

# Viscous Regularization And High-order Nonlinear Viscosity Methods For Magnetohydrodynamics

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August 21st, 2023

# Why?

## Hydrogen bomb since 1950s

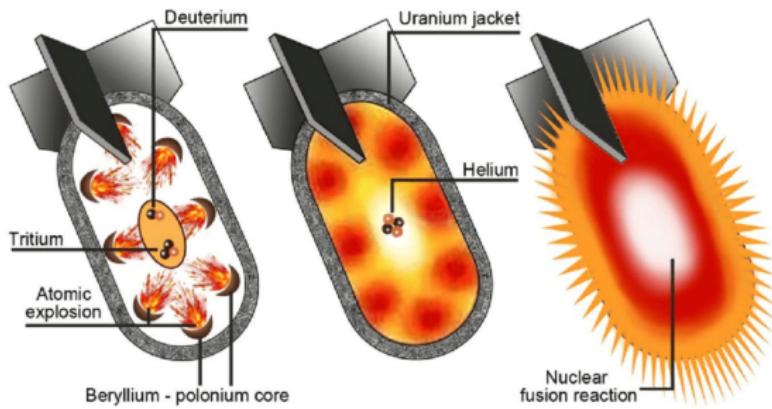


Figure: [Jianan Wang, 2020]

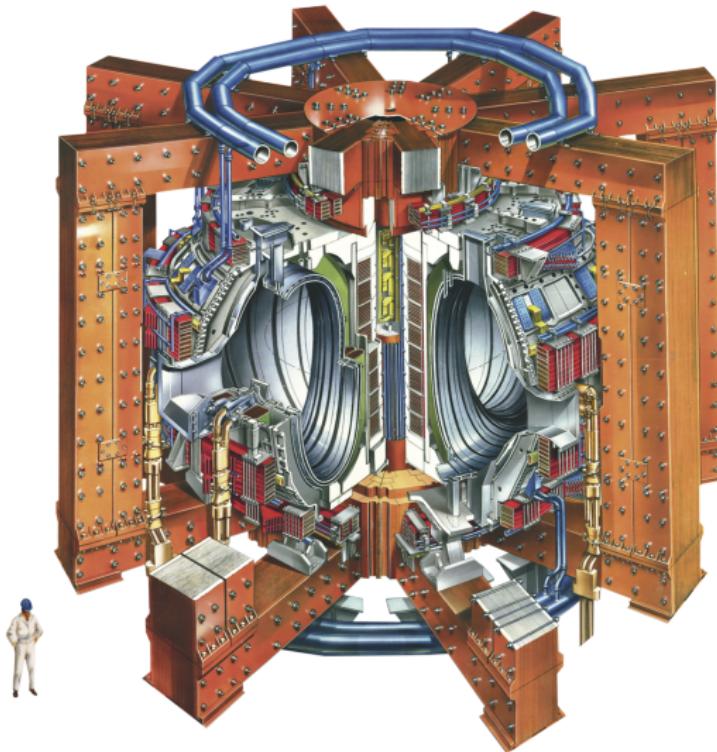


Figure: Tokamak fusion reactor

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By IANS · 11 June, 2021 · TWC India



The experimental advanced superconducting tokamak (EAST).

(Xinhua/Zhou Mu/IANS)

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► 'Major scientific breakthrough': US recreates fusion - video

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**US scientists achieve net energy gain for second time in nuclear fusion reaction**

The Lawrence Livermore National Laboratory's National Ignition Facility achieved the feat using lasers to fuse two atoms



► The National Ignition Facility's preamplifier module at the Lawrence Livermore National Laboratory. Photograph: Lawrence Livermore National Laboratory/Reuters

Nonlinear visco

## Goals and objectives

$$\mathbf{U} := (\rho(\mathbf{x}, t), \mathbf{m}(\mathbf{x}, t), E(\mathbf{x}, t), \mathbf{B}(\mathbf{x}, t))^{\top}, \quad (\mathbf{x}, t) \in \mathbb{R}^d \times \mathbb{R}^+$$

