

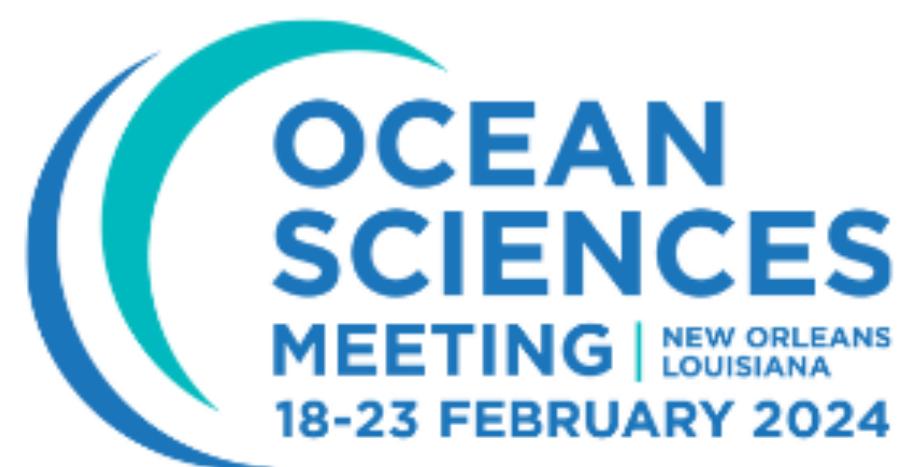
A large, semi-transparent image of an underwater environment occupies the left side of the slide. It shows a coral reef with various types of coral, including brain coral and soft coral, in shades of yellow, orange, and brown. Small, silhouetted fish are scattered throughout the water column. A bright white diagonal band cuts across the image from the top-left corner to the bottom-right corner.

Toward Improved OHC Mapping and Uncertainty Quantification by Modeling Vertical Spatio-temporal Dependence

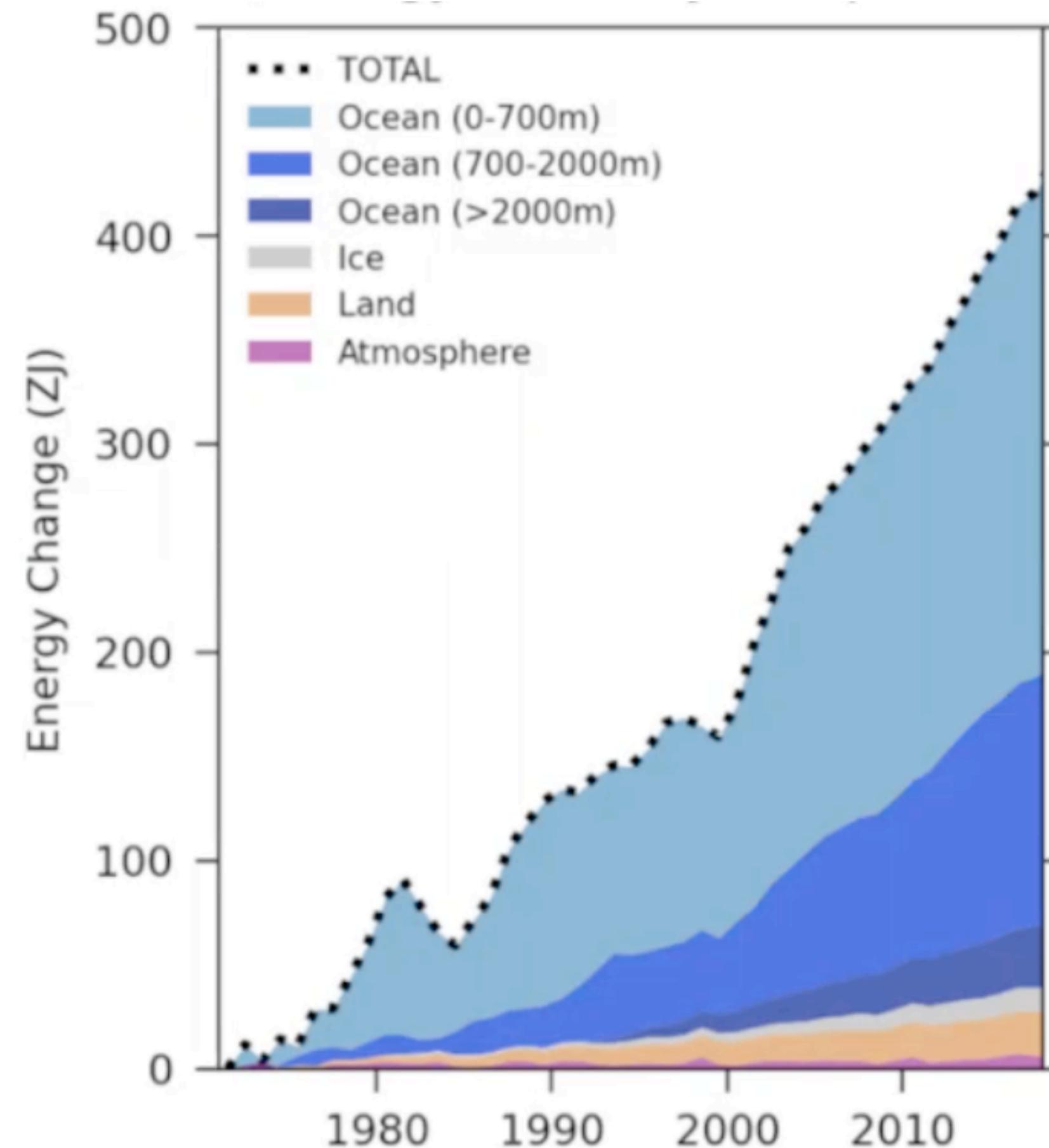
Thea Sukianto¹
Donata Giglio²
Mikael Kuusela¹

¹Carnegie Mellon University
²University of Colorado Boulder

#OSM24

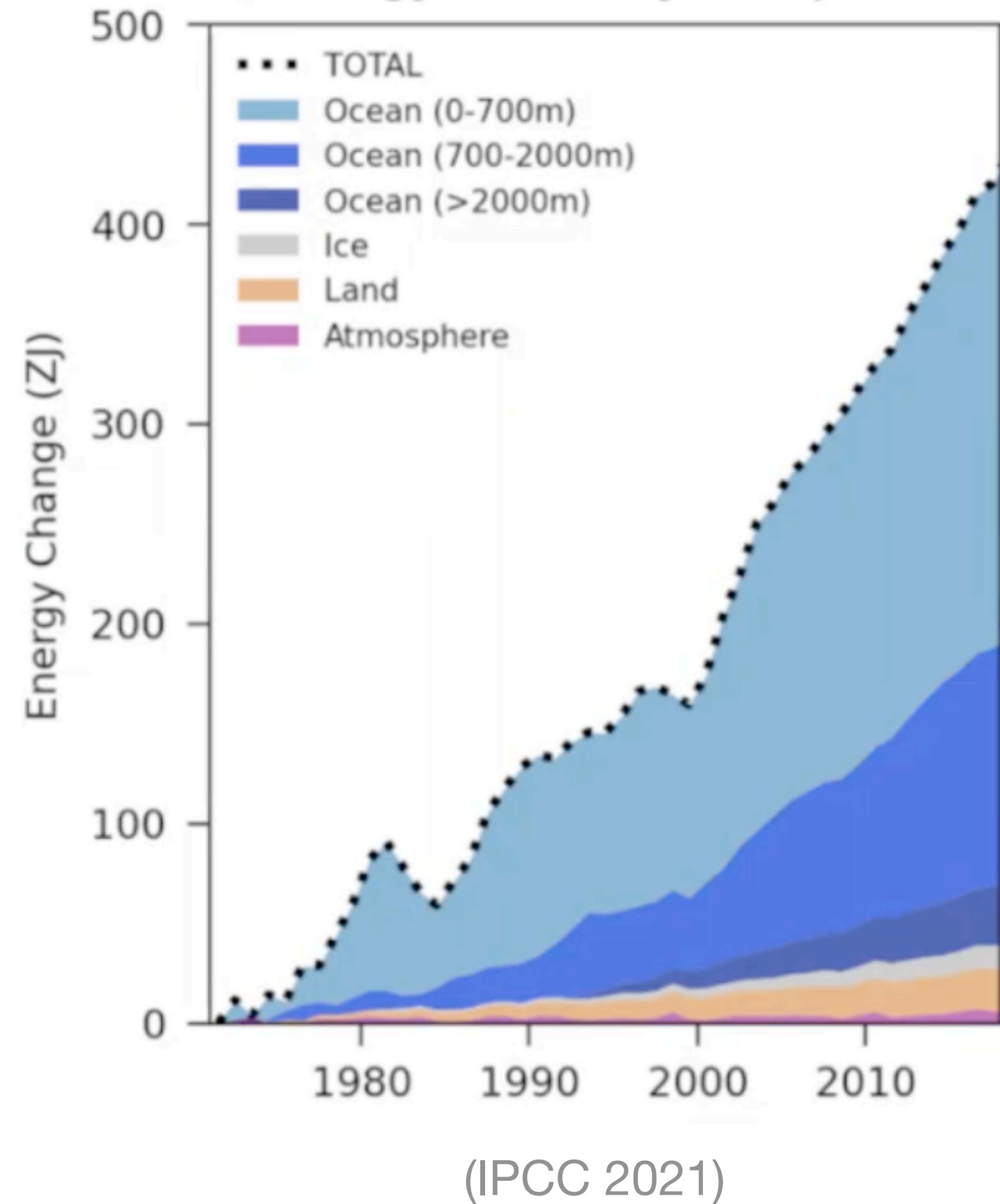


Most of the excess heat in the climate system has been stored in the ocean



(IPCC 2021)

Changes in OHC contribute to extreme climate events

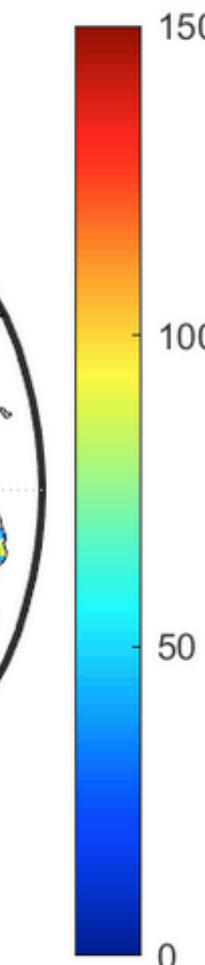
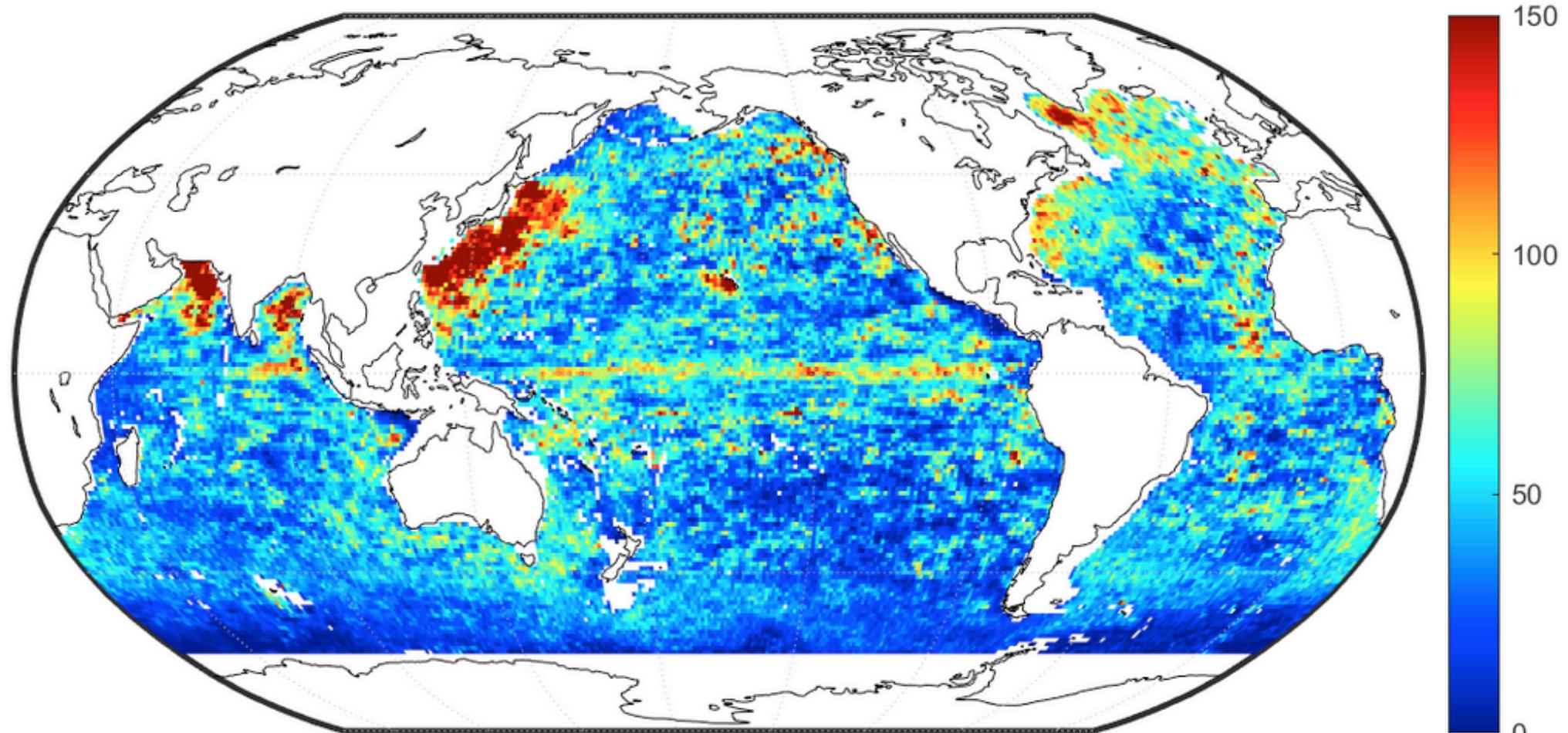


Intensified tropical storms

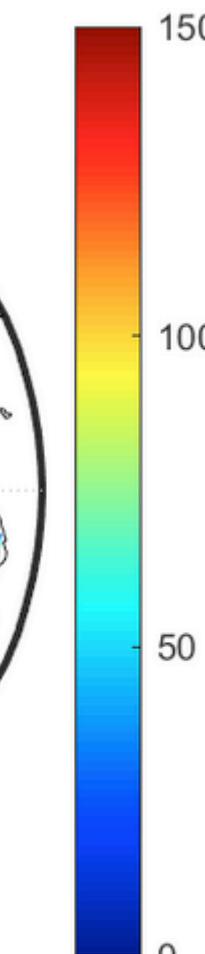
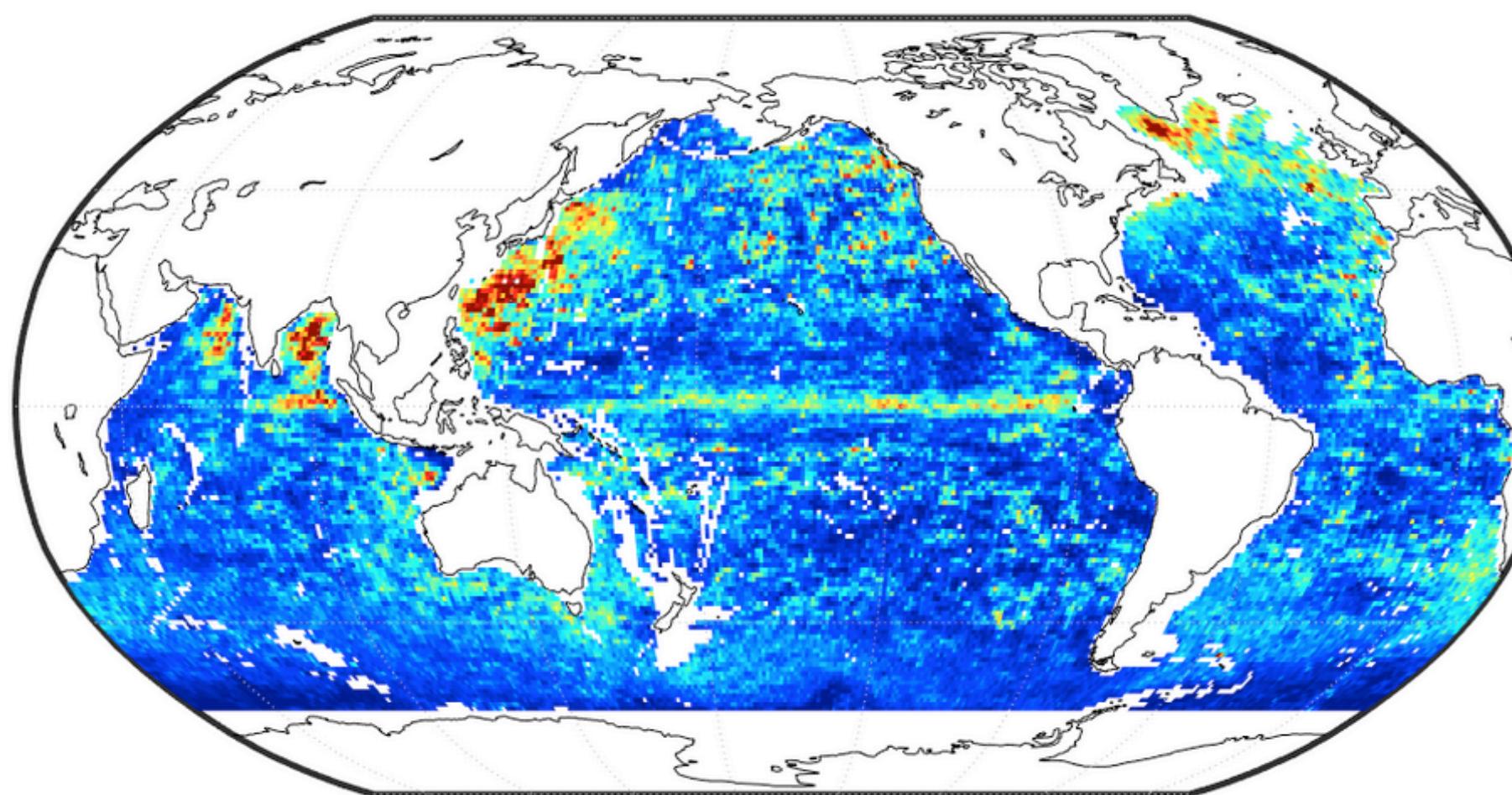


Rising sea levels

We use Argo data (2004-2021) to estimate 15-1850 dbar OHC

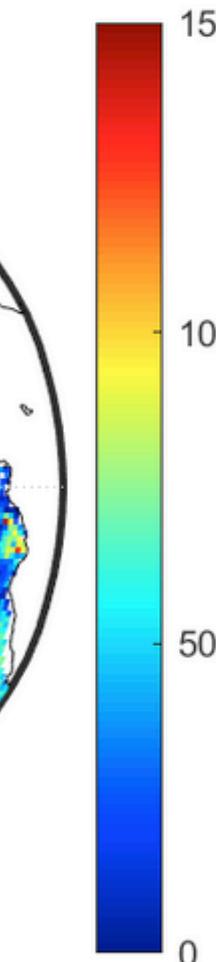
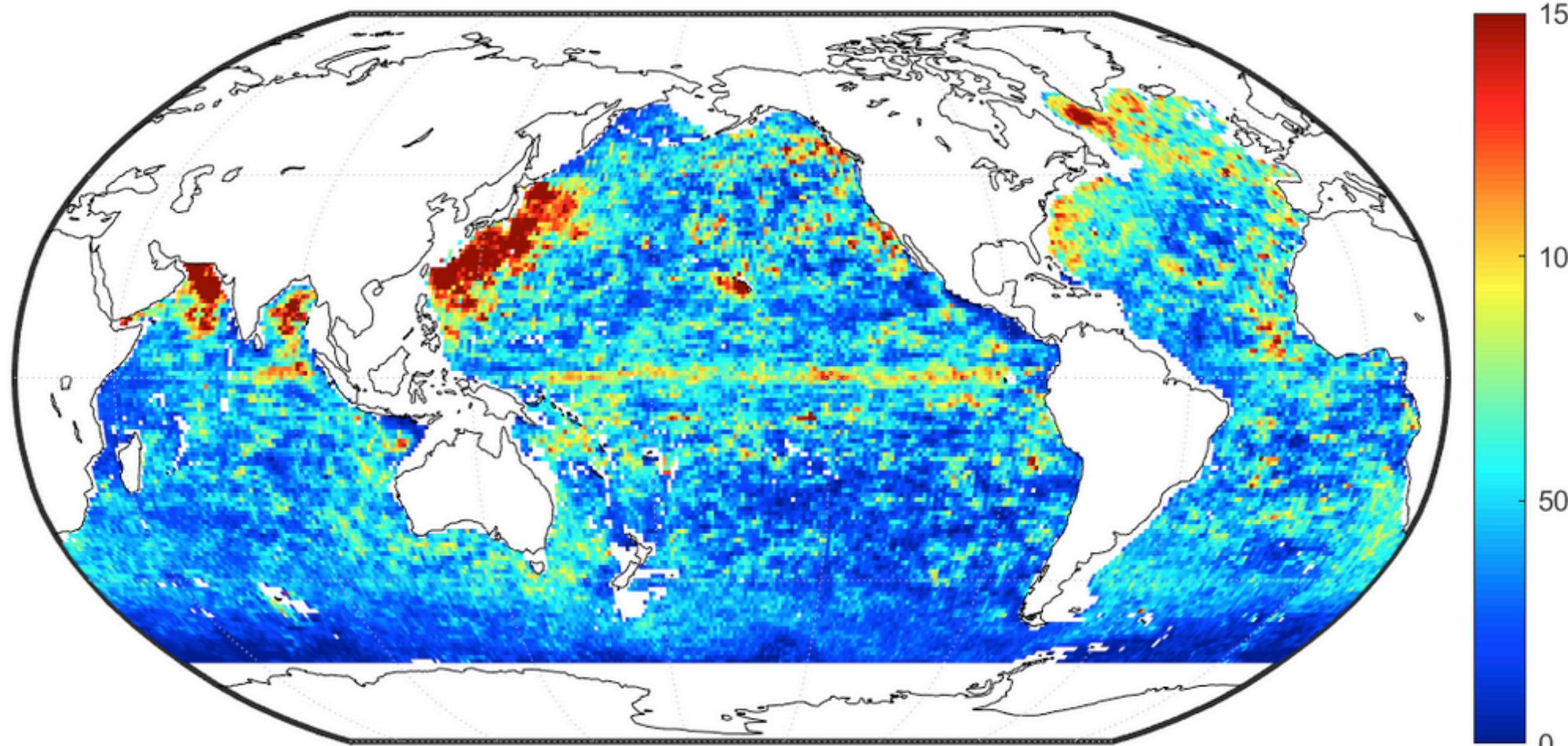


→ Top layer profiles (15-975 dbar)

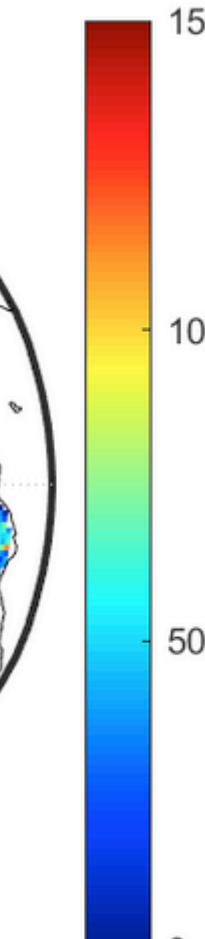
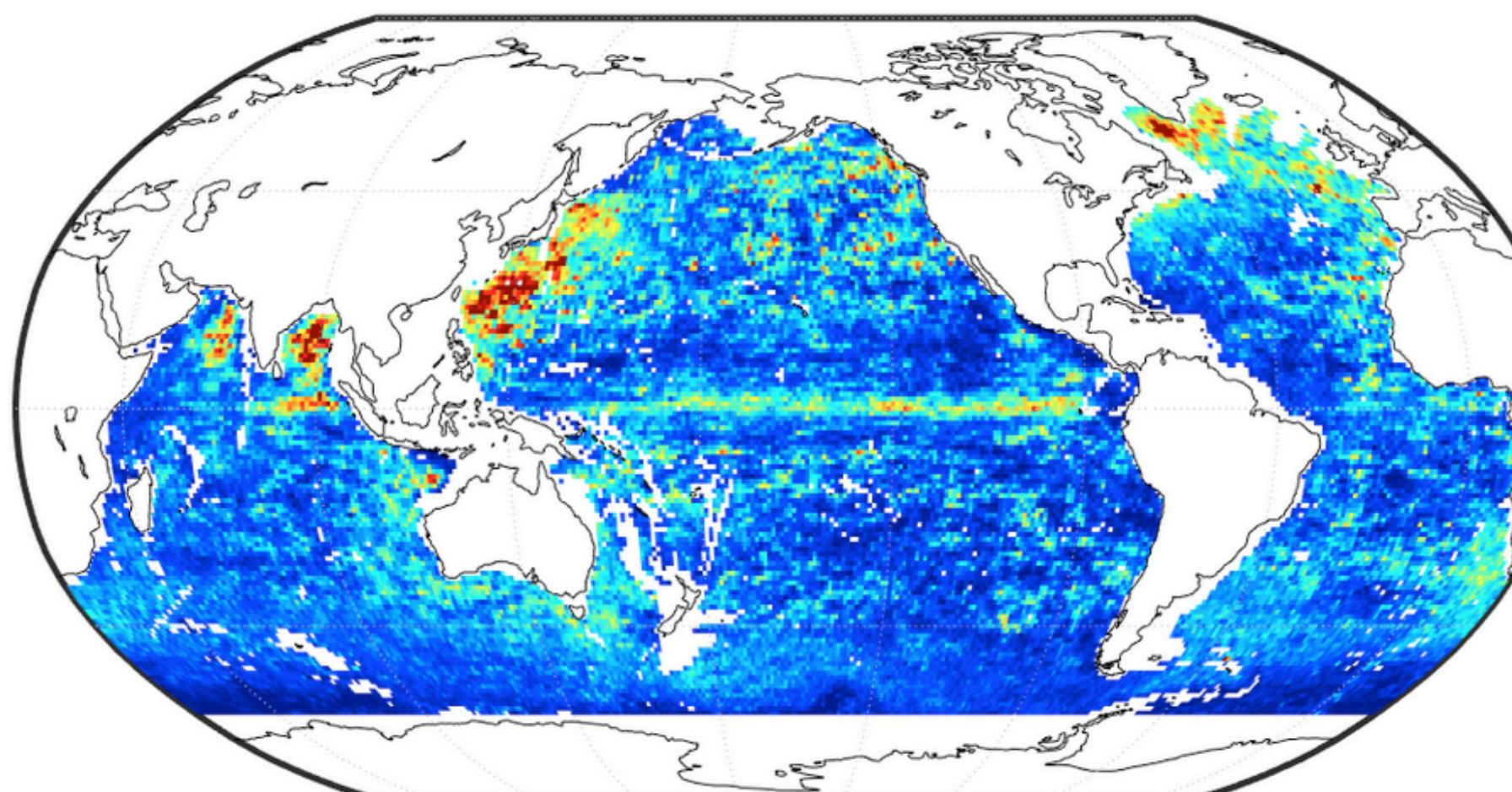


