Near-consistent robust estimations of moments for unimodal distributions

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Descriptive statistics for parametric models currently heavily rely on the accuracy of distributional assumptions. Here, leveraging the invariant structures of unimodal distributions, a series of sophisticated yet efficient estimators, robust to both gross errors and departures from parametric assumptions, are proposed for estimating mean and central moments for common unimodal distributions. This article also illuminates the understanding of the common nature of probability distributions and the measures of them.

orderliness | invariant | unimodal | adaptive estimation | U-statistics

The potential biases of robust location estimators in estimating the population mean have been noticed for more than two centuries (1), with numerous significant attempts made to address them. In calculating a robust location estimator, the procedure of identifying and downweighting extreme values inherently necessitates the formulation of certain distributional assumptions. Biases natually arise when these assumptions, parametric or semiparametric, are violated. Previously, it was demonstrated that, due to the presence of infinite-dimensional nuisance shape parameters, the semiparametric approach struggles to consistently address distributions with shapes more intricate than γ-symmetry. Newcomb (1886) provided the first modern approach to robust parametric estimation by developing a class of estimators that gives "less weight to the more discordant observations" (2). In 1964, Huber (3) used the minimax procedure to obtain M-estimator for the contaminated normal distribution, which has played a pre-eminent role in the later development of robust statistics. However, as previously demonstrated, under growing asymmetric departures from normality, the bias of the Huber M-estimator increases rapidly. This is a common issue in parametric robust statistics. For example, He and Fung (1999) constructed (4) a robust M-estimator for the two-parameter Weibull distribution, from which all moments can be calculated. Nonetheless, it is inadequate for other parametric distributions, e.g., the gamma, Perato, lognormal, and the generalized Gaussian distributions (SI Dataset S1). Another interesting approach is based on L-estimators, such as percentile estimators. For examples of percentile estimators for the Weibull distribution, the reader is referred to the works of Menon (1963) (5), Dubey (1967) (6), Marks (2005) (7), and Boudt, Caliskan, and Croux (2011) (8). At the outset of the study of percentile estimators, it was known that they arithmetically utilize the invariant structures of probability distributions (5, 6). An estimator is classified as an I-statistic if it asymptotically satisfies $I\left(\mathrm{LE}_1, \ldots, \mathrm{LE}_l\right) = (\theta_1, \ldots, \theta_q)$ for the distribution it is consistent, where LEs are calculated with the use of LU-statistics (defined in Subsection A), I is defined using arithmetic operations and constants but may also incorporate transcendental functions and quantile functions, and θs are the population parameters it estimates. In this article, two subclasses of I-statistics are introduced, recombined

I-statistics and quantile I-statistics. Based on LU-statistics, I-statistics are naturally robust. Compared to probability density functions (pdfs) and cumulative distribution functions (cdfs), the quantile functions of many parametric distributions are more elegant. Since the expectation of an L-estimator can be expressed as an integral of the quantile function, I-statistics are often analytically obtainable. However, it is observed that even when the sample follows a gamma distribution, which belongs to the same larger family as the Weibull model, the generalized gamma distribution, a misassumption can still lead to substantial biases in Marks percentile estimator (7), rendering the approach ill-suited (SI Dataset S1).

On the other hand, while robust estimation of scale has also been intensively studied with established methods (9, 10), the development of robust measures of asymmetry and kurtosis lags behind, despite the availability of several approaches (11–15). The purpose of this paper is to demonstrate that, in light of previous works, the estimation of central moments can be transformed into a location estimation problem by using U-statistics, the central moment kernel distributions possess desirable properties, and by utilizing the invariant structures of unimodal distributions, a suite of robust estimators can be constructed whose biases are typically smaller than the variances (as seen in Table **??** for $n = 4096$).

