

Notes for New Constructions of DMPF

tbd

ABSTRACT

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CCS CONCEPTS

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1 INTRODUCTION

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2 PRELIMINARY

2.1 Basic Notations

Point and multi-point functions. Given a domain size N and Abelian group \mathbb{G} , a *point function* $f_{\alpha,\beta} : [N] \rightarrow \mathbb{G}$ for $\alpha \in [N]$ and $\beta \in \mathbb{G}$ evaluates to β on input α and to $0 \in \mathbb{G}$ on all other inputs. We denote by $\hat{f}_{\alpha,\beta} = (N, \hat{\mathbb{G}}, \alpha, \beta)$ the representation of such a point function, where $\hat{\mathbb{G}}$ denotes the description of the group \mathbb{G} . A *t-point function* $f_{A,B} : [N] \rightarrow \mathbb{G}$ for $A = \{\alpha_1, \dots, \alpha_t\} \subset [N]$ listed in ascending order and $B = (\beta_1, \dots, \beta_t) \in \mathbb{G}^t$ evaluates to β_i on input α_i for $1 \leq i \leq t$ and to 0 on all other inputs. Denote $\hat{f}_{A,B}(N, \hat{\mathbb{G}}, t, A, B)$ the representation of such a *t-point function*. Call the collection of all *t-point functions* for all *t* *multi-point functions*.

2.2 Distributed Multi-Point Functions

We begin by defining the notion of distributed point functions (DPF) and distributed multi-point functions (DMPF), that additively and succinctly share point functions (multi-point functions) respectively.

DEFINITION 1 (DPF [5, 11]). A (2-party) distributed point function (DPF) is a triple of algorithms $\Pi = (\text{Gen}, \text{Eval}_0, \text{Eval}_1)$ with the following syntax:

- $\text{Gen}(1^\lambda, \hat{f}_{\alpha,\beta}) \rightarrow (k_0, k_1)$: On input security parameter $\lambda \in \mathbb{N}$ and point function description $\hat{f}_{\alpha,\beta} = (N, \hat{\mathbb{G}}, \alpha, \beta)$, the (randomized) key generation algorithm Gen returns a pair of keys

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$k_0, k_1 \in \{0, 1\}^*$. We assume that N and \mathbb{G} are determined by each key.

- $\text{Eval}_b(k_b, x) \rightarrow y_b$: On input key $k_b \in \{0, 1\}^*$ and input $x \in [N]$ the (deterministic) evaluation algorithm of server b , Eval_b returns $y_b \in \mathbb{G}$.

We require Π to satisfy the following requirements:

- **Correctness:** For every λ , $\hat{f} = \hat{f}_{\alpha,\beta} = (N, \hat{\mathbb{G}}, \alpha, \beta)$ such that $\beta \in \mathbb{G}$, and $x \in [N]$, for $b = 0, 1$,

$$\Pr \left[(k_0, k_1) \leftarrow \text{Gen}(1^\lambda, \hat{f}), \sum_{i=0}^1 \text{Eval}_i(k_i, x) = f_{\alpha,\beta}(x) \right] = 1$$

- **Security:** Consider the following semantic security challenge experiment for corrupted server $b \in \{0, 1\}$:

- (1) The adversary produces two point function descriptions $(\hat{f}^0 = (N, \hat{\mathbb{G}}, \alpha_0, \beta_0), \hat{f}^1 = (N, \hat{\mathbb{G}}, \alpha_1, \beta_1)) \leftarrow \mathcal{A}(1^\lambda)$, where $\alpha_b \in [N]$ and $\beta_b \in \mathbb{G}$.
- (2) The challenger samples $b \leftarrow \{0, 1\}$ and $(k_0, k_1) \leftarrow \text{Gen}(1^\lambda, \hat{f}^b)$.
- (3) The adversary outputs a guess $b' \leftarrow \mathcal{A}(k_b)$.

Denote by $\text{Adv}(1^\lambda, \mathcal{A}, i) = \Pr[b = b'] - 1/2$ the advantage of \mathcal{A} in guessing b in the above experiment. For every non-uniform polynomial time adversary \mathcal{A} there exists a negligible function v such that $\text{Adv}(1^\lambda, \mathcal{A}, i) \leq v(\lambda)$ for all $\lambda \in \mathbb{N}$.

DEFINITION 2 (DMPF). A (2-party) distributed multi-point function (DMPF) is a triple of algorithms $\Pi = (\text{Gen}, \text{Eval}_0, \text{Eval}_1)$ with the following syntax:

- $\text{Gen}(1^\lambda, \hat{f}_{A,B}) \rightarrow (k_0, k_1)$: On input security parameter $\lambda \in \mathbb{N}$ and point function description $\hat{f}_{A,B} = (N, \hat{\mathbb{G}}, t, A, B)$, the (randomized) key generation algorithm Gen returns a pair of keys $k_0, k_1 \in \{0, 1\}^*$.
- $\text{Eval}_b(1^\lambda, k_b, x) \rightarrow y_b$: On input key $k_b \in \{0, 1\}^*$ and input $x \in [N]$ the (deterministic) evaluation algorithm of server b , Eval_b returns $y_b \in \mathbb{G}$.

We require Π to satisfy the following requirements:

- **Correctness:** For every λ , $\hat{f} = \hat{f}_{A,B} = (N, \hat{\mathbb{G}}, t, A, B)$ such that $B \in \mathbb{G}^t$, and $x \in [N]$, for $b = 0, 1$,

$$\Pr \left[(k_0, k_1) \leftarrow \text{Gen}(1^\lambda, \hat{f}), \sum_{i=0}^1 \text{Eval}_i(k_i, x) = f_{A,B}(x) \right] = 1$$

- **Security:** Consider the following semantic security challenge experiment for corrupted server $b \in \{0, 1\}$:

- (1) The adversary produces two *t-point function* descriptions $(\hat{f}^0 = (N, \hat{\mathbb{G}}, t, A_0, B_0), \hat{f}^1 = (N, \hat{\mathbb{G}}, t, A_1, B_1)) \leftarrow \mathcal{A}(1^\lambda)$, where $\alpha_b \in [N]$ and $\beta_b \in \mathbb{G}$.
- (2) The challenger samples $b \leftarrow \{0, 1\}$ and $(k_0, k_1) \leftarrow \text{Gen}(1^\lambda, \hat{f}^b)$.
- (3) The adversary outputs a guess $b' \leftarrow \mathcal{A}(k_b)$.

Denote by $\text{Adv}(1^\lambda, \mathcal{A}, i) = \Pr[b = b'] - 1/2$ the advantage of \mathcal{A} in guessing b in the above experiment. For every non-uniform polynomial time adversary \mathcal{A} there exists a negligible function v such that $\text{Adv}(1^\lambda, \mathcal{A}, i) \leq v(\lambda)$ for all $\lambda \in \mathbb{N}$.

We will also be interested in applying the evaluation algorithm on *all* inputs. Given a DMPF $(\text{Gen}, \text{Eval}_0, \text{Eval}_1)$, we denote by FullEval_b an algorithm which computes Eval_b on every input x . Hence, FullEval_b receives only a key k_b as input.

One can construct a DMPF scheme for t -point functions by simply summing t DPFs. We denote this DMPF scheme as the naïve construction.

CONSTRUCTION 1 (NAÏVE CONSTRUCTION OF DMPF). *Given DPF for domain of size N and output group \mathbb{G} , we can construct a DMPF scheme for t -point functions with domain size N and output group \mathbb{G} as follows:*

- $\text{Gen}(1^\lambda, \hat{f}_{A,B}) \rightarrow (k_0, k_1)$: Suppose $A = \{\alpha_1, \dots, \alpha_t\}$ and $B = \{\beta_1, \dots, \beta_t\}$. For $1 \leq i \leq t$, invoke $\text{DPF.Gen}(1^\lambda, \hat{f}_{\alpha_i, \beta_i}) \rightarrow (k_0^i, k_1^i)$. Set $(k_0, k_1) = (\{k_0^i\}_{i \in [t]}, \{k_1^i\}_{i \in [t]})$.
- $\text{Eval}_b(k_b, x) \rightarrow y_b$: Compute $y_b = \sum_{i \in [t]} \text{DPF.Eval}_b(k_b^i, x)$.
- $\text{FullEval}_b(k_b) \rightarrow Y_b$: Compute $Y_b = \sum_{i \in [t]} \text{DPF.FullEval}_b(k_b^i, x)$.

When the DPF scheme is correct and secure, the naïve construction of DMPF is also correct and secure. We note that the keysize and running time of Gen , Eval and FullEval of the naïve construction of DMPF equals $t \times$ the keysize and $t \times$ the running time of Gen , Eval and FullEval of DPF, respectively. In the remainder of this paper, we'll provide DMPF schemes that has Eval and FullEval time almost independent to t .

2.3 Batch Code

We introduce probabilistic batch code, a batch code permitting small decoding errors, which can be used to construct DMPF (see construction 3).

DEFINITION 3 (PROBABILISTIC BATCH CODE (PBC)[1, 12, 19]). *An $(N, M, t, m, l, \epsilon)$ -PBC over alphabet Σ is given by a tuple of efficient algorithms $(\text{Encode}, \text{Decode})$ with respect to the public randomness r such that:*

- $\text{Encode}_r(x \in \Sigma^N) \rightarrow (C_1, C_2, \dots, C_m)$: Any string $x \in \Sigma^N$ is encoded into an m codewords (or 'buckets') $C_1, C_2, \dots, C_m \in \Sigma^*$ of total length M .
- $\text{Decode}_r(I, C_1, C_2, \dots, C_m) \rightarrow x[I]$: On input a set $I \subseteq [N]$ of $\leq t$ distinct elements in $[N]$ and m codewords, recover the subset $x[I]$ of x indexed by I , while querying at most l positions in each codeword.
- **Correctness**: for any string x and any set I of t distinct indices in $[N]$,

$$\Pr_r[(C_1, \dots, C_m) \leftarrow \text{Encode}_r(x), \\ x[I] \neq \text{Decode}_r(I, C_1, \dots, C_m)] \leq \epsilon$$

By default, we assume the batch code to be systematic, which means each symbol of x is encoded to some fixed positions in the buckets. This is formalized by two sub-processes of Encode_r and Decode_r respectively:

- $\text{Position}_r(k \in [N]) \rightarrow C_{i_1}[j_1], C_{i_2}[j_2], \dots$: On input an index $k \in [N]$, output the sequence of positions in buckets relevant to $x[k]$.
- $\text{Schedule}_r(k \in I) \rightarrow C_{i_1}[j_1], C_{i_2}[j_2], \dots$: For any $I \subseteq [N]$ such that $|I| \leq t$, and $k \in I$, $\text{Schedule}_r(k)$ outputs a set of positions in buckets relevant to k that Decode_r reads when

decoding to $x[I]$. For all $i \in [m]$, $|C_i \cap \bigcup_{k \in I} \text{Schedule}_r(k)| \leq l$.

We will focus on the case $b = 1$ and a special class of batch code called combinatorial batch code (CBC)[1, 12, 16], where each codeword C_i is a subset of x . In this case, Encode_r sends $x[k]$ to the positions defined by $\text{Position}_r(k)$, and Decode_r recovers $x[I]$ by rearranging the symbols it reads, whose positions are defined by Schedule . Note that when $b = 1$, Schedule algorithm implies finding a perfect matching from the size- t subset $I \subseteq [N]$ to the m buckets, in an (N, m) -bipartite graph where $k \in [N]$ is connected to $j \in [m]$ if and only if $x[k]$ is contained in C_j .

