Discrete Fourier Transform (DFT)

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Recall that the spectrum of the discrete-time signal x is given by

$$X(\omega) = \sum_{n = -\infty}^{\infty} x(n)e^{-j\omega n}$$

where the signal \boldsymbol{x} can be recovered from its spectrum by the inverse Fourier transform

$$x(n) = \frac{1}{2\pi} \int_0^{2\pi} X(\omega) e^{j\omega n} d\omega$$



Frequency analysis of discrete-time signals is usually and most conveniently performed on a digital signal processor:

- ullet we convert the discrete-time signal x to an equivalent frequency-domain representation
- \bullet such a representation is given by the Fourier transform $X(\omega)$ of x
- ullet however, $X(\omega)$ is a continuous function of frequency and therefore not a convenient representation of x

We will consider the representation of x by samples of its spectrum $X(\omega)$, which will lead to the discrete Fourier transform (DFT)



Recall that discrete-time aperiodic finite-energy signals have continuous 2π -periodic spectra

$$X(\omega) = \sum_{n = -\infty}^{\infty} x(n)e^{-j\omega n}$$

Taking N equally spaced samples of $X(\omega)$ on the fundamental frequency range $[0,2\pi)$ yields

$$X\left(\frac{2\pi}{N}k\right) = \sum_{n=-\infty}^{\infty} x(n)e^{-j\frac{2\pi}{N}kn}, \quad k = 0, \dots, N-1$$



What do these frequency samples tell us about x?

$$X\left(\frac{2\pi}{N}k\right) = \sum_{n=-\infty}^{\infty} x(n)e^{-j\frac{2\pi}{N}kn}$$

$$= \sum_{m=-\infty}^{\infty} \sum_{n=mN}^{(m+1)N-1} x(n)e^{-j\frac{2\pi}{N}kn}$$

$$= \sum_{m=-\infty}^{\infty} \sum_{n=0}^{N-1} x(n+mN)e^{-j\frac{2\pi}{N}kn}$$

$$= \sum_{n=0}^{N-1} \left(\sum_{m=-\infty}^{\infty} x(n+mN)\right) e^{-j\frac{2\pi}{N}kn}$$



The signal

$$x_p(n) = \sum_{m=-\infty}^{\infty} x(n+mN)$$

is an N-periodic repetition of x.

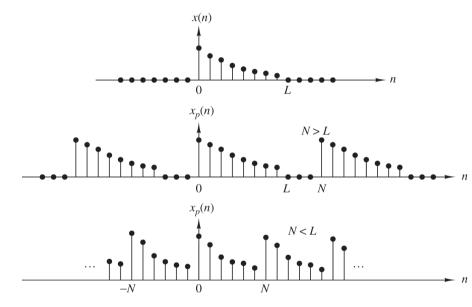


Figure 7.1.2 Aperiodic sequence x(n) of length L and its periodic extension for $N \ge L$ (no aliasing) and N < L (aliasing).



As a consequence, it has a Fourier series expansion

$$x_p(n) = \sum_{k=0}^{N-1} c_k e^{j\frac{2\pi}{N}kn}$$

with Fourier coefficients

$$c_k = \frac{1}{N} \sum_{n=0}^{N-1} x_p(n) e^{-j\frac{2\pi}{N}kn} = \frac{1}{N} X\left(\frac{2\pi}{N}k\right)$$

As a consequence, we have

$$x_p(n) = \frac{1}{N} \sum_{k=0}^{N-1} X\left(\frac{2\pi}{N}k\right) e^{j\frac{2\pi}{N}kn}$$



This relation shows how to reconstruct x_p from the samples of $X(\omega)$. However, it does not imply that we can recover $X(\omega)$ (and thus x) from its samples. To accomplish this, we need to consider the relation between x_p and x

Since x_p is the periodic extension of x, x can be recovered if it has finite support of L samples less than N ($N \ge L$)

On the other hand, if N < L, it is not possible to recover x from its periodic extension due to time-domain aliasing