→ Bottom layer profiles (975-1850 dbar)

We use Argo data (2004-2021) to estimate 15-1850 dbar OHC



→ Top layer profiles (15-975 dbar)



→ Bottom layer profiles (975-1850 dbar)

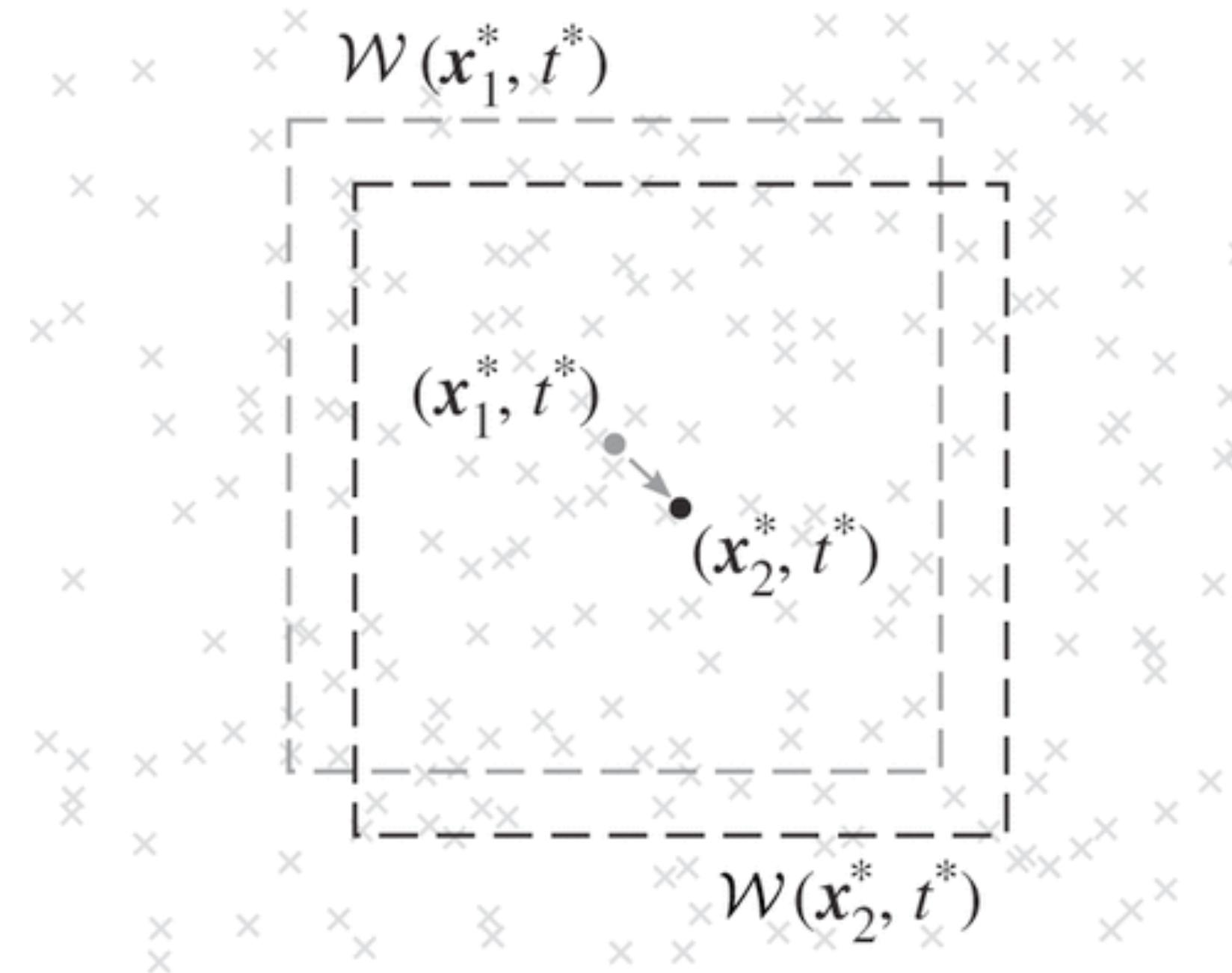
Due to having fewer observations deeper in the water column, we model the OHC in the top and bottom layers **separately**.

How do we model OHC from sparse observations?

1. Model the **vertical dimension** (consider two layers and integrate Argo profiles in each layer)
2. Model **horizontal and temporal dimension**
3. Estimate **uncertainties** based on (1) and (2)

We can estimate a gridded temperature field with GP regression

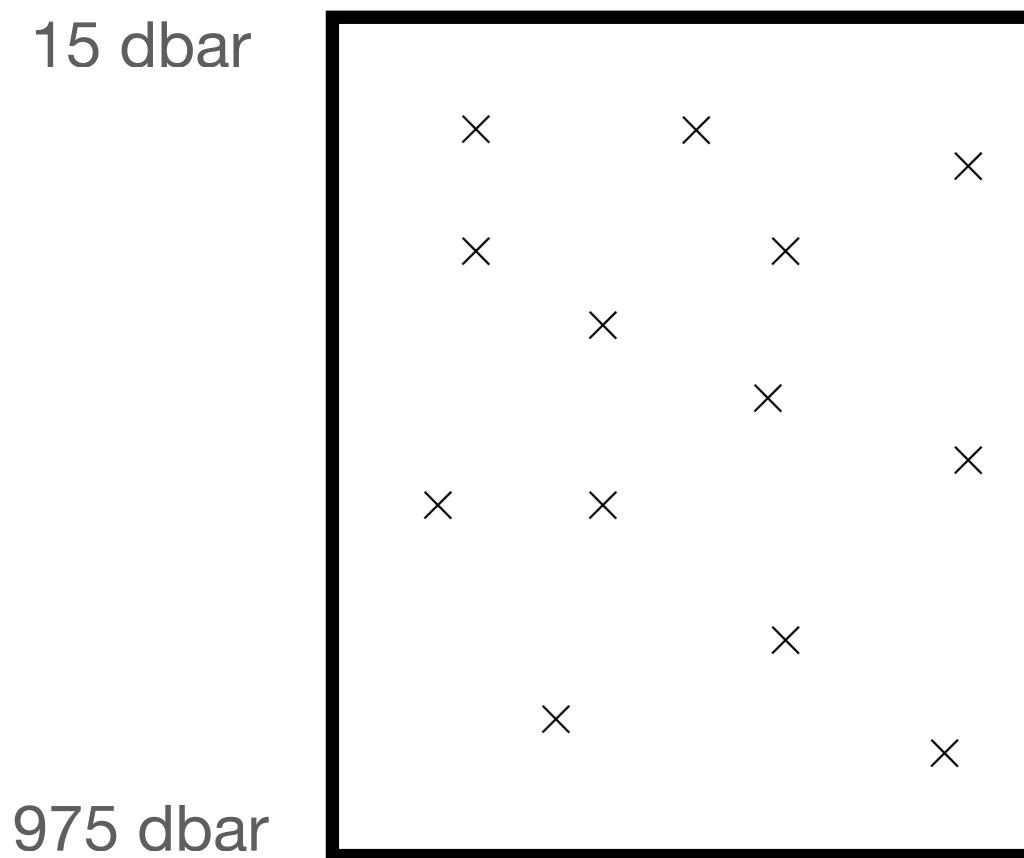
1. Model temperature mean field: local least squares regression (Roemmich and Gilson 2009) + linear time trend
2. Model residuals (**anomalies**): locally stationary Gaussian process (GP) regression (Kuusela and Stein 2018)



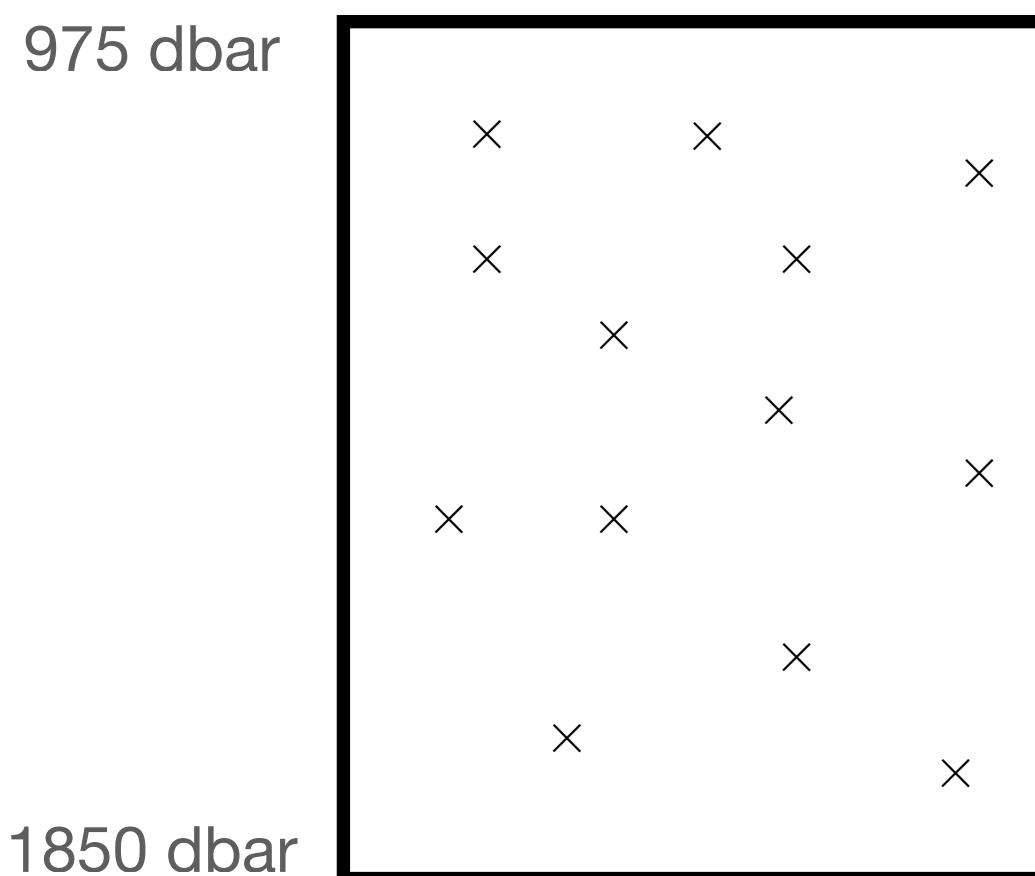
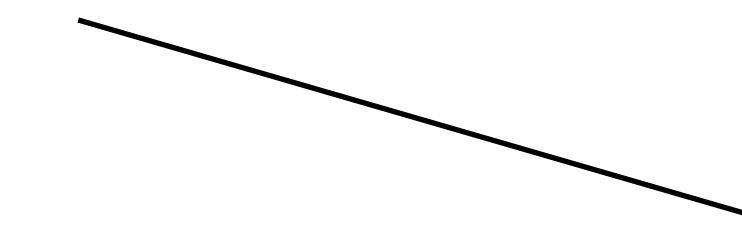
How do we estimate uncertainties for the total (top + bottom layers) OHC?

$$\text{Var}(\text{OHC}_{\text{total}}|\text{data})$$

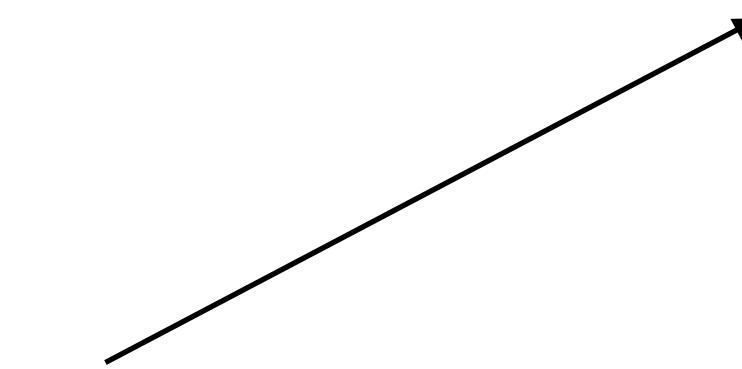
How do we estimate uncertainties for the total (top + bottom layers) OHC?



$\text{Var}(\text{OHC}_{\text{top}}|\text{data})$

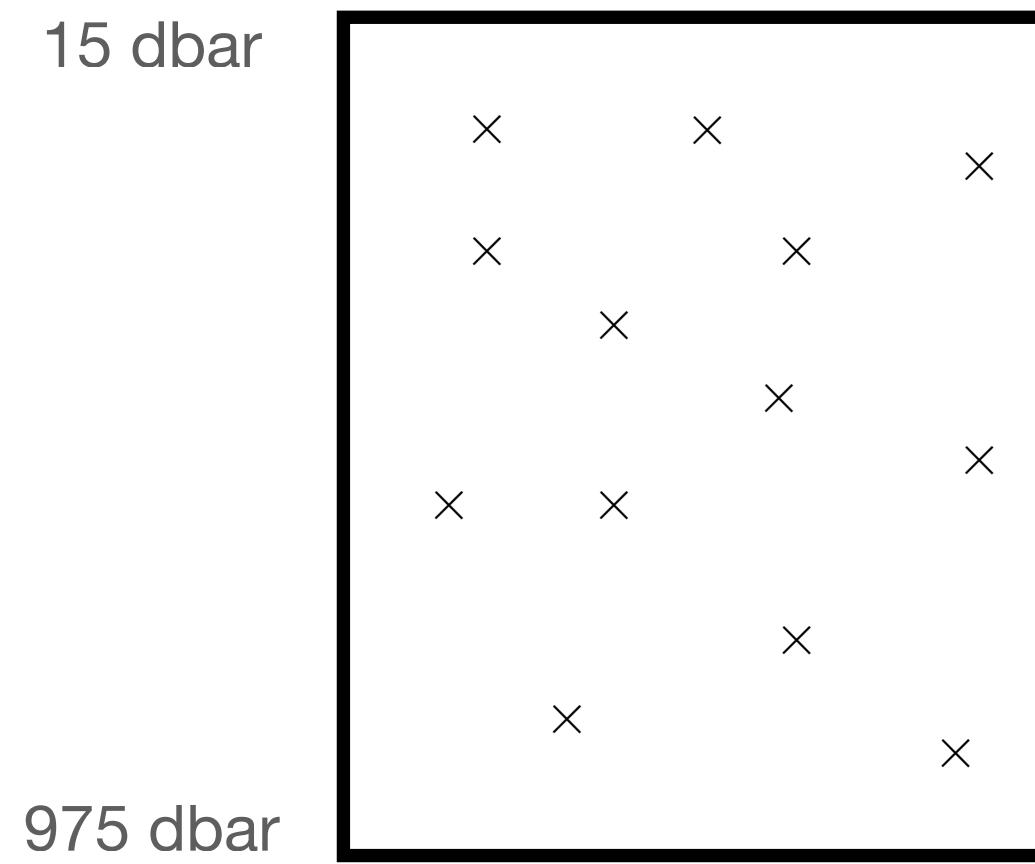


$\text{Var}(\text{OHC}_{\text{bot}}|\text{data})$

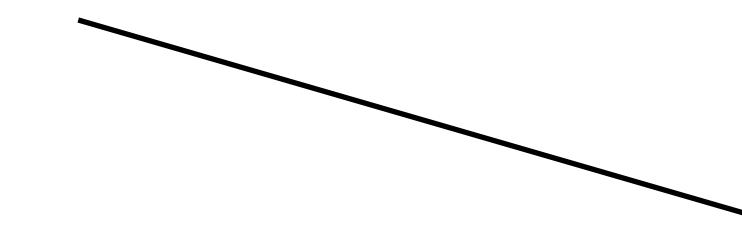


$\text{Var}(\text{OHC}_{\text{total}}|\text{data})$

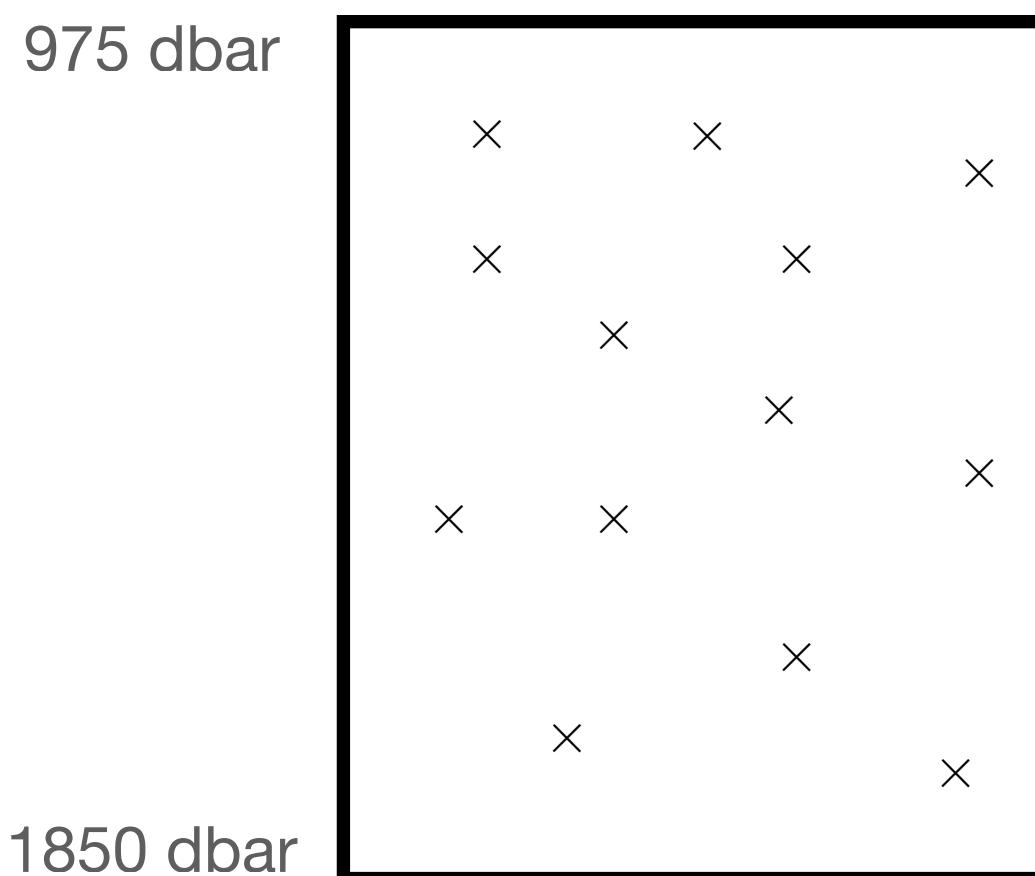
How do we estimate uncertainties for the total (top + bottom layers) OHC?



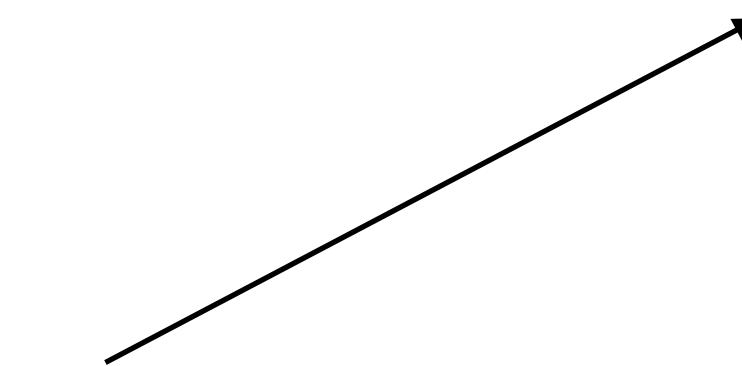
$\text{Var(OHC}_{\text{top}}|\text{data})$



$\text{Var(OHC}_{\text{total}}|\text{data})$



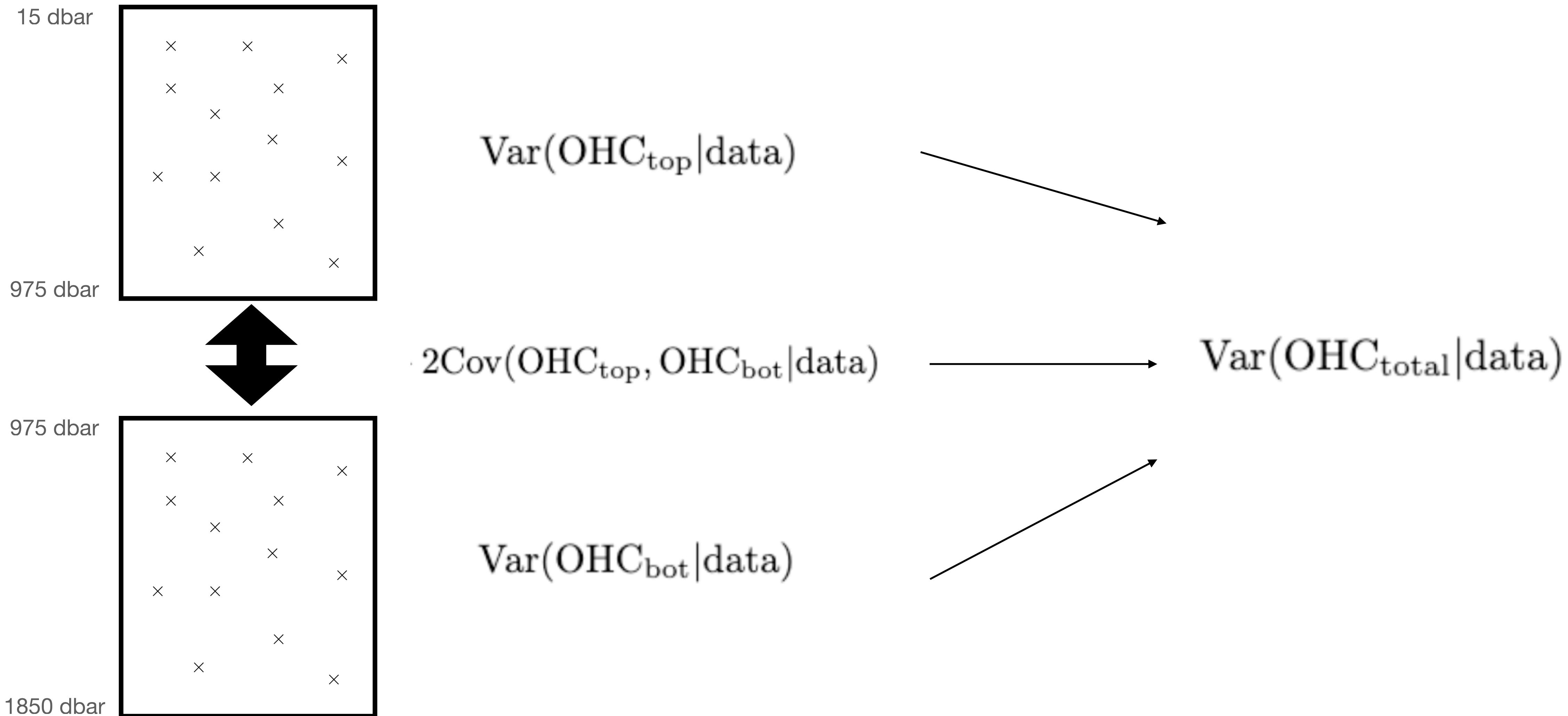
$\text{Var(OHC}_{\text{bot}}|\text{data})$



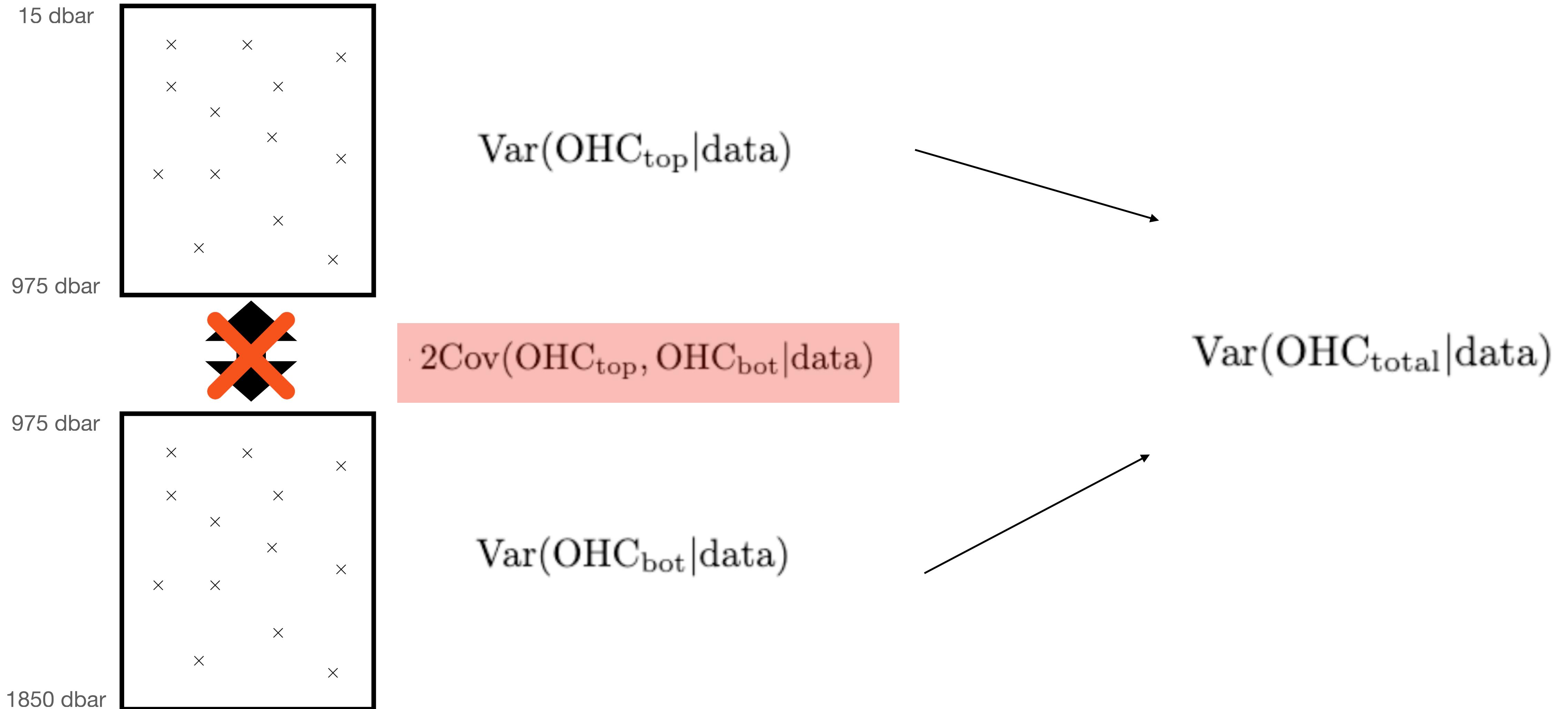
$\text{Var(OHC}_{\text{top}}|\text{data}) + \text{Var(OHC}_{\text{bot}}|\text{data})$

Summing the variances
for each layer
underestimates the
uncertainties of the total
OHC.

