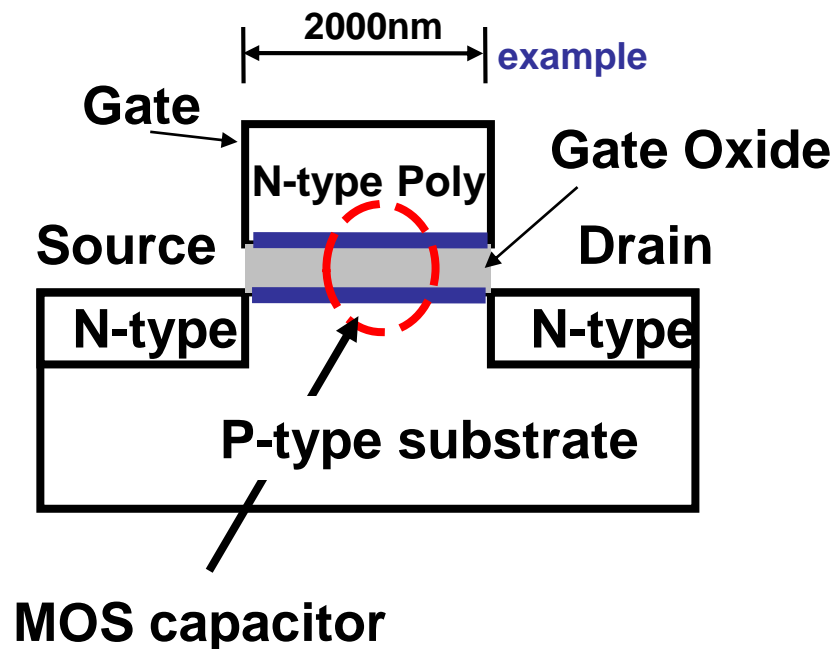


N+: heavily doped silicon
= low resistive electrode

L: Channel length
W: Channel width
FET: Field Effect Transistor

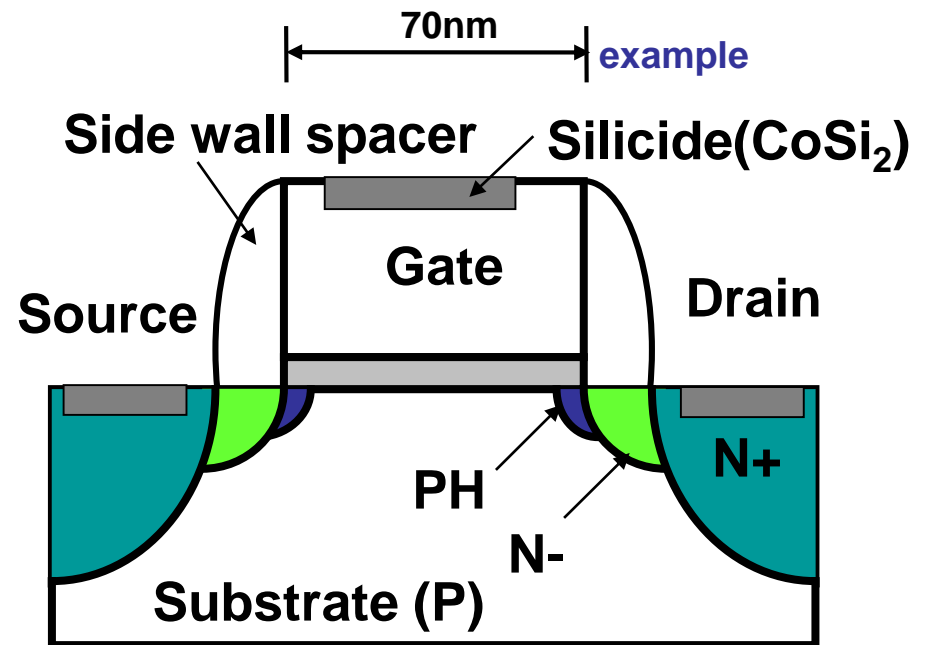
Basic MOSFET structure

By applying voltage to Gate, charges are induced at the capacitor edge. These charges are pulled out by Drain.



Basic structure

to be used in BF001 for simplicity

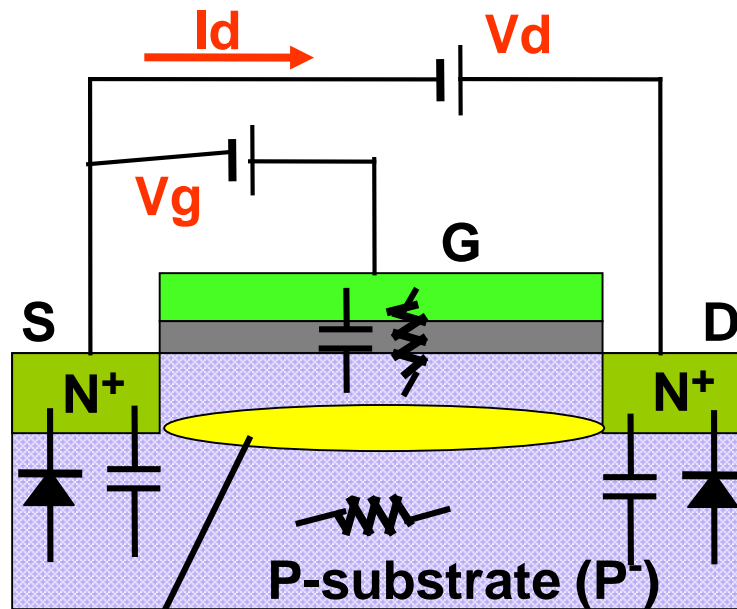


magnified schematics

Advanced structure

to be explained in BD002

Channel and Parasitic Devices



channel

$$I_d = f(V_d, V_g)$$

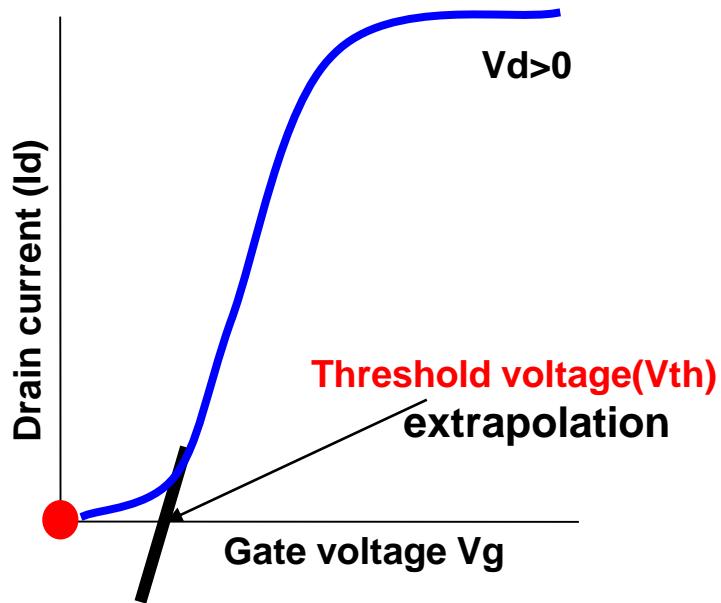
Gate characteristics: I_d vs. V_g

Drain characteristics: I_d vs. V_d



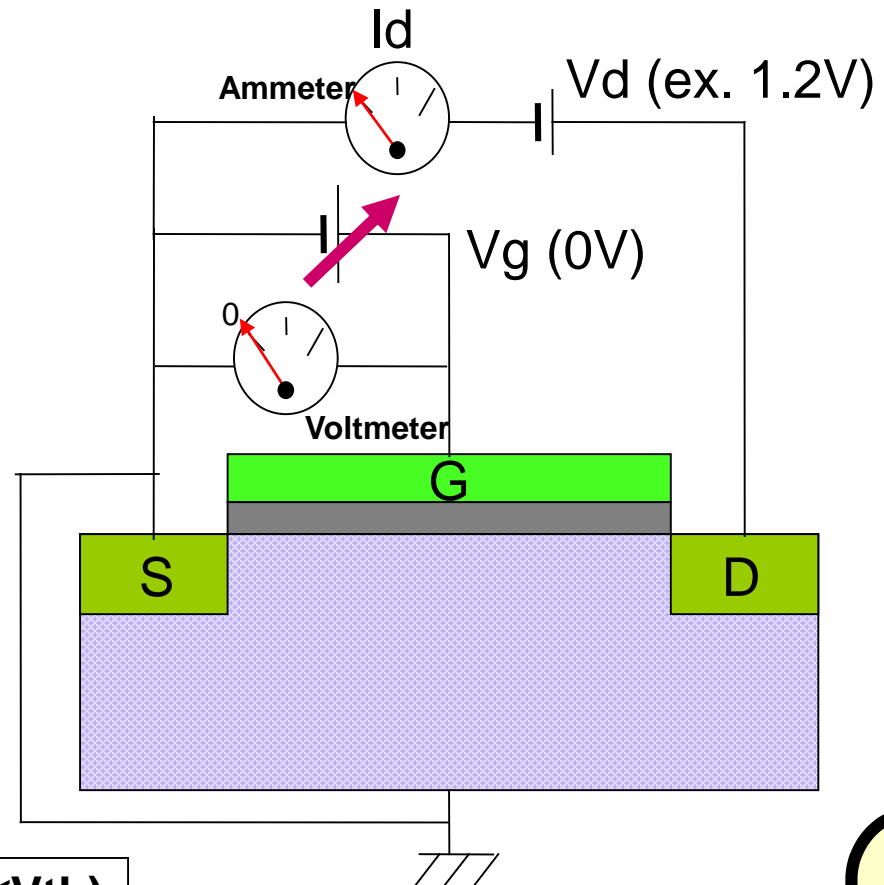
Operation of N-channel MOSFET (1)

- Gate characteristics



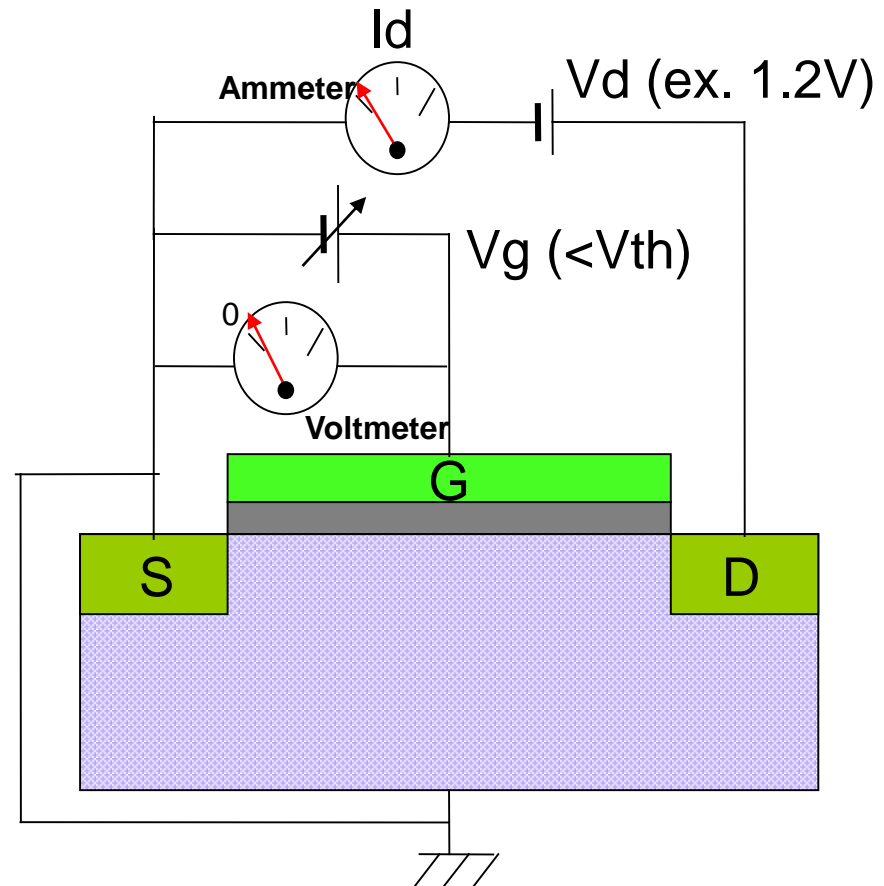
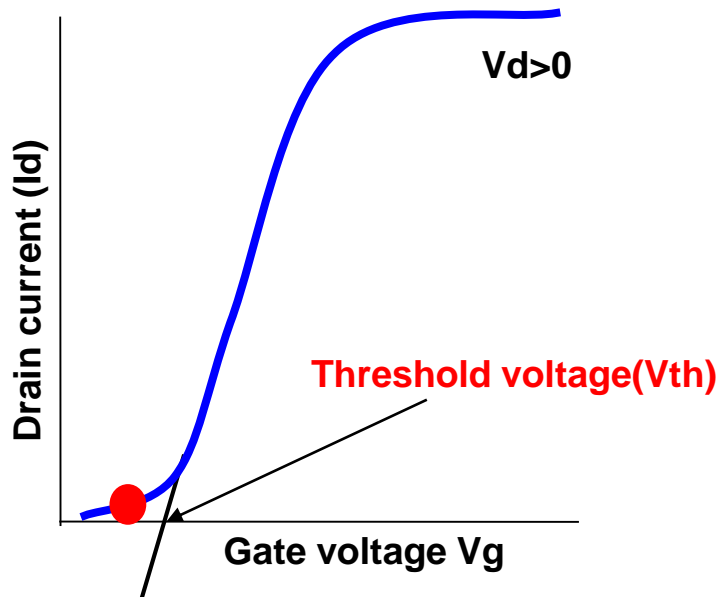
Sub-threshold region ($0 \leq V_g \leq V_{th}$)

$I_d = 0$ (nearly)



Operation of N-channel MOSFET (2)

- Gate characteristics

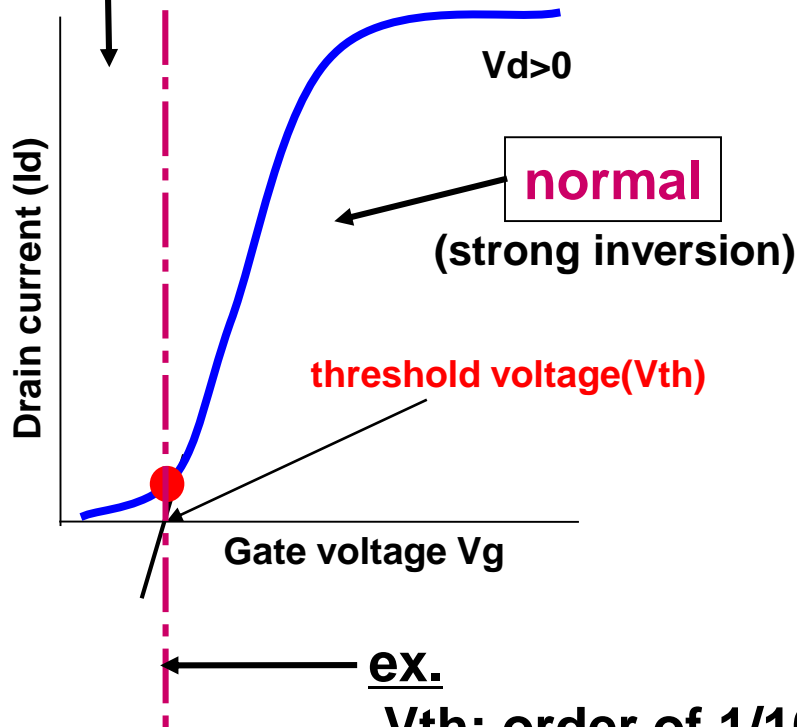


When $V_g < V_{th}$, the electric current is called **sub-threshold current**. This is one of the leakage currents.

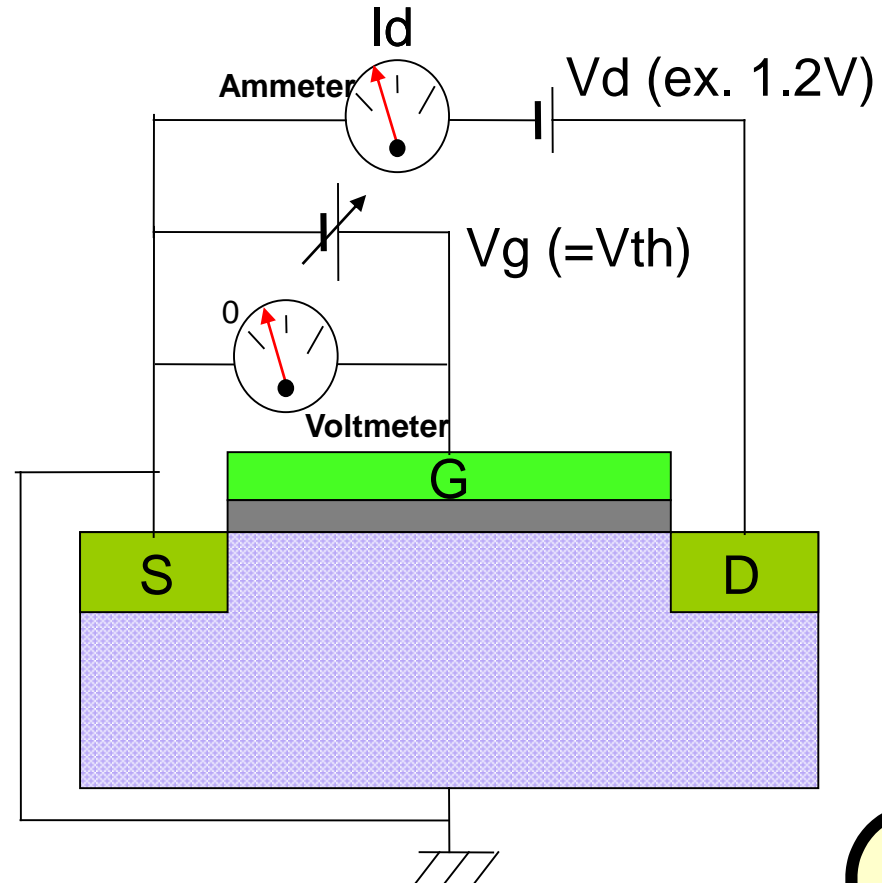
Operation of N-channel MOSFET (3)

- Gate characteristics

sub-threshold (weak inversion)

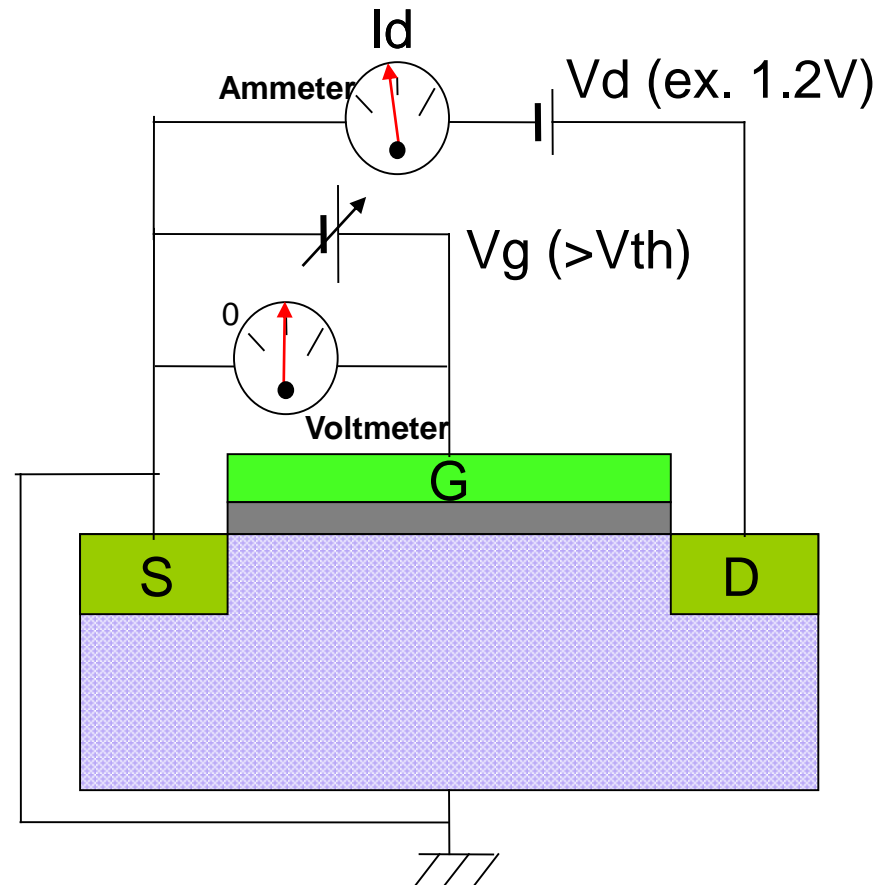
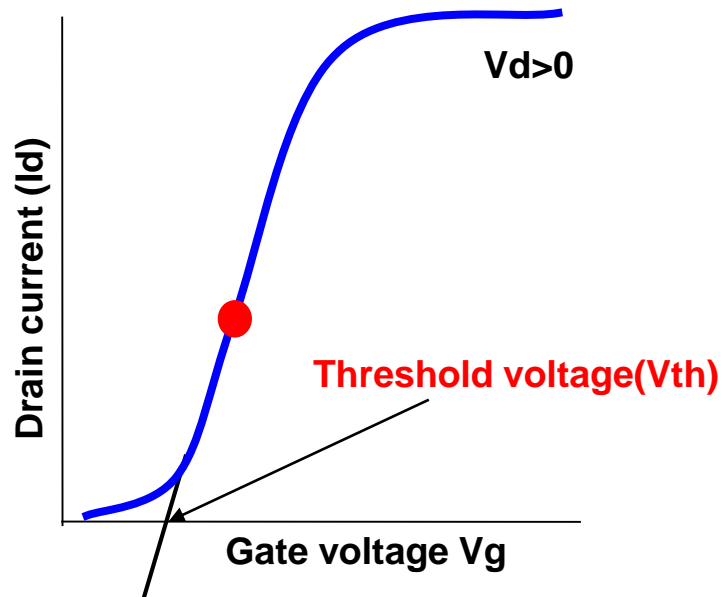


ex.
 V_{th} : order of 1/10 V
 I_d : order of nA



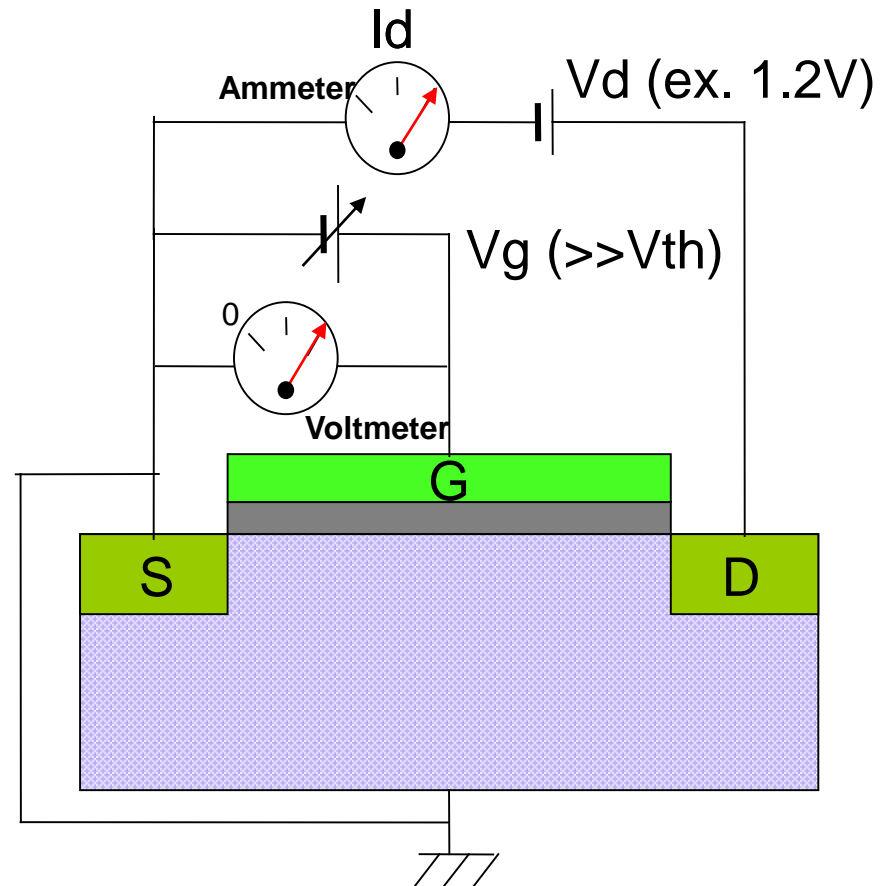
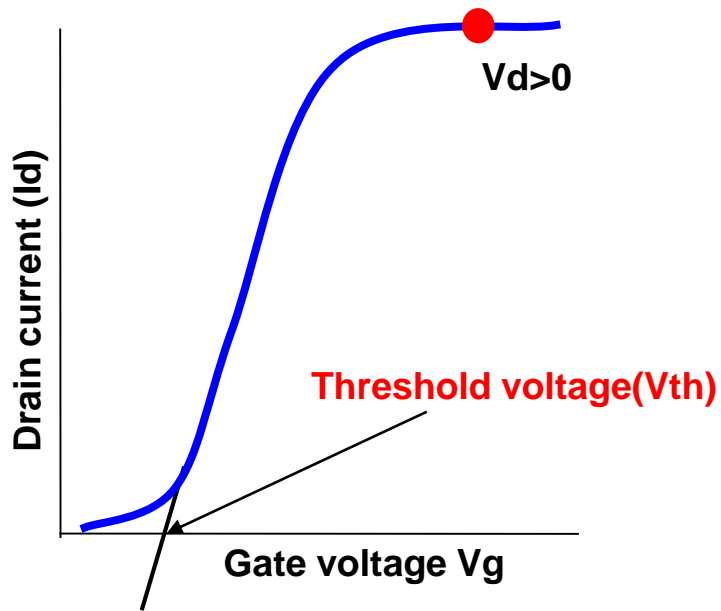
Operation of N-channel MOSFET (4)

- Gate characteristics



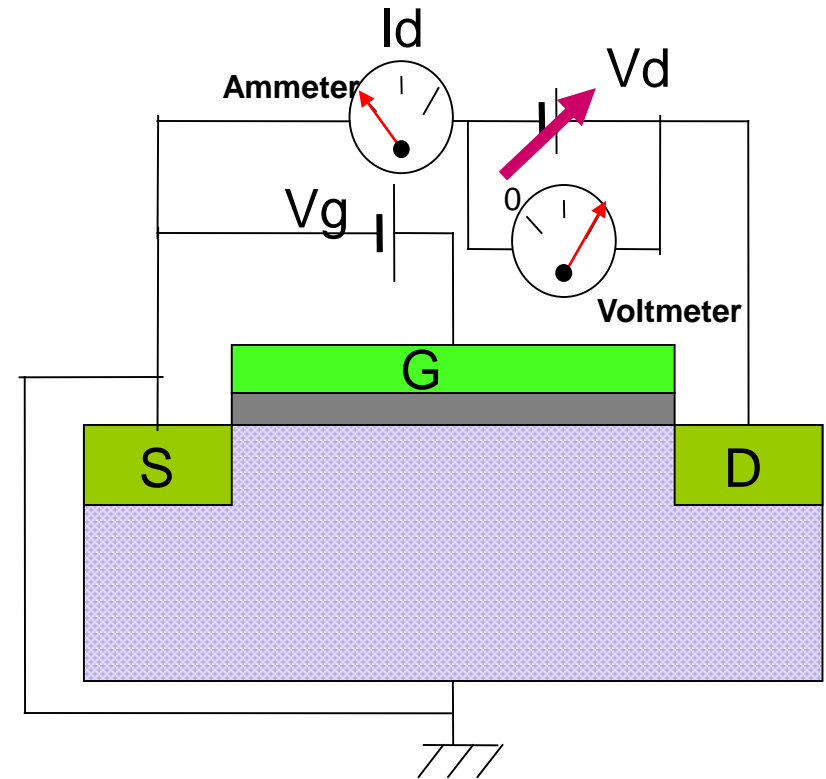
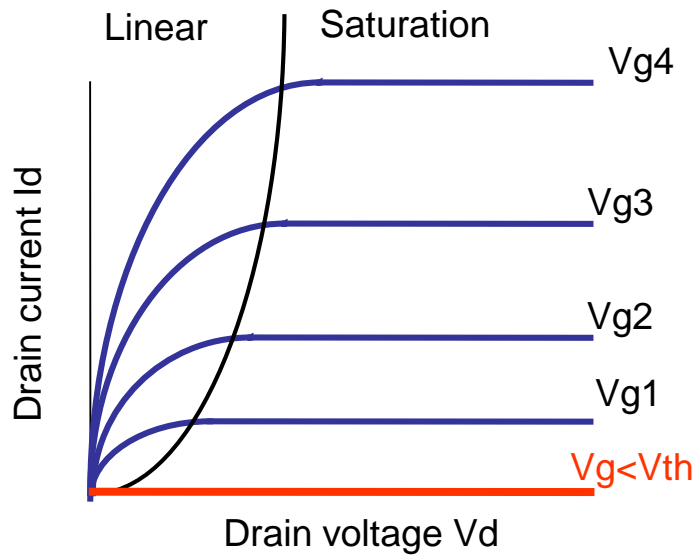
Operation of N-channel MOSFET (5)

- Gate characteristics



Operation of N-channel MOSFET (6)

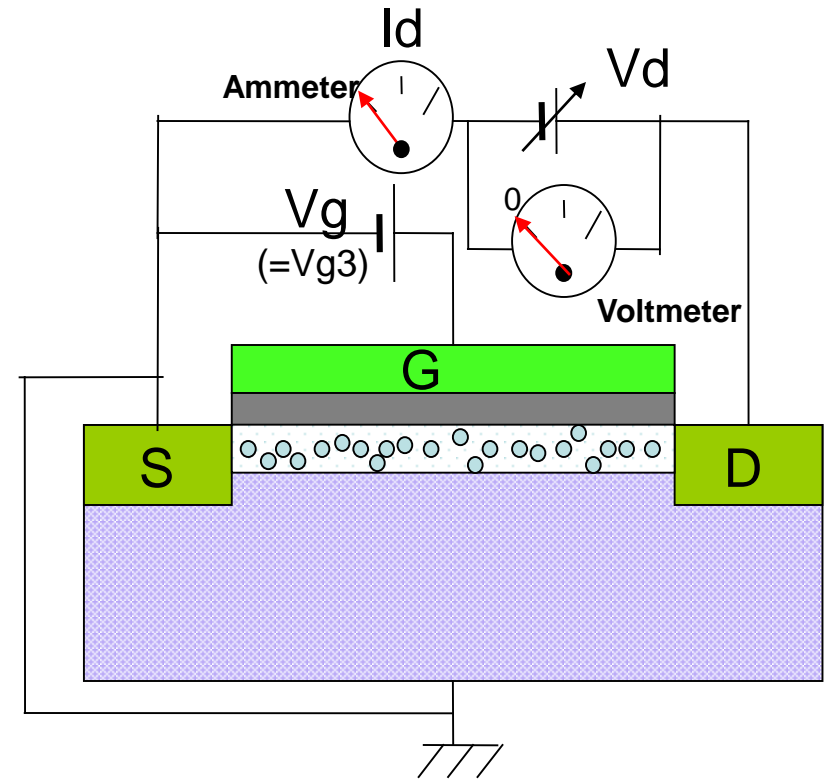
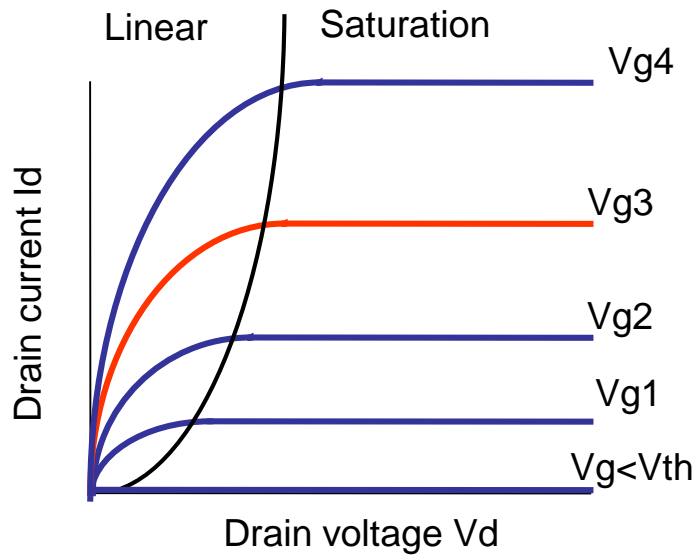
- Drain characteristics



Even if $V_d > 0$, there is no current (except leakage) when $V_g < V_{th}$.

Operation of N-channel MOSFET (7)

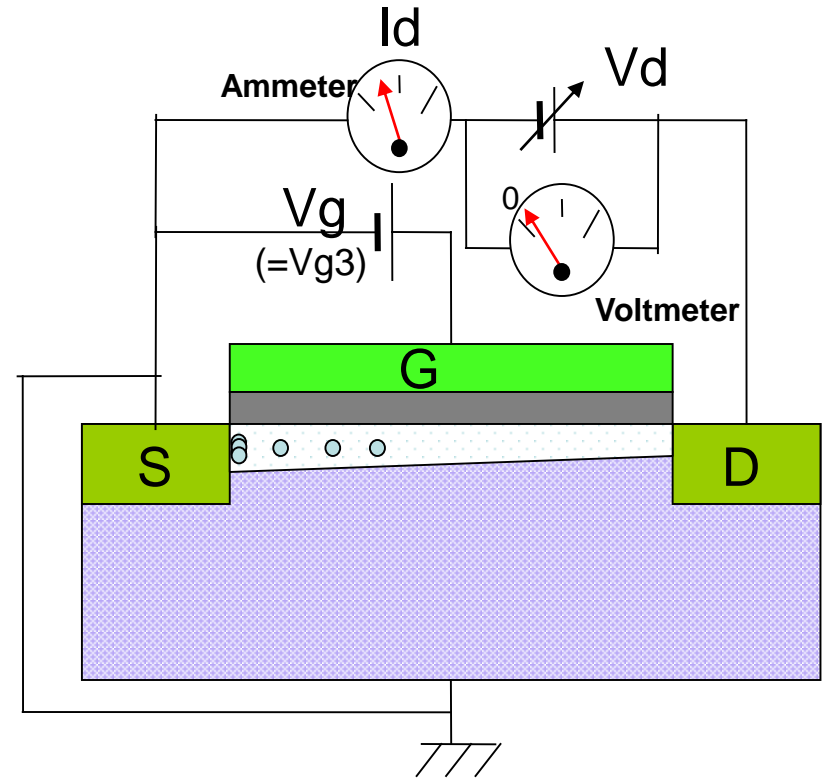
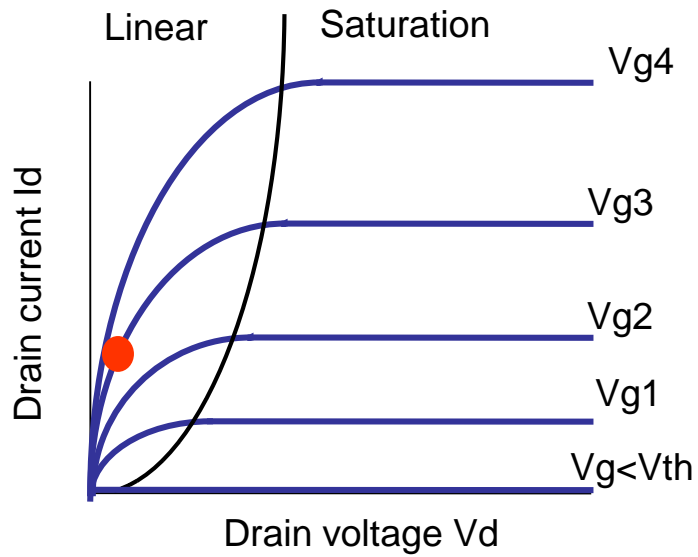
- Drain characteristics



Apply $V_g = V_{g3}$, and watch what happens.