A. Robust Estimations of the Central Moments. In 1979, Bickel and Lehmann (10), in their final paper of the landmark series *Descriptive Statistics for Nonparametric Models*, generalized a class of estimators called measures of spread, which "do not require the assumption of symmetry." From this, a popular efficient scale estimator, the Rousseeuw-Croux scale estimator (16), was derived in 1993, but the importance of tackling the symmetry assumption has been greatly underestimated. While they had already considered one version of the trimmed standard deviation, which is a measures of dispersion, in the third paper of that series (9); in the final section of that paper (10), they explored another two versions of the trimmed standard deviation based on pairwise differences, one is modified here

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Significance Statement

Bias, variance, and contamination are the three main errors in statistics. Consistent robust estimation is unattainable without parametric assumptions. In this article, invariant moments are proposed as a means of achieving near-consistent and robust estimations of moments, even in scenarios where moderate violations of distributional assumptions occur, while the variances are sometimes smaller than those of the sample moments.

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for comparison,

$$\left[\binom{n}{2} (1-\epsilon-\gamma\epsilon) \right]^{-\frac{1}{2}} \left[\sum_{i=\binom{n}{2}\gamma\epsilon}^{\binom{n}{2}(1-\epsilon)} \left(X - X' \right)_i^{\,2} \right]^{\frac{1}{2}}, \quad [1]$$

where $(X - X')_1 \leq \ldots \leq (X - X')_{\binom{n}{2}}$ are the order statistics of the pseudo-sample, $X_i - X_j$, $i < j$. Let $\Delta = X_i - X_j$. They showed that, when $\epsilon = 0$, [1] is $\sqrt{2}$ times the standard deviation. The paper ended with, "We do not know a fortiori which of the measures is preferable and leave these interesting questions open."

To address their open question, the nomenclature used in this paper is introduced as follows:

Nomenclature. Given a robust estimator $\hat{\theta}$, which has an adjustable breakdown point that can approach zero asymptotically, the name of $\hat{\theta}$ comprises two parts: the first part denotes the type of estimator, and the second part is the name of the population parameter θ that the estimator approaches as $\epsilon \to 0$. The abbreviation of the estimator combines the initial letters of the first part and the population parameter. If the estimator is symmetric, the upper asymptotic breakdown point, ϵ (defined in Subsection **??**, or $\epsilon_{U_\mathbf{k}}$ for LU-statistic), is indicated in the subscript of the abbreviation of the estimator, with the exception of the median. For an asymmetric estimator based on quantile average, the associated γ follows ϵ.

In the previous article on semiparametric robust mean estimation, it was shown that the bias of a robust estimator with an adjustable breakdown point is often monotonic with respect to the breakdown point in a semiparametric distribution. Naturally, the estimator's name should reflect the population parameter that it approaches as $\epsilon \to 0$. If multiplying all pseudo-samples by a factor of $\frac{1}{\sqrt{2}}$, then [1] is the trimmed standard deviation adhering to this nomenclature, since $\psi_2(x_1, x_2) = \frac{1}{2}(x_1 - x_2)^2$ is the kernel function of the unbiased estimation of the second central moment by using U-statistic. It should be preferable, not only because it is the square root of a trimmed U-statistic, which is closely related to the minimum-variance unbiased estimator (MVUE), but also because the second γ-orderliness of the second central moment kernel distribution is ensured by the next exciting theorem.

Theorem A.1. *The second central moment kernel distribution generated from any unimodal distribution is second γ-ordered.*

Proof. In 1954, Hodges and Lehmann established that if X and Y are independently drawn from the same unimodal distribution, $X - Y$ will be a symmetric unimodal distribution peaking at zero [17]. Given the constraint in the pseudo-sample that $X_i < X_j$, $i < j$, it directly follows from Theorem 1 in [17] that the pairwise difference distribution (Ξ_Δ) generated from any unimodal distribution is always monotonic increasing with a mode at zero. The transformation of the pairwise difference distribution via squaring and multiplication by $\frac{1}{2}$ does not change the monotonicity, making the pdf to become monotonically decreasing with a mode at zero. In the previous article, it was proven that a right-skewed distribution with a monotonic decreasing pdf is always second γ-ordered, which gives the desired result. $\qquad\square$

Previously, it was shown that any γ-symmetric distribution is νth γ-ordered, suggesting that νth γ-orderliness does not require unimodality, e.g., a symmetric bimodal distribution is also νth ordered. An analysis of the Weibull distribution showed that unimodality does not assure orderliness. Theorem A.1 uncovers a profound relationship between unimodality and second γ-orderliness, which is sufficient for γ-trimming inequality and γ-orderliness.