Assume $N \geq L$. As in the continuous-time case, we can express the spectrum $X(\omega)$ in terms of its samples $X(\frac{2\pi}{N}k)$ using an interpolation formula

$$X(\omega) = \sum_{n=0}^{N-1} \left(\frac{1}{N} \sum_{k=0}^{N-1} X\left(\frac{2\pi}{N}k\right) e^{j\frac{2\pi}{N}kn} \right) e^{-j\omega n}$$

x(n)

$$= \sum_{k=0}^{N-1} X\left(\frac{2\pi}{N}k\right) \left(\frac{1}{N}\sum_{n=0}^{N-1} e^{-j(\omega - \frac{2\pi}{N}k)n}\right)$$



Since

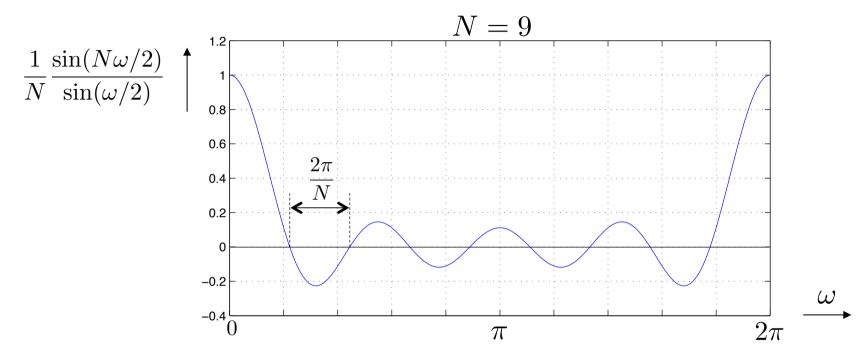
$$\sum_{n=0}^{N-1} e^{-j\omega n} = \frac{1 - e^{-j\omega N}}{1 - e^{-j\omega}} = e^{-j\omega \frac{N-1}{2}} \frac{\sin(\frac{\omega N}{2})}{\sin(\frac{\omega}{2})} = G(\omega)$$

we conclude that

$$X(\omega) = \frac{1}{N} \sum_{k=0}^{N-1} X\left(\frac{2\pi}{N}k\right) G\left(\omega - \frac{2\pi}{N}k\right)$$

The function $G(\omega)$ is not the familiar sinc-function, but a periodic counterpart of it





Clearly, $\frac{1}{N}G(\omega)$ is an interpolation function since

$$\frac{1}{N}G\left(\frac{2\pi}{N}k\right) = \begin{cases} 1, & k = 0\\ 0, & k = 1,\dots, N-1 \end{cases}$$

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Similarly to what we did with sampling continuous-time signals, we can evaluate the time-domain description of interpolating the spectral samples. If

$$X(\omega) = \frac{1}{N} \sum_{k=0}^{N-1} X\left(\frac{2\pi}{N}k\right) G\left(\omega - \frac{2\pi}{N}k\right)$$

then

$$x(n) = g(n)x_p(n)$$

with

$$g(n) = \left\{ \begin{array}{ll} 1, & \text{for } n = 0, \dots, N-1 \\ 0, & \text{otherwise} \end{array} \right.$$

Hence, g is a rectangular window taking N samples out of x_p

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Example (N < L**):** $x(n) = a^n u(n), \ a < 1.$ The Fourier transform of x is given by

$$X(\omega) = \frac{1}{1 - ae^{-j\omega}} \quad \Rightarrow \quad X\left(\frac{2\pi}{N}k\right) = \frac{1}{1 - ae^{-j\frac{2\pi}{N}k}}$$

The periodic extension of x is given by

$$x_p(n) = \sum_{m=-\infty}^{\infty} x(n+mN) = \sum_{m=0}^{\infty} a^{n+mN} = \frac{a^n}{1-a^n}$$

The factor $1/(1-a^N)$ represents the effect of aliasing which tends to zero as $N \to \infty$



Ideal interpolation of the spectral samples corresponds to selecting the first N-samples of x_p

$$\hat{x}(n) = \begin{cases} x_p(n), & \text{for } n = 0, \dots, N-1 \\ 0, & \text{otherwise} \end{cases}$$