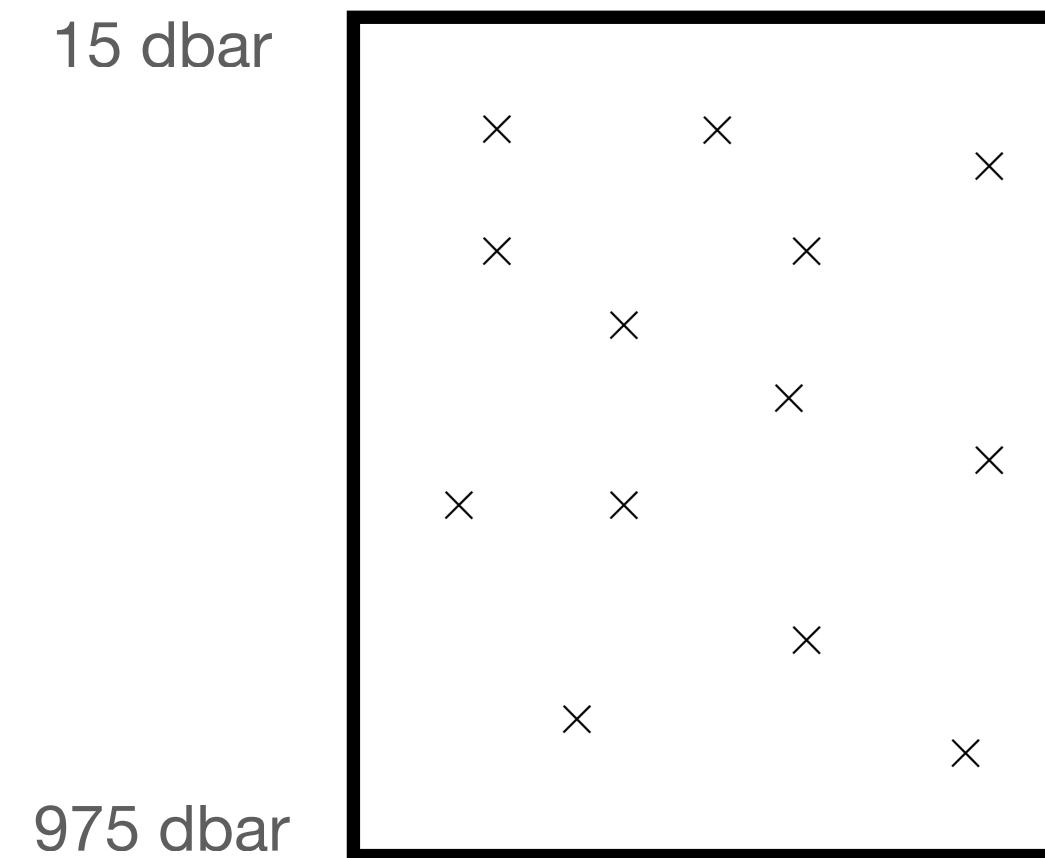
How do we estimate uncertainties for the total (top + bottom layers) OHC?



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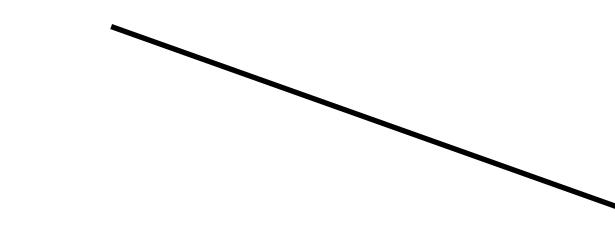


$\text{Var}(\text{OHC}_{\text{top}}|\text{data})$



$2\text{Cov}(\text{OHC}_{\text{top}}, \text{OHC}_{\text{bot}}|\text{data})$

$\text{Var}(\text{OHC}_{\text{bot}}|\text{data})$



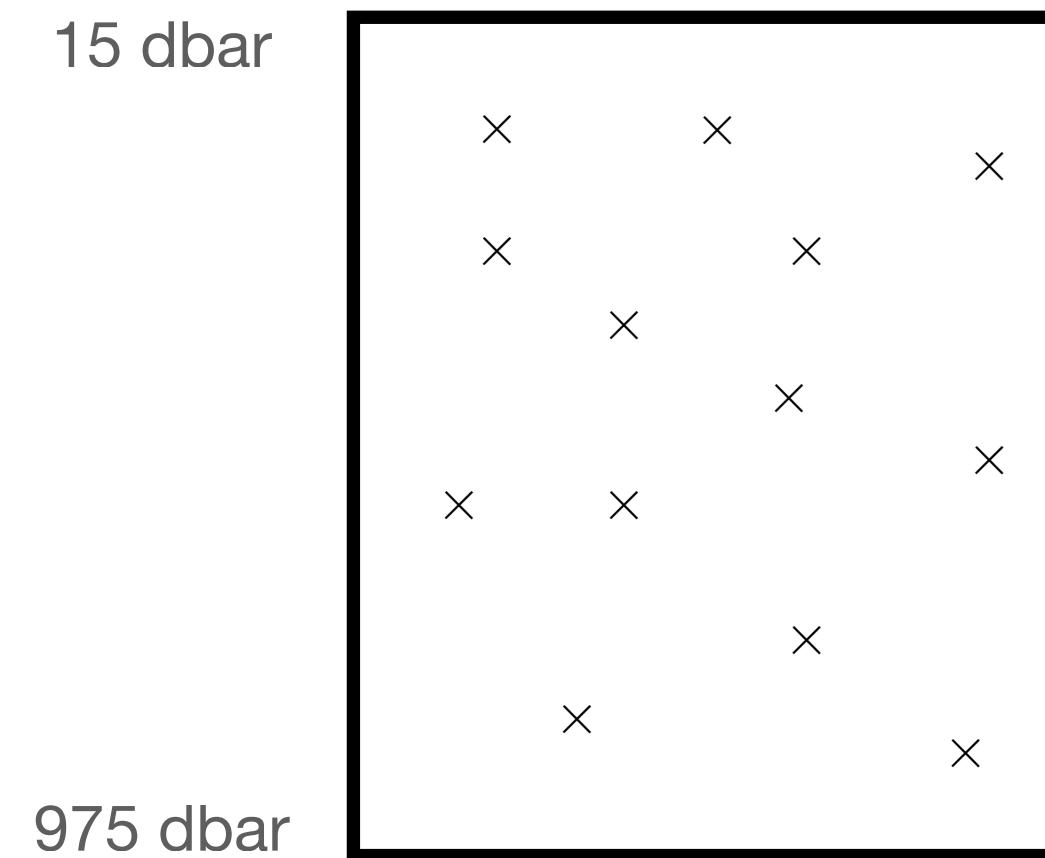
$\text{Var}(\text{OHC}_{\text{total}}|\text{data})$

(conservative upper bound)

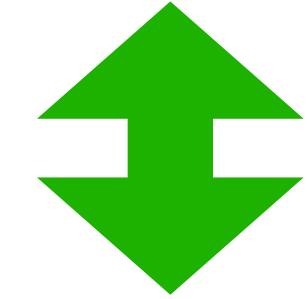
$$(\sqrt{\text{Var}(\text{OHC}_{\text{top}}|\text{data})} + \sqrt{\text{Var}(\text{OHC}_{\text{bot}}|\text{data})})^2$$

Squaring the sum of the standard deviations for each layer **overestimates** the uncertainties of the total OHC.

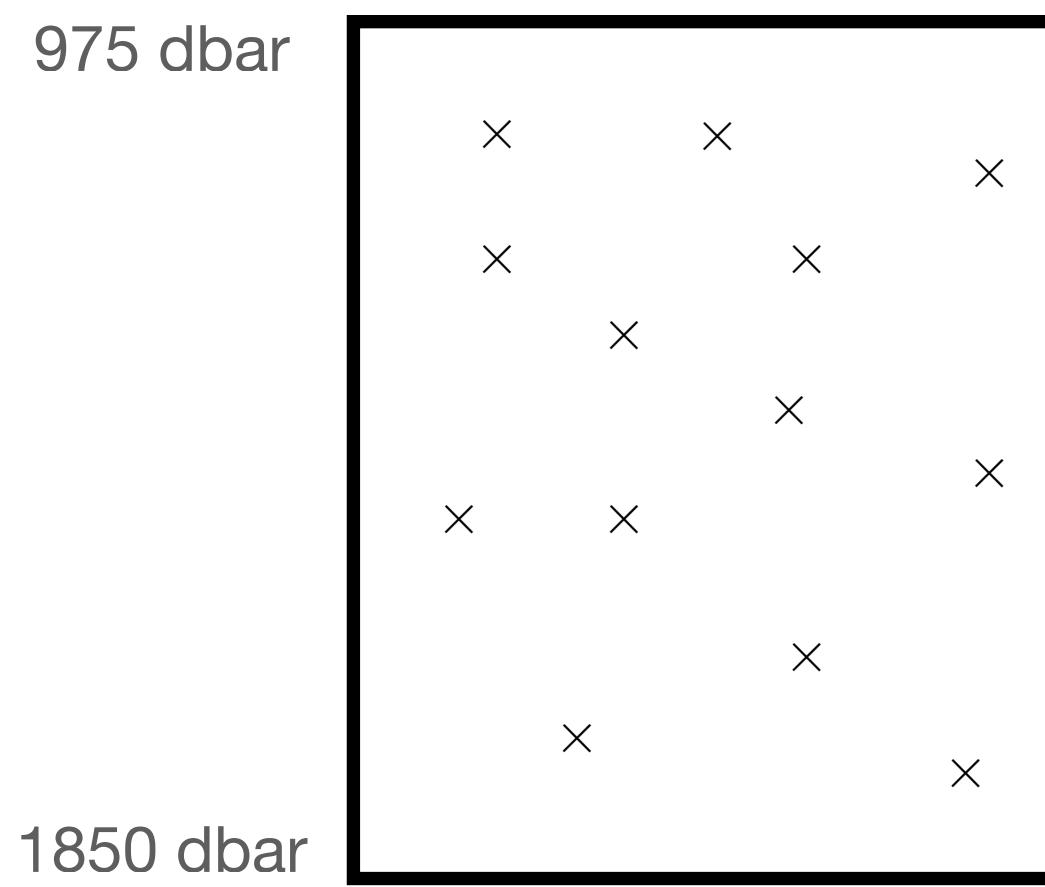
How do we estimate uncertainties for the total (top + bottom layers) OHC?



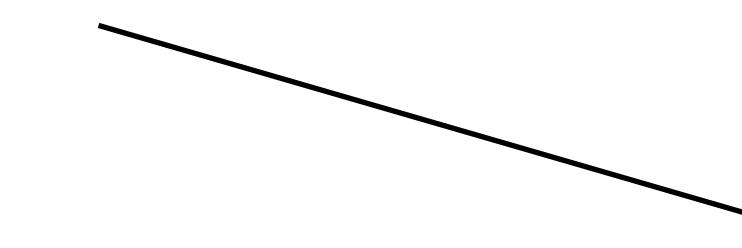
$$\text{Var}(\text{OHC}_{\text{top}}|\text{data})$$



$$2\text{Cov}(\text{OHC}_{\text{top}}, \text{OHC}_{\text{bot}}|\text{data})$$



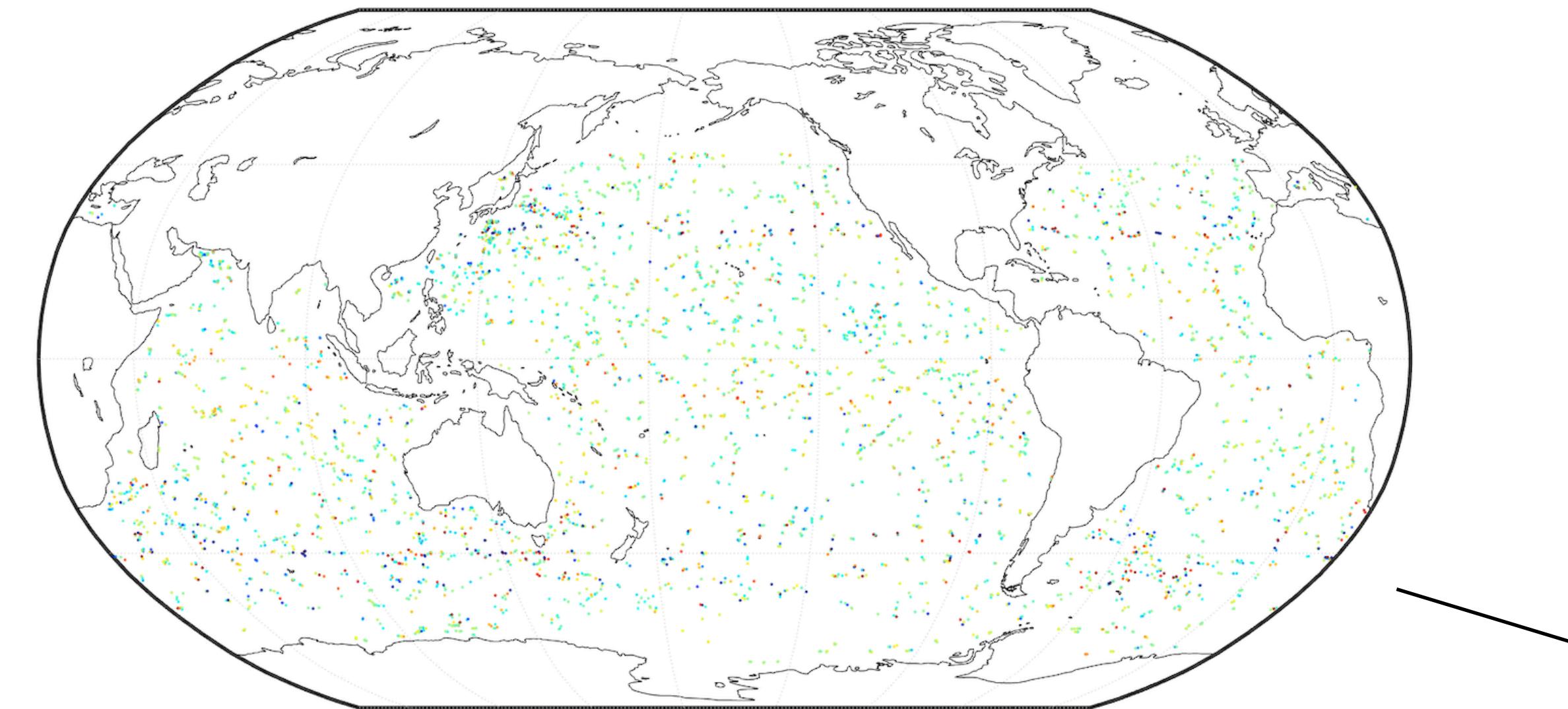
$$\text{Var}(\text{OHC}_{\text{bot}}|\text{data})$$



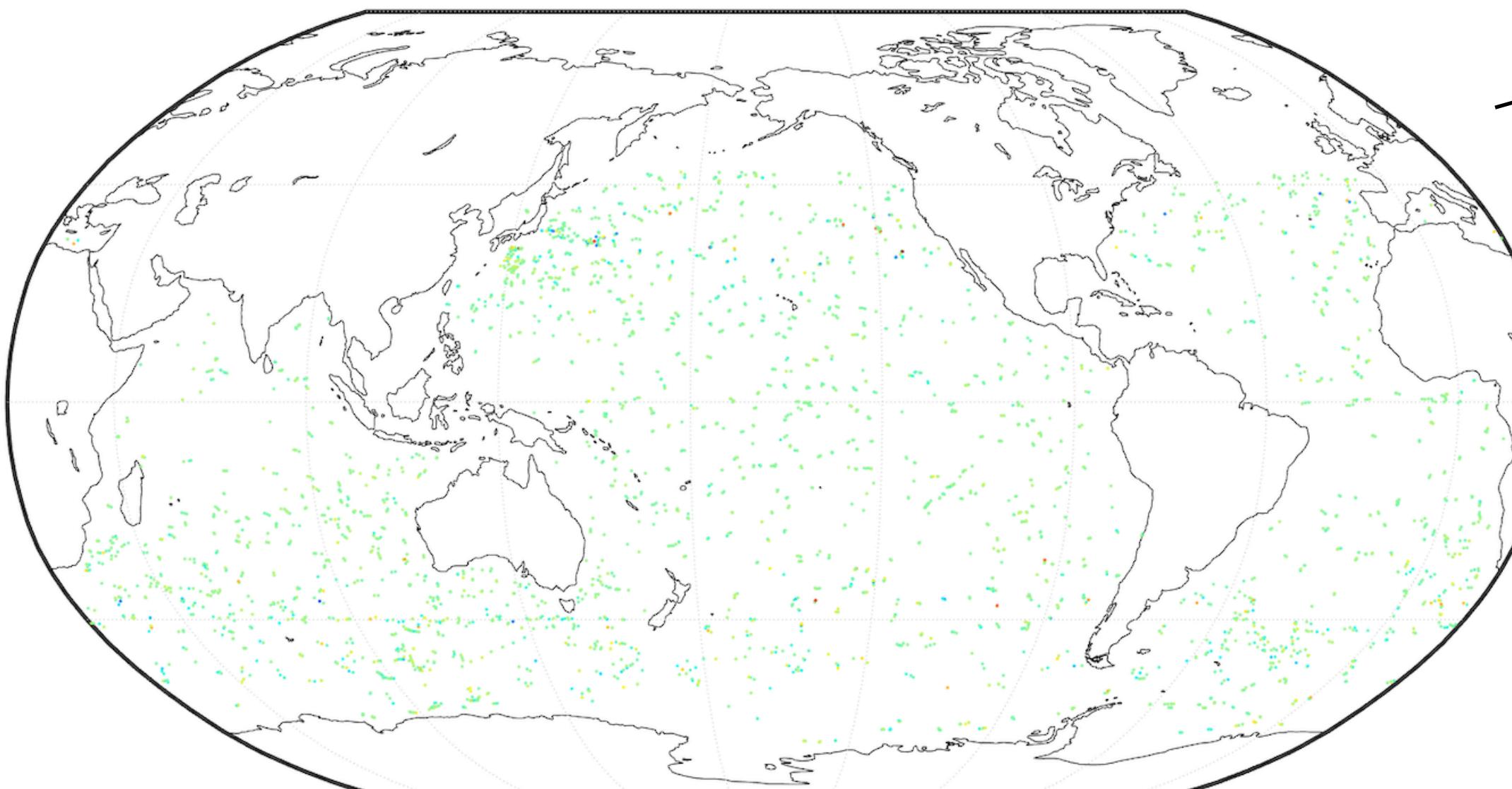
$$\text{Var}(\text{OHC}_{\text{total}}|\text{data})$$

We can improve the uncertainty estimates by also modeling the **correlation**.