Density, momentum, total energy, magnetic field

### The ideal MHD equations

$$\partial_t \mathbf{U} + \nabla \cdot \mathbf{F}_{\mathcal{E}}(\mathbf{U}) + \nabla \cdot \mathbf{F}_{\mathcal{B}}(\mathbf{U}) = 0, \quad (1)$$

$$\mathbf{F}_{\mathcal{E}} := \begin{pmatrix} \mathbf{m} \\ \mathbf{m} \otimes \mathbf{u} + p\mathbb{I} \\ \mathbf{u}(E + p) \\ 0 \end{pmatrix}, \quad \mathbf{F}_{\mathcal{B}} := \begin{pmatrix} 0 \\ -\boldsymbol{\beta} \\ -\boldsymbol{\beta}\mathbf{u} \\ \mathbf{u} \otimes \mathbf{B} - \mathbf{B} \otimes \mathbf{u} \end{pmatrix},$$

$\boldsymbol{\beta}$  is the Maxwell stress tensor:

$$\boldsymbol{\beta} = \left( -\frac{1}{2}(\mathbf{B} \cdot \mathbf{B})\mathbb{I} + \mathbf{B} \otimes \mathbf{B} \right).$$

In addition:

$$\nabla \cdot \mathbf{B} = 0, \text{ and } p = \rho T,$$

where  $T$  is the temperature.

## Viscous fluxes

**Comparison between resistive and monolithic viscous fluxes:**  
( $\kappa, \eta, \epsilon$  are all positive constants,  $\tau$  is the stress tensor)

$$\mathbf{F}_V(\mathbf{U}) := \begin{pmatrix} 0 \\ \tau \\ \mathbf{u} \cdot \tau + \kappa \nabla T + \eta \mathbf{B} \cdot (\nabla \mathbf{B} - \nabla \mathbf{B}^\top) \\ \eta (\nabla \mathbf{B} - \nabla \mathbf{B}^\top) \end{pmatrix}$$

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$$\mathbf{F}_V(\mathbf{U}) := \begin{pmatrix} \epsilon \nabla \rho \\ \epsilon \nabla \mathbf{m} \\ \epsilon \nabla E \\ \epsilon \nabla \mathbf{B} \end{pmatrix}$$

## Goals and objective

- Investigate viscous regularization of the MHD system

$$\partial_t \mathbf{U} + \nabla \cdot \mathbf{F}_{\mathcal{E}}(\mathbf{U}) + \nabla \cdot \mathbf{F}_{\mathcal{B}}(\mathbf{U}) = \nabla \cdot (\epsilon \nabla \mathbf{U}),$$

where  $\epsilon > 0$ .

- **Investigate mathematically** if the above equation is compatible with thermodynamic properties, such as
  - positivity of density
  - positivity of internal energy
  - minimum entropy principle
- **Investigate numerically** if the above viscous regularization can be used to construct a stable and high-order method.

## Positivity of density and internal energy

### Theorem (D. & Nazarov 2022)

Assume the solution of the regularized MHD system is sufficiently smooth, and  $\mathbf{u}$ ,  $\nabla \cdot \mathbf{u}$  and  $\partial_t \rho + \nabla \cdot (\rho \mathbf{u})$  are bounded. Then, the density solution satisfies the following positivity property

$$\text{essinf}_{\mathbf{x} \in \mathbb{R}^d} \rho(\mathbf{x}, t) > 0, \quad \forall t > 0.$$

### Theorem (D. & Nazarov 2022)

The specific internal energy  $e$  and the internal energy  $\rho e$  of the regularized MHD system always remain positive given that the initial data fulfills  $e > 0$ .

## Minimum entropy principle

Theorem (D. & Nazarov 2022)

Assume sufficient smoothness and that the density and the internal energy uniformly converge to stationary constant states  $\rho^*, e^*$  outside of a compact set  $\Omega \in \mathbb{R}^d$ . The regularized MHD system exhibits a specific entropy function  $s$  which satisfies

$$\inf_{\boldsymbol{x} \in \mathbb{R}^d} s(\boldsymbol{x}, t) \geq \inf_{\boldsymbol{x} \in \mathbb{R}^d} s_0(\boldsymbol{x}).$$

Let  $f(s)$  is a twice differentiable function. Consider a class of strictly convex generalized entropies in the form  $\rho f(s)$ .