Its Fourier transform is given by

$$\hat{X}(\omega) = \sum_{n=0}^{N-1} x_p(n)e^{-j\omega n} = \frac{1}{1 - a^N} \frac{1 - a^N e^{-j\omega N}}{1 - ae^{-j\omega}}$$

Note that $\hat{X}(\omega) \neq X(\omega)$, except for sample values at $\omega_k = \frac{2\pi}{N}k$



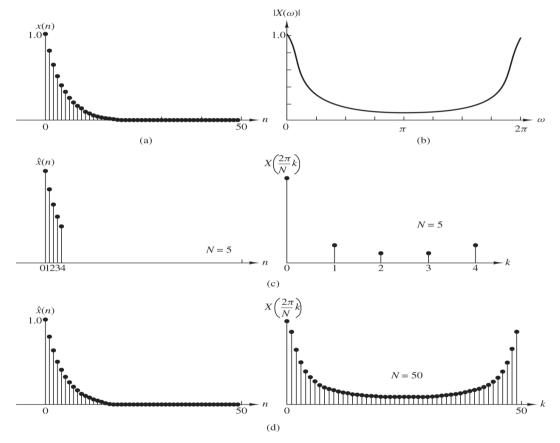


Figure 7.1.4 (a) Plot of sequence $x(n) = (0.8)^n u(n)$; (b) its Fourier transform (magnitude only); (c) effect of aliasing with N = 5; (d) reduced effect of aliasing with N = 50.



In summary, a finite support signal x of length N can be represented by N samples of its continuous-frequency spectrum $X(\omega)$. These samples uniquely determined x

Discrete Fourier transform (DFT):

DFT:
$$X(k) = \sum_{n=0}^{N-1} x(n)e^{-j\frac{2\pi}{N}kn}, \quad k = 0, \dots, N-1$$

IDFT:
$$x(n) = \frac{1}{N} \sum_{k=0}^{N-1} X(k) e^{j\frac{2\pi}{N}kn}, \quad n = 0, \dots, N-1$$



Let $W_N = e^{j\frac{2\pi}{N}}$. We have

$$\begin{pmatrix} X(0) \\ X(1) \\ X(2) \\ \vdots \\ X(N-1) \end{pmatrix} = \begin{pmatrix} 1 & 1 & 1 & \cdots & 1 \\ 1 & W_N^{-1} & W_N^{-2} & \cdots & W_N^{-(N-1)} \\ 1 & W_N^{-2} & W_N^{-4} & \cdots & W_N^{-2(N-1)} \\ \vdots & \vdots & \ddots & \vdots \\ 1 & W_N^{-(N-1)} & W_N^{-2(N-1)} & \cdots & W_N^{-(N-1)(N-1)} s \end{pmatrix} \begin{pmatrix} x(0) \\ x(1) \\ x(2) \\ \vdots \\ x(N-1) \end{pmatrix}$$

$$= \begin{pmatrix} 1 & 1 & 1 & \cdots & 1 \\ 1 & W_N^{-1} & W_N^{-2} & \cdots & W_N^{1} \\ 1 & W_N^{-2} & W_N^{-4} & \cdots & W_N^{2} \\ \vdots & \vdots & \ddots & \vdots \\ 1 & W_N^{1} & W_N^{2} & \cdots & W_N^{N-1} \end{pmatrix} \begin{pmatrix} x(0) \\ x(1) \\ x(2) \\ \vdots \\ x(N-1) \end{pmatrix}$$

$$\xrightarrow{\text{matrix } F_N}$$



The DFT matrix F_N is unitairy:

$$F_N F_N^* = F_N^* F_N = NI$$

Proof: the (i,j)th-element of the product $F_N F_N^*$ is given by

$$(F_N F_N^*)_{i,j} = \sum_{n=0}^{N-1} W_N^{-in} W_N^{jn} = \sum_{n=0}^{N-1} W^{(j-i)n} = \left\{ \begin{array}{l} N, & \text{if } i = j \\ 0, & \text{otherwise} \end{array} \right. \\ \left(\begin{array}{l} 1 & 1 & 1 & \cdots & 1 \\ \vdots & \vdots & \ddots & \vdots \\ 1 & W_N^{-i} & W_N^{-2i} & \cdots & W_N^{-(N-1)i} \\ \vdots & \vdots & \ddots & \vdots \\ 1 & W_N^1 & W_N^2 & \cdots & W_N^{N-1} \end{array} \right) \left(\begin{array}{l} 1 & \cdots & 1 & \cdots & 1 \\ 1 & \cdots & W_N^j & \cdots & W_N^{-1} \\ 1 & \cdots & W_N^{2j} & \cdots & W_N^{-2} \\ \vdots & \vdots & \ddots & \vdots \\ 1 & \cdots & W_N^{(N-1)j} & \cdots & W_N^{-(N-1)} \end{array} \right) = NI$$



Since $F_n F_N^* = NI$, we conclude that the inverse DFT is given by :

$$F_N^{-1} = \frac{1}{N} F_N^* = \frac{1}{N} \begin{pmatrix} 1 & 1 & 1 & \cdots & 1 \\ 1 & W_N^1 & W_N^2 & \cdots & W_N^{-1} \\ 1 & W_N^2 & W_N^4 & \cdots & W_N^{-2} \\ \vdots & \vdots & \ddots & \vdots \\ 1 & W_N^{-1} & W_N^{-2} & \cdots & W_N^{-(N-1)} \end{pmatrix}$$

Hence,

$$x(n) = \frac{1}{N} \sum_{k=0}^{N-1} X(k) e^{j\frac{2\pi}{N}kn}, \quad n = 0, \dots, N-1$$



Some facts:

- the DFT is a powerful computational tool for performing frequency analysis of discrete-time signals
- there exists a fast implementation of the DFT, the fast Fourier transform (FFT).
- we know from Fourier theory that pointwise multiplication in the frequency domain transforms into (linear) convolution in the time domain and vice versa. The DFT, however, transforms pointwise multiplication into cyclic convolution, rather than linear convolution
- © linear convolution can be implemented using cyclic convolution

Fast Fourier Transform

A direct computation of an N-points DFT requires N^2 multiplications. However, we have

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$$N-\text{points DFT}$$

$$X(k) = \sum_{n=0}^{N-1} x(n)e^{-j\frac{2\pi}{N}kn}$$

$$= \sum_{n=0}^{N/2-1} x(2n)e^{-j\frac{2\pi}{N}2nk} + \sum_{n=0}^{N/2-1} x(2n+1)e^{-j\frac{2\pi}{N}(2n+1)k}$$

$$= \sum_{n=0}^{N/2-1} x(2n)e^{-j\frac{2\pi}{N}2nk} + e^{-j\frac{2\pi}{N}k} \sum_{n=0}^{N/2-1} x(2n+1)e^{-j\frac{2\pi}{N}2nk}$$

$$N/2-\text{points DFT}$$

$$= \sum_{n=0}^{N/2-1} x(2n)e^{-j\frac{2\pi}{N/2}nk} + e^{-j\frac{2\pi}{N}k} \sum_{n=0}^{N/2-1} x(2n+1)e^{-j\frac{2\pi}{N/2}nk}$$

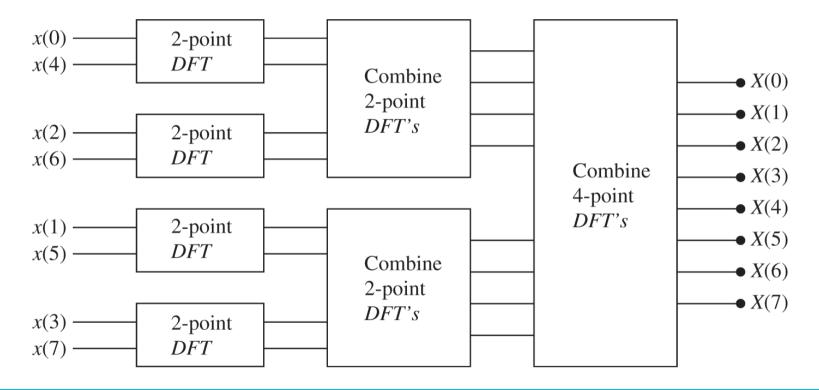
$$= \sum_{n=0}^{N/2-1} x(2n)e^{-j\frac{2\pi}{N/2}nk} + e^{-j\frac{2\pi}{N}k} \sum_{n=0}^{N/2-1} x(2n+1)e^{-j\frac{2\pi}{N/2}nk}$$