A bivariate GP model accounts for cross-layer correlation

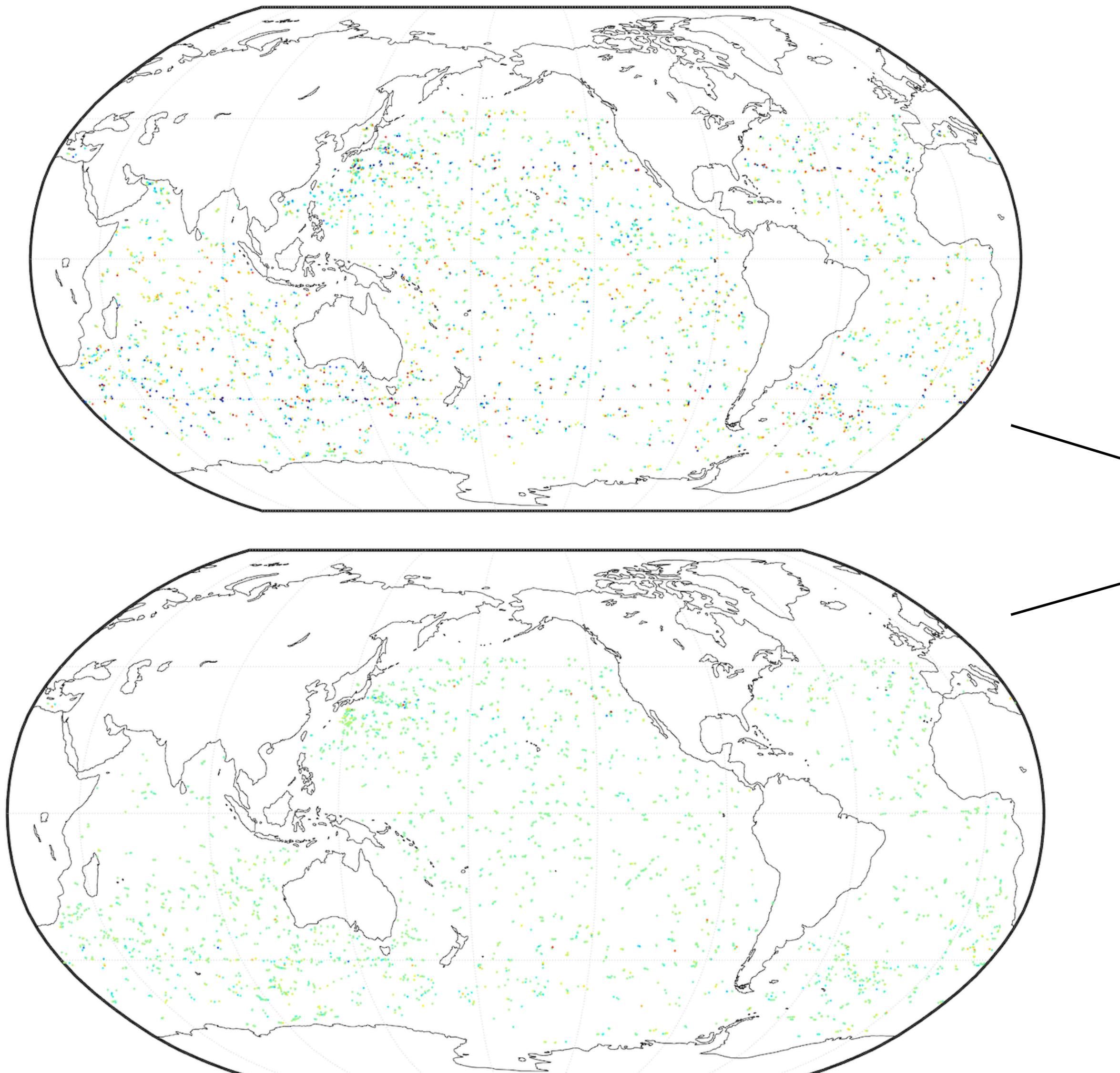


Temperature
residuals



$$\begin{bmatrix} y_{\text{top}} \\ y_{\text{bot}} \end{bmatrix}_{i,j}$$

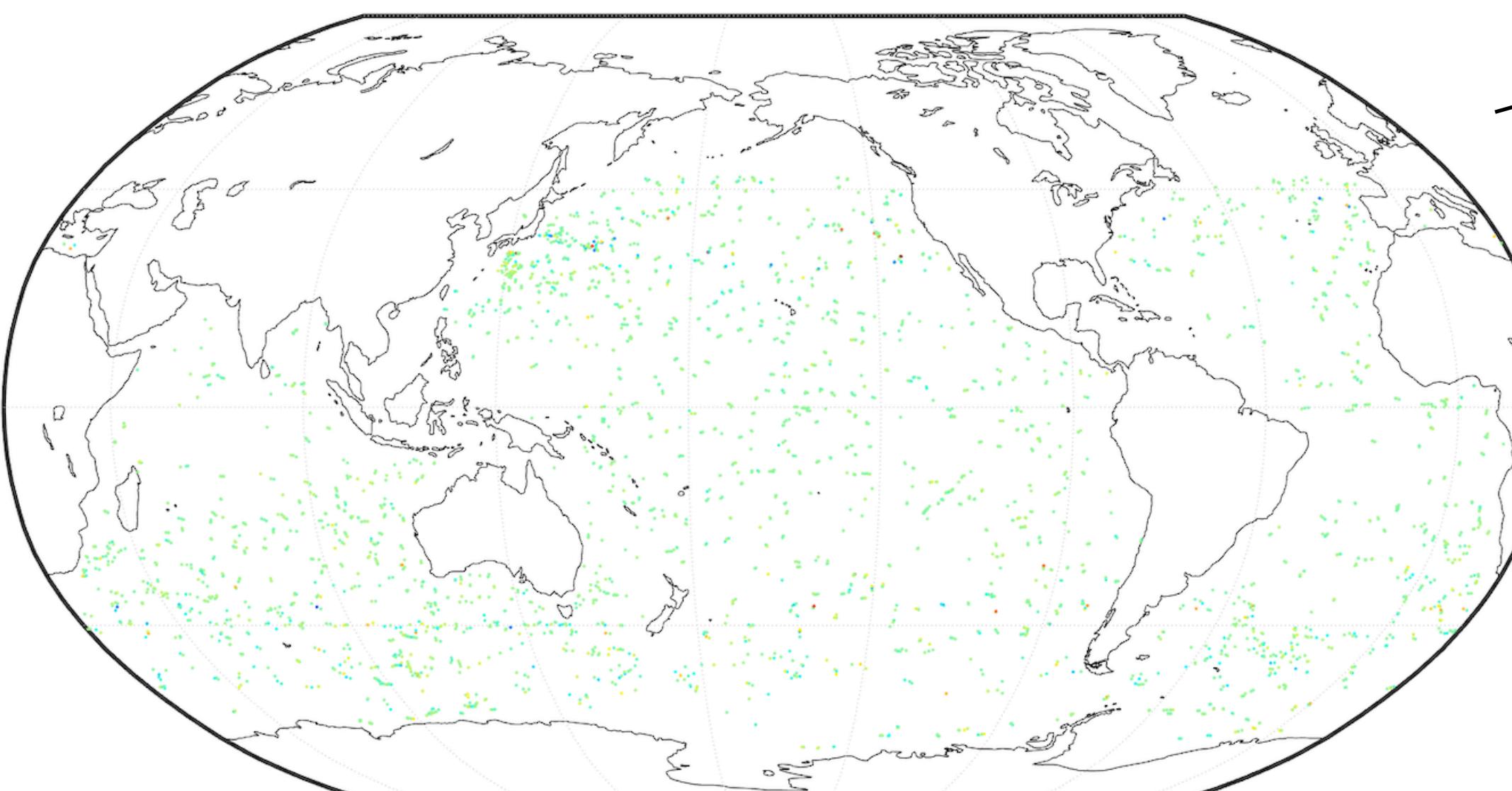
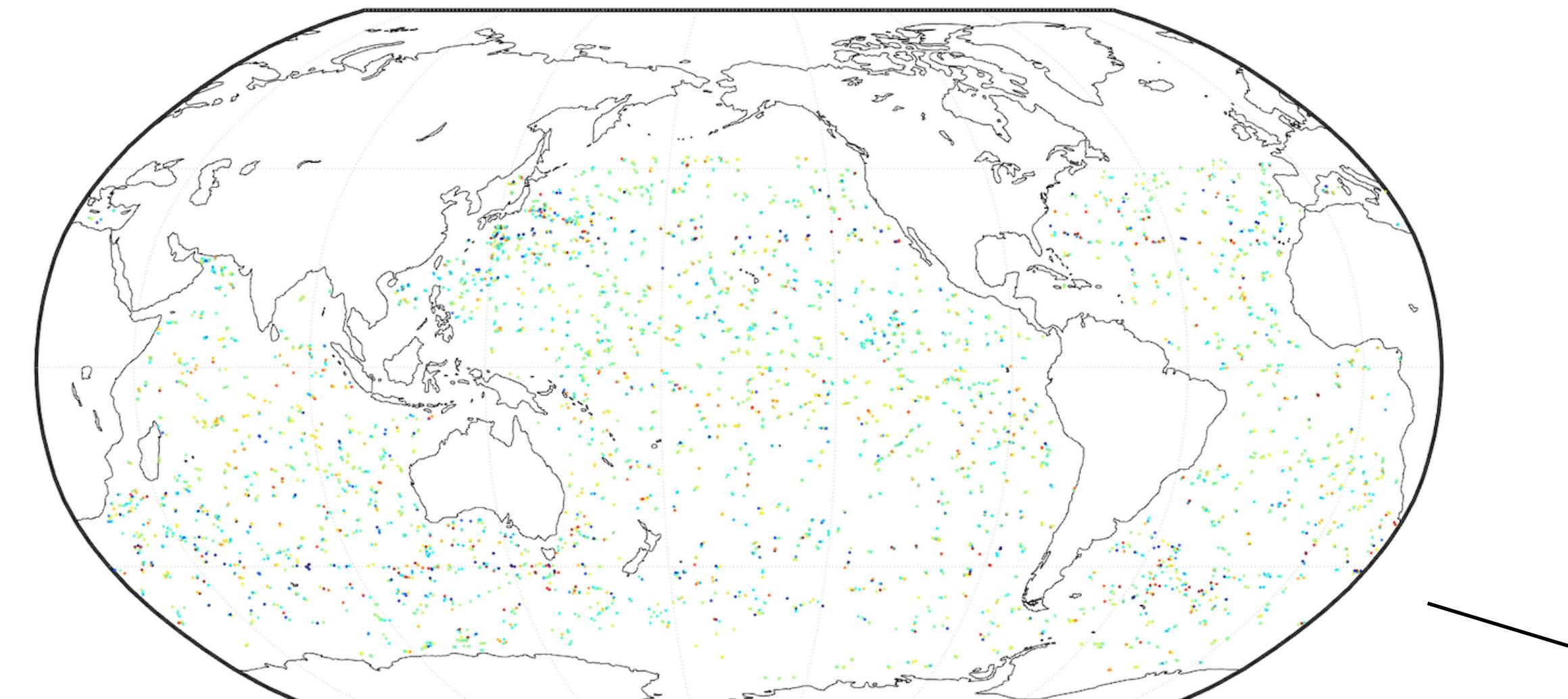
A bivariate GP model accounts for cross-layer correlation



$$\begin{bmatrix} y_{\text{top}} \\ y_{\text{bot}} \end{bmatrix}_{i,j} = f_i \left(\begin{bmatrix} x_{\text{top}} \\ x_{\text{bot}} \end{bmatrix}_{i,j}, \begin{bmatrix} t_{\text{top}} \\ t_{\text{bot}} \end{bmatrix}_{i,j} \right)$$

$$f_i \stackrel{\text{iid}}{\sim} \text{GP} \left(\begin{bmatrix} 0 \\ 0 \end{bmatrix}, \mathbf{K}(x_1, t_1, x_2, t_2; \boldsymbol{\theta}) \right)$$

A bivariate GP model accounts for cross-layer correlation



Temperature
residuals

Latitude
Longitude

Date

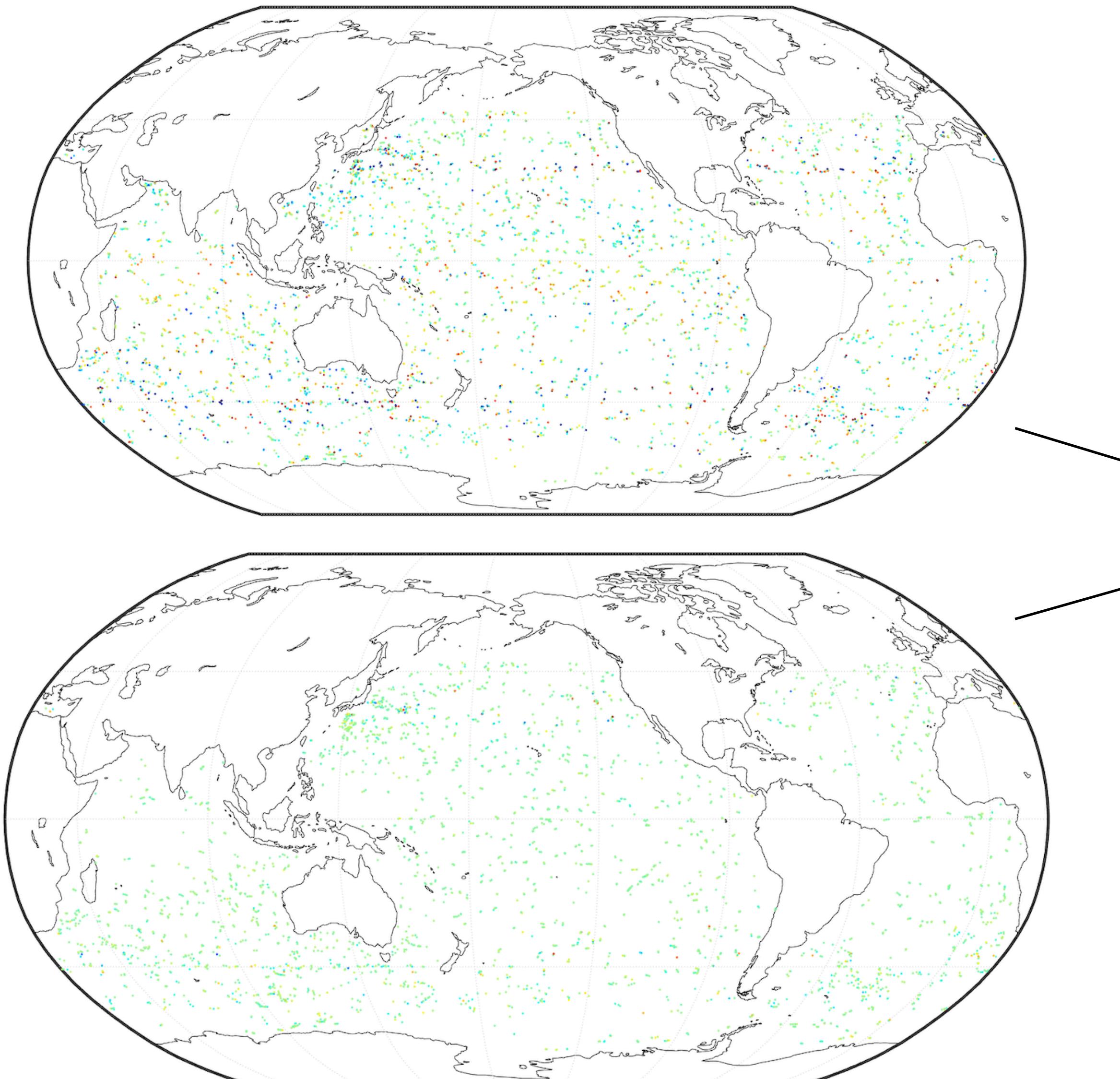
Nugget
effect

$$\begin{bmatrix} y_{\text{top}} \\ y_{\text{bot}} \end{bmatrix}_{i,j} = f_i \left(\begin{bmatrix} x_{\text{top}} \\ x_{\text{bot}} \end{bmatrix}_{i,j}, \begin{bmatrix} t_{\text{top}} \\ t_{\text{bot}} \end{bmatrix}_{i,j} \right) + \begin{bmatrix} \epsilon_{\text{top}} \\ \epsilon_{\text{bot}} \end{bmatrix}_{i,j}$$

$$f_i \stackrel{\text{iid}}{\sim} \text{GP} \left(\begin{bmatrix} 0 \\ 0 \end{bmatrix}, K(x_1, t_1, x_2, t_2; \theta) \right)$$

$$\begin{bmatrix} \epsilon_{\text{top}} \\ \epsilon_{\text{bot}} \end{bmatrix} \stackrel{\text{iid}}{\sim} N \left(\begin{bmatrix} 0 \\ 0 \end{bmatrix}, \Sigma_\epsilon(\theta_\epsilon) \right)$$

A bivariate GP model accounts for cross-layer correlation



Temperature
residuals

Latitude
Longitude

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Nugget
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$$\begin{bmatrix} y_{\text{top}} \\ y_{\text{bot}} \end{bmatrix}_{i,j} = f_i \left(\begin{bmatrix} x_{\text{top}} \\ x_{\text{bot}} \end{bmatrix}_{i,j}, \begin{bmatrix} t_{\text{top}} \\ t_{\text{bot}} \end{bmatrix}_{i,j} \right) + \begin{bmatrix} \epsilon_{\text{top}} \\ \epsilon_{\text{bot}} \end{bmatrix}_{i,j}$$

$$f_i \stackrel{\text{iid}}{\sim} \text{GP} \left(\begin{bmatrix} 0 \\ 0 \end{bmatrix}, K(x_1, t_1, x_2, t_2; \theta) \right)$$

(Covariance function)

$$\begin{bmatrix} \epsilon_{\text{top}} \\ \epsilon_{\text{bot}} \end{bmatrix} \stackrel{\text{iid}}{\sim} N \left(\begin{bmatrix} 0 \\ 0 \end{bmatrix}, \Sigma_\epsilon(\theta_\epsilon) \right)$$

A bivariate GP model accounts for cross-layer correlation

Marginal covariance
(Kuusela and Stein 2018)

$$K_{ii}(z_1, z_2; \theta)$$

A bivariate GP model accounts for cross-layer correlation

Marginal covariance
(Kuusela and Stein 2018)

$$K_{ii}(z_1, z_2; \theta) = \frac{\delta_i^2}{\sqrt{|\Theta_i|}}$$

GP variance

A bivariate GP model accounts for cross-layer correlation

Marginal covariance
(Kuusela and Stein 2018)

$$K_{ii}(z_1, z_2; \theta) = \frac{\delta_i^2}{\sqrt{|\Theta_i|}} \exp(-\sqrt{(z_1 - z_2)^T \Theta_i^{-1} (z_1 - z_2)})$$

GP variance **Space-time distance
w/ length scale parameters**

A bivariate GP model accounts for cross-layer correlation

Marginal covariance
(Kuusela and Stein 2018)

$$\mathbf{K}_{ii}(\mathbf{z}_1, \mathbf{z}_2; \boldsymbol{\theta}) = \frac{\delta_i^2}{\sqrt{|\boldsymbol{\Theta}_i|}} \exp(-\sqrt{(\mathbf{z}_1 - \mathbf{z}_2)^T \boldsymbol{\Theta}_i^{-1} (\mathbf{z}_1 - \mathbf{z}_2)})$$

GP variance **Space-time distance
w/ length scale parameters**

Cross-covariance
(Kleiber and Nychka 2012)

$$\mathbf{K}_{\text{top},\text{bot}}(\mathbf{z}_1, \mathbf{z}_2; \boldsymbol{\theta}) = \beta \frac{\delta_{\text{top}} \delta_{\text{bot}}}{\sqrt{|\boldsymbol{\Theta}_{\text{top},\text{bot}}|}} \exp(-\sqrt{(\mathbf{z}_1 - \mathbf{z}_2)^T \boldsymbol{\Theta}_{\text{top},\text{bot}}^{-1} (\mathbf{z}_1 - \mathbf{z}_2)})$$

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(Cross) correlation

Obtaining uncertainties is facilitated by local conditional simulations

anomaly|data ?

Obtaining uncertainties is facilitated by local conditional simulations

anomaly|data - **multivariate normal** with conditional covariance Σ_i

(parameterized by estimated GP variance, length scales, cross-correlation)

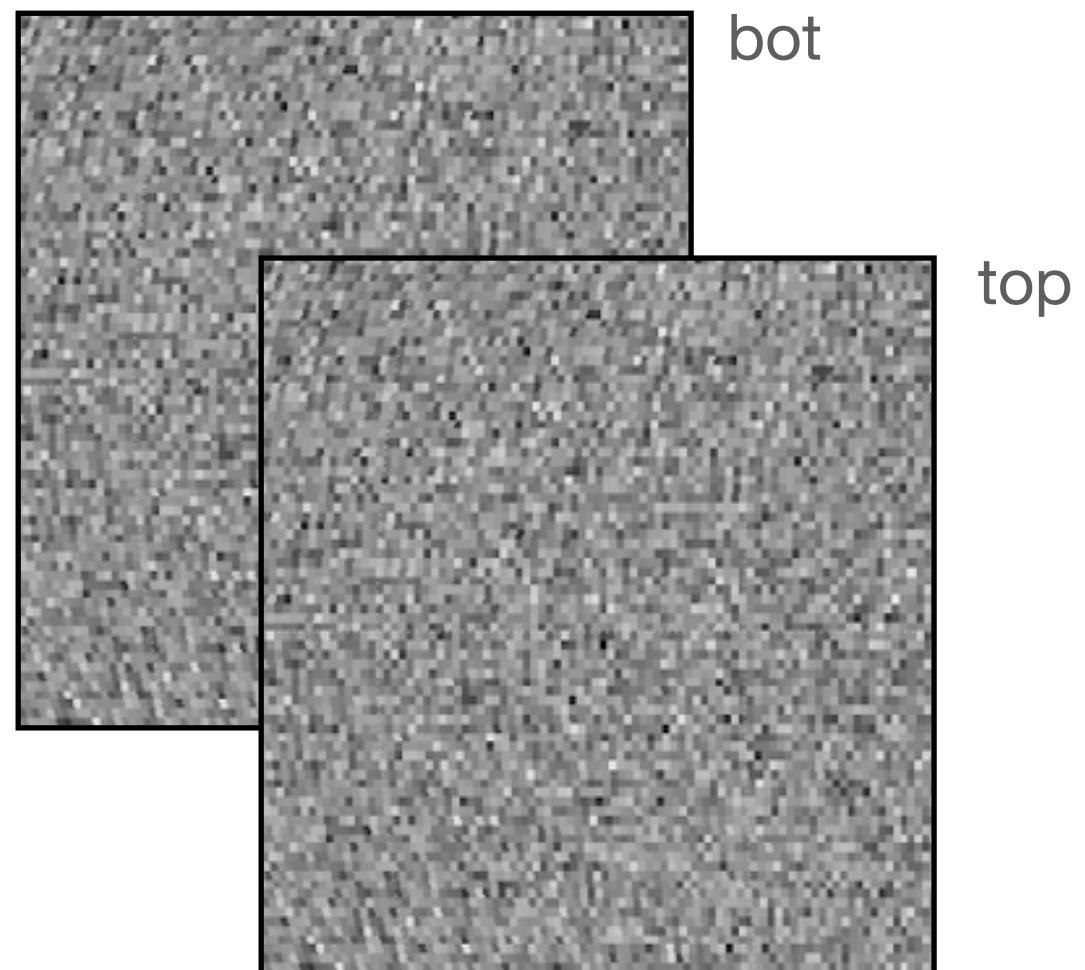
Obtaining uncertainties is facilitated by local conditional simulations

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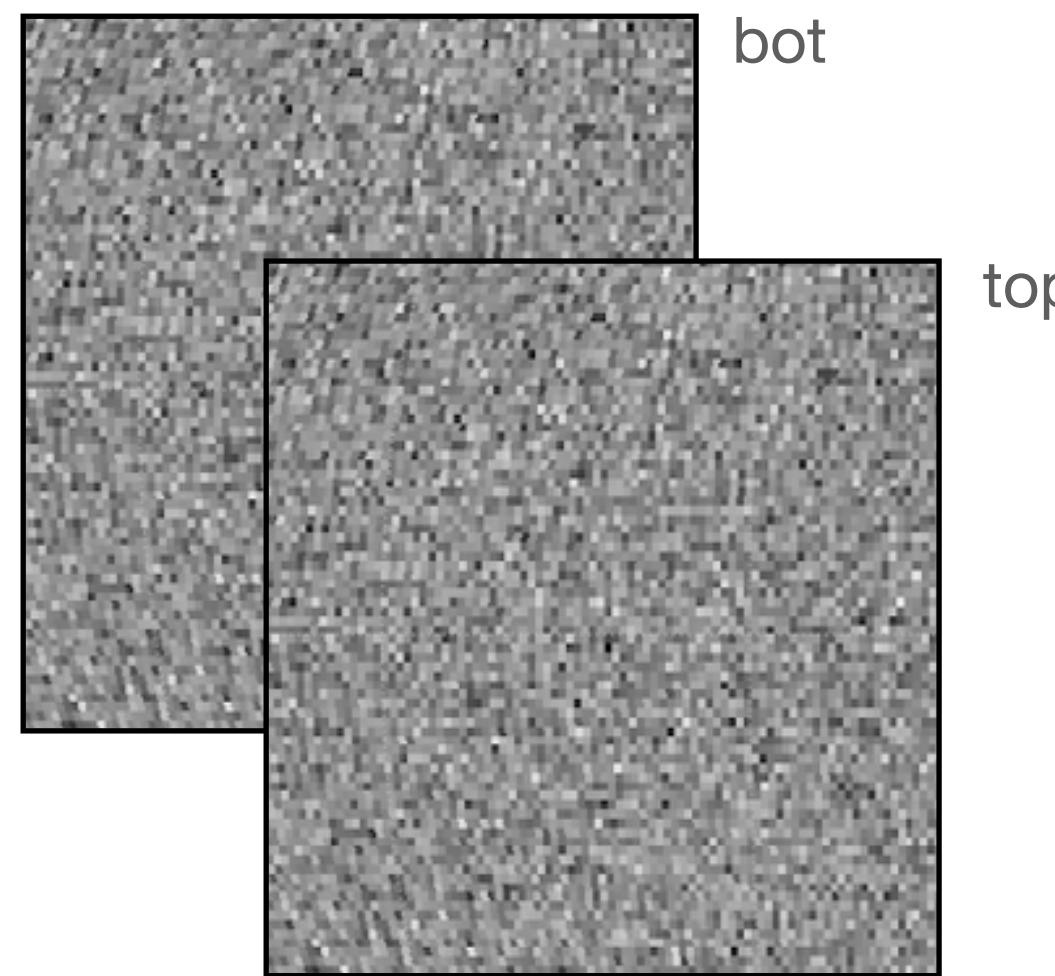
Local conditional simulations! (extension of Nychka et.al. 2018)

Obtaining uncertainties is facilitated by local conditional simulations

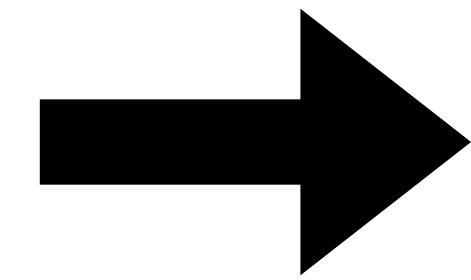


Simulate Gaussian
white noise over grid
(keep fixed)

Obtaining uncertainties is facilitated by local conditional simulations



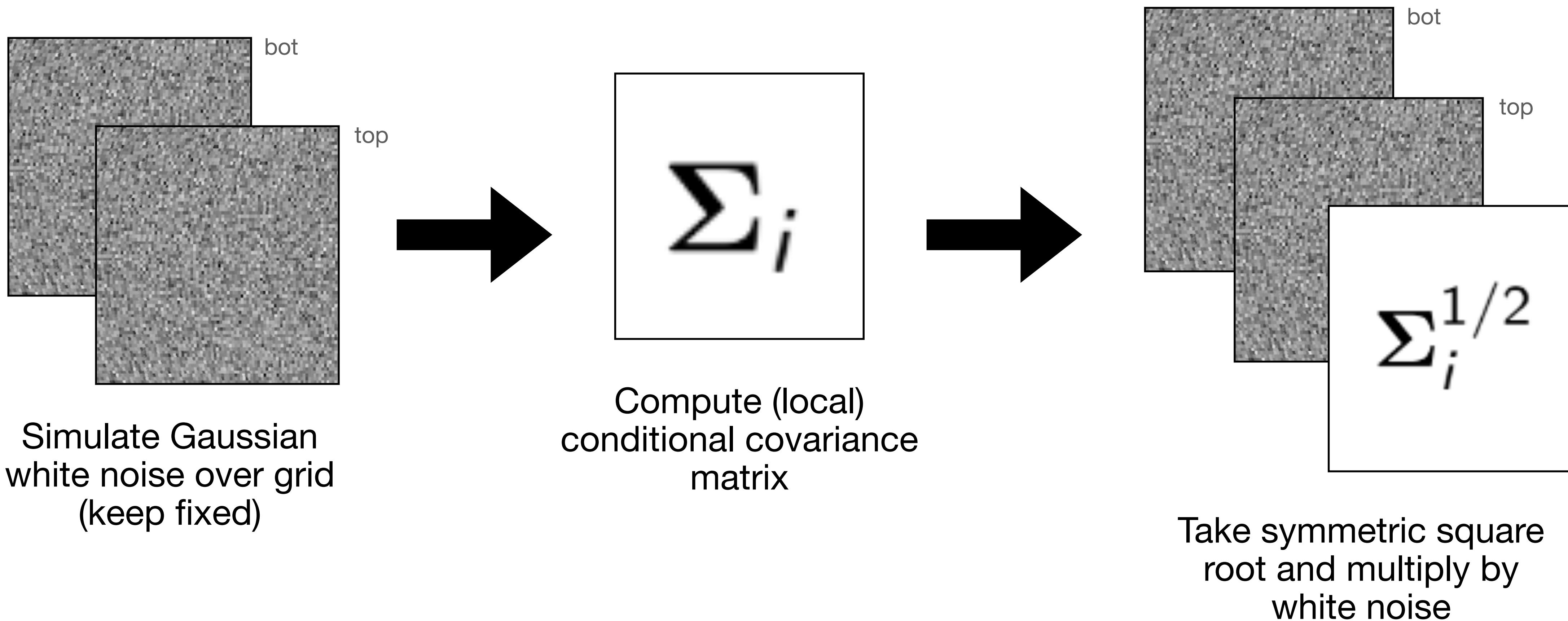
Simulate Gaussian
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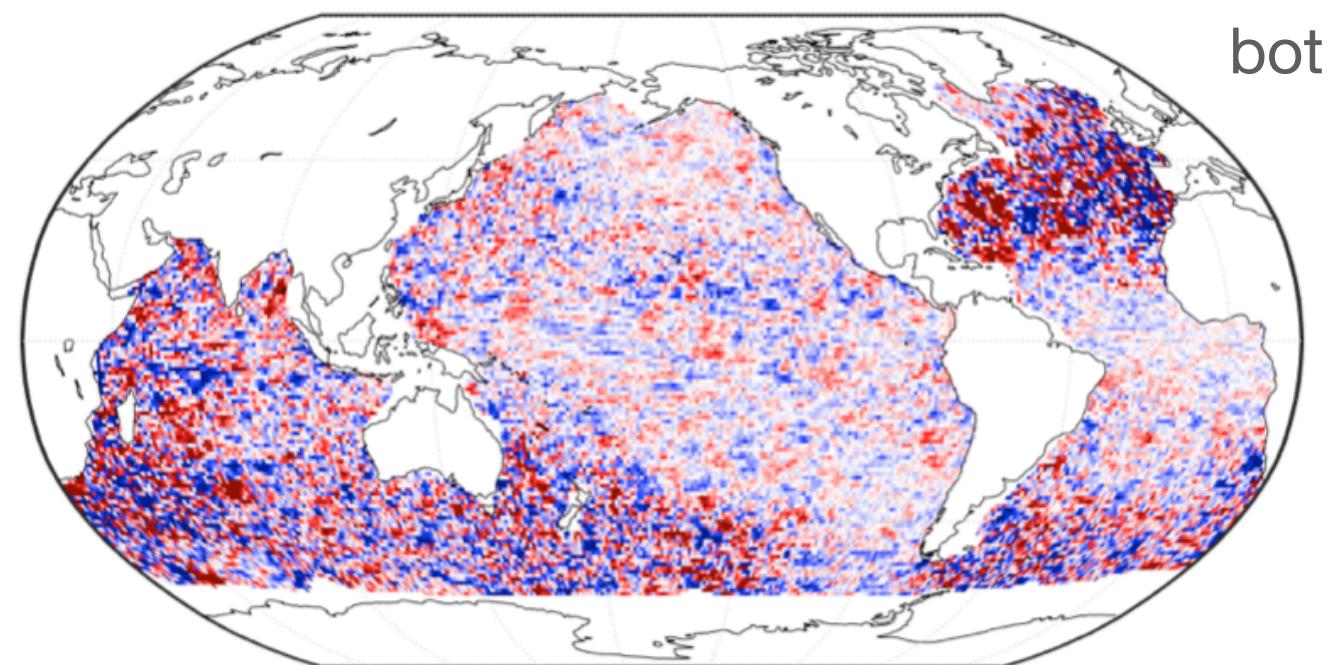
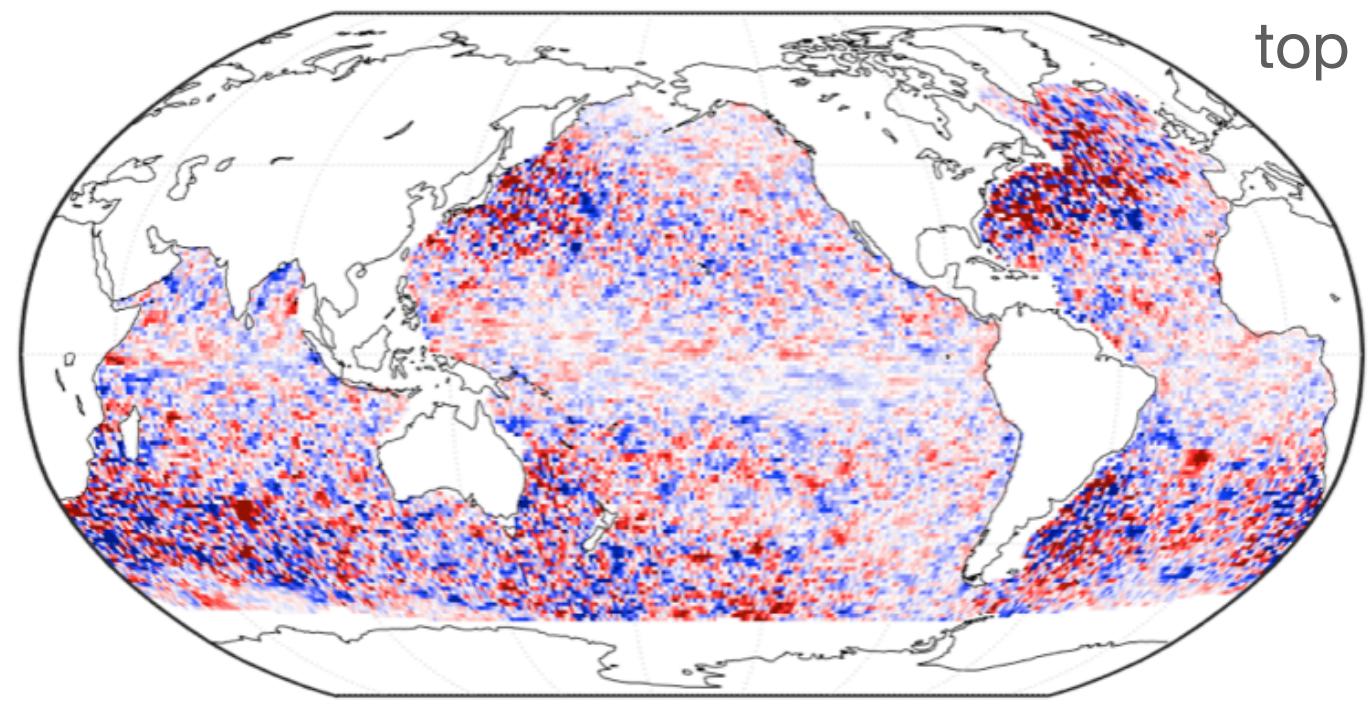
$$\Sigma_i$$

