## HUST

ĐẠI HỌC BÁCH KHOA HÀ NỘI HANOI UNIVERSITY OF SCIENCE AND TECHNOLOGY

ONE LOVE. ONE FUTURE.





#### ĐẠI HỌC BÁCH KHOA HÀ NỘI HANOI UNIVERSITY OF SCIENCE AND TECHNOLOGY

# FUNDAMENTALS OF OPTIMIZATION

Modelling

ONE LOVE. ONE FUTURE.

#### **Outline**

- Modelling a Combinatorial Optimization Problem
  - Combinatorial Optimization Problem
  - N-Queen problem
  - Sudoku problem
  - Balanced Class Teacher Assignment Problem
  - Class Allocation Problem
  - Traveling Salesman Problem
  - Exercise
- Backtracking algorithm



#### **Combinatorial Optimization Problem**

Find a solution (usually a combinatorial configuration) that satisfies a given set of constraints while simultaneously optimizing one or more specified objective functions.

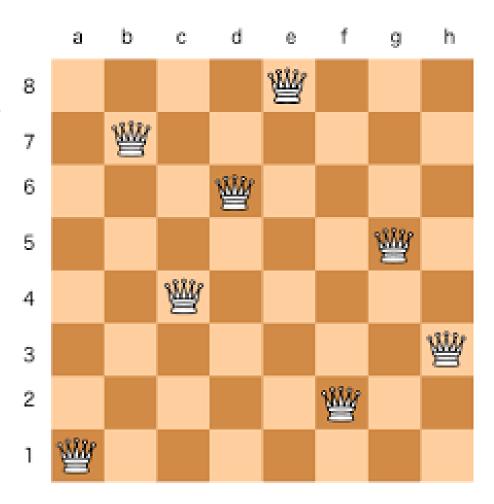
- Constraint Satisfaction Problem (CSP) = (X, D, C)
  - $X = \{x_1, ..., x_n\}$ , set of variables
  - $D = \{D_1, ..., D_n\}$ , domains of the variables
  - $C = \{C_1, \dots, C_k\}$ , set of constraints
- Combinatorial Optimization Problem (COP) = (X, D, C, f)
  - $X = \{x_1, ..., x_n\}$ , set of variables
  - $D = \{D_1, \dots, D_n\}$ , domains of the variables
  - $C = \{C_1, \dots, C_k\}$ , set of constraints
  - *f*: objective function



#### **Example: Constraint Satisfaction Problem**

#### Problem N-Queen, CSP = (X, D, C)

- Variables:  $X = \{x_1, ..., x_n\}$ , in which  $x_i$  is the row of the queen in column  $i, \forall i \in \{1, ..., n\}$
- Domains:  $D_i = D(x_i) = \{1, ..., n\}, \forall i \in \{1, ..., n\}$
- Constraints: For all pair (i, j),  $1 \le i < j \le n$ :
  - $x_i \neq x_j$
  - $x_i + i \neq x_j + j$
  - $x_i i \neq x_j j$





#### **Example: Constraint Satisfaction Problem**

#### Sudoku Problem, CSP = (X, D, C)

- Variables:  $X = \{x_{1,1}, ..., x_{9,9}\}$ , where  $x_{i,j}$  is the value in cell  $(i, j), \forall i, j \in \{1, 2, ..., 9\}$
- **Domain**:  $D(x_{i,j}) = \{1, ..., 9\}, \forall i, j \in \{1, 2, ..., 9\}$
- Constraints:
  - The numbers in each column are pairwise distinct:

$$x_{i_1 j} \neq x_{i_2 j}$$
 for all  $1 \le i_1 < i_2 \le 9$ ,  $1 \le j \le 9$ 

• The numbers in each row are pairwise distinct:

$$x_{ji_1} \neq x_{ji_2}$$
 for all  $1 \le i_1 < i_2 \le 9$ ,  $1 \le j \le 9$ 

• The numbers in each 3x3 subgrid are pairwise distinct:  $x_{3i+i_1,3j+j_1} \neq x_{3i+i_2,3j+j_2}$  for all  $0 \leq i,j \leq 2, 1 \leq i_1,i_2,j_1,j_2 \leq$  satisfying  $(i_1,j_1) \neq (i_2,j_2)$ 

5	3	4	6	7	8	9	1	2
6	7	2	1	0	5	თ	4	8
1	9	8	ო	4	2	5	6	7
8	5	9	7	6	1	4	2	3
4	2	6	8	5	ω	7	9	1
7	1	3	9	2	4	8	5	6
9	6	1	5	М	7	2	8	4
2	8	7	4	1	9	6	3	5
3	4	5	2	8	6	1	7	9