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Fast Fourier Transform

Computational complexity $\mathcal{O}(N \log N)$ for the FFT versus $\mathcal{O}(N^2)$ for the DFT



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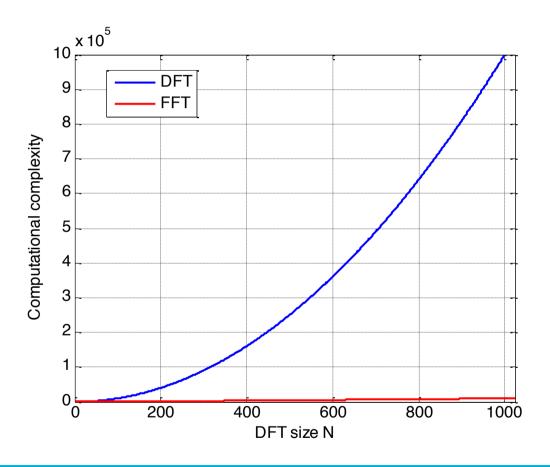


Fast Fourier Transform

Example: N = 1024

DFT: 1,000,000 mults/adds

FFT: 10,000 mults/adds





Radix-2 FFT Algorithm

We have

$$X(k) = X_1(k) + W_N^k X_2(k), \quad k = 0, \dots, N-1$$

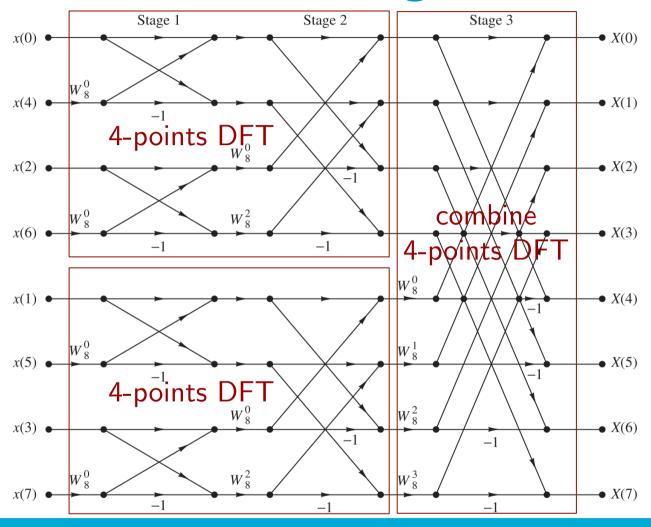
where X_1 and X_2 are the N/2-points DFTs of the sequences x(2n) and $x(2n+1), \ n=0,\ldots,N/2$, and are, therefore, N/2 periodic. Moreover, we have that $W_N^{k+N/2}=-W_N^k$. With this, we have

$$X(k) = X_1(k) + W_N^k X_2(k), \quad k = 0, \dots, \frac{N}{2}$$
$$X\left(k + \frac{N}{2}\right) = X_1(k) - W_N^k X_2(k), \quad k = 0, \dots, \frac{N}{2}$$