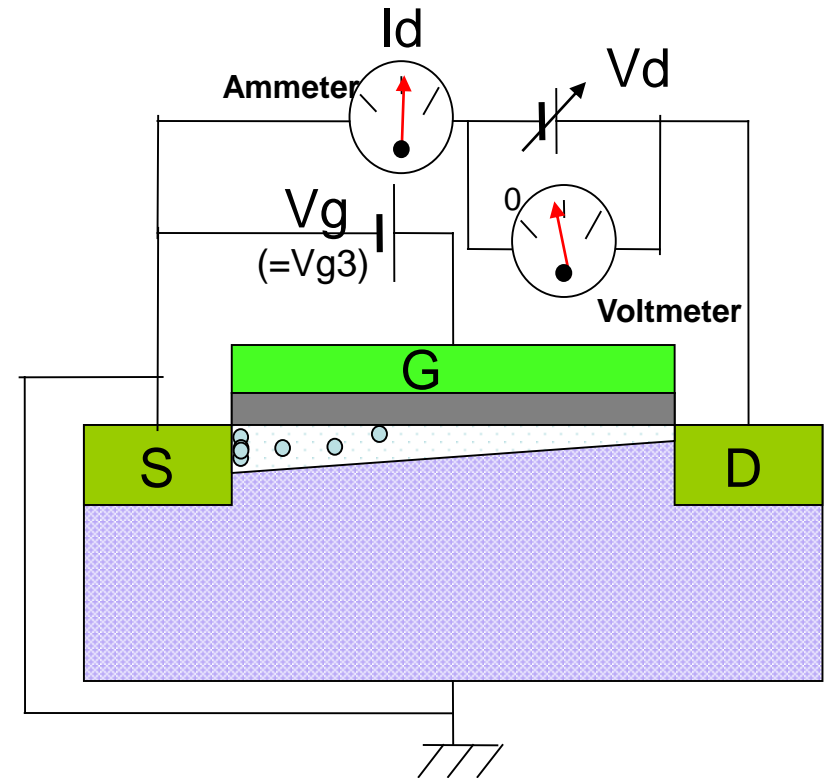
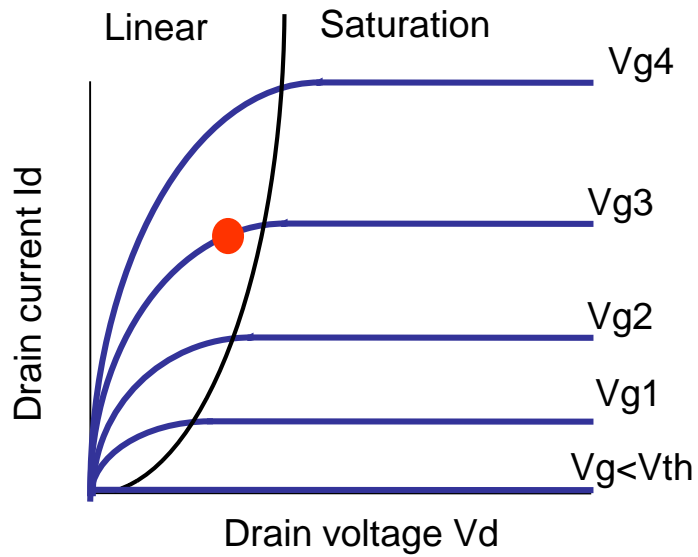
Operation of N-channel MOSFET (8)

- Drain characteristics



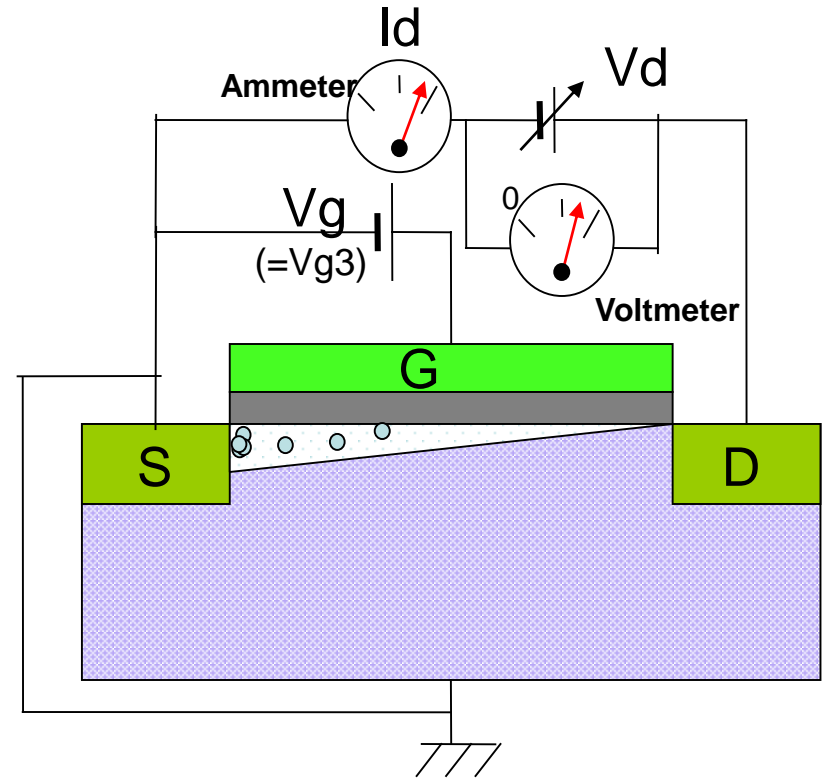
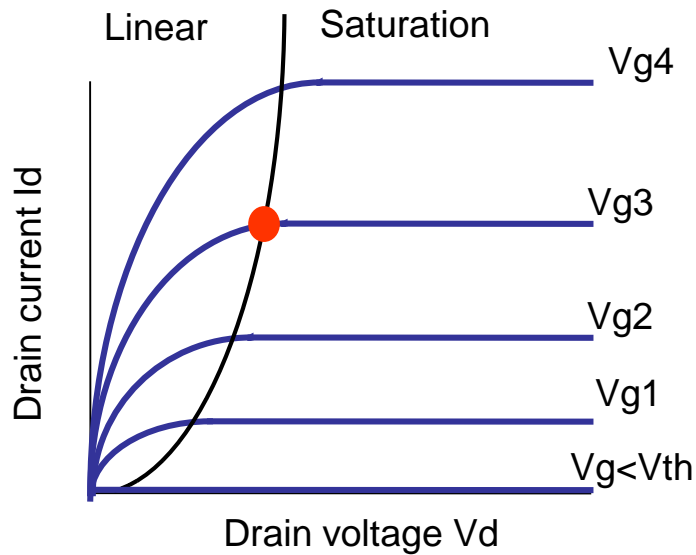
Operation of N-channel MOSFET (9)

- Drain characteristics



Operation of N-channel MOSFET (10)

- Drain characteristics



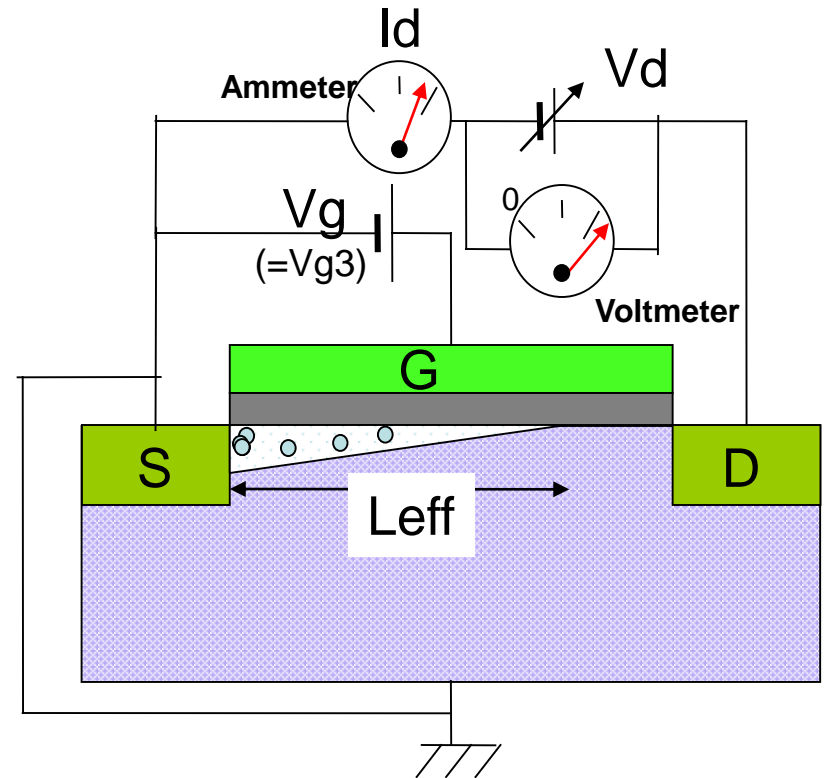
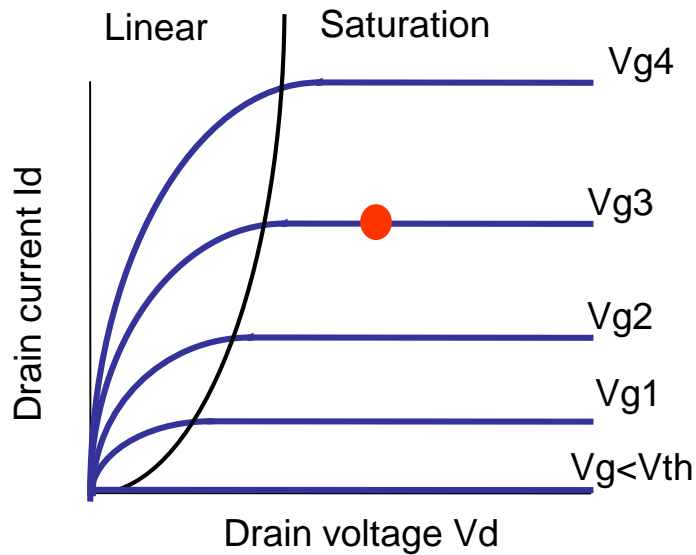
When $V_d = V_g - V_{th}$, it is called “**pinch-off point**”.
 $V_d = V_g - V_{th}$ is boundary of linear region & saturation region



BD002

Operation of N-channel MOSFET (11)

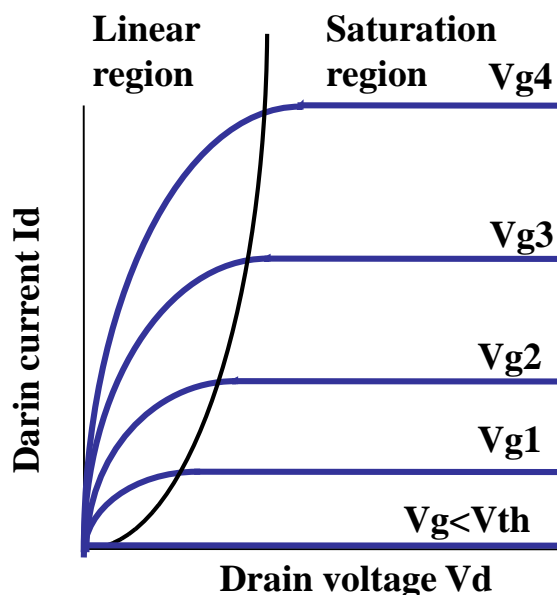
- Drain characteristics



After pinch-off, the current **becomes constant**.
Electrons are attracted by drain field and flow through the depletion region.

Current characteristics of MOSFET (Summary)

v5.7



I_d : Drain current

W : Channel width

L : Channel length

V_{th} : Threshold voltage

C_{ox} : Gate capacitance

$$= \epsilon * \epsilon_0 / T_{ox}$$

V_g : Gate voltage

μ : Mobility of carrier

ϵ : Relative permittivity

ϵ_0 : Permittivity of vacuum

T_{ox} : Gate Oxide thickness

Linear region ($0 \leq V_d \leq V_g - V_{th}$)

$$I_d = \mu C_{ox} \frac{W}{L} \left\{ (V_g - V_{th}) V_d - \frac{1}{2} V_d^2 \right\} \quad (\text{parabolic})$$

Saturation region ($V_d > V_g - V_{th}$)

$$I_d = \frac{W}{2L} \mu C_{ox} (V_g - V_{th})^2$$



Short Quiz

1/ What are two regions in the I_{ds} - V_{ds} curves, and what are their boundaries ?

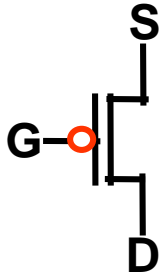
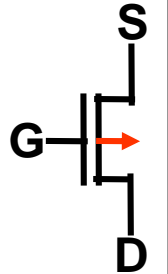
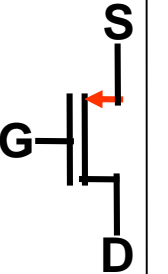
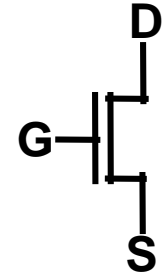
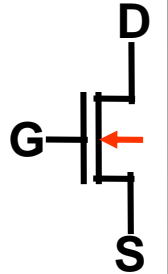
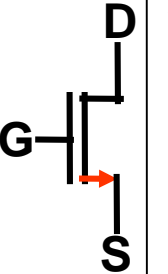
References

- Physics of Semiconductor Devices 2nd Edition by S.M.Sze, 1981
- Fundamentals of MODERN VLSI DEVICES by Y.Taur and T.H.Ning, 1998

**Let's take a 15-minutes
BREAK**

3.2 MOS Operations

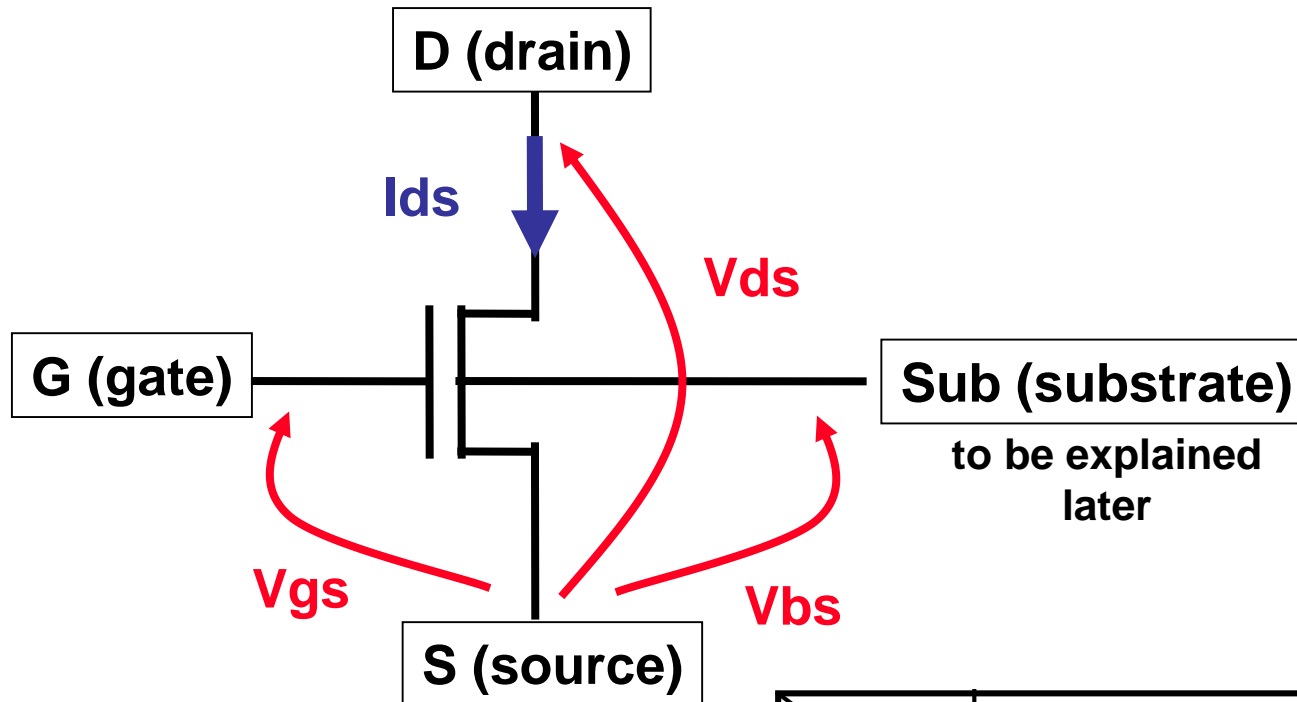
Notations and Operations of MOS Transistors

	Notations			Operations
pMOS transistor				When electric potential of gate (G) decreases* from potential level of source (S), current flows from source (S) to drain (D) .
nMOS transistor				When electric potential of gate (G) exceeds* that of potential level of source (S), current flows from drain (D) to source (S) .

All three notations are commonly used.

* Accurately, threshold voltages must be considered as biases.

Naming Convention



Sometimes “s” is eliminated, such as V_g , V_d , I_d , and V_b .

	Sign (polarity)			
	V_{gs}	V_{ds}	I_{ds}	V_{bs}
nMOS	+	+	+	-
pMOS	-	-	-	+

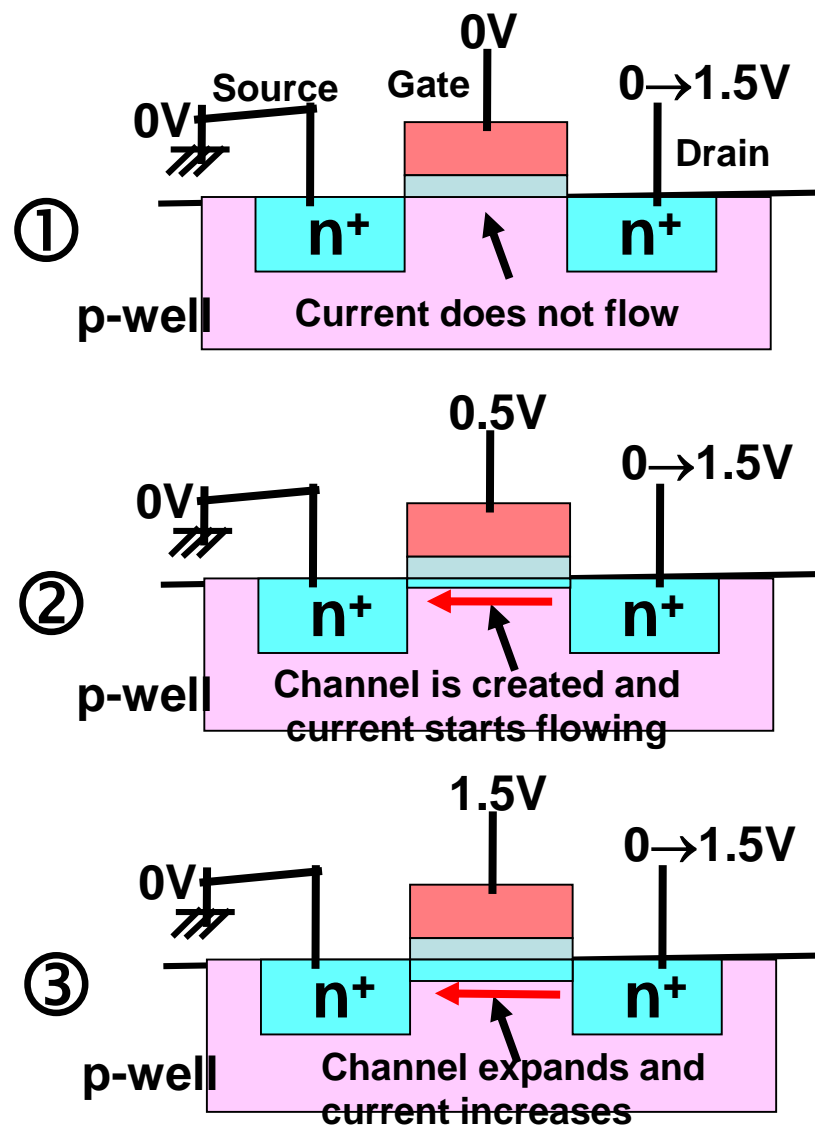
3.2 MOS Operations

- **nMOS Operation**

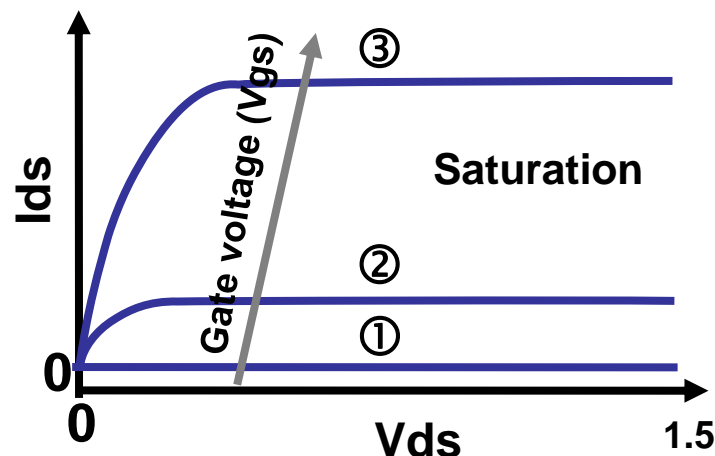
- **pMOS Operation**

- **CMOS Structure**

Operations of nMOS Transistor



<Characteristics of drain current >



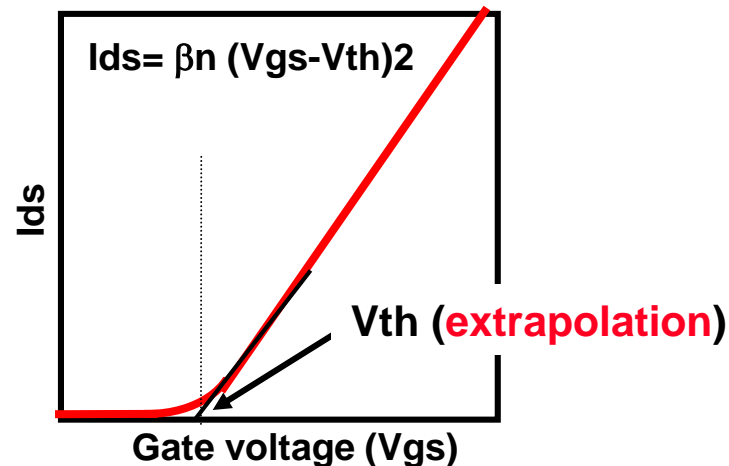
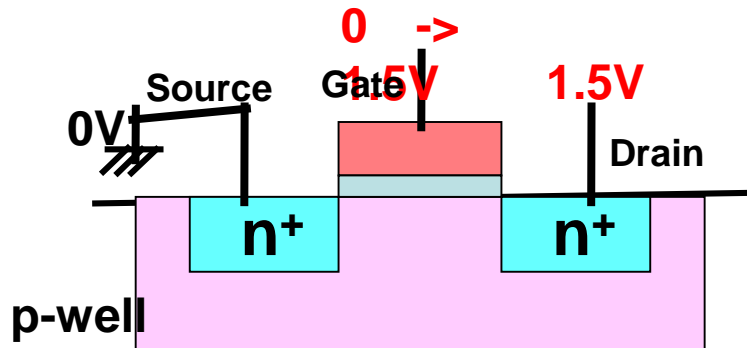
<Formula of drain current>

$$I_{ds} = \begin{cases} \beta_n \{ 2V_{ds} \cdot (V_{gs} - V_{thn}) - V_{ds}^2 \} & (\text{when } 0 \leq V_{ds} \leq V_{gs} - V_{thn}) \\ \beta_n (V_{gs} - V_{thn})^2 & (\text{when } V_{ds} > V_{gs} - V_{thn}) \end{cases}$$

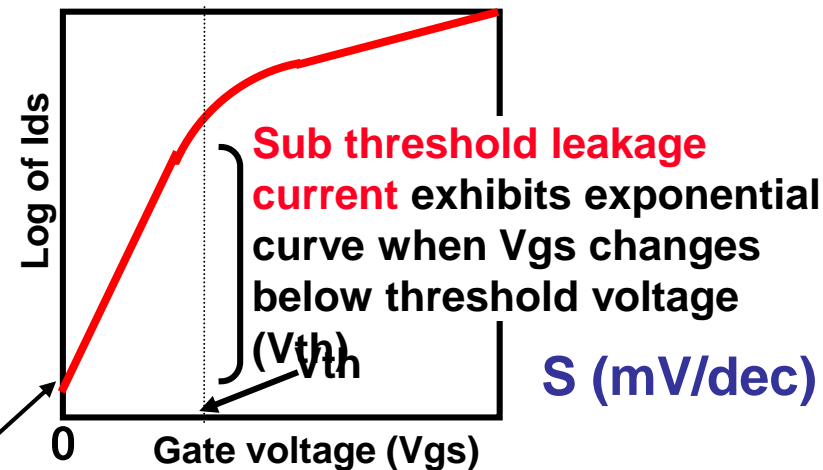
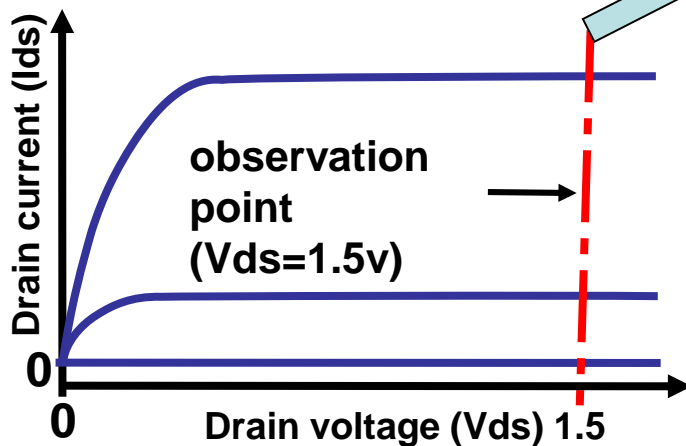
β_n : proportionality coefficient
 V_{thn} : threshold voltage (gate voltage required to switch ON transistor)

Relationship between threshold voltage and drain current (1)

- Changing gate voltage with holding drain voltage constant



<Characteristics of drain current>



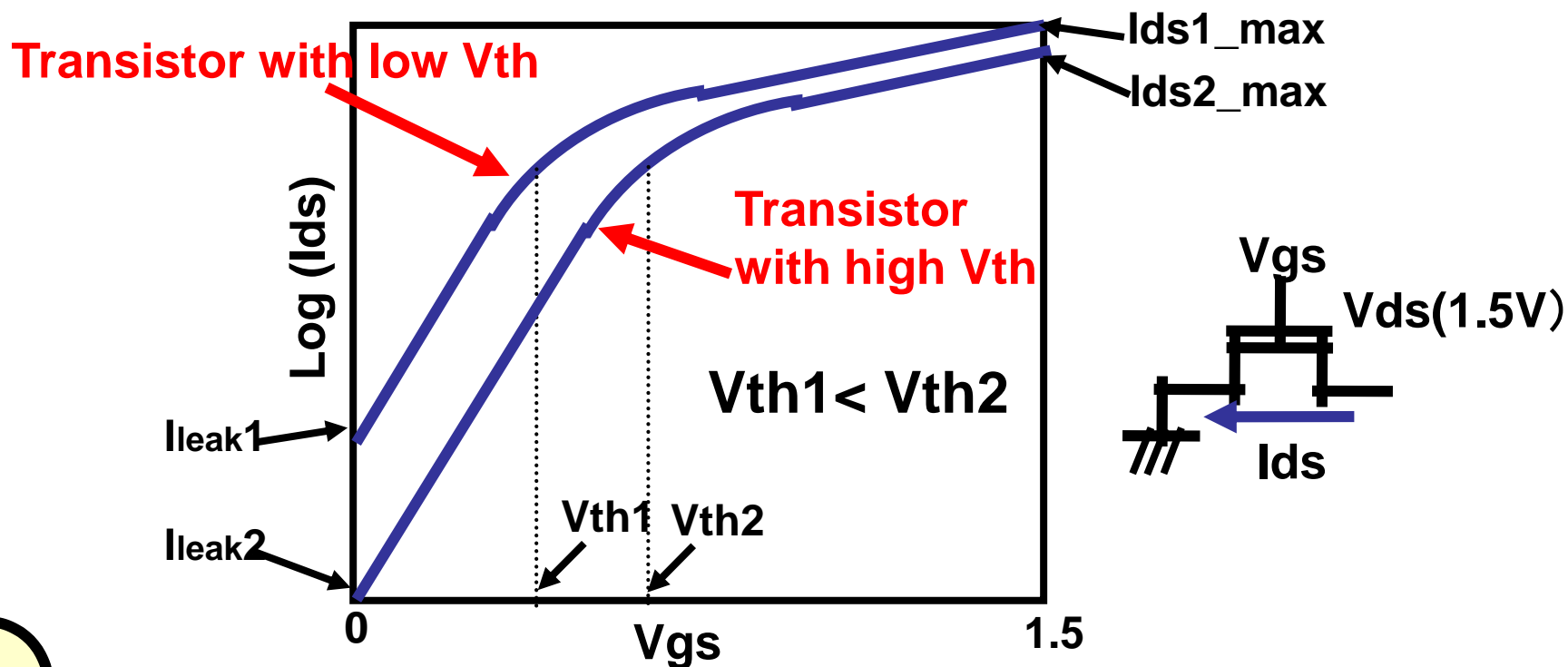
OFF state leakage current

When V_{thn} varies, 'OFF state leakage current' also changes exponentially



Relationship between threshold voltage and drain current (2)

< Different transistor characteristics according to different V_{th} >

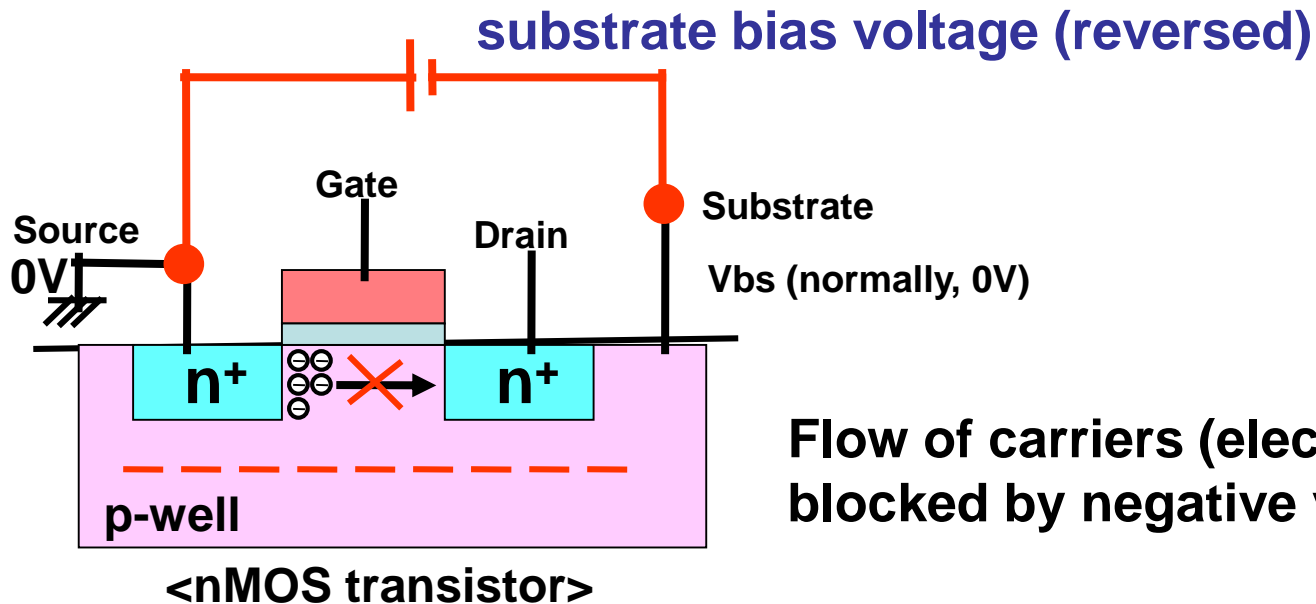


- ◆ V_{th} can be tuned during fabrication by ion implantation.
- ◆ Transistor with lower V_{th} is?

V_{th}, Important Parameter

V_{th} is determined by impurity concentration below gate oxide.
→ LSI designers cannot change its value?

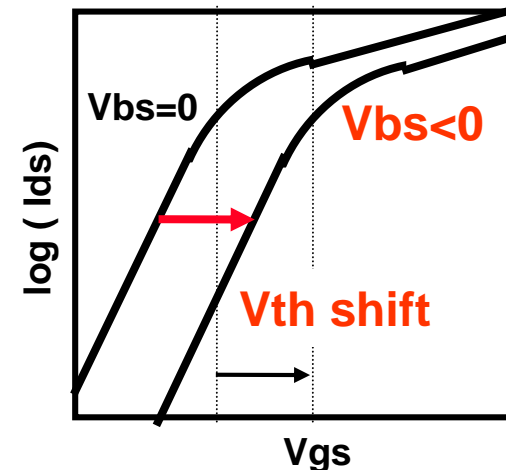
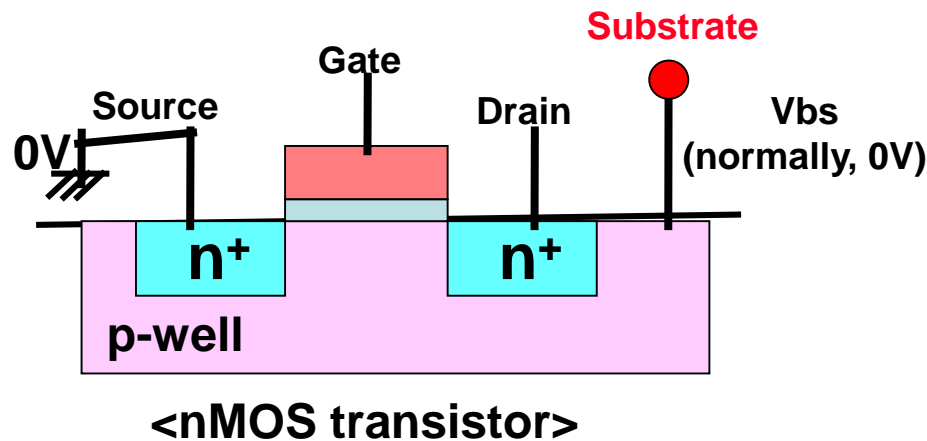
Yes, we can!