### Theorem (Dao & N. 2022)

*Any smooth solution to the regularized MHD system satisfies the entropy inequality*

$$\partial_t(\rho f(s)) + \nabla \cdot (\mathbf{u} \rho f(s) - \epsilon \rho \nabla f(s) - \epsilon f(s) \nabla \rho) \geq 0.$$

## Finite element approximation

- Let  $\Omega \subset \mathbb{R}^d$  be an open and bounded domain
- Define a triangulation  $\mathcal{T}_h := \{\overline{K_i}\}_{i=1}^{N_e} = \overline{\Omega}$ , where  $\overline{K_i}$  is the closure of  $K_i$ .
- Construct continuous finite element spaces:

$$\mathcal{Q}_h := \{v \in C^0(\overline{\Omega}) \mid v|_{K_i} \in \mathbb{P}_k(K_i), \forall i = 1, \dots, N_e\}, \quad \mathcal{V}_h := [\mathcal{Q}_h]^d.$$

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- Find  $\mathbf{U}_h(t) := (\rho_h(t), \mathbf{m}_h(t), E_h(t), \mathbf{B}_h(t))^\top \in \mathcal{C}^1(\mathbb{R}^+, \mathcal{Q}_h \times \mathcal{V}_h \times \mathcal{Q}_h \times \mathcal{V}_h)$  such that

$$\begin{aligned} & (\partial_t \mathbf{U}_h, \mathbf{V}_h) + (\nabla \cdot \mathbf{F}_{\mathcal{E}}(\mathbf{U}_h), \mathbf{V}_h) + (\nabla \cdot \mathbf{F}_{\mathcal{B}}(\mathbf{U}_h), \mathbf{V}_h) \\ & + (\mathbf{F}_{\mathcal{V}}^m(\mathbf{U}), \nabla \mathbf{V}_h) - (\mathbf{n} \cdot \mathbf{F}_{\mathcal{V}}^m(\mathbf{U}), \mathbf{V}_h)_{\partial\Omega} = 0, \end{aligned} \tag{2}$$

for all test functions  $\mathbf{V}_h \in \mathcal{Q}_h \times \mathcal{V}_h \times \mathcal{Q}_h \times \mathcal{V}_h$ ,

## Time-stepping and first-order viscosity

- Use 4th order Strong-Stability-Preserving Runge-Kutta scheme
- For every time-level  $t_n$  and every node  $N_i$  compute the largest eigenvalue of the MHD system:

$$\lambda_{\max,i}^n := \max_{j=1,8} |\lambda_{j,i}^n|.$$

- Define the time-step using the following CFL condition:

$$\Delta t_n := \text{CFL} \frac{\min_{N_i \in \mathcal{V}} h_i}{\max_{N_i \in \mathcal{V}} \lambda_{\max,i}^n}.$$

- Compute first order viscosity:

$$\epsilon_i^n := \frac{1}{2} h_i \lambda_{\max,i}^n.$$

## Divergence cleaning

- Consider  $\nabla \cdot \mathbf{B} \neq 0$  ?  $\longrightarrow$  add Powell term (Godunov form)
- Divergence cleaning: projection, hyperbolic cleaning (GLM-MHD)
- H-curl conforming elements for the magnetic field

## Numerical examples

Comparison between resistive and monolithic viscous fluxes:

$$\mathbf{F}_V^r(\mathbf{U}) := \begin{pmatrix} 0 \\ \boldsymbol{\tau} \\ \mathbf{u} \cdot \boldsymbol{\tau} + \kappa \nabla T + \eta \mathbf{B} \cdot (\nabla \mathbf{B} - \nabla \mathbf{B}^\top) \\ \eta (\nabla \mathbf{B} - \nabla \mathbf{B}^\top) \end{pmatrix}$$

$$\mathbf{F}_V(\mathbf{U}) := \begin{pmatrix} \epsilon \nabla \rho \\ \epsilon \nabla \mathbf{m} \\ \epsilon \nabla E \\ \epsilon \nabla \mathbf{B} \end{pmatrix}$$