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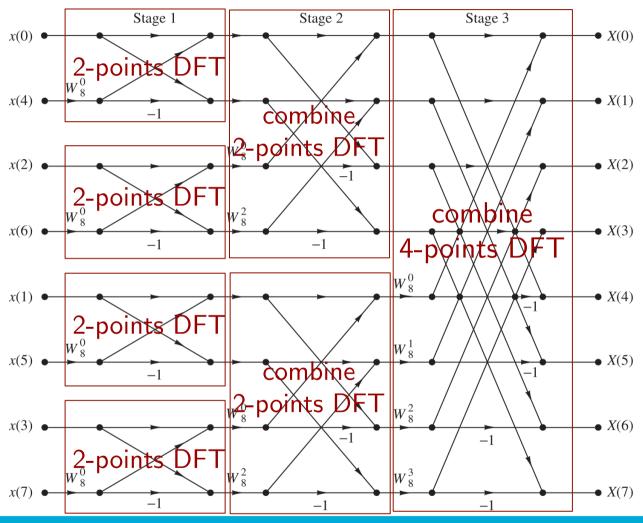


Radix-2 FFT Algorithm





Radix-2 FFT Algorithm





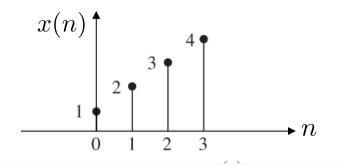
Proposition:

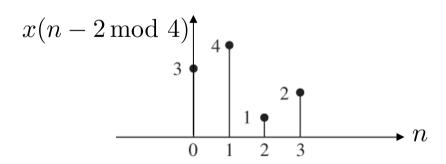
$$X \cdot Y \stackrel{DFT}{\longleftrightarrow} x \circledast_N y$$

where

$$(x \circledast_N y)(n) = \sum_{m=0}^{N-1} x(m)y(n-m \mod N)$$

Hence, the product of two DFTs results in the DFT of *cyclicly* convolved sequences, *not* linearly convolved sequences!







Proof:

$$\frac{1}{N} \sum_{k=0}^{N-1} \left(\sum_{m=0}^{N-1} x(m) e^{-j\frac{2\pi}{N}km} \right) \left(\sum_{l=0}^{N-1} y(l) e^{-j\frac{2\pi}{N}kl} \right) e^{j\frac{2\pi}{N}kn}$$

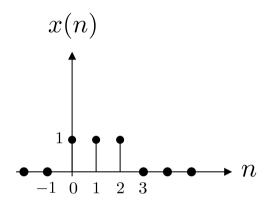
$$= \frac{1}{N} \sum_{m=0}^{N-1} x(m) \sum_{l=0}^{N-1} y(l) \sum_{k=0}^{N-1} e^{j\frac{2\pi}{N}k(n-l-m)}$$

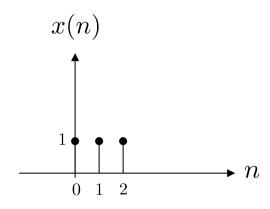
$$= \begin{cases} N, & l = n-m \mod N \\ 0, & \text{otherwise} \end{cases}$$

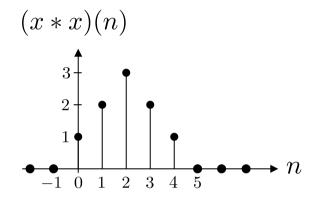
$$= \sum_{m=0}^{N-1} x(m) y(n-m \mod N)$$

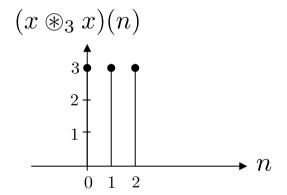


Example:











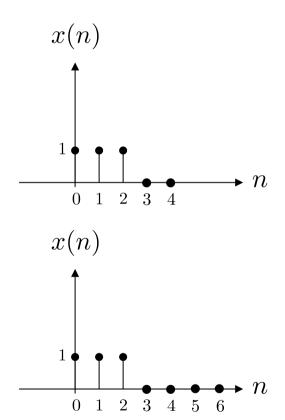
We can, however, implement a linear convolution using a cyclic convolution by zero-padding:

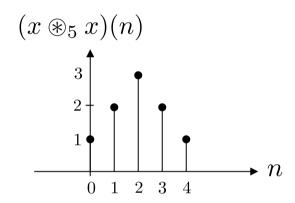
- ullet let N_x and N_y denote the length of the sequences to be convolved
- ullet length of the linearly convolved sequence is N_x+N_y-1
- ullet zero-pad both x and y to a length of at least N_x+N_y-1
- ullet the linear convolution is then given by the first N_x+N_y-1 samples of $x\circledast y$

