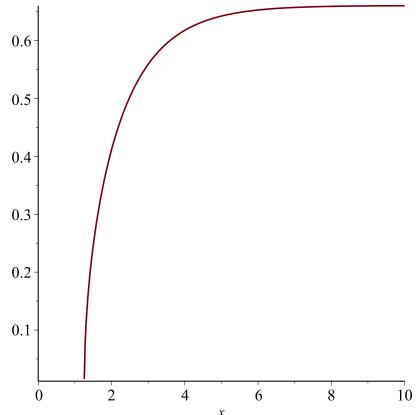
## Ad voorbeeld van de slides (slide 1)



$$\rightarrow diff(f(x),x);$$

$$= \frac{1}{2} \frac{\cos\left(\ln\left(\arctan\left(\frac{e^{x}}{x+1}\right)\right)\right) \left(\frac{e^{x}}{x+1} - \frac{e^{x}}{(x+1)^{2}}\right)}{\sqrt{\sin\left(\ln\left(\arctan\left(\frac{e^{x}}{x+1}\right)\right)\right)} \left(1 + \frac{\left(e^{x}\right)^{2}}{(x+1)^{2}}\right) \arctan\left(\frac{e^{x}}{x+1}\right)}$$

$$= \frac{1}{2} \frac{\left(1.2\right)}{\sqrt{\sin\left(\ln\left(\arctan\left(\frac{e^{x}}{x+1}\right)\right)\right)} \left(1 + \frac{\left(e^{x}\right)^{2}}{(x+1)^{2}}\right) \arctan\left(\frac{e^{x}}{x+1}\right)}$$

## ▼ Ad voorbeeld van de slides (slide 7)

> restart; >  $G := (r, \text{theta}) \rightarrow f(r \cdot \cos(\text{theta}), r \cdot \sin(\text{theta}));$ 

```
G := (r, \theta) \rightarrow f(r\cos(\theta), r\sin(\theta))
                                                                                                                                                                                                                                                                                                                                                              (2.1)
 \rightarrow diff(G(r, theta), r);
                                  D_{1}(f) \left(r\cos(\theta), r\sin(\theta)\right) \cos(\theta) + D_{2}(f) \left(r\cos(\theta), r\sin(\theta)\right) \sin(\theta)
                                                                                                                                                                                                                                                                                                                                                              (2.2)
\rightarrow diff(G(r, theta), theta);
                           -D_1(f) \left(r\cos(\theta), r\sin(\theta)\right) r\sin(\theta) + D_2(f) \left(r\cos(\theta), r\sin(\theta)\right) r\cos(\theta)
                                                                                                                                                                                                                                                                                                                                                              (2.3)
\rightarrow diff(G(r, theta), r, r);
  \left( D_{1,1}(f) \left( r \cos(\theta), r \sin(\theta) \right) \cos(\theta) + D_{1,2}(f) \left( r \cos(\theta), r \sin(\theta) \right) \sin(\theta) \right) \cos(\theta)
                                                                                                                                                                                                                                                                                                                                                              (2.4)
                   + \left( \mathbf{D}_{1,2}(f) \left( r \cos \left( \theta \right), r \sin \left( \theta \right) \right) \cos \left( \theta \right) + \mathbf{D}_{2,2}(f) \left( r \cos \left( \theta \right), r \sin \left( \theta \right) \right) \right) \right) + \mathbf{D}_{2,2}(f) \left( r \cos \left( \theta \right), r \sin \left( \theta \right) \right) \right) + \mathbf{D}_{2,2}(f) \left( r \cos \left( \theta \right), r \sin \left( \theta \right) \right) \right) + \mathbf{D}_{2,2}(f) \left( r \cos \left( \theta \right), r \sin \left( \theta \right) \right) \right) + \mathbf{D}_{2,2}(f) \left( r \cos \left( \theta \right), r \sin \left( \theta \right) \right) \right) + \mathbf{D}_{2,2}(f) \left( r \cos \left( \theta \right), r \sin \left( \theta \right) \right) \right) + \mathbf{D}_{2,2}(f) \left( r \cos \left( \theta \right), r \sin \left( \theta \right) \right) \right) + \mathbf{D}_{2,2}(f) \left( r \cos \left( \theta \right), r \sin \left( \theta \right) \right) \right) + \mathbf{D}_{2,2}(f) \left( r \cos \left( \theta \right), r \sin \left( \theta \right) \right) \right) + \mathbf{D}_{2,2}(f) \left( r \cos \left( \theta \right), r \sin \left( \theta \right) \right) \right) + \mathbf{D}_{2,2}(f) \left( r \cos \left( \theta \right), r \sin \left( \theta \right) \right) \right) + \mathbf{D}_{2,2}(f) \left( r \cos \left( \theta \right), r \sin \left( \theta \right) \right) \right) + \mathbf{D}_{2,2}(f) \left( r \cos \left( \theta \right), r \sin \left( \theta \right) \right) \right) + \mathbf{D}_{2,2}(f) \left( r \cos \left( \theta \right), r \sin \left( \theta \right) \right) + \mathbf{D}_{2,2}(f) \left( r \cos \left( \theta \right), r \cos \left( \theta \right) \right) \right)
               r\sin(\theta)) \sin(\theta)) \sin(\theta)
\rightarrow diff (G(r, \text{theta}), r, \text{theta});
  \left(-\mathrm{D}_{1,\,1}(f)\left(r\cos(\theta),r\sin(\theta)\right)r\sin(\theta)+\mathrm{D}_{1,\,2}(f)\left(r\cos(\theta),r\sin(\theta)\right)\right)
                                                                                                                                                                                                                                                                                                                                                              (2.5)
                 r\sin(\theta)) r\cos(\theta) \cos(\theta) - D_1(f) (r\cos(\theta), r\sin(\theta)) \sin(\theta) + (
                 -D_{1,2}(f)\left(r\cos(\theta),r\sin(\theta)\right)r\sin(\theta)+D_{2,2}(f)\left(r\cos(\theta),r\sin(\theta)\right)r\cos(\theta)
                  \sin(\theta) + D_2(f) (r\cos(\theta), r\sin(\theta)) \cos(\theta)
\rightarrow diff (G(r, \text{theta}), \text{theta}, \text{theta});
  \begin{aligned} & -\left(-\mathrm{D}_{1,\,1}(f)\,\left(r\cos(\theta),r\sin(\theta)\right)\,r\sin(\theta) + \mathrm{D}_{1,\,2}(f)\,\left(r\cos(\theta),\\ & r\sin(\theta)\right)\,r\cos(\theta)\right)\,r\sin(\theta) - \mathrm{D}_{1}(f)\,\left(r\cos(\theta),r\sin(\theta)\right)\,r\cos(\theta) + \left(\\ & -\mathrm{D}_{1,\,2}(f)\,\left(r\cos(\theta),r\sin(\theta)\right)\,r\sin(\theta) + \mathrm{D}_{2,\,2}(f)\,\left(r\cos(\theta),r\sin(\theta)\right)\,r\cos(\theta)\right) \end{aligned} 
                                                                                                                                                                                                                                                                                                                                                              (2.6)
                  r\cos(\theta) - D_2(f) (r\cos(\theta), r\sin(\theta)) r\sin(\theta)
```