Compute (local)
conditional covariance
matrix

Obtaining uncertainties is facilitated by local conditional simulations

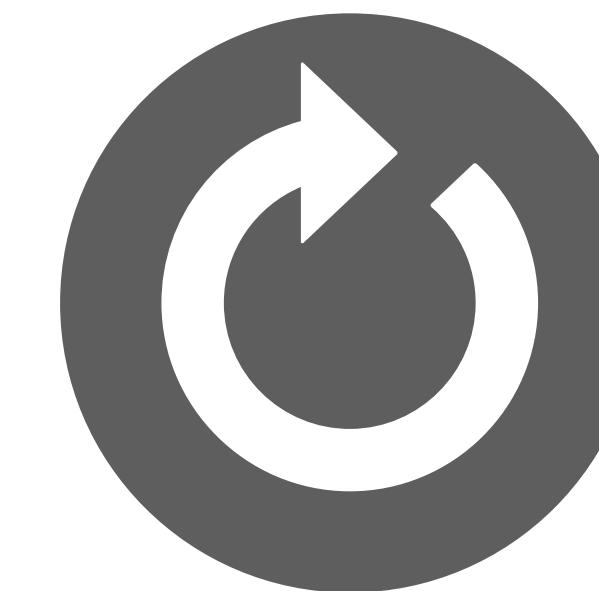
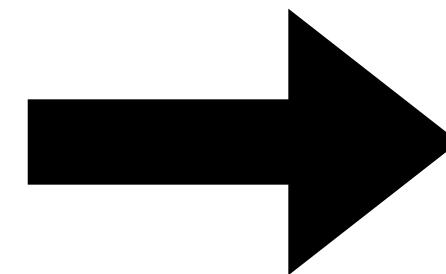
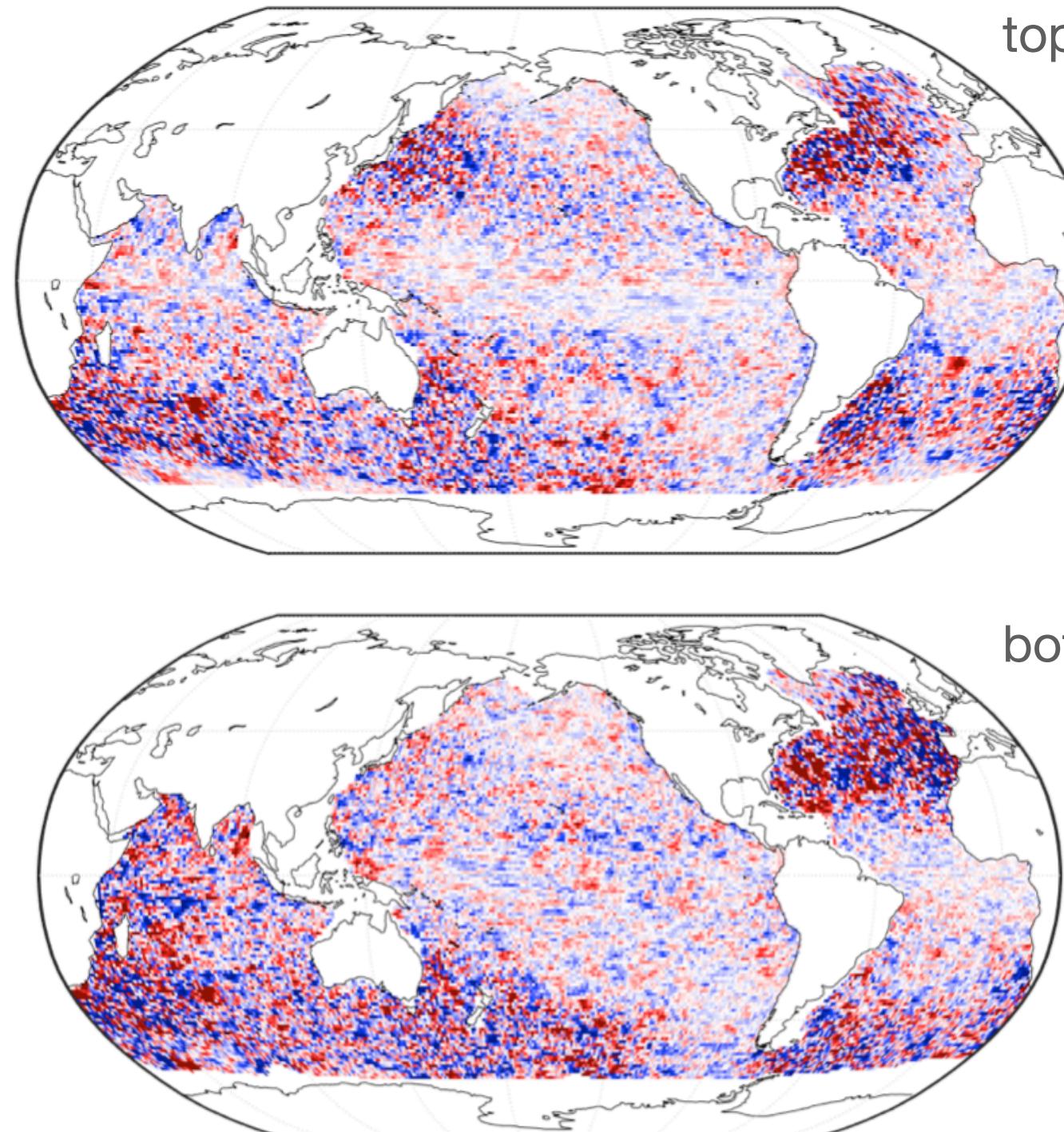


Obtaining uncertainties is facilitated by local conditional simulations



Keep the center point
and repeat for all grid
points

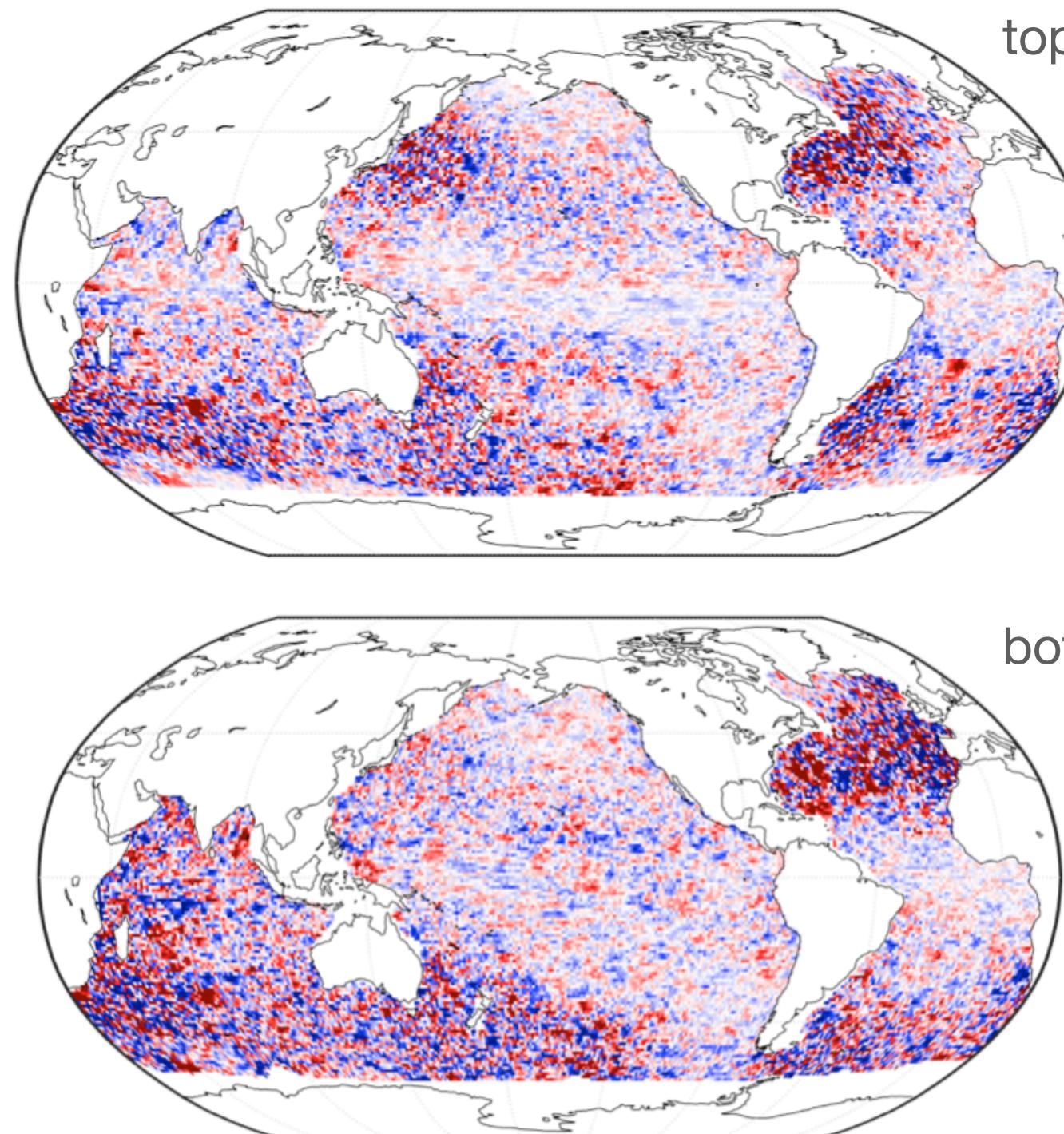
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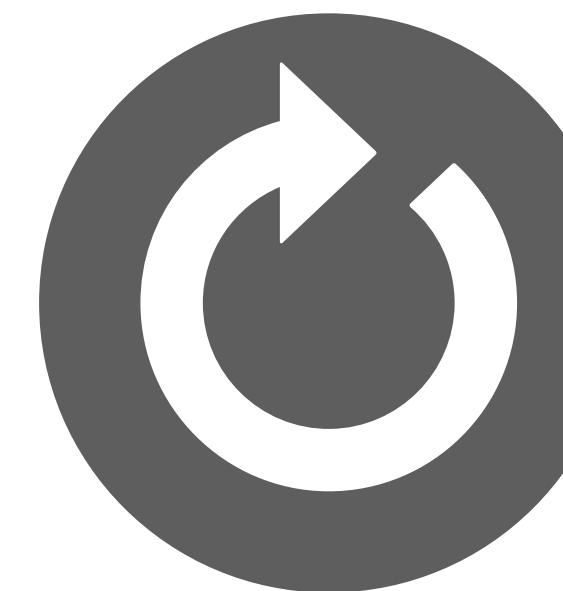
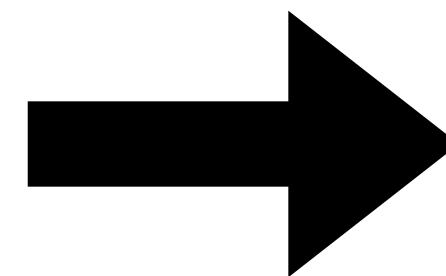
Repeat for desired
number of ensemble
members

Keep the center point
and repeat for all grid
points

Obtaining uncertainties is facilitated by local conditional simulations



Keep the center point
and repeat for all grid
points



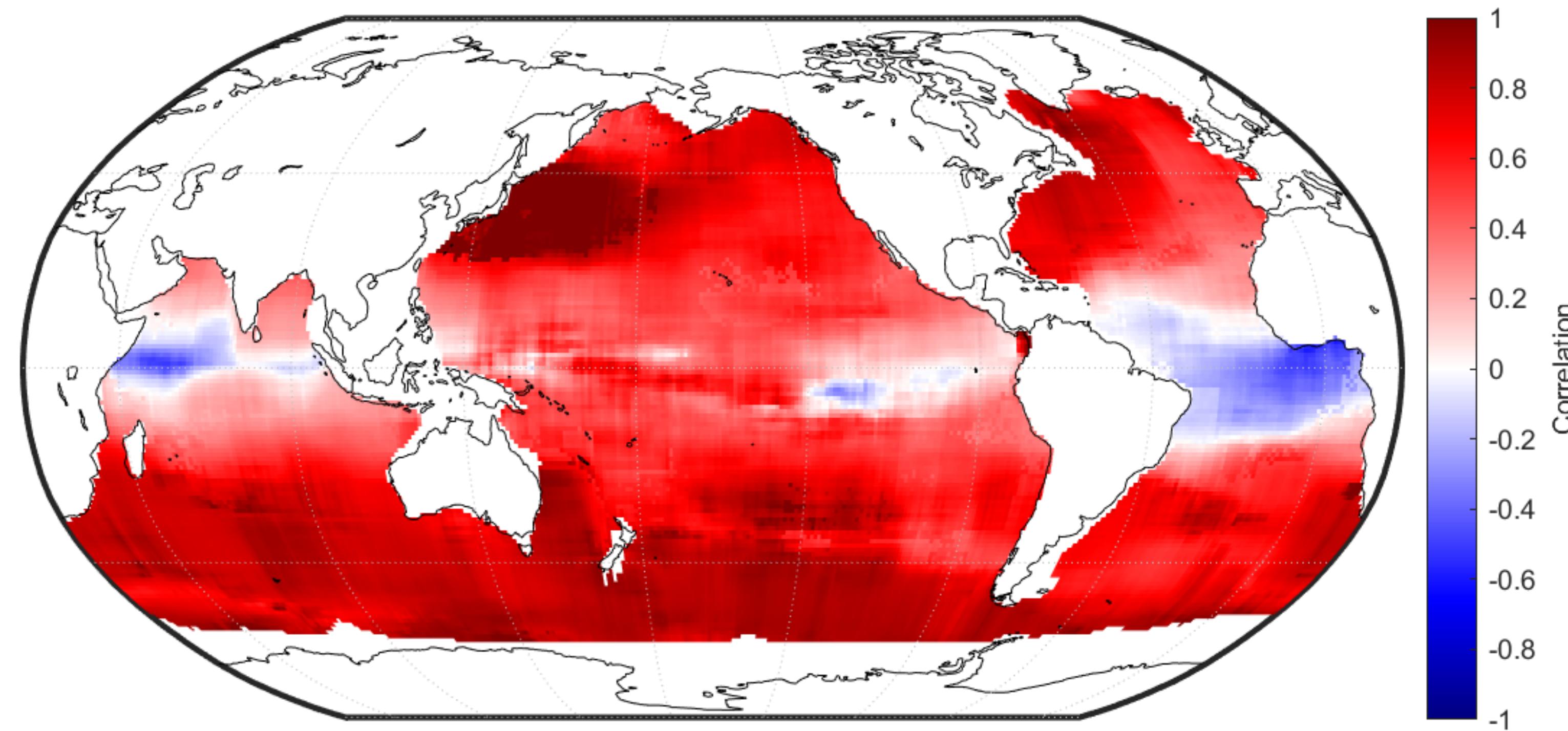
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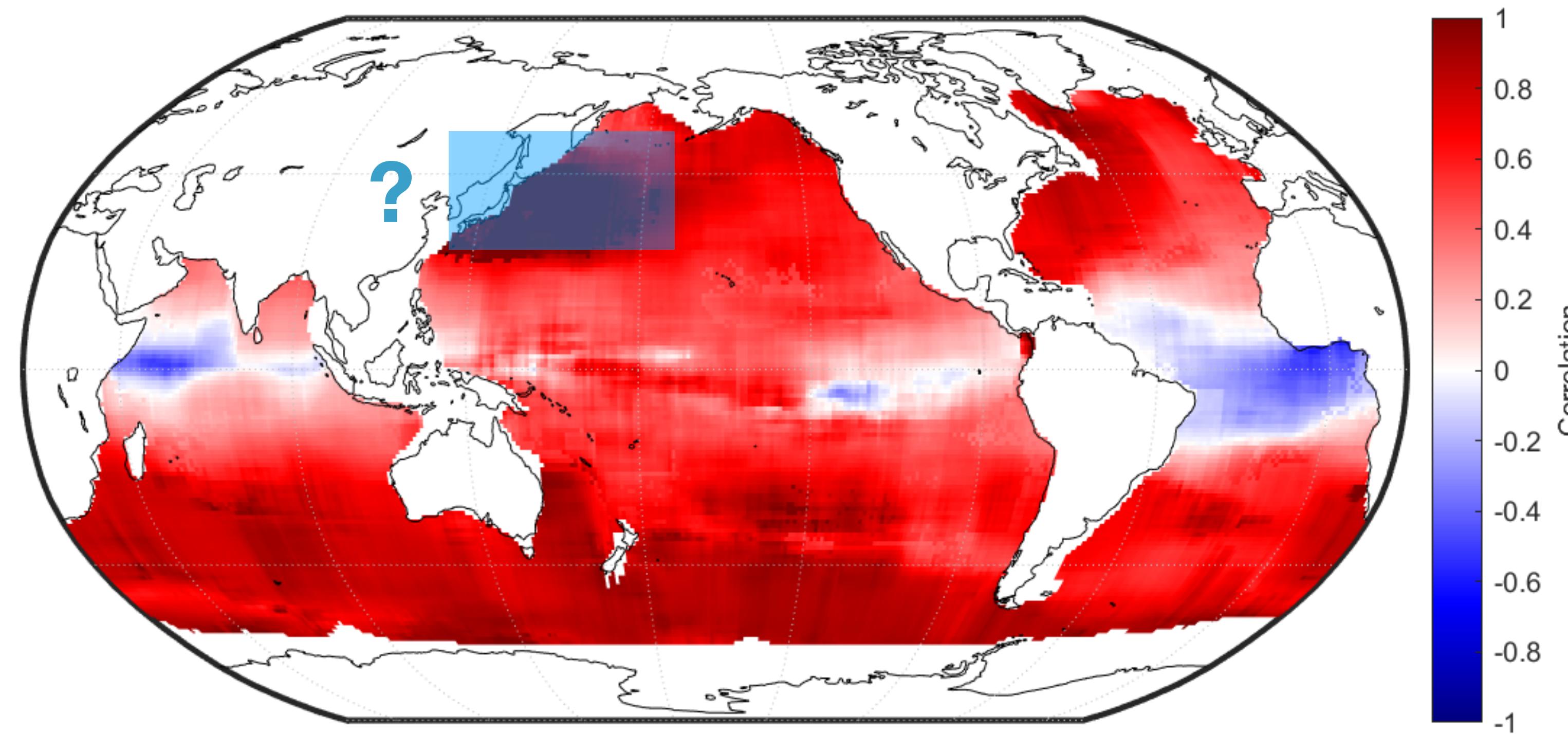
We modeled the correlation, so
sample variance of top + bottom
layer integrated ensemble
members is estimate of