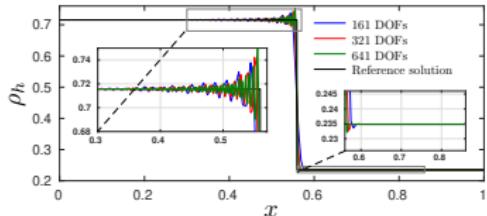
## Contact line problem

Consider the following initial condition:

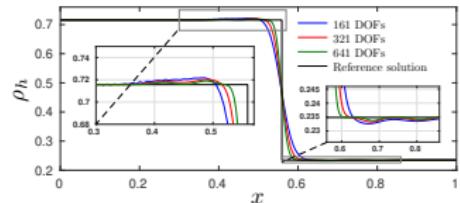
- Let the domain be  $\Omega = [0, 1]$ .
- The gas constant is  $\gamma = 2$ .
- The initial data:
  - velocity  $\mathbf{u} = (u_x, u_y)$ ,  $u_x = 0.5915470932$ ,  $u_y = -1.5792628803$
  - pressure  $p = 0.5122334291$
  - magnetic field  $\mathbf{B} = (B_x, B_y)$ ,  $B_x = 0.75$ ,  $B_y = -0.5349102426$
  - density

$$\rho = \begin{cases} 0.7156521382, & \mathbf{x} \in [0, 0.5], \\ 0.2348529760, & \mathbf{x} \in (0.5, 1]. \end{cases}$$

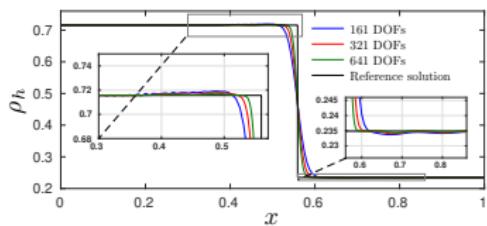
# Contact line problem



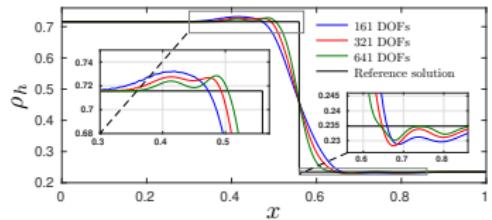
(a)  $\kappa = 0$



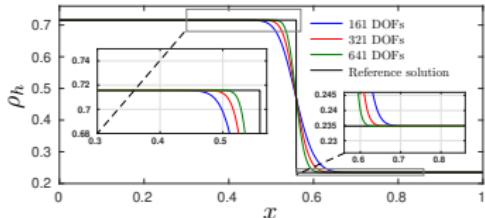
(b)  $\kappa = 1$



(c)  $\kappa = 0.5$



(d)  $\kappa = 5$



(e) monolithic

## Entropy viscosity

- For every time level  $t_n$  and every node  $N_i$  compute an entropy residual:

$$R_i^n(t) := \sum_{K \in \mathcal{T}_h} \frac{1}{|K|} \int_K |D_t S_h^n + \nabla \cdot (\mathbf{u}_h^n S_h^n)| \varphi_i \, d\mathbf{x},$$

where  $S_h^n$  is an entropy functional for the MHD system.

- Compute the low-order viscosity:

$$\epsilon_i^{\mathsf{L},n} := \frac{1}{2} h_i \lambda_{\max,i}^n.$$

- Compute the high-order viscosity:

$$\epsilon_i^{\mathsf{H},n} = c_E h_i^2 \frac{|R_i^n|}{\|\overline{R_h^n} - R_h^n\|_{\infty,\Omega}},$$

- Compute the entropy viscosity:

$$\epsilon_i^n = \min(\epsilon_i^{\mathsf{L},n}, \epsilon_i^{\mathsf{H},n}).$$

## Convergence test on a smooth problem

Smooth wave propagation, [Wu and Shu, 2018].