In 1928, Fisher constructed $\mathbf{k}$-statistics as unbiased estimators of cumulants [18]. Halmos (1946) proved that a functional θ admits an unbiased estimator if and only if it is a regular statistical functional of degree $\mathbf{k}$ and showed a relation of symmetry, unbiasness and minimum variance [19]. Hoeffding, in 1948, generalized U-statistics [20] which enable the derivation of a minimum-variance unbiased estimator from each unbiased estimator of an estimable parameter. In 1984, Serfling pointed out the speciality of Hodges-Lehmann estimator, which is neither a simple L-statistic nor a U-statistic, and considered the generalized L-statistics and trimmed U-statistics [21]. Given a kernel function $h_\mathbf{k}$ which is a symmetric function of $\mathbf{k}$ variables, the LU-statistic is defined as:

$$LU_{h_\mathbf{k}, \mathbf{k}, k, \epsilon_{U_\mathbf{k}}, \gamma, n} \coloneqq LL_{k, \epsilon, \gamma, n}\left(\left(h_\mathbf{k}\left(X_{N_1}, \ldots, X_{N_\mathbf{k}}\right) \right)_{N=1}^{\binom{n}{\mathbf{k}}} \right),$$

where $\epsilon_{U_\mathbf{k}} = 1 - (1-\epsilon)^{\frac{1}{\mathbf{k}}}$ (proven in Subsection **??**), $X_{N_1}, \ldots, X_{N_\mathbf{k}}$ are the n choose $\mathbf{k}$ elements from the sample, $LL_{k, \epsilon, \gamma, n}(Y)$ denotes the LL-statistic with the sequence $\left(h_\mathbf{k}\left(X_{N_1}, \cdots, X_{N_\mathbf{k}}\right) \right)_{N=1}^{\binom{n}{\mathbf{k}}}$ serving as an input. In the context of Serfling's work, the term 'trimmed U-statistic' is used when $LL_{k, \epsilon, \gamma, n}$ is the trimmed mean [21].

In 1997, Heffernan [22] obtained an unbiased estimator of the $\mathbf{k}$th central moment by using U-statistics and demonstrated that it is the minimum variance unbiased estimator for distributions with the finite first $\mathbf{k}$ moments. The weighted Hodges-Lehmann $\mathbf{k}$th central moment ($2 \leq \mathbf{k} \leq n$) is thus defined as,

$$\mathrm{WHL}km_{k, \epsilon_{U_\mathbf{k}}, \gamma, n} \coloneqq LU_{h_\mathbf{k}=\psi_\mathbf{k}, \mathbf{k}, k, \epsilon_{U_\mathbf{k}}, \gamma, n},$$

where $\mathrm{WHLM}_{k, \epsilon, \gamma, n}$ is used as the $LL_{k, \epsilon, \gamma, n}$ in LU, $\psi_\mathbf{k}(x_1, \ldots, x_\mathbf{k}) = \sum_{j=0}^{\mathbf{k}-2} (-1)^j \left(\frac{1}{\mathbf{k}-j} \right) \sum \left(x_{i_1}^{\mathbf{k}-j} x_{i_2} \ldots x_{i_{j+1}} \right) + (-1)^{\mathbf{k}-1} (\mathbf{k}-1) x_1 \ldots x_\mathbf{k}$, the second summation is over $i_1, \ldots, i_{j+1} = 1$ to $\mathbf{k}$ with $i_1 \neq i_2 \neq \ldots \neq i_{j+1}$ and $i_2 < i_3 < \ldots < i_{j+1}$ [22]. Despite the complexity, the following theorem offers an approach to infer the general structure of such kernel distributions.