A natural way to construct PBC is to define the allocation of symbols in x to the buckets by a random (N, m) -bipartite graph where each left node has degree w for a fixed parameter w . To implement Encode and Decode (or more specifically Position and Schedule), we use the w -way cuckoo hashing algorithm[15] as a concrete and efficient instantiation of PBC as in [1, 8, 19].

w -way cuckoo hashing algorithm. Given t balls, $m = et$ buckets (e is an expansion parameter that is bigger than 1), and w independent random hash functions h_1, h_2, \dots, h_w , each mapping the balls to the buckets, a w -way cuckoo hashing algorithm we describe here aims to allocate t balls to m buckets such that each ball is allocated to one of the buckets output by the w hash functions, and each bucket contains at most one ball through the following process:

1. Choose an arbitrary unallocated ball b . If there is no unallocated ball, output the allocation.
2. Choose a random hash function h_i , and compute the bucket index $h_i(b)$. If this bucket is empty, then allocate b to this bucket and go to step 1. If this bucket is not empty and filled with ball b' , then evict b' , allocate b to this bucket, and repeat step 2 with unallocated ball b' .

If the algorithm terminates then it outputs a desired allocation of balls to buckets. To prevent it from running forever, one may set a fixed amount of running time. We call it a *failure* whenever the algorithm fails to output a desired allocation where each bucket contains at most one ball. We'll next summarize known asymptotic and empirical results about the failure probability of cuckoo hashing.

The failure probability of cuckoo hashing. Let's denote the failure probability of w -way cuckoo hashing to be $\epsilon = 2^{-\lambda_{\text{stat}}}$. In practice we usually consider the statistical security parameter λ_{stat} to be 40. The relations among the number of balls t , the number of hash functions w , the number of buckets m and the security parameters λ_{stat} are listed in Table 1.

There are different ways to generalize cuckoo hashing algorithm in order to achieve negligible failure probability. For instance, one may allow at most $l > 1$ balls to be allocated to each bucket, instead of allowing at most one. One may also add an overflow stash with size s as an additional cache-like bucket [13]. We mostly use cuckoo hashing with $l = 1$ and $s = 0$ to construct PBC and DMPF, but will also point out how general cuckoo hashing may help with these constructions. **Yaxin: argue again after construction.**

Now we display the instantiation of PBC using cuckoo hashing.

Yaxin: Dec 31: The following construction is mentioned in [19]. There are several points to note:

Table 1: he relations among the number of balls t , the number of hash functions w , the expansion parameter $e = m/t$ where m denotes the number of buckets and the security parameters λ_{stat} in cuckoo hashing with bucket size 1 and no stash.

	Type	t	λ_{stat}	w	$e = m/t$
[19, Theorem 1] [†]	Asymptotic			$O(\sqrt{\lambda_{\text{stat}} \log t})$	$O(1)$
[7]	Asymptotic			3	$O(\lambda_{\text{stat}} + \log t)$
[8, Appendix B]	Empirical	$t \geq 4$	$\lambda_{\text{stat}} = a_t \cdot e - b_t - \log t$ $a_t = 123.5 \cdot \text{CDF}_{\text{Normal}}(x = t, \mu = 6.3, \sigma = 2.3)$ $b_t = 120 \cdot \text{CDF}_{\text{Normal}}(x = t, \mu = 6.45, \sigma = 2.18)$	3^{\ddagger}	e
[7] simplifying the above	Empirical	$t \geq 30^*$	$\lambda_{\text{stat}} = 123.5e - 120 - \log t$	3	e
[6]**	Empirical	11041	$40 (\lambda_{\text{stat}} = 124.4e - 144.6)$	3	$m = 2^{14}, e \approx 1.5$
		5535	$40 (\lambda_{\text{stat}} = 125e - 145)$	3	$m = 2^{13}, e \approx 1.5$

[†] $O(\sqrt{\lambda_{\text{stat}} \log t})$ queries to the hash functions and supposes the hash functions from a $O(t\sqrt{\lambda_{\text{stat}} \log t})$ -wise independent hash function family.

[‡] Parameters are only slightly different for $w > 3$.

* Should extend to smaller t like $t = 16, 25$.

** It first fixes $m = 2^{13}, 2^{14}$ and then computes the correlation between λ_{stat} and e .

(1) [19] modified the hash functions' domain in the following way: it divides the m buckets evenly to w blocks, and for $1 \leq i \leq w$, $h_i : [N] \rightarrow [m/w]$ maps an element to a bucket in the i th block. The paper does this to claim better asymptotic provable success probability of cuckoo hashing, but using superconstant number ($w = \lambda_{\text{stat}}/\log \log N$) of hash functions, which does not align with empirical results that suggests constant number (say 3) of hash functions. I think to us this means that if making h_i to map to the i th block could be useful in implementation somehow (although I doubt this), then it also makes sense to do this modification.

(2) It should be mentioned that both the capacity of cuckoo hashing bins (which is 1 here) and the number of lookup in each C_i that PCBC is allowed (also 1 here) can be simultaneously generalized to any number l along with different parameters and overheads, but the paper still applied only $l = 1$ case to applications like batch PIR, and I haven't seen any efficient empirical parameters and results for $l > 1$ setting. However it is plausible to use general l along with $O(t/l)$ buckets, each expanded to a DMPF_l truth table. It may be mentioned as a future direction in the end.

CONSTRUCTION 2 (PBC FROM CUCKOO HASHING). Given w -way cuckoo hashing as a sub-procedure allocating t balls to m buckets with failure probability ϵ , an $(N, wN, t, m, 1, \epsilon)$ -PBC is as follows:

- $\text{Encode}_r(x \in \Sigma^N) \rightarrow (C_1, \dots, C_m)$: Use r to determine w independent random hash functions h_1, h_2, \dots, h_w that maps from $[N]$ to $[m]$. For all $k \in [N]$, replicate $x[k]$ in the positions indicated by $\text{Position}_r(k)$. Each output bucket C_j will be $\{x[k] : h_i(k) = j \text{ for some } i \in [w]\}$, in ascending order of k .
- $\text{Decode}_r(I, C_1, \dots, C_m) \rightarrow \{x[i]\}_{i \in I}$: Determine h_1, \dots, h_w by r as in Encode . For each $k \in I$, recover $x[k]$ from the position indicated by $\text{Schedule}_r(i)$.

with the following sub-processes:

- $\text{Position}_r(k \in [N]) \rightarrow C_{h_1(k)}[j_1], \dots, C_{h_w(k)}[j_w]$: For $1 \leq l \leq w$, j_l is the order of k in the set $\{k' : \exists t \in [w], h_t(k') = h_l(k)\}$ of all indices mapped to bucket $C_{h_l(k)}$.
- Schedule_r : For I of size at most t , run the w -way cuckoo hashing algorithm to allocate the indices in I to the m buckets, such that each bucket contains at most one index in I . For $k \in I$, $\text{Schedule}_r(k)$ outputs the position $C_i[j]$ such that k is allocated to bucket C_i , and j is the order of k in bucket C_i (i.e., $x[k]$ will be sent to $C_i[j]$ in the encoding process).

Note that the incorrectness of the above PBC scheme is equal to the failure probability of Schedule_r on set I , which equals ϵ .

Computing Position_r and Schedule_r requires computing the order of some index $k \in [N]$ in a bucket C_j it is mapped to, which may be inefficient when N is large. [7] address this issue by implementing w hash functions by a single (pseudo-)random permutation P mapping from $[w] \times [N]$ to $[m] \times [B]$, where $B = wN/m$. Invocation of $h_i(j)$ is done by computing $P(i, j)$, which outputs the bucket number in $[m]$ and the index in $[B]$. Note that in this case h_1, \dots, h_w are not independent random hash functions, but it is empirically verified that the cuckoo hashing algorithm still succeeds with sufficient probability.

2.4 DMPF Construction from CBC

Next we display the construction of DMPF from black-box usage of DPF basing on PBC with appropriate parameters, which has been discussed in previous literature[3, 7, 18].

CONSTRUCTION 3 (DMPF FROM DPF BASING ON PBC). Given DPF for any domain of size no larger than N and output group \mathbb{G} , and an $(N, M, t, m, 1, \epsilon)$ -PBC (which is systematic and combinatorial) with alphabet $\Sigma = \mathbb{G}$, we can construct a DMPF for t -point functions with domain size N and output group \mathbb{G} as follows:

- $\text{Gen}(1^\lambda, \hat{f}_{A,B}) \rightarrow (k_0, k_1)$: Suppose $A = \{\alpha_1, \dots, \alpha_t\}$ and $B = \{\beta_1, \dots, \beta_t\}$. Suppose the PBC encodes to buckets C_1, \dots, C_m . Compute $\text{PBC.Schedule}(\alpha_k) \rightarrow C_{i_k}[j_k]$, allocating elements in A to positions in the m buckets.

For all $1 \leq k \leq t$ For $1 \leq i \leq m$, let $f_i : [|C_i|] \rightarrow \mathbb{G}$ be the following:

- If there is no such $k \in [t]$ that $i_k = i$, then set f_i to be the all-zero function.
- If there is exactly one $k \in [t]$ that $i_k = i$, then set f_i to be the point function that outputs β_j on j_k and 0 elsewhere.

For $1 \leq i \leq m$, invoke $\text{DPF.Gen}(1^\lambda, f_i) \rightarrow (k_0^i, k_1^i)$. Set $(k_0, k_1) = (\{k_0^i\}_{i \in [m]}, \{k_1^i\}_{i \in [m]})$.

- $\text{Eval}_b(k_b, x) \rightarrow y_b$: Invoke $\text{PBC.Position}(x)$ to obtain the positions $C_{i_1}[j_1], \dots, C_{i_s}[j_s]$ to which x is sent. Compute $y_b = \sum_{l=1}^s \text{DPF.Eval}_b(k_b^i, j_l)$.
- $\text{FullEval}_b(k_b) \rightarrow Y_b$: Compute $Y_b^i = \text{DPF.FullEval}_b(k_b^i)$ for $1 \leq i \leq m$. For all $x \in [N]$, invoke $\text{PBC.Position}(x) \rightarrow C_{i_1}[j_1], \dots, C_{i_s}[j_s]$, and set $Y_b[x] \leftarrow \sum_{l=1}^s Y_b^i[j_l]$.

The scheme is correct with at least $1 - \epsilon$ probability and has distinguish advantage $O(\epsilon)$.

When instantiating PBC using w -way cuckoo hashing as in Construction 2, the *evaluation time* is the sum of the time for $\text{PBC.Position}(x)$ plus the time for w invocations of DPF.Eval . Similarly, the *full-domain evaluation time* is roughly the time for N invocations of PBC.Position plus w invocations of DPF.FullEval . Therefore, one may expect the evaluation time for the above construction of DMPF to be dependent to w instead of t . We will discuss about its efficiency in later sections.

Yaxin: Discuss about using PBC with bucket size $l > 1$.

2.5 Oblivious Key-Value Stores

We introduce the notion of Oblivious key-value stores (OKVS) which can be used to construct DMPF. OKVS was originally proposed as a primitive for private set intersection (PSI) protocols (see [10, 17]).

