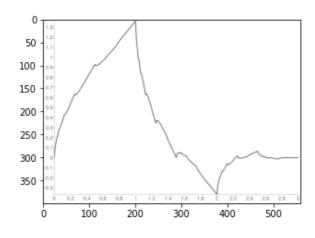
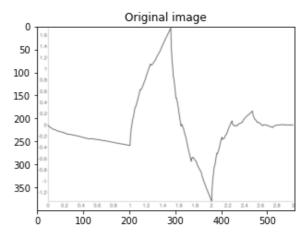
```
In [2]:
```

```
%matplotlib inline
from IPython.display import display, Math, Latex
import numpy as np
import matplotlib.pyplot as plt
import requests
from PIL import Image
from io import BytesIO
import pywt
from PIL import Image
from math import sqrt
import sys, getopt
from matplotlib import rcParams
import numpy as np
import scipy.ndimage.filters
from scipy.signal import convolve
import matplotlib.pyplot as plt
import os
url 1 = 'https://i.ibb.co/TkMRC83/chart-1.png'
url 2 = 'https://i.ibb.co/xj3X1rG/chart-2.png'
response_1 = requests.get(url_1)
response 2 = requests.get(url 2)
img_1 = Image.open(BytesIO(response_1.content)).convert('L')
img_2 = Image.open(BytesIO(response_2.content)).convert('L')
output url = 'https://i.ibb.co/2cHH0s5/Comparision.png'
output_response = requests.get(output_url)
output image = Image.open(BytesIO(output response.content)).convert('L')
# display the image
rcParams['figure.figsize'] = 11 ,8
fig, ax = plt.subplots(1, 2)
ax[0].imshow(img_1, cmap='gray', vmin=0, vmax=255);
ax[1].imshow(img 2, cmap='gray', vmin=0, vmax=255);
plt.title("Original image")
```

Out[2]:

Text(0.5, 1.0, 'Original image')





In []:

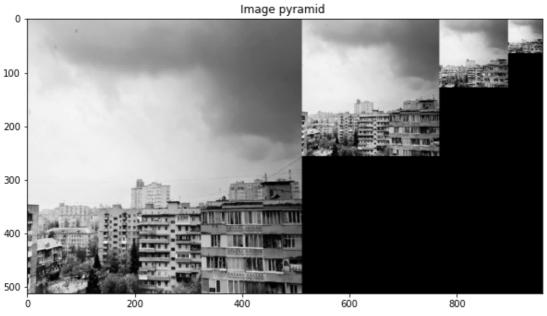
```
def gaussian_filter(filter_size):
    """ get gaussian filter with filter size"""

if filter_size == 1:
    return np.array([[1]])

filter = np.float64(np.array([[1, 1]]))
```

```
for i in range(filter size - 2):
        filter = scipy.signal.convolve2d(filter, np.array([[1, 1]]))
    return filter / np.sum(filter)
def blur im(im, filter vec):
    """ blur an image with filter vector"""
   blur rows = scipy.ndimage.filters.convolve(im, filter vec)
   blur columns = scipy.ndimage.filters.convolve(blur rows, filter vec.T)
   return blur columns
def reduce(im, filter vec):
    """ reduce an image"""
   blurred im = blur im(im, filter vec)
   return blurred im[::2, ::2]
def expand(im, filter vec):
    """ expand an image"""
    # zero padding
   im shape = im.shape
   expanded im = np.zeros((2 * im shape[0], 2 * im shape[1]))
   expanded im[::2, ::2] = im
    return blur im(expanded im, 2 * filter vec)
def build_gaussian_pyramid(im, max_levels, filter_size):
    """ functions that construct a Gaussian pyramid of a given image."""
   pyr = []
   filter vec = gaussian filter(filter size)
   next level im = im
   \max \text{ levels} = \min(\max \text{ levels}, \inf(\text{np.log}(\text{im.shape}[0] // 16) / \text{np.log}(2)) + 1,
                     int(np.log(im.shape[1] // 16) / np.log(2)) + 1)
   for i in range(max levels):
        pyr.append(next level im)
        next level im = reduce(np.copy(next level im), filter vec)
   return pyr, filter vec
def build laplacian pyramid(im, max levels, filter size):
    """ functions that construct a Laplacian pyramid of a given image."""
   pyr = []
   gaus pyr, filter vec = build gaussian pyramid(im, max levels, filter size)
   for i in range(len(gaus pyr) - 1):
       Ln = gaus pyr[i] - expand(np.copy(gaus pyr[i + 1]), filter vec)
        pyr.append(Ln)
   pyr.append(gaus pyr[-1])
   return pyr, filter vec
def laplacian to image(lpyr, filter vec, coeff):
    """ reconstruction of an image from its Laplacian Pyramid."""
    reconstructed im = lpyr[-1] * coeff[-1]
    for i in range (len(lpyr) - 2, -1, -1):
        reconstructed im = lpyr[i] * coeff[i] + expand(reconstructed im, filter ve
C)
    return reconstructed im
def render pyramid(pyr, levels):
```

```
mmm = mmm
   levels=min(len(pyr), levels)
   new shape0 = pyr[0].shape[0]
   new shape1 = int(pyr[0].shape[1] * (1 - np.power(0.5, levels)) / 0.5)
   res = np.zeros((new shape0, new shape1))
   start col = 0
   stretched im = []
   for level in range(levels):
        #stretched im.append(stretch im(np.copy(pyr[level])))
        stretched im.append(pyr[level])
        cur_level_shape = stretched_im[level].shape
        res[:cur level shape[0], start col:cur level shape[1] + start col] = stret
ched im[level]
       start col += cur level shape[1]
   return res
def display pyramid(pyr, levels):
    """ render and display the stacked pyramid image"""
   res = render pyramid(pyr, levels)
   figsize = (10, 10)
   plt.figure(figsize=figsize)
   plt.imshow(res, cmap='gray')
   plt.title("Image pyramid ")
   plt.show()
   return res
input url = 'https://github.com/Dubbinary/wavelet transform/blob/434e3cf3f8a8913be
d638182057a36d37c0a3499/res/6.jpg?raw=true'
input_response = requests.get(input url)
input image = Image.open(BytesIO(input response.content)).convert('L')
input image = np.asarray(input image)
# build gaussian pyramid
pyr, filter vec = build gaussian pyramid(input image, 4, 1)
display pyramid(pyr, 4)
```



```
array([[181., 181., 182., ...,
                                93., 91.,
       [182., 182., 182., ...,
                                    89.,
                                92.,
       [181., 182., 182., ...,
                                89.,
                                     86.,
                               0.,
       [176., 180., 110., ...,
                                     0.,
                                             0.],
                                     0.,
       [180., 174., 102., ...,
                               0.,
                                            0.],
       [178., 162., 99., ...,
                               0.,
                                      0.,
                                             0.]])
```