- There are n classes labeled 1, 2, ..., n that have already been scheduled in a timetable, and they need to be assigned to m teachers labeled 1, 2, ..., m
- Each class i has T(i), a list of teachers who can teach it  $(i = \{1, ..., n\})$ , and c(i), the number of credits for the subject of that class.
- Since the timetable has been pre-arranged, there exists a set Q of pairs of classes (i, j) that are scheduled at the same time (these two classes cannot be assigned to the same teacher).
- Find an assignment of classes to teachers such that the maximum total number of credits assigned to any one teacher is minimized.



#### Example

Class	0	1	2	3	4	5	6	7	8	9	10	11	12
Credit	3	3	4	3	4	3	3	3	4	3	3	4	4

Teacher	List of classes that the teach can teach
0	0, 2, 3, 4, 8, 10
1	0, 1, 3, 5, 6, 7, 8
2	1, 2, 3, 7, 9, 11, 12

#### List Q

0	2
0	4
0	8
1	4
1	10
3	7
3	9
5	11
5	12
6	8
6	12



#### Example

Class	0	1	2	3	4	5	6	7	8	9	10	11	12
Credit	3	3	4	3	4	3	3	3	4	3	3	4	4

Teacher	List of classes that the teach can teach
0	0, 2, 3, 4, 8, 10
1	0, 1, 3, 5, 6, 7, 8
2	1, 2, 3, 7, 9, 11, 12

**Assignment solution** 



Teacher	List of classes assigned to the teacher	<b>Total credits</b>
0	2, 4, 8, 10	15
1	0, 1, 3, 5, 6	15
2	7, 9, 11, 12	14

#### List Q

0	2
0	4
0	8
1	4
1	10
3	7
3	9
5	11
5	12
6	8
6	12

#### Input:

- Set of classes:  $S = \{1, ..., n\}$
- Set of teachers:  $T = \{1, \dots, m\}$
- Set of conflict classes:  $Q = \{(i_1, j_1), ..., (i_k, j_k) | i_1, ..., i_k, j_1, ..., j_k \in C, i_t \neq j_t \ \forall t \in \{1, ..., k\}\}$
- Set of teachers who can give some class  $T = \{T_1, ..., T_n\}$ , in which  $T_i$  is the set of teachers who can give the class i ( $i \in \{1, ..., n\}$ )
- For each class i  $(i \in \{1, ..., n\}), c(i)$  is its number of credit  $(c(i) \in N)$

#### • Variables:

- Binary variable x<sub>ij</sub> (i ∈ C, j ∈ T) is equal to 1 if the class i is assigned to the teacher j, otherwise the value of this variable is equal to 0;
- Integral variable maxcredit represents the

maximum number of credits for a teacher;

- Domains of variables:
  - $D(x_{ij}) = \{0, 1\}, \forall i \in C, j \in T$
  - $D(maxcredit) = \{0, \dots, \sum_{i \in C} c(i)\}$
- Constraints:
  - Each class is assigned to one teacher  $\sum_{j \in T_i} x_{ij} = 1$ ,  $\forall i \in C$
  - Teacher is not assigned to a class that he cannot teach  $x_{ij} = 0, \forall i \in C, j \notin T_i$
  - Teacher cannot give two classes in the conflict set  $x_{i_1j} + x_{i_2j} \le 1, \forall j \in T, (i_1, i_2) \in Q$
  - Relation between variable maxcredit and workload of teacher  $\sum_{i \in C} c(i)x_{ij} \leq maxcredit$ ,  $\forall j \in T$
- Objective: *Minimize maxcredit*



- n classes labeled by 1, 2, ..., n need to be allocated in p semesters 1, 2, ..., p. Each class i has a credit value of c(i), and its prerequisite conditions are defined by a set Q of pairs (i, j), where subject i must be taken before j. Given the constant  $\alpha, \beta, \delta, \gamma$ , it is necessary to determine an allocation plan that satisfies the following:
  - The total number of classes assigned to each semester must be greater than or equal to  $\alpha$  and less than or equal to  $\beta$ .
  - The total number of credits of the classes assigned to each semester must be greater than or equal to  $\delta$  and less than or equal to  $\gamma$
  - For each pair  $(i,j) \in Q$ , class i must be scheduled in a semester prior to the semester in which class j is scheduled.
- Objective: The maximum number of credits in any one semester must be minimized.