DEFINITION 4 (OBLIVIOUS KEY-VALUE STORES (OKVS)[10, 17]).

An Oblivious Key-Value Stores scheme is a pair of randomized algorithms $(\text{Encode}_r, \text{Decode}_r)$ with respect to a statistical security parameter λ_{stat} and a computational security parameter λ , a randomness space $\{0, 1\}^\kappa$, a key space \mathcal{K} , a value space \mathcal{V} , input length t and output length m . The algorithms are of the following syntax:

- $\text{Encode}_r(\{(k_1, v_1), (k_2, v_2), \dots, (k_t, v_t)\}) \rightarrow P$: On input t key-value pairs with distinct keys, the encode algorithm with randomness r in the randomness space outputs an encoding $P \in \mathcal{V}^m \cup \perp$.
- $\text{Decode}_r(P, k) \rightarrow v$: On input an encoding from \mathcal{V}^m and a key $k \in \mathcal{K}$, output a value v .

We require the scheme to satisfy

- For all $S \in (\mathcal{K} \times \mathcal{V})^t$, $\Pr_{r \leftarrow \{0, 1\}^\kappa}[\text{Encode}_r(S) = \perp] \leq 2^{-\lambda_{\text{stat}}}$.
- For all $S \in (\mathcal{K} \times \mathcal{V})^t$ and $r \in \{0, 1\}^\kappa$ such that $\text{Encode}_r(S) \rightarrow P \neq \perp$, it is the case that $\text{Decode}_r(P, k) \rightarrow v$ whenever $(k, v) \in S$.

- **Obliviousness:** Given any distinct key sets $\{k_1^0, k_2^0, \dots, k_t^0\}$ and $\{k_1^1, k_2^1, \dots, k_t^1\}$ that are different, if they are paired with random values then their encodings are computationally indistinguishable, i.e.,

$$\{r, \text{Encode}_r(\{(k_1^0, v_1), \dots, (k_t^0, v_t)\})\}_{v_1, \dots, v_t \leftarrow \mathcal{V}, r \leftarrow \{0, 1\}^\kappa} \\ \approx_c \{r, \text{Encode}_r(\{(k_1^1, v_1), \dots, (k_t^1, v_t)\})\}_{v_1, \dots, v_t \leftarrow \mathcal{V}, r \leftarrow \{0, 1\}^\kappa}$$

One can obtain a linear OKVS if in addition require:

- **Linearity:** There exists a function family $\{\text{row}_r : \mathcal{K} \rightarrow \mathcal{V}^m\}_{r \in \{0, 1\}^\kappa}$ such that $\text{Decode}_r(P, k) = \langle \text{row}_r(k), P \rangle$.

The Encode process for a linear OKVS is the process of sampling a random P from the set of solutions of the linear system $\{\langle \text{row}_r(k_i), P \rangle = v_i\}_{1 \leq i \leq t}$.

We evaluate an OKVS scheme by its rate $(\frac{\text{input length } t}{\text{output length } m})$, encoding time and decoding time.

The most naïve OKVS construction is encoding $S = \{(k_i, v_i)\}_{1 \leq i \leq t}$ to a random truth table $TT : \mathcal{K} \rightarrow \mathcal{V}$ such that $TT(k_i) = v_i$ for all $1 \leq i \leq t$. Note that to ensure obliviousness, for k not appearing in S , the encoding should set $TT(k)$ to a random value. However this naïve construction is very inefficient since it requires the encoding size to be $m = |\mathcal{K}|$, and hence its rate $\frac{t}{|\mathcal{K}|}$ can be tiny.

A well-known, optimal-rate OKVS construction is encoding t key-value pairs using a deg- t polynomial:

CONSTRUCTION 4 (POLYNOMIAL). Suppose $\mathcal{K} = \mathcal{V} = \mathbb{F}$ is a field. Set

- $\text{Encode}(\{(k_i, v_i)\}_{1 \leq i \leq t}) \rightarrow P$ where P is the coefficients of a $(t-1)$ -degree \mathbb{F} -polynomial g_P that $g_P(k_i) = v_i$ for $1 \leq i \leq t$.
- $\text{Decode}(P, k) \rightarrow g_P(k)$.

The polynomial OKVS possesses an optimal encoding size $m = n$, but the Encode process is a polynomial interpolation which is only known to be achieved in time $O(t \log^2 t)$. The time for a single decoding is $O(t)$ and that for batched decodings is (amortized) $O(\log^2 t)$.

In the sequel we stress two alternative (linear) OKVS constructions that has near optimal encoding size but much better running time.

CONSTRUCTION 5 (RR22[10, 17]). Suppose $\mathcal{V} = \mathbb{F}$ is a field. Set $\text{row}_r(k) := \text{row}_r^{\text{sparse}}(k) \parallel \text{row}_r^{\text{dense}}(k)$ where $\text{row}_r^{\text{sparse}}(k)$ outputs a uniformly random weight- w vector in $\{0, 1\}^{m_1}$, and $\text{row}_r^{\text{dense}}(k)$ outputs a short dense vector in \mathbb{F}^{m_2} .

- $\text{Encode}_r(\{(k_i, v_i)\}_{1 \leq i \leq t}) \rightarrow P$ where P is randomly chosen from the solutions of the system $\{\langle \text{row}_r(k_i), P \rangle = v_i\}_{1 \leq i \leq t}$, solved by the triangulation algorithm in [17]. If the system has no solution then output \perp .
- $\text{Decode}_r(P, k) \rightarrow \langle \text{row}_r(k), P \rangle$.

We denote $m_1 = et$, where e is an expansion parameter indicating the rough blowup to store t pairs. In practice the number of dense columns m_2 is usually set to a small constant.

This OKVS construction features an efficient encoding process, constant decoding time $((w + m_2)$ additions and m_2 multiplications in \mathbb{F}) while having a linear encoding size.

Encode may output \perp if the matrix formed by $\{\text{row}_r(k_i)\}_{1 \leq i \leq t}$ is not full-rank. Therefore we need to adjust the parameters $m_1 = et$

and m_2 to ensure negligible error probability (represented by the statistical security parameter λ_{stat}). The expansion parameter e and the number of dense columns $m_2 := \hat{g}$ (where \hat{g} is a parameter relating to the equation system solving process) are given by the analysis in [17], with the range of N from 2^6 to 2^{18} . Given w , t and λ_{stat} , the choices of the e and \hat{g} are fixed through the following steps:

- Set $e^* = \begin{cases} 1.223 & w = 3 \\ 1.293 & w = 4 \\ 0.1485w + 0.6845 & w \geq 5 \end{cases}$.
- Compute $\alpha := 0.55 \log_2 t + 0.093w^3 - 1.01w^2 + 2.92w - 0.13$.
- $e := e^* + 2^{-\alpha}(\lambda_{\text{stat}} + 9.2)$.
- $\hat{g} := \frac{\lambda_{\text{stat}}}{(w-2)\log_2(et)}$.

Yaxin: Fix t and λ_{stat} , we want to find the best choice of w . The advantageous choices of w in [17] are $w = 3$ and $w = 5$. From the first sight when w is smaller e can be smaller but \hat{g} will be larger. Since $w + \hat{g}$ stands for number of \mathbb{F} -ADD's and \hat{g} stands for number of \mathbb{F} -MULT's in decoding, previously I thought \hat{g} is the dominating factor of Decode running time. However table 1 in [17] suggests that $w = 3$ outruns nearly all of other choices of w while $w = 5$ is almost 3 times slower in decoding time. This may suggest there are some other heavy computations other than \mathbb{F} -MULT that need to be considered when evaluating running time.

The range of t previous literature [10, 17] have considered in their empirical results are also limited, which will be one of our problems. We want to cover small t , say $t < 100$, while previous literature aiming for constructing PSI protocols usually consider very large t .

One may let $\text{row}_r^{\text{dense}}$ output a short dense vector in $\{0, 1\}^{m_2}$ to avoid multiplication of large field elements in the encoding and decoding processes. To achieve same level of security one could simply set $m_2 = \hat{g} + \lambda_{\text{stat}}$, as proposed in [10, 17]. As indicated by the empirical results in [17], this binary scheme is usually not as efficient as the original design. Therefore we mostly refer to construction 5.

CONSTRUCTION 6 (RB-OKVS[2]). Suppose $\mathcal{V} = \mathbb{G}$ is a group. Let $\text{row}_r(k)$ output a $\{0, 1\}^m$ vector consisting of a width- w random band. Formally speaking, $\text{row}_r(k)$ first determine a starting point $1 \leq i \leq m - w + 1$ for the band, and then determine random w -bit string to fill in the positions $[i, i + w - 1]$ of $\text{row}_r(k)$ and leave the rest as 0 entries.

- $\text{Encode}_r(\{(k_i, v_i)\}_{1 \leq i \leq t}) \rightarrow P$ where P is randomly chosen from the random band matrix system $\{\langle \text{row}_r(k_i), P \rangle = v_i\}_{1 \leq i \leq t}$. If the system has no solution then output \perp .
- $\text{Decode}_r(P, k) \rightarrow \langle \text{row}_r(k), P \rangle$.

Denote $m = et$ where $e > 1$ is an expansion parameter indicating the blowup to store t pairs.

The encoding time is equivalent to solving a random band matrix system, which can be efficiently done in $O(Nw + n \log n)$ time [2]. The decoding time is w additions in \mathbb{F} and the rate can be very close to 1.

Again, to guarantee the success of Encode, the random band matrix must be full-rank with overwhelming probability. According to [2], fixing $e > 1$ and taking $w = O(\lambda_{\text{stat}}/(e - 1) + \log N)$ ensures

the correctness and obliviousness with probability $2^{-\lambda_{\text{stat}}}$ and 2^{-w} , respectively. Practically, $e = 1.03, 1.05, 1.07, 1.1$ are taken while w being several hundred to reach the security $\lambda_{\text{stat}} = 40$, with the choice of N varying from 2^{10} to 2^{20} .

According to the comparison in [2] of the RR22-OKVS (construction 5) and the RB-OKVS (construction 6) with the choices of $N = 2^{16}, 2^{20}, 2^{24}$, the RB-OKVS has a better rate and features a tradeoff between rate and encoding/decoding time (one can choose to have better rate with longer encoding/decoding time). The RB-OKVS has better encoding time while the RR22-OKVS has better decoding time.

Yaxin: Maybe (and how to) put a (quantitative) summarizing table of OKVS efficiency here?

In our later sections, we will give the decoding efficiency of the OKVS the most priority. To this end, we refer to the RR22-OKVS (construction 5) when instantiating OKVS. One may switch to other OKVS constructions depending on different needs in practice.

3 NEW DMPF CONSTRUCTIONS

In this section, we display two new constructions of DMPF in section 3.2 and section 3.3 respectively, that follow the same paradigm introduced in section 3.1.

3.1 DMPF paradigm

We begin by introducing the DMPF paradigm in fig. 1, which is based on the idea of the DPF construction in [5]. Each key k_b ($b = 0, 1$) generated by $\text{Gen}(1^\lambda, \hat{f}_{A,B})$ can span a depth- n (n is the input length of $\hat{f}_{A,B}$) complete binary tree T_b . Each node in either tree T_b is approached by a path starting from the root, which corresponds to a string in $\{0, 1\}^{\leq n}$ where 0 stands for going left and 1 stands for going right. We call a path that corresponds to any nonzero input $a \in A$ an accepting path.