$$\text{Var}(\text{OHC}_{\text{total}} | \text{data})$$

Most ocean regions' temperatures are positively correlated



Most ocean regions' temperatures are positively correlated

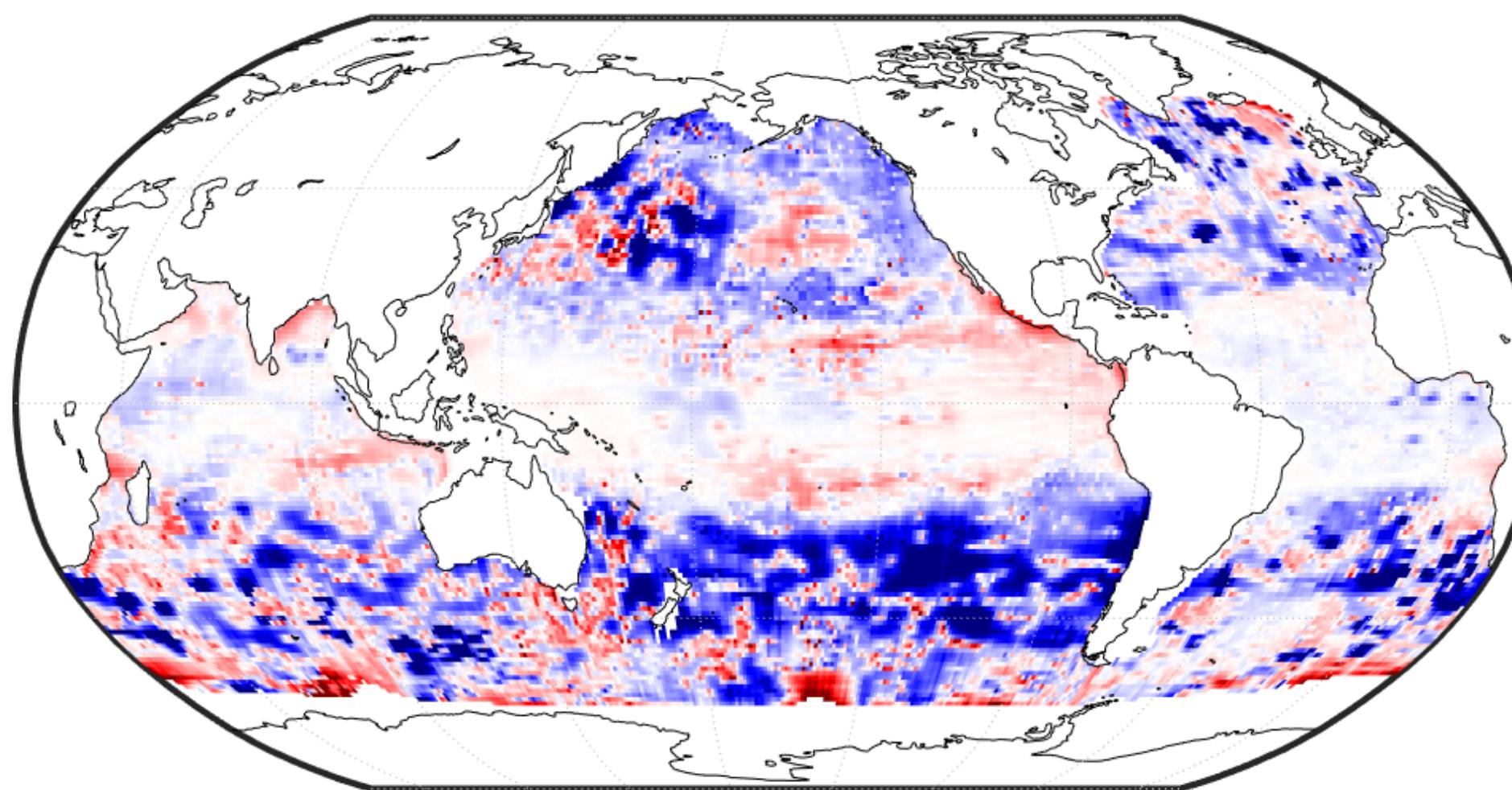


The bivariate model tends to produce lower kriging variances

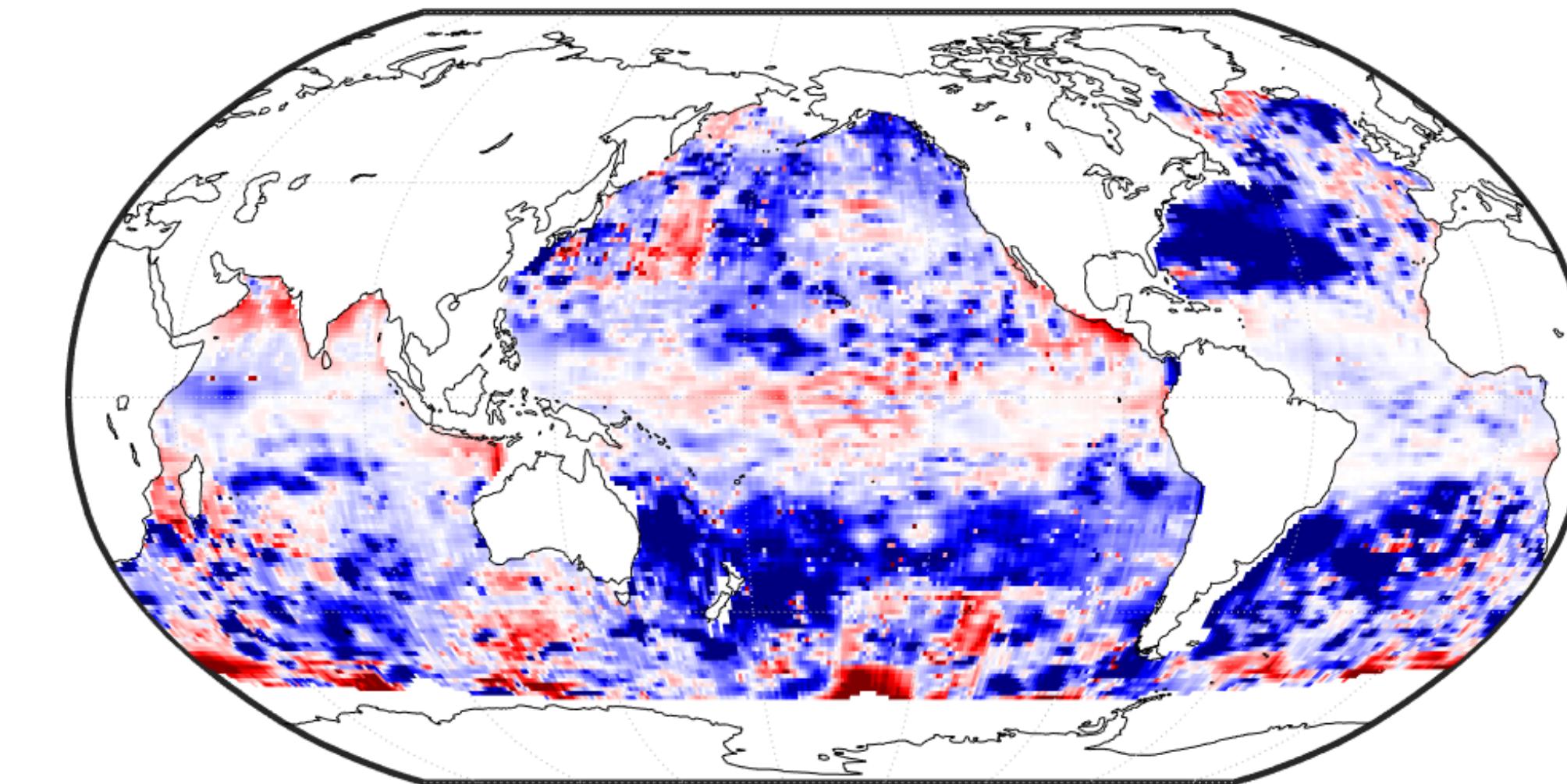
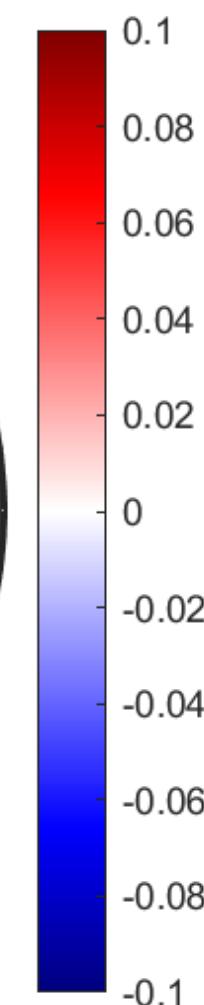
bivariate kriging variance - univariate kriging variance

(02/2010)

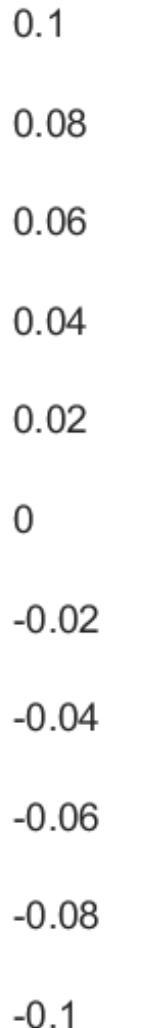
univariate kriging variance



Top layer

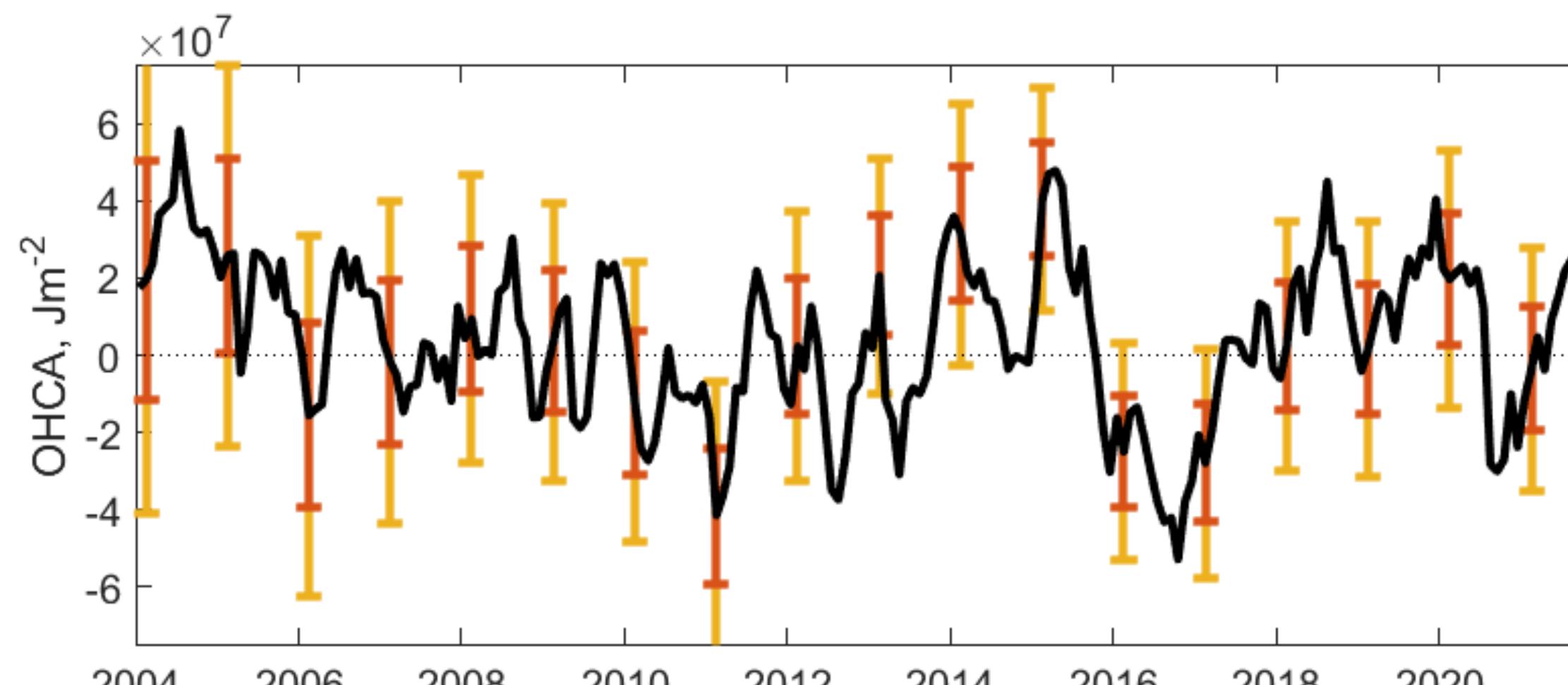


Bottom layer

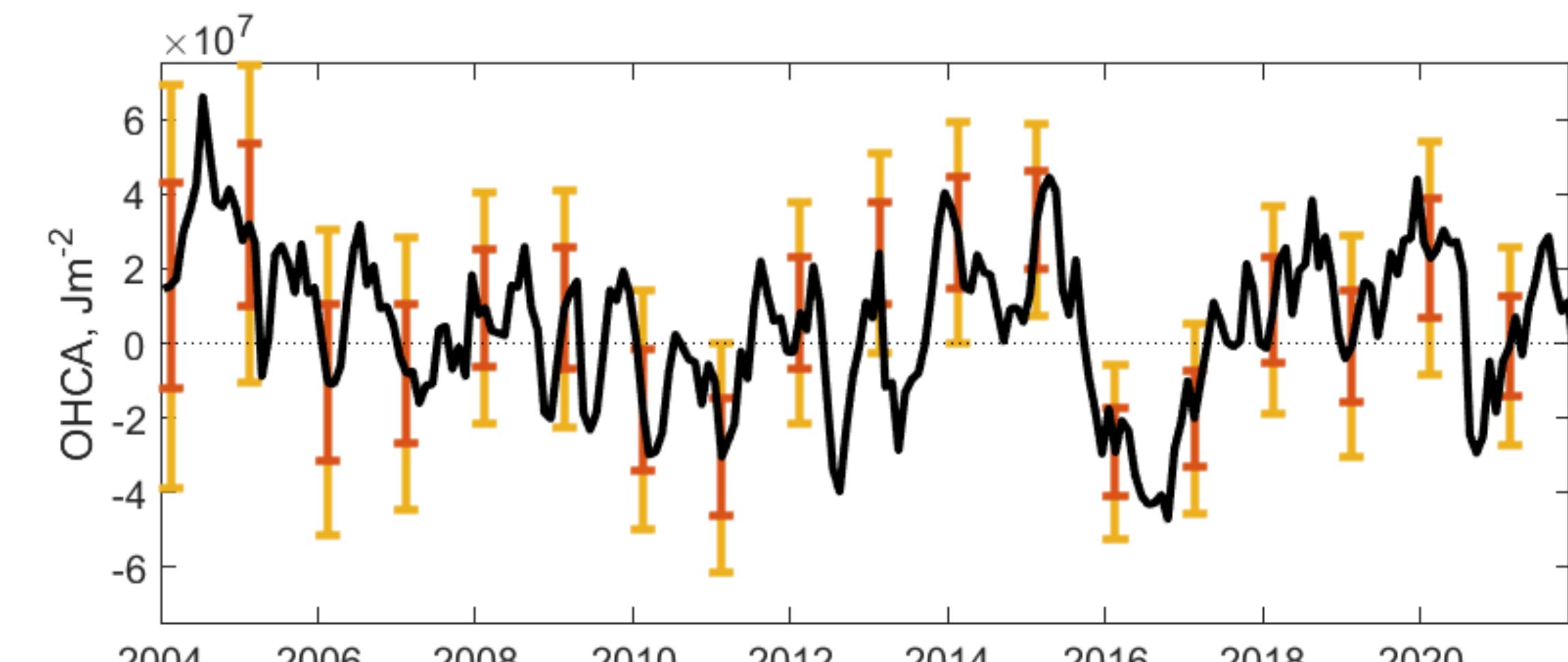


Bivariate total (top + bottom) OHC uncertainties tend to be ~15% smaller than univariate

Global OHC anomaly estimates

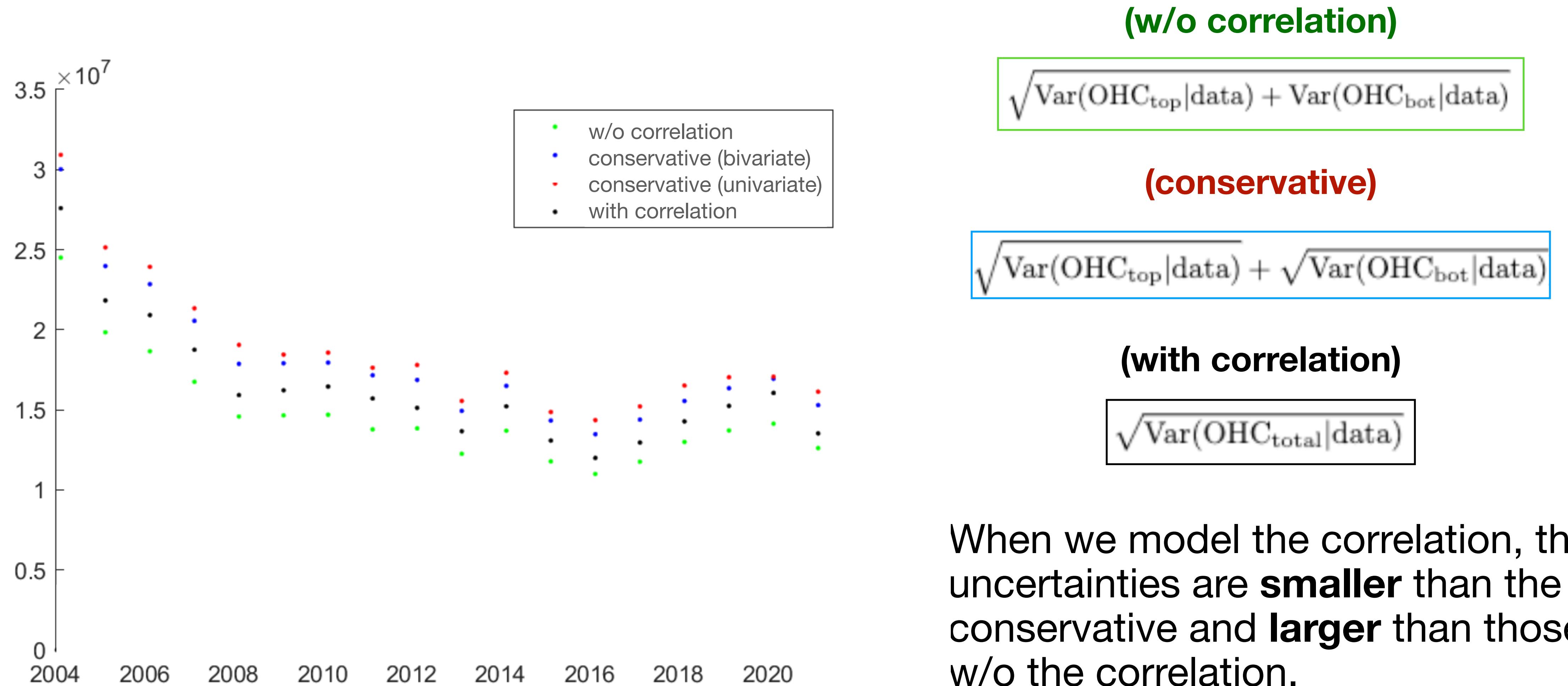


Univariate

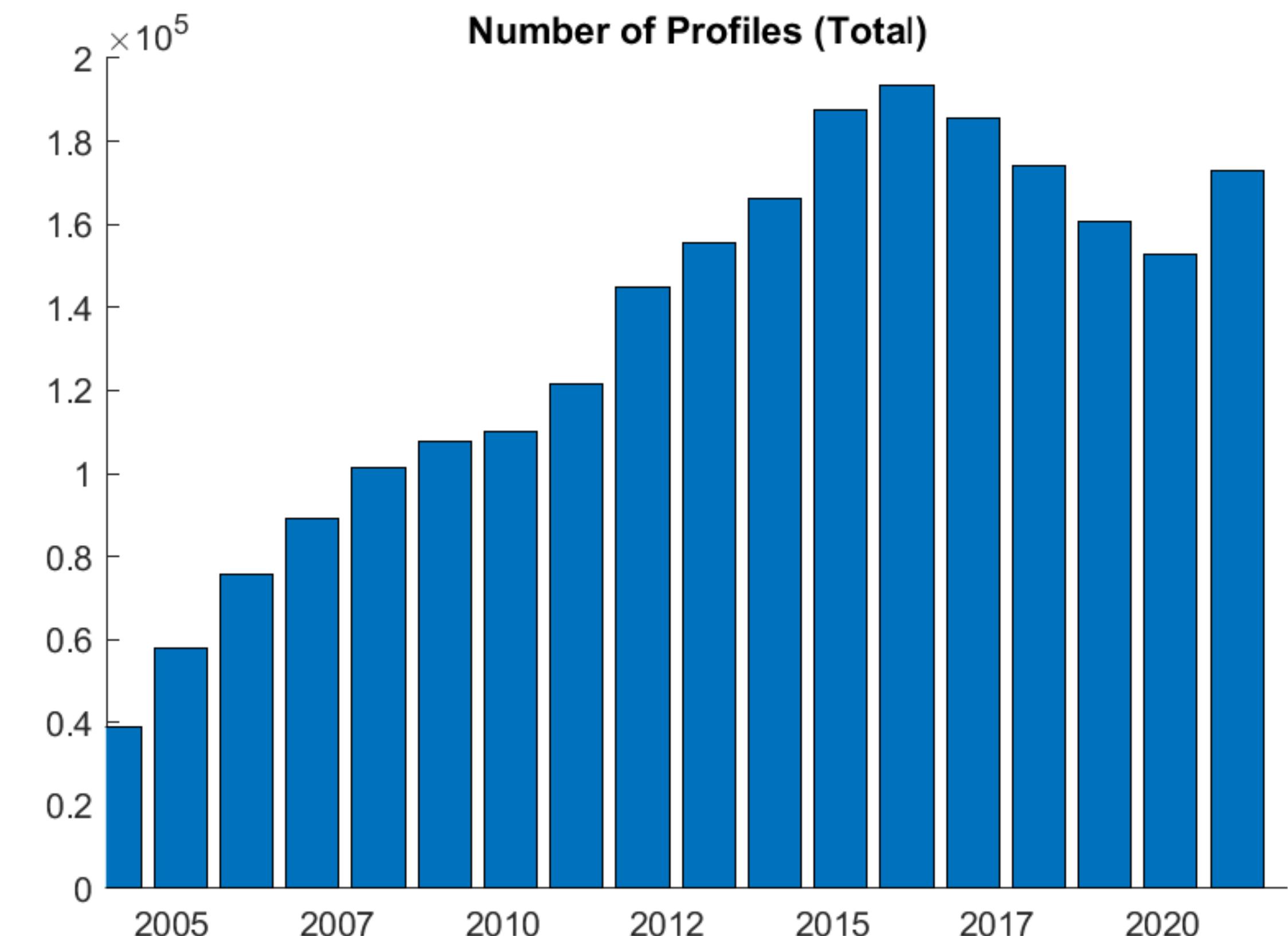
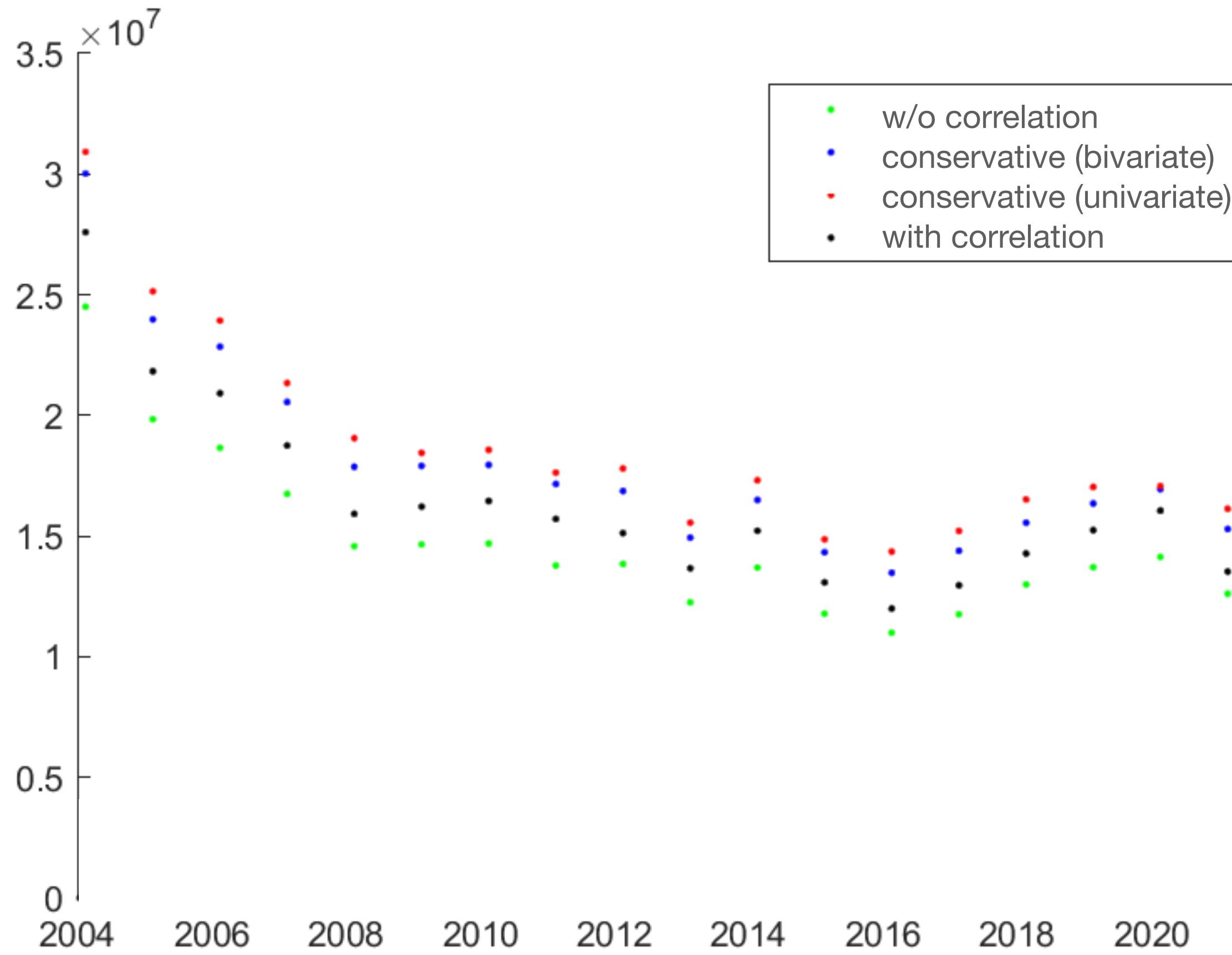


Bivariate

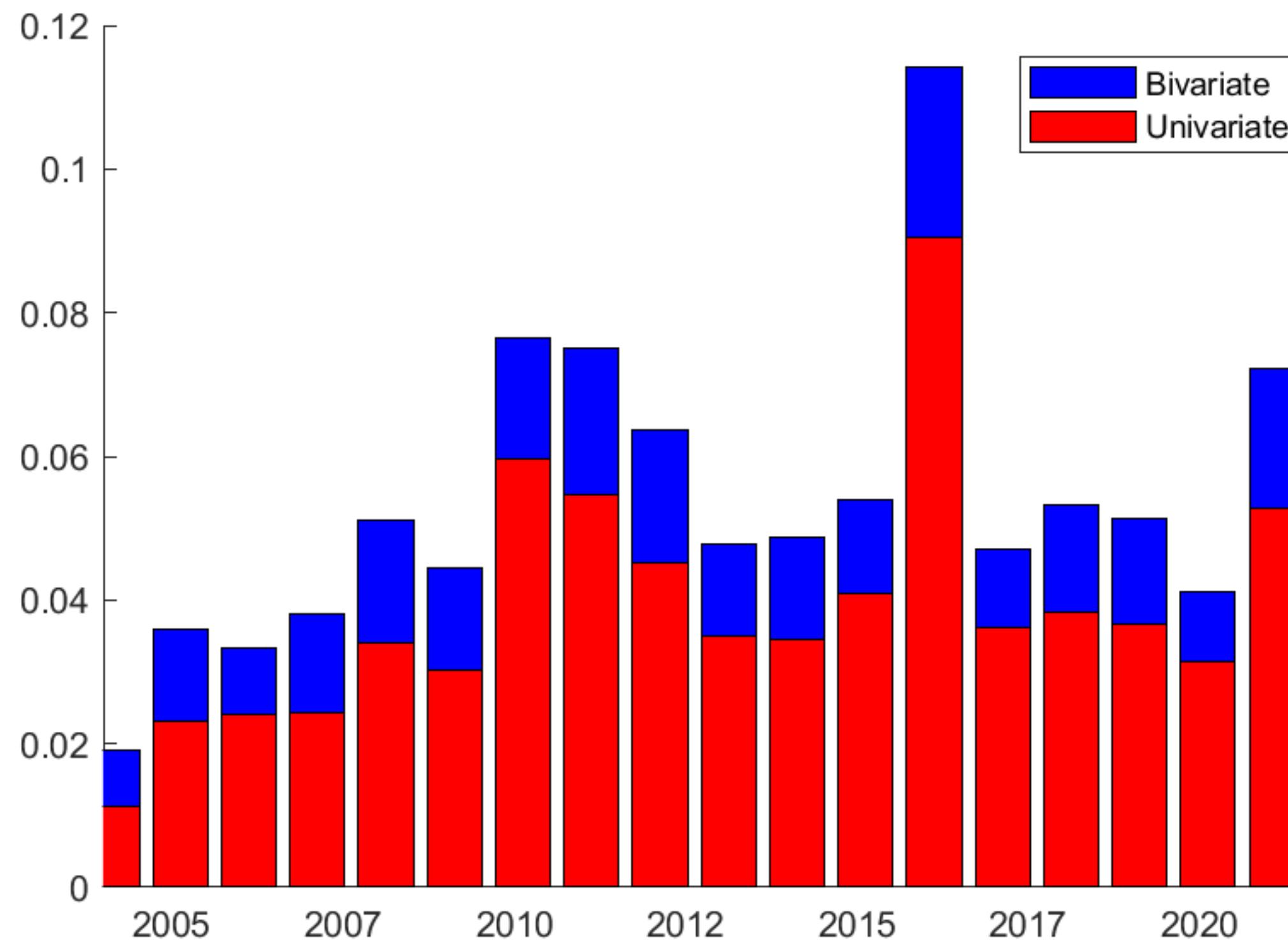
Bivariate total (top + bottom) OHC uncertainties tend to be ~15% smaller than univariate