Flow of carriers (electron) is blocked by negative voltage.

Substrate Node Potential

- Electrical potential of substrate (formed by WELL structure) as 4th electrode also affects transistor characteristics.



< threshold voltage dependency on substrate voltage >

$$V_{th} = V_{t0} + k(\sqrt{-V_{bs} + 2\phi} - \sqrt{2\phi})$$

V_{t0}, k, φ: constants

BD002

Body Effect

<nMOS>

- * V_{bs} << 0, then ...?
- * speed, leakage...?

<pMOS>

- * V_{bs} >> 0, then ...?
- * speed, leakage...?



Short Quiz

<nMOS>

*** $V_{bs} \ll 0$, then ...?**

*** speed, leakage...?**

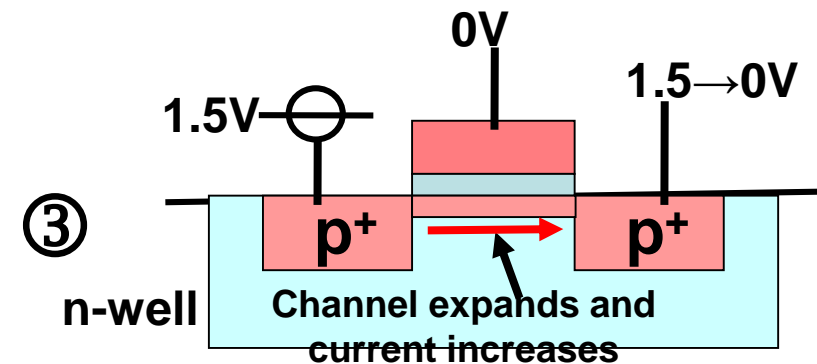
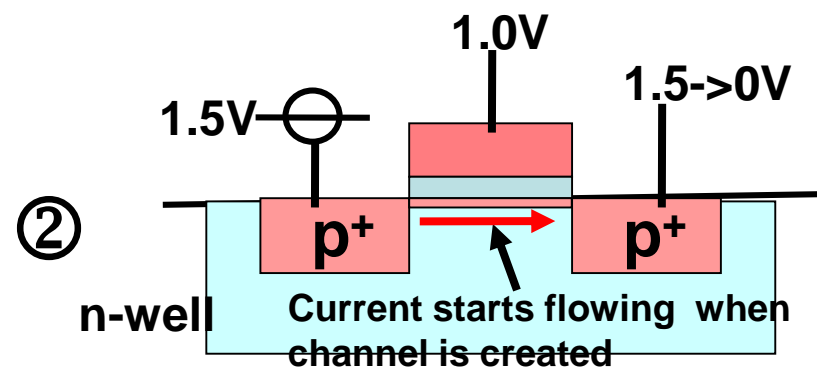
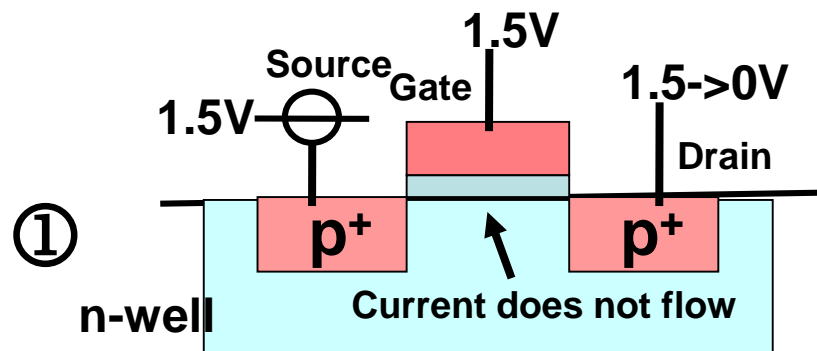
3.2 MOS Circuit Fundamentals

- nMOS Operation

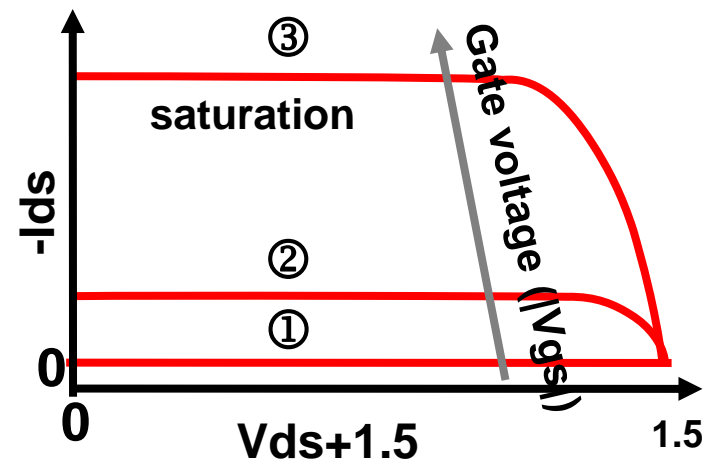
- pMOS Operation

- CMOS Structure

Operations of pMOS Transistor



<Current characteristics>



<Formula of current>

$$I_{ds} = \begin{cases} -\beta_p \{2V_{ds} \cdot (V_{gs} - V_{thp}) - V_{ds}^2\} & (\text{when } V_{gs} - V_{thp} \leq V_{ds} \leq 0) \\ -\beta_p (V_{gs} - V_{thp})^2 & (\text{when } V_{ds} < V_{gs} - V_{thp}) \end{cases}$$

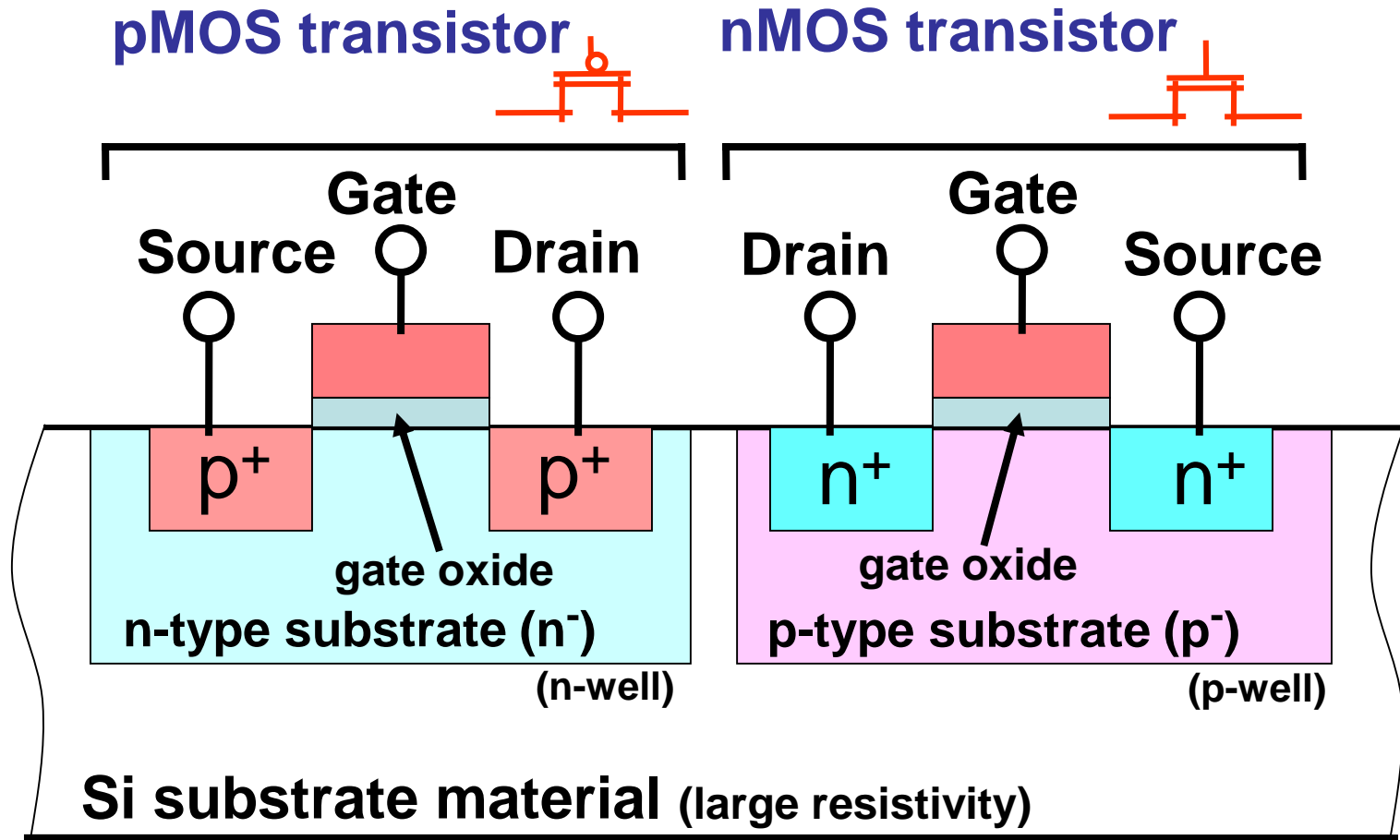
β_p : proportionality coefficient

V_{thp} : threshold voltage (gate voltage required to switch ON transistor)

3.2 MOS Circuit Fundamentals

- nMOS Operation
- pMOS Operation
- **CMOS Structure**

Structure of CMOS Transistor



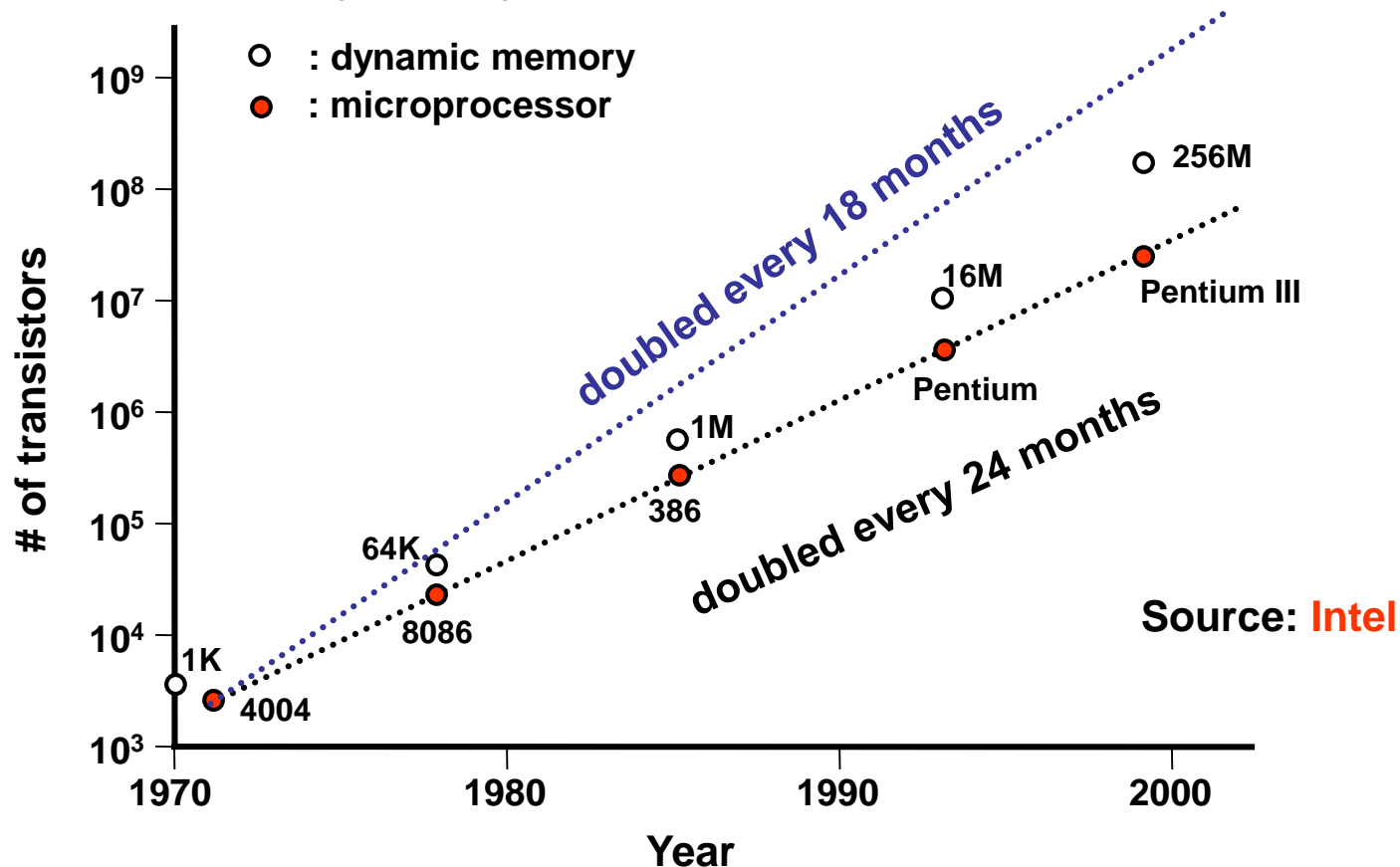
MOS: Metal-Oxide Semiconductor
CMOS: Complementally MOS

3.3 Scaling

- **Moore's Law**
- **Scaling Rule**

Moore's Law

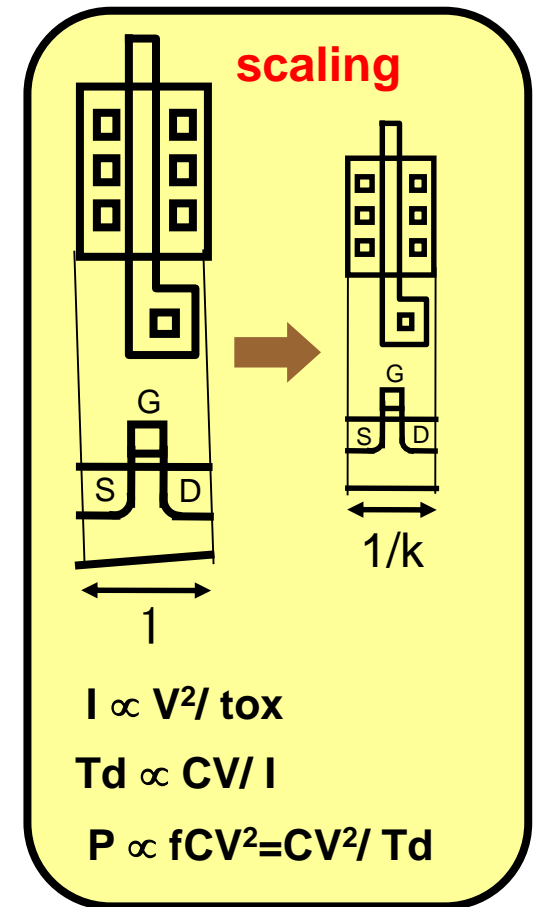
Gordon Moore predicted that the number of transistors that could be inexpensively placed on an IC chip would be doubled every 1.5-2 years.



Scaling Rule

k: scaling factor

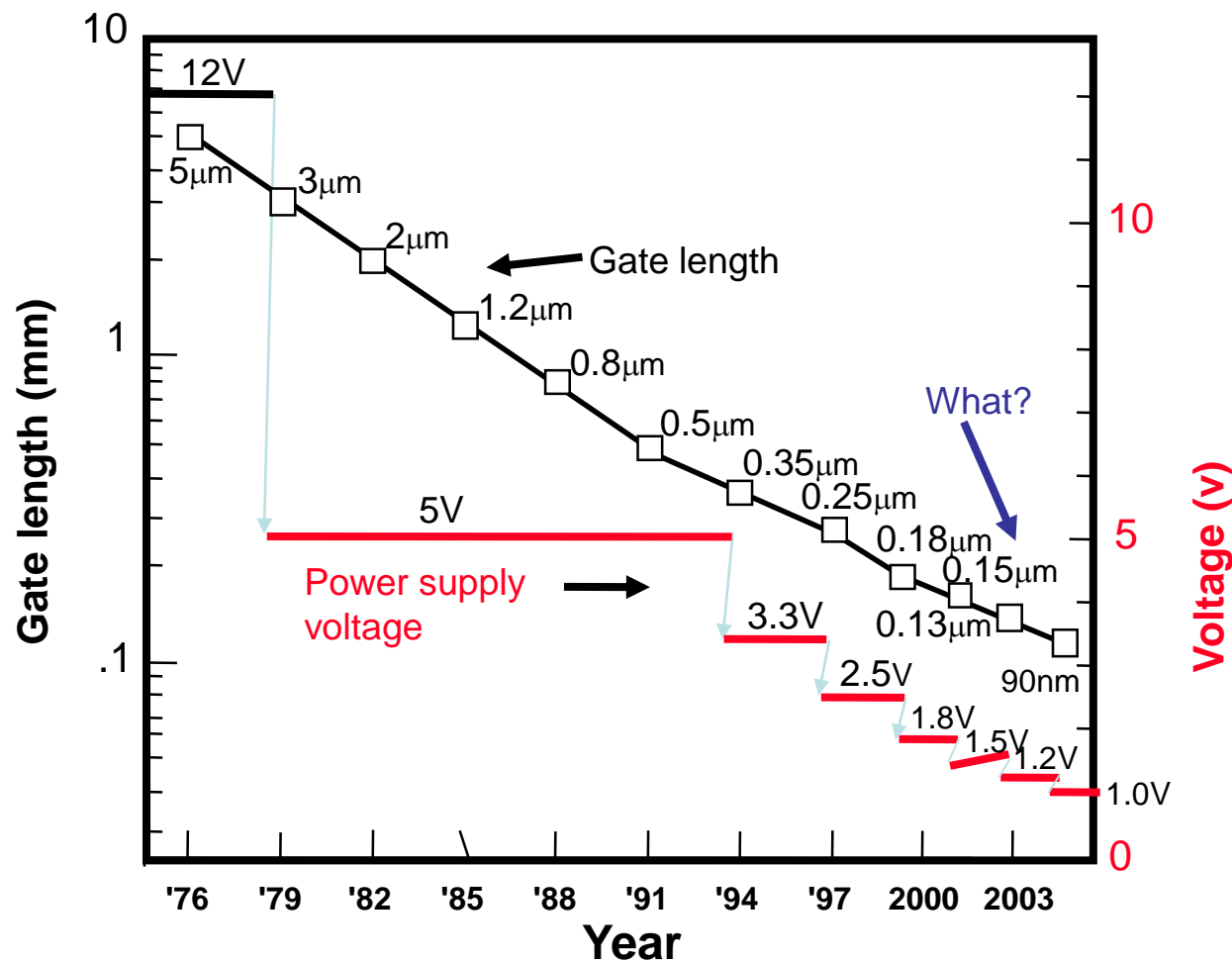
	To keep voltage constant (Old)	To keep electric field Constant (Now)
One side of length (X)	1/k	1/k
Gate oxide thickness (tox)	1/k	1/k
Power supply voltage (V)	1	1/k
Electric field strength (E)	k	1
Electric current (I)	k	1/k
Capacity (C)	1/k	1/k
Delay time (Td)	1/k ²	1/k
Power consumption (P)	k	1/k ²
Power density (P/X ²)	k ³	1



- ◆ The effects of scaling are prominent in establishing high speed, low power consumption, and high density.
- ◆ Till now, these effects have been realized by continuously developed process generations.

Success history of semiconductor development !!
However...

Trend of Power Supply Voltage vs. Scaling



➡ After 0.35 μm generation, power supply voltage has been reduced to maintain electric field constant in gate oxide.

Limitation on Scaling Rule

1. Some items are not fully scaled

L: 1.0 μ m \rightarrow 0.06 μ m (1/17)

Tox: 20nm \rightarrow 1.5nm (1/13)

Vdd: 5V \rightarrow 1.2V (1/4)

2. Driveability

I: 1/k

I/W: 1

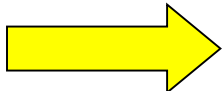
3. Unscalable factors

Vth

(S factor)

(Surface potential....)

BD002



Short Channel Effect becomes glaring

Short Channel Effect

Sub-threshold

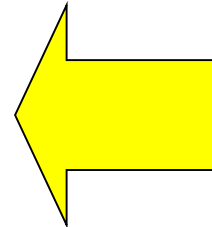
$I_d = 0$ (nearly)

Linear region

$$I_d = \frac{W}{L} \mu C_{ox} \left\{ (V_g - V_{th}) V_d - \frac{1}{2} V_d^2 \right\}$$

Saturation region

$$I_d = \frac{W}{2L} \mu C_{ox} (V_g - V_{th})^2$$



“L” becomes shorter

BD002

1. Increase in off state leakage current

- V_{th} decrease (roll off)
- S factor increase (slack of I_{ds} - V_{gs} curve)
- V_{th} is varied by drain voltage (V_{th} decrease)

2. I_{ds} does not increase in proportion to $1/L$

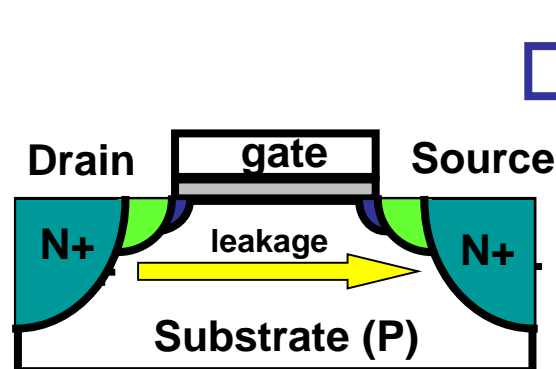


How to prevent?



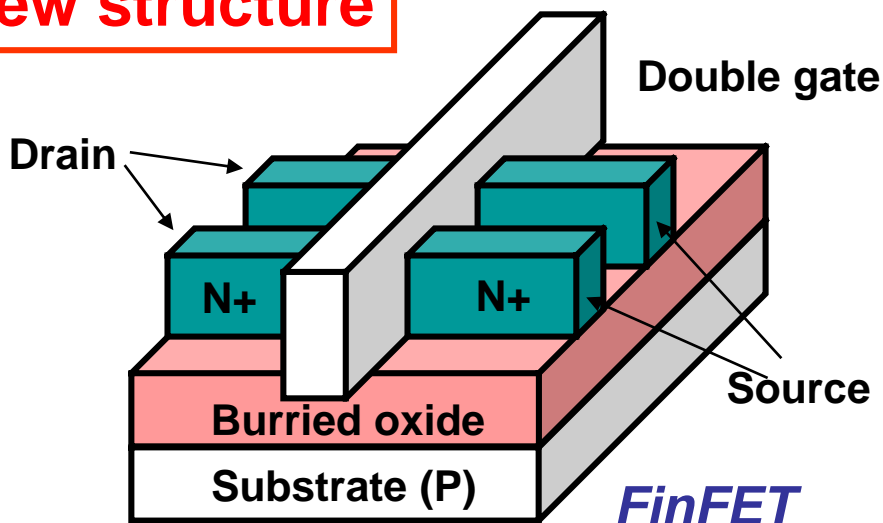
Non-classical CMOS

<More Moore>



bulk MOSFET

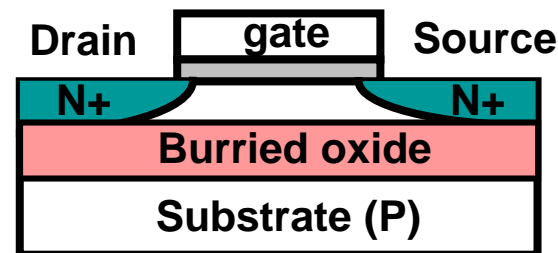
New structure



FinFET

New material

- high-k metal gate (HKMG)
- strained silicon
- 110 wafer (surface orientation)

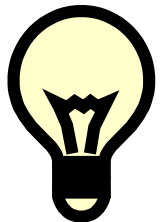


SOI MOSFET

SOI (Silicon On Insulator)

Summary of MOS Transistor

- Characteristics of nMOS and pMOS transistors are **symmetrical**, and polarity of signals is opposite.
- I_{ds}/V_{ds} curves are divided into **linear** and **saturation** regions, where their boundary is **$V_{ds} = V_{gs} - V_{th}$** .
- I_{ds}/V_{gs} curve is divided into normal and **sub threshold** regions, where boundary is **$V_{gs} = V_{th}$** .
- V_{th} determines max I_{ds} and leakage current: faster but leakier.
- Substrate node acts as 4th terminal, and affects V_{th} .
- Scaling has been success story of semiconductor with reduction of power supply voltage.
- But now, more Moore.



3.4 Basic CMOS Logic Circuits

➤ Inverter

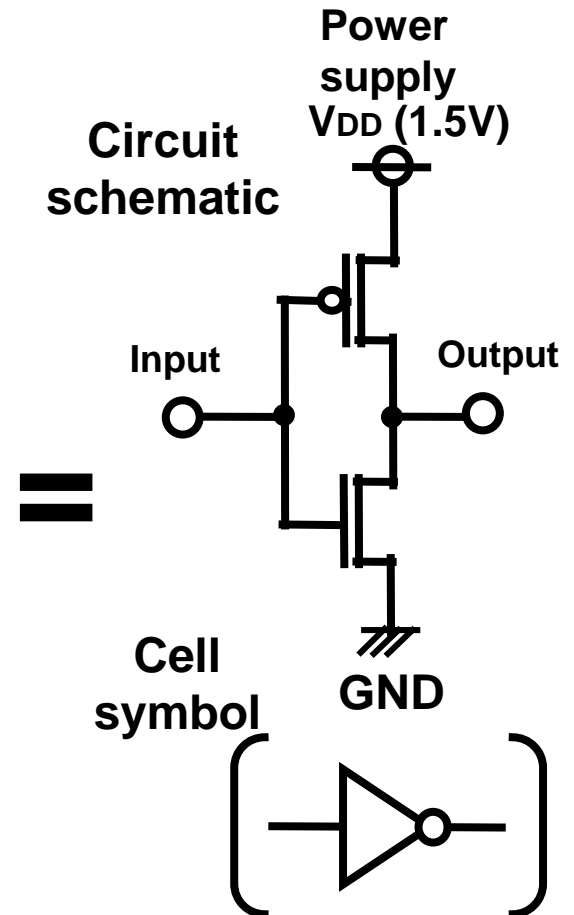
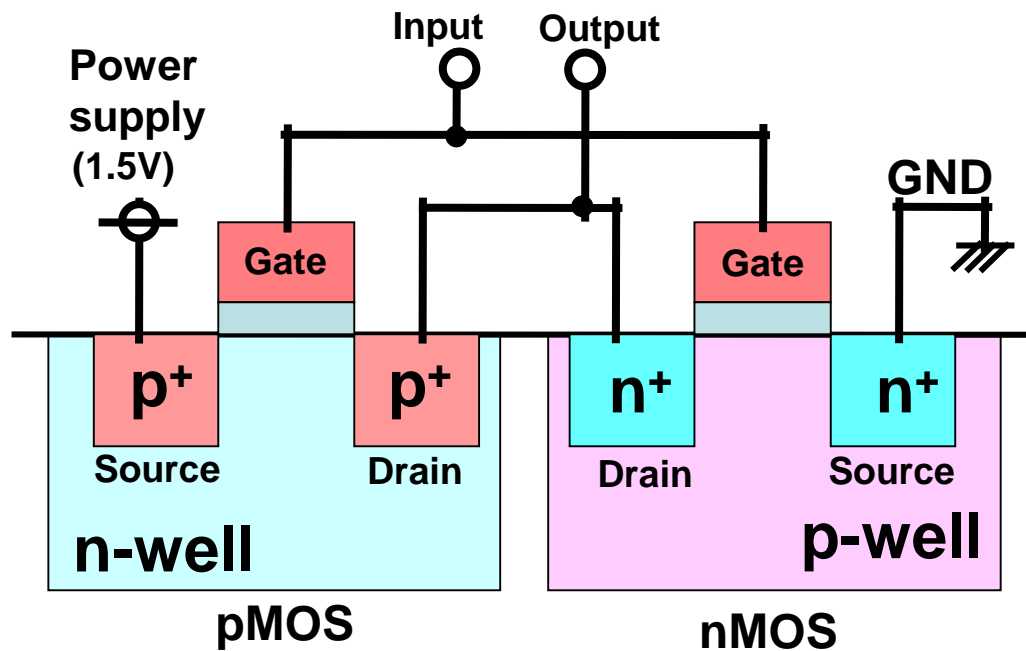
- Delay time
- Power consumption

➤ Logic gate

➤ Logic Block

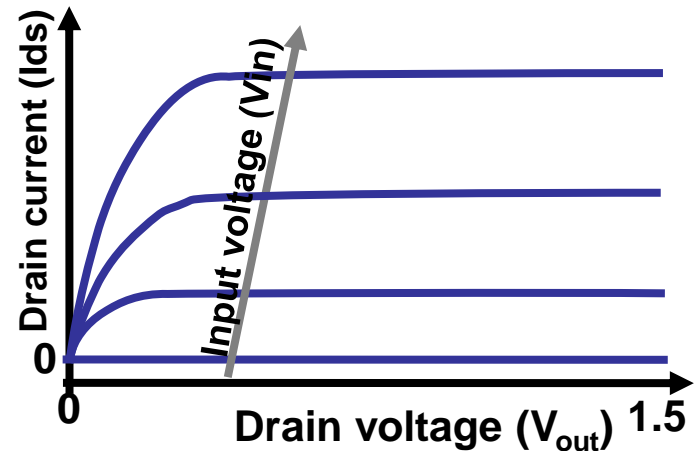
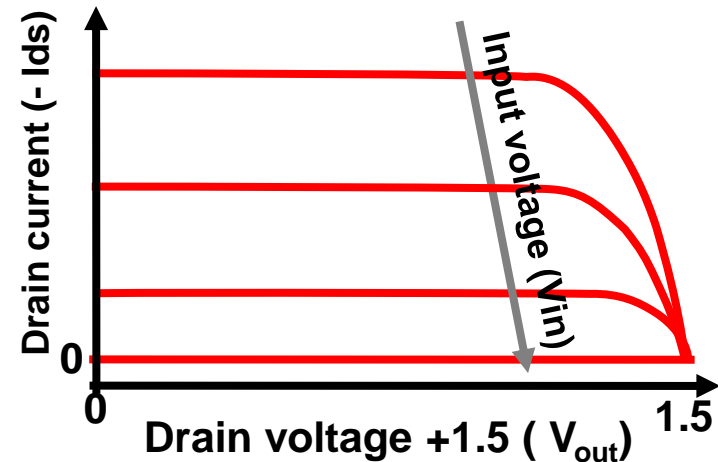
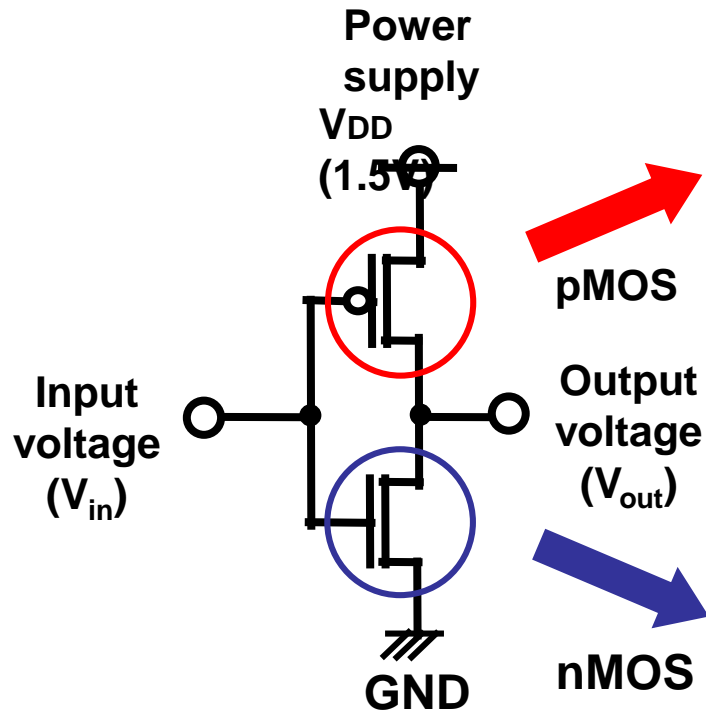
Inverter

<CMOS inverter Structure >



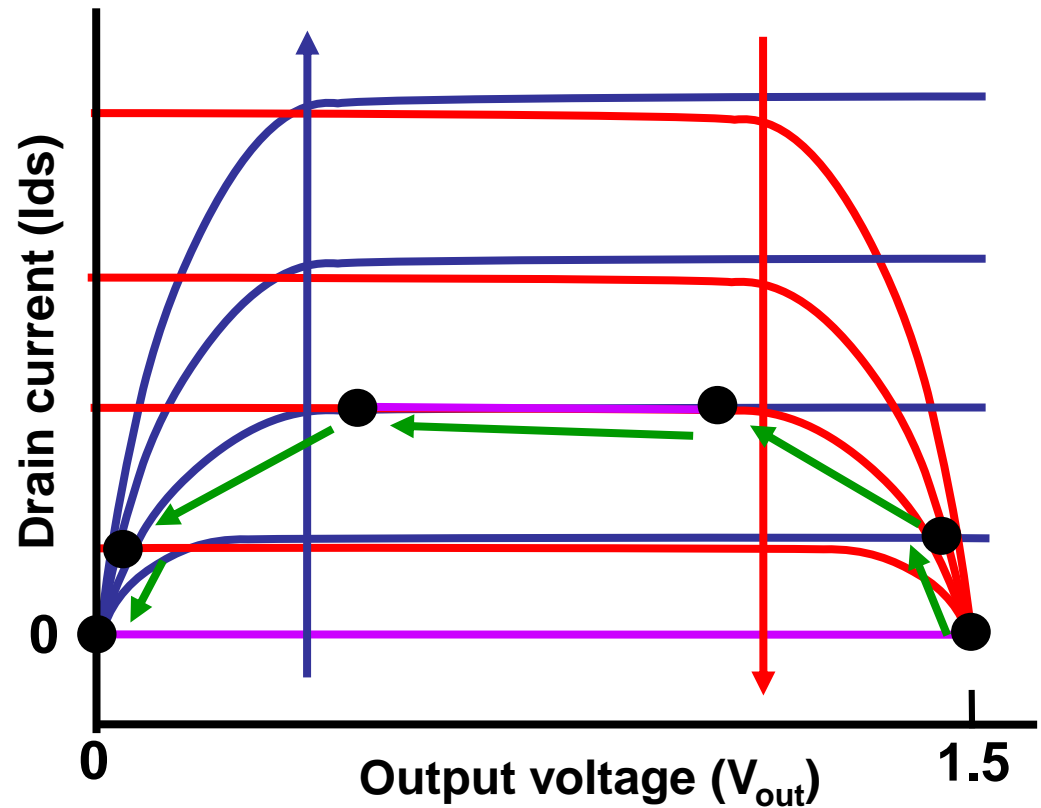
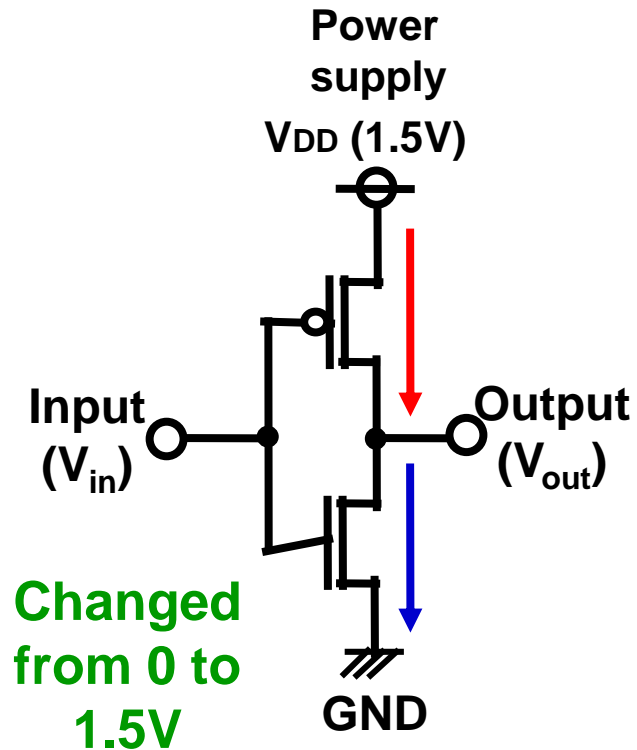
Simplest logic circuit with a pair of pMOS and nMOS transistors

Current Characteristics



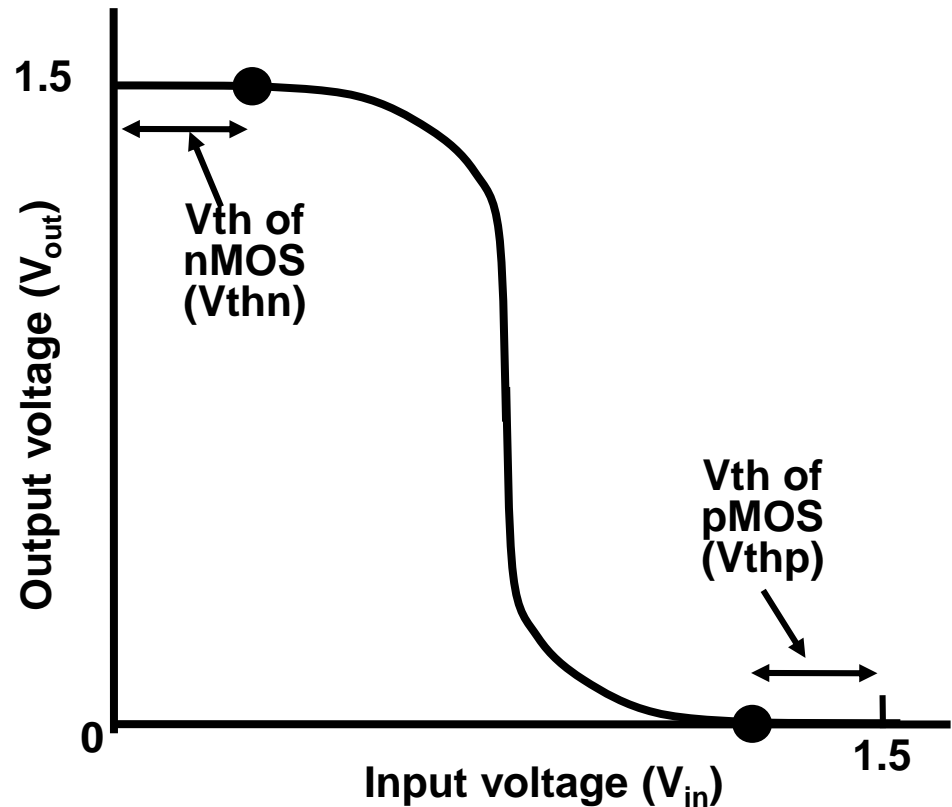
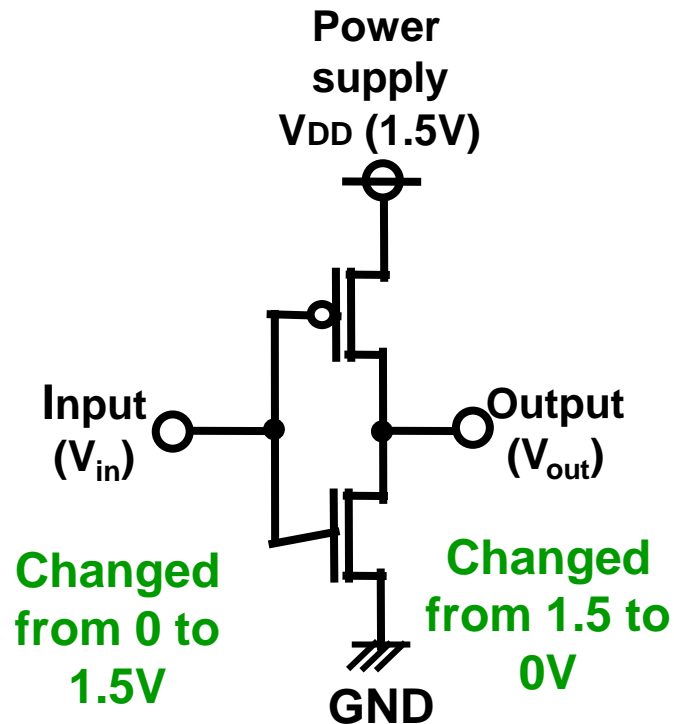
Inverter characteristics are defined by current characteristics of both transistors.