We call the trees T_0, T_1 the evaluation trees. Each node in the evaluation tree T_b is associated with a $(\lambda + l)$ -bit pseudorandom string $\text{seed}||\text{sign}$ (the λ -bit seed and l -bit sign are defined in line 6). The two evaluation trees satisfies the following important properties:

- (1) T_0 and T_1 have identical strings on every node except for the nodes lying on accepting paths.
- (2) For a node lying on an accepting path, its seed strings in T_0 and T_1 are pseudorandom and independent, while its sign strings are pseudorandom and follow some correlation (the correlation is designed by specific instantiations).

Party b can evaluate the input $x = x_1 \cdots x_n$ by calling $\text{Eval}_b(1^\lambda, k_b, x)$, which first parse the key k_b to the $\text{seed}||\text{sign}$ string at the root together with n hints $\{CW^{(i)}\}_{i \in [n]}$, for the depth- i layer ($1 \leq i \leq n$) respectively. $\text{Eval}_b(1^\lambda, k_b, x)$ traverses T_b along the path indicated by x , starting from the root, and at a depth- $(i - 1)$ node with string $\text{seed}||\text{sign}$ generates its children's strings by first computing the $(2\lambda + 2l)$ -bit pseudorandom string $G(\text{seed})$ where $G : \{0, 1\}^\lambda \rightarrow \{0, 1\}^{2\lambda + 2l}$ is a pseudorandom generator, then adding to $G(\text{seed})$ a correction computed by $\text{Correct}(x_1 \dots x_{i-1}, \text{sign}, CW^{(i)})$ (see line 5), and then assign the left $(\lambda + l)$ -bit string to its left child and the rest to its right child. In particular, the additive correction for the seed strings of two children nodes are the same (C_{seed} in line 5), but those for the sign strings of two children nodes are different

Figure 1: The paradigm of our DMPF schemes. We leave the sign string length l , methods Initialize, GenCW, GenConvCW, Correct, ConvCorrect to be determined by specific constructions.

```

1: Public parameters:
2: The  $t$ -point function family  $\{f_{A,B}\}$  with  $t$  an upperbound of the number of nonzero points, input domain  $[N] = \{0, 1\}^n$  and the output group  $\mathbb{G}$ .
3: Suppose there is a public PRG  $G : \{0, 1\}^\lambda \rightarrow \{0, 1\}^{2\lambda+2l}$ . Parse  $G(x) = G_0(x) \| G_1(x)$  to the left half and right half of the output. Moreover, for simplicity, for  $b = 0, 1$  define  $G_b^{\text{seed}} : \{0, 1\}^\lambda \rightarrow \{0, 1\}^\lambda$  to be  $G_b^{\text{seed}}(x) = G_b(x)[1 \dots \lambda]$ , the first  $\lambda$  bits. Similarly, define  $G_b^{\text{sign}} : \{0, 1\}^\lambda \rightarrow \{0, 1\}^l$  to be  $G_b^{\text{sign}}(x) = G_b(x)[(\lambda + 1) \dots (\lambda + l)]$ , the last  $l$  bits of  $G_b$ . Denote  $G^{\text{sign}} : \{0, 1\}^\lambda \rightarrow \{0, 1\}^{2l}$  to be  $G^{\text{sign}}(x) = G_0^{\text{sign}}(x) \| G_1^{\text{sign}}(x)$ .
4: Suppose there is a public PRG  $G_{\text{conv}} : \{0, 1\}^\lambda \rightarrow \mathbb{G}$ .

1: procedure GEN( $1^\lambda, \hat{f}_{A,B}$ )
2:   Denote  $A = (\alpha_1, \dots, \alpha_t)$  in lexicographically order,  $B = (\beta_1, \dots, \beta_t)$ . If  $|A| < t$ , extend  $A$  to size- $t$  with arbitrary  $\{0, 1\}^n$  strings and  $B$  with 0's.
3:   For  $0 \leq i \leq n-1$ , let  $A^{(i)}$  denote the sorted and deduplicated list of  $i$ -bit prefixes of strings in  $A$ . Specifically,  $A^{(0)} = [\epsilon]$ .
4:   For  $0 \leq i \leq n-1$  and  $b = 0, 1$ , initialize empty lists  $\text{seed}_b^{(i)}$ ,  $\text{sign}_b^{(i)}$  and  $V^{(i)}$ .
5:   Initialize( $\{\text{seed}_b^{(0)}, \text{sign}_b^{(0)}\}_{b=0,1}$ ).
6:   for  $i = 1$  to  $n$  do
7:     for  $k = 1$  to  $|A^{(i-1)}|$  do
8:       For  $c = 0, 1$ , compute  $\Delta \text{seed}^c = G_{\text{seed}}^c(\text{seed}_0^{(i-1)}[k]) \oplus G_{\text{seed}}^c(\text{seed}_1^{(i-1)}[k])$  and  $\Delta \text{sign}^c = G_{\text{sign}}^c(\text{seed}_0^{(i-1)}[k]) \oplus G_{\text{sign}}^c(\text{seed}_1^{(i-1)}[k])$ .
9:       if  $A^{(i-1)}[k] \| 0 \in A^{(i)}$  and  $A^{(i-1)}[k] \| 1 \in A^{(i)}$  then
10:         Randomly sample  $r \leftarrow \{0, 1\}^\lambda$  and append  $r \| \Delta \text{sign}^0 \| \Delta \text{sign}^1$  to  $V^{(i-1)}$ .
11:       else
12:         Suppose  $A^{(i-1)}[k] \| z \in A^{(i)}$ . Append  $\Delta \text{seed}^{1-z} \| \Delta \text{sign}^0 \| \Delta \text{sign}^1$  to  $V^{(i-1)}$ .
13:       end if
14:     end for
15:      $CW^{(i)} \leftarrow \text{GenCW}(i, A, V^{(i-1)})$ .
16:     for  $k = 1$  to  $|A^{(i-1)}|$  and  $z = 0, 1$  do
17:       Compute  $C_{\text{seed},b} \| C_{\text{sign}^0,b} \| C_{\text{sign}^1,b} \leftarrow \text{Correct}(A^{(i-1)}[k], \text{sign}_b^{(i-1)}[k], CW^{(i)})$  for  $b = 0, 1$ , where  $|C_{\text{seed},b}| = \lambda$  and  $|C_{\text{sign}^0,b}| = |C_{\text{sign}^1,b}| = l$ .
18:       if  $A^{(i-1)}[k] \| z \in A^{(i)}$  then
19:         Append the first  $\lambda$  bits of  $G_z(\text{seed}_b^{(i-1)}[k]) \oplus (C_{\text{seed},b} \| C_{\text{sign}^z,b})$  to  $\text{seed}_b^{(i)}$  and the rest  $l$  bits to  $\text{sign}_b^{(i)}$ .
20:       end if
21:     end for
22:   end for
23:    $CW^{(n+1)} \leftarrow \text{GenConvCW}(A, B, \{\text{seed}_b^{(n)}, \text{sign}_b^{(n)}\}_{b=0,1})$ .
24:   Set  $k_b \leftarrow (\text{seed}_b^{(0)}, \text{sign}_b^{(0)}, CW^{(1)}, CW^{(2)}, \dots, CW^{(n+1)})$ .
25:   return  $(k_0, k_1)$ .
26: end procedure

1: procedure EVAL $_b(1^\lambda, k_b, x)$ 
2:   Parse  $k_b = ([\text{seed}], [\text{sign}], CW^{(1)}, CW^{(2)}, \dots, CW^{(n+1)})$ .
3:   Denote  $x = x_1 x_2 \dots x_n$ .
4:   for  $i = 1$  to  $n$  do
5:      $C_{\text{seed}} \| C_{\text{sign}^0} \| C_{\text{sign}^1} \leftarrow \text{Correct}(x_1 \dots x_{i-1}, \text{sign}, CW^{(i)})$ , where  $|C_{\text{seed}}| = \lambda$  and  $|C_{\text{sign}^0}| = |C_{\text{sign}^1}| = l$ .
6:      $\text{seed} \| \text{sign} \leftarrow G_{x_i}(\text{seed}) \oplus (C_{\text{seed}} \| C_{\text{sign}^{x_i}})$ , where  $|\text{seed}| = \lambda$  and  $|\text{sign}| = l$ .
7:   end for
8:   return  $(-1)^b \cdot (G_{\text{conv}}(\text{seed}) + \text{ConvCorrect}(x, \text{sign}, CW^{(n+1)}))$ .
9: end procedure

10: procedure FULLEVAL $_b(1^\lambda, k_b)$ 
11:   Parse  $k_b = (\text{seed}^{(0)}, \text{sign}^{(0)}, CW^{(1)}, CW^{(2)}, \dots, CW^{(n+1)})$ .
12:   For  $1 \leq i \leq n$ ,  $\text{Path}^{(i)} \leftarrow$  the lexicographical ordered list of  $\{0, 1\}^i$ .  $\text{Path}^{(0)} \leftarrow [\epsilon]$ .
13:   Yaxin: The evaluation is BFS-style, which costs a lot of memory to store lists  $\text{seed}^{(i)}, \text{sign}^{(i)}$ . Need a DFS version for large  $N$  to reduce memory use? Write in the clear or explain by words?
14:   for  $i = 1$  to  $n$  do
15:     for  $k = 1$  to  $2^{i-1}$  do
16:        $C_{\text{seed}} \| C_{\text{sign}^0} \| C_{\text{sign}^1} \leftarrow \text{Correct}(\text{Path}^{(i-1)}[k], \text{sign}^{(i-1)}[k], CW^{(i)})$ , where  $|C_{\text{seed}}| = \lambda$  and  $|C_{\text{sign}^0}| = |C_{\text{sign}^1}| = l$ .

```

(C_{sign^0} for the left child and C_{sign^1} for the right child) in order to force the desired correlation of sign strings.

It is $\text{Gen}(1^\lambda, \hat{f}_{A,B})$'s job to generate appropriate strings for roots of T_0 and T_1 and hints $\{CW^{(i)}\}$ for all layers that maintains the properties 1 and 2. At the depth- i layer, $\text{Gen}(1^\lambda, \hat{f}_{A,B})$ utilizes $\text{GenCW}(i, A, V^{(i)})$ to generate the hint $CW^{(i)}$ for both parties (line 15), where $V^{(i-1)}$ records the crucial difference between the i th layer of T_0 and T_1 if their seed||sign string is just the output of the PRG on the seed strings of the $(i-1)$ th layer. To force the properties 1 and 2 of the evaluation tree, the hint $CW^{(i)}$ should satisfy the following principles:

- (1) If a depth- $(i-1)$ parent node is on an accepting path and it has a child node exiting this accepting path, then the corrections for this child node (computed by line 5) should force the strings at this node in T_0 and T_1 to be the same.
- (2) For every depth- $(i-1)$ parent node on an accepting path, the sign corrections for its child that is still on an accepting path should force the sign strings at this node in T_0 and T_1 to follow the desired correlation.

The detailed realization of these principles will be discussed in concrete instantiations. We note that forcing the same strings at each node that exits an accepting suffices for achieving property 1: According to the computation of Eval_b , if a parent node is associated with the same strings in T_0 and T_1 , then each of its children is associated with the same strings in T_0 and T_1 , and so is each of the nodes in the subtree rooted at the parent node.