## **Ad Gradient**

```
> with(VectorCalculus);
[\&x, `*`, `+`, `-`, `.`, <, >, <|>, About, AddCoordinates, ArcLength, BasisFormat,
                                                                                              (3.1)
    Binormal, Compatibility, ConvertVector, CrossProduct, Curl, Curvature, D, Del,
    DirectionalDiff, Divergence, DotProduct, Flux, GetCoordinateParameters,
    GetCoordinates, GetNames, GetPVDescription, GetRootPoint, GetSpace, Gradient,
    Hessian, IsPositionVector, IsRootedVector, IsVectorField, Jacobian, Laplacian, LineInt,
    MapToBasis, Nabla, Norm, Normalize, PathInt, PlotPositionVector, PlotVector,
    PositionVector, PrincipalNormal, RadiusOfCurvature, RootedVector, ScalarPotential,
    SetCoordinateParameters, SetCoordinates, SpaceCurve, SurfaceInt, TNBFrame,
    Tangent, TangentLine, TangentPlane, TangentVector, Torsion, Vector, VectorField,
    VectorPotential, VectorSpace, Wronskian, diff, eval, evalVF, int, limit, series]
> with(plots);
[animate, animate3d, animatecurve, arrow, changecoords, complexplot, complexplot3d,
                                                                                              (3.2)
    conformal, conformal3d, contourplot, contourplot3d, coordplot, coordplot3d,
    densityplot, display, dualaxisplot, fieldplot, fieldplot3d, gradplot, gradplot3d,
    implicitplot, implicitplot3d, inequal, interactive, interactiveparams, intersectplot,
```

listcontplot, listcontplot3d, listdensityplot, listplot, listplot3d, loglogplot, logplot, matrixplot, multiple, odeplot, pareto, plotcompare, pointplot, pointplot3d, polarplot, polygonplot, polygonplot3d, polyhedra\_supported, polyhedraplot, rootlocus, semilogplot, setcolors, setoptions, setoptions3d, spacecurve, sparsematrixplot, surfdata, textplot, textplot3d, tubeplot]

=   
> 
$$Gradient(x^2 + y^2, [x, y]);$$
  $2 x \bar{e}_x + 2 y \bar{e}_y$  (3.3)

> 
$$gradplot((x^2+y^2), x=-2..2, y=-2..2);$$

> gradplot(
$$\sin(x^2 + y^2)$$
,  $x = -2...2$ ,  $y = -2...2$ );

---- $\frac{-}{2}$ ----

> gradplot3d 
$$\left(\sin\left(x^2+y^2+z^2\right)^{\frac{1}{2}}, x=-2..2, y=-2..2, z=-2..2\right);$$