Behavior



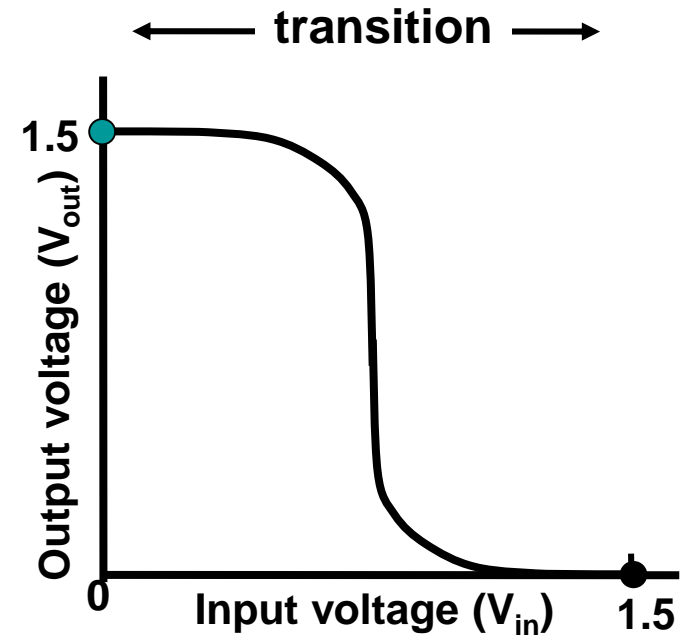
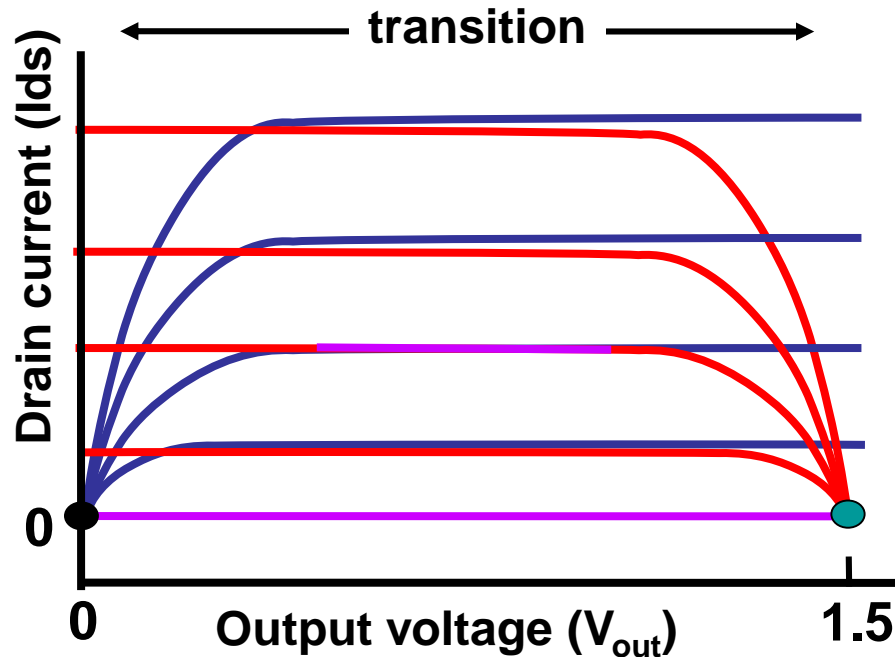
Output voltages (V_{out}) are determined by intersection points (● mark) of pMOS and nMOS current curves.

I/O Characteristics



Signal logically inverted from input appears at output: inverter

Merits of CMOS Inverter



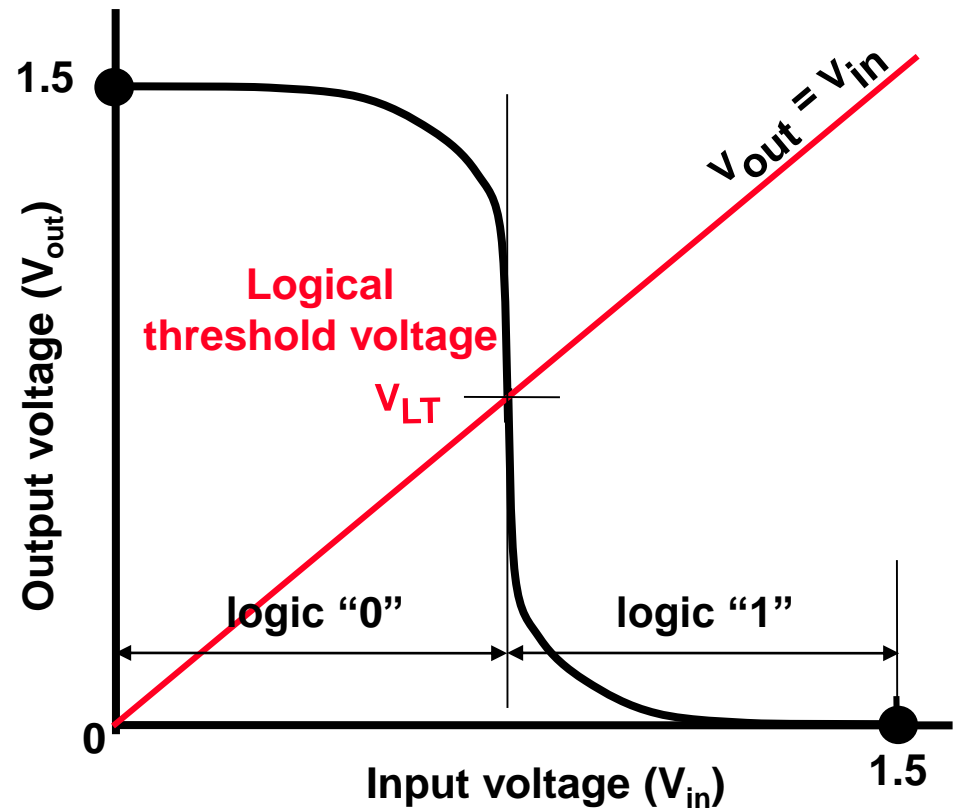
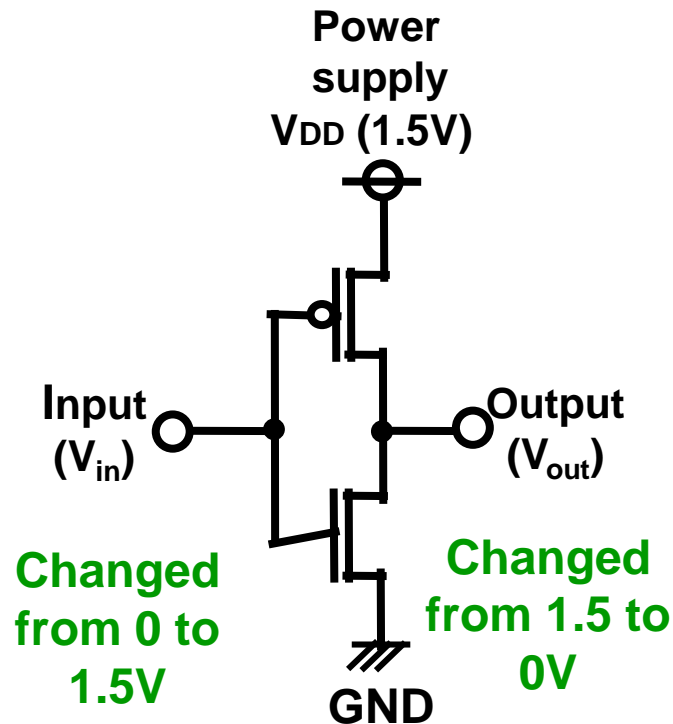
● and ● : steady state

Complementary Operation

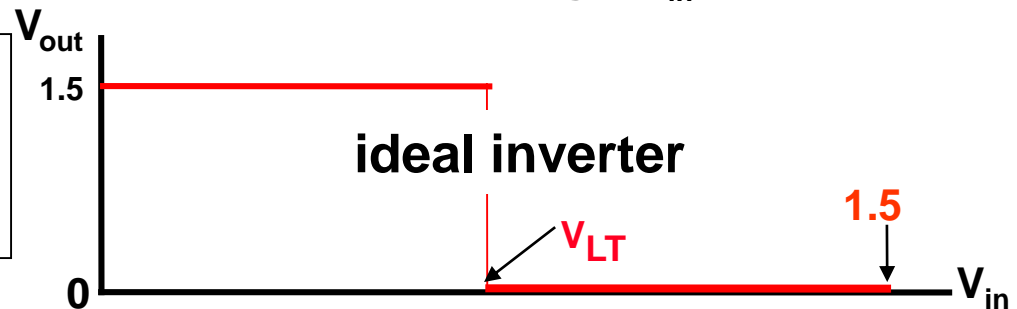
Either nMOS or pMOS is ON in steady state: no direct current flow. Input and output voltages swing from 0 to 1.5v (V_{DD}).



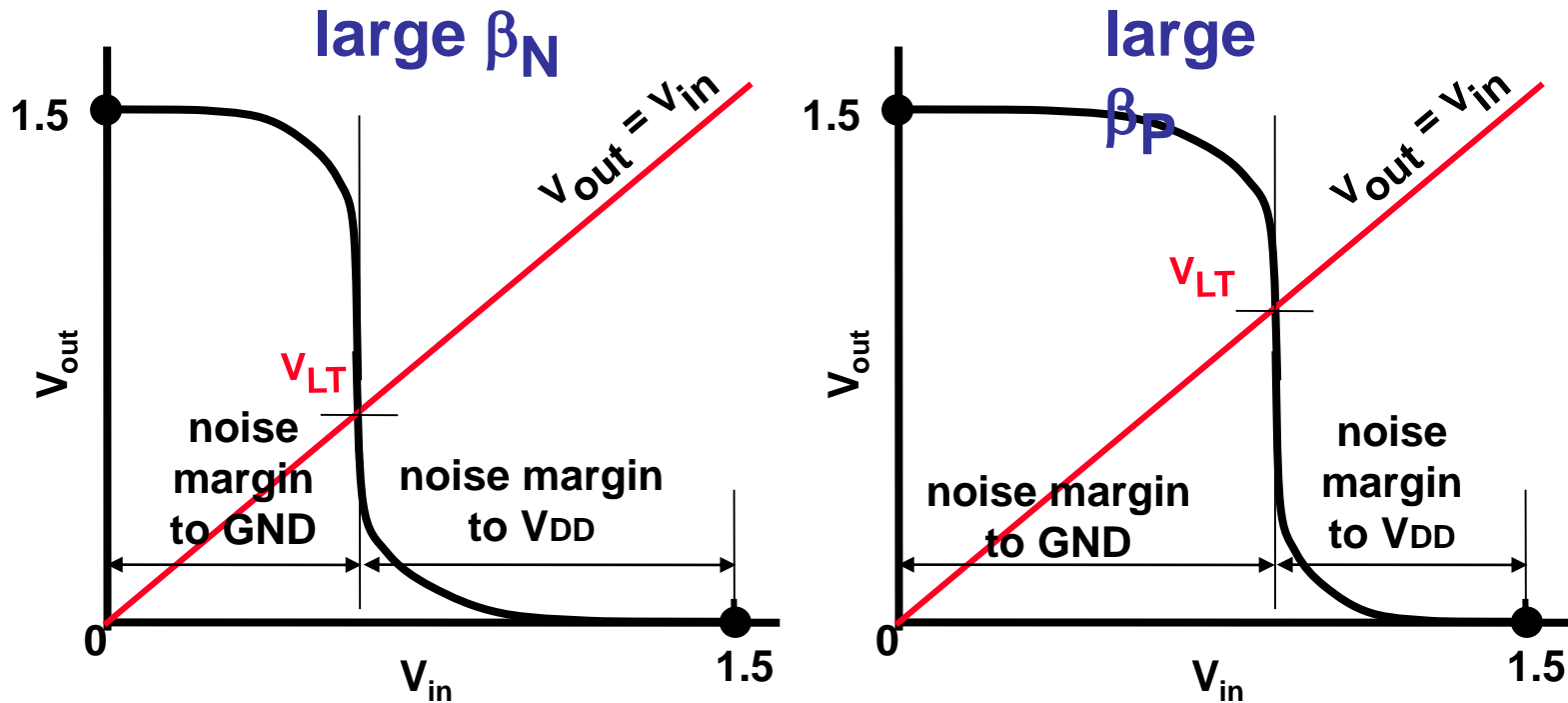
Logical Threshold Voltage



$V_{in} < V_{LT}$:
Inverter acknowledges input=logic0.
 $V_{in} > V_{LT}$:
Inverter acknowledges input=logic1.



Noise Margins



To set logical threshold voltage of each gate at the same level is important to **secure noise margin**: $V_{LT} = V_{DD}/2$

Features of CMOS Circuit

Advantage

- (1) Low power dissipation
 - (2) Wide operating voltage range
 - (3) Large noise margin
 - (4) Wide operating temperature
-

Disadvantage

- (1) Subject to Latch up
- (2) Complicated wafer process
- (3) Large device area



**Let's take a 10-minutes
BREAK**

3.4 Basic CMOS Logic Circuits

- Inverter

- Delay time
 - Power consumption

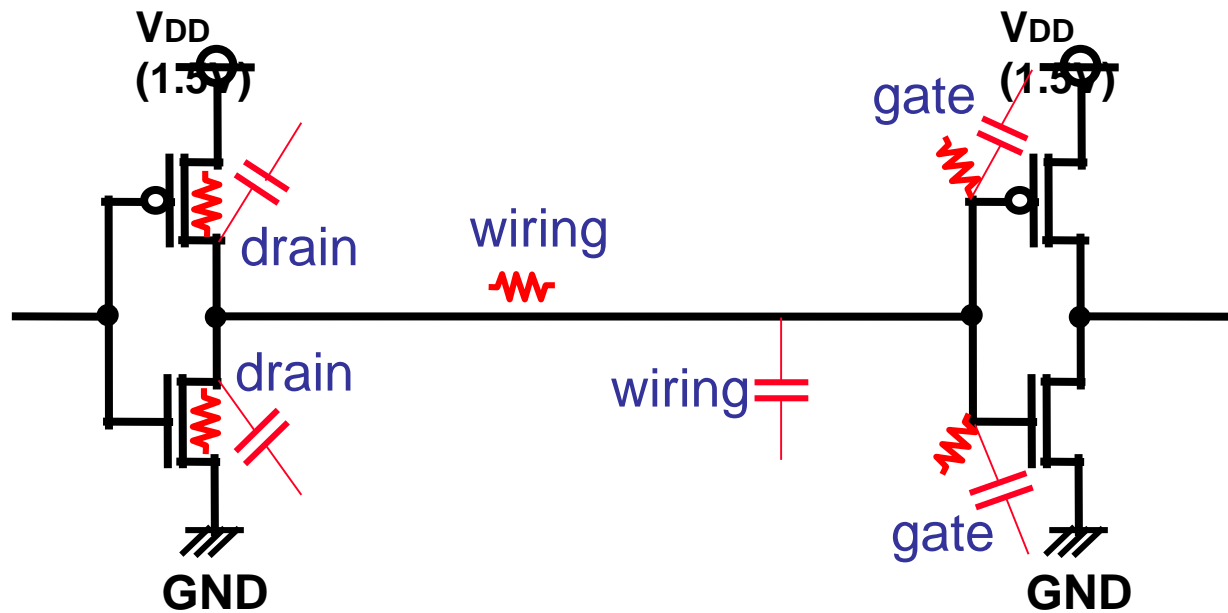
- Logic gate

- Logic Block

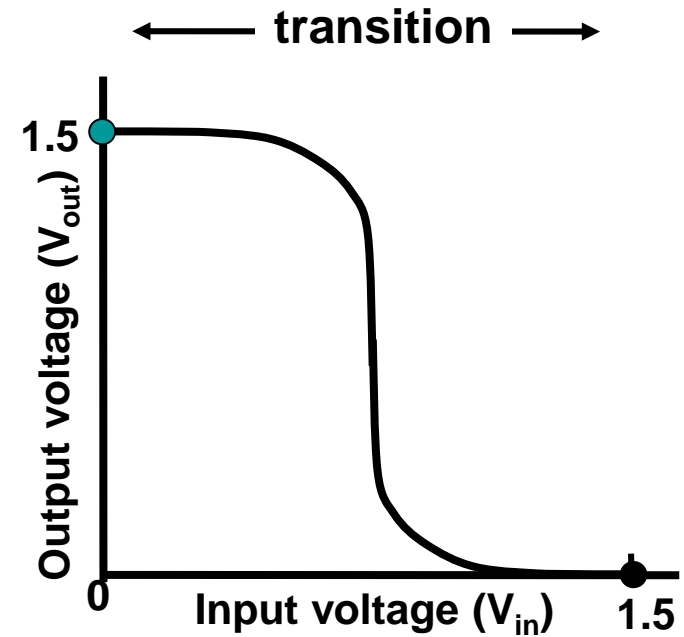
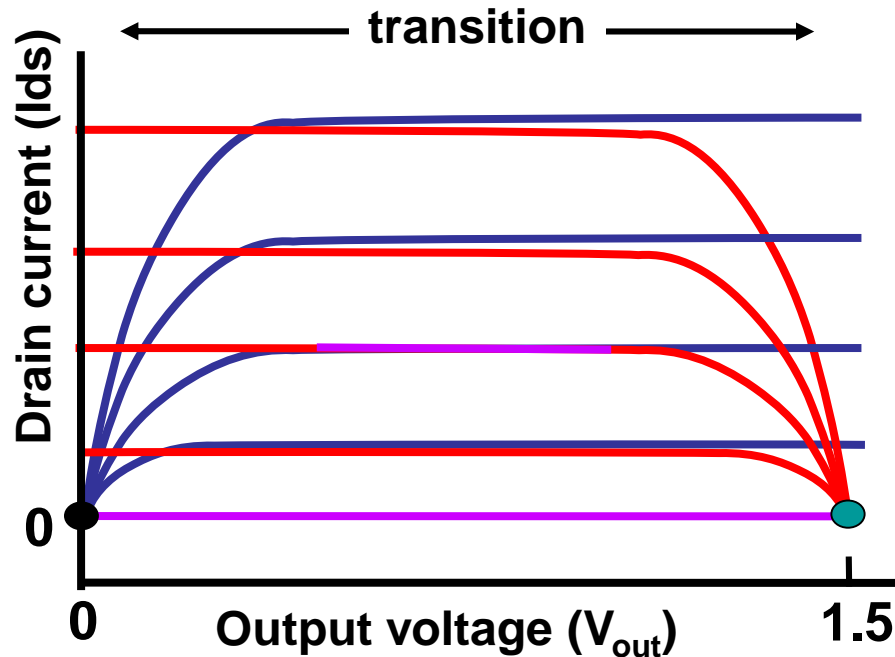
Circuit Model

- for estimating **delay time** and **power consumption** -

An inverter chain with parasitic devices will be investigated.



Merits of CMOS Inverter



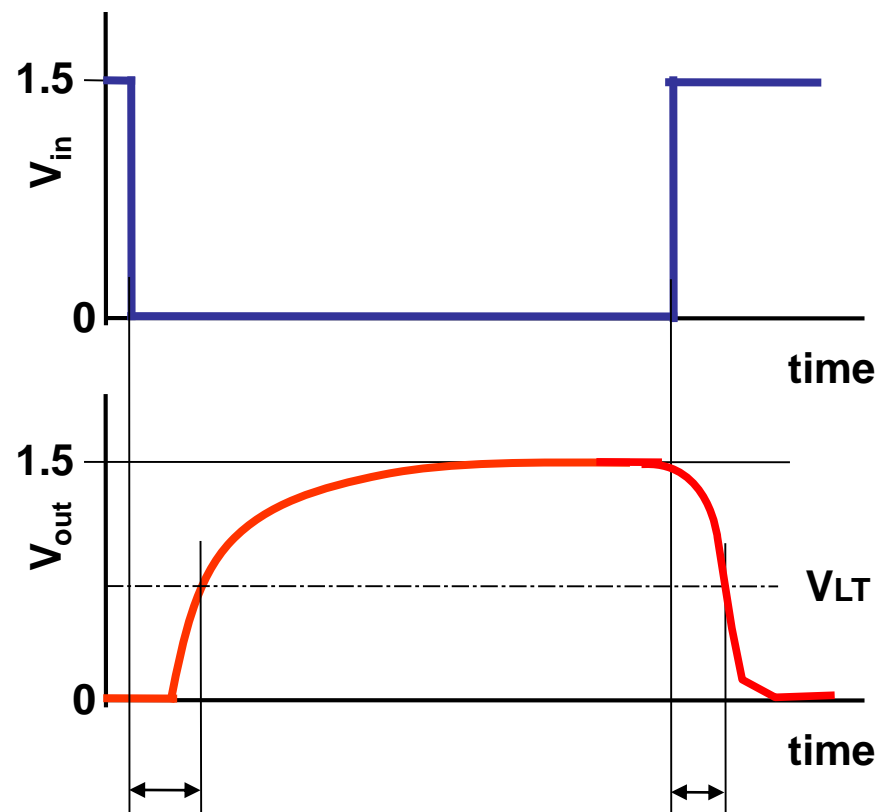
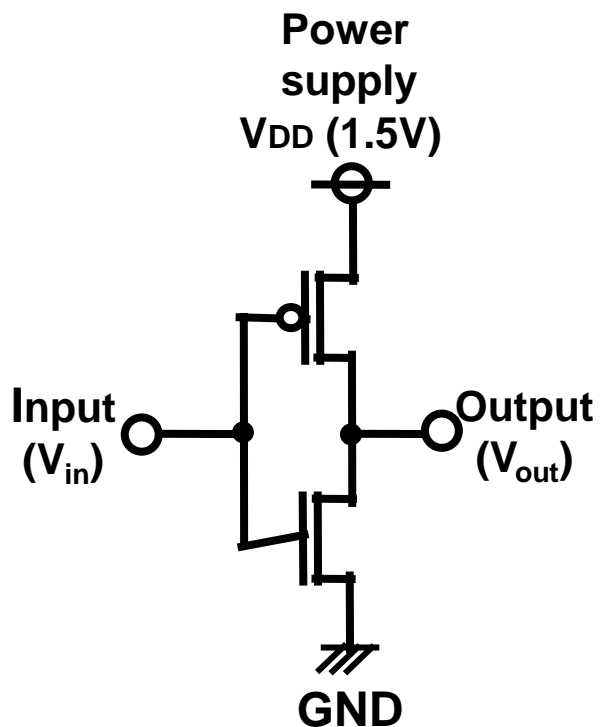
● and ● : steady state

$$I_d = \frac{W}{L} \mu C_{ox} f(V_d, V_g)$$

for both nMOS and pMOS

- time-varying functions
- multi-dimensional differential equations

Delay Time

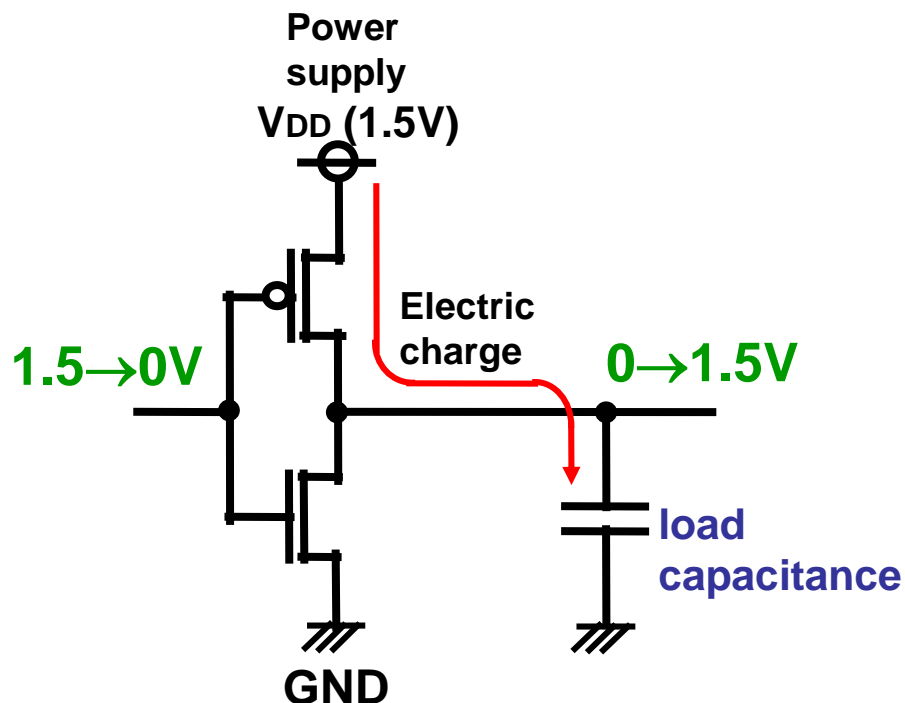


Delay time (rising)

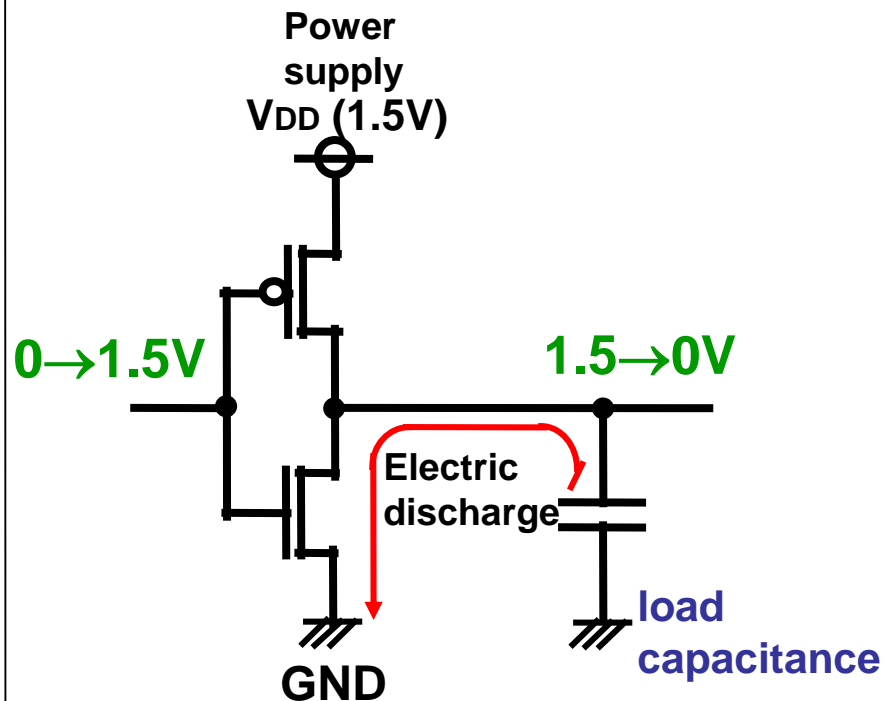
Delay time (falling)

Propagation delay time

< Propagation of "1→0" >



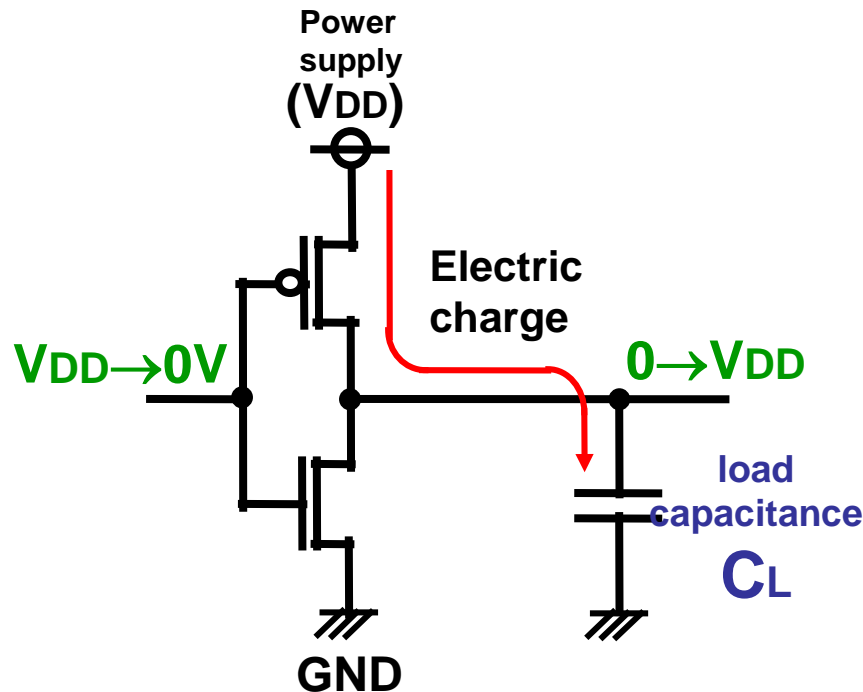
< Propagation of "0→1" >



- ◆ Electric charging / discharging at load capacitance take time: delay is caused.
- ◆ Load capacitance : stray capacitance of wiring, junction capacitance at drains, gate capacitance of succeeding circuit

Delay Time for Charging

< “1→0” propagation >



◆ Current flows when pMOS is ON,

$$I_{ds} = -\beta_p \cdot (-V_{DD} - V_{thp})^2 \\ = -\beta_p \cdot (V_{DD} - |V_{thp}|)^2$$

◆ Electric charge to be charged

$$Q = C_L \cdot V_{DD}$$

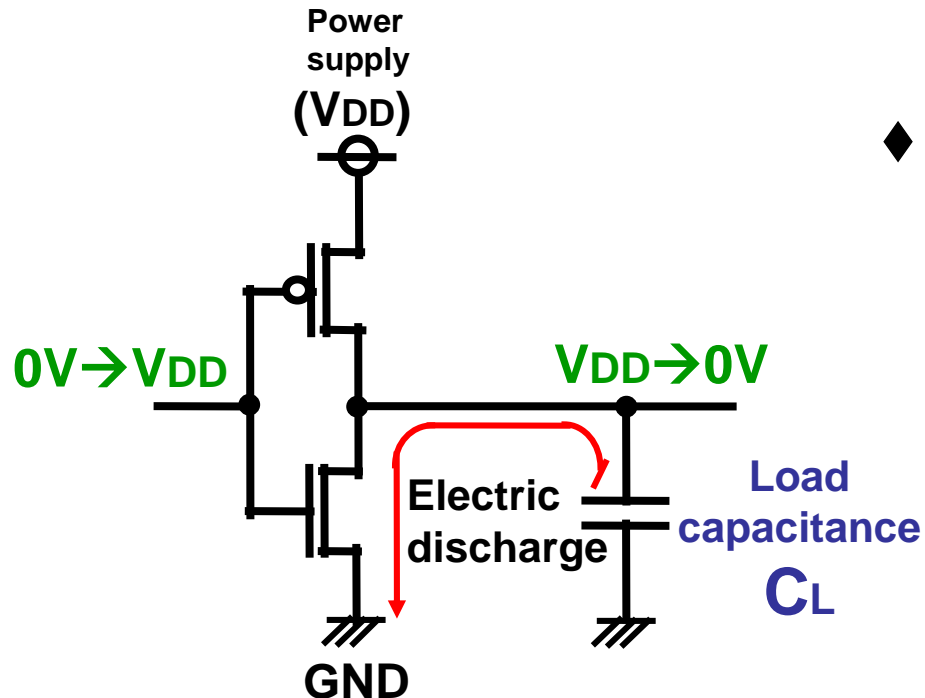
Delay time is

$$T_d = Q / |I_{ds}|$$

$$= \frac{C_L \cdot V_{DD}}{\beta_p \cdot (V_{DD} - |V_{thp}|)^2}$$

Delay Time for Discharging

< “0→1” propagation >



◆ Current flows when nMOS is ON,
 $I_{ds} = \beta_n \cdot (V_{DD} - V_{thn})^2$

◆ Electric charge to be discharged
 $Q = C_L \cdot V_{DD}$



Delay Time is,

$$T_d = Q / I_{ds}$$

$$= \frac{C_L \cdot V_{DD}}{\beta_n \cdot (V_{DD} - V_{thn})^2}$$

Summary of Delay Time

$$T_d = \begin{cases} \frac{C_L \cdot V_{DD}}{\beta_p \cdot (V_{DD} - |V_{thp}|)^2} & \text{: rising} \\ \frac{C_L \cdot V_{DD}}{\beta_n \cdot (V_{DD} - V_{thn})^2} & \text{: falling} \end{cases}$$

- ◆ Faster, if load capacitance C_L is smaller
- ◆ Faster, when power supply voltage, V_{DD} is higher
- ◆ Faster, if $|V_{th}|$ is smaller
- ◆ Faster, if β is greater

$$\beta = \mu \cdot C_{ox} \cdot W / 2L$$

Mobility

Capacity of gate oxide

- ◆ Faster, if gate length L is shorter
- ◆ Faster, if gate width W is wider

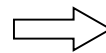
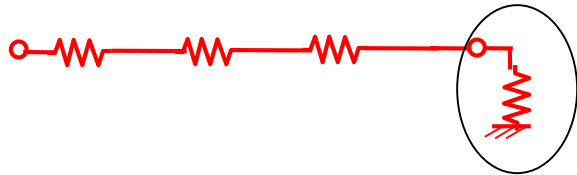
But min. L exists!