The paradigm add a convert layer after the last layer of the evaluation tree to convert the strings at the leaf nodes to an element in the output group \mathbb{G} of $\hat{f}_{A,B}$. A hint $CW^{(n+1)}$ is associated with the convert layer. The output at a leaf node x with string seed||sign is generated by first computing a pseudorandom \mathbb{G} -element $G_{\text{conv}}(\text{seed})$, then adding to $G_{\text{conv}}(\text{seed})$ a correction computed by $\text{ConvCorrect}(x, \text{sign}, CW^{(n+1)})$, and then give a sign $(-1)^b$ depending on the party (see line 8). If the leaf node is not on any accepting path, then $G_{\text{conv}}(\text{seed})$ and the correction should be the same in T_0 and T_1 , which means the outputs in T_0 and T_1 at this node should add up to $0_{\mathbb{G}}$. On the other hand, if the leaf node is on any accepting path, then the hint $CW^{(n+1)}$ given by $\text{Gen}(1^\lambda, \hat{f}_{A,B})$ should yield corrections that force the outputs in T_0 and T_1 to add up to the corresponding element in B . Such $CW^{(n+1)}$ is correctly generated by GenConvCW (see line 23).

To sum up, we provide the key generation Gen , single-input evaluation Eval and full-domain evaluation FullEval in the paradigm in fig. 1. The computation involves the following methods which will be realized in the next sections:

- Initialize defines the strings at the roots of T_0, T_1 .
- GenCW computes hints $\{CW^{(1)}, \dots, CW^{(n)}\}$ associated with n layers that help generate corrections for the strings at the nodes. Two parties use the same set of correction words.
- GenConvCW computes the hint $CW^{(n+1)}$ associated with the convert layer that help generate corrections for the final output. Two parties use the same set of correction words.
- Correct given a depth- $(i-1)$ parent node, its sign string and the hint $CW^{(i)}$, outputs an (additive) correction for its children's strings.

- ConvCorrect given a leaf node, its sign string and the hint $CW^{(n+1)}$, outputs a correction for the final output in the output group \mathbb{G} .

Yaxin: Mention early termination?

3.2 Big-State DMPF

We display our first instantiation of DMPF in fig. 2, basing on the paradigm of DMPF in fig. 1. In the big-state DMPF we set the length l of the sign string to be t , the number of accepting inputs indicated in $\hat{f}_{A,B}$. The evaluation trees T_0 and T_1 satisfies properties 1 and 2, such that the sign string at a node stores a share of the unit vector indicating which accepting path this node is on: for a node lying on the k th accepting path in the depth- i layer, its sign strings in T_0 and T_1 should add up (by bit-wise XOR) to $e_k = 0^{k-1}10^{t-k}$. Then, the (additive) corrections for computing strings at its children generated by line 31 of fig. 2 equals $CW^{(i)}[k]$, the k th entry of the hint $CW^{(i)}$ associated with this layer. According to line 17 in the construction of GenCW , if one of the children exits the accepting path, the seed correction C_{seed} will zero out the difference of this child's seed strings in T_0 and T_1 . Otherwise C_{seed} will be a random correction. The sign corrections C_{sign^0} and C_{sign^1} will force the sign strings at each child to be a share of 0^t if this child exits the accepting path, or to be a unit vector indicating the index of the accepting path in the next layer this child lies on.

For the convert layer, GenConvCW set $CW^{(n+1)}[k]$ to be the correction that makes the k th accepting leaf's outputs in T_0 and T_1 to add up to $B[k]$.

We informally argue that the correctness of the big-state DMPF holds since properties 1 and 2 of T_0 and T_1 are ensured, which in turn gives correct shares of outputs in the end of evaluation. The security holds since (1) the seed||sign string at the root of T_b is independent of A and B , and (2) each hint $CW^{(i)}$ is masked by the pseudorandom value determined by the other party's key, which is indistinguishable with a truly random hint.

In the end of this section we briefly discuss about the efficiency of the big-state DMPF, which will be discussed in more details in section 4. Set the naïve solution of DMPF that is a sum of t DPFs as a primary benchmark. The ratio of keysize of the big-state DMPF over the naïve solution is roughly $(\lambda+2t)/(\lambda+2) > 1$, which is close to 1 if $t \ll \lambda$. Gen , Eval and FullEval all traverse one evaluation tree while the naïve solution traverse t evaluation trees. However, the PRG used in the big-state DMPF have output length $2\lambda + 2t$, which means the running time still grows with t . In short, the big-state DMPF is faster than the naïve solution with the sacrifice of larger keysize. When $t \ll \lambda$, compared to the naïve solution, the big-state DMPF has similar keysize and almost $\times t$ speedup in running time.

3.3 OKVS-based DMPF

Next we display our second instantiation of DMPF in fig. 3, basing on the paradigm of DMPF in fig. 1. We call this instantiation the OKVS-based DMPF, since we utilize primitive OKVS (see section 2.5 for introduction).

In the OKVS-based DMPF, we set the length l of the sign string to be 1. The sign strings at the same node in T_0 and T_1 will obey the following correlation: they are shares of 1 if this node is on an

Figure 2: The parameter l and methods' setting that turns the paradigm of DMPF in fig. 1 into the big-state DMPF.

```

1: Set  $l \leftarrow t$ , the upperbound of  $|A|$ .
2: procedure INITIALIZE( $\{\text{seed}_b^{(0)}, \text{sign}_b^{(0)}\}_{b=0,1}$ )
3:   For  $b = 0, 1$ , let  $\text{seed}_b^{(0)} = [r_b]$  where  $r_b \xleftarrow{\$} \{0, 1\}^\lambda$ .
4:   For  $b = 0, 1$ , set  $\text{sign}_b^{(0)} = [b \| 0^{t-1}]$ .
5: end procedure

6: procedure GENCW( $i, A, V^{(i-1)}$ )
7:   Let  $\{A^{(i)}\}_{0 \leq i \leq n}$  be defined as in fig. 1.
8:   Sample a list  $CW$  of  $t$  random strings from  $\{0, 1\}^{\lambda+2t}$ .
9:   for  $k = 1$  to  $|A^{(i-1)}|$  do
10:    Parse  $V^{(i-1)}[k] = \Delta \text{seed} \| \Delta \text{sign}^0 \| \Delta \text{sign}^1$ .
11:    if  $A^{(i-1)}[k] \| z \in A^{(i)}$  holds for both  $z = 0, 1$  then
12:       $d \leftarrow$  the index of  $A^{(i-1)}[k] \| 0$  in  $A^{(i)}$ .
13:       $CW[k] \leftarrow \Delta \text{seed} \| (\Delta \text{sign}^0 \oplus e_d) \| (\Delta \text{sign}^1 \oplus e_{d+1})$ 
      where  $e_d = 0^{d-1} 1 0^{t-d}$ .
14:    else
15:      Suppose  $A^{(i-1)}[k] \| z \in A^{(i)}$ . Let  $d$  be the index of
       $A^{(i-1)}[k] \| z$  in  $A^{(i)}$ .
16:       $\Delta \text{sign}^z \leftarrow \Delta \text{sign}^z \oplus e_d$ .
17:       $CW[k] \leftarrow \Delta \text{seed} \| \Delta \text{sign}^0 \| \Delta \text{sign}^1$ .
18:    end if
19:  end for
20:  return  $CW$ .
21: end procedure

22: procedure GENCONVCW( $A, B, \{\text{seed}_b^{(n)}, \text{sign}_b^{(n)}\}$ )
23:  Sample a list  $CW$  of  $t$  random  $\mathbb{G}$ -elements.
24:  for  $k = 1$  to  $|A|$  do
25:     $\Delta g \leftarrow G_{\text{conv}}(\text{seed}_0^{(n)}[k]) - G_{\text{conv}}(\text{seed}_1^{(n)}[k])$ .
26:     $CW[k] \leftarrow (-1)^{\text{sign}_0^{(n)}[k]} (\Delta g - B[k])$ .
27:  end for
28:  return  $CW$ .
29: end procedure

30: procedure CORRECT( $\tilde{x}, \text{sign}, CW$ )
31:  return  $C_{\text{seed}} \| C_{\text{sign}^0} \| C_{\text{sign}^1} \leftarrow \sum_{i=1}^t \text{sign}[i] \cdot CW[i]$ , where
   $C_{\text{sign}^0}$  and  $C_{\text{sign}^1}$  are  $t$ -bit.
32: end procedure

33: procedure CONVCORRECT( $x, \text{sign}, CW$ )
34:  return  $\sum_{i=1}^t \text{sign}[i] \cdot CW[i]$ .
35: end procedure

```

accepting path and 0 if this node is not on any accepting path. In order to ensure properties 1 and 2, for a parent node on an accepting path, the additive correction C_{seed} , C_{sign^0} and C_{sign^1} for the strings at its children are determined such that, if one of its children exits the accepting path, then the seed correction C_{seed} should zero out this child's seed strings in T_0 and T_1 . Otherwise C_{seed} will be a random correction. The sign corrections C_{sign^0} and C_{sign^1} will force

the sign strings at each child to be a share of 0 if this child exits the accepting path, or to be a share of 1 if it remains on an accepting path.

To generate hints $\{CW^{(i)}\}$ to yield the corrections, we utilize the OKVS primitive that can encode key-value pairs to a data structure, which can be later decoded with any stored key to its corresponding value. On the depth- i layer, we define the key space to be the set of all depth- i nodes and the value space to be $\{0, 1\}^{\lambda+2}$. Each node on this layer that is also on an accepting path needs a $(\lambda + 2)$ -bit correction, recorded by the value list $V^{(i-1)}$. We encode these (node, correction) pairs (there are up to t such pairs) using an OKVS scheme and set the hint $CW^{(i)}$ to be the encoding (see line 22). When evaluating, we decode $CW^{(i)}$ using the same OKVS scheme to obtain the correction with regard to any node (see line 33).

For the convert layer, GenConvCW set $CW^{(n+1)}$ to be the encoding of (leaf node, output correction) pairs where each output correction associated with a leaf node makes the leaf's outputs in T_0 and T_1 add up to the corresponding element in B .

Note that in fig. 3 the OKVS scheme OKVS_i we use for the depth- i layer has key space of size 2^i and value space $\{0, 1\}^\lambda$. For simplicity we may extend the key space of OKVS_i to size 2^n , and realize $\{\text{OKVS}_i\}_{i \in [n]}$ using the same OKVS scheme. For the upmost few layers where $2^i < t$, OKVS_i may be realized by the most naïve way of encoding to a random truth table (see Section 2.5), which achieves the optimal rate in this occasion.

Yaxin: One point: the row matrix of the current layer contains the row matrix of the previous layers, which might be useful for speedup.

We informally argue that armed with an OKVS scheme that fails with negligible probability, the correctness of the OKVS-based DMPF holds with overwhelming probability since properties 1 and 2 are ensured, which in turn gives correct shares of outputs in the end of evaluation. The security holds as long as the OKVS scheme is oblivious. Since the corrections are pseudorandom strings that are masked by pseudorandom values determined by the other party's key, the OKVS scheme won't leak any information about the accepting paths due to its obliviousness.