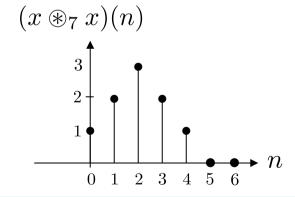
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Example:

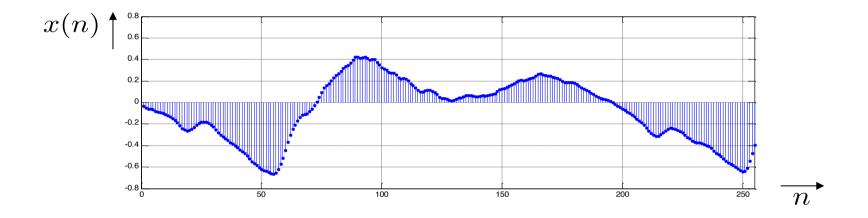








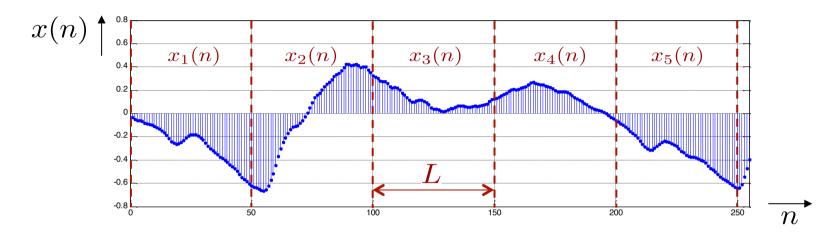
Application: FIR filtering of long data sequences



We assume that the FIR filter has a support of M samples

We apply the FIR filter on a block-by-block basis, where each block is of length L, and we assume that $L\gg M$ without loss of generality





We express x as

$$x(n) = \sum_{l=-\infty}^{\infty} x_l(n)$$

where

$$x_l(n) = \begin{cases} x(n-lL), & n = 0, \dots, L-1 \\ 0, & \text{otherwise} \end{cases}$$

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With this, the convolution x * h can be expressed as

$$y(n) = \sum_{k=0}^{M-1} h(k)x(n-k)$$

$$= \sum_{k=0}^{M-1} h(k) \sum_{l=-\infty}^{\infty} x_l(n-k)$$

$$= \sum_{l=-\infty}^{\infty} \sum_{k=0}^{M-1} h(k)x_l(n-k)$$

$$= \sum_{l=-\infty}^{\infty} \sum_{k=0}^{M-1} h(k)x_l(n-k)$$



In conclusion, the convolution x * h can be expressed as a linear combination of convolutions $x_l * h$.

- In order to use the DFT (or FFT) to implement the convolutions, we have to apply a DFT of size N=M+L-1. Hence, to each block of data x_l we append M-1 zeros and compute the N-points DFT.
- \bullet Similarly, we compute the $N\mbox{-points}$ DFT of h (padded with L-1 zeros)
- We multiply the two N-points DFTs: $Y_l = X_l H$
- ullet The inverse DFT yields data blocks of length N which have to be added (overlapped)

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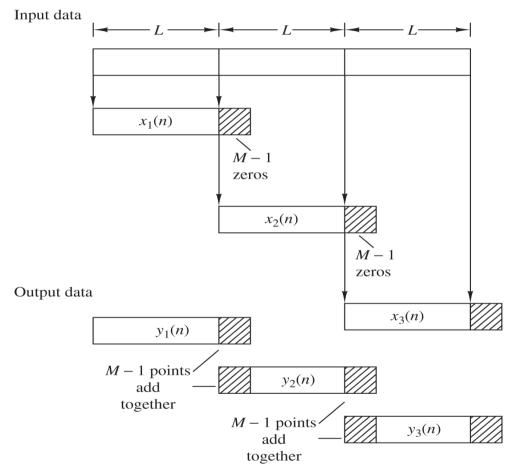


Figure 7.3.2 Linear FIR filtering by the overlap-add method.