Further Disturbances

Influence of R, C and L

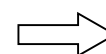
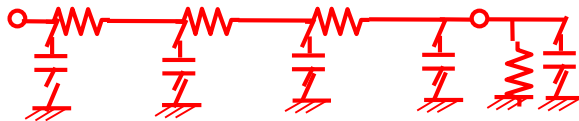
R



Voltage drop

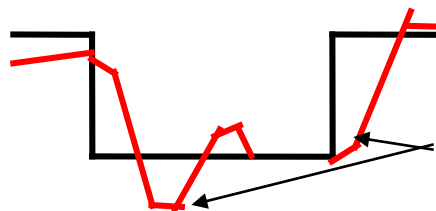
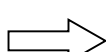
IR drop

+C

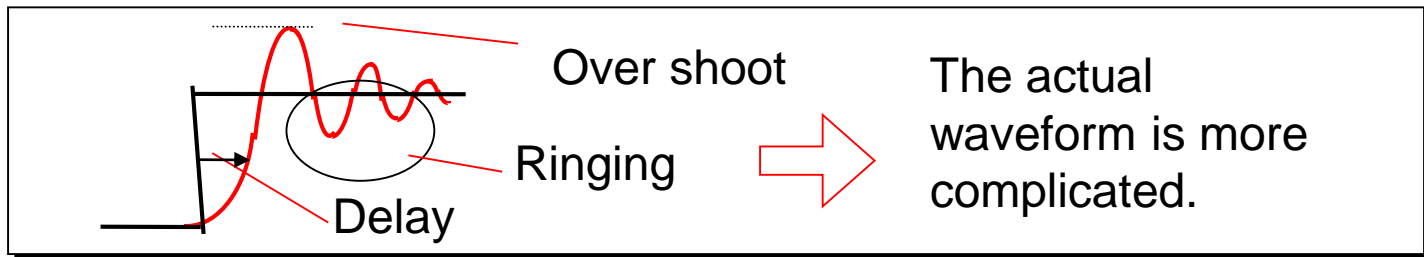


slowdown
wiring delay

+L



Oscillation
(further delay)



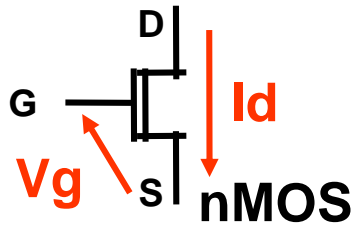
3.4 Basic CMOS Logic Circuits

Afternoon Section

- Review morning Section – Q&A
- Inverter
 - Delay time
 - **Power consumption**
- Logic gate
- Logic Block

Review Morning Section – Q&A

Exercise 1



Linear region ($0 \leq V_d \leq V_g - V_{th}$)

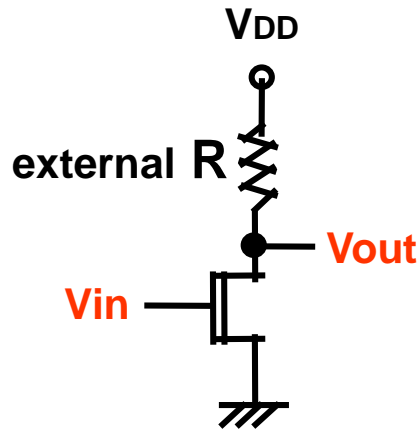
$$I_d = \frac{W}{L} \mu C_{ox} \left\{ (V_g - V_{th}) V_d - \frac{1}{2} V_d^2 \right\}$$

Saturation region ($V_d > V_g - V_{th}$)

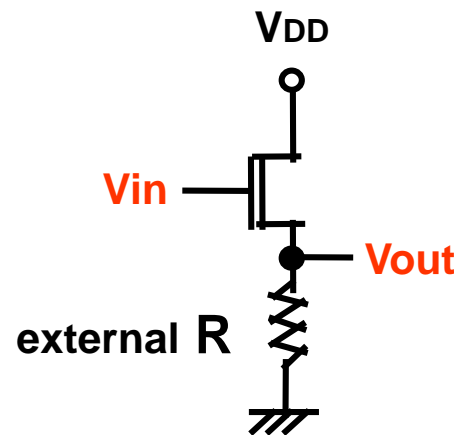
$$I_d = \frac{W}{2L} \mu C_{ox} (V_g - V_{th})^2$$

$$\alpha = \mu C_{ox} W / 2L$$

Vin is connected to Vdd, and R becomes infinity, then Vout = ?



Vout =



Vout =

Power Consumption

- ◆ Actual LSI power consumption is time variant, but generally represented by its **average value**. This is important figure for longer battery shutoff time.
- ◆ Breakdown of average power consumption P:

$$P = P_{dynamic} + P_{SC} + P_{leak}$$

$P_{dynamic}$: Dynamic power

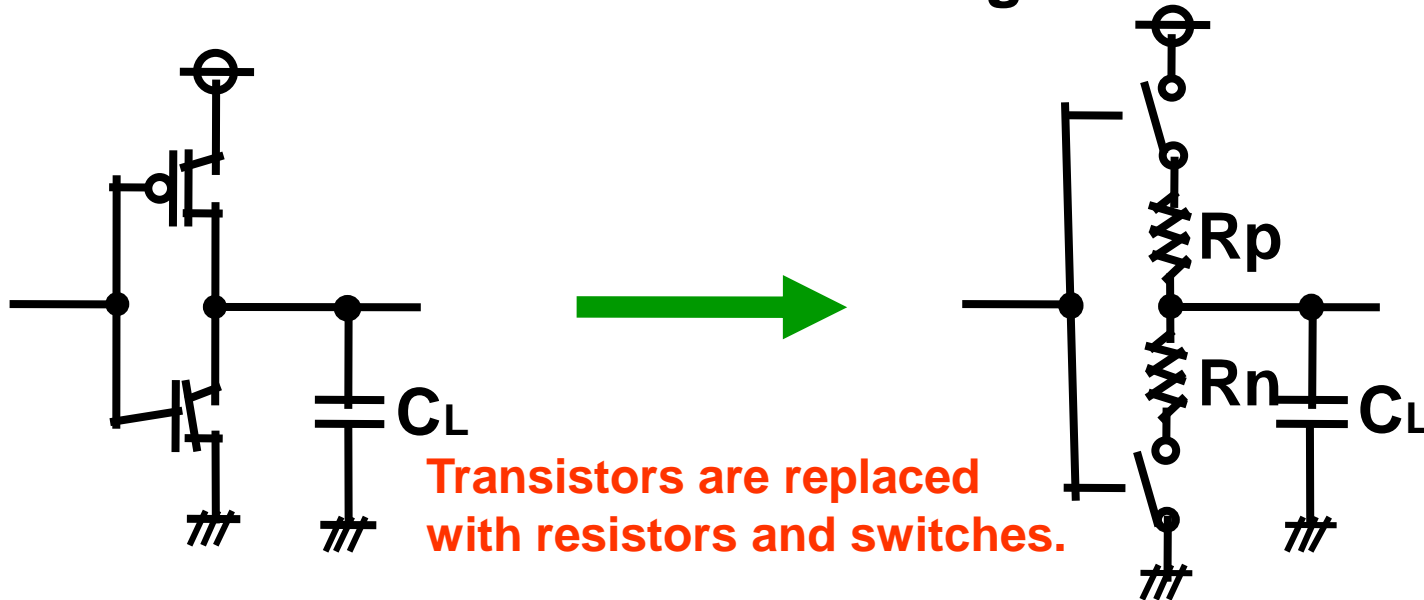
P_{SC} : Short Circuit power

P_{leak} : Leakage power

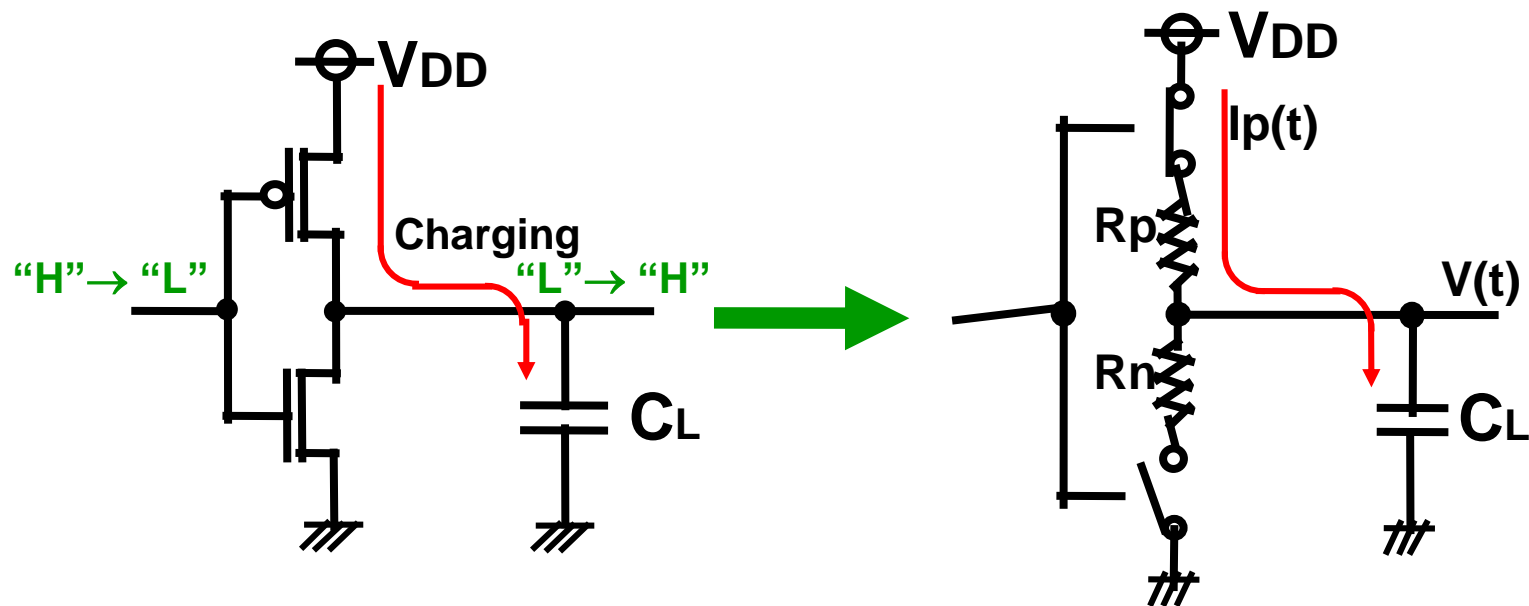
- ◆ Start from simple inverter case

Dynamic power

- ◆ Power consumption due to charging and discharging of load capacitance
- ◆ Basically IV , I^2R , V^2/R are represented by functions of time.
 - The following simplified, computational model is used to obtain average value of time



Charging



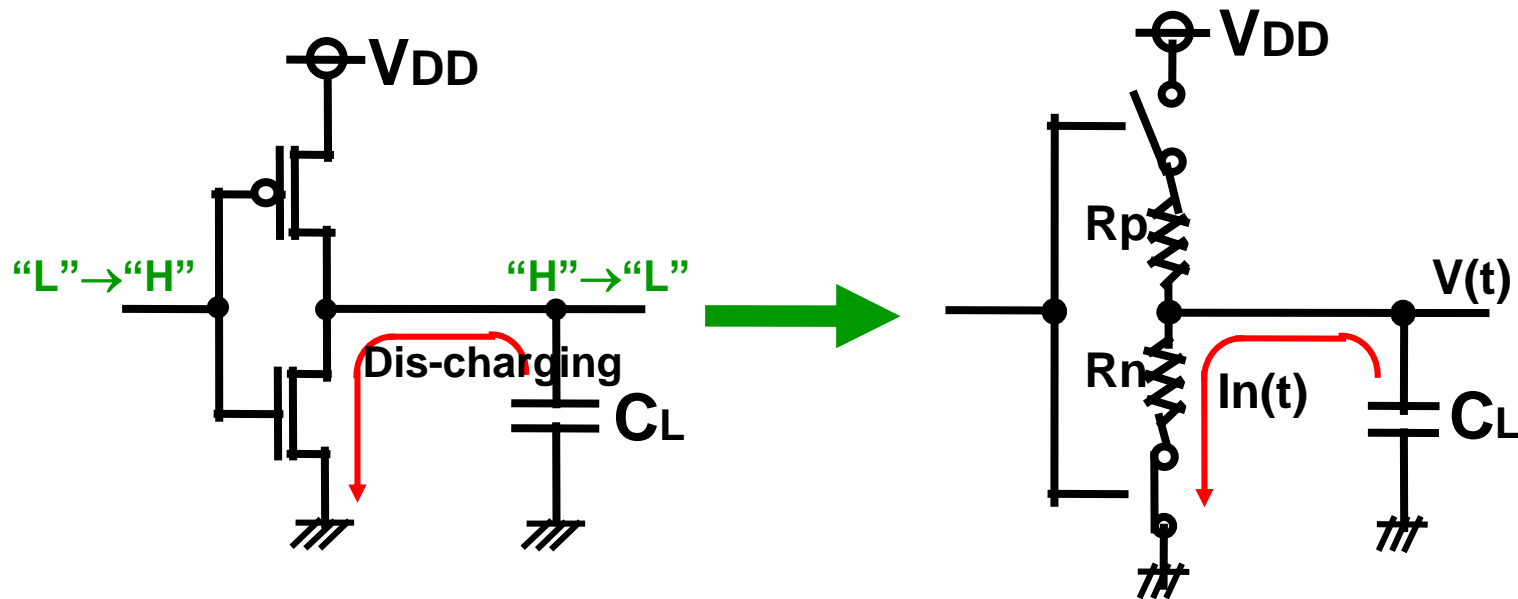
$$C_L \frac{dV}{dt} = I_P$$

Power = $(V_{DD} - V) \cdot I_P$: function of time

$$\begin{aligned} \text{Energy} &= \int_{t=0}^{\infty} (V_{DD} - V) \cdot I_P dt = \int_{V=0}^{V_{DD}} C_L \cdot (V_{DD} - V) dV \\ &= \frac{1}{2} C_L \cdot V_{DD}^2 \end{aligned}$$

← R_p independent

Discharging



$$-C_L \frac{dV}{dt} = I_n$$

Power = $V \cdot I_n$: function of time

$$\begin{aligned} \text{Energy} &= \int_{t=0}^{\infty} V \cdot I_n dt = \int_{V=V_{DD}}^0 -C_L \cdot V dV \\ &= \frac{1}{2} C_L \cdot V_{DD}^2 \end{aligned}$$

← R_n independent

Dynamic Power of Inverter

- ◆ Energy consumed during **one cycle** of inverter toggle operation

$$\frac{1}{2}C_L \cdot V_{DD}^2 + \frac{1}{2}C_L \cdot V_{DD}^2 = \boxed{C_L \cdot V_{DD}^2}$$

(Charging energy) (Discharging energy)

Energy consumption of inverter is defined by power supply voltage and parasitic capacitance, irrespective of R_p and R_n resistors.

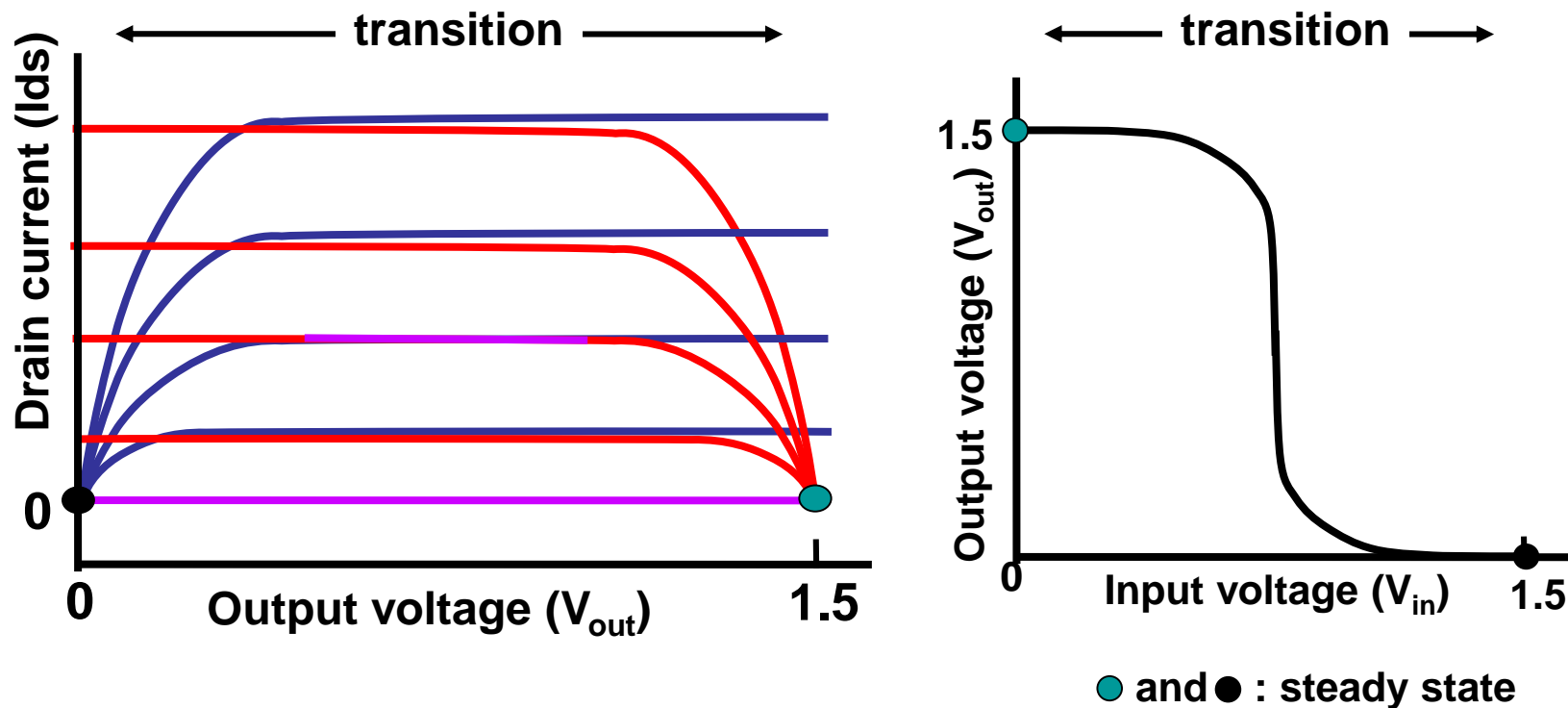
- ◆ Power consumption (= energy consumed in **1 second**)

Assuming inverter toggles f times in 1 second, thus average dynamic power is represented by $f \cdot C_L \cdot V_{DD}^2$



Although simplified equation, comprehend relation among dimensions.

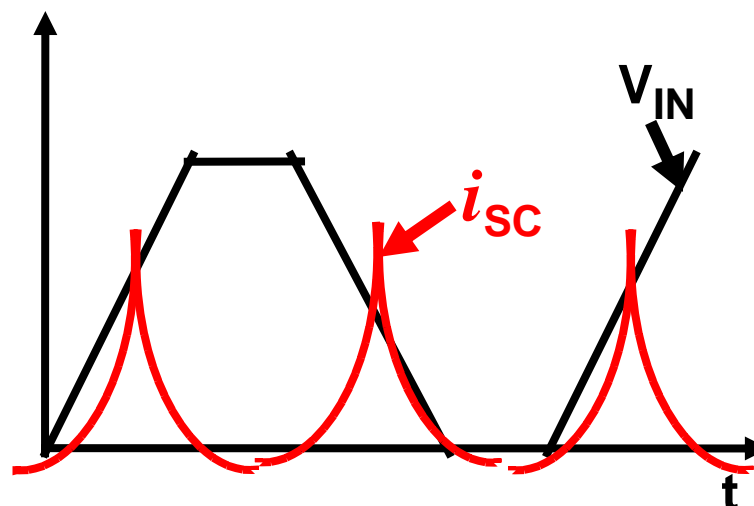
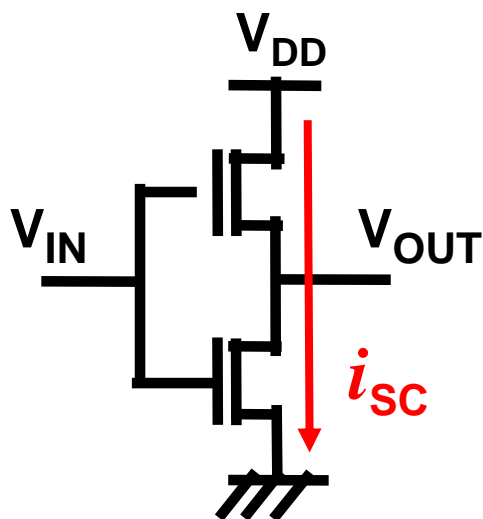
Complementary Operation (restudy)



Either nMOS or pMOS is ON in steady state: no direct current flow.
→ Complementary operation, **BUT, BUT, BUT!**
Input and output voltages swing from 0 to 1.5v (V_{DD}).

Short-Circuit Power

- ◆ When inverter switching occurs, inrush, **short circuit current** i_{SC} flows from V_{DD} to GND during state transition, which actually dissipates power.
- ◆ Short-circuit power remains 10~15% of overall power consumption, as long as circuits are designed so that their input transition time and output one are equal.
- ◆ Short-circuit power is proportional to operating frequency.



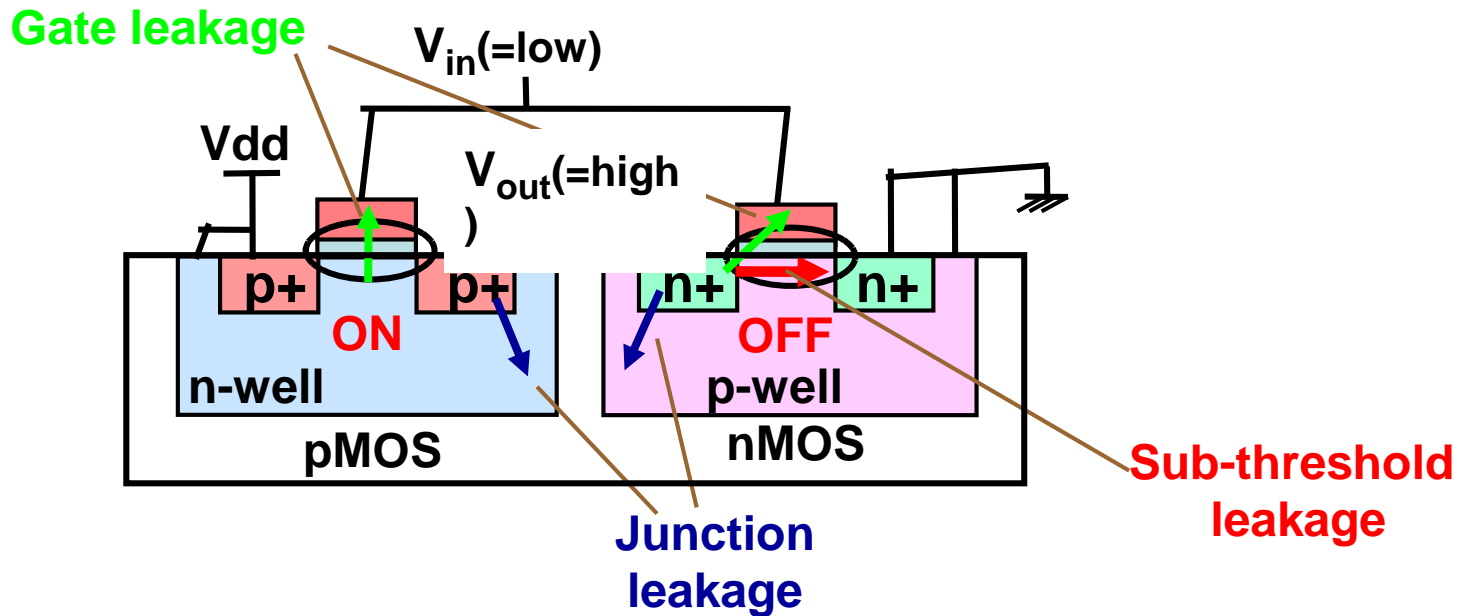
Leakage Power

◆ Power consumption due to leakage current :

$$I_{\text{leak}} \cdot V_{\text{DD}}$$

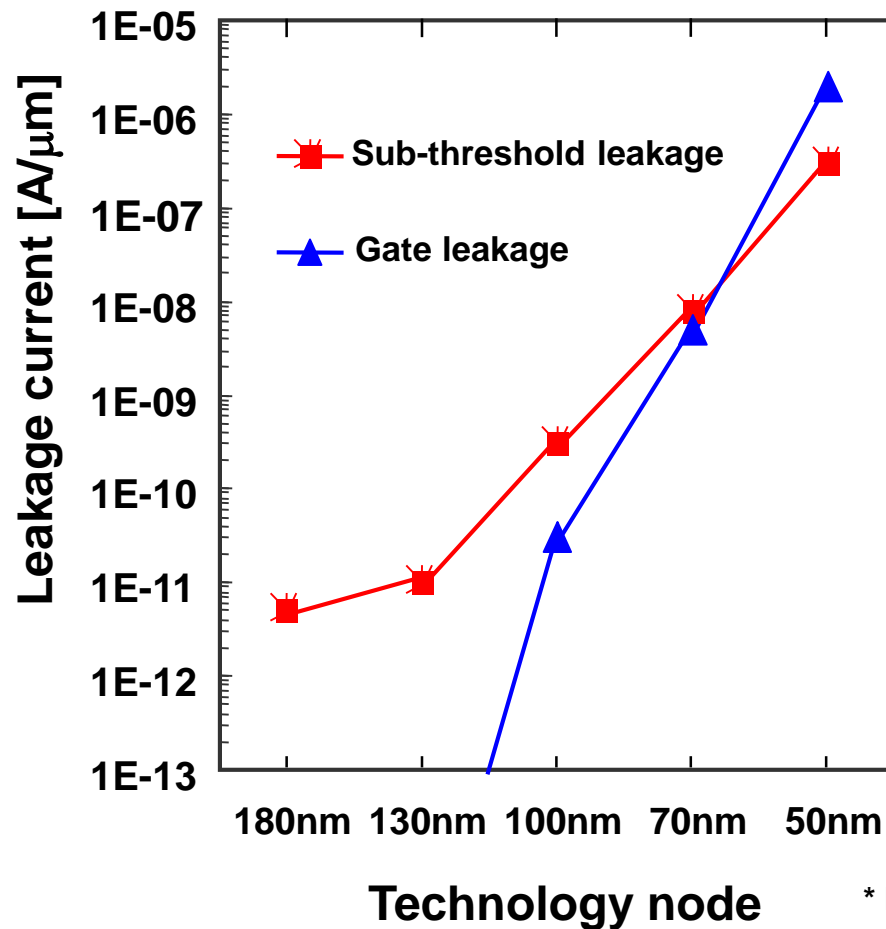
◆ Breakdown of I_{leak} :

- Reverse-bias current of source and drain junctions: junction leak
- Sub-threshold leakage at channel
- Gate leakage at gate oxide



Trend of MOS Leakage Current

(excerpt from CICC-00*, pp.409-412, 2000, T. Inukai et al.)



- ◆ Both sub-threshold and gate leakage are increased along with evolution of technology node.
- ◆ Gate leakage will become more dominant.

→ **Serious problem in reducing power consumption**

* IEEE 2000 Custom Integrated Circuits Conference

Dynamic Power of CMOS LSI

- ◆ Dynamic power of **entire LSI** is shown in the following expression by using **activation rate** α , by considering that whole circuits are not actively operating all the time.

$$P_{\text{dynamic}} = \alpha \cdot f \cdot \Sigma C_L \cdot V_{DD}^2$$

α : average activation rate of the circuit (empirical)

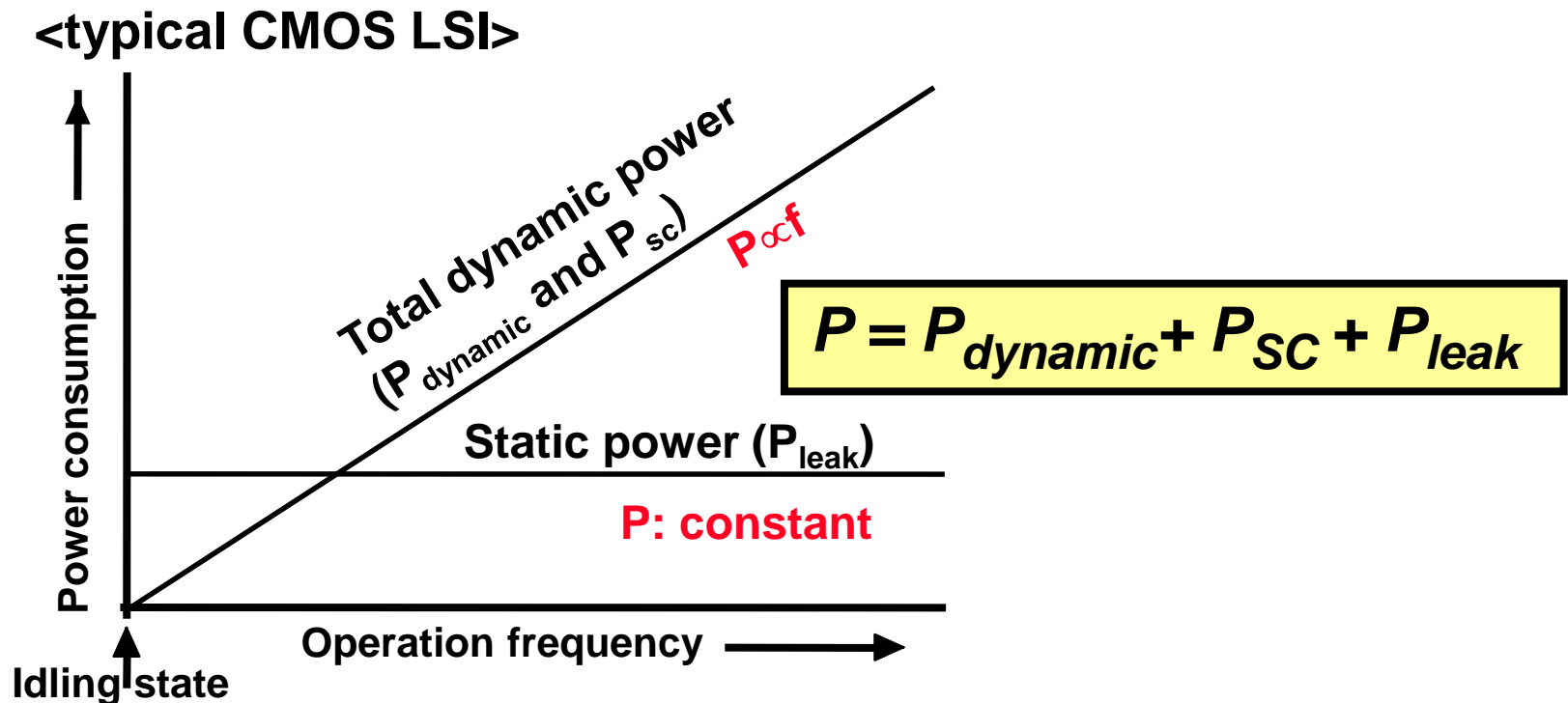
f : operation frequency

ΣC_L : aggregate parasitic capacitance of entire LSI

V_{DD} : power supply voltage

- ◆ The equation above is conceptual. In actual designs, design tools are used to tentatively estimate the entire power dissipation during logic synthesis.

Dynamic And Static Power Consumption



- ◆ Static power consumption is dominant during low-speed and idle operations.
- ◆ Dynamic power consumption is dominant during high-speed operation. However, due to increases in leakage current (sub threshold and gate) and circuit complexity, **static power consumption becomes critical** even in high-speed operation area.