The efficiency of OKVS-based DMPF highly relies on the efficiency of the OKVS scheme it uses. Setting the naïve solution as a benchmark, the ratio of keysize of the naïve solution over the OKVS-based DMPF is roughly the rate of the OKVS scheme. Similar to the advantage of the big-state DMPF, the OKVS-based DMPF also only traverse one evaluation tree (as opposed to traversing t evaluation trees in the naïve solution). However Gen consumes an OKVS encoding time per layer, and Eval and FullEval consume an OKVS decoding/batch decodings per layer. Therefore with an OKVS scheme that has high rate, fast encoding and decoding will result in an OKVS-based DMPF scheme that has small keysize, fast Gen and Eval/FullEval, respectively.

3.4 Comparison

In this section we summarize the efficiency of the DMPF instantiations we've mentioned and constructed so far. We display the key-size and running time of Gen, Eval and FullEval of different DMPF schemes, computed in terms of costs of abstract tools such as PRG,

Figure 3: The parameter l and methods' setting that turns the paradigm of DMPF in fig. 1 into the OKVS-based DMPF.

```

1: Set  $l \leftarrow 1$ .
2: For  $1 \leq i \leq n$ , let  $\text{OKVS}_i$  be an OKVS scheme (definition 4)
   with key space  $\mathcal{K} = \{0, 1\}^{i-1}$ , value space  $\mathcal{V} = \{0, 1\}^{\lambda+2}$  and
   input length  $t$ .
3: let  $\text{OKVS}_{\text{conv}}$  be an OKVS scheme with key space  $\mathcal{K} = \{0, 1\}^n$ ,
   value space  $\mathcal{V} = \mathbb{G}$  and input length  $\min\{2^{i-1}, t\}$ .

4: procedure INITIALIZE( $\{\text{seed}_b^{(0)}, \text{sign}_b^{(0)}\}_{b=0,1}$ )
5:   For  $b = 0, 1$ , let  $\text{seed}_b^{(0)} = [r_b \xleftarrow{\$} \{0, 1\}^\lambda]$  and  $\text{sign}_b^{(0)} = [b]$ .
6: end procedure

7: procedure GENCW( $i, A, V^{(i-1)}$ )
8:   Let  $\{A^{(i)}\}_{0 \leq i \leq n}$  be defined as in fig. 1.
9:   Sample a list  $V$  of  $t$  random strings from  $\{0, 1\}^{\lambda+2}$ .
10:  for  $k = 1$  to  $|A^{(i-1)}|$  do
11:    Parse  $V^{(i-1)}[k] = \Delta\text{seed} \parallel \Delta\text{sign}^0 \parallel \Delta\text{sign}^1$ .
12:    for  $z = 0, 1$  such that  $A^{(i-1)}[k] \parallel z \in A^{(i)}$  do
13:       $\text{sign}^z \leftarrow \text{sign}^z \oplus 1$ .
14:    end for
15:    Update  $V^{(i-1)}[k] \leftarrow \Delta\text{seed} \parallel \Delta\text{sign}^0 \parallel \Delta\text{sign}^1$ .
16:  end for
17:  Copy the list  $A^{(i-1)}$  to the list  $K$ .
18:  for  $j = |K| + 1$  to  $\min\{2^{i-1}, t\}$  do
19:    Set  $K[j]$  to be an arbitrary string in  $\{0, 1\}^{i-1}$  that is
    different from  $K[1 \dots j-1]$ .
20:    Set  $V[j]$  to be a random string in  $\{0, 1\}^{\lambda+2}$ .
21:  end for
22:  return  $\text{OKVS}_i.\text{Encode}(\{(K[j], V[j])\}_{1 \leq j \leq |K|})$ .
23: end procedure

24: procedure GENCONVCW( $A, B, \{\text{seed}_b^{(n)}, \text{sign}_b^{(n)}\}$ )
25:   Sample a list  $V$  of  $t$  random  $\mathbb{G}$ -elements.
26:   for  $k = 1$  to  $|A|$  do
27:      $\Delta g \leftarrow G_{\text{conv}}(\text{seed}_0^{(n)}[k]) - G_{\text{conv}}(\text{seed}_1^{(n)}[k])$ .
28:      $V[k] \leftarrow (-1)^{\text{sign}_0^{(n)}[k][k]}(\Delta g - B[k])$ .
29:   end for
30:   return  $\text{OKVS}_{\text{conv}}(\{(A[k], V[k])\}_{1 \leq k \leq t})$ .
31: end procedure

32: procedure CORRECT( $\tilde{x}, \text{sign}, CW$ )
33:   return  $C_{\text{seed}} \parallel C_{\text{sign}^0} \parallel C_{\text{sign}^1} \leftarrow \text{sign} \cdot \text{OKVS}_i.\text{Decode}(CW, \tilde{x})$ ,
   where  $C_{\text{sign}^0}$  and  $C_{\text{sign}^1}$  are bits.
34: end procedure

35: procedure CONVCORRECT( $x, \text{sign}, CW$ )
36:   return  $\text{sign} \cdot \text{OKVS}_{\text{conv}}.\text{Decode}(CW, x)$ .
37: end procedure

```

batch code and OKVS. The concrete efficiency will be discussed later in application scenarios in section 4.

Take PCG as a potential application. We care about FullEval time which is related to PCG seed expanding time. In this aspect, the CBC-based DMPF consumes w times the number of PRGs than big-state DMPF and OKVS-based DMPF, while big-state DMPF's FullEval time scales with t^2 (since the large-bit-XOR time scales with t^2) and OKVS-based DMPF in addition consumes large field operations (in OKVS decoding, and maybe more than this). Therefore we expect different DMPF schemes to be the top choice in different choices of t and depending on the computing time of PRG and large field multiplication, and it is likely that the big-state construction performs the best when t is small, while the CBC-based and OKVS-based constructions performs well when t is large.

3.5 Distributed Key Generation

3.6 Distributed Multi-Interval

Table 2: Keysize and running time comparison for different DMPF constructions for domain size N , t accepting points, output group \mathbb{G} and computational security parameter λ . We leave this table with the abstraction of (probabilistic) batch code in the second column and the abstraction of OKVS in the last column, and plug in concrete instantiations later. m in the second column stands for the number of buckets in batch code, and w stands for the number of buckets that each input coordinate is mapped to (we only consider regular degree because this is the case in most instantiations). **Yaxin: Denote T_G as the time for computing $G : \{0, 1\}^{\lambda+1} \rightarrow \{0, 1\}^{2\lambda+2}$, and $T_{G_{\text{conv}}}$ as the time for computing $G_{\text{conv}} : \{0, 1\}^\lambda \rightarrow \mathbb{G}$. In the last column, denote OKVS as the OKVS scheme used for the first n layers, and $\text{OKVS}_{\text{conv}}$ as the OKVS scheme used for the convert layer.**

	Sum of t DPFs	CBC-based DMPF[1, 3, 7, 18]	Big-state DMPF	OKVS-based DMPF
Keysize	$t(\lambda + 2) \log N + t \log \mathbb{G}$	$m(\lambda + 2) \log(wN/m) + m \log \mathbb{G}$	$t(\lambda + 2t) \log N + t \log \mathbb{G}$	$\log N \times \text{OKVS.CodeSize} + \text{OKVS}_{\text{conv}}.\text{CodeSize}$
$Gen()$	$2t \log N \times T_G + 2t \times T_{G_{\text{conv}}}$	$2m \log(wN/m) \times T_G + 2m \times T_{G_{\text{conv}}}$ CBC.Encode + CBC.Decode	$2t \log N \times T_{G^*}^1$ $+ t \log N \times (\lambda + t)\text{-bit-XOR}$	$2t \log N \times T_G + 2t \times T_{G_{\text{conv}}}$ $+ \log N \times \text{OKVS.Encode}$ $+ \text{OKVS}_{\text{conv}}.\text{Encode}$
$Eval()$	$t \log N \times T_G + t \times T_{G_{\text{conv}}}$	$w \log(wN/m) \times T_G + w \times T_{G_{\text{conv}}}$ Finding all positions the input is mapped to	$\log N \times T_{G^*} + T_{G_{\text{conv}}}$ $+ t \log N \times (\lambda + t)\text{-bit-XOR}$	$\log N \times T_G$ $+ \log N \times \text{OKVS.Decode}$ $+ \text{OKVS}_{\text{conv}}.\text{Decode}$
$FullEval()$	$tN \times T_G + tN \times T_{G_{\text{conv}}}$	$wN \times T_G + wN \times T_{G_{\text{conv}}}$ Finding the full mapping	$N \times T_{G^*} + N \times T_{G_{\text{conv}}}$ $+ 2tN \times (\lambda + t)\text{-bit-XOR}$	$N \times T_G$ $+ N \times \text{OKVS.Decode}$ $+ N \times \text{OKVS}_{\text{conv}}.\text{Decode}$

¹ The PRG used in big-state DMPF maps from $\{0, 1\}^\lambda$ to $\{0, 1\}^{2\lambda+2t}$ whose computation time should grow with t . We mark this PRG as G^* and its computation time as T_{G^*} .

4 APPLICATIONS

In this section we compare and discuss about the efficiency of different DMPF schemes in concrete application scenarios, namely when used for constructing pseudorandom correlation generator (PCG) and unbalanced private set intersection protocol (unbalanced PSI). For convenience of discussion, we use $\text{DMPF}_{t,N,\mathbb{G}}$ to denote a DMPF scheme for t -point functions with domain $[N]$ and output group \mathbb{G} .

To give a rough impression, we list the number of accepting points t , the domain size N and the output group \mathbb{G} of DMPF usually used in generating the PCG or unbalanced PSI protocol in table 3.

4.1 PCG for OLE from Ring-LPN

In this section we discuss the efficiency of different DMPF schemes in the PCG application. We begin by briefly introducing the protocol of PCG for OLE from Ring-LPN assumption, proposed in [4].

The PCG protocol for OLE correlation. The hardness assumption we will make use of is a variant of Ring-LPN, called module-LPN assumption.

DEFINITION 5 (MODULE-LPN). Let $c \geq 2$ be an integer, $R = \mathbb{Z}_p[X]/F(X)$ for a prime p and a deg- N polynomial $F(X) \in \mathbb{Z}_p[X]$, and $\mathcal{H}\mathcal{W}_{R,t}$ be the uniform distribution over weight- t polynomials in R whose degree is less than N and has at most t nonzero coefficients. For $R = R(\lambda)$, $t = t(\lambda)$ and $m = m(\lambda)$, we say that the module-LPN problem R^c -LPN is hard if for every nonuniform polynomial-time probabilistic distinguisher \mathcal{A} , it holds that

$$\begin{aligned} & |\Pr[\mathcal{A}(\{\vec{a}^{(i)}, \langle \vec{a}^{(i)}, \vec{s} \rangle + \vec{e}^{(i)}\}_{i \in [m]})] \\ & - \Pr[\mathcal{A}(\{\vec{a}^{(i)}, \vec{u}^{(i)}\}_{i \in [m]})]| \leq \text{negl}(\lambda) \end{aligned}$$

where the probabilities are taken over the randomness of \mathcal{A} , random samples $\vec{a}^{(1)}, \dots, \vec{a}^{(m)} \leftarrow R^{c-1}$, $\vec{u}^{(1)}, \dots, \vec{u}^{(m)} \leftarrow R$, $\vec{s} \leftarrow \mathcal{H}\mathcal{W}_{R,t}^{c-1}$, and $\vec{e}^{(1)}, \dots, \vec{e}^{(m)} \leftarrow \mathcal{H}\mathcal{W}_{R,t}$.