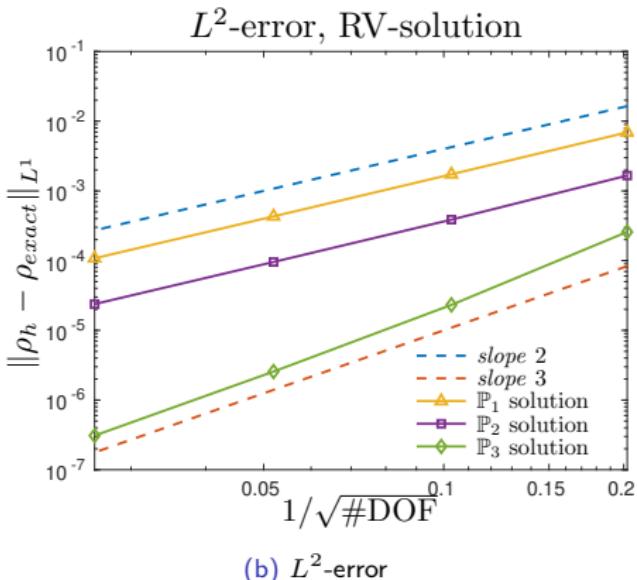
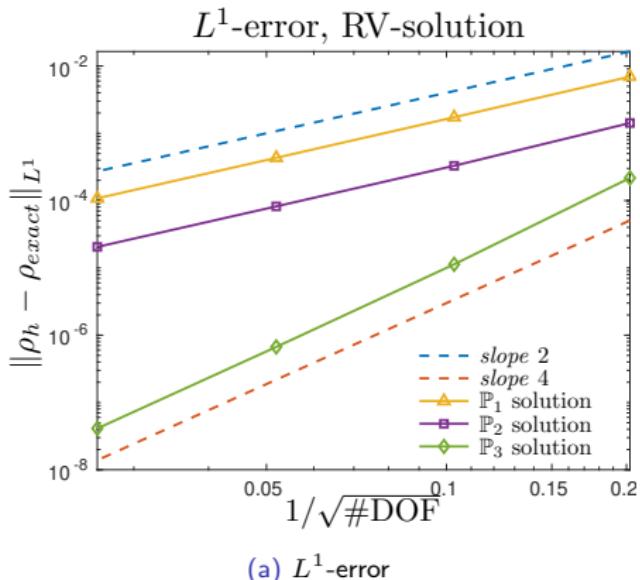


Figure:  $\mathbb{P}_1$ ,  $\mathbb{P}_2$ ,  $\mathbb{P}_3$  convergence for smooth solutions.

## Brio-Wu shock-tube using entropy viscosity

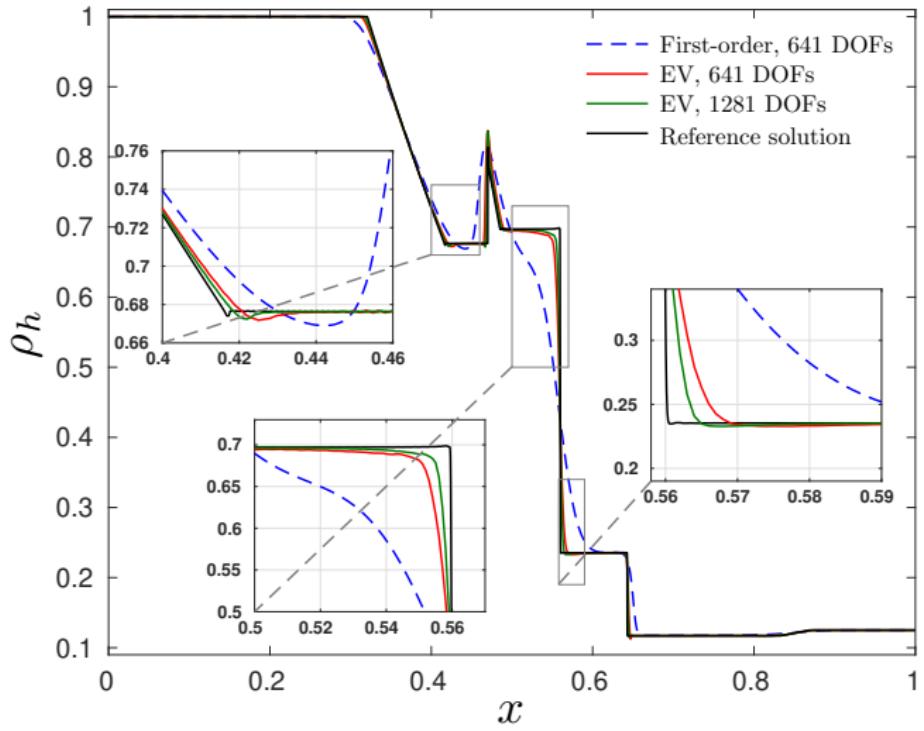


Figure:  $\hat{t} = 0.1$ .