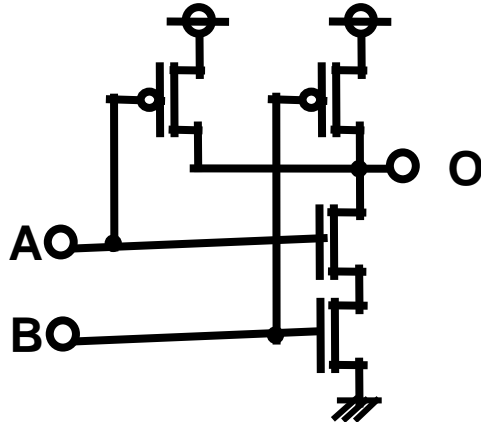
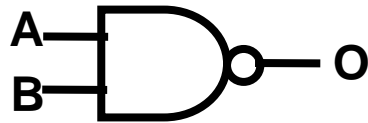
3.4 Basic CMOS Logic Circuits

- Inverter
- Logic gate
- Logic Block

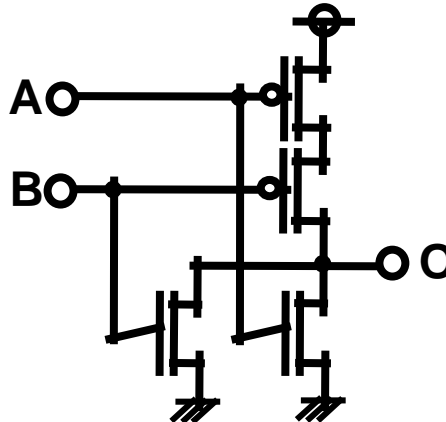
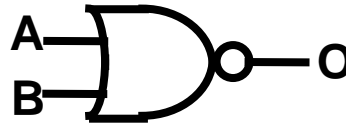
Logic Gate

Examples of logic gates

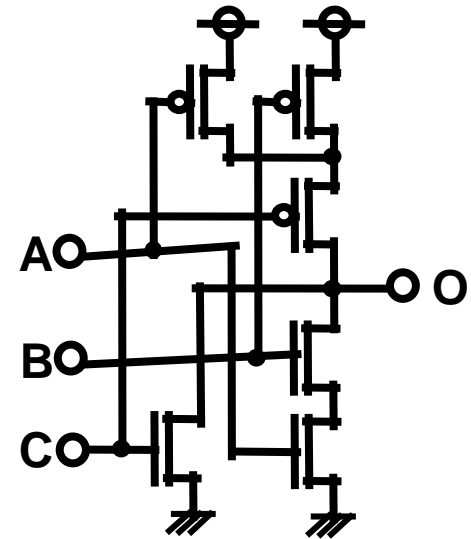
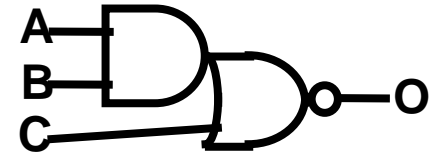
○ 2 input NAND ($O = \overline{A \cdot B}$)



○ 2 input NOR ($O = \overline{A + B}$)



○ Combinational gate ($O = \overline{A \cdot B + C}$)



- ◆ With **complementary** transistor configurations, all logic circuits can be implemented.
- ◆ Basically their complementary operations are similar to those of an inverter.

Basic Rules for Logic Gate Configuration

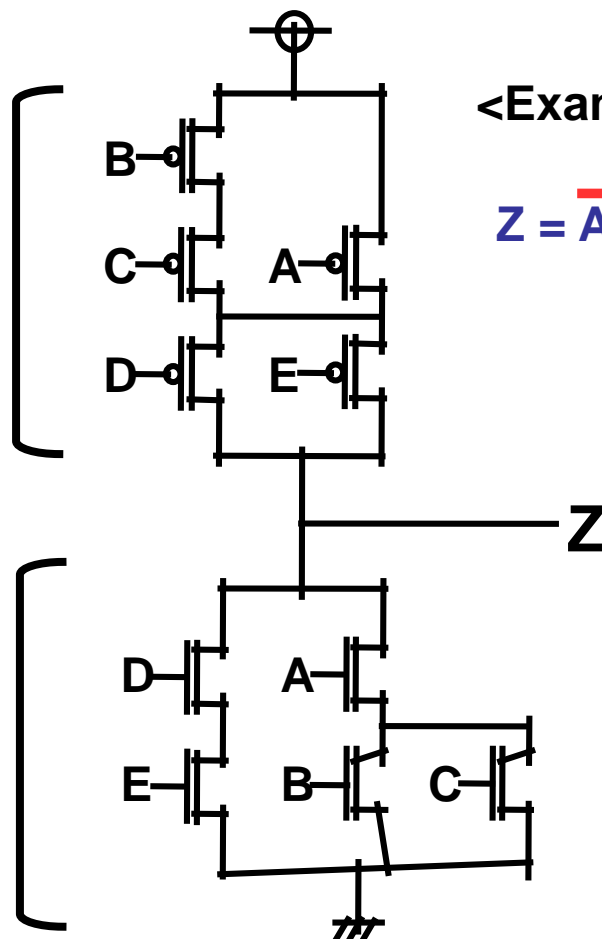
pMOS:

Logical product in parallel
Logical addition in serial

Duality

nMOS:

Logical addition in parallel
Logical product in serial



<Example>

$$Z = \overline{A \cdot (B + C) + D \cdot E}$$

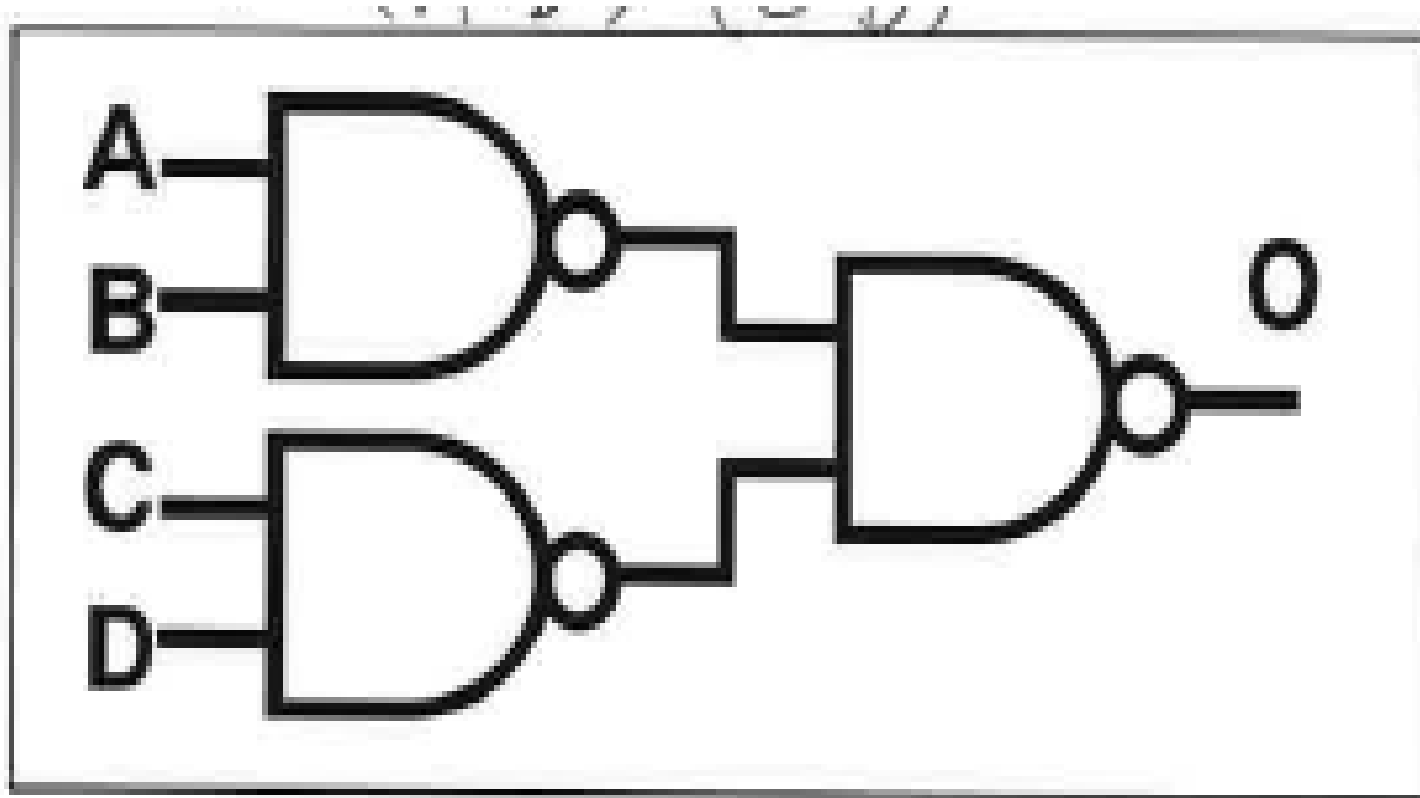
over-bar



According to these rules, any logic gate can be implemented in a complementary way._

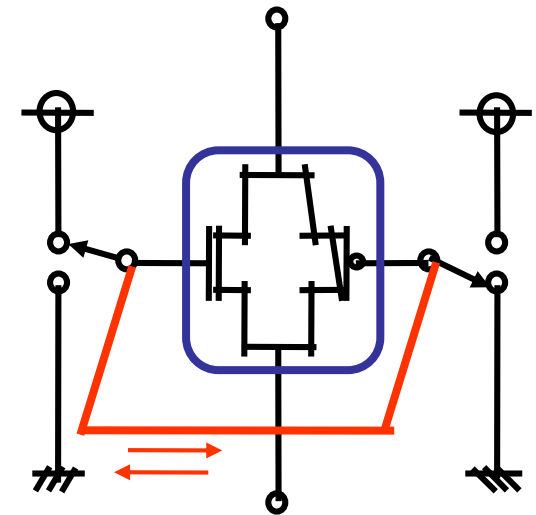
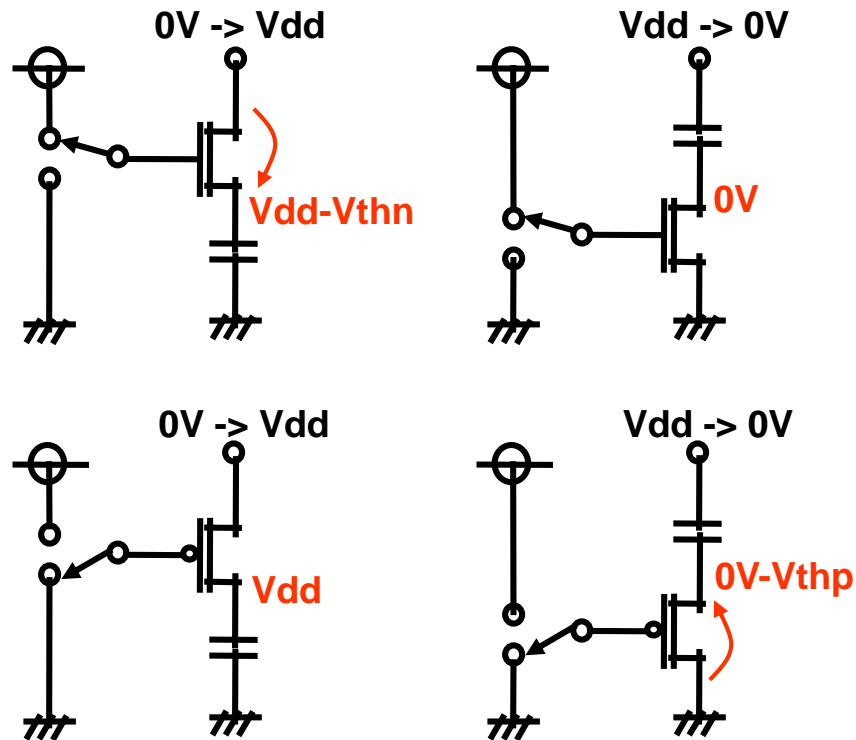
Exercise 2

Draw CMOS circuit for below logic gate



Transistor Switches

Voltage reduction by V_{th}



Voltage reduction by V_{th} can be prevented by complementary operations.

3.4 Basic CMOS Logic Circuits

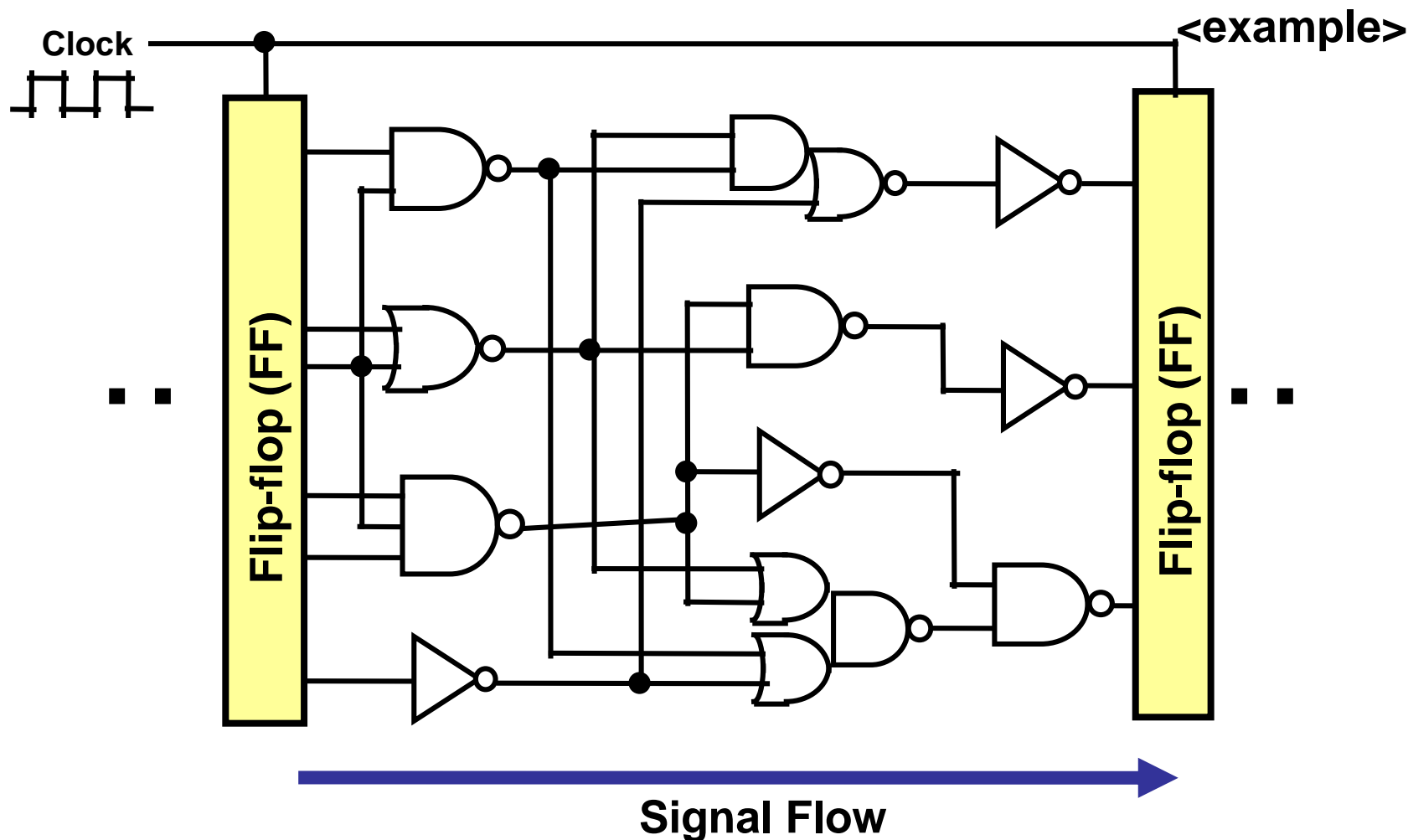
➤ Inverter

- Delay time
- Power consumption

➤ Logic gate

➤ Logic Block

Standard Organization of Logic Block

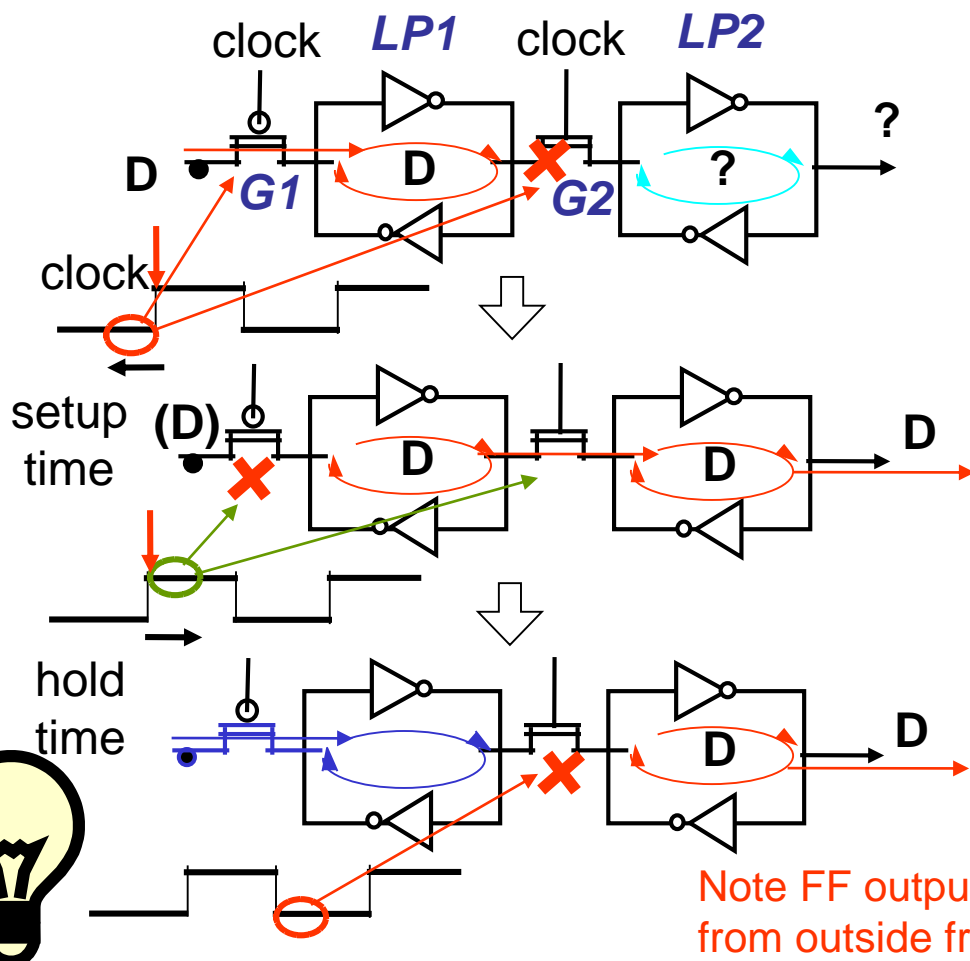


FF: A circuit that holds the input data and transmits it to the next stage by using a clock signal.

Flip Flops

Principle of operation

The figures shown left are a simplified example.



1. Gate G1 is ON while clock remains low, and data D is taken into loop LP1.

2. When clock rises, G1 is OFF and G2 is ON to pass data D into next loop LP2.

3. When clock goes low, G2 is OFF and LP2 keeps its data D.

Note FF output is not determined until any value is set from outside from logic simulation standpoint. Especially cares should be taken after power on.

Key Components of Logic LSI

<Control Logic Circuit>

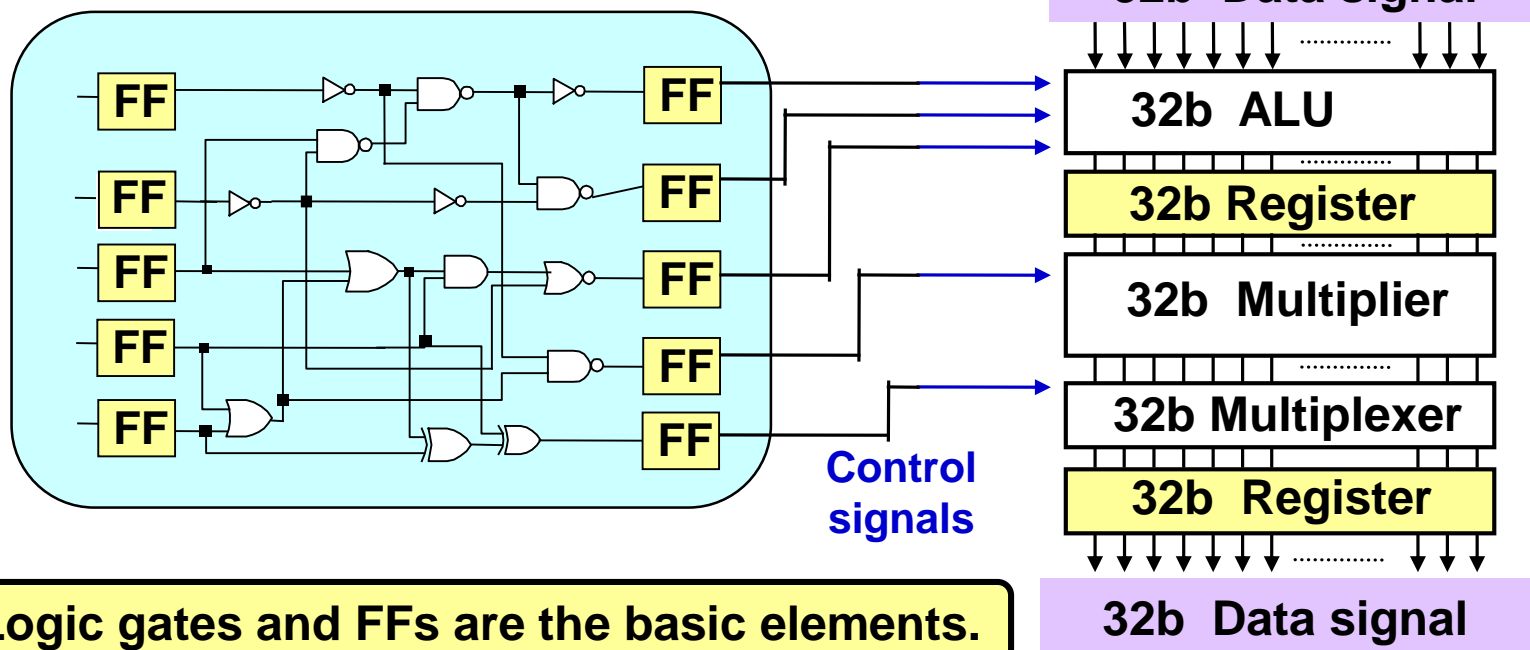
- Control of data path
- Control of whole chip
- Control of interface with external chip

<Data Path>

- Execution units
- Registers, selectors
- multiple-bit width

A register is the data storing circuit.

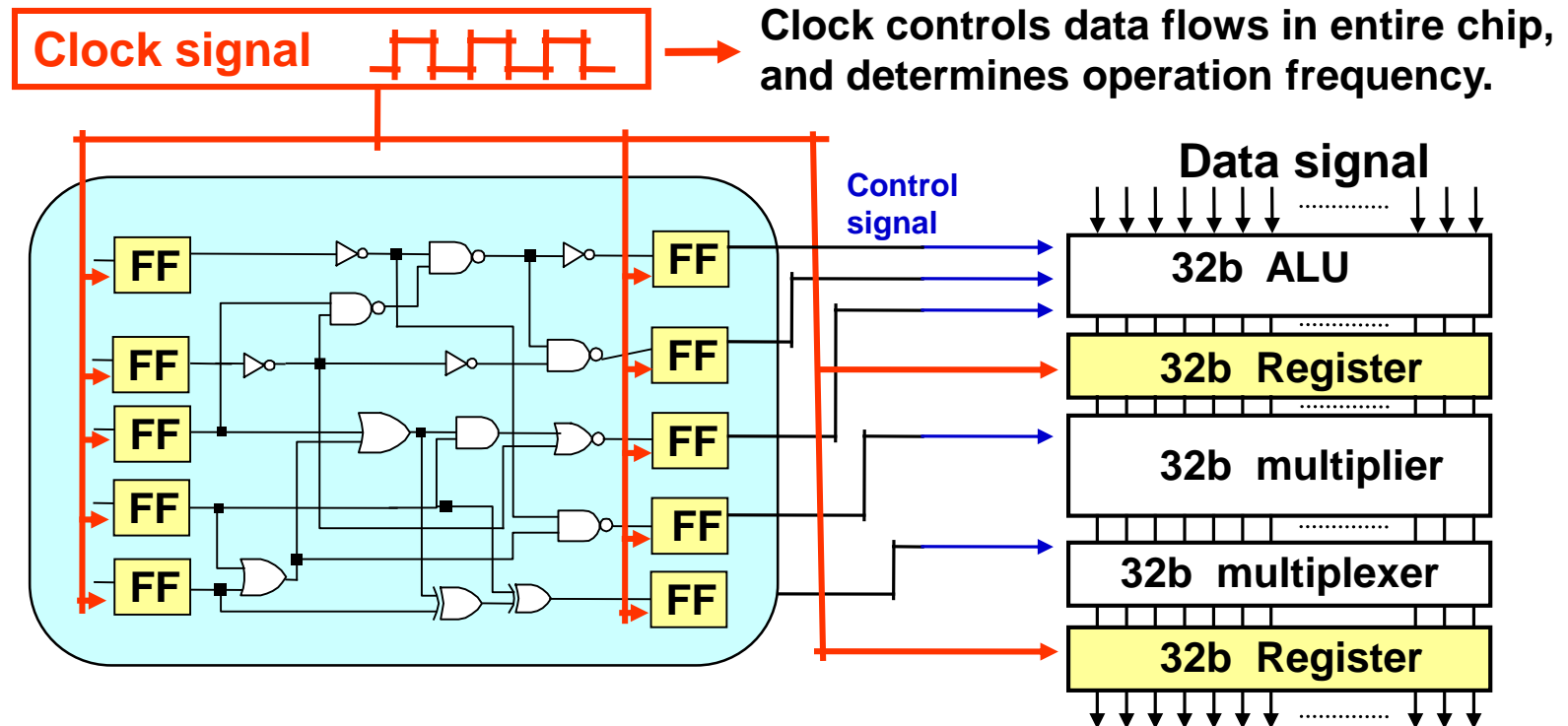
Example of 32b data path and its control logic



Clock Signal

- FFs and registers require clock signal for their operation
- **Clock-skew*** must be minimized in synchronous design

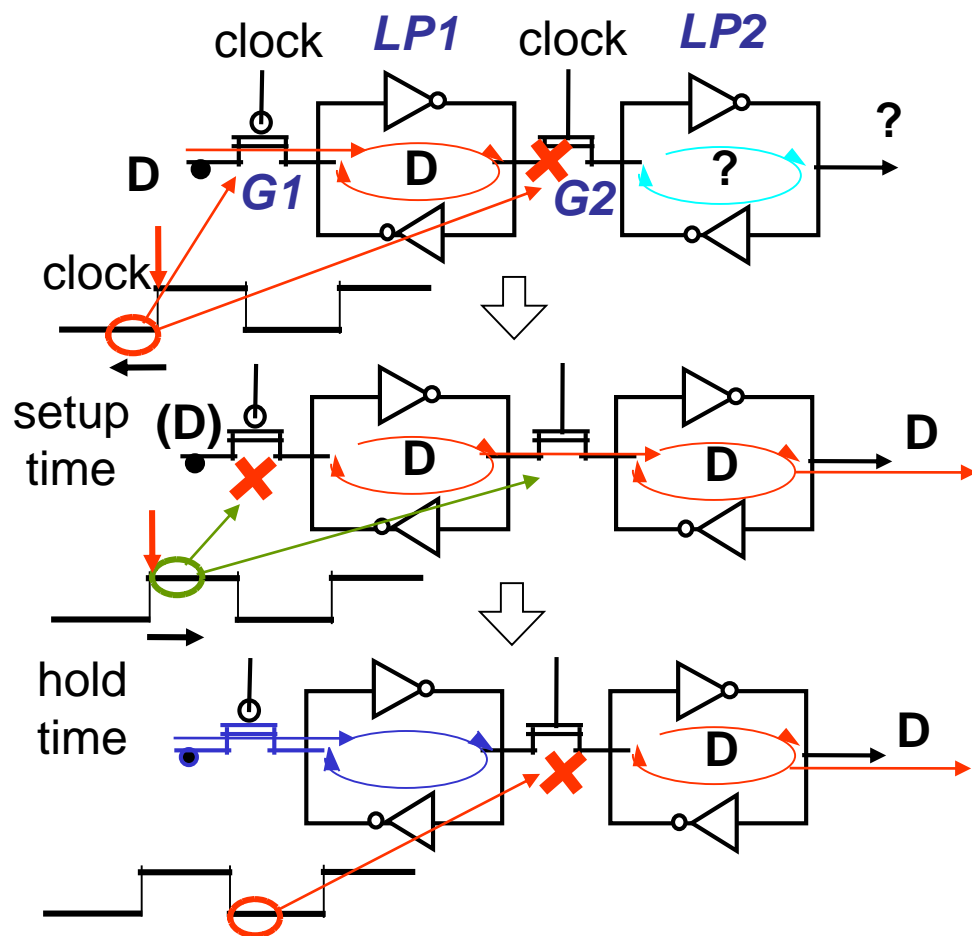
*clock-skew ... time lag of clock signals among FFs and registers



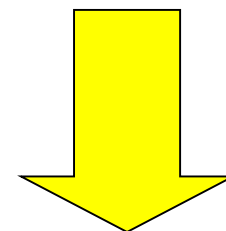
Routed over entire chip, clock signal is the key factor in determining speed and power consumption

Flip Flops, Again

Principle of operation

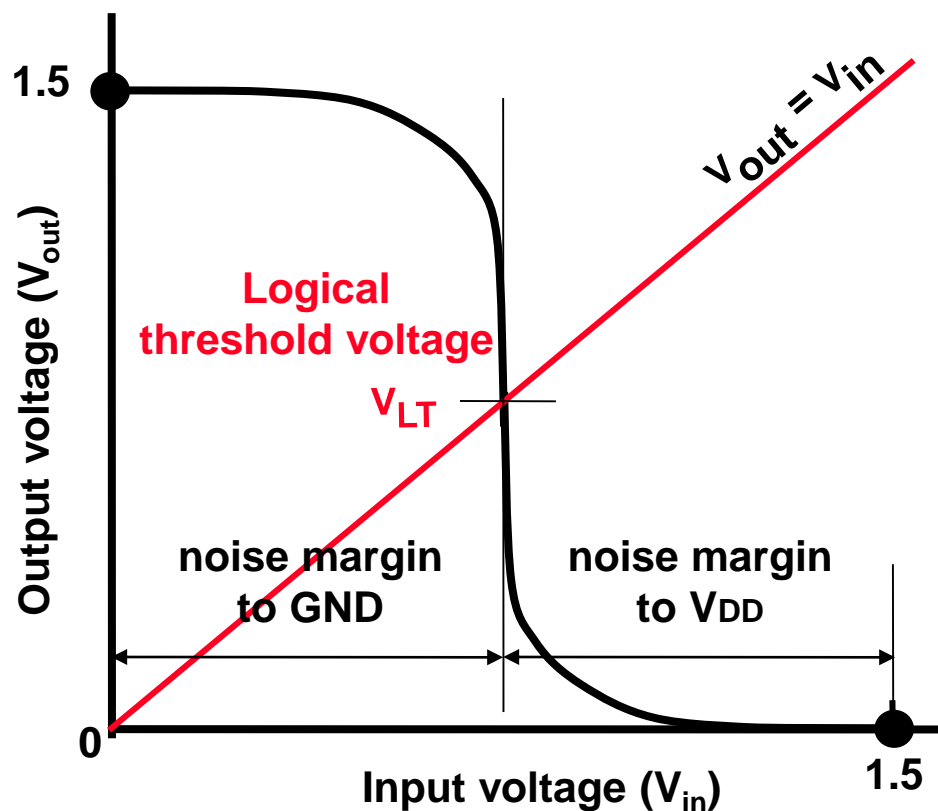
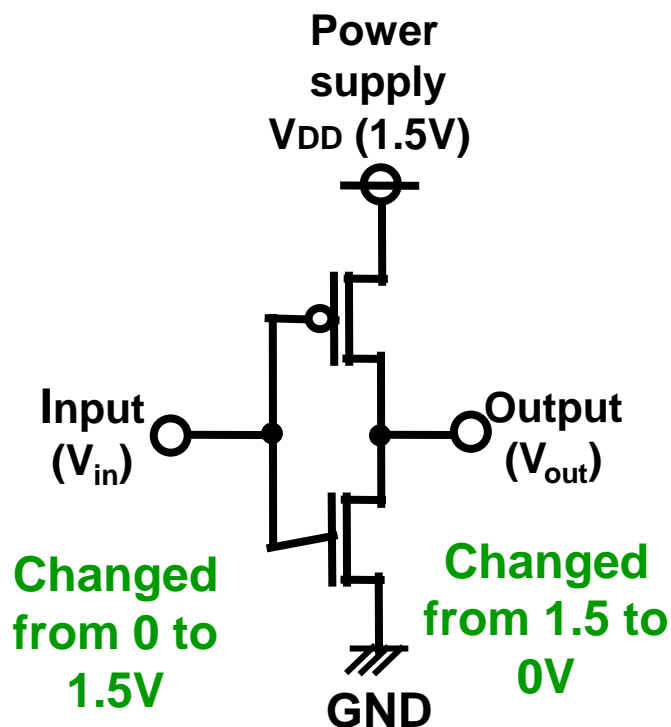


**Unavoidable Problem
of flip flop**



**Synchronous design
must be adopted.**

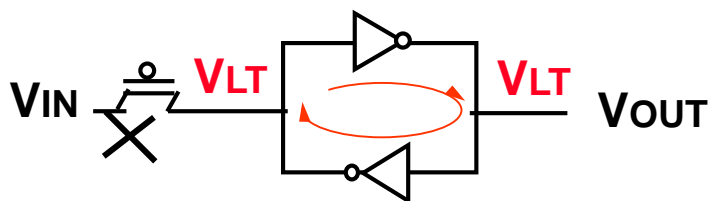
Logical Threshold Voltage (restudy)



To set logical threshold voltage of each gate at the same level is important to secure noise margin: $V_{LT} = V_{DD}/2$

Metastable State (1)

- To set logical threshold voltage of each GATE at the same level is important to secure noise margin: $V_{LT} = 1/2 V_{DD}$.
- But big problem in FLIP FLOPs.

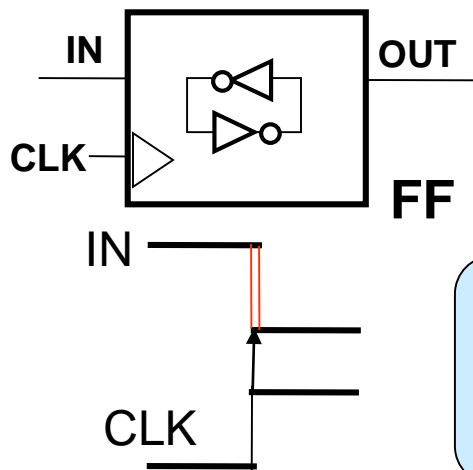


- When input V_{IN} is held at V_{LT} and then gate becomes OFF, the flip flop MIGHT keep this level for unpredictable period.
- But actually when small plus noise is applied to left node of loop, V_{OUT} accordingly becomes 0. In minus case, V_{out} goes to 1.
- Behavior of V_{OUT} is **not predictable** depending upon noise level: **metastable**.