When we only consider $m = 1$, each R^c -LPN instance $\langle \vec{a}, \vec{s} \rangle + \vec{e}$ can be restated as $\langle \vec{a}', \vec{e}' \rangle$ where $\vec{a}' = 1||\vec{a}$ and $\vec{e}' \leftarrow \mathcal{H}\mathcal{W}_{R,t}^c$.

The PCG protocol in [4] generates seed for the OLE correlation $(x_0, x_1, z_0, z_1) \in R^4$ such that $x_0 + x_1 = z_0 \cdot z_1$, where $R = \mathbb{Z}_p[X]/F(X)$ for a prime p and a deg- N polynomial $F(X) \in \mathbb{Z}_p[X]$. The idea is to first set $z_b = \langle \vec{a}, \vec{e}_b \rangle$ (an R^c -LPN instance with public \vec{a} and $\vec{e}_b \leftarrow \mathcal{H}\mathcal{W}_{R,t}^c$). Basing on the fact that $\langle \vec{a}, \vec{e}_0 \rangle \cdot \langle \vec{a}, \vec{e}_1 \rangle = \langle \vec{a} \otimes \vec{a}, \vec{e}_0 \otimes \vec{e}_1 \rangle$, the next step is to additively share the tensor product $\vec{e}_0 \otimes \vec{e}_1$ and each party can compute an additive share of $z_0 \cdot z_1$. Note that the tensor product $\vec{e}_0 \otimes \vec{e}_1$ consists of c^2 entries, each being an deg- $2N$ polynomial with at most t^2 nonzero coefficients. Therefore it can be shared by invoking $\text{DMPF}_{t^2, 2N, \mathbb{Z}_p}$ for c^2 times.

One can compute the seed size and expanding time of this PCG protocol as follows:

- The seed size is $ct(\log N + \log p)$ bits for specifying \vec{e}_b plus the $c^2 \times \text{keysize}$ of DMPF.
- The expanding time is c^2 multiplications in the deg- $2N$ polynomial ring **Yaxin: or $2c^2$ multiplications since $\vec{a} \otimes \vec{a}$ need also be computed?** plus $c^2 \times \text{full-domain evaluation time}$ of DMPF.

REMARK 6 (FROM OLE OVER POLYNOMIAL RING R TO OLE OVER \mathbb{Z}_p). Note that the above PCG protocol generates seed for OLE correlation over deg- N polynomial ring R . One can immediately convert an OLE correlation over ring R to N **OLE correlations over \mathbb{Z}_p** if the polynomial $F(X)$ splits into N distinct linear factors modulo p [4]. Therefore we mostly consider reducible F and more concretely F a two-power cyclotomic due to its useful properties.

Table 3: Parameters of DMPF in concrete applications.

Concrete application	Cost in terms of DMPF per correlation/execution	Typical DMPF parameters
PCG for OLE from Ring-LPN	seedsize $\propto \text{DMPF.keysize}$ expand time $\propto \text{DMPF.FullEval}()$	Number of accepting points: $5^2, 16^2, 76^2$ Domain size: 2^{20} Output group: \mathbb{Z}_p where $\log p = 128$
PSI-WCA	communication $\propto \text{DMPF.keysize}$ client computation $\propto \text{DMPF.Gen}()$ server computation $\propto \text{DMPF.Eval}()$	Number of accepting points: any Domain size: 2^{128} Output group: any

Amortized expanding time for each OLE correlation over \mathbb{Z}_p . The amortized expanding time for each OLE correlation over \mathbb{Z}_p is computed by

$$T_{\text{Amortized}} = c^2 \cdot (2\bar{T}_N^{\text{MULT}} + \bar{T}_{t,N}^{\text{FullEval}})$$

where

$$\bar{T}_N^{\text{MULT}} := \frac{\deg < N \text{ polynomial multiplication}}{N}$$

is the amortized cost for computing one $\deg < N$ polynomial multiplication, and

$$\bar{T}_{t,N}^{\text{FullEval}} := \frac{\text{DMPF}_{t^2, 2N, \mathbb{Z}_p}.\text{FullEval}}{N}$$

is the amortized cost for computing a share of an entry of $\vec{e}_0 \otimes \vec{e}_1$. This cost differs under different $\text{DMPF}_{t^2, 2N, \mathbb{Z}_p}$ instantiations: **Yaxin:** $T_{G_{\text{conv}}}$ is ignored for now.

- Sum of DPFs: $2t^2 \times T_G$.
- CBC-based DMPF ($\mathcal{H}\mathcal{W}_t$): $2w \times T_G + 2w \times T_{\text{hash}}^1$.
- Big-state DMPF: $2T_{G^*}$, where G^* maps λ -bit to $(2\lambda + 2t)$ -bit.
- OKVS-based DMPF: $2(T_G + \text{OKVS.Decode})^2$.

Using the regular noise distribution to split $\text{DMPF}_{t^2, 2N, \mathbb{Z}_p}$. A previous optimization in [4], aiming to share the entries of $\vec{e}_0 \otimes \vec{e}_1$ through DPFs but with less overhead (in contrast to the $2t^2 \times T_G$ cost before), is to substitute $\mathcal{H}\mathcal{W}_{R,t}$ with the distribution of random regular weight- t polynomials denoted as $\mathcal{R}\mathcal{H}\mathcal{W}_{R,t}$. Each regular weight- t polynomial e contains exactly one nonzero coefficient e_j in the range of degree $[j \cdot N/t, (j+1) \cdot N/t - 1]$ for $j = 0, \dots, t-1$. When multiplying two regular weight- t polynomials e and f , $e_i \cdot f_j$ contributes to a coefficient in the range of degree $[(i+j) \cdot N/t, (i+j+2) \cdot N/t - 2]$. Therefore the $\deg-2N$ polynomial $e \cdot f$ can be shared by invoking $\{\text{DMPF}^{(k)} = \text{DMPF}_{\min(k, 2t-k), 2N/t, \mathbb{Z}_p}\}_{1 \leq k \leq 2t-1}$, where $\text{DMPF}^{(k)}$'s domain corresponds to the coefficients in the range of degree $[(k-1)N/t, (k+1)N/t - 2]$ in the resulting polynomial $e \cdot f$. Then each $\text{DMPF}^{(k)}$ in the set $\{\text{DMPF}^{(k)}\}_{1 \leq k \leq 2t-1}$ can be instantiated by one of the mentioned schemes: sum of DPFs (used in [4]), CBC-based, big-state, or OKVS-based DMPF. We note that the efficiency (in terms of FullEval time) of all these instantiations are more or less related to the number of nonzero inputs in the targeted DMPF, therefore using $\mathcal{R}\mathcal{H}\mathcal{W}_{R,t}$ instead of $\mathcal{H}\mathcal{W}_{R,t}$ reduces the

number of nonzero inputs from t^2 to at most t may be beneficial in some occasions.

An alternative way to split $\text{DMPF}_{t^2, 2N, \mathbb{Z}_p}$, basing on the previous observation, is to share the coefficients of $e \cdot f$ by invoking $\{\text{DMPF}'^{(k)} = \text{DMPF}_{2\min(k+1, 2t-k)-1, N/t, \mathbb{Z}_p}\}_{0 \leq k \leq 2t-1}$, where $\text{DMPF}'^{(k)}$'s domain corresponds to the coefficients in the range of degree $[kN/t, (k+1)N/t - 1]$. Since the number of nonzero coefficients in $[kN/t, (k+1)N/t - 1]$ is upperbounded by the sum of number of nonzero coefficients in $[(k-1)N/t, (k+1)N/t - 2]$ and in $[kN/t, (k+2)N/t - 2]$, $\text{DMPF}'^{(k)}$ has at most $2\min(k+1, 2t-k) - 1$ nonzero inputs. The advantage of using $\{\text{DMPF}'^{(k)}\}_{0 \leq k \leq 2t-1}$ is that the previous concatenation through $\{\text{DMPF}^{(k)}\}_{1 \leq k \leq 2t-1}$ creates overlapping ranges, which doubles the number of PRG invocations when realizing by CBC-based, big-state, and OKVS-based DMPF. By using $\{\text{DMPF}'^{(k)}\}_{0 \leq k \leq 2t-1}$, the ranges are not overlapping and therefore maintains the minimal PRG invocations, while also preserving a relatively small number of nonzero inputs (at most $2t-1$) in each $\text{DMPF}'^{(k)}$.

Previously, [4] uses sum of DPFs to instantiate $\{\text{DMPF}^{(k)}\}_{1 \leq k \leq 2t-1}$ in the first optimized design with regular noise distribution. It indicates using batch code to achieve DMPF as another optimization but not in the clear. We'll analyze the cost of this PCG protocol under the following settings:

- (1) with noise distribution $\mathcal{H}\mathcal{W}_{R,t}$ and each multiplication of sparse polynomials is shared by $\text{DMPF}_{t^2, 2N, \mathbb{Z}_p}$
- (2) ith noise distribution $\mathcal{R}\mathcal{H}\mathcal{W}_{R,t}$ and each multiplication of regular sparse polynomials is shared by

$$\{\text{DMPF}^{(k)} = \text{DMPF}_{\min(k, 2t-k), 2N/t, \mathbb{Z}_p}\}_{1 \leq k \leq 2t-1}$$

- (3) ith noise distribution $\mathcal{R}\mathcal{H}\mathcal{W}_{R,t}$ and each multiplication of sparse polynomials is shared by

$$\{\text{DMPF}'^{(k)} = \text{DMPF}_{2\min(k+1, 2t-k)-1, N/t, \mathbb{Z}_p}\}_{0 \leq k \leq 2t-1}$$

Yaxin: Dec 27: It is also mentioned using more advanced noise distributions to avoid overlapping ranges. For now it remains to give the concrete costs for (1) $\text{DMPF}_{t^2, 2N, \mathbb{Z}_p}$; (2) $\text{DMPF}_{1/2/\dots/(2t-1), N/t, \mathbb{Z}_p}$; (3) $\text{DMPF}_{1/2/\dots/(2t-1), N/t, \mathbb{Z}_p}$ under sum of DPFs/CBC-based/big-state/OKVS-based instantiations.

We'll instantiate DMPF in different ways as listed in table 2. The costs of PCG protocols under different settings are listed in table 4.

Yaxin: One caveat: can CBC-based / OKVS-based DMPF fit into the regular design, while it requires shares of 1, 2, 3-point functions?

¹The hash function's domain and range are related to t .

²The OKVS scheme encodes at most t key-value pairs. OKVS.Decode usually takes a small number of field addition or field multiplication in \mathbb{F}_{2^λ} , depending on the implementation.

Table 4: Seed size and expanding time of PCG protocols for the same (λ, N, c, t) with different choices of noise distributions in module-LPN assumption, and with different DMPF instantiations. We use construction 5 as an instantiation of OKVS. The seed size is represented by total DMPF share size and the expanding time is represented by total DMPF.FullEval time. The PRG evaluations in the first $\log(2N)$ layers and in the convert layer are both regarded as the same PRG. $e = m/t$ in the second row represents the expansion parameter for PBC where m is the number of buckets, and e' in the last row represents the expansion parameter (the inverse of rate) for OKVS.