## Orszag-Tang problem

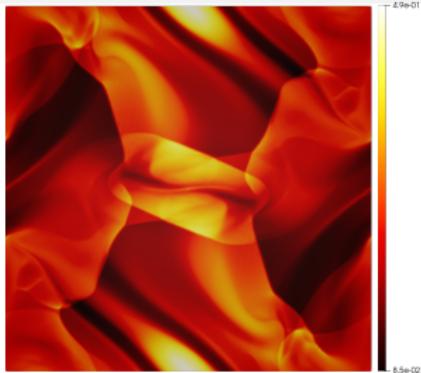
Consider the following initial condition:

- Let the domain be  $\Omega = [0, 1] \times [0, 1]$ .
- The gas constant is  $\gamma = \frac{5}{3}$ .
- The initial data:

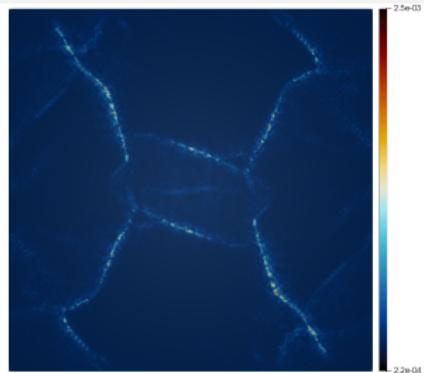
$$(\rho_0, \mathbf{u}_0, p_0, \mathbf{B}_0) = \left( \frac{25}{36\pi}, (-\sin(2\pi y), \sin(2\pi x)), \frac{5}{12\pi}, \left( -\frac{\sin(2\pi y)}{\sqrt{4\pi}}, \frac{\sin(4\pi x)}{\sqrt{4\pi}} \right) \right).$$

- Final time:  $\hat{t} = 1$ .

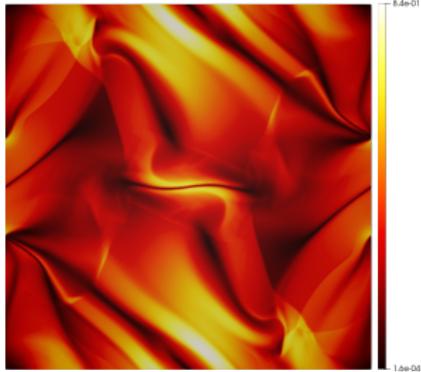
## Orszag-Tang problem



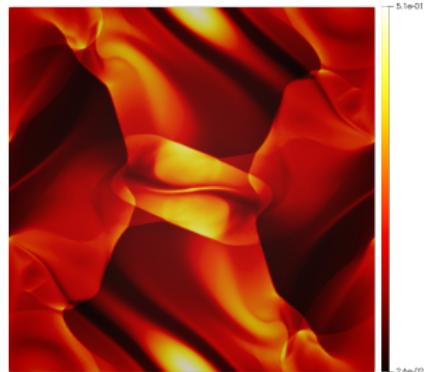
(a) Density  $\rho_h$



(b) Entropy viscosity  $\mu_h$



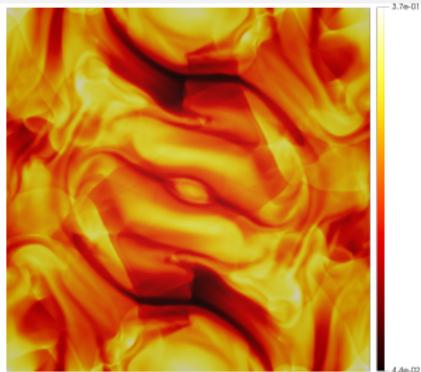
(c) Magnetic pressure  $\frac{1}{2} \mathbf{B}_h^2$