Out[]:

```
def encoding grayscale(image ch, CL, threshold):
    :param image ch: Numpy array of image channel
    :param CL: Coefficients of low frequency filter
    :param threshold: threshold: Parameter of quantization [0..1]
    :return: Encoded numpy image array
   image ch = image ch / 255
   w, h = image ch.shape
   while w >= len(CL) and h >= len(CL):
        image_ch[0:w, 0:h] = dwt2(image_ch[0:w, 0:h], CL)
        w = int(w / 2)
       h = int(h / 2)
    show_image_from_nmlz_data(image_ch, color_mode="F")
   if verbose:
       print("Quantization with parameter: ",
              "\nGRAYSCALE CHANNEL = "+str(threshold))
    image_ch[abs(image_ch) < threshold] = 0</pre>
    #show image from nmlz data(image ch, color mode="F")
   return image ch
def decode grayscale(image ch, CL):
    :param image ch: Numpy array of encoded image channel (grayscale)
    :param CL: Coefficients of low frequency filter
    :return: Decoded image object
   im width, im heigh = image ch.shape
   w = h = len(CL)
   while w <= im width and h <= im heigh:
        image ch[0:w, 0:h] = idwt2(image ch[0:w, 0:h], CL)
       w *= 2
       h *= 2
   decoded img = Image.fromarray(image ch * 255, "F")
   return decoded img
def idwt2(data, CL):
    :param data: two-dimensional transformed image
    :param CL: Coefficients of low frequency filter
    :return: Return two-dimensional backward transformation of image
   w, h = data.shape
    # Rearrange the columns and rows back
   imageT = data.copy()
   imageT[0:h:2, 0:w:2] = data[0:int(h/2), 0:int(w/2)]
   imageT[1:h:2, 0:w:2] = data[int(h/2):h, 0:int(w/2)]
   imageT[0:h:2, 1:w:2] = data[0:int(h/2), int(w/2):w]
   imageT[1:h:2, 1:w:2] = data[int(h/2):h, int(w/2):w]
   CH = get_hpf_coeffs(CL)
   iCL, iCH = get_icoeffs(CL, CH)
                                        # Copy the original image to convert
   image = imageT.copy()
                                        # Process the columns
   for i in range(w):
        image[:, i] = pconv(image[:, i], iCL, iCH, delta=len(iCL)-2)
    for i in range(h):
                                         # Process the lines
        image[i, :] = pconv(image[i, :], iCL, iCH, delta=len(iCL)-2)
   return image
def dwt2(image, CL):
    :param image: two-dimensional array representation of image
    :param CL: Coefficients of low frequency filter
    :return: Return two-dimensional transformation of image
```

```
CH = get hpf coeffs(CL)  # Calculate the missing coefficients
   w, h = image.shape
   imageT = image.copy()
                               # Copy the original image to convert ############
########
   for i in range(h):
                               # Process the lines
       imageT[i, :] = pconv(imageT[i, :], CL, CH)
   for i in range(w): # Process the columns
       imageT[:, i] = pconv(imageT[:, i], CL, CH)
   # Rearrange the columns and rows isolating filters
   data = imageT.copy()
   data[0:int(h / 2), 0:int(w / 2)] = imageT[0:h:2, 0:w:2] # top-left
   data[int(h / 2):h, 0:int(w / 2)] = imageT[1:h:2, 0:w:2] # bottom-left
   data[0:int(h / 2), int(w / 2):w] = imageT[0:h:2, 1:w:2] # top-right
   data[int(h / 2):h, int(w / 2):w] = imageT[1:h:2, 1:w:2] # bottom-right
   return data
def get hpf coeffs(CL):
                                   # Coefficients of high frequency filter
   :param CL: Coefficients of low frequency filter
   :return: Return list with coefficients of high frequency filter
   N = len(CL)
                                  # The number of coefficients
   CH = [(-1)**k * CL[N - k - 1] # The coefficients in reverse order with alter
nating sign
       for k in range(N)]
   return CH
def pconv(data, CL, CH, delta = 0):
   :param data: Data on which performed transformation
   :param CL: Coefficients of low frequency filter
   :param CH: Coefficients of high frequency filter
   :param delta: Parameter which provide shift of coefficients
   :return: Return transformed data
   assert(len(CL) == len(CH))
                                       # Dimensions lists factors should be equal
   N = len(CL)
   M = len(data)
   out = []
                                      # List a result, until empty
   for k in range(0, M, 2):
                                       # Loop through the numbers 0, 2, 4 ...
                                       # Low-frequency coefficient
       sL = 0
       sH = 0
                                       # High-frequency coefficient
       for i in range(N):
                                       # We find ourselves weighted sums
           sL += data[(k + i - delta) % M] * CL[i]
           sH += data[(k + i - delta) % M] * CH[i]
       out.append(sL)
       out.append(sH)
   return out
def get icoeffs(CL, CH):
   :param CL: Coefficients of low frequency filter
   :param CH: Coefficients of high frequency filter
   :return: Return coefficients that used in backward transformation
   assert(len(CL) == len(CH))
                                       # Dimensions lists factors should be equal
   iCL = []
                                       # The coefficients of the first line
   iCH = []
                                       # The coefficients of the second line
   for k in range(0, len(CL), 2):
       iCL.extend([CL[k-2], CH[k-2]])
       iCH.extend([CL[k-1], CH[k-1]])
   return (iCL, iCH)
# display the output
figsize = (15, 15)
plt.figure(figsize=figsize)
```

```
plt.imshow(output_image, cmap='gray', vmin=0, vmax=255)
plt.title("Image compression using the Wavelet function ")
```

Out[]:

Text(0.5, 1.0, 'Image compression using the Wavelet function ')