< hypothetical case >

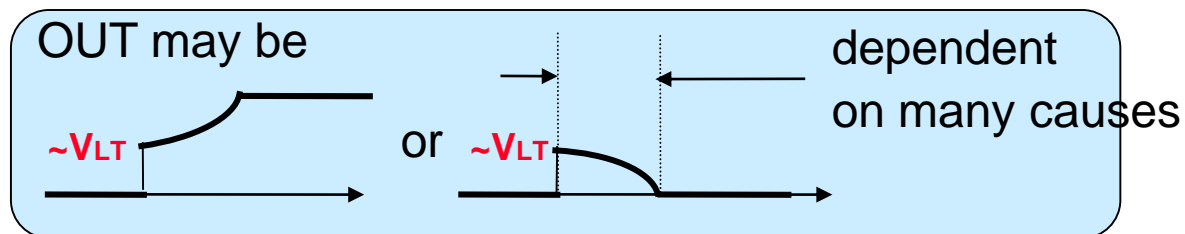
Metastable State (2)

< actual case >



When falling edge of IN and rising edge of CLK are very close, voltages at inverter loop within FF become close to V_{LT} depending on timing of IN.

Succeeding behavior is unpredictable.

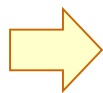
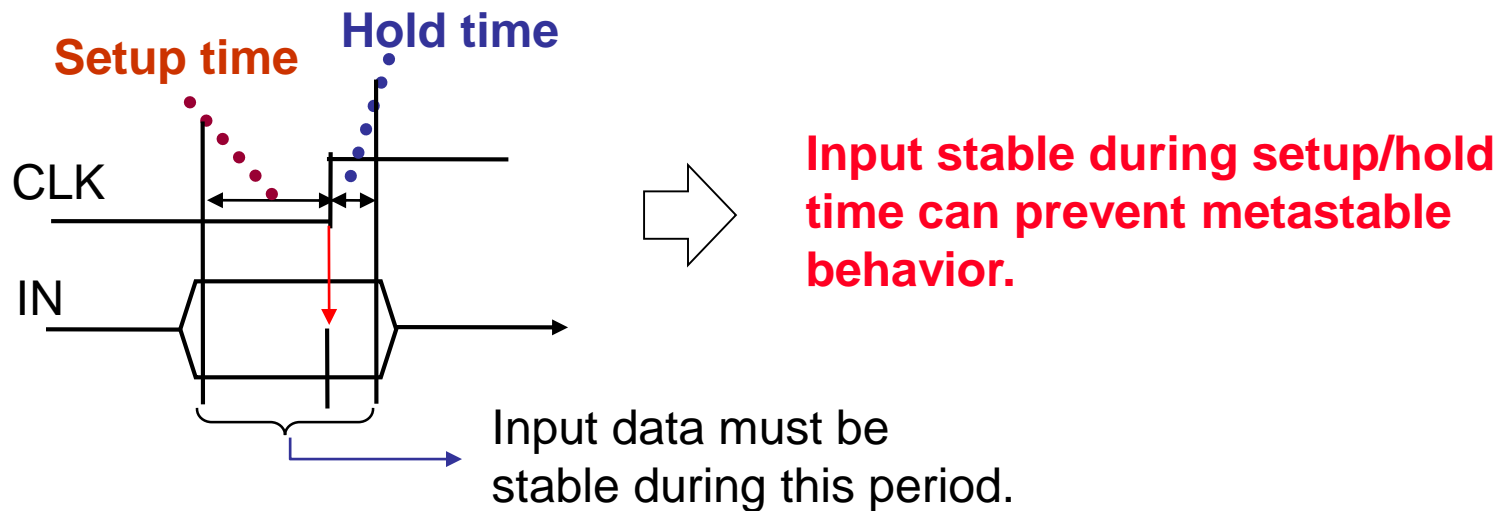


➡ This phenomenon surely happens when IN is asynchronous with CLK. OUT must be sensed at least one clock cycle after CLK rising edge under focusing.

➡ **Asynchronous input must be clocked twice to wait for settlement of metastable behavior.**

Asynchronous data transfer may cause one of the most serious logic design bugs that need long time to be fixed because failure is intermittent.

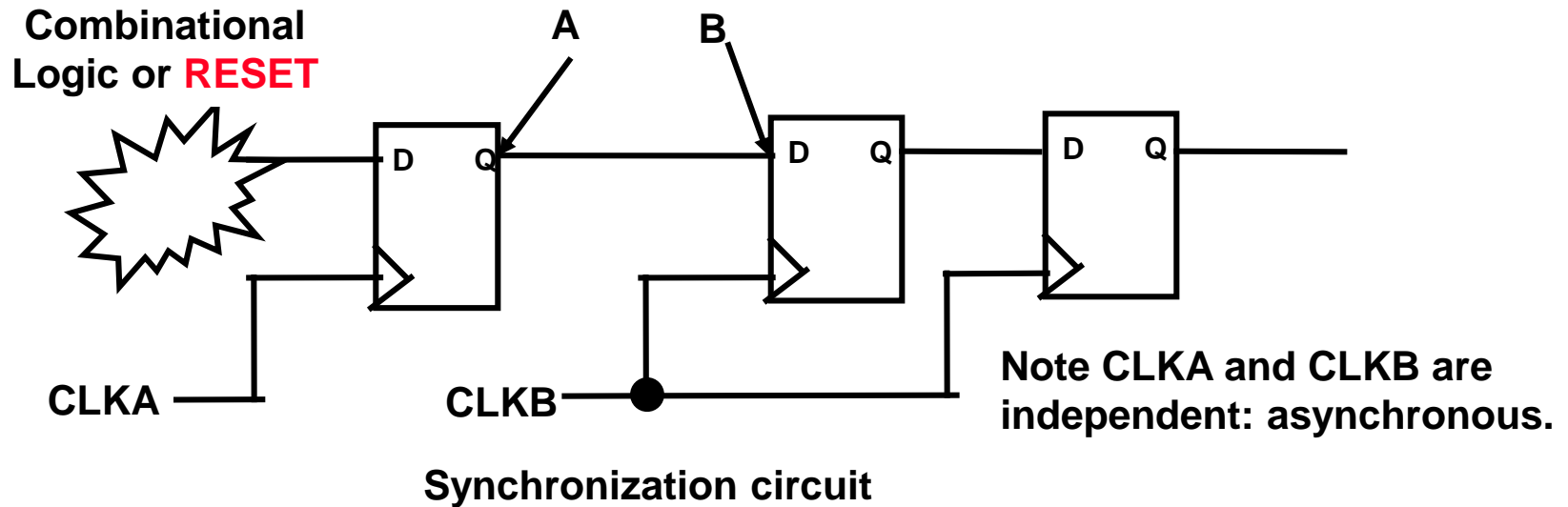
Synchronous Design



To observe setup/hold time is the key in synchronous design.

Note : setup/hold time is different from “delay”. Be sure to thoroughly verify it with STA.

Asynchronous Input



Designers common knowledge : asynchronous input must be clocked twice to wait for settlement of metastable state

Pitfalls = Error :

- overlook that CLKA and CLKB are independent
- nodes A and B are not 1-to-1 connection
- $f_{CLKA} > f_{CLKB}$

Summary for Logic Circuits (1)

- Inverter, a fundamental logic circuit, is comprised of a pair of nMOS and pMOS transistors, where both gates are commonly connected to input, and both drains to output.
- Output voltage swings from GND to V_{DD} , and no direct current flows from V_{DD} to GND.
- Logical threshold voltage: $V_{LT}=V_{IN}=V_{OUT} \rightarrow V_{DD}/2$
- Delay time:
$$T_d = \frac{C_L \cdot V_{DD}}{\beta \cdot (V_{DD} - V_{th})^2}$$
- Power consumption : $P = P_{dynamic} + P_{sc} + P_{leak}$,
 $P_{dynamic} = \alpha \cdot f \cdot \Sigma C_L \cdot V_{DD}^2$
- Based on inverter structure, any functional gate can be configured in complementary way by applying duality rules.
- Standard logic block is composed of combinational logic sandwiched by 2 rows of FFs.



Summary for Logic Circuits (2)

- Typical logic LSI designs include logic blocks, and datapath controlled by some of logic blocks.
- Clock signal must be carefully considered in terms of timing designs and routing because it is routed to every flip flop and register.
- Metastable behavior is inherent in FF. To avoid this, synchronous design is straightforward as far as setup/hold time is appropriately observed.
- Asynchronous data transfer must be carefully designed.

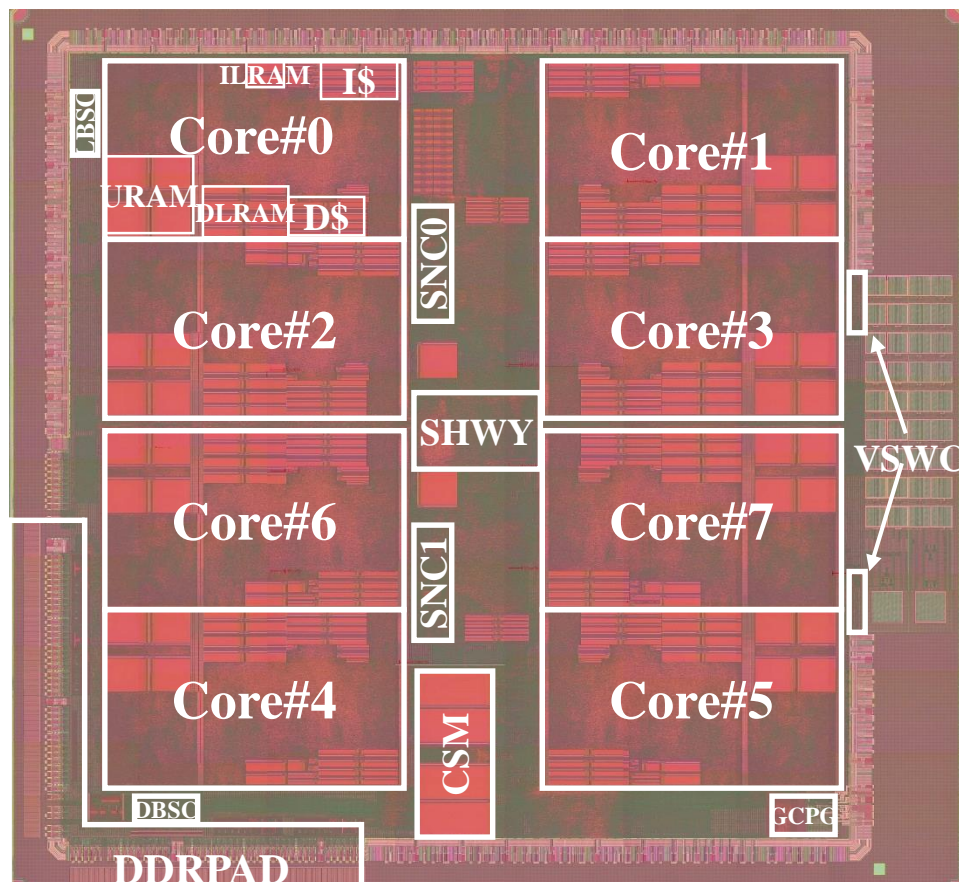


References

- Circuit Design for CMOS VLSI by John P. Uyemura, 1992
- Application-Specific Integrated Circuits
by Michael John Sebastian Smith, 1997
- Digital Integrated Circuits A Design Perspective by Jan M. Rabaey, 1996

Appendix

LSI Example 1 (processor chip)

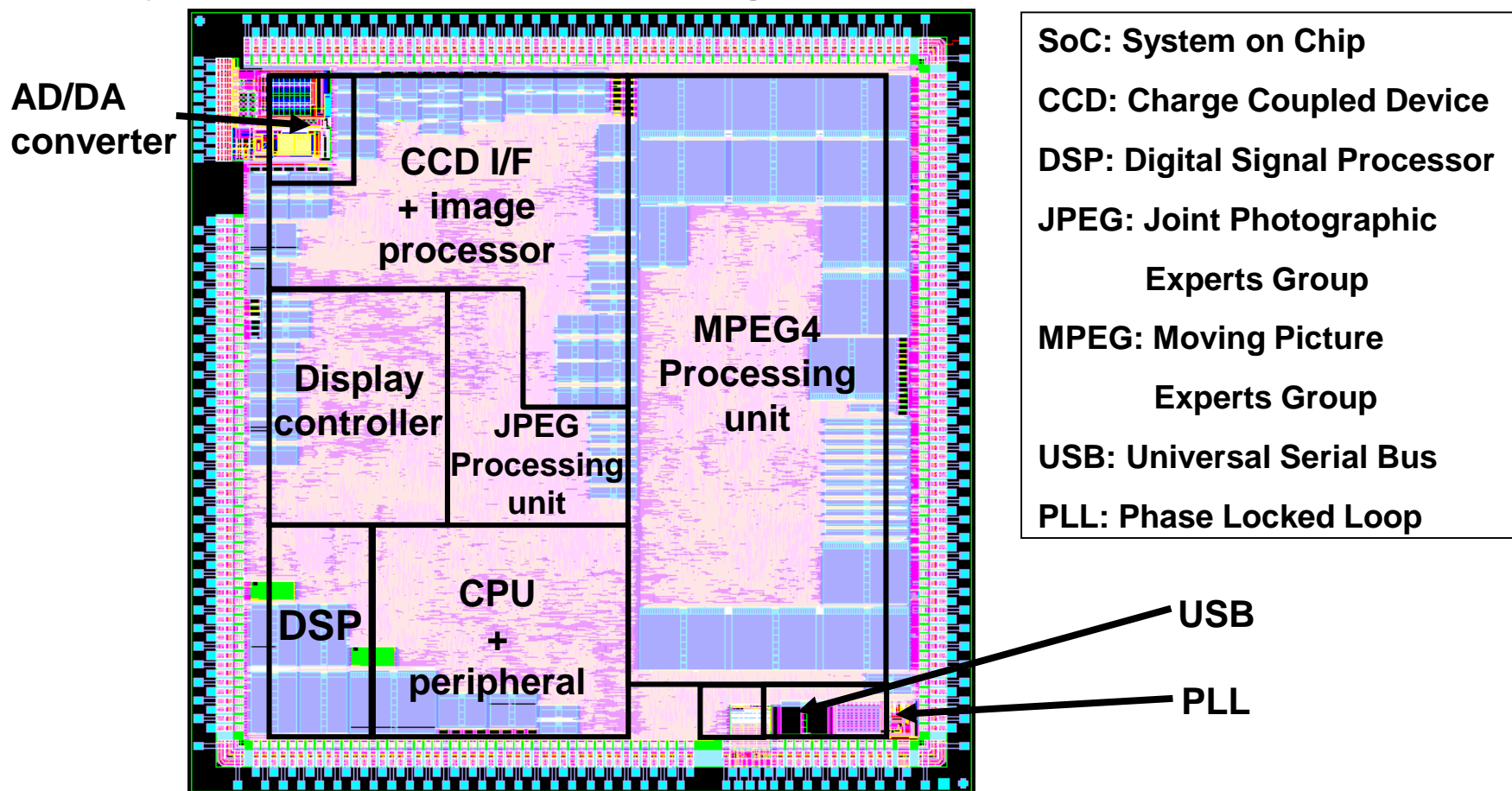


Process Technology	90nm, 8-layer, triple-Vth, CMOS
Chip Size	104.8mm ² (10.61mm x 9.88mm)
CPU Core Size	6.6mm ² (3.36mm x 1.96mm)
Supply Voltage	1.0V–1.4V (internal), 1.8/3.3V (I/O)
Power Domains	17 (8 CPUs, 8 URAMs, common)

LSI: Large Scale Integration

LSI Example 2 (SoC)

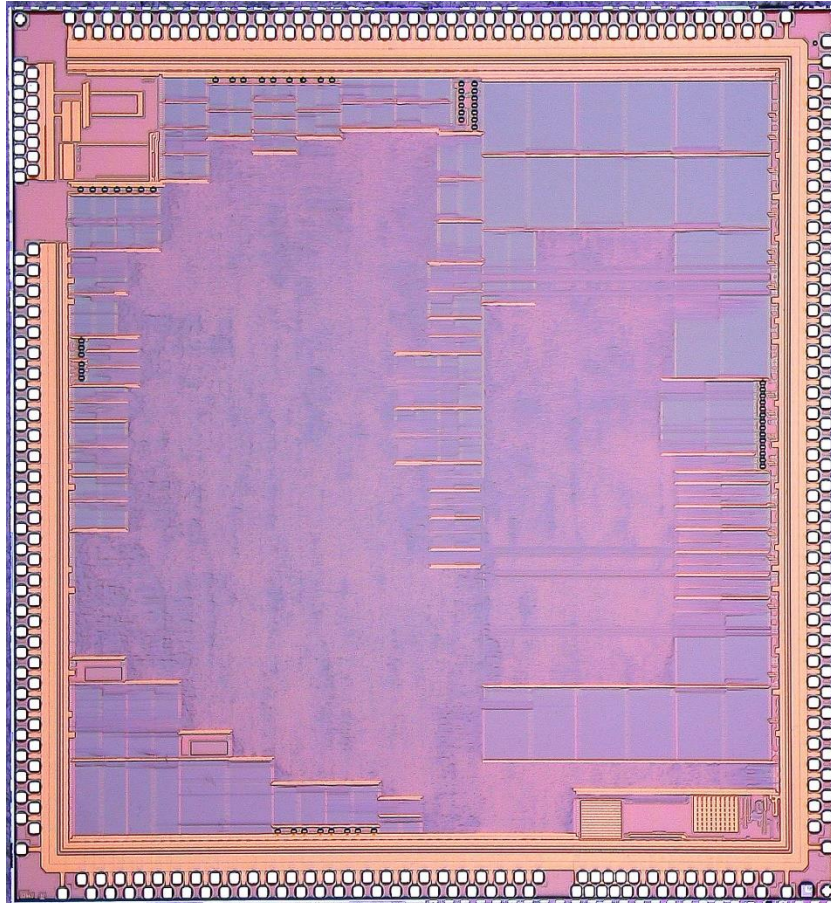
< Layout plot of SoC chip for Digital Still Camera (DSC) >



Wide variety of functional units are integrated on a single chip to configure an SoC

Die Photo and Outline of SoC for DSC

<Die photo>



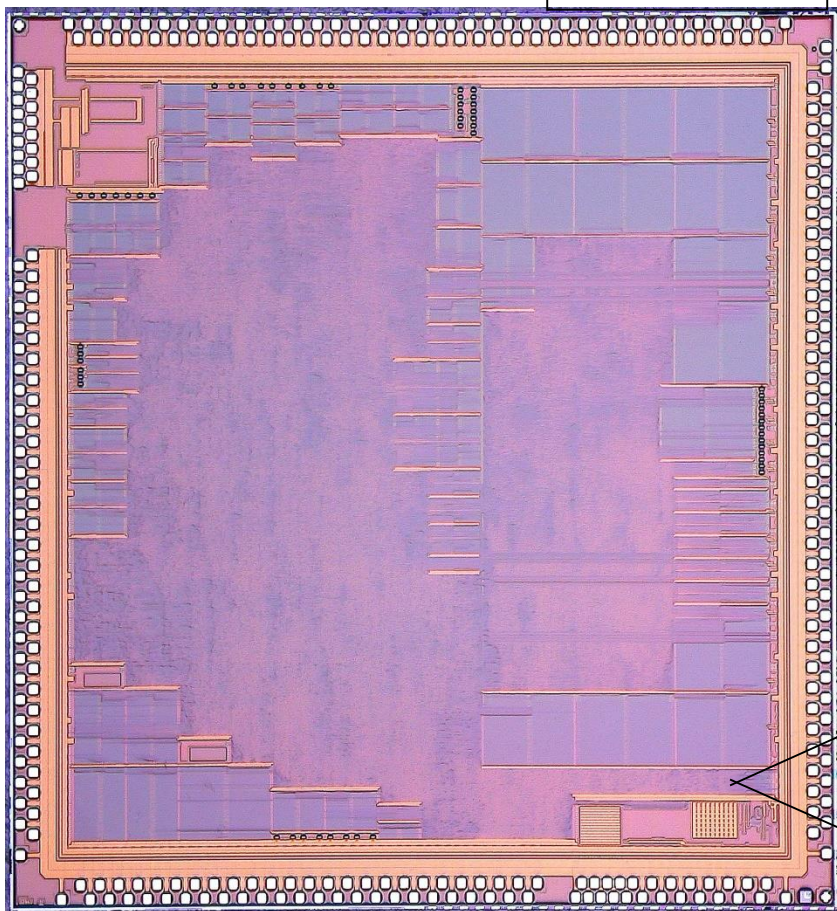
<Chip summary>

Number of logic gates	2.5M gates (1 gate =4 trs.)
SRAM	equipped with 90 pcs, totally 3M bits
ROM	equipped with 3 pcs of 64K- bit block
Analog	PLL, ADC, DAC, USB
Process	0.15μm, 5-layer metal
Chip size	7.85 x 7.85 mm ²

Physical Dimensions

<Die photo>

um: 10^{-6} m
nm: 10^{-9} m



~11 um

fine silk

2,000~100,000 nm
(naked eye)

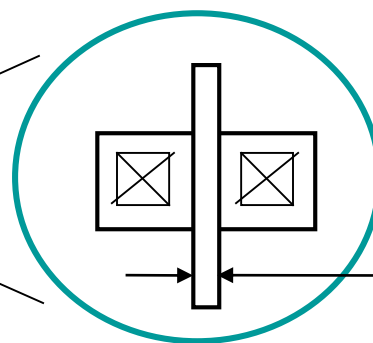
mold
(spore)

500~3,000 nm
(microscope)

bacteria

10~400 nm
(elec. microscope)

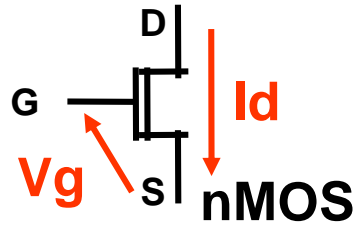
virus



MOS transistor

channel length:
100~150 nm

Exercise 1



Linear region ($0 \leq V_d \leq V_g - V_{th}$)

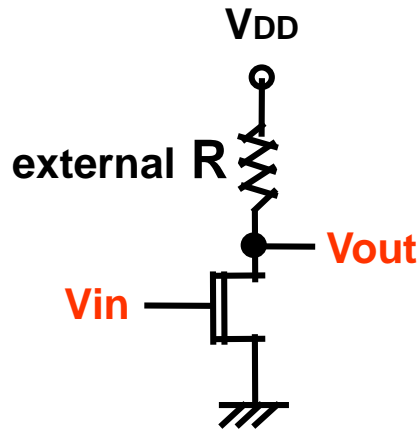
$$I_d = \frac{W}{L} \mu C_{ox} \left\{ (V_g - V_{th}) V_d - \frac{1}{2} V_d^2 \right\}$$

Saturation region ($V_d > V_g - V_{th}$)

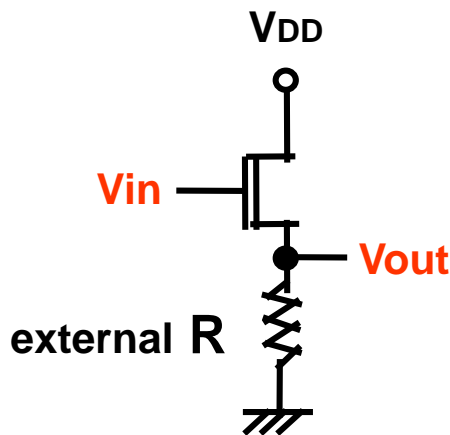
$$I_d = \frac{W}{2L} \mu C_{ox} (V_g - V_{th})^2$$

$$\alpha = \mu C_{ox} W / 2L$$

Vin is connected to Vdd, and R becomes infinity, then Vout = ?

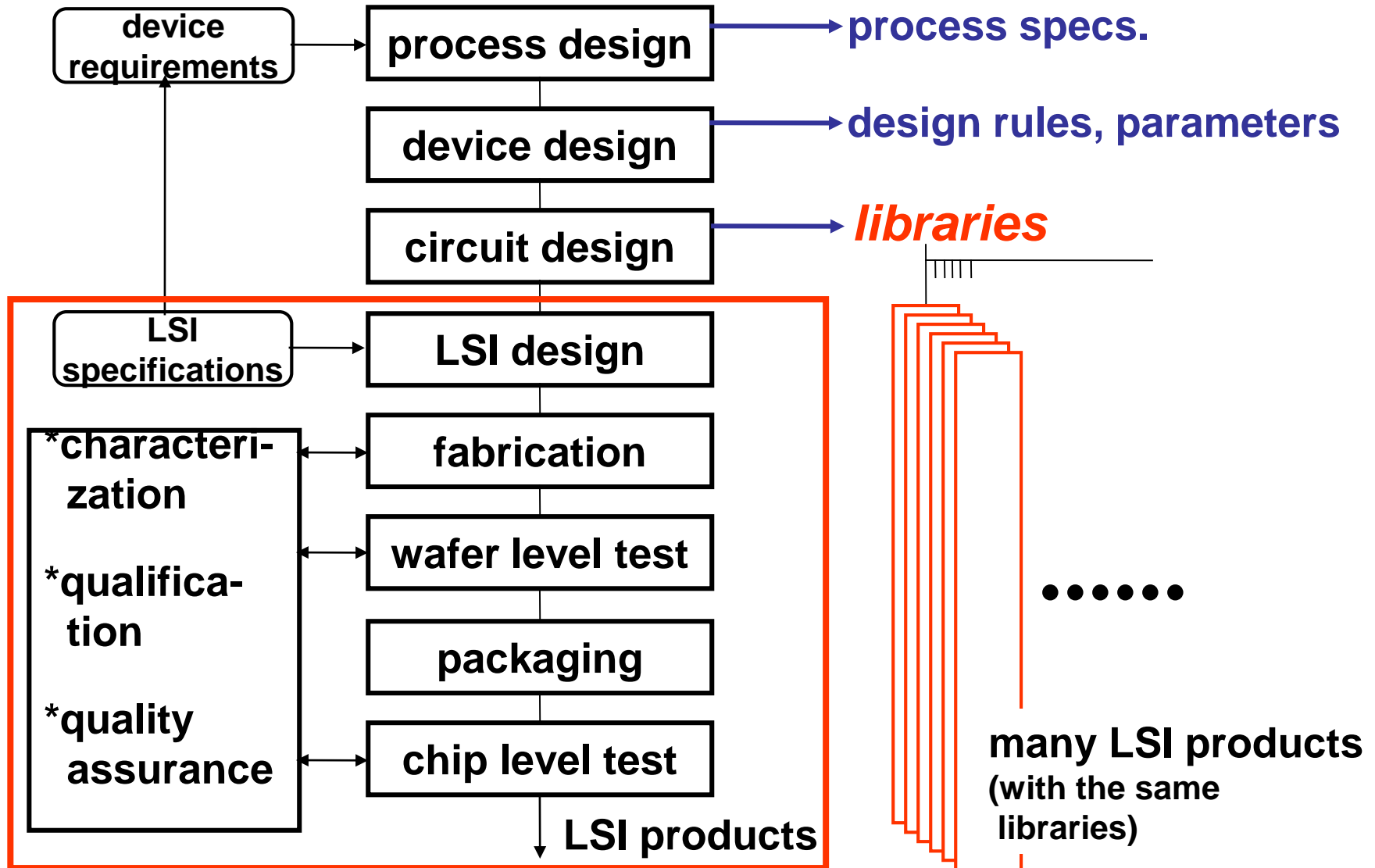


Vout =

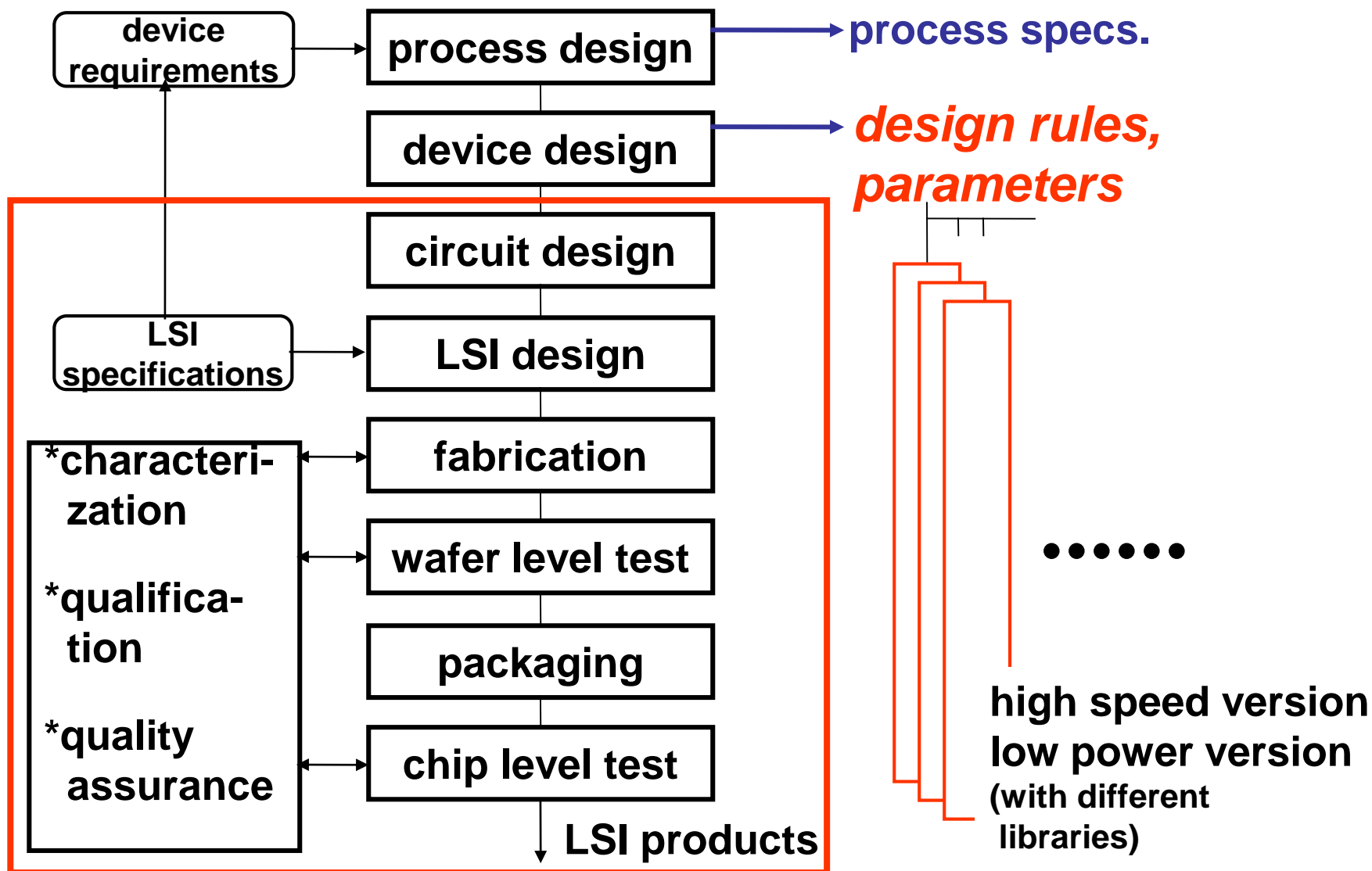


Vout =

Diversifications (1)



Diversifications (2)



Calculation of MOS capacitance

Capacitance C is a capability to store charges.

$$C = \epsilon \times \epsilon_0 \times S / t$$

C : Capacitance (Cox)

S : Area of capacitor

t : Thickness of insulator

ϵ : Relative permittivity of insulator(3.9 for SiO₂)

ϵ_0 : Permittivity of vacuum (8.84 x 10⁻¹⁴ F/cm)

Example The capacitance of MOS capacitor(P-substrate) whose area is 2.5 x 10⁻³ (cm²) with applying voltage of - 3.0V is 884 (pF). Calculate the gate thickness.

The amount of charge to be stored is determined by the product of C and Voltage.