DMPF instantiation	Noise type	Total share size	Total FullEval time (only listed PRG and OKVS)
Sum of DPFs	regular	$c^2 t^2 \lambda \log(2N/t) + c^2 t^2 \log p$	$4c^2 t N \times \text{PRG}$
	nonregular	$c^2 t^2 \lambda \log(2N) + c^2 t^2 \log p$	$4c^2 t^2 N \times \text{PRG}$
Batch-code DMPF	regular	$ec^2 t^2 \lambda \log(\frac{wN}{et}) + ec^2 t^2 \log p$	$8c^2 w N \times \text{PRG}$
	nonregular	$ec^2 t^2 \lambda \log(\frac{2wN}{et^2}) + ec^2 t^2 \log p$	$4c^2 w N \times \text{PRG}$
Big-state DMPF	regular	$c^2 t^2 (\lambda + \frac{4}{3}t) \log(2N) + c^2 t^2 \log p$	$8c^2 N \times \text{PRG}^{*1}$
	nonregular	$c^2 t^2 (\lambda + 2t) \log(2N) + c^2 t^2 \log p$	$4c^2 N \times \text{PRG}^*$
OKVS-based DMPF	regular	$e' c^2 t^2 \lambda \log(2N/t) + e' c^2 t^2 \log p$	$8c^2 N \times \text{PRG} + 8c^2 N \times \text{OKVS.Decode}$
	nonregular	$e' c^2 t^2 \lambda \log(2N) + e' c^2 t^2 \log p$	$4c^2 N \times \text{PRG} + 4c^2 N \times \text{OKVS.Decode}$

¹ The PRG used in big-state DMPF maps from $\{0, 1\}^\lambda$ to $\{0, 1\}^{2\lambda+2t^2}$ whose computation time should grow with t^2 .

Setting parameters (N, c, t) against best attacks. Next we plug in concrete parameters and evaluate the performance of different DMPF schemes under different PCG parameter settings.

The parameters (N, c, t) should be set in a way that the corresponding R^c -LPN problem is secure with computational security parameter λ . In [4] the parameters are taken to be $(\lambda, N, c, t) \in \{(128, 2^{20}, 8, 5), (128, 2^{20}, 4, 16), (128, 2^{20}, 2, 76)\}$ against several attacks, with the best among which predicted to be the SD or ISD family. Yaxin: Dec 28: Using the new lowerbound in [14] (if I understood it correctly), the setting of parameters (fixing $\lambda = 128$ and $N = 2^{20}$) becomes $(\lambda, N, c, t) \in \{(128, 2^{20}, 8, 5), (128, 2^{20}, 4, 14), (128, 2^{20}, 2, 70)\}$. In fact, N is independent to other parameters because R is a reducible polynomial ring. The three parameters are comparable in efficiency in [4] because they used the second DMPF instantiation (concatenation of DPFs under \mathcal{RW}_t distribution) whose cost scales with $c^2 t$. By using the new DMPF instantiations we may see significant difference among the three tuples of parameters.

How to compute (N, c, t) : We set the parameters (λ, c, N, t) such that the best attack requires at least 2^λ arithmetic operations over field \mathbb{F}_p of size approximately 2^{128} .

An R^c -LPN instance $a \cdot e$ can be viewed as a (dual)-LPN $_{cN, N, \mathcal{HW}_{N,t}^{sc}}$ instance $\{H, H \cdot \vec{e}\}$, where $H \in \mathbb{Z}_p^{N \times cN}$ is a concatenation of c circular matrices representing multiplication with a , and $\vec{e} \in \mathbb{Z}_p^{cN}$ with distribution $\mathcal{HW}_{N,t}^{sc}$ represents the concatenation of coefficients of e . The bit security of the R^c -LPN problem is equivalent to the bit security of the described (dual)-LPN problem. As in [4], we consider the bit security of the described (dual)-LPN problem to be the same as the bit security of the standard (dual)-LPN problem, whose error distribution is $\mathcal{HW}_{cN, ct}$, the random weight- ct noises.

According [4], for R from an irreducible F , we lowerbound the number of arithmetic operations by $N \cdot (c \cdot \frac{N}{N-1})^{ct} \approx N \cdot c^{ct}$. Yaxin:

Dec 28: [14] seems to indicate a better lowerbound of $N^{2.8} \cdot c^{ct}$. For R from a reducible F , the number of arithmetic operations is lowerbounded by $2^i \cdot c^{w_i}$ Yaxin: Dec 28: or $2^{2.8i} \cdot c^{w_i}$ by [14], where w_i is the expected number of noisy coordinates modulo an 1-sparse $\deg-2^i$ polynomial and $i :=$ the smallest integer such that $w_i < 2^i$. Then t is computed by the equation

$$w_i = c \cdot 2^i \left(1 - (1 - 2^{-i})^t\right)$$

Yaxin: Dec 29: In [4] there are two formulas calculating w_i . One is as above, and the other is

$$w_i = ct - 2^i c + ((2^i - 1)c + ct) \cdot (1 - 2^{-i})^{t-1}$$

The second one does not make sense to me but is used to compute the concrete results. Nevertheless the two formulas computes similar results so I used the first one which makes more sense to me.

4.2 Unbalanced PSI-WCA

A private set intersection (PSI) protocol allows two parties with input X, Y being two sets to learn about their intersection $X \cap Y$ without revealing additional information of X or Y . We denote by PSI-WCA (weighted cardinality) a variant of PSI that computes the weighted cardinality of elements in $X \cap Y$ where the weights are determined by a pre-fixed function $w(\cdot)$.

We will be interested in *unbalanced* PSI-WCA where $|X| \gg |Y|$ and the output should be received by the party holding Y . In this problem we call the party holding X as the server, and the party holding Y as the client. If further the big set X is held by two non-colluding servers, then such an unbalanced PSI-WCA protocol can be constructed from DMPF, as suggested in [9]:

- The client invokes $\text{DMPF.Gen}(1^\lambda, \hat{f}_{Y, w(Y)}) \rightarrow (k_0, k_1)$, where $w(Y)$ is the set of weights of elements in Y . Then the client send k_0 to server 0 and k_1 to server 1.
- Server b computes $s_b = \sum_{x \in X} \text{DMPF.Eval}_b(1^\lambda, k_b, x)$ and send it back to the client.
- The client computes $s_0 + s_1$, which will be the weighted cardinality of $X \cap Y$.

One caveat is that this protocol reveals information about Y that is leaked by DMPF. Plugging in any DMPF instantiations we have mentioned, the size of $|Y|$ will be leaked to the servers.

The cost of our unbalanced PSI-WCA can be computed as follows:

- The communication cost equals the keysize of DMPF.
- The client computation time equals the key generation time of DMPF.
- The server computation time equals $|X| \times$ the evaluation time of DMPF.

We'll instantiate DMPF in different ways as listed in table 2. As suggested in [9], we take an infeasibly large domain for the sets X and Y to locate, whose size is $N = 2^{128}$. The set sizes $|X|$ and $|Y|$ can vary depending on application scenarios. Since $|Y|$ is the crucial factor that distinguishes different DMPF instantiations, we will only consider the change of $|Y|$. The costs of PSI-WCA protocols under different settings of $|Y|$ are listed in table 5.

4.3 Security analysis

4.4 Heavy-hitters

private heavy-hitter
or parallel ORAM?

5 ACKNOWLEDGMENTS

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A SECURITY PROOFS

We say that a realization of GenCW is hiding if it gives no information about the multi-point function $f_{A,B}$. It is defined using an indistinguishability-based definition as follows:

DEFINITION 7 (COMPUTATIONALLY HIDING OF GenCW). GenCW is computationally hiding if $\forall i \in [n], \forall A \neq A',$ and for randomly and independently sampled lists $V^{(i-1)}[k] \leftarrow \{0, 1\}^{\lambda+2l}$ for $1 \leq k \leq |A^{(i-1)}|$ and $V'^{(i-1)}[k] \leftarrow \{0, 1\}^{\lambda+2l}$ for $1 \leq k \leq |A'^{(i-1)}|$,

$$\{CW \leftarrow \text{GenCW}(i, A, V^{(i-1)})\} \approx_c \{CW \leftarrow \text{GenCW}(i, A', V'^{(i-1)})\}$$

Similarly we define a realization of GenConvCW to be hiding if it gives no information about $f_{A,B}$:

DEFINITION 8 (COMPUTATIONALLY HIDING OF GenConvCW). GenConvCW is computationally hiding if $\forall i \in [n], \forall (A, B) \neq (A', B'),$ and for randomly and independently sampled lists $\text{seed}_0, \text{seed}_1 \leftarrow \{0, 1\}^{\lambda \times t}$ and $\text{sign}_0, \text{sign}_1 \leftarrow \{0, 1\}^l$,

$$\{CW \leftarrow \text{GenConvCW}(A, B, \{\text{seed}_b, \text{sign}_b\}_{b=0,1})\}_{\text{seed}_0, \text{seed}_1 \leftarrow (\{0, 1\}^{\lambda})^{\otimes t}, \text{sign}_0, \text{sign}_1 \leftarrow (\{0, 1\}^l)^{\otimes t}} \approx_c \{CW \leftarrow \text{GenConvCW}(A', B', \{\text{seed}_b, \text{sign}_b\}_{b=0,1})\}_{\text{seed}_0, \text{seed}_1 \leftarrow (\{0, 1\}^{\lambda})^{\otimes t}, \text{sign}_0, \text{sign}_1 \leftarrow (\{0, 1\}^l)^{\otimes t}}$$

Next we show that if GenCW and GenConvCW in the DMPF paradigm Figure 1 are computationally hiding, then the DMPF is computationally secure.

LEMMA 9.

Table 5: Communication cost, client and server computation time of the PSI-WCA protocol for domain size $N = 2^{128}$, weight group \mathbb{G} , and different choices of client's set size $|Y|$. We use construction 5 as an instantiation of OKVS. The PRG evaluations in the first $\log N$ layers and in the convert layer are both regarded as the same PRG. e in the second row represents the expansion parameter for PBC, and e' in the last row represents the expansion parameter for OKVS.

DMPF instantiation	Communication cost	Client computation time	Server computation time
Sum of DPFs	$ Y \lambda \log N + Y \log \mathbb{G} $	$2 Y \log N \times \text{PRG}$	$ X \cdot Y \log N \times \text{PRG}$
Batch-code DMPF	$e Y \lambda \log(\frac{wN}{e Y }) + e Y \log \mathbb{G} $	$2e Y \log(\frac{wN}{e Y }) \times \text{PRG}$	$w X \log(\frac{wN}{e Y }) \times \text{PRG}$
Big-state DMPF	$ Y (\lambda + 2 Y) \log N + Y \log \mathbb{G} $	$2 Y \log N \times \text{PRG}^{*1}$	$ X \log N \times \text{PRG}^*$
OKVS-based DMPF	$e' Y \lambda \log N + e' Y \log \mathbb{G} $	$2 Y \log N \times \text{PRG} + \log N \times \text{OKVS.Encode}$	$ X (\log N \times \text{PRG} + \log N \times \text{OKVS.Decode})$

¹ The PRG used in big-state DMPF maps from $\{0, 1\}^\lambda$ to $\{0, 1\}^{2\lambda+2|Y|}$ whose computation time should grow with $|Y|$.