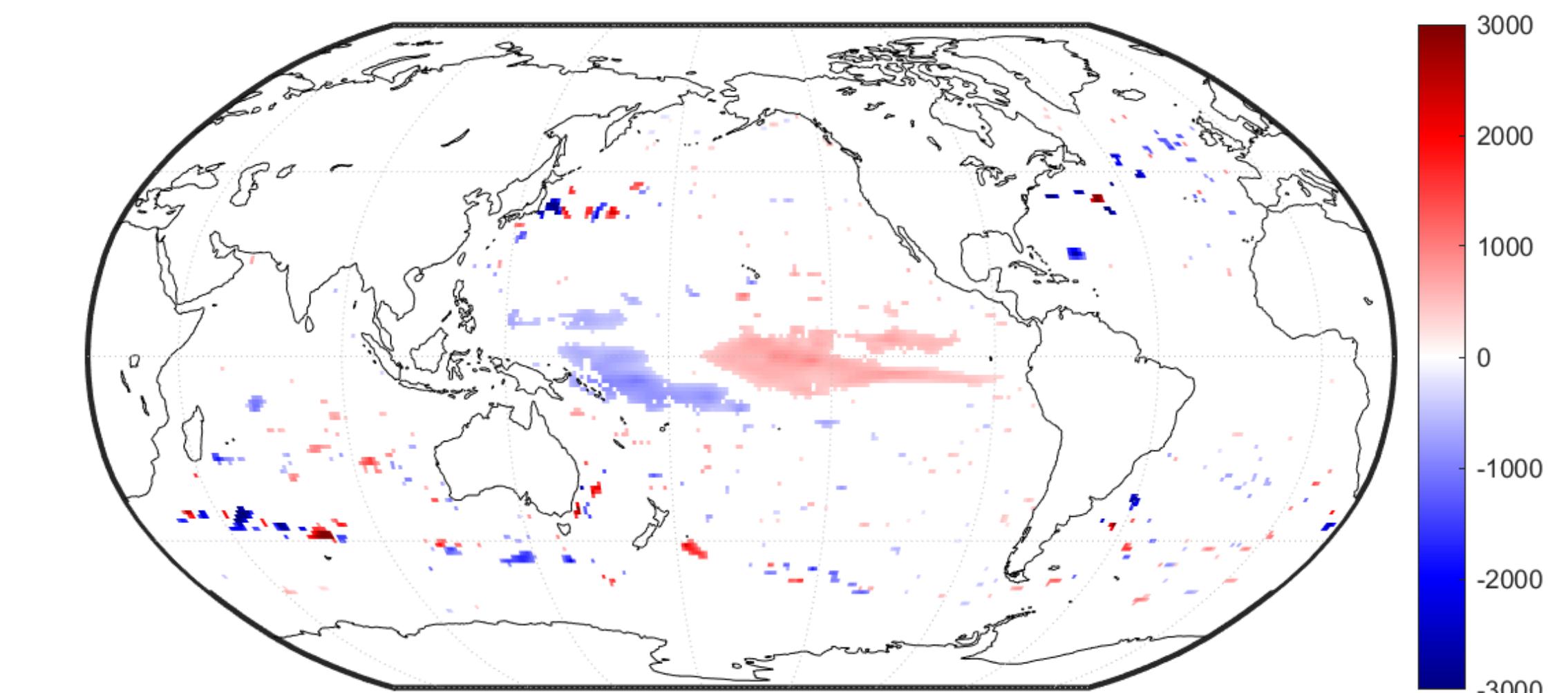
The uncertainty trend follows the number of profiles/floats



The equatorial OHC anomalies are consistently significant

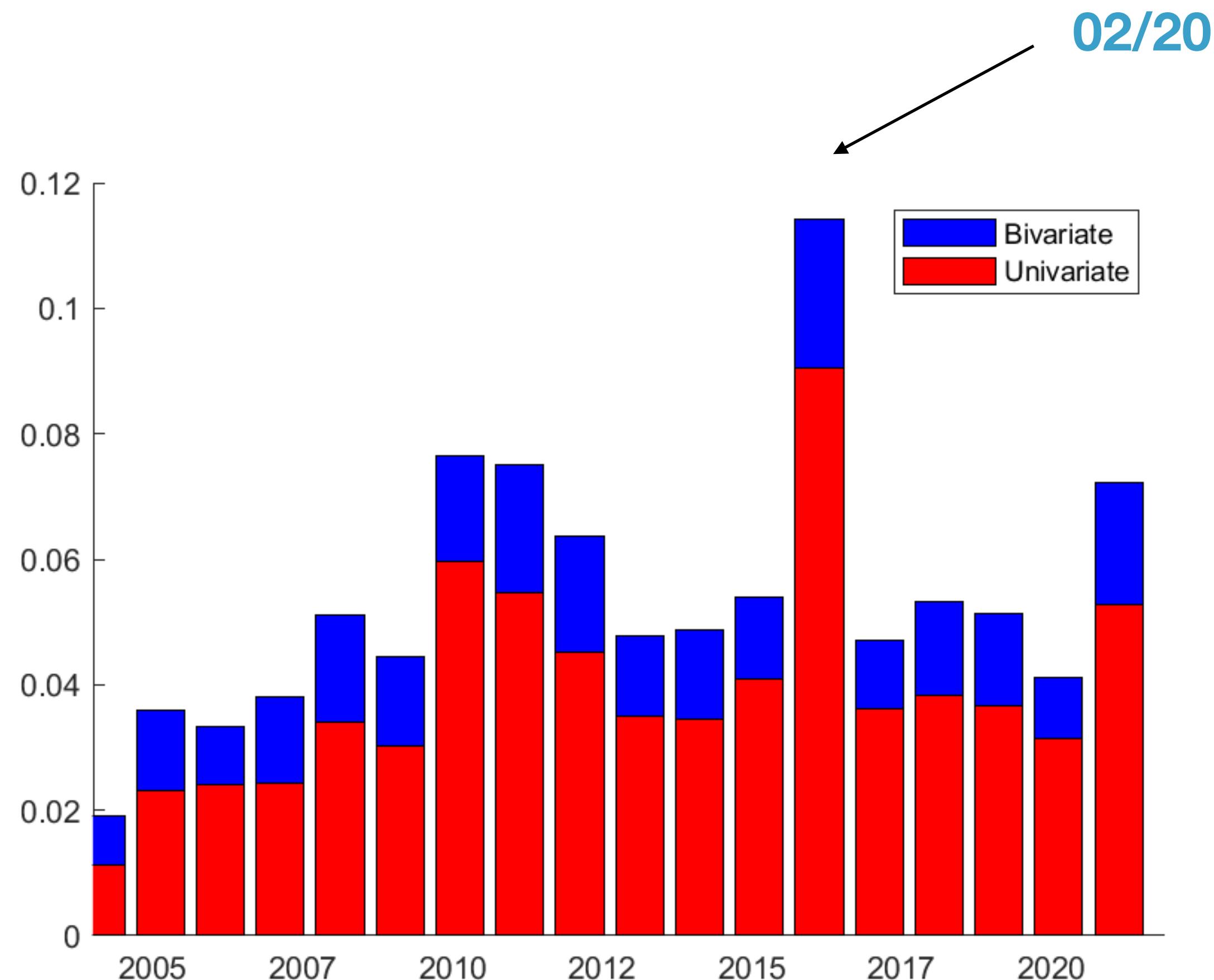


Proportion of grid points with significant anomalies over time (95% level)

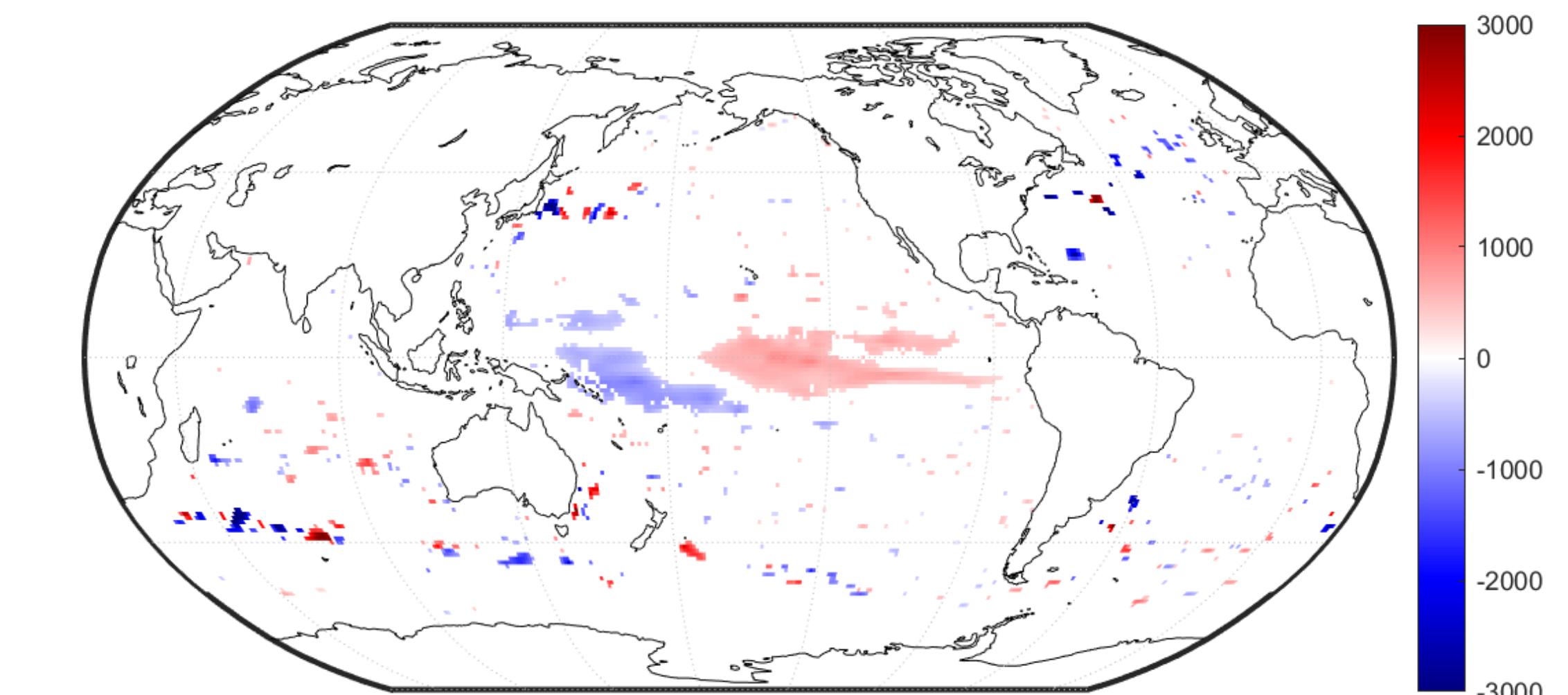


Significant temperature anomalies (02/2010)

The equatorial OHC anomalies are consistently significant

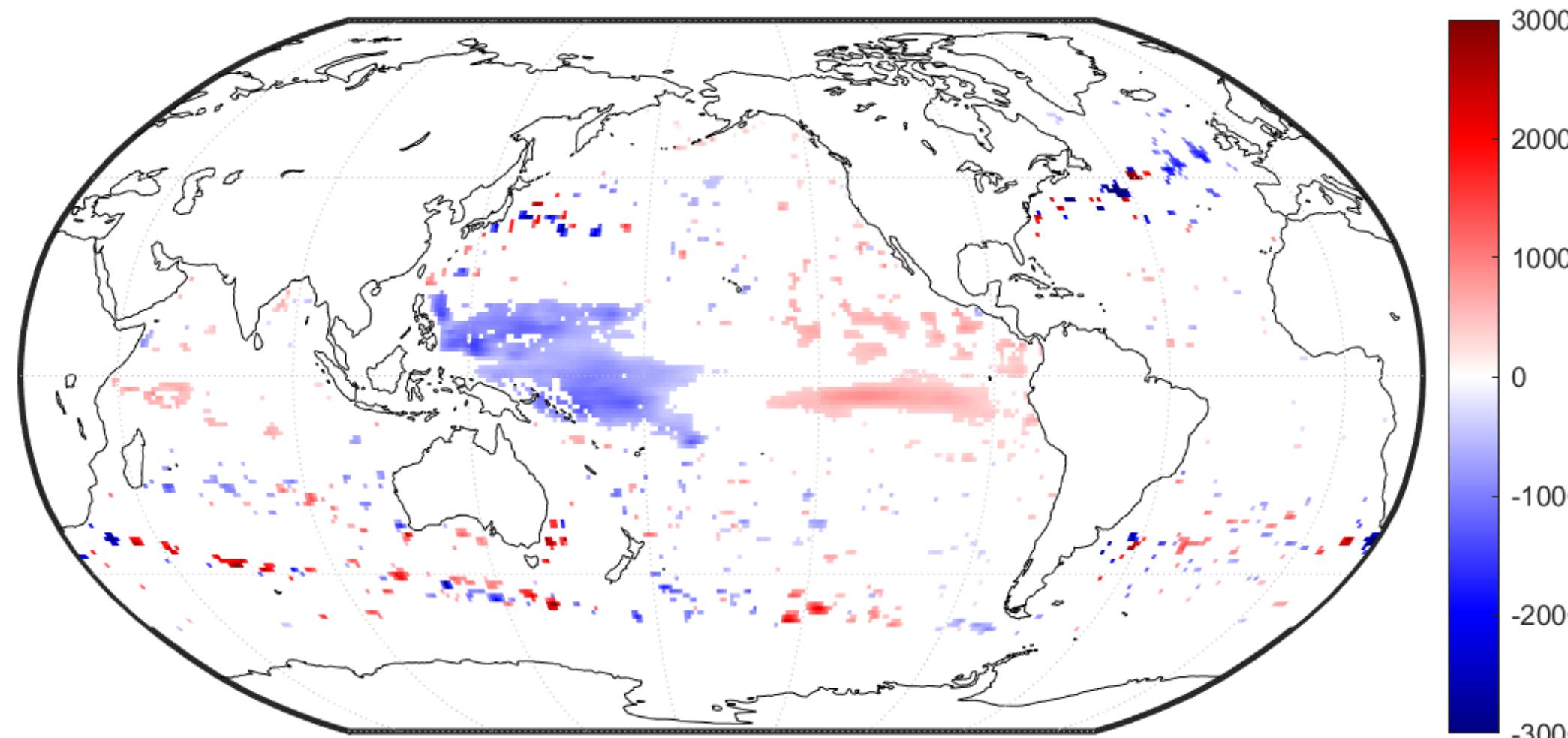


Proportion of grid points with significant anomalies over time (95% level)

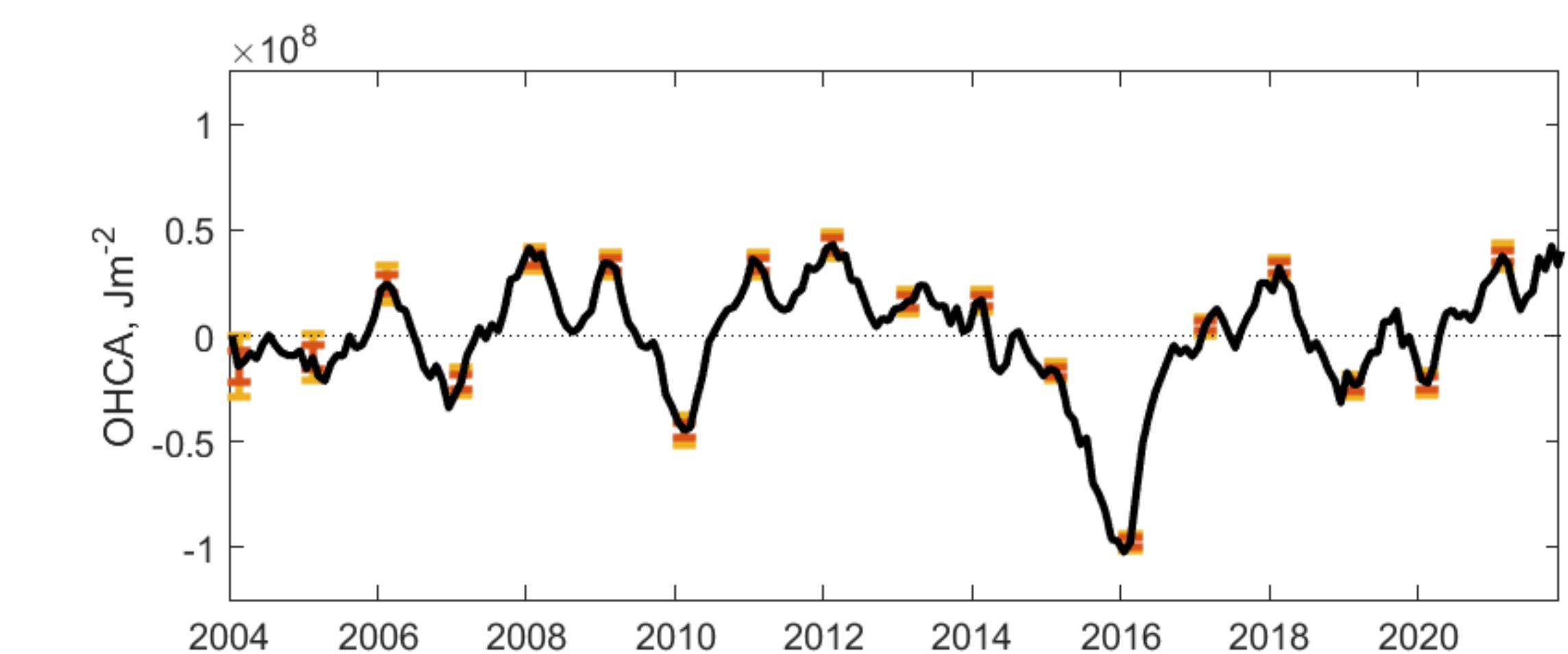


Significant temperature anomalies (02/2010)

The 2015-16 El Niño appears in the equatorial OHC anomalies

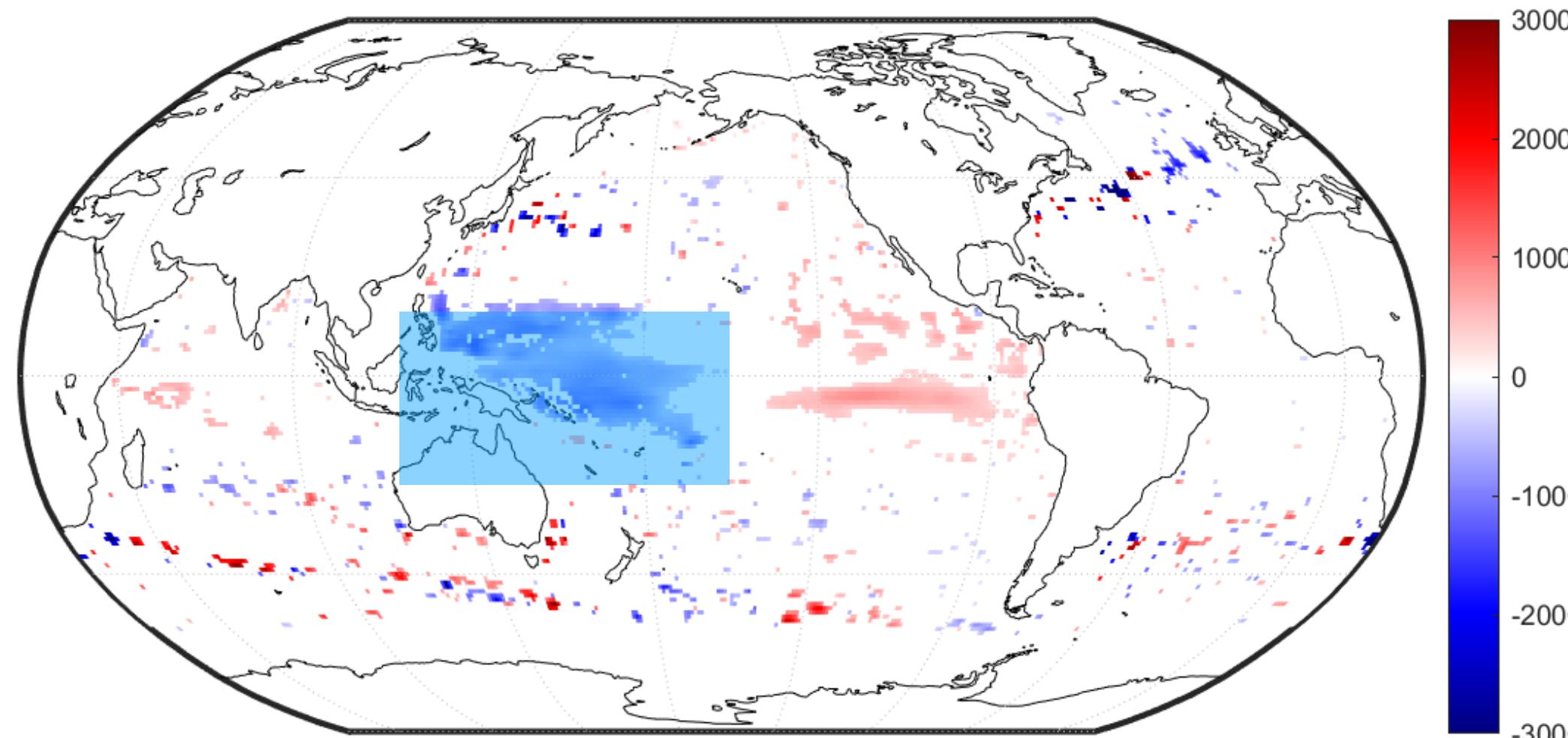


Significant temperature anomalies (02/2016)

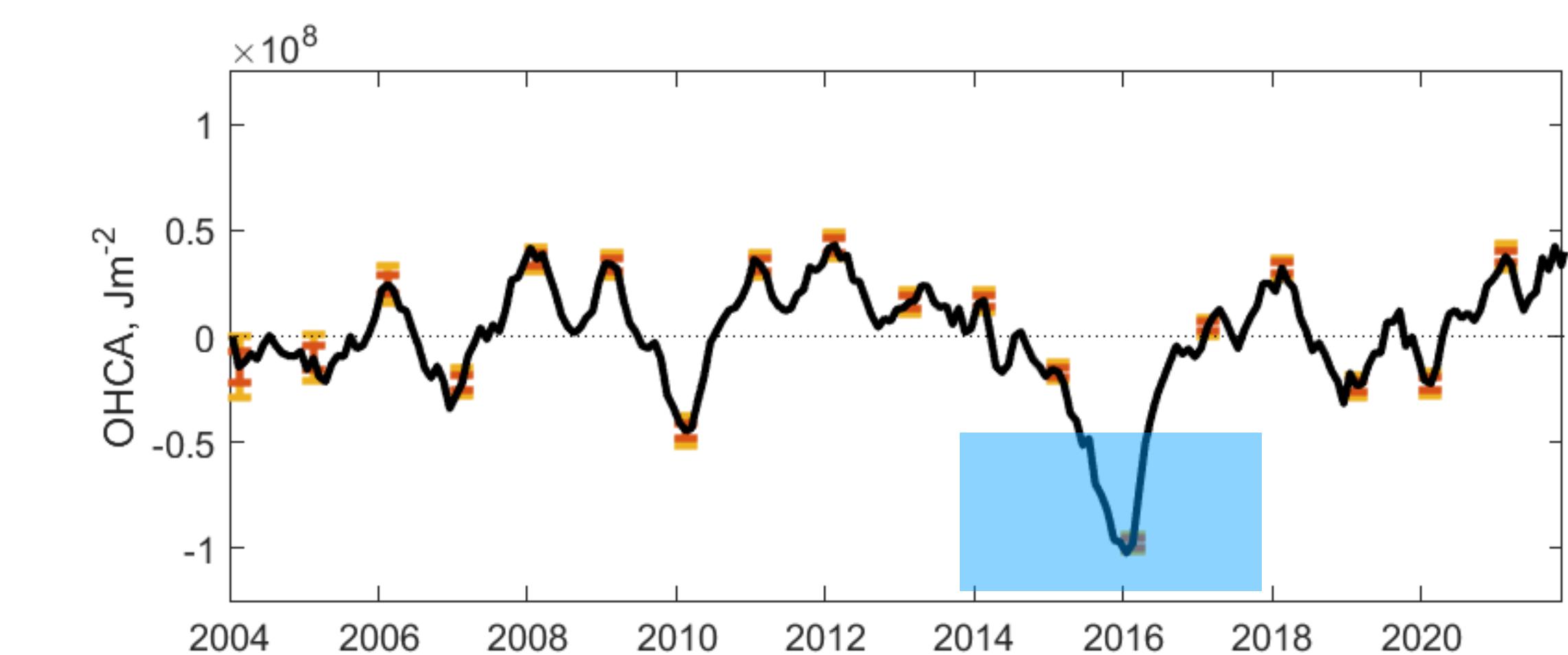


Western Equatorial Pacific OHC anomalies

The 2015-16 El Niño appears in the equatorial OHC anomalies



Significant temperature anomalies (02/2016)