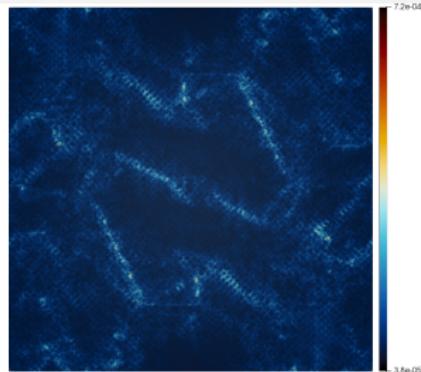
(d) Thermodynamic pressure  $p_h$

Entropy viscosity solution of the Orszag-Tang problem at time  $\hat{t} = 0.5$ , 90000  $\mathbb{P}_3$  nodes.

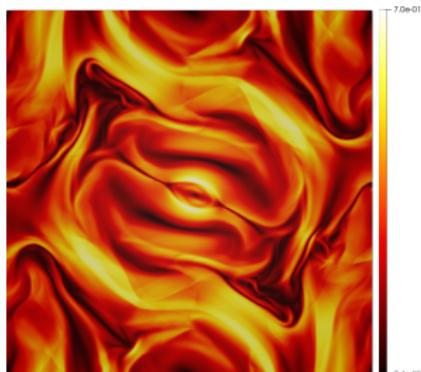
## Orszag-Tang problem



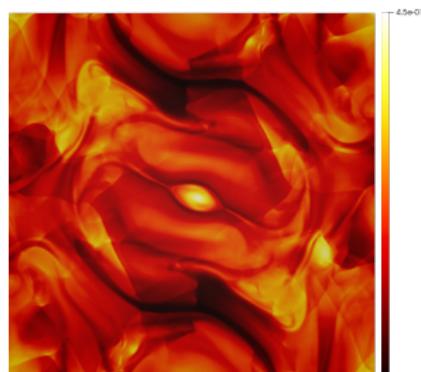
(a) Density  $\rho_h$



(b) Entropy viscosity  $\mu_h$



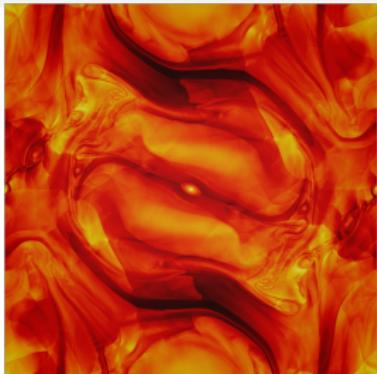
(c) Magnetic pressure  $\frac{1}{2} B_h^2$



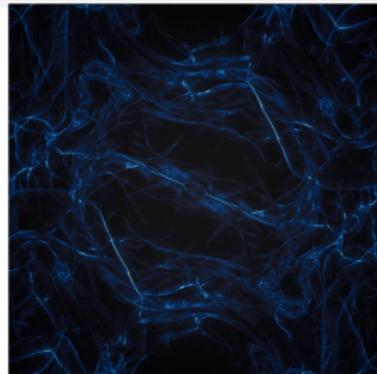
(d) Thermodynamic pressure  $p_h$

Entropy viscosity solution of the Orszag-Tang problem at time  $\hat{t} = 1$ , 90000  $\mathbb{P}_3$  nodes.

## Orszag-Tang problem



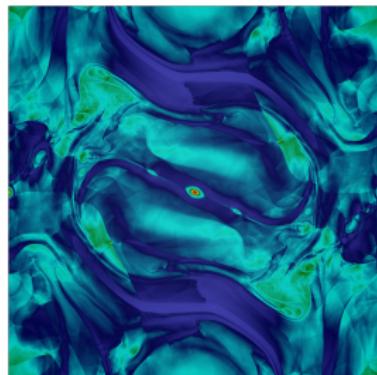
(a) Density  $\rho_h$



(b) Entropy viscosity  $\mu_h$



(c) Magnetic pressure  $\frac{1}{2} B_h^2$



(d) Thermodynamic pressure  $p_h$

Entropy viscosity solution of the Orszag-Tang problem at time  $\hat{t} = 1$ , 20mln  $\mathbb{P}_3$  nodes.

Thank you!



[D. & Nazarov, CMAME, 2022]



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