#### Example

Class	1	2	3	4	5	6	7	8	9	10	11	12
Number of credits	2	1	2	1	3	2	1	3	2	3	1	3

3 ≤ Number of classes in each semester ≤ 3

5 ≤ Number of credits in each semester ≤ 7

#### Set Q

1
9
6
8
11
12
7
10
7
11
12



#### Example

Class	1	2	3	4	5	6	7	8	9	10	11	12
Number of credits	2	1	2	1	3	2	1	3	2	3	1	3

- 3 ≤ Number of classes in each semester ≤ 3
- 5 ≤ Number of credits in each semester ≤ 7

Allocation solution



Semester	1	2	3	4
List of classes	2, 5, 3	1, 6,10	4,7,8	9,11,12

#### Set Q

2	1
6	9
5	6
5	8
4	11
6	12
2	7
3	10
5	7
8	11
4	12



#### Input:

- Set of classes:  $C = \{1, ..., n\}$
- Set of semesters:  $S = \{1, ..., p\}$
- Set of precedent classes:  $Q = \{(i_1, j_1), ..., (i_k, j_k) | i_1, ..., i_k, j_1, ..., j_k \in C, i_t \neq j_t \ \forall t \in \{1, ..., k\}\}$
- Constant  $\alpha$ ,  $\beta$ ,  $\delta$ ,  $\gamma$

#### Variables:

- Binary variable  $x_{ij}$  ( $i \in C, j \in S$ ) is equal to 1 if the class i is assigned to the semester j, otherwise the value of this variable is equal to 0;
- Integral variable *maxcredit* represents the maximum number of credits for a semester

#### Constraints:

- Every class is allocated to some semester  $\sum_{i \in S} x_{ij} = 1, \forall i \in C$
- Number of classes in a semester must be in a range of  $[\alpha, \beta]$ , it means that  $\alpha \le \sum_{i \in C} x_{ij} \le \beta, \forall j \in S$
- Number of credits in a semester must be in a range of  $[\delta, \gamma]$ , it means that  $\delta \leq \sum_{i \in C} c(i)x_{ij} \leq \gamma$
- For each pair  $(i_1, i_2) \in Q$ , class  $i_1$  must be scheduled in a semester prior to the semester in which class  $i_2$  is scheduled  $\sum_{j \in S} j x_{i_1 j} < \sum_{j \in S} j x_{i_2 j}$ ,  $\forall (i_1, i_2) \in Q$
- Relation between variable maxcredit and workload in a semester  $\sum_{i \in C} c(i)x_{ij} \leq maxcredit$ ,  $\forall j \in S$
- Objective: *Minimize maxcredit*



#### **Traveling Salesman Problem**

• A traveler starts from city 1 and needs to visit cities 2, 3, ..., n, passing through each city exactly once before returning to the starting city. The cost of traveling from city i to city j is c(i,j). Calculate the plan for the traveler that results in the minimum total cost.

#### **Traveling Salesman Problem**

- Input:
  - *n* number of cities
  - c(i,j) traveling cost from the city i to the city j
- Variables:
  - Binary variable  $x_{ij}$  with  $i, j \in \{1, ..., n\}$ ,  $i \neq j$  is equal to 1 if the traveler go from the city i to the city j in the optimal plan, otherwise the value of this variable is equal to 0;
- Constraints:
  - For each city, the traveler goes in once and goes out once

$$\sum_{j \in \{1, \dots, n\}} x_{ij} = \sum_{j \in \{1, \dots, n\}} x_{ji} = 1, \forall i \in \{1, \dots, n\}$$

No subtour

$$\sum_{i,j\in S, i\neq j} x_{ij} \leq |S|-1, \forall S \subset \{1,\dots,n\}$$

• Objective:  $Minimize \sum_{i,j \in \{1,...,n\}, i \neq j} c(i,j) x_{ij}$ 

#### **Exercises**

Modelling the problem in your mini-project



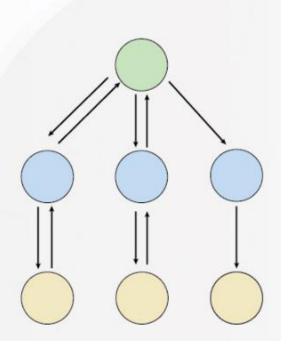
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#### **Backtracking Algorithm**

- Backtracking is a problem-solving algorithmic technique that involves finding a solution incrementally by trying different options and undoing them if they lead to a dead end. It is commonly used in situations where you need to explore multiple possibilities to solve a problem, like searching for a path in a maze or solving puzzles like Sudoku. When a dead end is reached, the algorithm backtracks to the previous decision point and explores a different path until a solution is found or all possibilities have been exhausted.
- Backtracking can be defined as a general algorithmic technique that considers searching every possible combination in order to solve a computational problem.