Theorem A.2. *Define a set T comprising all pairs $(\psi_\mathbf{k}(\mathbf{v}), f_{X,\ldots,X}(\mathbf{v}))$ such that $\psi_\mathbf{k}(\mathbf{v}) = \psi_\mathbf{k}(Q(p_1), \ldots, Q(p_\mathbf{k}))$ with $Q(p_1) < \ldots < Q(p_\mathbf{k})$ and $f_{X,\ldots,X}(\mathbf{v}) = \mathbf{k}! f(Q(p_1)) \ldots f(Q(p_\mathbf{k}))$ is the probability density of the $\mathbf{k}$-tuple, $\mathbf{v} = (Q(p_1), \ldots, Q(p_\mathbf{k}))$ (a formula drawn after a modification of the Jacobian density theorem). T_Δ is a subset of T consisting all those pairs for which the $\mathbf{k}$-tuples satisfy that $\Delta = Q(p_1) - Q(p_\mathbf{k})$. A quasi-distribution, denoted by ξ_Δ, has a pdf $f_{\xi_\Delta}(\bar{\Delta}) = \sum_{\substack{(\psi_\mathbf{k}(\mathbf{v}), f_{X,\ldots,X}(\mathbf{v})) \in T_\Delta \\ \bar{\Delta}=\psi_\mathbf{k}(\mathbf{v})}} f_{X,\ldots,X}(\mathbf{v})$, i.e., sum over all $f_{X,\ldots,X}(\mathbf{v})$ such that the pair $(\psi_\mathbf{k}(\mathbf{v}), f_{X,\ldots,X}(\mathbf{v}))$ is in the set T_Δ and the first element of the pair, $\psi_\mathbf{k}(\mathbf{v})$, is equal to $\bar{\Delta}$. The $\mathbf{k}$th, where $\mathbf{k} > 2$, central moment kernel distribution,*

labeled $\Xi_{\mathbf{k}}$, can be seen as a quasi-mixture distribution comprising an infinite number of component quasi-distributions, $\xi_\Delta s$, each corresponding to a different value of Δ, which ranges from $Q(0) - Q(1)$ to 0. Each component quasi-distribution has a support of $\left(-\left(\frac{\mathbf{k}}{\frac{3+(-1)^{\mathbf{k}}}{2}}\right)^{-1}(-\Delta)^{\mathbf{k}}, \frac{1}{\mathbf{k}}(-\Delta)^{\mathbf{k}}\right)$.

Proof. The support of ξ_Δ is the extrema of $\psi_{\mathbf{k}}$ subject to the inequality constraints. Using the Lagrange multiplier, one can easily determine the only critical point at $x_1 = \ldots = x_{\mathbf{k}} = 0$, where $\psi_{\mathbf{k}} = 0$. Other candidates are within the boundaries, i.e., $\psi_{\mathbf{k}}(x_1 = x_1, x_2 = x_{\mathbf{k}}, \ldots, x_{\mathbf{k}} = x_{\mathbf{k}})$, $\ldots$, $\psi_{\mathbf{k}}(x_1 = x_1, \ldots, x_i = x_1, x_{i+1} = x_{\mathbf{k}}, \ldots, x_{\mathbf{k}} = x_{\mathbf{k}})$, $\ldots$, $\psi_{\mathbf{k}}(x_1 = x_1, \ldots, x_{\mathbf{k}-1} = x_1, x_{\mathbf{k}} = x_{\mathbf{k}})$. $\psi_{\mathbf{k}}(x_1 = x_1, \ldots, x_i = x_1, x_{i+1} = x_{\mathbf{k}}, \ldots, x_{\mathbf{k}} = x_{\mathbf{k}})$ can be divided into $\mathbf{k}$ groups. $\square$

Data Availability. Data for Table **??** are given in SI Dataset S1. All codes have been deposited in [GitHub](#).

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