Western Equatorial Pacific OHC anomalies

Future/related work

- Validate kriging variances and uncertainties (e.g. cross-validation)
- Investigate the Kuroshio region (account for non-Gaussianity?)
- Uncertainties for mean field and climatological time trend
- Generalize GP regression model to more than two layers
- Apply model to other fields (e.g. SSH and OHC, oxygen and T/S)

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- Mapping synthetic profiles and comparing to model truth
(Giglio et. al., #1343)
- Uncertainties for OHC trend, OHU, OHCA-ONI cross-correlation
(Kuusela et. al., #1346)

Summary

- Estimating ocean heat content (with reliable uncertainties) is crucial for **tracking climate change**
- Due to having fewer observations deeper in the water column, we model the OHC in the top and bottom layers **separately**
- To model the uncertainties of the total OHC in the water column (top + bottom) we need to estimate the spatially-varying cross-layer **correlation**
- Empirically, using a bivariate GP model to estimate the correlation reduces the OHC anomaly uncertainties both for each layer separately and ~15% in the water column (top + bottom)

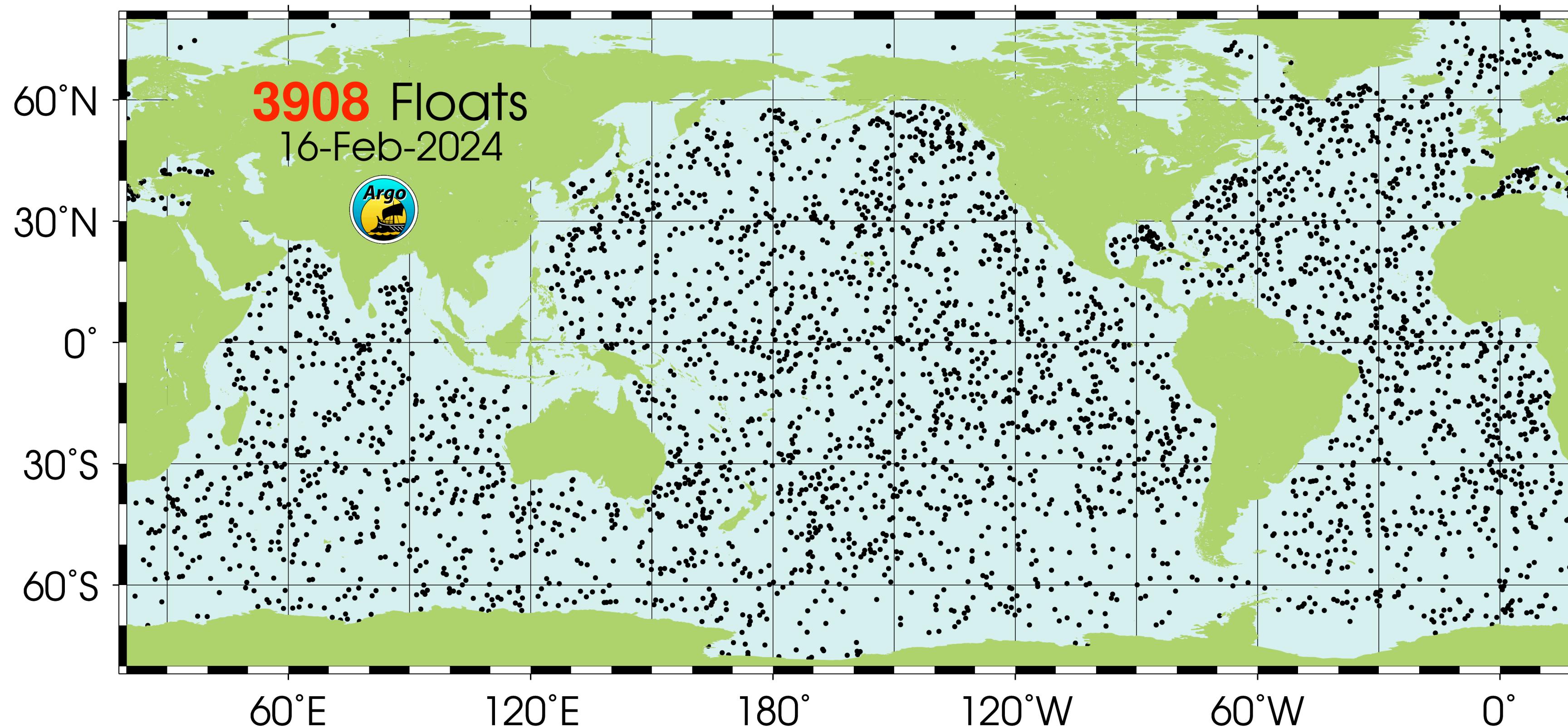
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Thank you!

Backup

Argo floats are the state-of-the-art in ocean temperature measurements

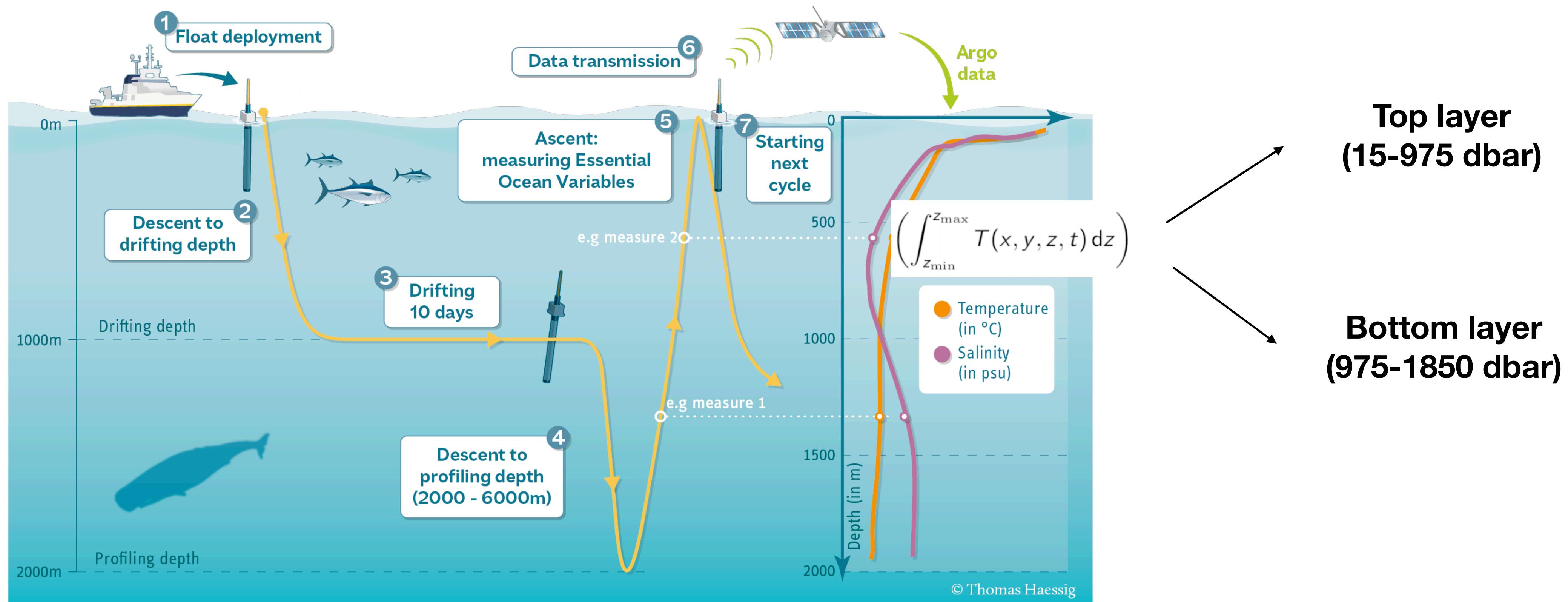


(Argo Program)



OHC integral must be split into layers due to Argo data availability

$$\text{OHC}(t) = \rho_0 c_{p,0} \iint \left(\int_{z_{\min}}^{z_{\max}} T(x, y, z, t) dz \right) dx dy$$



Top layer
(15-975 dbar)

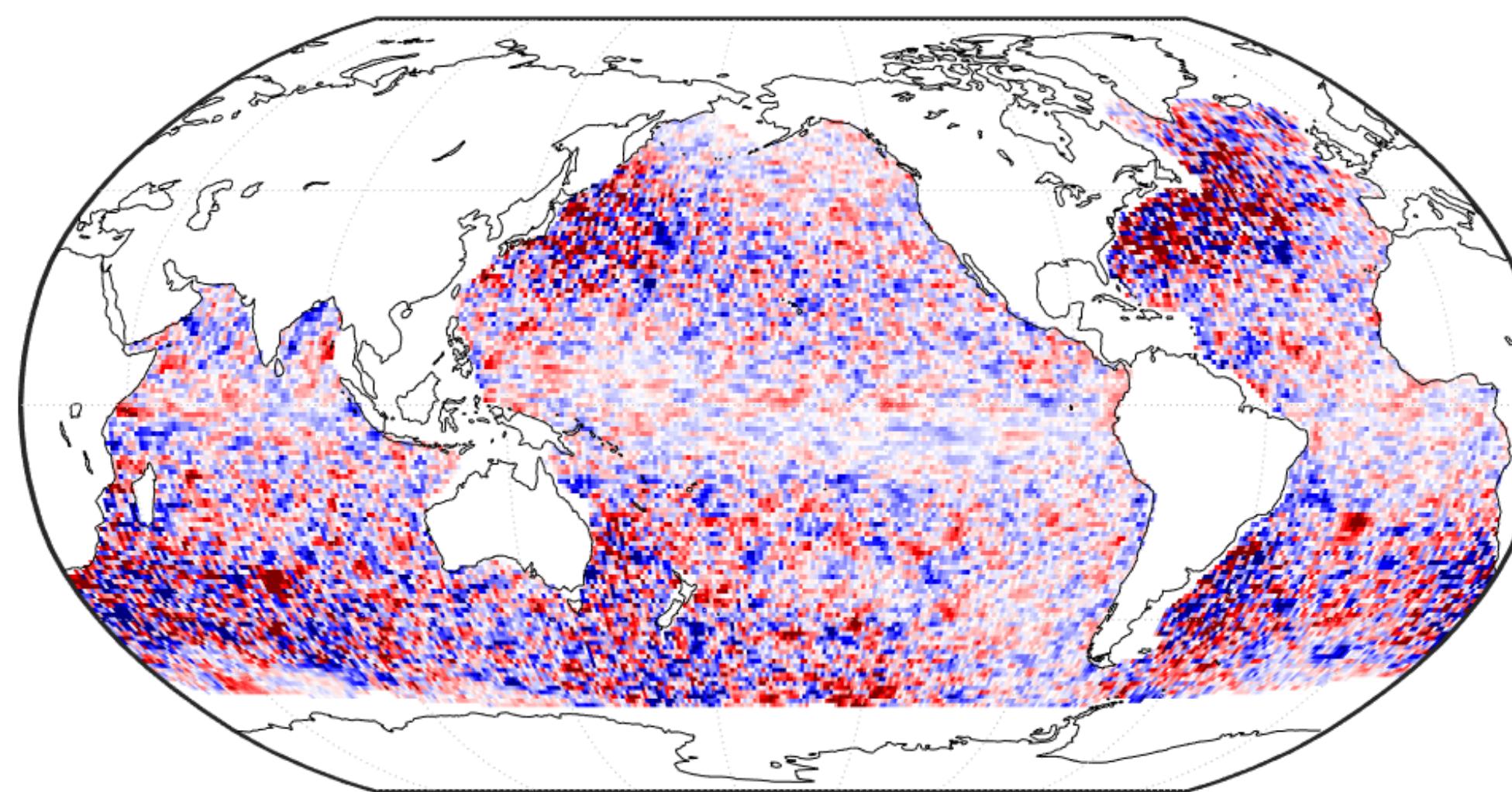
Bottom layer
(975-1850 dbar)

The implementation is still computationally challenging

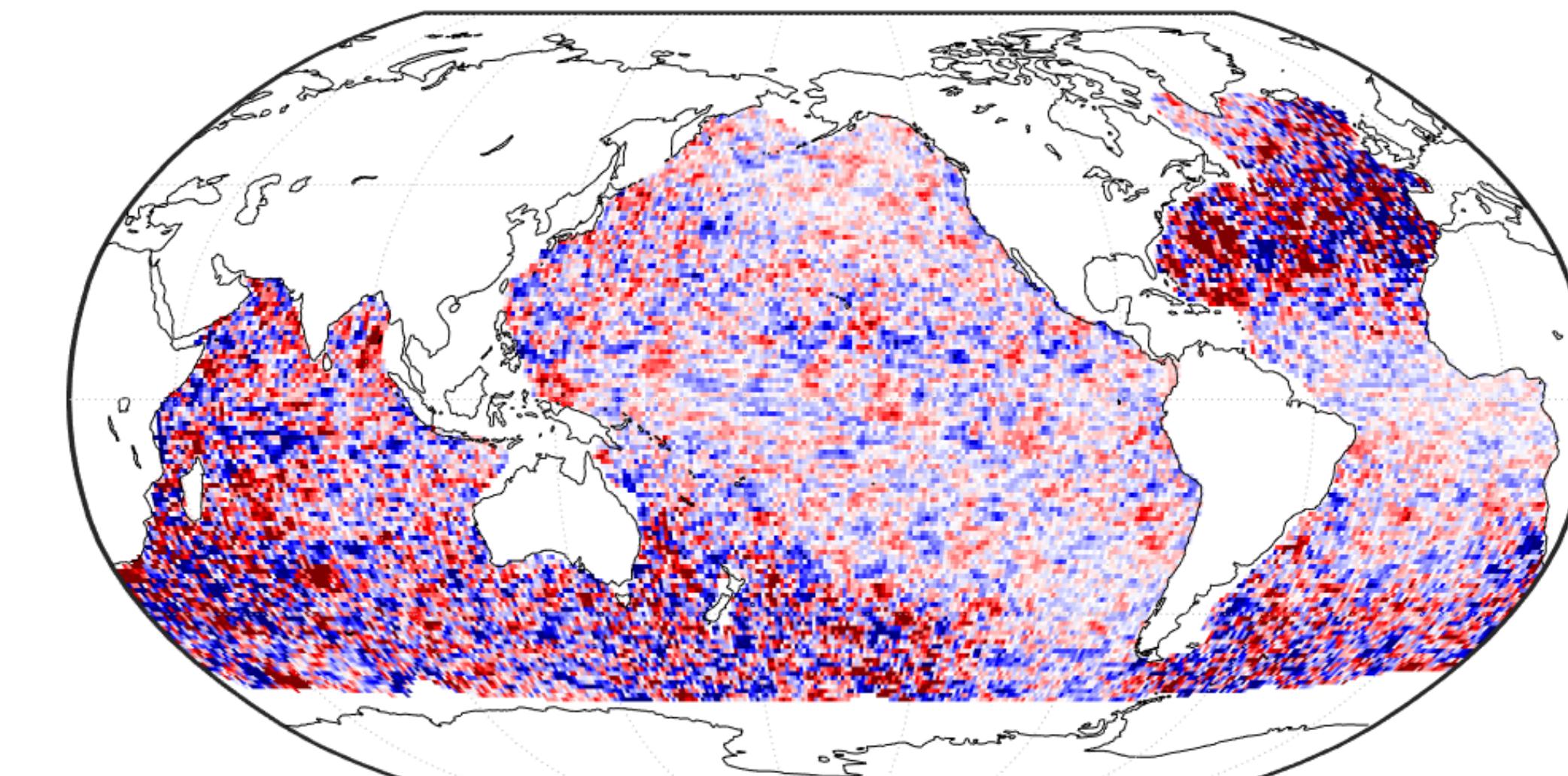
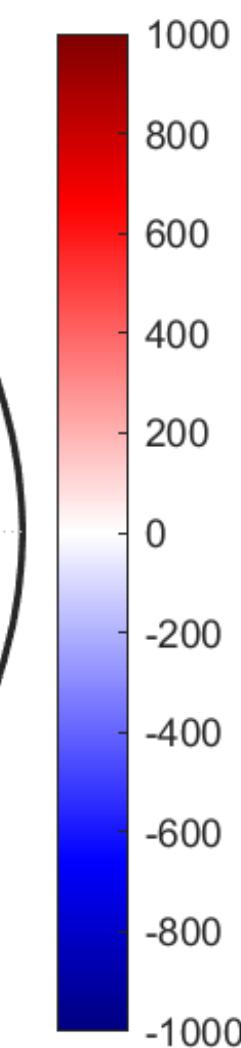
- For every grid point, use data in a 10 degree/3 month window
- Estimate GP model parameters numerically with MLE + BFGS algorithm
- How many grid points? **360 long x 180 lat = 64,800 grid points (!)**
- Embarrassingly parallel, but still computationally challenging
 - Fit parameters for 180 x 20 slice: **67h (desktop) / 8h (PSC)**
 - Obtain conditional simulations for Feb of every year: **~12h (desktop)**

The bivariate uncertainties tend to be ~15% smaller than the univariate

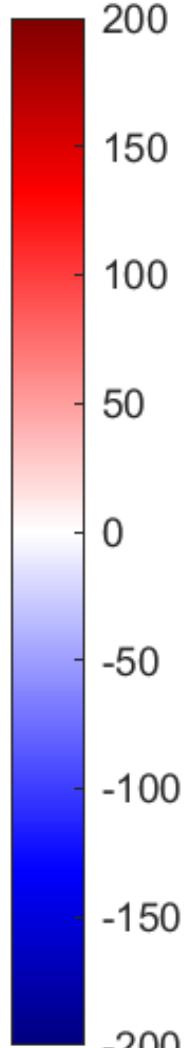
Conditional simulation realization (02/2010)



Upper ocean

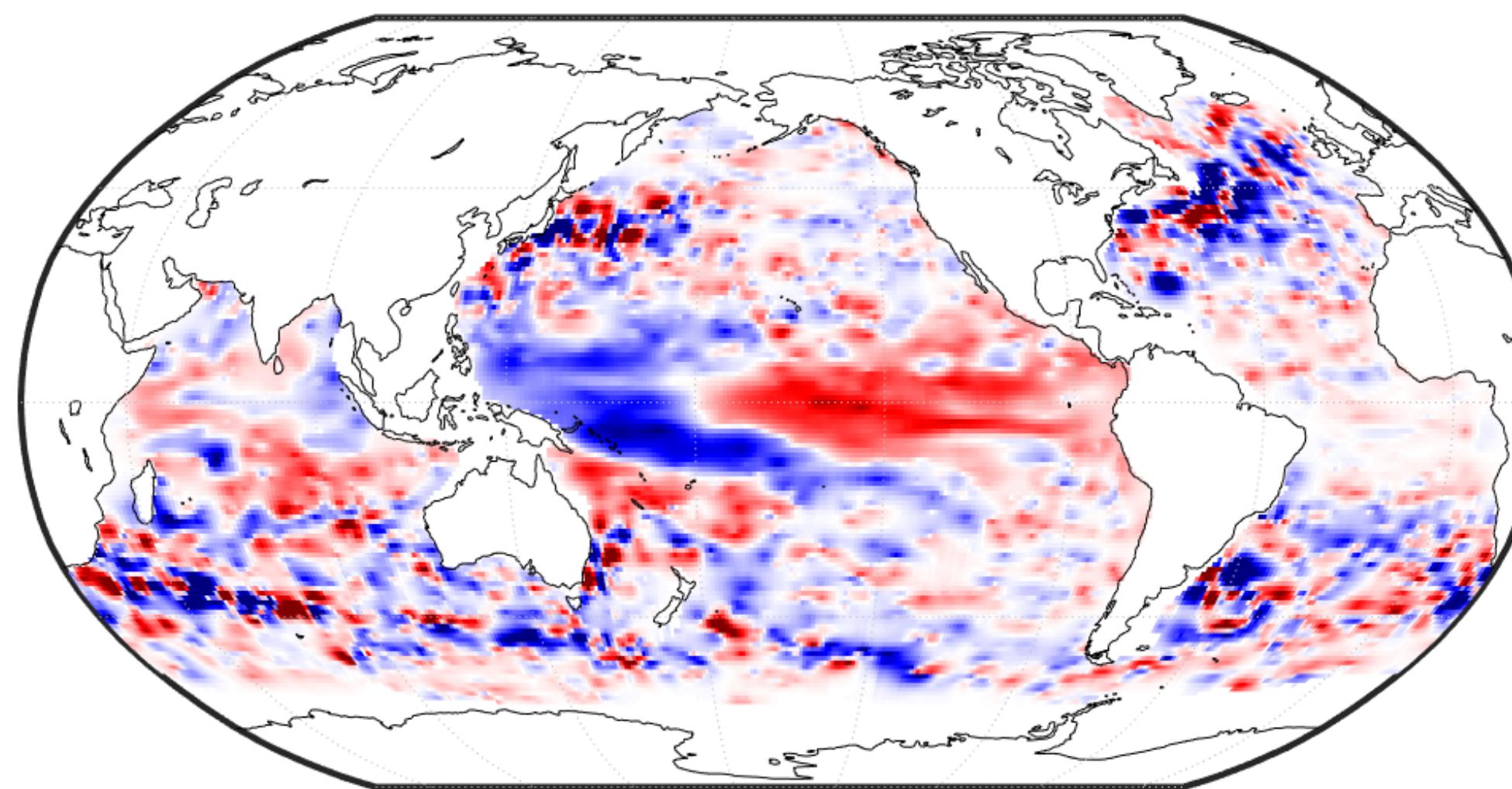


Mid-ocean

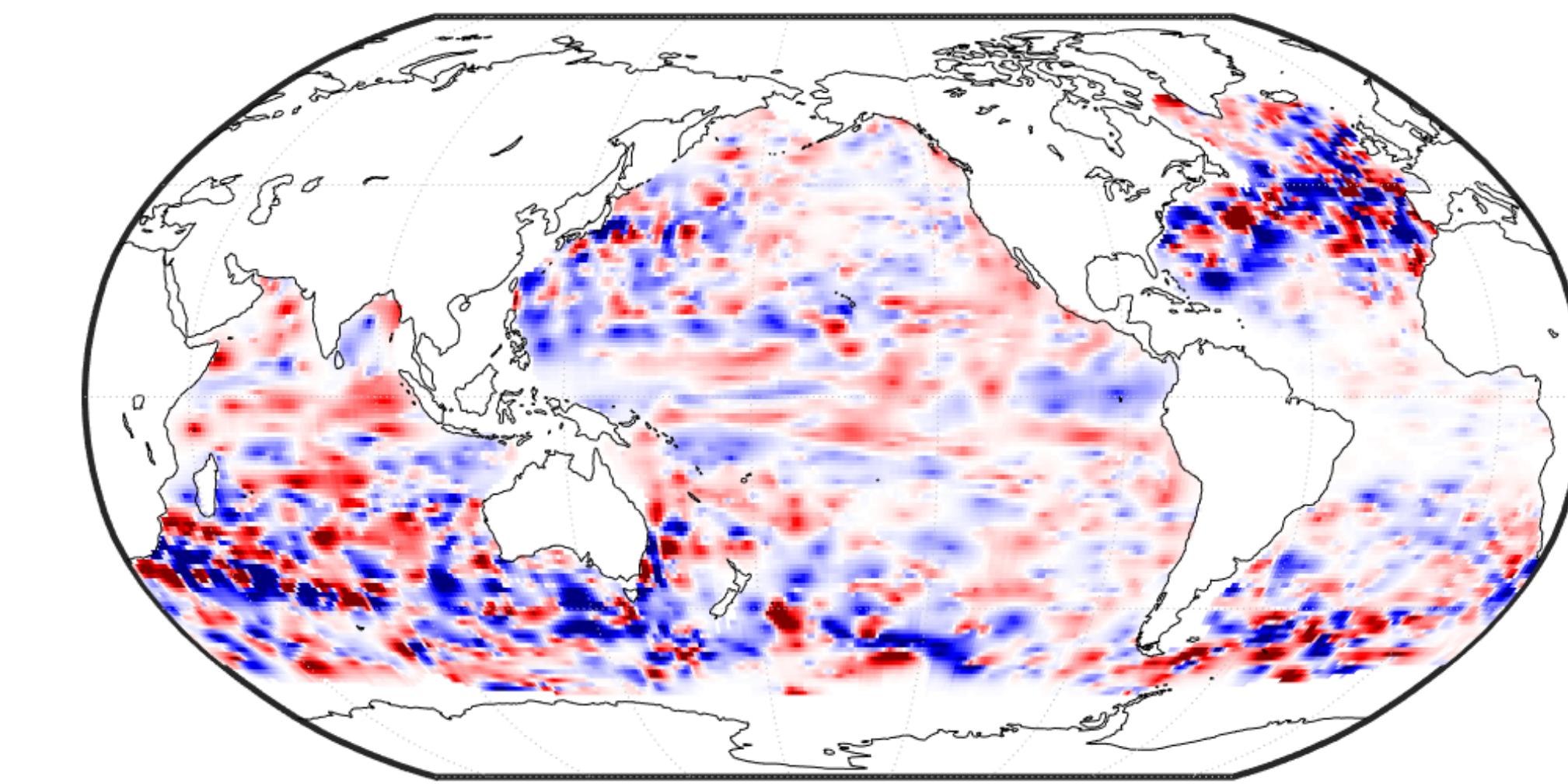
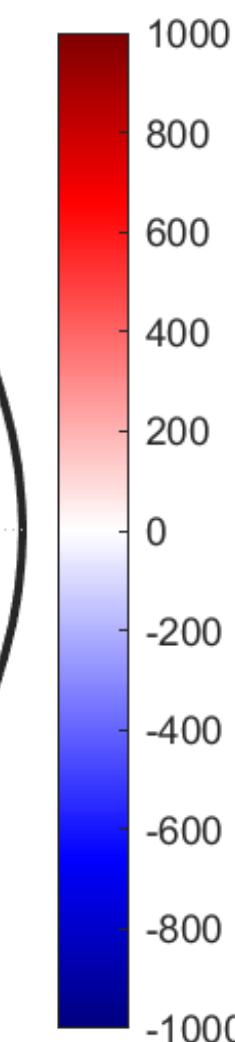


The bivariate model tends to produce lower kriging variances

Predicted temperature anomalies (02/2010)



Top layer



Bottom layer