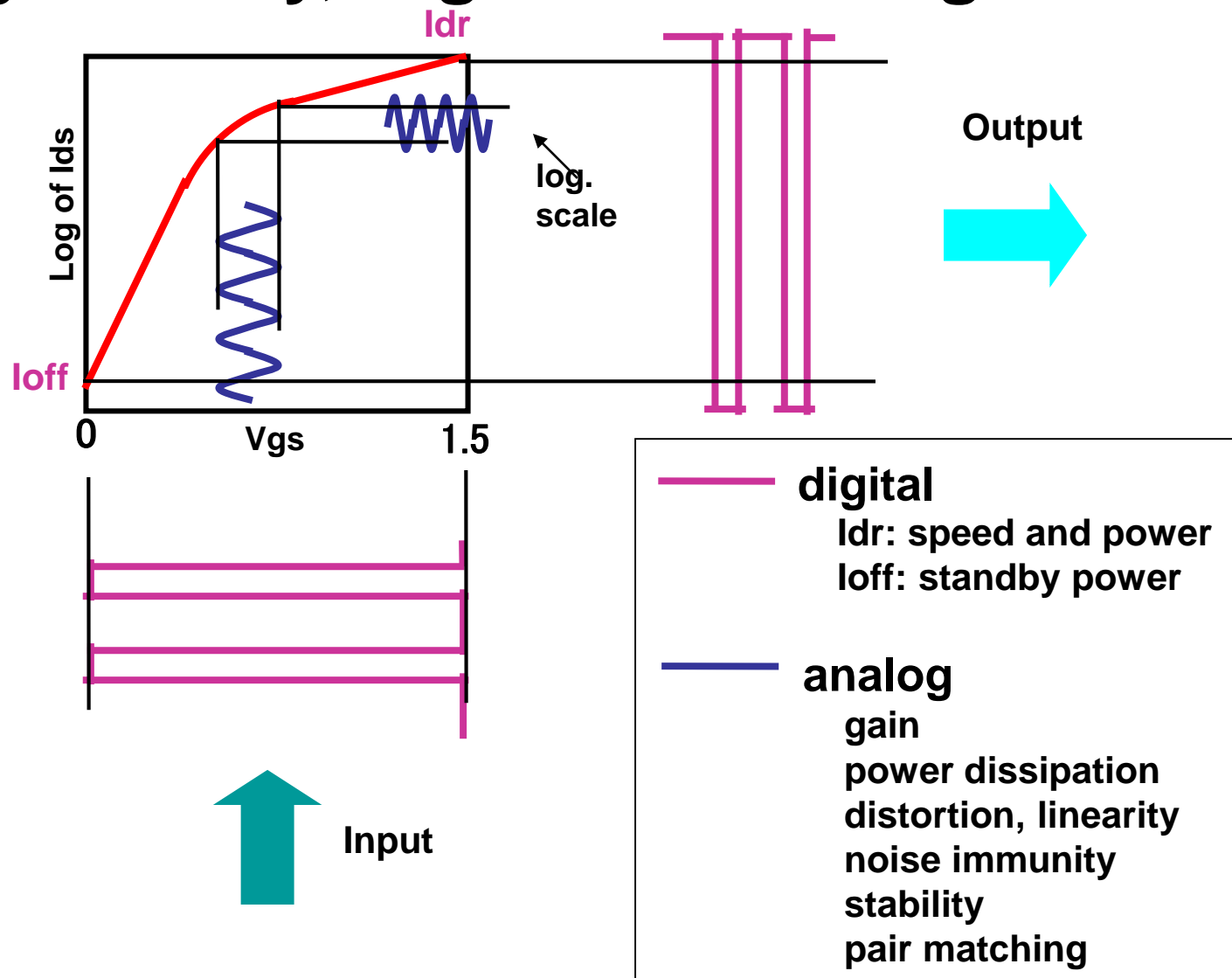
$$Q = C \times V$$

Q : Stored charge

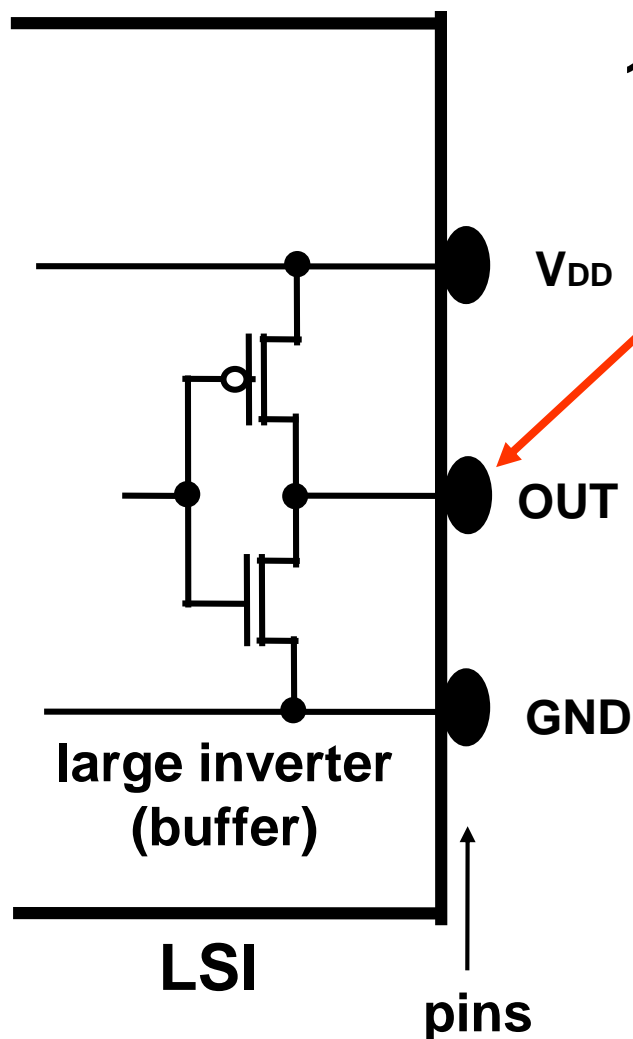
V : Applied voltage

$$T_{ox} = \frac{8.84 \times 10^{-14} \times 3.9 \times 2.5 \times 10^{-3}}{884 \times 10^{-12}} = 9.75 \times 10^{-7} \text{ cm} = 9.75 \text{ nm}$$

By the way, Digital vs. Analog



What is Latch Up



1. Large noise ($>V_{DD}$) or negative noise (<0)

2. Then, large current **keeps flowing** from V_{DD} to GND due to parasitic bipolar transistors

3. Malfunction will occur.

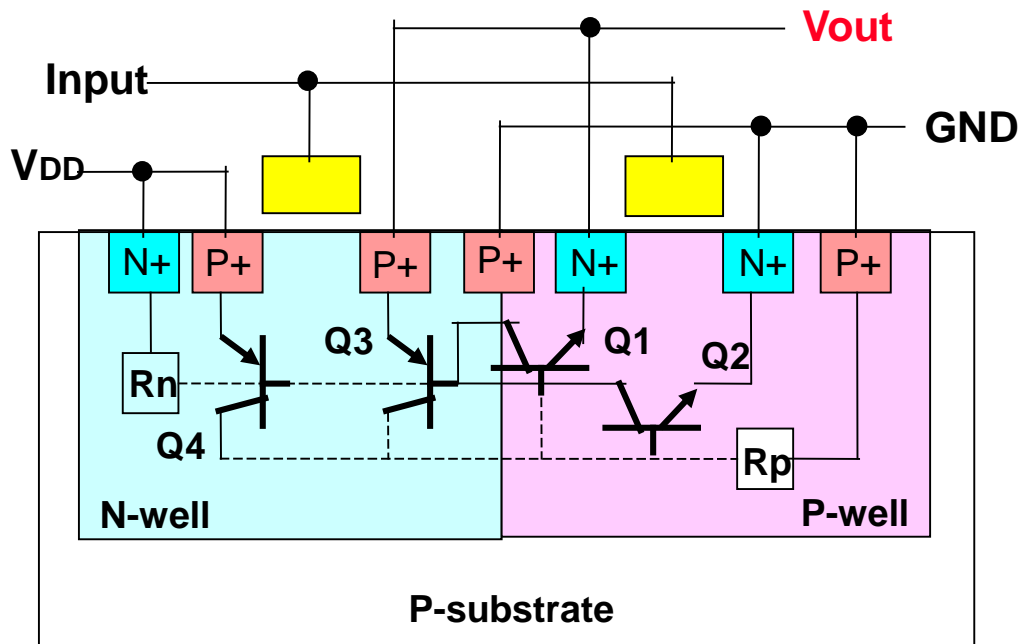
4. Finally, power lines in LSI may **melt down** due to high current.

BD002

Latch up, a worrying problem

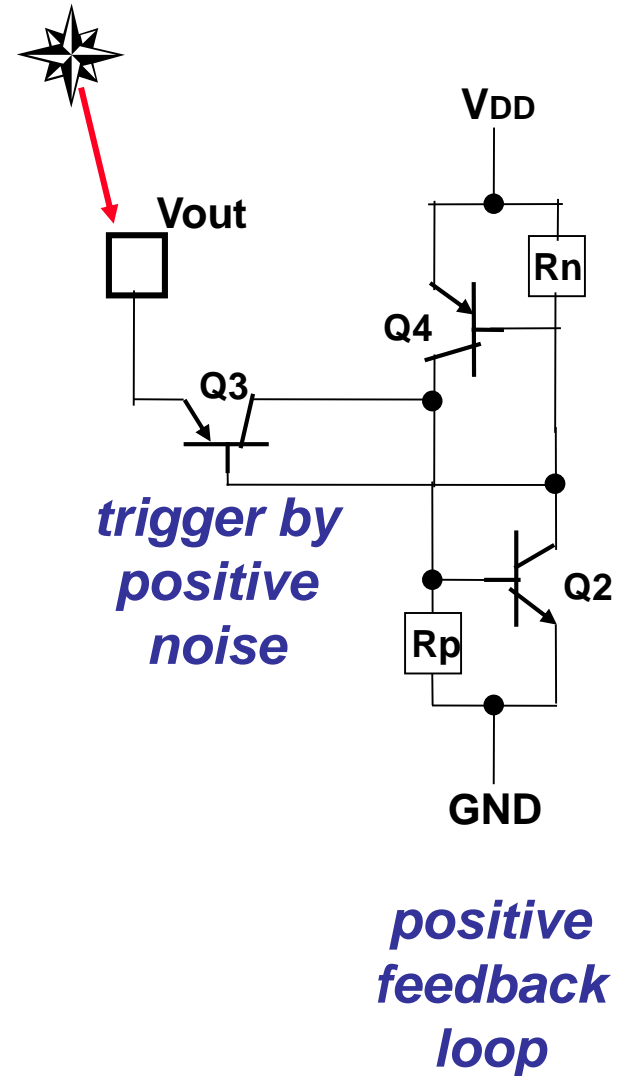
- Reason: positive feedback loop including **parasitic bipolar transistors** in CMOS
- Cause: **noise spike** or improper circuit hookup.
- Conditions: depending on bipolar transistors gain and resistivity of n-wells and p-wells (**dimension dependent**).
- Once the latch up occurs, the only way to stop it is to reduce the current below a critical level, or usually to **shut down** the power source.
- With process advancement (finer, thinner, closer), the latch up **becomes serious**.

What is Latch Up



pMOS
FET transistors
lateral bipolar
transistors (pnp)

nMOS
FET transistors
lateral bipolar
transistors (npn)



Latchup Sequence

- Excessive surge voltage is applied to Vout.
- Base and Emitter of Q3 is forward biased ($|V_{BE}| > 0.6V$), and surge current flows to V_{DD} through R_n .
- Q3 becomes ON, and collector current flows to GND through R_p .
- Voltage across R_p exceeds 0.6V, and emitter and base of Q2 is forward biased ($|V_{BE}| > 0.6V$).
- Q2 becomes ON, and collector current flows from V_{DD} through R_n .
- Voltage across R_n exceeds 0.6V, and emitter and base of Q4 is forward biased ($|V_{BE}| > 0.6V$).
- Q4 becomes ON, and collector current flows to GND through R_p .
- Go to (4), where $V_{BE} \gg 0.6V$. Then, (5), (6), (7), (8), (5), **(6)**.....

➔ melt down

Characteristics of leakage currents

(supplement)

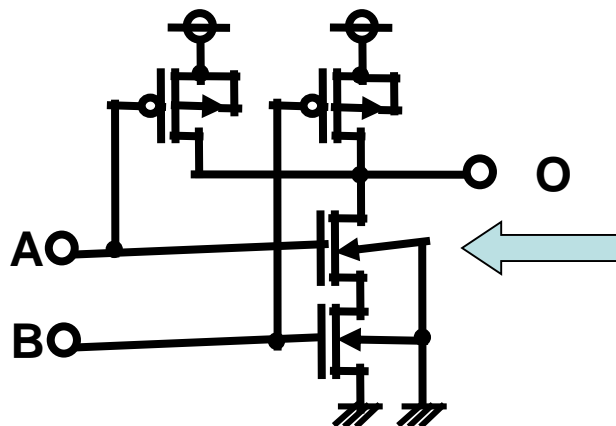
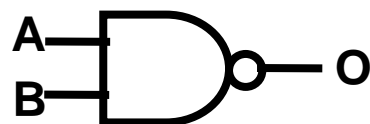
	Voltage dependency	Temperature dependency	Application of substrate bias(Reverse)
Sub-threshold leak	small	large	decrease
Gate leak	large	small	non
Junction leak	large	small	increase

- The component of leakage varies depending on junction temperature.
- Can be reduced by controlling power supply voltage and substrate bias.

Substrate Node of Logic Gate

Examples of logic gates

○ 2 input NAND ($O = \overline{A \cdot B}$)

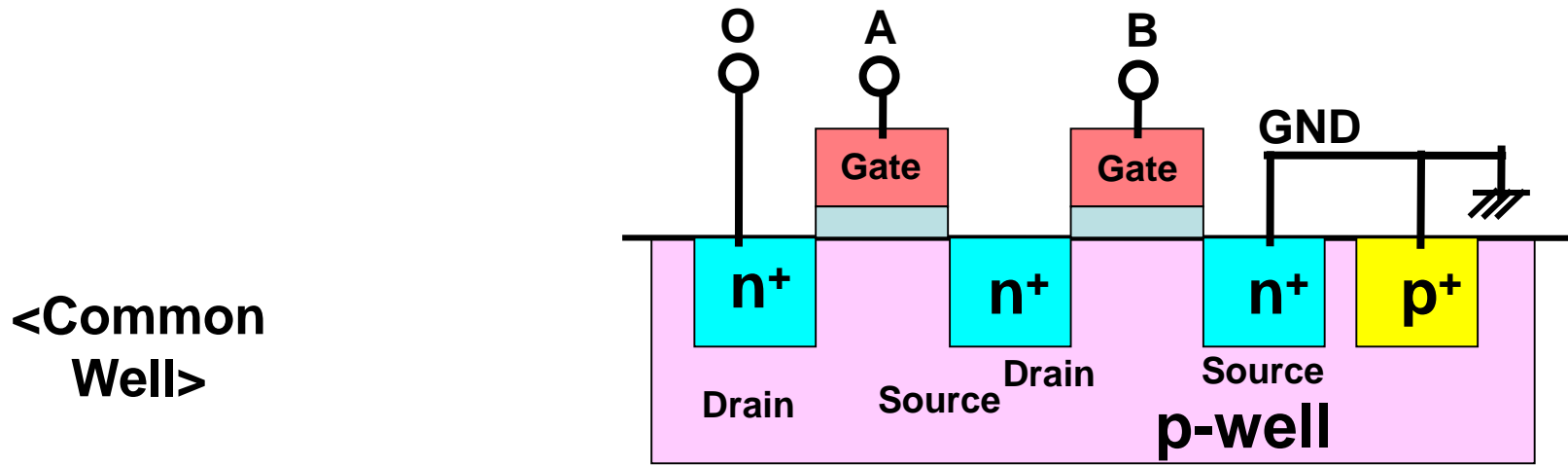
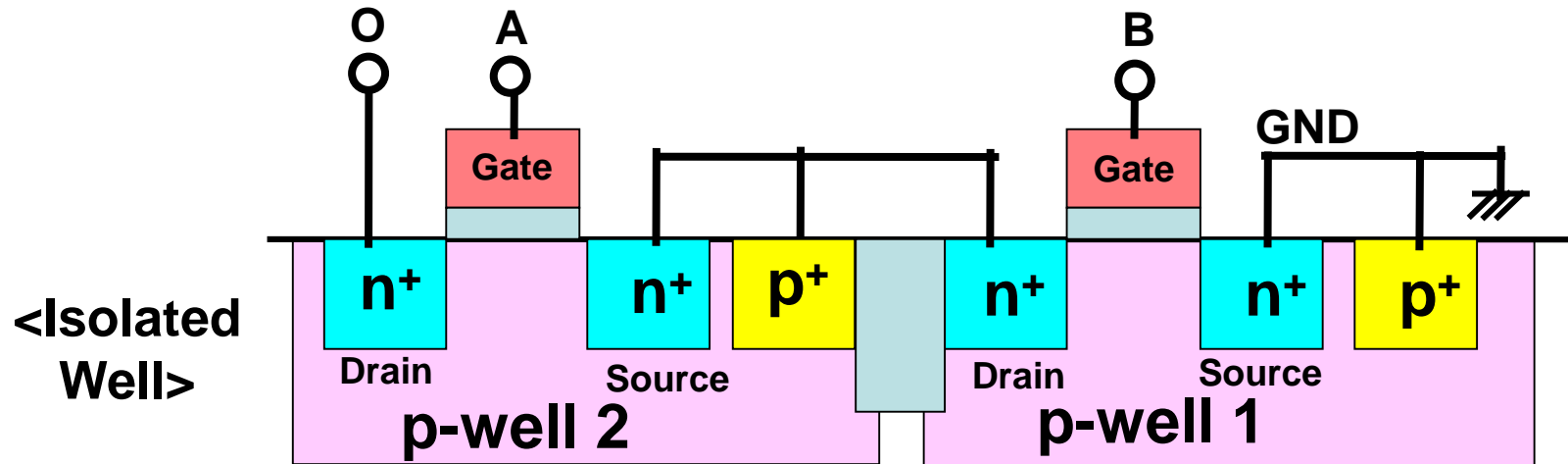


V_{thn} of this transistor is increased because V_{bs} becomes negative in some cases: **body effect**.

To prevent body effect of this transistor, its WELL might be isolated from that of lower transistor, which makes cell layout area irresistibly larger.

→ **WELL is commonly formed in typical designs.**

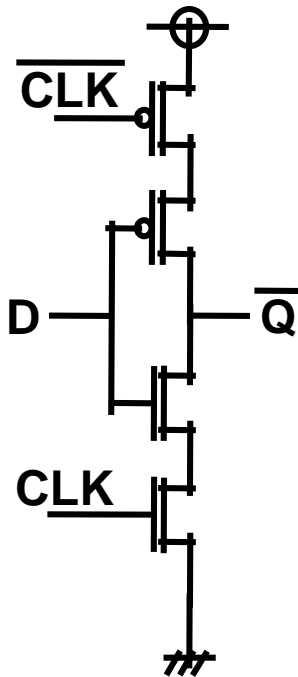
Device Isolation



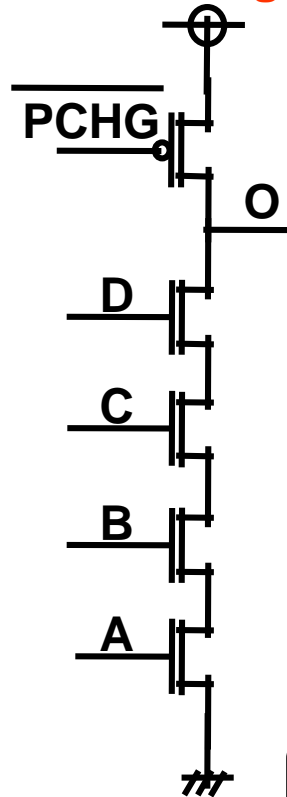
Tricky Circuits

Less transistor counts, but more traps

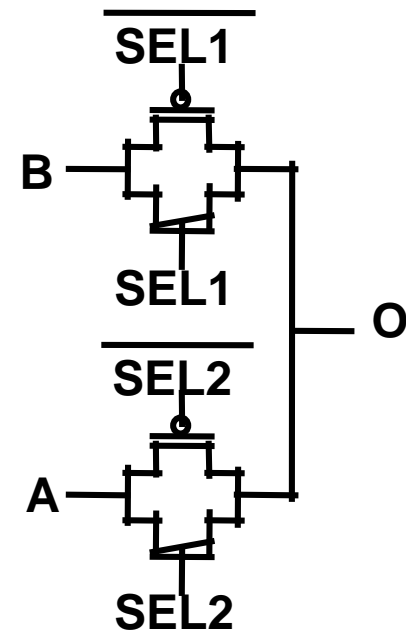
**clocked gate
(dynamic latch)**



**dynamic
4-NAND gate**



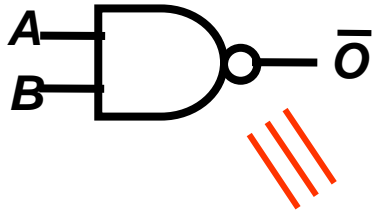
**multiplexer
(selector)**



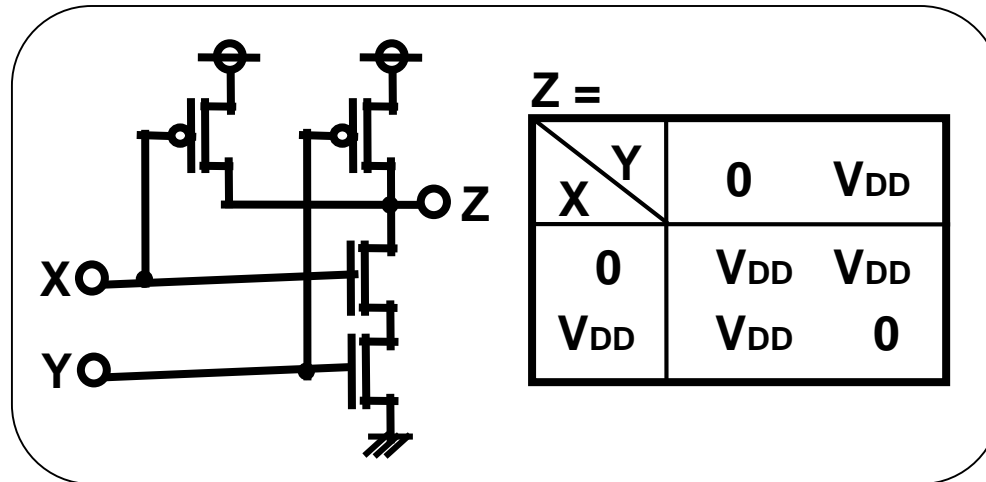
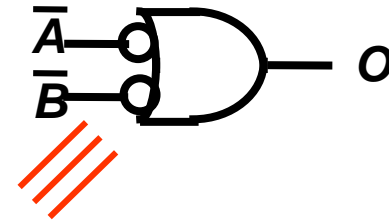
Extensive review is a MUST!

Polarity

○ 2 input NAND ($\bar{O} = A \cdot B$)

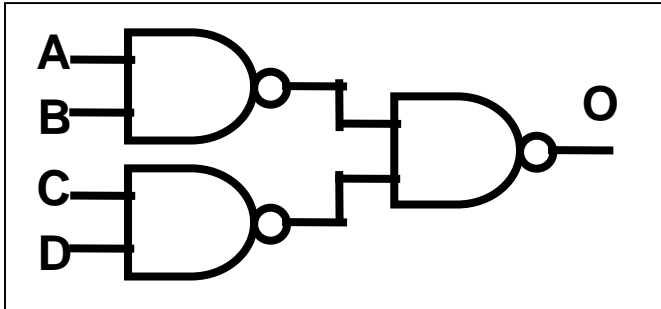


○ 2 input OR ($O = \bar{A} + \bar{B}$)



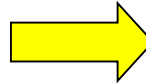
- ◆ NAND gate acts as NAND or OR depending upon input polarity.
- positive logic: “0” = 0V, “1” = V_{DD}
- negative logic: “0” = V_{DD} , “1” = 0V

Exercise 3

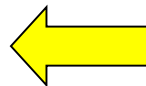


Actual simplified circuit

Rewrite symbols

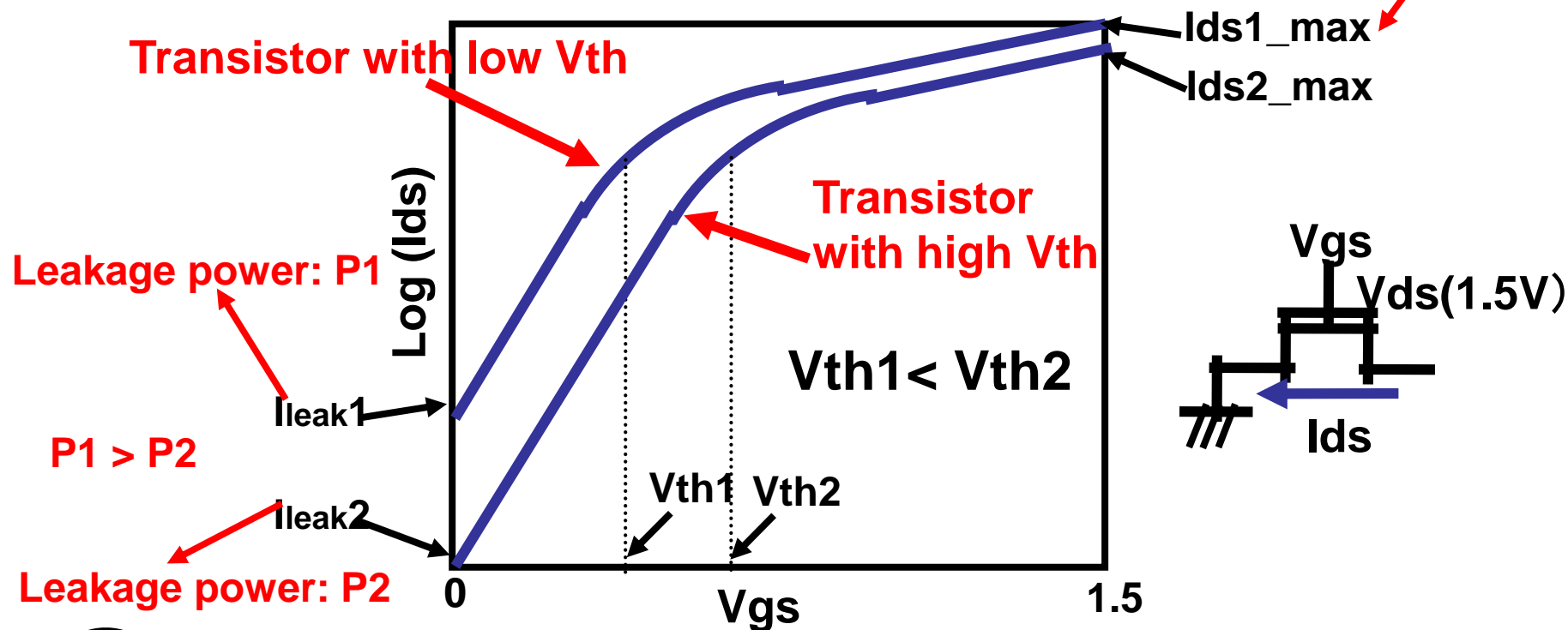


Simplify symbols



Relationship between threshold voltage and drain current (2)

< Different transistor characteristics according to different V_{th} >



- ◆ V_{th} can be tuned during fabrication by ion implantation.
- ◆ Transistor with lower V_{th} is?

What is the relation between I_{ds} and speed of CMOS ?

Please refer to slide: Propagation delay time

- The Load Capacitance at the output of CMOS Inverter always exists.

- # This capacitance consists of stray capacitance of wiring, junction

- # capacitance at drains, gate capacitance of succeeding circuit.

- Due to Load Capacitance, output of CMOS Inverter can NOT change immediately whenever input changes. It make a delay time at the output (as you saw in slide : Delay time)

=> This delay time = time for charging/discharging the load capacitors, and it depends on charged/discharged current I_{ds} .

If I_{ds} is large,charging/discharging time is small=>delay time is small.

If I_{ds} is small,charging/discharging time is large=>delay time is large.

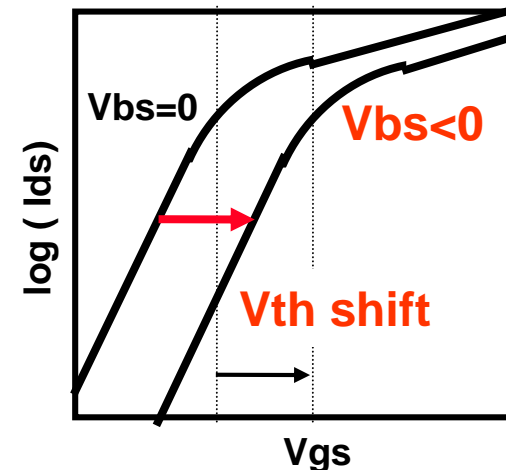
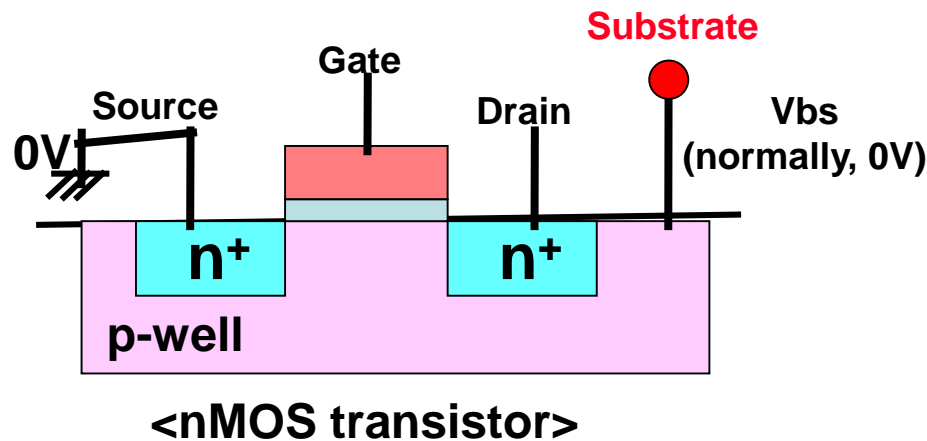
"Speed of a circuit" is related to response time of circuit.

If delay time is smaller, the circuit is faster

If delay time is larger, the circuit is slower

Substrate Node Potential

- Electrical potential of substrate (formed by WELL structure) as 4th electrode also affects transistor characteristics.



< threshold voltage dependency on substrate voltage >

$$V_{th} = V_{t0} + k(\sqrt{-V_{bs} + 2\phi} - \sqrt{2\phi})$$

V_{t0} , k , ϕ : constants

BD002

Body Effect

<nMOS>

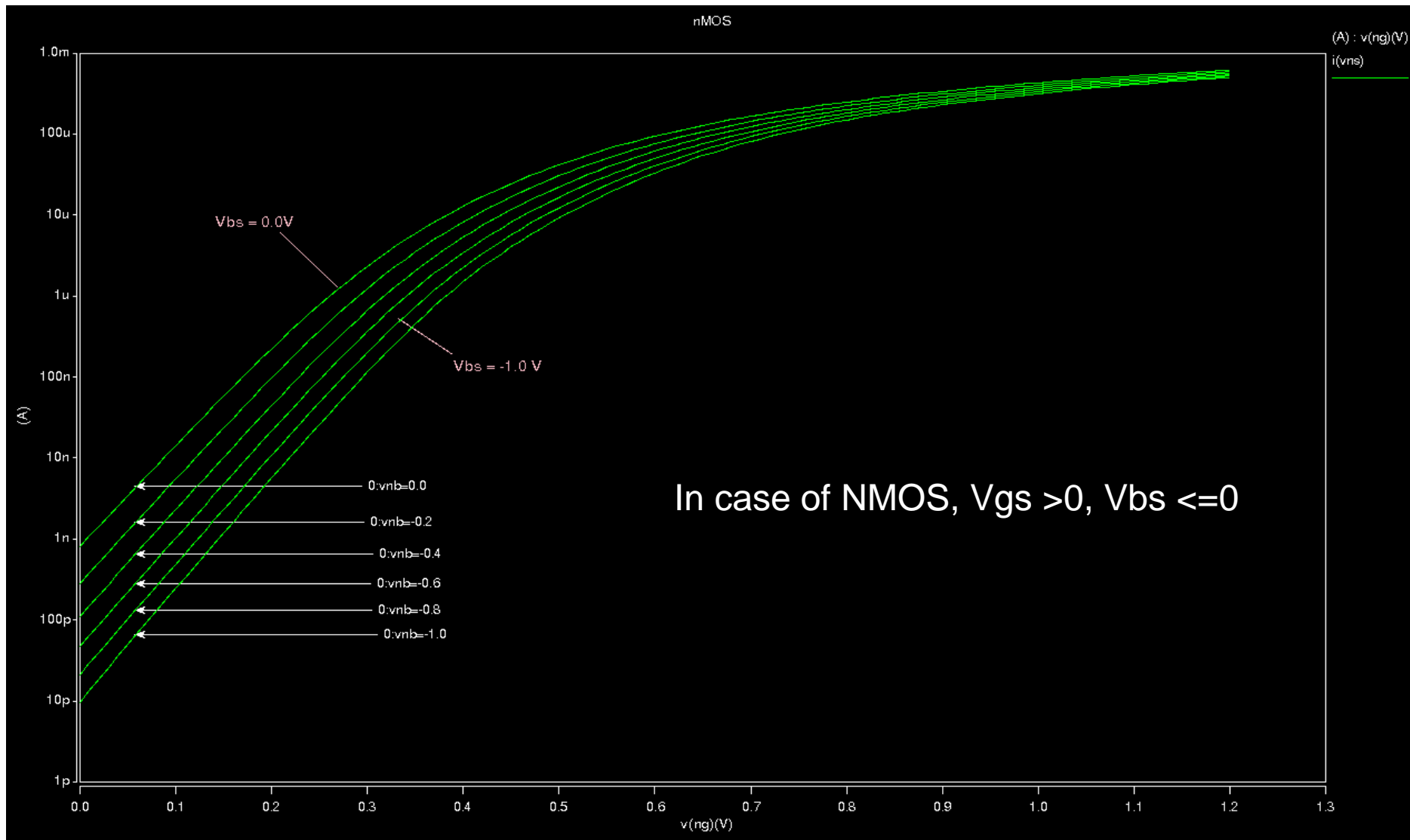
- * $V_{bs} \ll 0$, then ...?
- * speed, leakage...?

<pMOS>

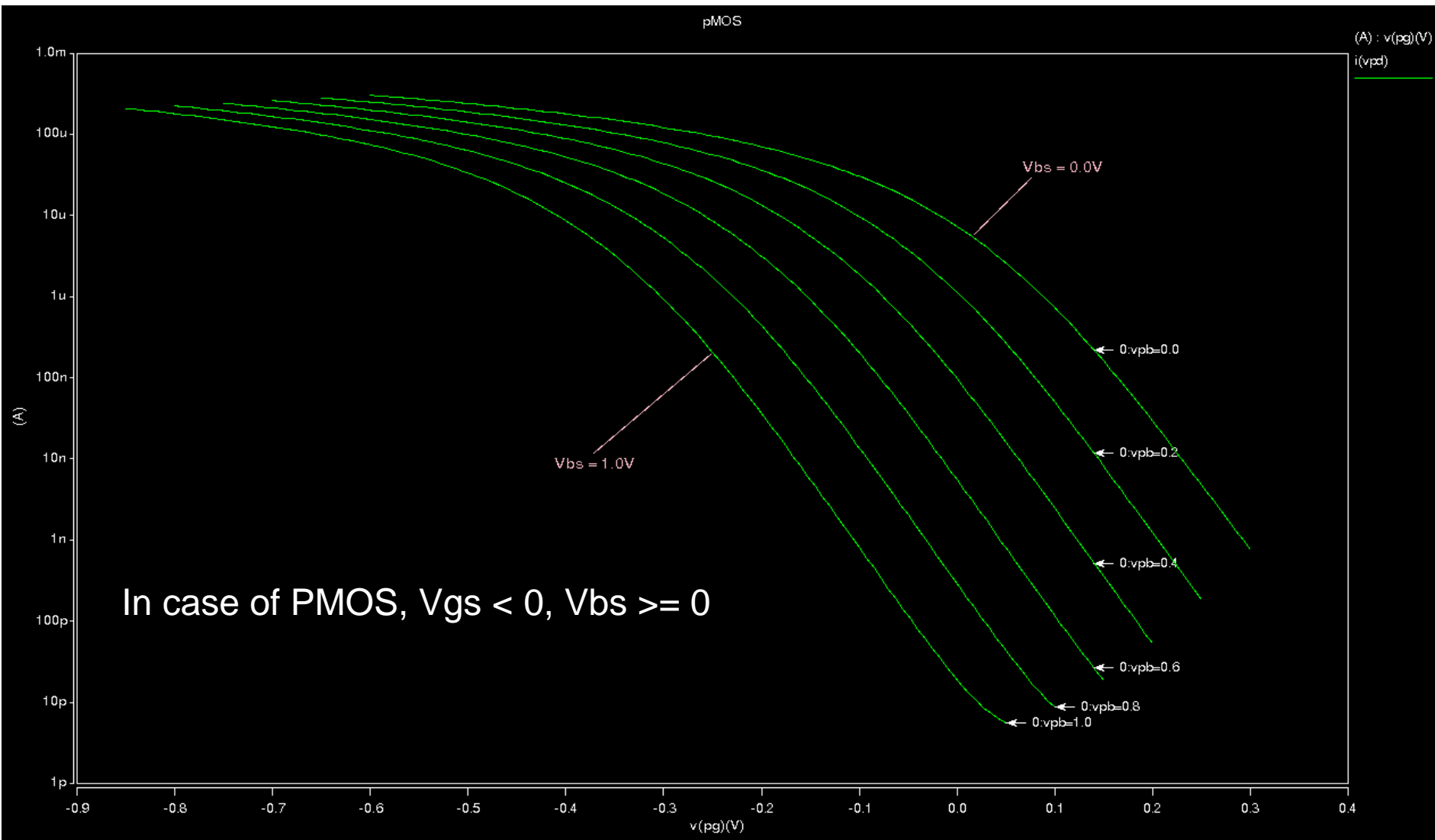
- * $V_{bs} \gg 0$, then ...?
- * speed, leakage...?



Substrate Node Potential - NMOS



Substrate Node Potential - PMOS





Renesas Electronics Corporation