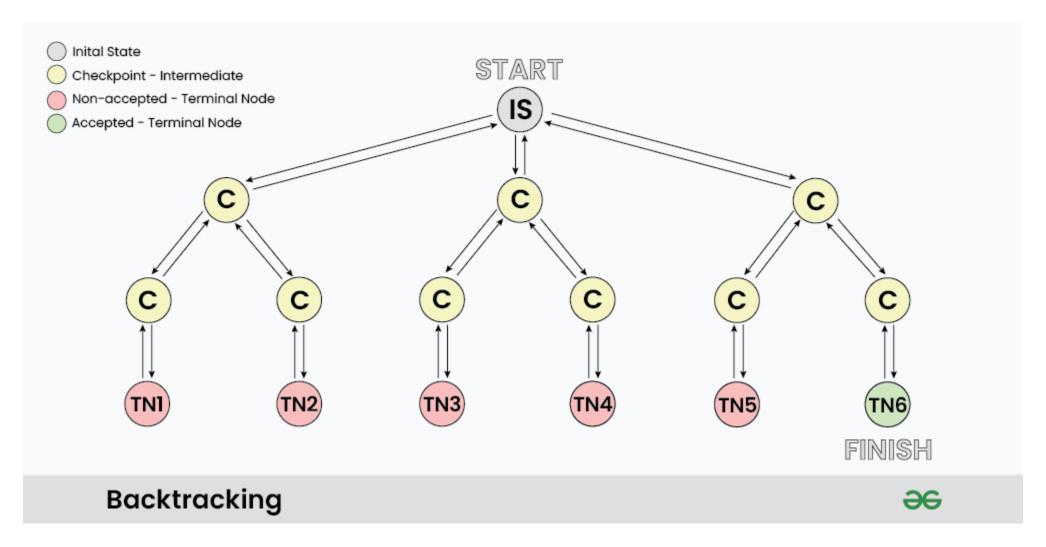


#### **Backtracking Algorithm**

- Candidate: A candidate is a potential choice or element that can be added to the current solution.
- **Solution**: The solution is a valid and complete configuration that satisfies all problem constraints.
- Partial Solution: A partial solution is an intermediate or incomplete configuration being constructed during the backtracking process.
- **Decision Space**: The decision space is the set of all possible candidates or choices at each decision point.
- Decision Point: A decision point is a specific step in the algorithm where a candidate is chosen and added to the partial solution.

- Feasible Solution: A feasible solution is a partial or complete solution that adheres to all constraints.
- **Dead End**: A dead end occurs when a partial solution cannot be extended without violating constraints.
- Backtrack: Backtracking involves undoing previous decisions and returning to a prior decision point.
- Search Space: The search space includes all possible combinations of candidates and choices.
- Optimal Solution: In optimization problems, the optimal solution is the best possible solution.

#### **Backtracking Algorithm**





#### Recursive Technique for Backtracking Algorithm

```
TRY(k)
  Begin
    Foreach \nu in A_k
     if check(v,k) /* Check for feasibility of assigning v to x_k */
       Begin
         X_b = V;
         [Update data structure D]
         if (k = n) save a feasible solution;
         else TRY(k+1);
         [Recovery D]
       End
  End
Main()
Begin
 TRY(1);
End
```

#### Generate binary string

```
n = 3
x = [-1] * n
def Try(k):
    if k == n:
        print(x)
    else:
        for i in range(2):
            x[k] = i
            Try(k+1)
Try(0)
```

```
[0, 0, 0]
[0, 0, 1]
[0, 1, 0]
[0, 1, 1]
[1, 0, 0]
[1, 0, 1]
[1, 1, 0]
[1, 1, 1]
```

#### Generate permutation of a set

```
n = 3
x = [-1] * n
visited = [False] * (n)
def Try(k):
    if k == n:
        print(x)
        return
    for i in range(0, n):
        if visited[i] == True:
            continue
        x[k] = i
        visited[i] = True
        Try(k+1)
        visited[i] = False
Try(0)
```

```
[0, 1, 2]
[0, 2, 1]
[1, 0, 2]
[1, 2, 0]
[2, 0, 1]
[2, 1, 0]
```



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### THANK YOU!