view_frames Result Recorded at time: 35.305 map Broadcaster: /rtabmap/rtabmap Average rate: 20.283 Hz Most recent transform: 35.359 (-0.054 sec old) Buffer length: 3.599 sec odom Broadcaster: /gazebo Average rate: 10.281 Hz Most recent transform: 35.301 (0.004 sec old) Buffer length: 3.599 sec robot_footprint Broadcaster: /robot_state_publisher Average rate: 10000.000 Hz Most recent transform: 0.000 (35.305 sec old) Buffer length: 0.000 sec chassis Broadcaster: /robot_state_publisher Broadcaster: /robot_state_publisher

RGBD_camera hokuyo Broadcaster: /robot_state_publisher Average rate: 10000.000 Hz Most recent transform: 0.000 (35.305 sec old) Buffer length: 0.000 sec Depth_camera

Broadcaster: /robot_state_publisher

Average rate: 10000.000 Hz

Most recent transform: 0.000 (35.305 sec old)

Buffer length: 0.000 sec

Broadcaster: /robot_state_publisher Average rate: 10.281 Hz Average rate: 10000.000 Hz Most recent transform: 0.000 (35.305 sec old) Most recent transform: 35.300 (0.005 sec old) Buffer length: 0.000 sec Buffer length: 3.599 sec

left_wheel

Buffer length: 3.599 sec

Average rate: 10.281 Hz Most recent transform: 35.300 (0.005 sec old)

right_wheel